USART

PIC Microcontroller: An Introduction to Software & Hardware Interfacing

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Why Serial Communication?

- **Parallel** I/O uses many signal pins
- Synchronization problem over longer distance
- Cost of cable
- Many applications do not need high data rate

Types of Serial I/O

1. USART (universal synchronous asynchronous receiver and transceiver)
2. SPI (synchronous peripheral interface)
3. I^2C (inter-integrated circuit)
4. CAN bus (controller area network bus)
5. LIN (local interconnect network) – won't be covered

The EIA232 Standard

- Developed in 1960 by electronic industry association.
- The latest revision is EIA232E.
- EIA232 is also referred to as RS232 for historical reason.
- Both computers and terminals are called **data terminal equipment** (DTE).
- Modems, bridges, and routers are called **data communication equipment** (DCE).
- There are four aspects to the EIA232:

1. Electrical specifications
2. Functional aspects—the function of each signal
3. Mechanical specifications
4. Procedural specifications

Electrical Specifications

- Data rates: EIA232 is applicable to data rate no more than 20 Kbps. The most commonly used data rates are 300, 1200, 2400, 9600, and 19200 baud.

- Signal state voltage assignments:
  1. voltages between -3 V to -25 V are considered as logic 1
  2. voltages between +3 V to 25 V are considered as logic 0
- Signal transfer distance: Signal should be able to transferred correctly up to 15 meters.

Functional Specifications

- Twenty-two signals are defined.
- Signals are divided into six groups:

1. Signal ground and shield
2. Primary communication channel
3. Secondary communication channel
4. Modem status and control signals
5. Transmitter and receiver timing signals
6. Channel test signals

- Secondary communication channel consists of the same signals as in the primary channel but rarely used.
- Timing signals are not used in asynchronous mode.
- Channel test signals are not used in normal communications.

Primary Communication Channel Signals

- Pin 2: transmit data
- Pin 3: receive data
- Pin 4: request to send signal (RTS)—asserted when in logic 0
- Pin 5: clear to send signal (CTS)—asserted when in logic 0

Modem Status and Control Signals

- Pin 6: data set ready (DSR)—asserted when in logic 0
- Pin 20: DTE ready (DTR)—asserted when in logic 0
- Pin 8: received line signal detector (CD)—also called carrier detect, asserted in logic 0
- Pin 22: ring indicator (RI)—asserted when in logic 0
- Pin 23: data signal rate selector—asserted when in logic 0

Mechanical Specification

- Specifies a 25-pin connector
- A 9-pin connector is used most often in PC but not specified in the standard

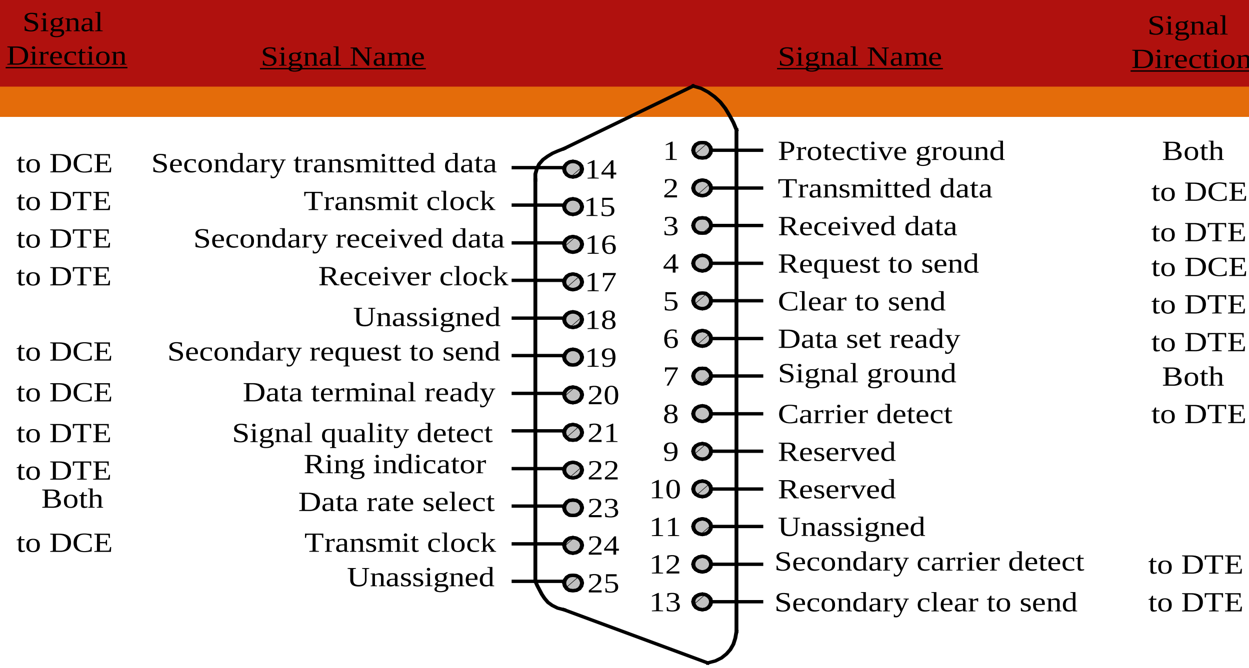


Figure 9.1a EIA232E DB25 connector and pin assignment

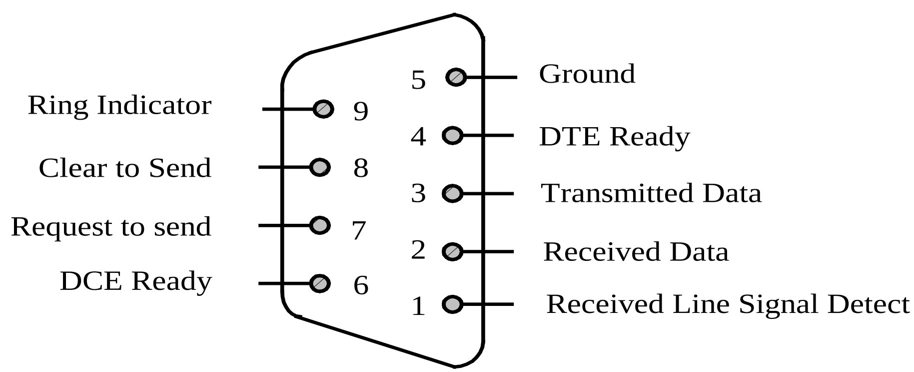
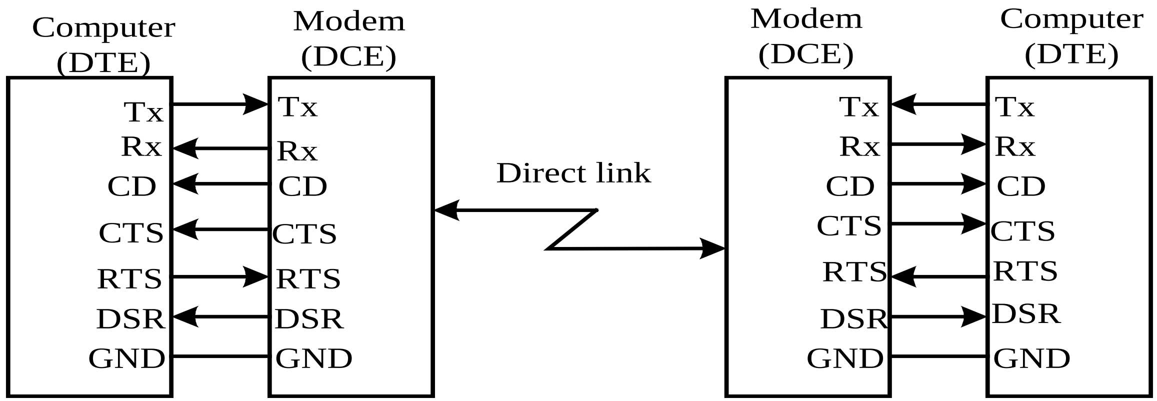


Figure 9.1b EIA232E DB9 connector and signal assignment

EIA232 Procedural Specification

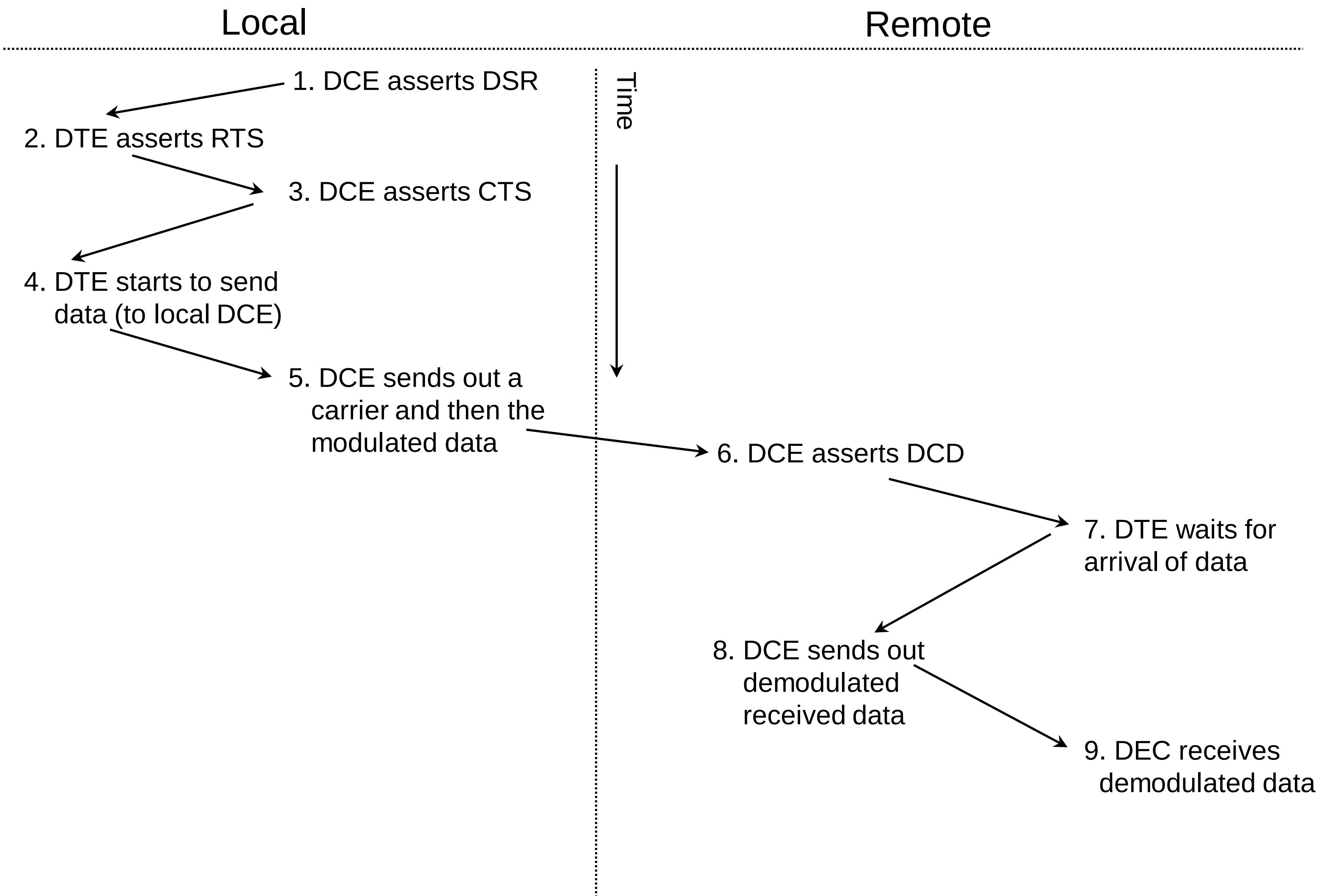
Case 1: Point-to-point asynchronous connection



Tx: transmit data
Rx: receive data
CD: data carrier detect
CTS: clear to send
RTS: request to send
DSR: data set ready

Figure 9.2 Point-to-point asynchronous connection

Sequence of events occurred during data transmission over dedicated link



Case 2: two DTEs exchange data over public phone lines

- Two additional signals are needed: DTR and RI
- There are three phases in the data transmission:
  1. Establishing the connection
  2. Data transmission
  3. Disconnection

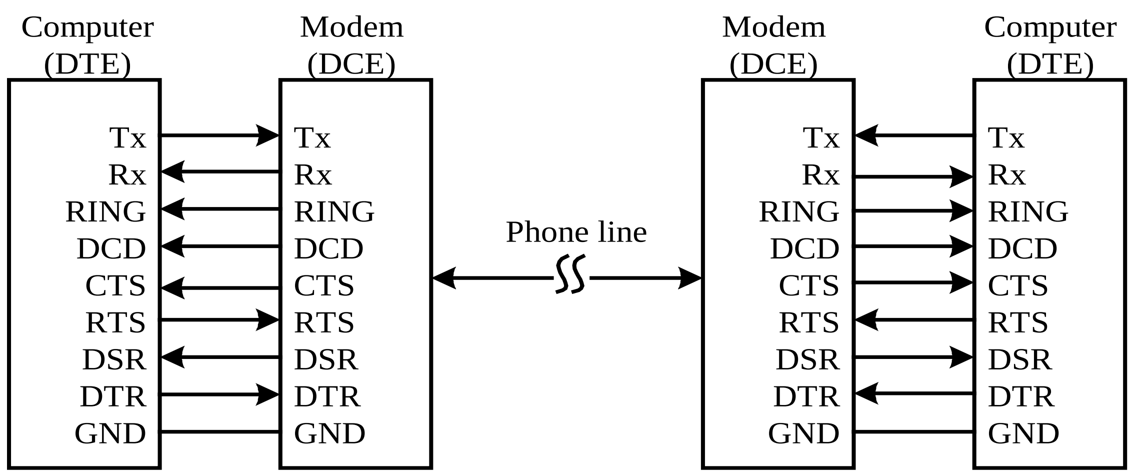


Figure 9.3 Asynchronous connection over public phone line

Local (transmission side) | Remote (receiving side)

time

Connection establishment phase

1. DTE asserts DTR

2. DCE dials the phone number

3. DCE detects the ring and asserts RING

4. DTE asserts DTR to accept the call

5. DCE sends out a carrier and asserts DSR

6. DCE asserts DSR and DCD and also sends out a carrier for full duplex operation

7. DCE asserts DCD (full duplex operation)

Sequence of events occur during data transmission (continued)

Local (transmission side)	Remote (receiving side)

time

Data transmission phase

1. DTE asserts RTS
2. DCE asserts CTS
3. DTE sends out data to DCE
4. DCE modulates data and sends it out
5. DCE demodulates data and forwards the data to DTE
6. DTE receives data

Disconnection phase

1. DTE drops RTS
2. DCE drops CTS and drops the carrier
3. DCE deasserts DCD & DSR
4. DTE deasserts DTR

Data Format

- Data is transmitted character by character.
- Each character is preceded by a start bit, followed by seven to nine data bits, and terminated by one to two stop bits.
- The receiver uses a clock signal with a frequency that is a multiple (usually 16) of the data rate to sample the incoming data in order to detect the arrival of start bit and determine the bit values.
- A majority circuit takes three samples (bit 7, 8, and 9) in each bit time to detect the arrival of the start bit and determine the logic value of each data bit.
- In older designs, a character can be terminated by one, one and a half, two stop bits.
- In new designs, only one stop bit is used.

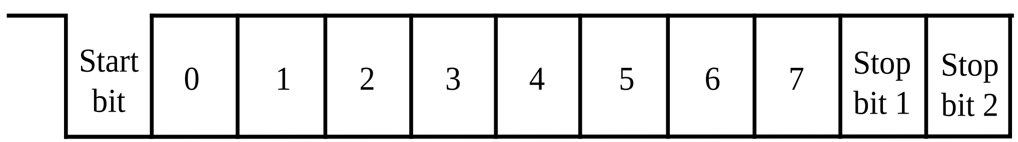
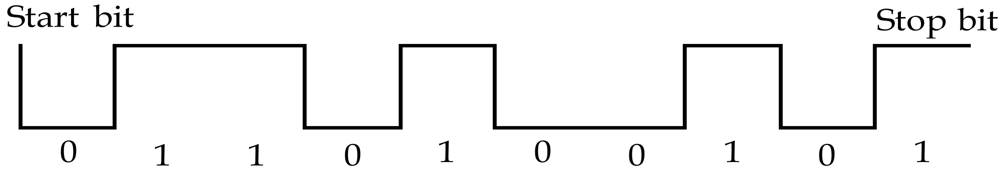
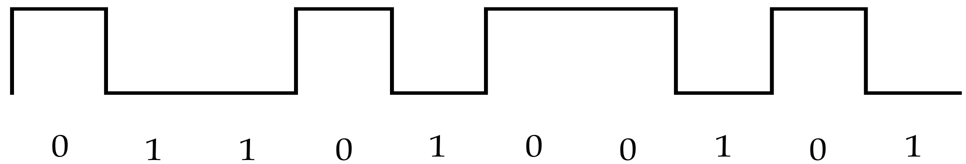


Figure 9.4 The format of a character

Example 9.1 Sketch the output of the letter K when it is transmitted using the format of one start bit, eight data bits, and one stop bit.
Solution: Letters are represented in ASCII code. The ASCII code of letter **K** is \$4B (= 01001011). The format of the output of letter **K** is shown in Figure 9.6.



(a) output waveform at microcontroller interface



(b) output waveform at EIA232E interface

Figure 9.6 Data format for letter **k**

Data Transmission Errors

1. Framing error
   - May occur due to clock synchronization problem
   - Can be detected by the missing stop bit
2. Receiver overrun
   - May occur when the CPU did not read the received data for a while
3. Parity errors
   - Occur due to odd number of bits change values

Null Modem Connection

- Used when two DTEs are located side by side and use the EIA232 interface to exchange data.
- Null modem connection connects signals in such a way to full two DTEs to think that they connected through a modem.
- In Figure 9.7, the signals on the same row of DTE1 and DTE2 are connected together.
- The cost of two modems are saved with Null modem connection.

Signal Name	DTE 1		DTE 2		Signal Name
	DB25 pin	DB9 pin	DB9 pin	DB25 pin	
FG (frame ground)	1	-	-	1	FG
TD (transmit data)	2	3	2	3	RD
RD (receive data)	3	2	3	2	TD
RTS (request to send)	4	7	8	5	CTS
CTS (clear to send)	5	8	7	4	RTS
SG (signal ground)	7	5	5	7	SG
DSR (data set ready)	6	6	4	20	DTR
CD (carrier detect)	8	1	4	20	DTR
DTR (data terminal ready)	20	4	1	8	CD
DTR (data terminal ready)	20	4	6	6	DSR

Figure 9.7 Null Modem connection

The PIC18 Serial Communication Interface

- A serial communication interface can be called a USART or UART.
- A USART supports both synchronous and asynchronous modes of operation.
- A PIC18 device supports either one or two identical USARTs.
- The USART port can be used to communicate with a CRT terminal, a personal computer, A/D converter, D/A converter, and serial EEPROMs.
- The USART can operate in three modes:

1. Asynchronous mode (full duplex)
2. Synchronous—master (half duplex)
3. Synchronous—slave (half duplex)

USART-Related Pins

- RC6/TX1/CK1 and RC7/RX1/DT1 (USART1)
- RG1/TX2/CK2 and RG2/TX2/DT2 (USART2)

USART-Related Registers

- Transmit status register (TXSTA)
- Transmit register (TXREG)
- Receive status register (RCSTA)
- Receive register (RCREG)
- Baud rate generate register (SPBRG)

	7	6	5	4	3	2	1	0
	CSRC	TX9	TXEN	SYNC	--	BRGH	TRMT	TX9D
Value after reset	0	0	0	0	0	0	1	0

CSRC: Clock Source Select bit
Asynchronous mode: (don't care)
Synchronous mode:
0 = Slave mode (clock from external source)
1 = Master mode (clock generated internally from BRG)
TX9: 9-bit Transmit Enable bit
0 = selects 8-bit transmission
1 = selects 9-bit transmission
TXEN: Transmit Enable Bit
0 = Transmit disabled
1 = Transmit enabled
SYNC: USART Mode Select Bit
0 = Asynchronous mode
1 = Synchronous mode
BRGH: High Baud Rate Select Bit
Asynchronous mode:
0 = low speed
1 = high speed
Synchronous mode (unused)
TRMT: Transmit Shift Register Status Bit
0 = TSR full
1 = TSR empty
TX9D: 9th bit of transmit data
Can be Address/Data bit or a parity bit

Figure 9.8 The TXSTA Register (redraw with permission of Microchip)

	7	6	5	4	3	2	1	0
	SPEN	RX9	SREN	CREN	ADDEN	FERR	OERR	RX9D
Value after reset	0	0	0	0	0	0	1	0

SPEN: Serial Port Enable bit
0 = Serial port disabled
1 = Serial port enabled
RX9: 9-bit Receive Enable bit
0 = Selects 8-bit reception
1 = Selects 9-bit reception
SREN: Single Receive Enable bit
Asynchronous mode (don't care)
Synchronous mode - Master (This bit is cleared after reception is complete):
0 = Disables single receive
1 = Enables single receive
Synchronous mode - Slave: (don't care)
CREN: Continuous Receive Enable bit
Asynchronous mode:
0 = Disables receiver
1 = Enables receiver
Synchronous mode:
0 = Disables continuous receive
1 = Enables continuous receive (CREN overrides SREN)
ADDEN: Address Detect Enable bit
Asynchronous mode 9-bit (RX9 = 1):
0 = Disables address detection, all bytes are received, and 9th bit can be used as parity bit.
1 = Enables address detection, enable interrupt and load of the receive buffer when RSR<8> is set
FERR: Framing Error bit
0 = no framing error
1 = Framing error
OERR: Overrun Error bit
0 = No overrun error
1 = Overrun error (can be cleared by clearing bit CREN)
RX9D: 9th bit of Received Data
This can be Address/Data bit or a parity bit, and must be calculated by firmware.

Figure 9.9 The RXSTA Register (redraw with permission of Microchip)

- The shift clock for the USART is generated by the **baud rate generator (SPBRG).**
- In asynchronous mode, the BRGH bit of the TXSTA register also involves in the baud rate computation.
- The baud rate is computed using the formula shown in Table 9.2.

Table 9.2 Formula for baud rate

SYNC bit	BRGH = 0 (low speed)	BRGH = 1 (high speed)
0	(Asynchronous) Baud rate = $F_{OSC}/(64(X+1))$	Baud Rate = $F_{OSC}/(16(X+1))$
1	(Synchronous) Baud Rate = $F_{OSC}/(4(X+1))$	N/A

Note. X is the content of the SPBRG register

In asynchronous mode:

When BRGH = 1, SPBRG = (F_{OSC}/(16 x baud rate)) - 1

When BRGH = 0, SPBRG = (F_{OSC}/(64 x baud rate)) - 1

In synchronous mode:

SPBRG = (FOSC/(4 x baud rate)) - 1

Example 9.2 Compute the value to be written into the SPBRG register to generate 9600 baud for asynchronous mode high-speed transmission assuming the frequency of the crystal oscillator is 20 MHz.

Solution: The value (for BRGH = 1) to be written into the SPBRG register is

$$SPBRG = 20 \times 10^6 \div (16 \times 9600) - 1 = 130 - 1 = 129$$

The actual baud rate is

$$20{,}000{,}000 \div (16 \times 130) = 9615.4$$

The resultant error rate is $(9615.4 - 9600) \div 9600 \times 100\% = 0.16\%$.

The same baud rate can also be achieved by using low speed (BRGH = 0) approach in which

$$SPBRG = 20{,}000{,}000 \div (64 \times 9600) - 1 = 31$$

The actual baud rate is

$$20000000 \div (64 \times 32) = 9765.6$$

The resultant error rate is $(9765.6 - 9600) \div 9600 \times 100\% = 1.7\%$.

Example 9.3 Write a subroutine to configure the USART1 transmitter to transmit data in asynchronous mode using 8-bit data format, disable interrupt, set baud rate to 9600. Assume the frequency of the crystal oscillator is 16 MHz.

Solution:

- Write the value of 0x24 into the TXSTA1 register
- Configure TX1 pin for output, RX1 pin for input:

```
usart1_open movlw   0x24
            movwf   TXSTA1
            movlw   D'103'          ; set baud rate to 9600
            movwf   SPBRG1          ;          "
            bsf     TRISC,RC7       ; configure RX1 pin for input
            bcf     TRISC,RC6       ; configure TX1 pin for output
            bcf     PIE1,TXIE       ; disable transmit interrupt
            bsf     RCSTA1,SPEN     ; enable USART1
            return
```

In C language,

```
void usart1_open(void)
{
	TXSTA1		= 0x24;
	SPBRG1		= 103;
	TRISCbits.RC7		= 1;	/* configure RX1 pin for input */
	TRISCbits.RC6		= 0;	/* configure TX1 pin for output */
	PIE1bits.TXIE  = 0;	/* disable transmit interrupt */
	RCSTA1bits.SPEN = 1;	/* enable USART port */
}
```

Example 9.4 Write a subroutine to output the character in WREG to USART1 using the polling method.

Solution:

- Data can be sent to the transmitter only when the transmit register is empty.

```
putc_usart1     btfss   PIR1,TXIF,A ; wait until TXIF flag is set before output
                bra     putc_usart1
                movwf   TXREG1
                return
```

In C language,

```
void putc_usart1 (char xc);
{
    while (!PIR1bits.TX1IF);
    TXREG1 = xc;
}
```

Example 9.5 Write a subroutine to output a string (in program memory) pointed to by TBLPTR and terminated by a NULL character from USART1.
Solution:

```
; ***************************************************************
; The following subroutine outputs the string pointed to by TBLPTR. It is called
; with fast save enabled.
; ***************************************************************
puts_usart1          TBLRD*+        ; read one character into TABLAT
          movf       TABLAT,W,A     ; place the character in WREG
          bz         done           ; is it a NULL character?
          call       putc_usart1    ; not NULL, output
          bra        puts_usart1    ; continue
done      return     fast
```

In C language,

```
void puts_usart1 (unsigned rom char *cptr)
{
    while(*cptr)
          putc_usart1 (*cptr++);
}
```

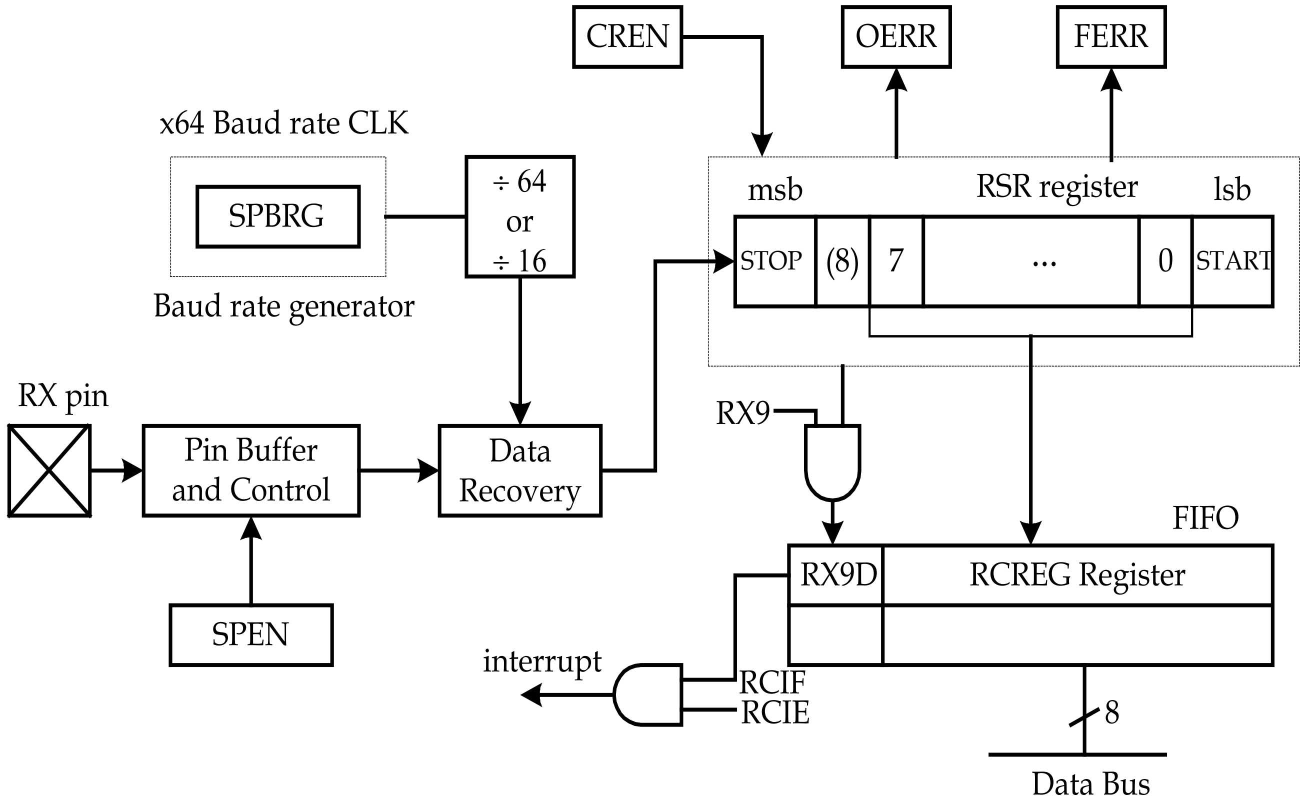


Figure 9.11 USART receive block diagram (redraw with permission of Microchip)

Example 9.6 Write an instruction sequence to configure the USART1 to receive data in asynchronous mode using 8-bit data format, disable interrupt, set baud rate to 9600. Assume that the frequency of the crystal oscillator is 16 MHz.
Solution:

```
movlw    0x90            ; enable USART1 and receiver
movwf    RCSTA1,A
movlw    D'103'
movwf    SPBRG1,A        ; set up baud rate to 9600
bsf      TRISC,RX1,A     ; configure RX1 pin for input
bcf      TRISC,TX1,A     ; configure TX1 pin for input
```

In C language,

```
RCSTA1  = 0x90;
SPBRG   = 103;
TRISC   |= 0x80;         /* configure RC7/RX1 pin for input */
TRISC   &= 0xBF          /* configure RC6/TX1 pin for output */
```

Example 9.7 Write a subroutine to read a character from USART1 and return the character in WREG using the polling method. Ignore any errors.
Solution: A new character is received if the RCIF flag of the PIR1 register is set to 1.

```
getc_usart1  btfss    PIR1,RCIF      ; make sure a new character has been received
             bra      getc_usart1
             movf     RCREG1,W       ; read the character
             return   FAST
```

In C language,

```
unsigned char getc_usart1 (void)
{
        while (!PIR1bits.RCIF);
        return RCREG1;
}
```

Example 9.8 Write a subroutine to read a string from the USART1 and store the string in a buffer pointed to by FSR0.

Solution:

The string from the USART port is terminated by a carriage return character.

```
CR          equ     0x0D
gets_usart1 call    getc_usart1
            movwf   INDF0           ; save the character in buffer
            sublw   CR
            bz      done
            clrf    PREINC0,F       ; move the pointer
            goto    gets_usart1
done        clrf    INDF0           ; terminate the string with a NULL character
            return
```

In C language,

```
#define    CR   0x0D
void  gets_usart1 (char *ptr)
{
        char xx;
        while (1)
        {
                xx = getc_usart1( );  /* read a character */
                if (xx == CR) {       /* is it a carriage return? */
                        *ptr = '\0';  /* terminate the string with a NULL */
                        return;
                }
                ptr++ = xx;           /* store the received character in the buffer */
        }
}
```

Flow Control of USART in Asynchronous Mode

- In some circumstances, the software cannot read the received data and needs to inform the transmitter to stop.
- In some other situation, the transmitter may need to be told to suspend transmission because the receiver is too busy to read data.
- Both situations are handled by flow control.
- There are two flow control methods: hardware and XON/XOFF.
- XON and XOFF are two standard ASCII characters.
- The ASCII code for XON and XOFF are 0x11 and 0x13, respectively.
- Whenever a microcontroller cannot handle the incoming data, it sends the XOFF to the transmitter.
- When the microcontroller can handle incoming characters, it sends out XON character.

C Library Functions for USART

Table 9.3a Library functions for devices with only one USART

Function	Description
BusyUSART	Is the USART transmitting?
CloseUSART	Disable the USART
DataRdyUSART	Is data available in the USART read buffer?
getcUSART	Read a byte from USART
getsUSART	Read a string from USART
OpenUSART	Configure the USART
putcUSART	Write a byte to the USART
putsUSART	Write a string from data memory to the USART
putrsUSART	Write a string from program memory to the USART
ReadUSART	Read a byte from the USART
WriteUSART	Write a byte to the USART

Table 9.3b Library functions for devices with multiple USARTs

Function	Description
Busy**x**USART	Is the USART **x** transmitting?
Close**x**USART	Disable the USART **x**
DataRdy**x**USART	Is data available in the USART **x** read buffer?
getc**x**USART	Read a byte from USART **x**
gets**x**USART	Read a string from USART **x**
Open**x**USART	Configure the USART **x**
putc**x**USART	Write a byte to the USART **x**
puts**x**USART	Write a string from data memory to the USART **x**
putrs**x**USART	Write a string from program memory to the USART **x**
Read**x**USART	Read a byte from the USART **x**
Write**x**USART	Write a byte to the USART **x**

Note. **x** = 1 or 2

The following functions return a “1” if the transmitted is busy:

char **BusyUSART** (void); -- used on devices with single USART
char **Busy1USART** (void); -- used on devices with two USARTs
char **Busy2USART** (void); -- used on devices with two USARTs

The following functions disable the transmitter and receiver:

void **CloseUSART** (void); -- used on devices with single USART
void **Close1USART** (void); -- used on devices with two USARTs
void **Close2USART** (void); -- used on devices with two USARTs

The following functions return a “1” if the RCIF flag is set:

char **DataRdyUSART** (void); -- used on devices with single USART
char **DataRdy1USART** (void); -- used on devices with two USARTs
char **DataRdy2USART** (void); -- used on devices with two USARTs

Any one of the following functions read a byte from the receive buffer including the 9th bit:

char **getcUSART** (void); -- used on devices with single USART
char **getc1USART** (void); -- used on devices with two USARTs
char **getc2USART** (void); -- used on devices with two USARTs
char **ReadUSART** (void); -- used on devices with single USART
char **Read1USART** (void); -- used on devices with two USARTs
char **Read2USART** (void); -- used on devices with two USARTs

The following functions read the specified number of byes from the USART module and save the string in a buffer:

void **getsUSART** (char *buffer, unsigned len); -- for devices with single USART
char **gets1USART** (char *buffer, unsigned len); -- for devices with two USART
char **gets2USART** (char *buffer, unsigned len); -- for devices with two USART

The status bit and the 9th data bit are saved in a union with the following declaration:

```
union USART
{
	unsigned char val;
	struct
	{
		unsigned RX_NINE: 1;
		unsigned TX_NINE: 1;
		unsigned FRAME_ERROR: 1;
		unsigned OVERRUN_ERROR: 1;
		unsigned fill: 4;
	};
};
```

The following functions write one character to the transmit buffer:

char **putcUSART** (char data); -- used on devices with single USART
char **putc1USART** (char data); -- used on devices with two USARTs
char **putc2USART** (char data); -- used on devices with two USARTs
char **WriteUSART** (char data); -- used on devices with single USART
char **Write1USART** (char data); -- used on devices with two USARTs
char **Write2USART** (char data); -- used on devices with two USARTs

The following functions output a string in program memory to the USART module:

void **putrsUSART** (const rom char *data); -- used on devices with single USART
void **putrs1USART** (const rom char *data); -- used on devices with two USARTs
void **putrs2USART** (const rom char *data); -- used on devices with two USARTs

The following functions output a string in data memory to the USART module:

void **putsUSART** (char *data);-- used on devices with single USART
void **puts1USART** (char *data); -- used on devices with two USARTs
void **puts2USART** (char *data); -- used on devices with two USARTs

The following functions configured the specified USART module:

void **OpenUSART** (unsigned char **config**,
char **spbrg**); -- used on devices with single USART
void **Open1USART** (unsigned char **config**,
char **spbrg**); -- used on devices with two USARTs
void **Open2USART** (unsigned char **config,**
char **spbrg**); -- used on devices with two USARTs

The **config** parameter is defined by ANDing the following parameters:

Interrupt on Transmission:

USART_TX_INT_ON	Transmit interrupt ON
USART_TX_INT_OFF	Transmit interrupt OFF

Interrupt on Reception:

USART_RX_INT_ON	Receive interrupt ON
USART_RX_INT_OFF	Receive interrupt OFF

USART Mode:

USART_ASYNCH_MODE	Asynchronous mode
USART_SYNCH_MODE	Synchronous mode

Transmission Width:

USART_EIGHT_BIT	8-bit transmit/receive
USART_NINE_BIT	9-bit transmit/receive

Slave/Master Select:

USART_SYNC_SLAVE	Synchronous slave mode
USART_SYNC_MASTER	Synchronous master mode

Reception mode:

USART_SINGLE_RX	Single reception
USART_CONT_RX	Continuous reception

Baud rate: (applied to asynchronous mode only)

USART_BRGH_HIGH	High baud rate
USART_BRGH_LOW	Low baud rate

The **spbrg** is the value to be written into the SPBRG register to set the baud rate.

An example,

```
Open1USART (USART_TX_INT_OFF & USART_RX_INT_OFF &
            USART_ASYNCH_MODE & USART_EIGHT_BIT &
            USART_BRGH_HIGH, 103);
```

Interface Asynchronous Mode USART with EIA232

- The USART in asynchronous mode is mainly used with the EIA232 interface.
- The USART module uses 0 and 5V to represent logic 0 and 1 and hence cannot be connected to the EIA232 circuit directly.
- A circuit called EIA232 transceiver is needed to translate the voltage levels of the USART to and from the voltage levels of the EIA232 interface.
- EIA232 transceivers are available from many vendors.
- LT1080/1081 from Linear Technology, ST232 from SGS Thompson, the ICL232 from Intersil, the MAX232 from MAXIM, and the DS14C232 from National Semiconductor are examples of the EIA232 transceiver. These EIA232 transceivers operate with a 5-V power supply.
- The pin assignment of the MAX232 is shown in Figure 9.12.
- The circuit connection of the MAX232 with the PIC18 is shown in Figure 9.13.

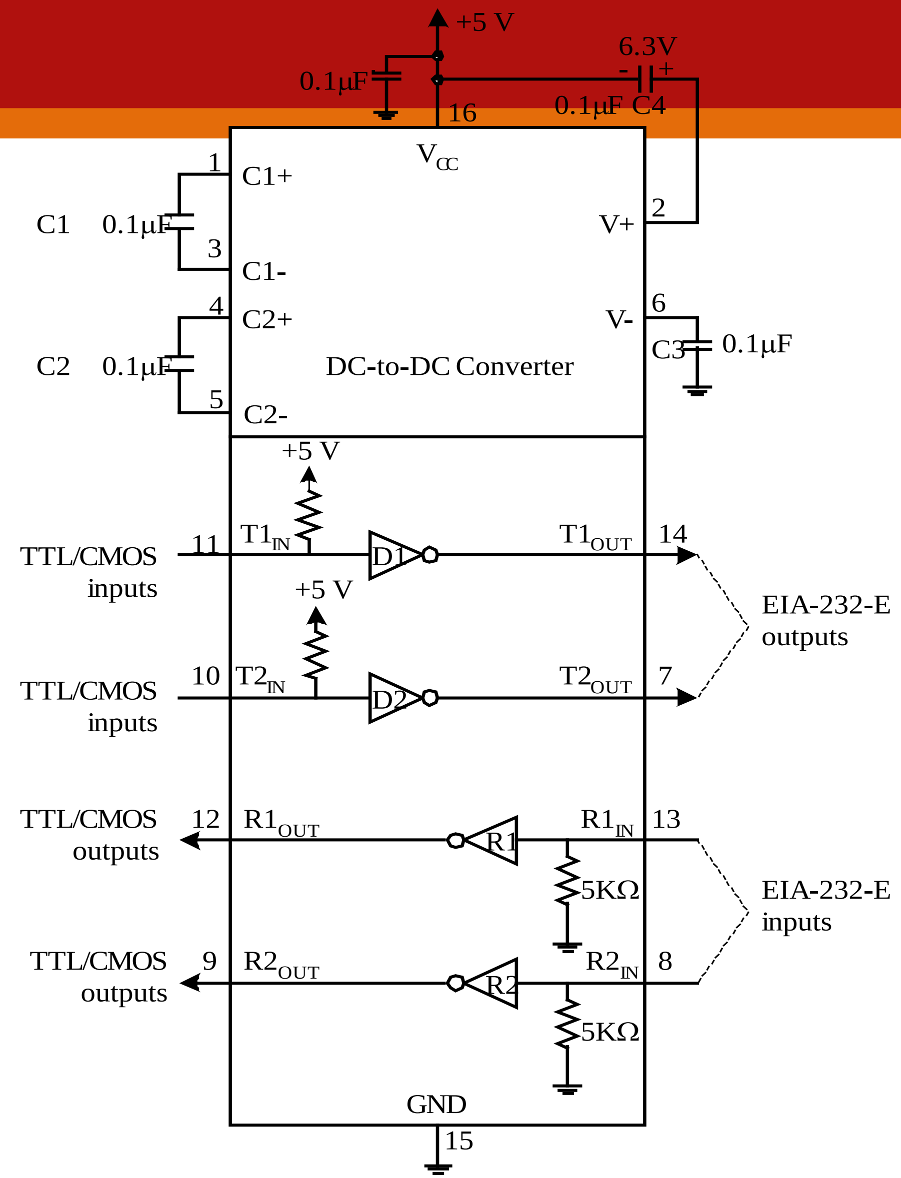
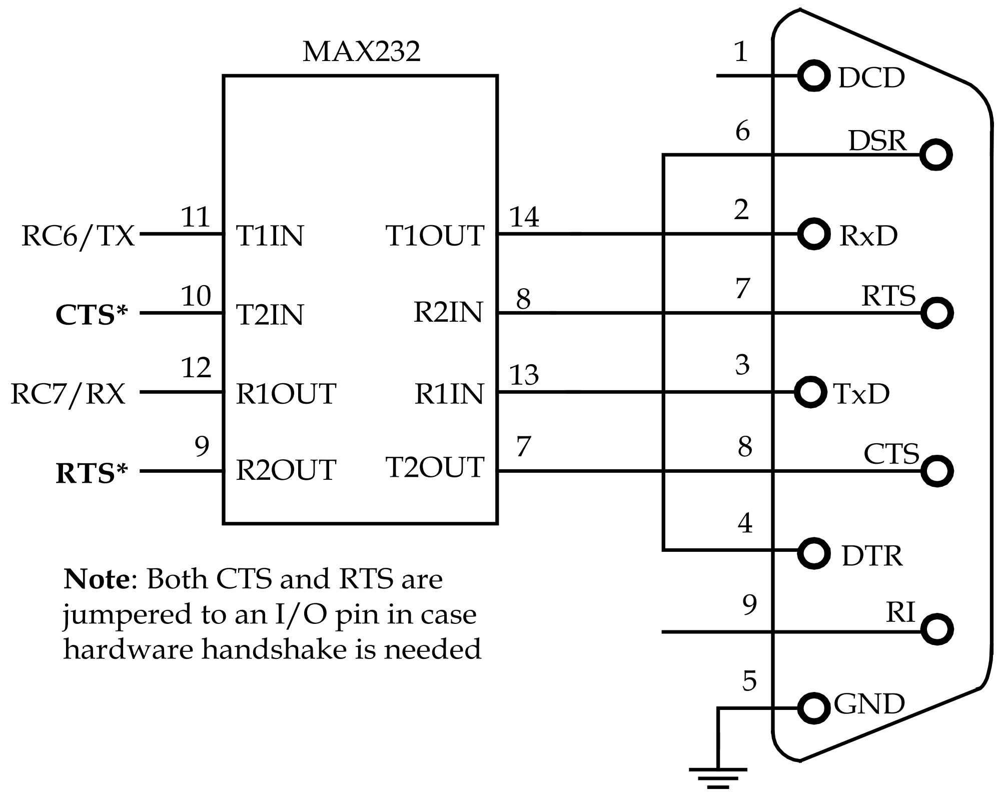


Figure 9.12 Pin assignments and connections of the MAX232A



Note: Both CTS and RTS are jumpered to an I/O pin in case hardware handshake is needed

Figure 9.13 Diagram of USART and EIA232 DB9 connector wiring in SSE452, SSE8680, and SSE8720 demo boards

USART Synchronous Master Mode

- This mode is entered by setting bits SYNC, SPEN and CSRC.
- Data is transmitted in half-duplex mode.
- The clock signal is driven out from the CK pin.

Synchronous Master Transmission

- Setting the TXEN bit enables the USART module, which will start the SPBRG circuit to generate the shift clock.
- The actual data transmission does not start until a byte is written into the TXREG register.
- The data bits are shifted out on the rising edge of CK and becomes stable on the falling edge of the same clock period.

Synchronous Master Reception

- Reception is enabled by setting the SREN or CREN bit.
- Data is sampled on the falling edge of the CK clock.
- If only the SREN bit is set, only one character will be received.
- If the CREN bit is set, the reception will continue until the CREN bit is cleared.

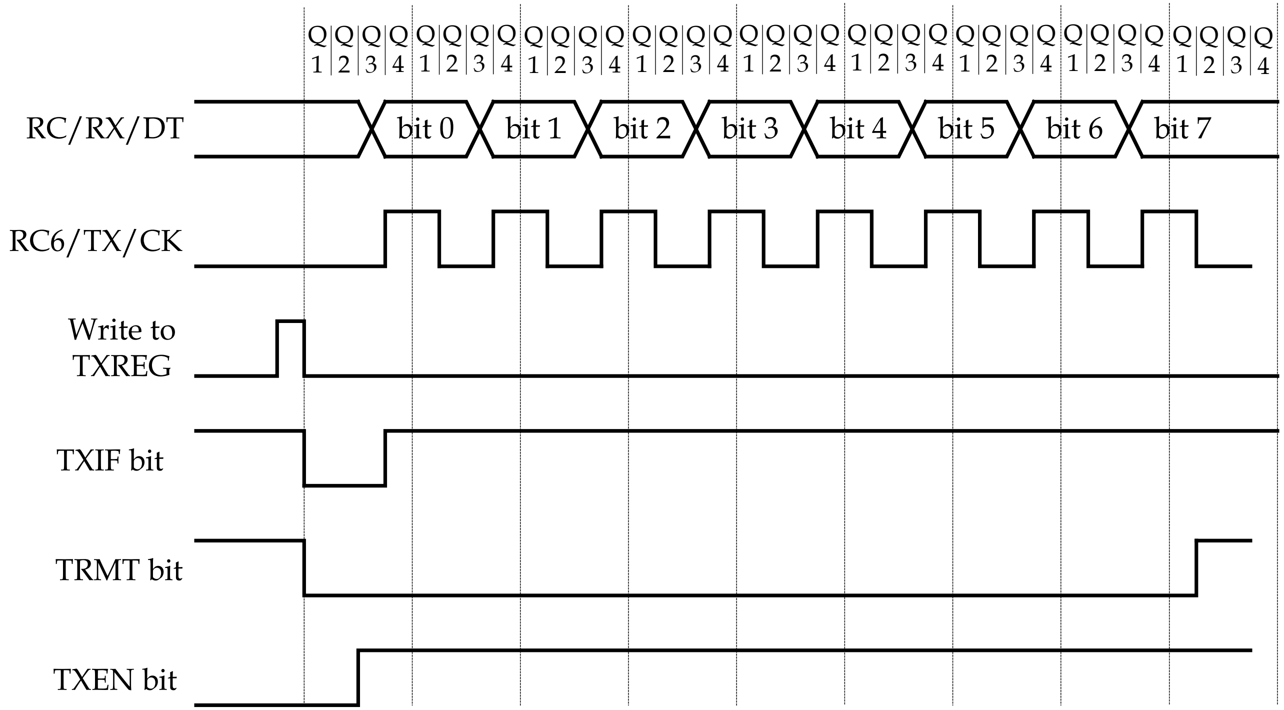


Figure 9.14 USART transmission in synchronous master mode (redraw with permission of Microchip)

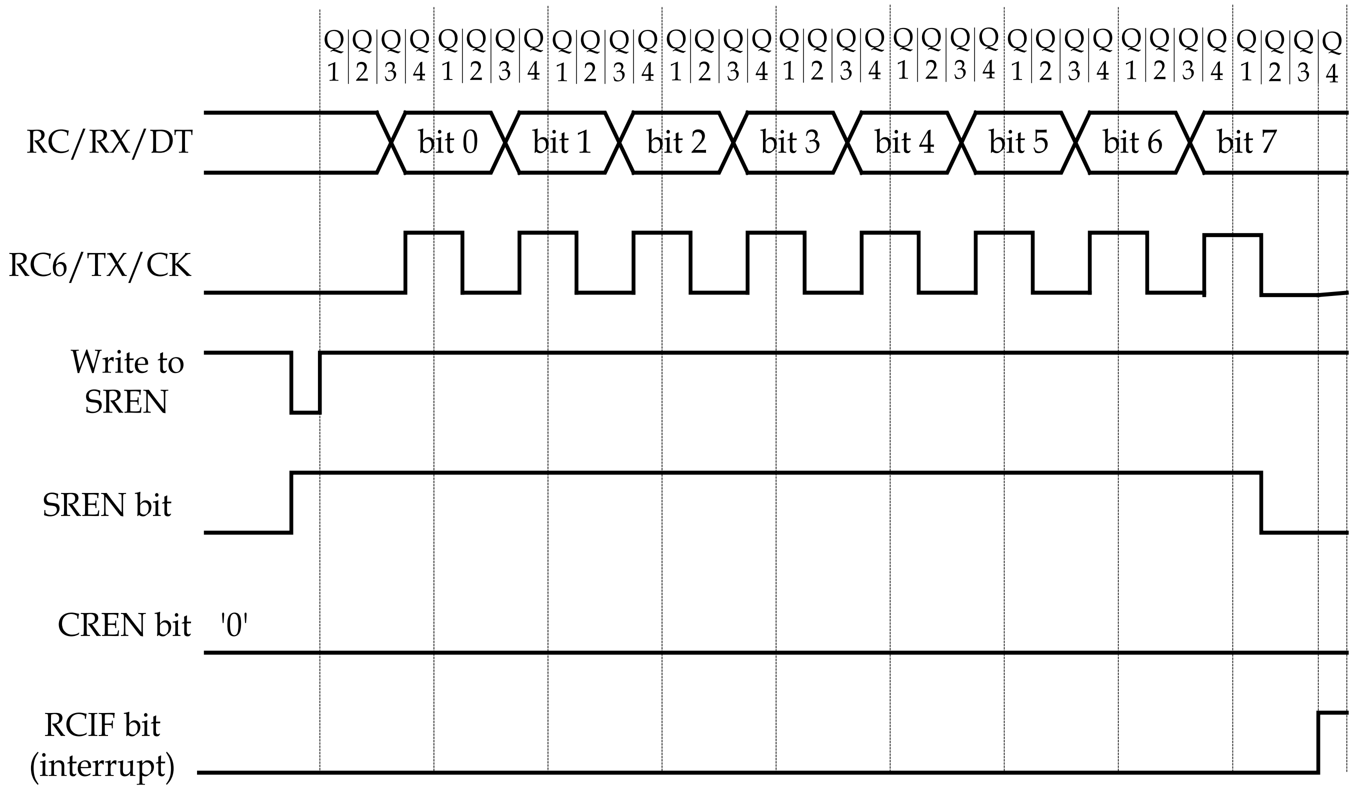


Figure 9.15 USART reception in synchronous master mode (SREN=1)
(redraw with permission of Microchip)

USART Synchronous Slave Mode

- Shift clock is provided by external device and is input to the CK pin.
- Slave mode is entered by setting both the SYNC and SPEN bits and clearing the CSRC bit.

Synchronous Slave Transmission

- The shift clock signal is an input from the CK pin.
- CREN bit must be cleared.
- Transmission is enabled by setting the TXEN bit.
- Transmission is started by loading data into the TXREG register.

Synchronous Slave Reception

- Clock source is an input from the CK pin.
- When the RCIF flag is set, read the RCREG register to get the lower 8 bits.
- If 9-bit reception is enabled, then read the 9th bit from the RCSTA register.
- If there is any error, then clear the error by clearing the CREN bit.

Applications of USART Synchronous Mode

- Interfacing with shift registers to expand the number of I/O ports.
- Exchange data with other PIC18 microcontrollers

The 74LS165 Shift Register

- Has parallel inputs P7…P0 to be loaded into 74LS165 when PL is low.
- Data is shifted in from the DS pin when the PL input is high, one clock input is high, and the second clock input has a rising edge.
- Data is shifted out from Q7, which allows multiple 74LS165 to be concatenated.

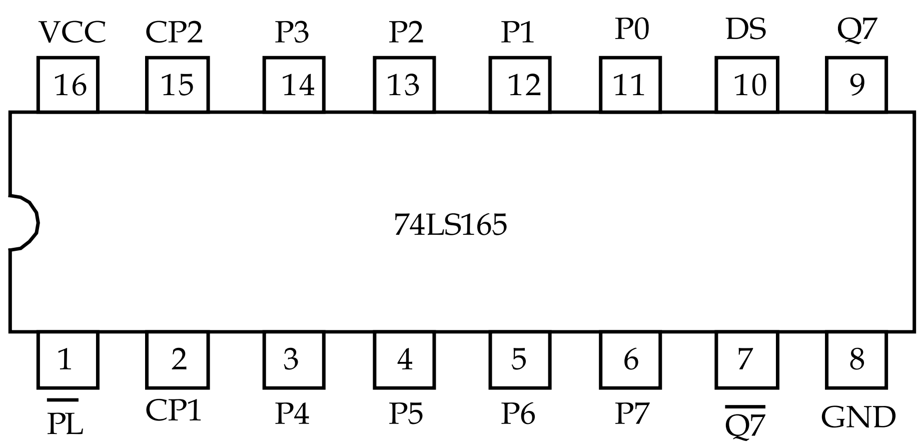


Figure 9.16 74LS165 pin assigment

Table 9.4 Truth table of 74LS165

PL	CP		Contents								Response
	1	2	Q0	Q1	Q2	Q3	Q4	Q5	Q6	Q7	
L	X	X	P0	P1	P2	P3	P4	P5	P6	P7	Parallel load
H	L	↑	DS	Q0	Q1	Q2	Q3	Q4	Q5	Q6	right shift
H	H	↑	Q0	Q1	Q2	Q3	Q4	Q5	Q6	Q7	no change
H	↑	L	DS	Q0	Q1	Q2	Q3	Q4	Q5	Q6	right shift
H	↑	H	Q0	Q1	Q2	Q3	Q4	Q5	Q6	Q7	no change

Example 9.9 Show the circuit connection for using one 74LS165 to add an input port to the PIC18F8720 using the USART2 in synchronous master mode. Write a subroutine to configure the USART2 properly and a subroutine to shift one byte of data assuming that the PIC18F8720 is running with a 16-MHz crystal oscillator. Assume that the user uses eight switches to set the value to be input and uses INT1 interrupt to inform the arrival of data.

Solution:

1. Use the synchronous master mode to interface with the 74LS165.
2. Configure RG2/DT2 and RG1/CK2 for input and output, respectively.
3. Set baud rate to 1 Mbps
4. Enable INT1 interrupt
5. Circuit connection is shown in Figure 9.17.

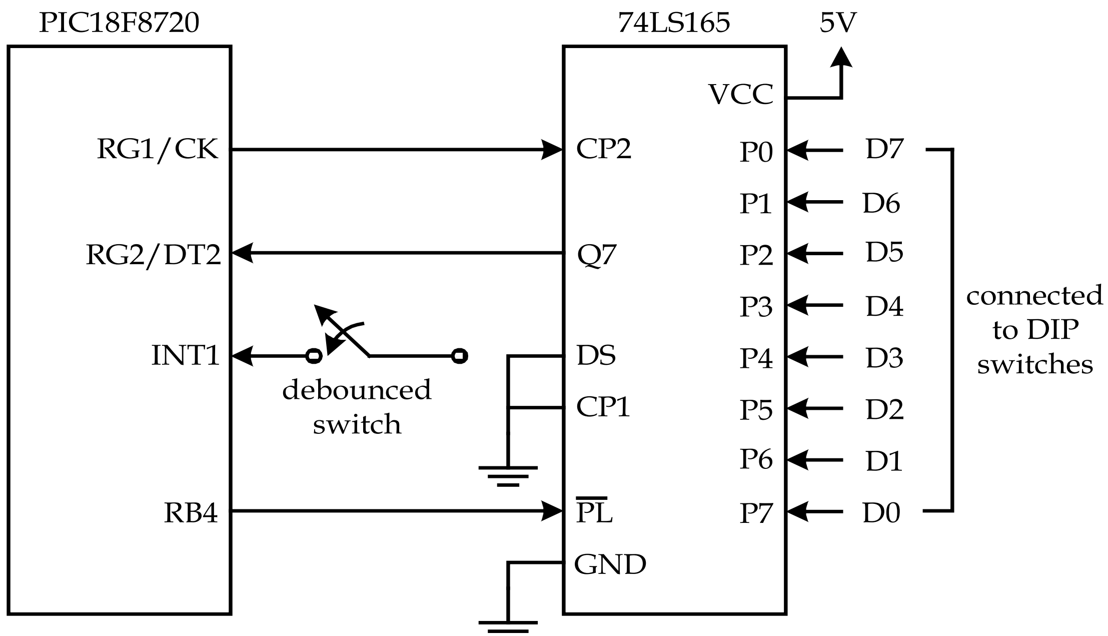


Figure 9.17 Circuit connection between the PIC18F8720 and 74LS165

Procedure for inputting data from 74LS165

1. Set up a new value to P0 to P7 using the DIP switches.
2. Press the debounced switch to request an interrupt using the INT1 pin.
3. The INT1 interrupt service routine reads in the data from the RCREG2.

```
        #include  <p18F8720.inc>
rcv_buf set       0             ; buffer to hold the received byte
        org       0x00
        goto      start
        org       0x08
        goto      hi_ISR
        org       0x18
        retfie
start   bcf       TRISG,RG1,A   ; configure CK2 pin for output
        bsf       TRISG,RG2,A   ; configure DT2 pin for input
        call      open_usart2
        call      open_INT1
forever nop
        bra       forever
```

```
; ******************************************************************
; The following function configures USART2 to operate in
; synchronous master mode with baud rate set to 10**6.
; ******************************************************************
open_usart2       movlw      0x03
        movwf      SPBRG2,A        ; set the shift rate to 1MHz
        movlw      0x90            ; set synchronous master mode
        movwf      TXSTA2,A        ;           "
        movlw      0x80            ; enable USART2 and disable
        movwf      RCSTA2,A        ; reception
        return
; *************************************************************************
; The following subroutine configures INT1 to high priority and
; then enable its interrupt.
; *************************************************************************
open_INT1  bsf     RCON,IPEN,A     ; enable priority interrupt
        movlw      0x48            ; set INT1 interrupt to high priority,
        movwf      INTCON3,A       ; and then enable INT1 interrupt
        movlw      0xC0            ; enable global interrupt
        movwf      INTCON          ;           "
        return
```

```
; ****************************************************************************
; The high priority interrupt service routine makes sure
; that the interrupt is caused by usart2 INT1IF and then enable
; reception by setting SPEN bit. Wait until a byte is received.
; ****************************************************************************
hi_ISR  btfss   INTCON3,INT1IF,A ; is interrupt caused by INT1?
        retfie                   ; interrupt is not caused by INT1
        bcf     INTCON3,INT1IF,A ; clear INT1IF
        bcf     PORTB,RB4,A      ; load data into 74LS165
        nop                      ;              "
        bsf     PORTB,RB4,A      ; disable new data into 74LS165
        bcf     PIR3,RC2IF,A     ;
        bsf     RCSTA2,SREN,A    ; enable single reception from USART2
wait    btfss   PIR3,RC2IF,A     ; wait for the arrival of a byte
        bra     wait
        movff   RCREG2,rcv_buf
        retfie
        end
```

The 74LS164 Shift Register

- Has parallel outputs and two serial inputs
- Pin assignment and truth table are shown in Figure 9.18 and Table 9.5, respectively.

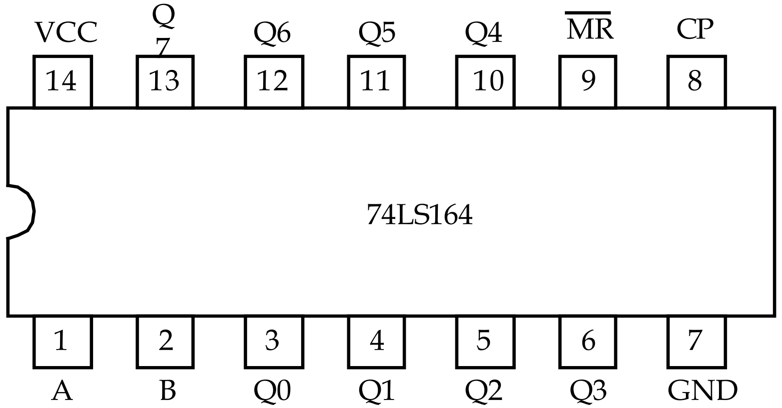


Figure 9.18 74LS164 pin assigment

Table 9.5 Truth table of 74LS164

Operating Mode	Inputs			Outputs	
	$\overline{MR}$	A	B	Q0	Q1 - Q7
Reset (clear)	L	X	X	L	L - L
Shift	H	L	L	L	Q0 - Q6
	H	L	H	L	Q0 - Q6
	H	H	L	L	Q0 - Q6
	H	H	H	H	Q0 - Q6

Example 9.10 Show the circuit connection if you are to use one 74LS164 to add an output port to the PIC18F8720 using the USART2 module in synchronous master mode. Write a subroutine to shift out one byte of data assuming that the PIC18F8720 is running with a 16-MHz crystal oscillator. The user may uses Q7..Q0 to drive LEDs.

Solution: The circuit connection is shown in Figure 9.19. Q7…Q0 should be used as the least significant bit to the most significant bit.

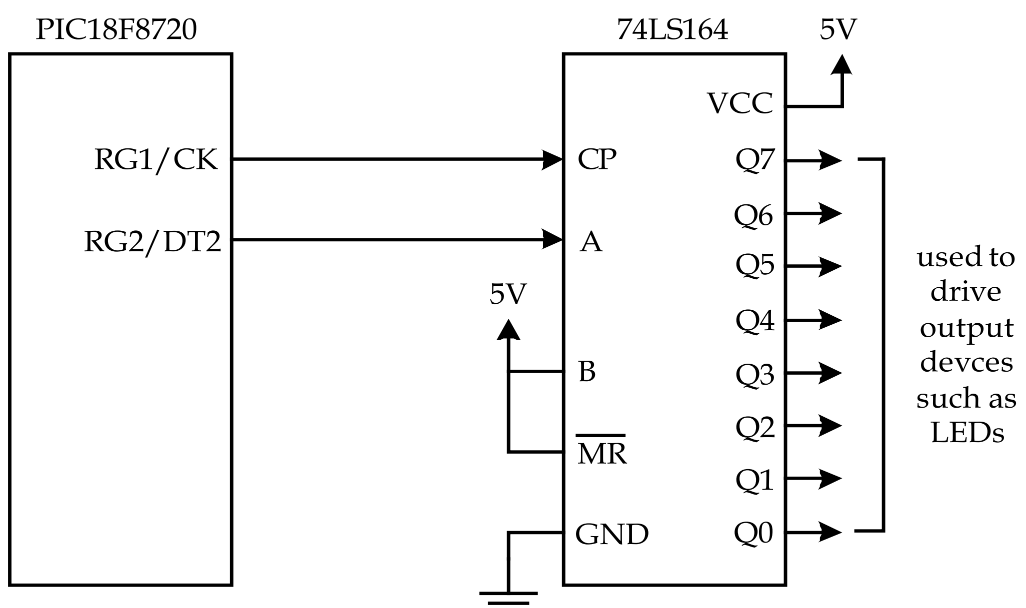


Figure 9.19 Circuit connection between the PIC18F8720 and 74LS164

The following subroutine outputs the character in WREG to the USART2:

```
outc_usart2 bsf     RCSTA2,SPEN     ; enable USART2 port pins
poll2       btfss   PIR3,TX2IF,A    ; is TX2IF flag set?
            bra     poll2
            movwf   TXREG2,A
            return
```

Using the USART Synchronous Mode to Exchange Data with other PIC18 MCUs

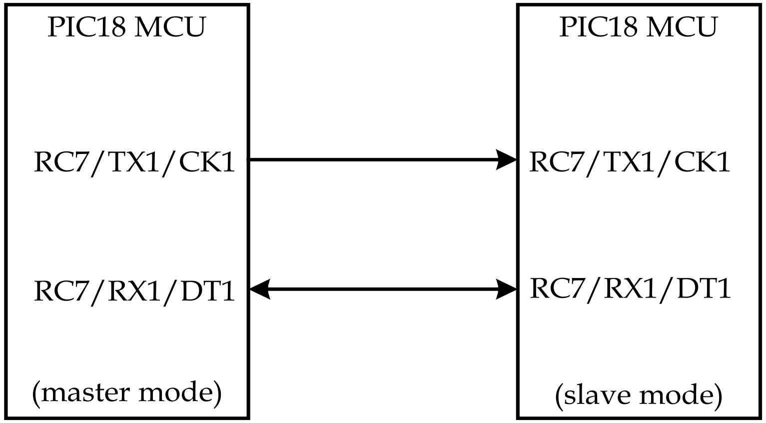


Figure 9.20 Two PIC18s exchange data using USART synchronous mode

Enhanced USART

- Newer PIC18 devices add some enhancements to the USART port:

    1. Automatic baud rate detection and calibration
    2. Sync break reception
    3. 12-bit break character transmit
    4. A baud rate control register (BAUDCONx, x = 1, or 2) is added for additional baud control

- These additional features can be used to support the LIN protocol