# M.Sc. (Five Year Integrated) in Computer Science (Artificial Intelligence & Data Science)

# Third Semester

# Laboratory Record 21-805-0306: ALGORITHMS LAB

Submitted in partial fulfillment
of the requirements for the award of degree in
Master of Science (Five Year Integrated)
in Computer Science (Artificial Intelligence & Data Science) of
Cochin University of Science and Technology (CUSAT)
Kochi



Submitted by

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This is to certify that the software laboratory record for 21-805-0306:

Algorithms Lab is a record of work carried out by AKSHADHA A(80521004),
in partial fulfillment of the requirements for the award of degree in Master of

Science (Five Year Integrated) in Computer Science (Artificial

Intelligence & Data Science) of Cochin University of Science and Technology

(CUSAT), Kochi. The lab record has been approved as it satisfies the academic
requirements in respect of the third semester laboratory prescribed for the Master of

Science (Five Year Integrated) in Computer Science degree.

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# QUICK SORT

## $\mathbf{AIM}$

To sort the elements using quick sort and to determine the time required to sort the elements.

```
#include<iostream>
#include <ctime>
#include <iomanip>
#include<cstdlib>
#include<chrono>
using namespace std;
using namespace std::chrono;
int Partition(int *A,int LB,int UB)
{
    int pivot = A[LB];
    int START = LB;
    int END = UB;
    while(START < END)</pre>
        while(A[START] <= pivot)</pre>
        {
            START++;
        }
        while(A[END] > pivot)
        {
            END--;
        if(START < END)
        {
            int temp = A[START];
            A[START] = A[END];
            A[END] = temp;
        }
    }
    int t1 = A[LB];
    A[LB] = A[END];
    A[END] = t1;
    return END;
}
```

```
void QuickSort(int *A,int LB,int UB)
{
    if (LB < UB)
    {
         int LOC = Partition(A,LB,UB);
         QuickSort(A,LB,LOC-1);
         QuickSort(A,LOC+1,UB);
    }
}
void display(int *A, int n)
{
    cout<<"The sorted list is : "<<" ";</pre>
    for(int i = 0; i<n; i++)</pre>
    {
        cout<<A[i]<<" ";
    }
}
int main()
{
    int n;
    char choice;
    do
    {
         cout<<"Enter the number of elements : "<<" ";</pre>
         cin>>n;
         int A[n];
         int endpt;
         cout<<"Enter the end point : "<<" ";</pre>
         cin>>endpt;
         for(int i = 0; i<n; i++)
         {
             A[i] = 1+rand()%endpt;
         cout<<"The array is : "<<" ";</pre>
        for(int i = 0; i<n; i++)
         {
             cout<<A[i]<<" ";
         }
         cout << end1;
         int LB = 0;
```

```
int UB = n;
auto start = high_resolution_clock::now();
QuickSort(A,LB,UB);
auto stop = high_resolution_clock::now();
auto doneTime = duration_cast<microseconds>(stop-start);
cout<< " You took " <<doneTime.count() << " nanoseconds\n";
display(A,n);
cout<<endl;
cout<<"Do you want to continue(y/n)? : "<<" ";
cin>>choice;
} while (choice!='n');
}
```

```
Enter the number of elements: 6
Enter the end point: 120
The array is: 42 108 95 101 90 5
You took 0 nanoseconds
The sorted list is: 5 42 90 95 101 108
Do you want to continue(y/n)?: n
```

# BREADTH FIRST SEARCH

## $\mathbf{AIM}$

To print all the nodes reachable from a given starting node in a digraph using BFS method

```
#include<iostream>
#include<vector>
#include<queue>
using namespace std;
void add_edge(vector<int>adj[],int u,int v)
{
    adj[u].push_back(v);
}
void bfs(int source, vector<int>adj[], bool visited[])
    queue<int>q;
    q.push(source);
    visited[source] = true;
    while(!q.empty())
    {
        int u = q.front();
        cout<<u<<" ";
       q.pop();
        //Traversal
       for(int i = 0;i<adj[u].size();i++)</pre>
           if(!visited[adj[u][i]])
           {
               q.push(adj[u][i]);
               visited[adj[u][i]] = true;
       }
    }
}
int main()
{
    cout<<"-----"<<endl;
    cout<<"Enter the no: of vertices : "<<" ";</pre>
```

```
cin>>n;
    vector<int>adj[n];
    bool visited[n];
    for(int i = 0; i < 5; i++)
    {
         visited[i] = false;
    }
    cout<<"Enter the no: of edges : "<<" ";</pre>
    cin>>e;
    int a,b,s;
    for(int i = 0; i < e; i++)
    {
         cout<<endl;</pre>
         cout<<"EDGE "<<i+1<<endl;</pre>
         cout<<"Enter the starting point : "<<" ";</pre>
         cout<<"Enter the final point : "<<" ";</pre>
         cin>>b;
         add_edge(adj,a,b);
    }
    cout<<endl;</pre>
    cout<<"Choose any vertex as the source : "<<" ";</pre>
    cin>>s;
    cout << end1;
    cout<<"BFS TRAVERSAL : "<<" ";</pre>
    bfs(s,adj,visited);
    cout<<endl;</pre>
}
```

```
----- BREADTH FIRST SEARCH-----
Enter the no: of vertices : 5
Enter the no: of edges
EDGE 1
Enter the starting point : 0
Enter the final point : 1
Enter the final point
EDGE 2
Enter the starting point : 0
Enter the final point
EDGE 3
Enter the starting point : 0
Enter the final point
EDGE 4
Enter the starting point : 1
Enter the final point
EDGE 5
Enter the starting point : 2
Enter the final point : 4
Choose any vertex as the source : 0
BFS TRAVERSAL : 0 1 2 3 4
```

# DEPTH FIRST SEARCH

#### AIM

To check whether a given graph is connected using DFS method

```
#include <iostream>
#include <vector>
using namespace std;
vector<int> g[10];
bool visited[10] = { false };
void create_edge(int src, int dest) {
    g[src].push_back(dest);
}
void dfs(int vertex) {
    if (visited[vertex] == true) return;
    cout << vertex << " ";</pre>
    visited[vertex] = true;
    for (auto node: g[vertex]) {
        dfs(node);
    }
}
int main() {
    int n,e,u,v;
    cout<<"----"<<endl;
    cout<<"Enter the no: of vertices : "<<" ";</pre>
    cin>>n;
    cout<<"Enter the no: of edges : "<<" ";</pre>
    cin>>e;
    for(int i = 0; i < e; i++)
        cout<<"Enter the start vertex : "<<" ";</pre>
        cin>>u;
        cout<<"Enter the end vertex : "<<" ";</pre>
        cin>>v;
```

```
create_edge(u, v);
}
dfs(0);
}
```

```
Enter the no: of vertices: 6
Enter the no: of edges: 5
Enter the start vertex: 0
Enter the end vertex: 1
Enter the start vertex: 0
Enter the start vertex: 2
Enter the end vertex: 2
Enter the end vertex: 5
Enter the end vertex: 6
Enter the end vertex: 6
Enter the start vertex: 7
0 1 2 5 6 7
```

# DIJKSTRA'S ALGORITHM

## $\mathbf{AIM}$

To find shortest paths to other vertices from a given vertex in a weighted connected graph using Dijkstra's algorithm

```
#include<iostream>
#include<stdio.h>
using namespace std;
#define INF 9999
#define V 5
void dijkstra(int G[V][V],int num,int start)
{
    int cost[V][V];
    int distance[V],pred[V];
    int visited[V],count,min_dist,next,i,j;
    for(i=0;i<num;i++)</pre>
                                    //Assigning the values (initialisation)
        for(j=0;j<num;j++)</pre>
        {
             if(G[i][j]==0)
                 cost[i][j]=INF;
             }
             else
                 cost[i][j]=G[i][j];
             }
        }
    }
    for(i=0;i<num;i++)</pre>
    {
        distance[i]=cost[start][i];
        pred[i]=start;
        visited[i] = 0;
    }
    distance[start] = 0;
    visited[start] = 1;
```

```
count = 1;
   while(count < num-1)</pre>
   {
       min_dist=INF;
       for(i=0;i<num;i++)</pre>
       {
           if(distance[i] < min_dist && !visited[i])</pre>
           {
               min_dist=distance[i];
              next = i;
           }
       visited[next] = 1;
       for(i=0;i<num;i++)</pre>
       {
           if(!visited[i])
               {
                  distance[i]=min_dist+cost[next][i];
                  pred[i]=next;
               }
           }
       }
       count++;
   }
   cout<<endl;</pre>
   cout<<"Vertex"<<"
                              "<<"Distance"<<endl;
   cout<<"----"<<endl;
   for(i=0;i<num;i++)</pre>
   {
       //if(i!=start)
           cout<<i<"
                                    "<<distance[i]<<endl;
           cout<<endl;</pre>
       }
   }
}
int main()
{
   int G[V][V];
```

```
int source;
   cout<<"-----"<<end1;
   for(int i = 0; i < V; i++)
   {
       cout<<"Enter the distance from vertex "<< i <<" to each vertex : "<<" ";
      for(int j = 0; j < V; j++)
       {
          cin>>G[i][j];
      }
   }
   cout<<endl<<endl;</pre>
   cout<<"Choose any vertex as source : "<<" ";</pre>
   cin>>source;
   dijkstra(G,V,source);
   return 0;
}
```

# BELLMAN FORD

#### AIM

To implement Bellman Ford's Algorithm

```
#include <bits/stdc++.h>
using namespace std;
// Struct for the edges of the graph
struct Edge {
    int u; //start vertex of the edge
    int v; //end vertex of the edge
    int w; //w of the edge (u,v)
};
struct Graph {
    int V; // Total number of vertices in the graph
    int E; // Total number of edges in the graph
    struct Edge* edge; // Array of edges
};
struct Graph* createGraph(int V, int E) {
    struct Graph* graph = new Graph;
    graph->V = V; // Total Vertices
    graph->E = E; // Total edges
    graph->edge = new Edge[E];
    return graph;
}
void printArr(int arr[], int size) {
    for (i = 0; i < size; i++) {
    printf("%d ", arr[i]);
    cout << endl;
}
void BellmanFord(struct Graph* graph, int u) {
    int V = graph->V;
    int E = graph->E;
    int dist[V];
    // Step 1: fill the distance array and predecessor array
    for (int i = 0; i < V; i++)
    dist[i] = INT_MAX;
```

```
// Mark the source vertex
    dist[u] = 0;
    // Step 2: relax edges |V| - 1 times
    for (int i = 1; i \le V - 1; i++) {
        for (int j = 0; j < E; j++) {
        // Get the edge data
        int u = graph->edge[j].u;
        int v = graph->edge[j].v;
        int w = graph->edge[j].w;
        if (dist[u] != INT_MAX && dist[u] + w < dist[v])</pre>
        dist[v] = dist[u] + w;
        }
    }
    // Step 3: detect negative cycle
    // if value changes then we have a negative cycle in the graph
    // and we cannot find the shortest distances
    for (int i = 0; i < E; i++) {
        int u = graph->edge[i].u;
        int v = graph->edge[i].v;
        int w = graph->edge[i].w;
        if (dist[u] != INT_MAX && dist[u] + w < dist[v]) {
        printf("Graph contains negative w cycle");
        return;
        }
    }
    // No negative weight cycle found!
    // Print the distance and predecessor array
    printArr(dist, V);
    return;
}
int main() {
    // Create a graph
    int V = 5; // Total vertices
    int E = 8; // Total edges
    struct Graph* graph = createGraph(V, E);
    //---- adding the edges of the graph
    //edge 0 --> 1
    graph \rightarrow edge[0].u = 0;
    graph->edge[0].v = 1;
    graph -> edge[0].w = 5;
    //edge 0 --> 2
```

```
graph \rightarrow edge[1].u = 0;
    graph->edge[1].v = 2;
    graph->edge[1].w = 4;
    //edge 1 --> 3
    graph->edge[2].u = 1;
    graph->edge[2].v = 3;
    graph->edge[2].w = 3;
    //edge 2 --> 1
    graph->edge[3].u = 2;
    graph->edge[3].v = 1;
    graph->edge[3].w = 6;
    //edge 3 --> 2
    graph -> edge[4].u = 3;
    graph->edge[4].v = 2;
    graph->edge[4].w = 2;
    BellmanFord(graph, 0); //0 is the source vertex
    return 0;
}
```

```
0 5 4 8 2147483647
...Program finished with exit code 0
Press ENTER to exit console.
```

# FLOYD WARSHALL

## $\mathbf{AIM}$

Program to implement All-Pairs Shortest Problem using Floyd's algorithm

```
#include<iostream>
using namespace std;
#define INF 99999
#define num 4
void floyd_warshall(int A[][num])
{
    int i,j,k;
    for(k = 0; k < num; k++)
        for(i= 0;i<num;i++)</pre>
            for(j=0;j<num;j++)</pre>
                if(A[i][j] > (A[i][k] + A[k][j]) && A[k][j]! = INF && A[i][k] != INF)
                {
                    A[i][j] = A[i][k] + A[k][j];
                }
            }
        }
   }
}
int main()
    int i,j;
    cout<<"-----"<<endl<:
    cout<<"Enter the value 99999 wherever infinity is present "<<endl<<endl;</pre>
    cout<<"Enter the input matrix : "<<" ";</pre>
    int M[num][num];
    for(i=0;i<num;i++)</pre>
    {
        for(j=0;j<num;j++)</pre>
```

```
{
         cin>>M[i][j];
    }
    cout<<endl;</pre>
}
cout<<"The Input matrix is : "<<endl;</pre>
for(i=0;i<num;i++)</pre>
{
    for(j=0;j<num;j++)</pre>
    {
         if (M[i][j] == INF)
         {
              cout<<"INF"<<" ";
         }
         else
         {
              cout<< M[i][j]<<"
         }
    }
    cout << end1;
}
floyd_warshall(M);
cout<<endl<<endl;</pre>
cout<<"The Final Distance matrix is : "<<endl;</pre>
for(i=0;i<num;i++)</pre>
{
    for(j=0;j<num;j++)</pre>
    {
         if (M[i][j] == INF)
         {
              cout<<"INF"<<" ";
         }
         else
         {
              cout<< M[i][j]<<" ";
         }
    }
    cout << end1;
}
return(0);
```

}

```
-----FLOYD WARSHALL ALGORITHM------FLOYD WARSHALL
Enter the value 99999 wherever infinity is present
Enter the input matrix :
      8
              99999
                         1
99999 0
                  1 99999
4 99999
                  0 99999
99999 2
                  9
                         0
The Input matrix is :
           INF
INF
                 INF
     INF
                 INF
4
INF
           9
                 0
The Final Distance matrix is :
         0
         3
              0
```

# KRUSKAL'S ALGORITHM

## $\mathbf{AIM}$

To find Minimal Cost Spanning Tree of a given undirected graph using Kruskal's algorithm

```
// Kruskal's algorithm in C++
#include <algorithm>
#include <iostream>
#include <vector>
using namespace std;
#define edge pair<int, int>
class Graph {
    private:
    vector<pair<int, edge> > G; // graph
    vector<pair<int, edge> > T; // mst
    int *parent;
    int V; // number of vertices/nodes in graph
    public:
    Graph(int V);
    void AddWeightedEdge(int u, int v, int w);
    int find_set(int i);
    void union_set(int u, int v);
    void kruskal();
    void print();
};
Graph::Graph(int V) {
    parent = new int[V];
//i 0 1 2 3 4 5
//parent[i] 0 1 2 3 4 5
    for (int i = 0; i < V; i++)
    parent[i] = i;
    G.clear();
    T.clear();
}
void Graph::AddWeightedEdge(int u, int v, int w) {
    G.push_back(make_pair(w, edge(u, v)));
}
int Graph::find_set(int i) {
    if (i == parent[i])
    return i;
```

```
else
    return find_set(parent[i]);
}
void Graph::union_set(int u, int v) {
    parent[u] = parent[v];
}
void Graph::kruskal() {
    int i, uRep, vRep;
    sort(G.begin(), G.end()); // increasing weight
    for (i = 0; i < G.size(); i++) {
        uRep = find_set(G[i].second.first);
        vRep = find_set(G[i].second.second);
        if (uRep != vRep) {
            T.push_back(G[i]); // add to tree
            union_set(uRep, vRep);
        }
    }
}
void Graph::print() {
    cout << "Edge : "<< " Weight" << endl;</pre>
    for (int i = 0; i < T.size(); i++) {</pre>
    cout << T[i].second.first << " - " << T[i].second.second << " : "
    << T[i].first;</pre>
    cout << endl;</pre>
    }
}
int main() {
    int n,u,v,w;
    cout<<"----"<<endl;
    cout<<"Enter the no: of vertices : "<<" ";</pre>
    cin>>n;
    Graph g(n);
    for (int i = 0; i < n; i++)
    {
        cout<<"Enter the start vertex : "<<" ";</pre>
        cin>>u;
        cout<<"Enter the end vertex : "<<" ";</pre>
        cin>>v;
        cout<<"Enter the weight : "<<" ";</pre>
        cin>>w;
        g.AddWeightedEdge(u, v, w);
```

```
g.kruskal();
g.print();
return 0;
}
```

```
-----KRUSKAL'S ALGORITHM-----
Enter the no: of vertices: 7
Enter the start vertex : 0
Enter the end vertex : 1
Enter the weight
                         : 28
Enter the start vertex : 0
Enter the end vertex : 5
Enter the weight : 10
Enter the start vertex : 5
Enter the end vertex : 4
Enter the end vertex : 4
Enter the weight
                           25
Enter the start vertex : 4
Enter the end vertex : 6
Enter the weight
                         : 24
Enter the start vertex: 4
Enter the end vertex : 3
Enter the weight
Enter the start vertex : 3
Enter the end vertex : 2
Enter the weight
Enter the start vertex : 1
Enter the end vertex
Enter the weight
                            16
 Edge : Weight 0 - 5 : 10
   - 2 : 16
   - 3 : 22
   - 6: 24
     4 : 25
```

# PRIM'S ALGORITHM

#### AIM

To find Minimal Cost Spanning Tree of a given undirected graph using Prim's algorithm

```
#include <iostream>
#include <bits/stdc++.h>
using namespace std;
const int MAX = 99999; // INF
#define V 5
bool createsMST(int u, int v, vector<bool> V_MST)
{
    if (u == v)
    {
        return false;
    if (V_MST[u] == false && V_MST[v] == false)
        return false;
    else if (V_MST[u] == true && V_MST[v] == true)
        return false;
    return true;
void MST_display(int cost[][V])
{
    vector<bool> V_MST(V, false);
    V_MST[0] = true;
    int edgeNo = 0, MSTcost = 0;
    while (edgeNo < V - 1)
    {
        int min = MAX, a = -1, b = -1;
        for (int i = 0; i < V; i++)
            for (int j = 0; j < V; j++)
                if (cost[i][j] < min)</pre>
```

```
{
                     if (createsMST(i, j, V_MST))
                     {
                          min = cost[i][j];
                          a = i;
                          b = j;
                     }
                 }
             }
        }
        if (a != -1 \&\& b != -1)
        {
             cout << "Edge " << edgeNo++ << " : (" << a << " , " << b << " ) : cost = "
             << min << endl;
             MSTcost += min;
             V_MST[b] = V_MST[a] = true;
        }
    }
    cout << "Cost of MST = " << MSTcost;</pre>
}
int main()
{
    int G[V][V];
    int source;
    //Enter the value 99999 wherever infinity is present
    for (int i = 0; i < V; i++)
    {
        cout << "Enter the distance from vertex " << i << " to each vertex : " \,
              << " ";
        for (int j = 0; j < V; j++)
        {
             cin >> G[i][j];
        }
    }
    cout << endl<< endl;</pre>
    cout << "Choose any vertex as source : "<< " ";</pre>
    cin >> source;
    cout << endl;</pre>
    cout << "The MST for the given tree is :\n";</pre>
    cout<<endl;</pre>
    MST_display(G);
```

```
return 0;
}
```

```
99999
                                                                                                      99999
Enter the distance from vertex 0 to each vertex :
                                                                             99999
Enter the distance from vertex 1 to each vertex :
                                                                      0
                                                                                 10
Enter the distance from vertex 2 to each vertex :
                                                              99999 10
                                                                                  0
                                                                                                      99999
Enter the distance from vertex 3 to each vertex :
                                                              99999 2
                                                                                              0
                                                                                                           1
                                                                                  4
Enter the distance from vertex 4 to each vertex :
                                                                             99999
                                                                                              1
                                                                                                           0
Choose any vertex as source: 0
The MST for the given tree is :
Edge 0 : (0 , 1 ) : cost = 3

Edge 1 : (1 , 3 ) : cost = 2

Edge 2 : (3 , 4 ) : cost = 1

Edge 3 : (2 , 3 ) : cost = 4
Cost of MST = 10
```

# MATRIX CHAIN MULTIPLICATION

# $\mathbf{AIM}$

Program to implement Matrix Chain Multiplication using Dynamic Programming

```
#include <bits/stdc++.h>
#include <iostream>
#include <iomanip>
using namespace std;
void MatrixChainOrder(int p[], int n)
{
    int m[n][n];
    int s[n-1][n-1]; // Stores the value of k
    int i, j, k, L, q;
    for (i = 1; i < n; i++)
    {
        for (int j = 1; j < n; j++)
        {
            m[i][j] = 0;
        }
    }
    for (i = 1; i < n; i++)
        for (int j = 1; j < n; j++)
        {
            if (i > j)
            {
                s[i][j] = 0;
            }
            else
            {
                s[i][j] = 1;
            }
        }
    }
    // L = chain length
    for (L = 2; L < n; L++)
    {
```

```
for (i = 1; i < n - L + 1; i++)
    {
        j = i + L - 1;
        m[i][j] = INT_MAX;
        for (k = i; k \le j - 1; k++)
        {
             // q = cost/scalar multiplications
             q = m[i][k] + m[k + 1][j] + p[i - 1] * p[k] * p[j];
             if (q < m[i][j])</pre>
             {
                 m[i][j] = q;
                 s[i][j] = k;
             }
        }
    }
}
cout << "RESULTANT MATRIX , M = " << endl</pre>
     << endl;
for (int i = 1; i < n; i++)
{
    for (int j = 1; j < n; j++)
    {
        cout << setw(5) << m[i][j] << setw(4);</pre>
    cout << endl;</pre>
}
cout << endl
     << endl;
cout << "MATRIX S = " << endl
     << endl;
for (int i = 1; i < n; i++)
{
    for (int j = 1; j < n; j++)
    {
        cout << setw(4) << s[i][j] << setw(4);</pre>
    cout << endl;</pre>
}
cout<<endl<<endl;</pre>
cout << "Minimum number of multiplications is : " << m[1][n - 1] << endl;
```

}

```
int main()
{
   cout<<"----"<<endl;
   cout << "Enter the no : of matrices : " \,
        << " ";
   cin >> num;
   int A[num + 1];
   cout << "Enter the order of the matrices one by one : "</pre>
            << " ";
   for (int i = 0; i < num + 1; i++)
   {
       cin >> A[i];
   }
   int size = sizeof(A) / sizeof(A[0]);
   cout<<endl;</pre>
   MatrixChainOrder(A, size);
   cout << endl << endl;
   return 0;
}
```

```
-----MATRIX CHAIN MULTIPLICATION------
Enter the no : of matrices : 4
Enter the order of the matrices one by one :
2
RESULTANT MATRIX , M =
           88 158
   0 120
          48 104
       0
   0
       0
           0 84
   0
        0
            0
MATRIX S =
      1
         1
             3
  1
  0
      1
  0
      0
         1
             3
Minimum number of multiplications is : 158
```

# 0/1 KNAPSACK PROBLEM

#### AIM

Program to implement 0/1 Knapsack Problem using Dynamic Programming

```
#include<iostream>
#define MAX 10
using namespace std;
struct product
  int product_num;
 int profit;
 int weight;
 float ratio;
 float take_quantity;
};
int main()
  cout<<"----"<<endl;
 product P[MAX],temp;
  int i,j,total_product,capacity;
  float value=0;
  cout<<"Enter no: of items : ";</pre>
  cin>>total_product;
  cout<<"Enter capacity of sack : ";</pre>
  cin>>capacity;
  cout<<"\n";
 for(i=0;i<total_product;++i)</pre>
    P[i].product_num=i+1;
    cout<<"Enter profit and weight of item "<<i+1<<" : ";</pre>
    cin>>P[i].profit>>P[i].weight;
    P[i].ratio=(float)P[i].profit/P[i].weight;
    P[i].take_quantity=0;
  }
```

```
//HIGHEST RATIO BASED SORTING
  for(i=0;i<total_product;++i)</pre>
    for(j=i+1;j<total_product;++j)</pre>
      if(P[i].ratio<P[j].ratio)</pre>
      {
        temp=P[i];
        P[i]=P[j];
        P[j]=temp;
      }
    }
  }
  for(i=0;i<total_product;++i)</pre>
  {
    if(capacity==0)
      break;
    else if(P[i].weight<capacity)</pre>
      P[i].take_quantity=1;
      capacity-=P[i].weight;
    }
    else if(P[i].weight>capacity)
      P[i].take_quantity=(float)capacity/P[i].weight;
      capacity=0;
    }
  }
  cout<<"\n\nItems to be taken -";</pre>
  for(i=0;i<total_product;++i)</pre>
    cout<<"\nTake item "<<P[i].product_num<<" : "<<P[i].take_quantity*P[i].weight<</pre>
    " units";
    value+=P[i].profit*P[i].take_quantity;
  cout<<"\nThe knapsack value is : "<<value;</pre>
}
```

```
Enter no: of items : 3
Enter capacity of sack : 6

Enter profit and weight of item 1 : 1 2
Enter profit and weight of item 2 : 2 3
Enter profit and weight of item 3 : 4 3

Items to be taken -
Take item 3 : 3 units
Take item 2 : 0 units
Take item 1 : 2 units
The knapsack value is : 5
```

# **HUFFMAN CODES**

## $\mathbf{AIM}$

Program to implement Huffman Coding using Greedy algorithm

```
#include <bits/stdc++.h>
using namespace std;
struct MinHeapNode
{
    char d;
    unsigned frequency;
    MinHeapNode *lChild, *rChild;
    MinHeapNode(char d, unsigned frequency)
    {
        lChild = rChild = NULL;
        this->d = d;
        this->frequency = frequency;
    }
};
// function to compare
struct compare
    bool operator()(MinHeapNode *1, MinHeapNode *r)
        return (1->frequency > r->frequency);
    }
};
void printCodes(struct MinHeapNode *root, string str)
    if (!root)
        return;
    if (root->d != '$')
        cout << root->d << "
                                           " << str << "\n";
```

```
printCodes(root->lChild, str + "0");
   printCodes(root->rChild, str + "1");
}
void HuffmanCodes(char d[], int frequency[], int size)
{
   struct MinHeapNode *lChild, *rChild, *top;
   priority_queue<MinHeapNode *, vector<MinHeapNode *>, compare> minHeap;
   for (int i = 0; i < size; i++)
       minHeap.push(new MinHeapNode(d[i], frequency[i]));
   while (minHeap.size() != 1)
   {
       1Child = minHeap.top();
       minHeap.pop();
       rChild = minHeap.top();
       minHeap.pop();
       top = new MinHeapNode('$', lChild->frequency + rChild->frequency);
       top->lChild = lChild;
       top->rChild = rChild;
       minHeap.push(top);
   }
   printCodes(minHeap.top(), " ");
}
int main()
{
   int num;
   cout<<"-----"<<endl;
   cout << "Enter the no: of characters : "<< " ";
   cin >> num;
   char A[num];
   int X[num];
   for (int i = 0; i < num; i++)
```

```
{
     cout << "Enter a character : "<< " ";</pre>
     cin >> A[i];
     cout << "Enter the frequency of the character : "<< " ";</pre>
     cin >> X[i];
  }
  cout<<endl<<endl;</pre>
  cout<<"----"<<endl;
  cout<<"-----"<<endl;
  for (int i = 0; i < num; i++)
  {
    cout<< A[i]<<"
                       "<<X[i]<<endl;
  }
  int size = sizeof(A) / sizeof(A[0]);
  cout<<endl;</pre>
  cout<<"-----"<<endl;
  cout<<"----"<<endl;
  HuffmanCodes(A, X, size);
  return 0;
}
```

```
-----HUFFMAN CODING------
Enter the no: of characters : 6
Enter a character: a
Enter the frequency of the character: 45
Enter a character : b
Enter the frequency of the character: 13
Enter a character : c
Enter the frequency of the character: 12
Enter a character: d
Enter the frequency of the character: 16
Enter a character : e
Enter the frequency of the character: 9
Enter a character : f
Enter the frequency of the character : 5
Character
         Frequency
              45
              13
b
              12
              16
              5
Character
          Assigned code
                0
а
               100
С
b
                101
                1100
                1101
                111
```

# TRAVELLING SALESMAN PROBLEM

## $\mathbf{AIM}$

Program to find the optimal solution for the Travelling Salesman Problem

```
#include<iostream>
using namespace std;
int ary[10][10],completed[10],n,cost=0;
void takeInput()
{
    int i,j;
    cout<<"Enter the number of vertices: ";</pre>
    cin>>n;
    cout<<"\nEnter the Cost Matrix\n";</pre>
    for(i=0;i < n;i++)
    {
         cout<<"\nEnter Elements of Row: "<<i+1<<"\n";</pre>
        for( j=0; j < n; j++)
             cin>>ary[i][j];
             completed[i]=0;
    }
    cout<<"\n\nThe cost list is:";</pre>
    for( i=0; i < n; i++)
    {
        cout << "\n";
        for(j=0; j < n; j++)
        cout<<"\t"<<ary[i][j];
    }
}
int least(int c)
    int i,nc=999;
    int min=999,kmin;
    for(i=0;i < n;i++)
        if((ary[c][i]!=0)&&(completed[i]==0))
        if(ary[c][i]+ary[i][c] < min)</pre>
         {
             min=ary[i][0]+ary[c][i];
```

```
kmin=ary[c][i];
            nc=i;
        }
    }
    if(min!=999)
        cost+=kmin;
    return nc;
}
void mincost(int city)
{
    int i,ncity;
    completed[city]=1;
    cout<<city+1<<"--->";
    ncity=least(city);
    if(ncity==999)
    {
        ncity=0;
        cout<<ncity+1;</pre>
        cost+=ary[city][ncity];
        return;
    }
    mincost(ncity);
}
int main()
{
    takeInput();
    cout<<"\n\nThe Path is:\n";</pre>
    mincost(0); //passing 0 because starting vertex
    cout<<"\n\nMinimum cost is "<<cost;</pre>
    return 0;
```

}

```
Enter the number of vertices: 4

Enter the Cost Matrix

Enter Elements of Row: 1
0 10 15 20

Enter Elements of Row: 2
5 0 9 10

Enter Elements of Row: 3
6 13 0 12

Enter Elements of Row: 4
8 8 9 0

The cost list is:

0 10 15 20
5 0 9 10
6 13 0 12
8 8 9 0

The Path is:
1--->2--->3--->4--->1

Minimum cost is 39
```