



ex. $y'' + 3y' + 2y = (\cos x + x)$
 $\hookrightarrow r(x)$

特性方程式 $\cdot \lambda^2 + 3\lambda + 2 = 0 \Rightarrow y_h = C_1 e^{-x} + C_2 e^{-2x}$

又 $y'' + 3y' + 2y = (\cos x) + (x)$, (分開找)
 $\hookrightarrow r_1(x) \quad \hookrightarrow r_2(x)$

$$\left(\begin{array}{l} y_{p1}'' + 3y_{p1}' + 2y_{p1} = r_1(x) \\ +) y_{p2}'' + 3y_{p2}' + 2y_{p2} = r_2(x) \\ \hline (y_{p1} + y_{p2})'' + 3(y_{p1} + y_{p2})' + 2(y_{p1} + y_{p2}) = r_1(x) + r_2(x) \\ \Rightarrow y_p = y_{p1} + y_{p2} \end{array} \right)$$

先做 $r_1(x)$.

$$\Rightarrow (D^2 + 3D + 2) y_{p1}(x) = \cos x.$$

$$\Rightarrow y_{p1}(x) = \frac{1}{(D^2 + 3D + 2)} \cos x = \frac{1}{-1 + 3D + 2} \cos x$$

$$\hookrightarrow L(D^2)$$

$$= \left(\frac{1}{3D + 1} \cos x \right) = \frac{1 - 3D}{1 - 9D^2} \cos x$$

$$\hookrightarrow \text{有理化.}$$

$$= \frac{1 - 3D}{10} \cos x = \frac{1}{10} \cos x - \frac{3}{10} D \cos x$$

$$= \frac{1}{10} \cos x - \frac{3}{10} (-\sin x)$$

相等

再做 $r_2(x)$.

$$\Rightarrow (D^2 + 3D + 2) y_{p2}(x) = x$$

$$\Rightarrow y_{p2}(x) = \frac{1}{D^2 + 3D + 2} \cdot x$$

$$= \frac{1}{2(1 + \frac{D^2 + 3D}{2})} \cdot x$$



$$(x \frac{1}{1+r} = 1 - r + r^2 - r^3 \dots)$$

$$= \frac{1}{2} (1 - \frac{D^2+3D}{2} + (\frac{D^2+3D}{2})^2 - \dots) x$$

$$= \frac{1}{2} x - \frac{D^2 x + 3Dx}{2} = \frac{1}{2} x - \frac{3}{4}$$

$$\Rightarrow y_p = \frac{1}{10} \cos x + \frac{3}{10} \sin x + \frac{1}{2} x - \frac{3}{4}$$

$$\Rightarrow y = c_1 e^{-x} + c_2 e^{-2x} + \frac{1}{10} \cos x + \frac{3}{10} \sin x + \frac{1}{2} x - \frac{3}{4} \quad \#$$

Method 4. variation of variables / parameter
變數變換法 / 參數變換法.

概念: $y_p = y_h \cdot \phi$

先舉例: $y' + 2y = e^x$

$$\Rightarrow y_h = c e^{-2x}$$

$$\Rightarrow y_p = e^{-2x} \cdot \phi(x)$$

$$y_p' = e^{-2x} \cdot \phi'(x) - 2e^{-2x} \cdot \phi(x)$$

} 代回去

$$\Rightarrow e^{-2x} \phi'(x) - 2e^{-2x} \phi(x) + 2e^{-2x} \phi(x) = e^x$$

$$\Rightarrow \phi'(x) = e^{3x}$$

$$\Rightarrow \phi(x) = \frac{1}{3} e^{3x} + k$$

$$\Rightarrow y_p = e^{-2x} (\frac{1}{3} e^{3x} + k)$$

$$= \frac{1}{3} e^x + k e^{-2x}$$

$$\Rightarrow y = y_h + y_p = \underline{c e^{-2x}} + \underline{\frac{1}{3} e^x} + \underline{k e^{-2x}}$$

$$= c e^{-2x} + \frac{1}{3} e^x \Rightarrow k \text{ 以後不用寫}$$

推廣如二階常微分方程式:

$$y''(x) + p(x) \cdot y'(x) + q(x) \cdot y(x) = r(x)$$

設 $y_1(x)$, $y_2(x)$ 分別為此方程式的齊性解



$$\Rightarrow y_R = C_1 y_1(x) + C_2 y_2(x).$$

$$\text{再 } y_1'' + P y_1' + Q y_1 = 0.$$

$$y_2'' + P y_2' + Q y_2 = 0.$$

$$\text{又 } y_R = y_1 \phi_1 + y_2 \phi_2.$$

$$\Rightarrow y_R' = y_1' \phi_1 + y_1 \phi_1' + y_2' \phi_2 + y_2 \phi_2'$$

$$= (y_1' \phi_1 + y_2' \phi_2) + (y_1 \phi_1' + y_2 \phi_2').$$

令為 0.

$$\Rightarrow y_R'' = y_1'' \phi_1 + y_1' \phi_1' + y_2'' \phi_2 + y_2' \phi_2'$$

代回去.

$$\Rightarrow y_1'' \phi_1 + y_1' \phi_1' + y_2'' \phi_2 + y_2' \phi_2'$$

$$+ P(y_1' \phi_1 + y_2' \phi_2)$$

$$+ Q(y_1 \phi_1 + y_2 \phi_2)$$

$$= r(x).$$

$$\Rightarrow \phi_1 (y_1'' + P y_1' + Q y_1) + \phi_2 (y_2'' + P y_2' + Q y_2)$$

$$+ y_1' \phi_1' + y_2' \phi_2' = r(x)$$

齊性解 = 0

$$\Rightarrow \begin{cases} y_1' \phi_1' + y_2' \phi_2' = r(x) \\ y_1 \phi_1' + y_2 \phi_2' = 0 \end{cases}$$

要每上式都滿足.

$$\left(\begin{cases} ax + by = c \\ dx + ey = f \end{cases} \Rightarrow x = \frac{\begin{vmatrix} c & b \\ f & e \end{vmatrix}}{\begin{vmatrix} a & b \\ d & e \end{vmatrix}}, y = \frac{\begin{vmatrix} a & c \\ d & f \end{vmatrix}}{\begin{vmatrix} a & b \\ d & e \end{vmatrix}} \right)$$

$$\Rightarrow \phi_1' = \frac{\begin{vmatrix} 0 & y_2 \\ r & y_2' \end{vmatrix}}{\begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}}$$

$$\phi_2' = \frac{\begin{vmatrix} y_1 & 0 \\ y_1' & r \end{vmatrix}}{\begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}}$$

$$= \frac{-r y_2}{\begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}}$$

$$= \frac{r y_1}{\begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}}$$

$$\Rightarrow \phi_1 = \int \frac{-r y_2}{\begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}} dx$$

$$\phi_2 = \int \frac{r y_1}{\begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}} dx$$



$$y_p = y_1 \phi_1 + y_2 \phi_2$$

$$= y_1 \int \frac{-r y_2}{\begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}} dx + y_2 \int \frac{r y_1}{\begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix}} dx$$

定義. Wronski $(y_1, y_2) = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix} = w(y_1, y_2)$

$$\Rightarrow y_p = y_1 \int \frac{-r y_2}{w(y_1, y_2)} dx + y_2 \int \frac{r y_1}{w(y_1, y_2)} dx \quad \#$$

ex. $y'' + 3y' + 2y = x$

$$y_p = y_1 \phi_1 + y_2 \phi_2$$

$$\lambda = -1, -2$$

$$\Rightarrow y_1 = e^{-2x}, \quad y_2 = e^{-x}$$

$$w(y_1, y_2) = \begin{vmatrix} y_1 & y_2 \\ y_1' & y_2' \end{vmatrix} = e^{-3x}$$

$$y_p = y_1 \int \frac{-r y_2}{e^{-3x}} dx + y_2 \int \frac{r y_1}{e^{-3x}} dx$$

$$= -e^{-2x} \left(\frac{1}{2} x e^{2x} - \frac{1}{4} e^{2x} \right) + e^{-x} (x e^x - e^x)$$

$$= \frac{1}{2} x - \frac{3}{4} \quad \#$$

用方法②:

$$(D+1)(D+2)y_p = x$$

$$I_1 = e^x, \quad I_2 = e^{2x}$$

$$\Rightarrow y_p = e^{2x} \int e^{2x} \left[e^x \int e^x r dx \right] dx$$

$$= \frac{1}{2} x - \frac{3}{4} \quad \#$$

ex. $y'' + 8y' + 16y = 3 \cdot e^{-4x}$



$$\tilde{y}_h = c_1 e^{-4x} + c_2 x e^{-4x}.$$

\tilde{y}_p ?

$$\textcircled{1}. \tilde{y}_p = kx^2 e^{-4x}$$

$$\tilde{y}_p' = k[x^2(-4e^{-4x}) + (2xe^{-4x})]$$

$$= k[-4x^2 e^{-4x} + 2xe^{-4x}]$$

$$\tilde{y}_p'' = k[16x^2 e^{-4x} - 16xe^{-4x} + 2e^{-4x}]$$

} 代回去.

$$\Rightarrow k[16x^2 e^{-4x} - 16xe^{-4x} + 2e^{-4x}]$$

$$+ k[-32x^2 e^{-4x} + 16xe^{-4x}]$$

$$\Rightarrow k = \frac{3}{2}.$$

$$+ k[16x^2 e^{-4x}] = 3 \cdot e^{-4x}.$$

$$\Rightarrow \tilde{y}_p = \frac{3}{2} x^2 e^{-4x} \quad \#.$$

$$\textcircled{2}. (D+4)(D+4)\tilde{y}_p = 3 \cdot e^{-4x}.$$

$$I_1 = e^{4x}, I_2 = e^{4x}.$$

$$\Rightarrow \tilde{y}_p = e^{-4x} \int e^{4x} [e^{-4x} \int e^{4x} \cdot r \cdot dx] dx$$

$$= \frac{3}{2} x^2 e^{-4x} \quad \#.$$

$$\textcircled{3}. \tilde{y}_p = \frac{1}{(D+4)^2} \cdot 3e^{-4x} \cdot 1$$

$$= 3 \cdot e^{-4x} \cdot \frac{1}{D^2} \cdot 1$$

$$= 3 \cdot e^{-4x} \iint 1 dx dx = \frac{3}{2} x^2 e^{-4x} \quad \#.$$

$$\textcircled{4}. \tilde{y}_1 = e^{-4x}, \tilde{y}_2 = x \cdot e^{-4x}.$$

$$w(\tilde{y}_1, \tilde{y}_2) = e^{-8x}.$$

$$\tilde{y}_p = \tilde{y}_1 \int \frac{-r\tilde{y}_2}{w} dx + \tilde{y}_2 \int \frac{r\tilde{y}_1}{w} dx.$$

$$= \frac{3}{2} x^2 e^{-4x} \quad \#.$$

①.③ 受限於 $r(x)$ 的型式: