

Linked Lists



Data Structures

Ching-Fang Hsu

Department of Computer Science and Information Engineering

National Cheng Kung University

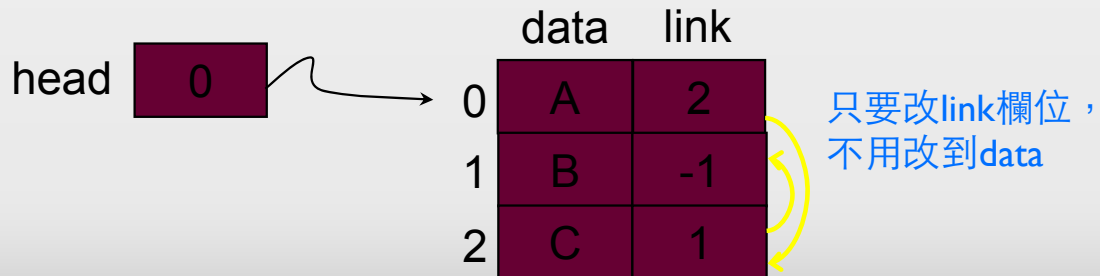
Why Lists?

❖ Problems of ordered lists implemented by arrays

- ❑ Data movement

使用array模擬
linked list

- ❑ Although the data movement problem can be avoided by implementing an ordered list by two arrays, memory management problem still exists.

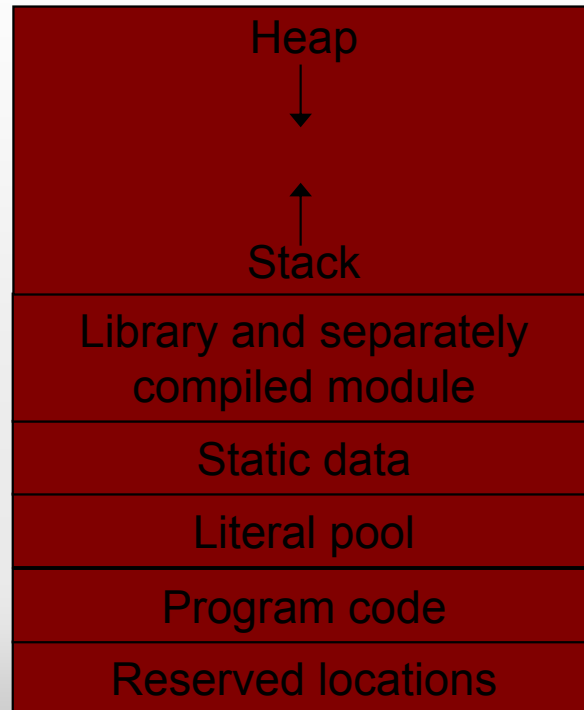


Pointers

- ❖ For any type T in C there is a corresponding type pointer-to- T .
- ❖ The actual value of a pointer type is **an address of memory**.
 - ❑ **&**: the **address operator** + variable
取出來是一個位置
 - ❑ *****: the **dereferencing** (or indirection) operator + address
Return出來是 data value
- ❖ Accessing dynamically allocated storage (i.e., heap)

Pointers (contd.)

❖ A typical program layout in memory



Pointers (contd.)

使用ptr需注意的問題

❖ Pointer problems

懸置指標：指標指到一個不存在任何有意義資訊的記憶體空間（不應該再去存取的ptr，下次再做dereferencing 將會取到錯誤的值）

❑ Dangling pointers problem

- ◆ A dangling pointer is a pointer that contains the address of a heap-dynamic variable that has been deallocated.

❑ Memory leakage

- ◆ This problem occurs when an allocated heap-dynamic variable is no longer accessible to the user program.

memory leakage :

如果 allocate 出來了之後、在沒有指標去指到那塊記憶體空間、又沒有做對應的 free 的情況下，就會產生「記憶體還是佔在那邊，但是卻沒有辦法使用、也沒辦法釋放」的問題

Pointers (contd.)

Pointer `p1` is set to point at a new heap-dynamic variable.



Pointer `p2` is assigned `p1`'s value.



The heap-dynamic variable pointed to by `p1` is explicitly deallocated, but `p2` is not changed by this operation.



`p2` is a dangling pointer.

Pointers (contd.)

Pointer `p1` is set to point to a newly heap-dynamic variable.



`p1` is later set to point to another newly created heap-dynamic variable.



The first heap-dynamic variable is inaccessible, or lost.

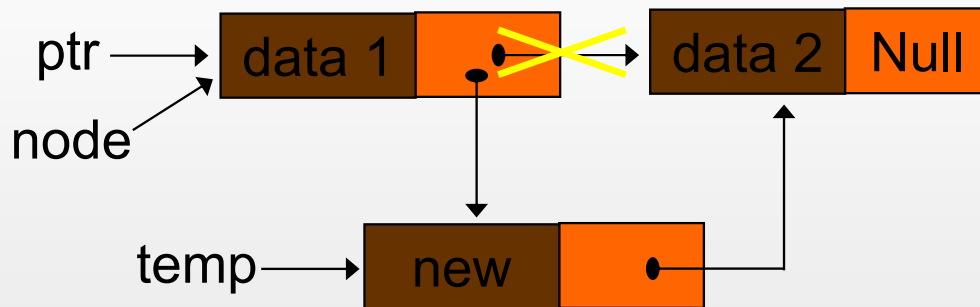
Singly Linked Lists

讓使用者可以去規範的node

- ❖ Each node on a singly linked list consists of exactly one link field and at least one other field (p.147, Fig. 4.2).
- ❖ Necessary capabilities to make linked representations possible
 - ❑ A mechanism for defining a node's structure
 - ❑ A way to create new nodes when we need them
 - ◆ *malloc* in C 凡是使用node記得做記憶體의釋放
 - ❑ A way to remove nodes that we no longer need
 - ◆ *free* in C

Singly Linked Lists -- Operations

❖ Insertion (p. 153, Program 4.2)



長度為3的linked list



Figure 4.2: Usual way to draw a linked list

```
void insert(listPointer *first, listPointer x)
/* insert a new node with data = 50 into the chain
   first after node x */
listPointer temp;
MALLOC(temp, sizeof(*temp));
temp->data = 50;
if (*first) {
    temp->link = x->link;
    x->link = temp;
}
else {
    temp->link = NULL;
    *first = temp;
}
}
```

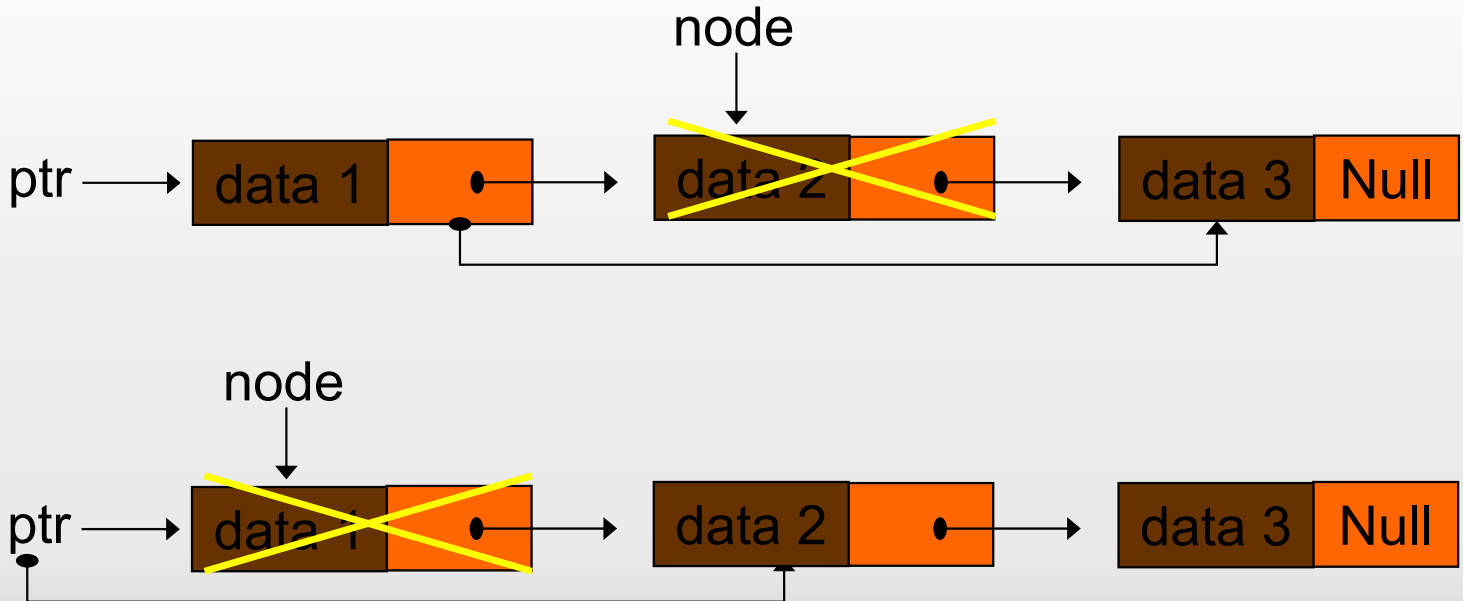
Program 4.2: Simple insert into front of list

```
void delete(listPointer *first, listPointer trail,
            listPointer x)
/* delete x from the list, trail is the preceding node
   and *first is the front of the list */
if (trail)
    trail->link = x->link;
else
    *first = (*first)->link;
free(x);
}
```

Program 4.3: Deletion from a list

Singly Linked Lists -- Operations (contd.)

❖ Deletion (p. 155, Program 4.3)



Dynamically Linked Stacks and Queues

❖ Stacks

- ❑ Structure definitions (p. 156)

- ❑ The initial condition 初始化，去做設定

 - ◆ $top[i] = NULL, 0 \leq i \leq MAX_STACKS$ 比較使用array去做存取stack

- ❑ Boundary conditions 判斷邊界

 - ◆ $top[i] = NULL$ iff the i th stack is empty, and

 - ◆ the memory is full 嘗試去做memory allocation，如果有free memory會return回ptr，如果滿了會回傳error message

- ❑ Push operation (p.158, Program 4.5)

- ❑ Pop operation (p.158, Program 4.6)

```

#define MAX_STACKS 10 /* maximum number of stacks */
typedef struct {
    int key;
    /* other fields */
} element;
typedef struct stack *stackPointer;
typedef struct stack {
    element data;
    stackPointer link;
};
stackPointer top[MAX_STACKS];

```

```

void push(int i, element item)
{ /* add item to the ith stack */
    stackPointer temp;
    MALLOC(temp, sizeof(*temp));
    temp->data = item;
    temp->link = top[i];
    top[i] = temp;
}

```

Program 4.5: Add to a linked stack

```

element pop(int i)
{ /* remove top element from the ith stack */
    stackPointer temp = top[i];
    element item;
    if (!temp)
        return stackEmpty();
    item = temp->data;
    top[i] = temp->link;
    free(temp);
    return item;
}

```

Program 4.6: Delete from a linked stack

Dynamically Linked Stacks and Queues (contd.)

❖ Queues

- ❑ Structure definitions (p. 158)
- ❑ The initial condition 初始化
 - ◆ $front[i] = NULL, 0 \leq i \leq MAX_QUEUES$
- ❑ Boundary conditions
 - ◆ $front[i] = NULL$ iff the i th queue is empty, and
 - ◆ the memory is full
- ❑ Insertion (p.159, Program 4.7)
- ❑ Deletion (p.160, Program 4.8)

```

#define MAX_QUEUES 10 /* maximum number of queues */
typedef struct queue *queuePointer;
typedef struct queue {
    element data;
    queuePointer link;
};
queuePointer front[MAX_QUEUES], rear[MAX_QUEUES];

```

```

void addq(i, item)
/* add item to the rear of queue i */
{
    queuePointer temp;
    MALLOC(temp, sizeof(*temp));
    temp->data = item;
    temp->link = NULL;
    if (front[i])
        rear[i]->link = temp;
    else
        front[i] = temp;
    rear[i] = temp;
}

```

Program 4.7: Add to the rear of a linked queue

```

element deleteq(int i)
/* delete an element from queue i */
{
    queuePointer temp = front[i];
    element item;
    if (!temp)
        return queueEmpty();
    item = temp->data;
    front[i] = temp->link;
    free(temp);
    return item;
}

```

Program 4.8: Delete from the front of a linked queue

Polynomials

❖ Each polynomial term can be defined as

coef	expon	link
------	-------	------

❖ Adding polynomials

□ Three cost measures

- ◆ Coefficient additions
- ◆ Exponent comparisons
- ◆ Creation of new nodes

□ Time complexity $O(m + n)$, assuming that the two polynomials have m and n terms, respectively

- ◆ p. 163~164, Program 4.9 and 4.10


```

polyPointer padd(polyPointer a, polyPointer b)
/* return a polynomial which is the sum of a and b */
polyPointer c, rear, temp;
int sum;
MALLOC(rear, sizeof(*rear));
c = rear;
while (a && b)
    switch (COMPARE(a->expon, b->expon)) {
        case -1: /* a->expon < b->expon */
            attach(b->coef, b->expon, &rear);
            b = b->link;
            break;
        case 0: /* a->expon = b->expon */
            sum = a->coef + b->coef;
            if (sum) attach(sum, a->expon, &rear);
            a = a->link; b = b->link; break;
        case 1: /* a->expon > b->expon */
            attach(a->coef, a->expon, &rear);
            a = a->link;
    }
/* copy rest of list a and then list b */
for (; a; a = a->link) attach(a->coef, a->expon, &rear);
for (; b; b = b->link) attach(b->coef, b->expon, &rear);
rear->link = NULL;
/* delete extra initial node */
temp = c; c = c->link; free(temp);
return c;
}

```

Program 4.9: Add two polynomials

```

void attach(float coefficient, int exponent,
            polyPointer *ptr)
{
    /* create a new node with coef = coefficient and expon =
       exponent, attach it to the node pointed to by ptr.
       ptr is updated to point to this new node */
    polyPointer temp;
    MALLOC(temp, sizeof(*temp));
    temp->coef = coefficient;
    temp->expon = exponent;
    (*ptr)->link = temp;
    *ptr = temp;
}

```

Program 4.10: Attach a node to the end of a list

```

listPointer invert(listPointer lead)
{
    /* invert the list pointed to by lead */
    listPointer middle, trail;
    middle = NULL;
    while (lead) {
        trail = middle;
        middle = lead;
        lead = lead->link;
        middle->link = trail;
    }
    return middle;
}

```

Program 4.16: Inverting a singly linked list

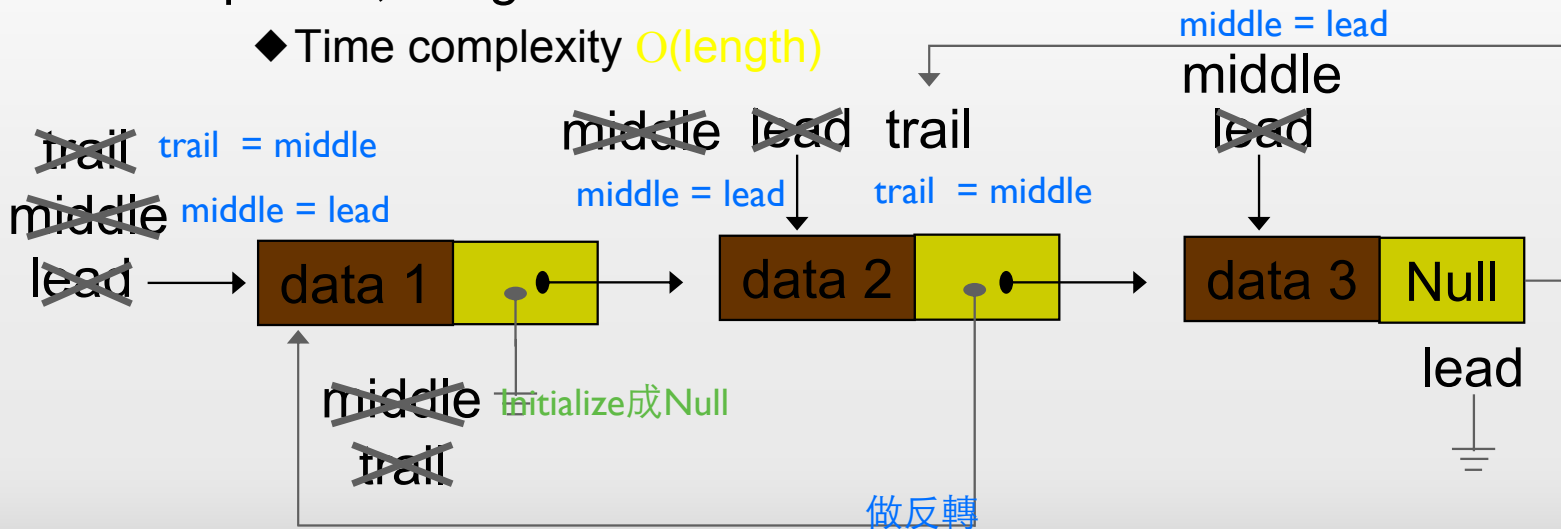
Additional List Operations

❖ Inverting chains 沒有用malloc

❑ “in place” processing if there are three pointers

❑ p. 171, Program 4.16

◆ Time complexity $O(\text{length})$



Equivalence Relations

同一個族群

❖ **Definition:** A **relation**, \equiv , over a set, S , is said to be an **equivalence relation** over S iff it is symmetric, reflexive, and transitive over S .

❑ **Reflexive:** $x \equiv x$ 自身性：自己和自己是同一群

❑ **Symmetric:** $x \equiv y \rightarrow y \equiv x$ 對稱性

❑ **Transitive:** $x \equiv y$ and $y \equiv z \rightarrow x \equiv z$ 遞移性

} 皆滿足即為
equivalence relation

❖ **Equivalence classes** of a set S

❑ Two members x and y of S are in the same equivalence class iff $x \equiv y$.

Equivalence Relations (contd.)

❖ Equivalence determination 分群：決定群數與其成員

- ❑ Phase 1: Read in and store the equivalence pairs $\langle i, j \rangle$

 - ◆ p. 176, Fig. 4.16 first 表示成 seq[]

- ❑ Phase 2: Begin at 0 and find all pairs of the form $\langle 0, j \rangle$, where 0 and j are in the same equivalence class.

❖ P. 177~178, Program 4.22

- ❑ Let m and n represent the number of related pairs and the number of objects, respectively.

- ❑ Phase 1: $O(m + n)$
- ❑ Phase 2: $O(m + n)$

⇒ The overall computing time is $O(m + n)$.

```
void equivalence()
{
    initialize seq to NULL and out to TRUE;
    while (there are more pairs) {
        read the next pair, <i,j>;
        put j on the seq[i] list;
        put i on the seq[j] list;
    }
    for (i = 0; i < n; i++)
        if (out[i]) {
            out[i] = FALSE;
            output this equivalence class;
        }
}
```

Program 4.21: A more detailed version of the equivalence algorithm

```

#include <stdio.h>
#include <alloc.h>
#define MAX_SIZE 24
#define FALSE 0
#define TRUE 1
typedef struct node *nodePointer;
typedef struct node {
    int data;
    nodePointer link;
};
void main(void)
{
    short int out[MAX_SIZE];
    nodePointer seq[MAX_SIZE];
    nodePointer x,y,top;
    int i,j,n;

    printf("Enter the size (<= %d) ",MAX_SIZE);
    scanf("%d",&n);
    for (i = 0; i < n; i++) {
        /* initialize seq and out */
        out[i] = TRUE;    seq[i] = NULL;
    }

    /* Phase 1: Input the equivalence pairs: */
    printf("Enter a pair of numbers (-1 -1 to quit): ");
    scanf("%d%d",&i,&j);
    while (i >= 0) {
        MALLOC(x, sizeof(*x));
        x->data = j;  x->link = seq[i];  seq[i] = x;
        MALLOC(x, sizeof(*x));
        x->data = i;  x->link = seq[j];  seq[j] = x;
        printf("Enter a pair of numbers (-1 -1 to quit): ");
        scanf("%d%d",&i,&j);
    }
}

```

Two node insertions


```

/* Phase 2: output the equivalence classes */
for (i = 0; i < n; i++)
    if (out[i]) {
        printf("\nNew class: %5d", i);
        out[i] = FALSE; /* set class to false */
        x = seq[i]; top = NULL; /* initialize stack */
        for (;;) { /* find rest of class */
            while (x) { /* process list */
                j = x->data;
                if (out[j]) {
                    printf("%5d", j); out[j] = FALSE;
                    y = x->link; x->link = top; top = x; x = y;
                }
                else x = x->link;
            }
            if (!top) break;
            x = seq[top->data]; top = top->link;
            /* unstack */
        }
    }
}

```

Preparing to process stack i with top element seq[i]

The initialization of the stack for class i

push z into the stack of class i

Program 4.22: Program to find equivalence classes

Sparse Matrices

- ❖ Each column of a sparse matrix is represented as a circularly linked list with a head node.
 - ❑ A similar representation for each row
- ❖ Node structure for sparse matrices (p. 179, Fig. 4.17)
 - ❑ A tag field is used to distinguish between head nodes and entry nodes.
 - ❑ The down field is used to link into a column list and the right field to link into a row list.
 - ◆ The head node for row i is also the head node for column i .

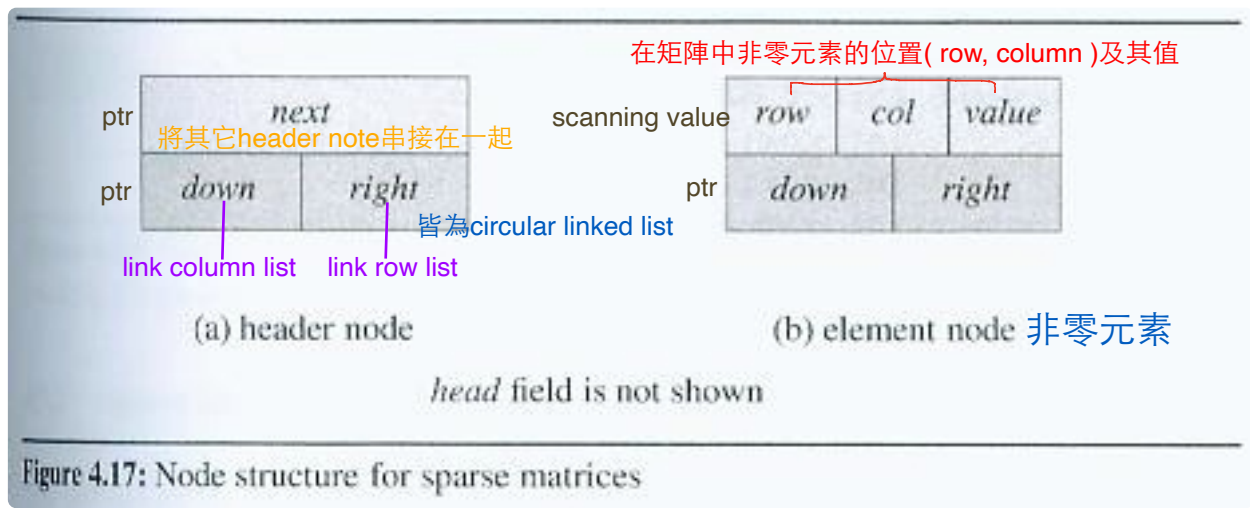


Figure 4.17: Node structure for sparse matrices



Sparse Matrices (contd.)

- ❖ Each head node is in three lists: a list of rows, a list of columns, and a list of head nodes.
- ❖ The list of head nodes also has a head node that has this node to store the matrix dimensions.

□ p. 180, Fig. 4.18; p. 181, Fig. 4.19

$$\begin{bmatrix} 2 & 0 & 0 & 0 \\ 4 & 0 & 0 & 3 \\ 0 & 0 & 0 & 0 \\ 8 & 0 & 0 & 1 \\ 0 & 0 & 6 & 0 \end{bmatrix}$$

Figure 4.18: 4×4 sparse matrix a

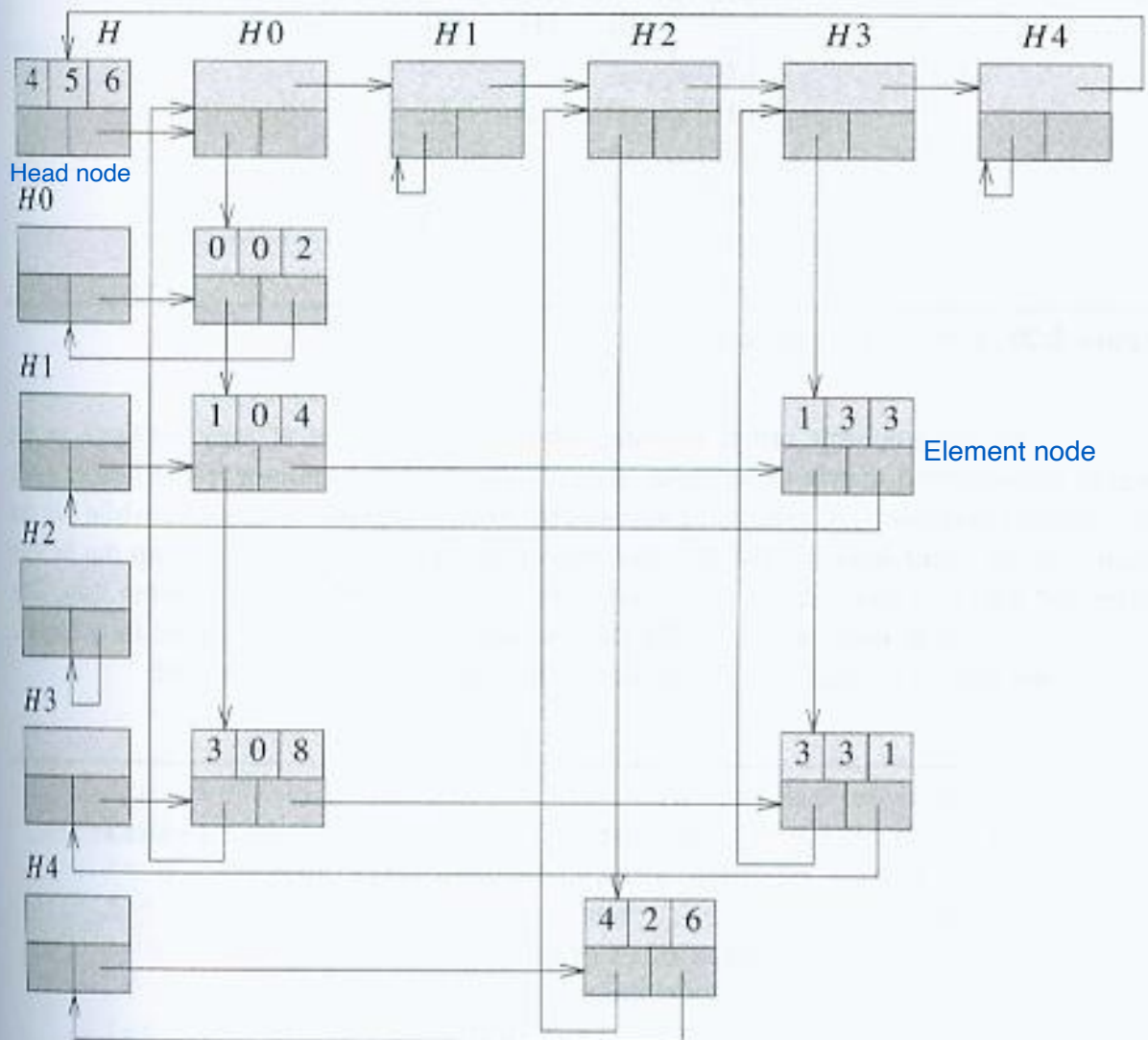


Figure 4.19: Linked representation of the sparse matrix of Figure 4.18 (the *head* field of a node is not shown)

Doubly Linked Lists

安全性較singly linked list佳

- ❖ Singly linked lists pose problems because we can move easily only in the direction of the links.
 - ❑ Doubly linked lists
- ❖ A node in a doubly linked list has at least three fields.
 - ❑ A left link field
 - ❑ A data field
 - ❑ A right link field

Doubly Linked Lists -- Doubly Linked Circular Lists (contd.)

- ❖ A doubly linked list may or may not be circular.
- ❖ A head node allows us to implement our operations more easily.
 - ❑ The item field of the head node usually contains no information.
 - ❑ An empty list is not really empty. (p. 188, Fig. 4.22)
- ❖ Insertion and Deletion
 - ❑ In constant time (p. 188~189, Program 4.26 and 4.27)



Figure 4.22: Empty doubly linked circular list with header node

```
void dininsert(nodePointer node, nodePointer newnode)
{ /* insert newnode to the right of node */
    newnode->llink = node;
    newnode->rlink = node->rlink;
    node->rlink->llink = newnode;
    node->rlink = newnode;
}
```

Program 4.26: Insertion into a doubly linked circular list

```
void ddelete(nodePointer node, nodePointer deleted)
{ /* delete from the doubly linked list */
    if (node == deleted)
        printf("Deletion of header node not permitted.\n");
    else {
        deleted->llink->rlink = deleted->rlink;
        deleted->rlink->llink = deleted->llink;
        free(deleted);
    }
}
```

Program 4.27: Deletion from a doubly linked circular list