

$$i = \sqrt{-1} \in \mathbb{C}$$

$$(i, k) \rightarrow (n, m)$$

Stability Analysis

By expressing $S := n\delta S$ and $t := m\delta t$, we will obtain a difference equation for the Black-Scholes equation.

$$V(S, t) = V(n\delta S, m\delta t) = V_n^m.$$

$\delta S = \frac{S^*}{N}$ where $S^* \gg E$ is a suitably large value of S ;
 $\delta t = \frac{T}{M}$. Taking N and M steps for S and t respectively,
 so

$$\begin{aligned} S &:= n\delta S & 0 \leq n \leq N \\ t &:= m\delta t & 0 \leq m \leq M. \end{aligned}$$

$$\left[\begin{aligned} &\frac{V_n^m - V_n^{m+1}}{\delta t} + \frac{1}{2}n^2\sigma^2 (V_{n-1}^m - 2V_n^m + V_{n+1}^m) + \\ &\frac{1}{2}(r - D)n (V_{n+1}^m - V_{n-1}^m) - rV_n^m = 0 \end{aligned} \right]$$

and rearrange to obtain a *forward marching* scheme in time

$$\begin{aligned} V_n^{m+1} &= V_n^m + \delta t \left(\frac{1}{2}n^2\sigma^2 (V_{n-1}^m - 2V_n^m + V_{n+1}^m) \right) \\ &\quad + \delta t \left(\frac{1}{2}(r - D)n (V_{n+1}^m - V_{n-1}^m) - rV_n^m \right) \\ &\equiv F(V_{n-1}^m, V_n^m, V_{n+1}^m) \end{aligned}$$

Is δS and δt related?

Now for the RHS collect coefficients of each variable term V , to get

$$V_n^{m+1} = \alpha_n V_{n-1}^m + \beta_n V_n^m + \gamma_n V_{n+1}^m \quad (1)$$

where

$$\begin{aligned} \alpha_n &= \frac{1}{2} (n^2 \sigma^2 - n(r - D)) \delta t, \\ \beta_n &= 1 - (r + n^2 \sigma^2) \delta t, \\ \gamma_n &= \frac{1}{2} (n^2 \sigma^2 + n(r - D)) \delta t \end{aligned} \quad (2)$$

is
 $\theta = \omega \Delta t$
 $\sin \theta$
 Euler's
 stability

Fourier Stability (Von Neumann's) Method

A method is called step-wise unstable if for a fixed grid (i.e. δt , δS constant) there exists an initial perturbation which "blows up" as $t \rightarrow \infty$, i.e. as we March in time. Here in a forward marching scheme. The question we wish to answer is "do small errors propagate along the grid and grow exponentially?".

error: $E_n^m \propto e^{in\omega}$

Assume an initial disturbance which is proportional to $\exp(in\omega)$. We therefore study the propagation of perturbations created at any given point in time.

G.D. Smith (Oxford) Numerical Methods for PDEs



If \hat{V}_n^m is an approximation to the exact solution V_n^m then

approx. exact error

$$\frac{\partial v}{\partial t} = \frac{1}{2} \sigma^2 \frac{\partial^2 v}{\partial s^2}$$

$$\hat{V}_n^m = V_n^m + E_n^m$$

where E_n^m is the associated error. Then E_n^m also satisfies the difference equation (4) to give

$$E_n^{m+1} = \alpha_n E_{n-1}^m + \beta_n E_n^m + \gamma_n E_{n+1}^m$$

Put

freq. ω (cycles per second)

$$E_n^m = \bar{a}^m \exp(in\omega) \quad (3)$$

which is oscillatory of amplitude \bar{a} and frequency ω . Substituting (3) into (1) gives

$$\bar{a}^{m+1} e^{i(n+1)\omega} = \alpha_n \bar{a}^m e^{i(n-1)\omega} + \beta_n \bar{a}^m e^{in\omega} + \gamma_n \bar{a}^m e^{i(n+1)\omega}$$

which becomes

$$\bar{a} = \alpha_n e^{-i\omega} + \beta_n + \gamma_n e^{i\omega}.$$

∴ Now stability criteria arises from the balancing of the time dependency and diffusion terms, so that

$$\frac{\partial V}{\partial t} + \frac{1}{2} \sigma^2 S^2 \frac{\partial^2 V}{\partial S^2} = 0$$

$$\left(\frac{\partial V}{\partial t} \right) \quad \left(\frac{\partial^2 V}{\partial S^2} \right)$$

From (2) we take the following contributions

$$\frac{\partial V}{\partial t} \quad \& \quad \frac{\partial^2 V}{\partial S^2}$$

$$\alpha_n = \frac{1}{2} n^2 \sigma^2 \delta t, \quad \beta_n = 1 - n^2 \sigma^2 \delta t, \quad \gamma_n = \frac{1}{2} n^2 \sigma^2 \delta t$$

$$\cos x = \frac{e^{ix} + e^{-ix}}{2}$$

$$\sin x = \frac{e^{ix} - e^{-ix}}{2i}$$

$$\cos 2x = \begin{cases} \cos^2 x - \sin^2 x \\ 2\cos^2 x - 1 \\ 1 - 2\sin^2 x \end{cases}$$

Important
Trig identities

$$\begin{aligned} \rightarrow \bar{a} &= \frac{1}{2} n^2 \sigma^2 \delta t (e^{i\omega} + e^{-i\omega}) + 1 - n^2 \sigma^2 \delta t \\ &= \frac{1}{2} n^2 \sigma^2 \delta t (\cos \omega + 1) + 1 - n^2 \sigma^2 \delta t \end{aligned}$$

$\cos \omega$ comes

we have

$$\bar{a} = 1 - 2n^2 \sigma^2 \sin^2 \frac{\omega}{2} \delta t$$

from $\frac{1}{2}(e^{i\omega} + e^{-i\omega})$

For stability \bar{a} must be bounded, i.e. $|\bar{a}| < 1$

$$\left| 1 - 2n^2 \sigma^2 \sin^2 \frac{\omega}{2} \delta t \right| < 1$$

\bar{a}^n

which upon simplifying we find is

stability condition

$$\delta t < \frac{1}{\sigma^2 N^2}$$

$$|\bar{a}| < 1 \quad (4)$$

so $\delta t \sim O(N^{-2})$.

$$-1 < 1 - 2N^2 \sigma^2 \delta t < 1$$

explicit scheme

$$\cos 2x = 1 - 2\sin^2 x$$

$$\begin{aligned} \cos 2x - 1 &= -2\sin^2 x \\ \cos \omega - 1 &= -2\sin^2 \frac{\omega}{2} \end{aligned}$$

$$x = \frac{\omega}{2}$$

$$4\delta t < \frac{1}{\sigma^2 N^2}$$

$$N \rightarrow 2N$$

$$\delta S = \frac{S^*}{N}$$