Polynomial chaos expansions part I: Method Introduction

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Lectures will include many examples using the Chaospy software



A very basic introduction to scientific Python programming: http://hplgit.github.io/bumpy/doc/pub/sphinx-basics/index.html

Installation instructions:

https://github.com/hplgit/chaospy

Example: bloodflow simulations





In colaboration with V. Eck and L. Hellevik

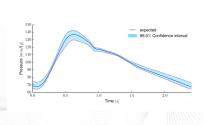
Modelling require uncertainty quantification

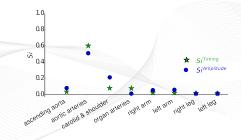








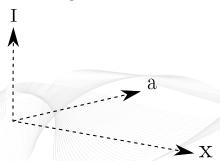




Introducing a testcase as a working example

$$\frac{du(x)}{dx} = -au(x) \qquad \qquad u(0) = I$$

- *u* The quantity of interest
- x Spatial location
- a, I Parameters containting uncertainties



This model can be analysed analytically

$$u(x; a, I) = Ie^{-ax}$$

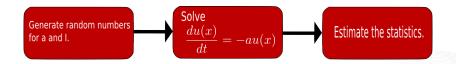
Initially assume model parameters:

$$a \sim \text{Uniform}(0, 0.1) \sim f_a(a)$$
 $I = 1 \text{ (known)}$

$$E(u) = \int_{-\infty}^{\infty} u(x; a) f_a(a) da = 10 \int_{0}^{0.1} e^{-ax} da = 10 \frac{1 - e^{-0.1x}}{x}$$

$$Var(u) = \int_{-\infty}^{\infty} (u(x; a) - E(u))^2 f_a(a) da = 20 \frac{1 - e^{-0.2ax}}{x} - \left(10 \frac{1 - e^{-0.1x}}{x}\right)^{\frac{1}{2}}$$

In general, models can be analysed using Monte Carlo integration

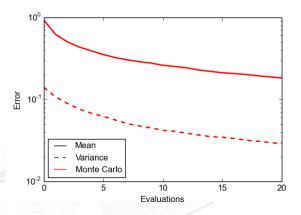


Monte Carlo with Chaospy

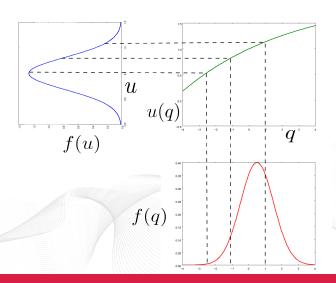
```
import chaospy as cp
import numpy as np
def u(x, a):
  return np.exp(-a*x)
dist_a = cp.Uniform(0,0.1)
samples_a = dist_a.sample(size=1000)
x = np.linspace(0, 10, 100)
samples_u = [u(x, a) for a in samples_a]
E = np.mean(samples_u, 0)
Var = np.var(samples_u, 0)
```

Convergence of Monte Carlo is slow

$$\varepsilon_E = \int_0^{10} |\mathsf{E}(u) - \mathsf{E}(\hat{u})| \, dx \quad \varepsilon_{Var} = \int_0^{10} |\mathsf{Var}(u) - \mathsf{Var}(\hat{u})| \, dx$$



Assumption: mapping from input q to output u is smooth



Using Lagrange polynomials to approximate u(q) (N-th degree polynomial interpolation)

$$u(x; a) \approx \hat{u}_M(x; a) = \sum_{n=0}^{N} c_n(x) P_n(a)$$
 $N = M + 1,$

where

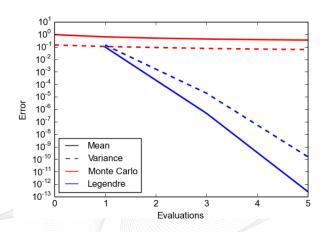
 c_n are model evaluations $u(x, a_n)$

 P_n are Lagrange polynomials:

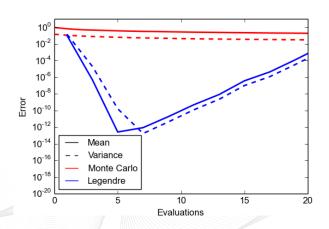
$$P_n(a) = \prod_{\substack{m=0\\m\neq n}}^N \frac{a - a_n}{a_m - a_n}$$

an are collocation nodes

The interpolation has much better convergence properties than Monte Carlo!



Oscillations in Lagrange polynomials (for large *N*) destroy the convergence



Let us introduce a better polynomial approximation: Polynomial Chaos (PC) theory

$$u(x;a) \approx \hat{u}_M(x;a) = \sum_{n=0}^N c_n(x) P_n(a), N = M+1$$

Coefficient Polynomial

PC employs inner product spaces weighted with the probability distribution

$$\langle u, v \rangle_Q = \mathsf{E}(u \cdot v) \qquad ||u||_Q = \sqrt{\langle u, u \rangle_Q}$$

= $\int f_Q(q)u(x, q)v(x, q)dq$

where Q is a random vector, i.e. (a, I).

Orthogonality:

$$\langle P_n, P_m \rangle_Q = \begin{cases} \|P_n\|_Q^2 & n = m \\ 0 & n \neq m \end{cases}$$

Coefficients are determined by least squares minimization

$$\min_{c_0, \dots, c_N} ||u - \hat{u}_M||_Q^2$$

$$\vdots$$

$$\left\langle \sum_{n=0}^N c_n P_n, P_k \right\rangle_Q = \sum_{n=0}^N c_n \left\langle P_n, P_k \right\rangle_Q = c_k \left\langle P_k, P_k \right\rangle_Q \quad k = 0, \dots, N$$

$$c_k = \frac{\langle u, P_k \rangle_Q}{\|P_k\|_Q^2}$$

Fourier coefficients

Least squares minimization implies minimization of variance

$$(c_0, \dots, c_N) = \underset{c_0, \dots, c_N}{\operatorname{argmin}} \| u - \hat{u}_M \|_Q$$

$$= \underset{c_0, \dots, c_N}{\operatorname{argmin}} \| u - \hat{u}_M \|_Q^2$$

$$= \underset{c_0, \dots, c_N}{\operatorname{argmin}} \operatorname{E}((u - \hat{u}_M)^2)$$

$$= \underset{c_0, \dots, c_N}{\operatorname{argmin}} \operatorname{Var}(u - \hat{u}_M)$$

The mean and variance have a simpler form

Assumption: $P_0 = 1$

$$\begin{split} \mathsf{E}(\hat{u}_M) &= \mathsf{E}\left(\sum_{n=0}^N c_n P_n\right) \qquad \mathsf{Var}(\hat{u}_M) = \mathsf{Var}\left(\sum_{n=0}^N c_n P_n\right) \\ &= \sum_{n=0}^N c_n \mathsf{E}(P_n) \qquad \qquad = \sum_{n=0}^N c_n c_m \left(\mathsf{E}(P_n P_m) - \mathsf{E}(P_n) \mathsf{E}(P_m)\right) \\ &= \sum_{n=0}^N c_n \left\langle P_n, P_0 \right\rangle_Q \qquad \qquad = \sum_{n=0}^N c_n c_m \left\langle P_n, P_m \right\rangle_Q - c_0^2 \\ &= \mathsf{E}(\hat{u}_M) = c_0 \qquad \qquad \mathsf{Var}(\hat{u}_M) = \sum_{n=0}^N c_n^2 \left\| P_n \right\|_Q \end{split}$$

Construct an orthogonal polynomial expansion using Gram-Schmidt orthogonalization

$$v_0, v_1, ..., v_N = 1, q, ..., q^N$$

The Gram Schmidt method is

$$P_{0} = v_{0}$$

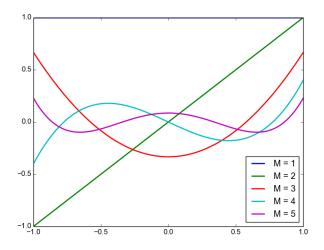
$$P_{n} = v_{n} - \sum_{m=0}^{n-1} \frac{\langle v_{n}, P_{m} \rangle_{Q}}{\|P_{m}\|_{Q}^{2}}$$

$$= v_{n} - \sum_{m=0}^{n-1} \frac{E(v_{n}P_{m})}{E(P_{m}^{2})}$$

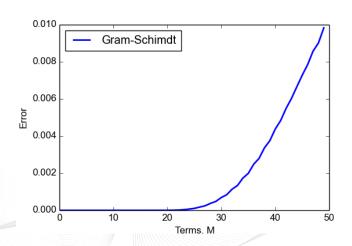
Gram-Schmidt with chaospy

```
M = 5; N = M - 1
dist_a = cp.Uniform(0, 0.1)
v = cp.basis(0, M, 1)
P = \lceil v \lceil 0 \rceil \rceil
for n in xrange(1, N):
    p = v[n]
    for m in xrange(0, n):
         p \rightarrow P[m]*cp.E(v[n]*P[m], dist_a)
                                 /cp.E(P[m] **2, dist_a)
    P.append(p)
P = cp.Poly(P)
```

Plot of all generated polynomials



Most constructors of orthogonal polynomials are ill-conditioned



The only numerically stable method for calculating orthogonal polynomials is through the three-term discretized Stiltjes recursion

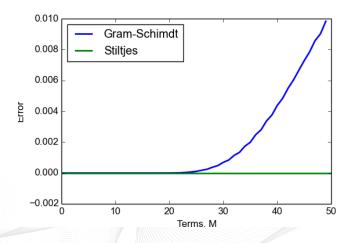
Three terms recursion relation:

$$P_{n+1} = (x - A_n)P_n - B_nP_{n-1}$$
 $P_{-1} = 0$ $P_0 = 1$,

where

$$A_{n} = \frac{\langle qP_{n}, P_{n}\rangle_{Q}}{\|P_{n}\|_{Q}^{2}} \qquad B_{n} = \begin{cases} \frac{\|P_{n}\|_{Q}^{2}}{\|P_{n-1}\|_{Q}^{2}} & n > 0\\ \|P_{n}\|_{Q}^{2} & n = 0 \end{cases}$$

Discretized Stiltjes method is numerically stable



People have found analytical orthogonal polynomials for many common probability distributions

Distribution	Polynomial	Support
Gaussian	Hermite	$(-\infty,\infty)$
Gamma	Laguerre	$[0,\infty]$
Beta	Jacobi	[a, b]
Uniform	Legendre	[a, b]

Three terms recursion in Chaospy

```
dist_a = cp.Normal()
P = cp.orth_ttr(3, dist_a)
print P
[1.0, q0, q0^2-1.0, q0^3-3.0q0]
```

Repetition of the problem

$$u(x; a, I) = Ie^{-ax}$$

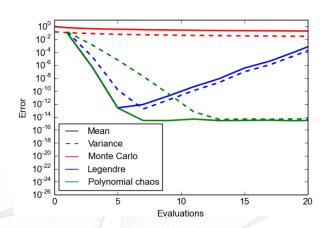
Initially assume model parameters:

$$a \sim \mathsf{Uniform}(0, 0.1) \sim f_a(a)$$
 $I = 1 \text{ (known)}$

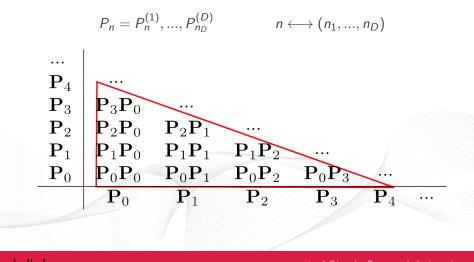
$$\mathsf{E}(u) = 10 \frac{1 - e^{-0.1x}}{x} \quad \mathsf{Var}(u) = 20 \frac{1 - e^{-0.2ax}}{x} - \left(10 \frac{1 - e^{-0.1x}}{x}\right)^2$$

$$arepsilon_E = \int_0^{10} |E(u) - E(\hat{u})| dx \quad arepsilon_{Var} = \int_0^{10} |Var(u) - Var(\hat{u})| dx$$

Convergence of orthogonal polynomial approximation



Next step: Extend the theory to multiple dimensions



We need a mapping from multiple indices to single index

Multi-index

 Single-index

$$N = \binom{M+D}{M}$$

Orthogonality for multivariate polynomials

$$\langle \mathbf{P}_{n}, \mathbf{P}_{m} \rangle_{Q} = \mathbb{E} \left(P_{n_{1}}^{(1)} \cdots P_{n_{D}}^{(D)} \cdot P_{m_{1}}^{(1)} \cdots P_{m_{D}}^{(D)} \right)$$

$$= \mathbb{E} \left(P_{n_{1}}^{(1)} \cdot P_{m_{1}}^{(1)} \right) \cdots \mathbb{E} \left(P_{n_{D}}^{(D)} \cdot P_{m_{D}}^{(D)} \right)$$

$$= \left\langle P_{n_{1}}^{(1)}, P_{m_{1}}^{(1)} \right\rangle_{Q} \cdots \left\langle P_{n_{D}}^{(D)}, P_{m_{D}}^{(D)} \right\rangle_{Q}$$

$$= \left\| P_{n_{1}}^{(1)} \right\|_{Q} \delta_{n_{1}m_{1}} \cdots \left\| P_{n_{D}}^{(D)} \right\|_{Q} \delta_{n_{D}m_{D}}$$

$$\langle \mathbf{P}_{n}, \mathbf{P}_{m} \rangle_{Q} = \left\| \mathbf{P}_{n} \right\|_{Q} \delta_{n_{m}}$$

Creating multivariate orthogonal polynomials in Chaospy

```
dist_a = cp.Uniform(0, 0.1)
dist_I = cp.Uniform(8, 10)
dist = cp.J(dist_a, dist_I)
P = cp.orth_ttr(1, dist)
print P
[1.0, q1-9.0, q0]
P = cp.orth_ttr(3, dist)
print cp.E(P[1]*P[2],dist)
0.0
print cp.E(P[3]*P[3], dist)
0.088888888903
```

A two-dimensional problem

$$u(x; a, I) = Ie^{-ax}$$

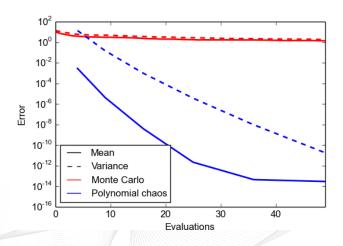
Uncertain model parameters:

$$a \sim \mathsf{Uniform}(\mathsf{0,\ 0.1})$$

$$I = Uniform(8, 10)$$

$$\varepsilon_E = \int_0^{10} |E(u) - E(\hat{u})| dx$$
 $\varepsilon_{Var} = \int_0^{10} |Var(u) - Var(\hat{u})| dx$

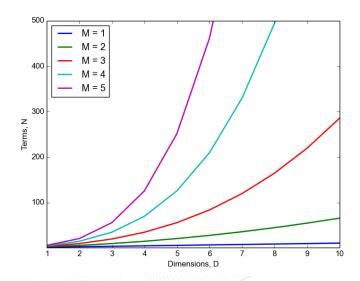
Convergence of the two-dimensional (a, l) problem



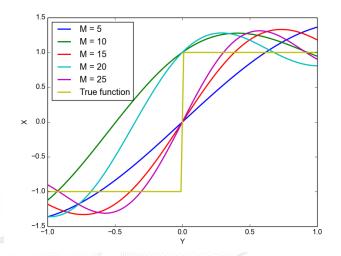
Teaser of the full implementation

```
def u(x,a, I):
  return I*np.exp(-a*x)
dist_a = cp.Uniform(0, 0.1)
dist_I = cp.Uniform(8, 10)
dist = cp.J(a,I)
P = cp.orth_ttr(2, dist)
nodes, weights = \
    cp.generate_quadrature(3, dist, rule="G")
x = np.linspace(0, 10, 100)
samples_u = [u(x, *node) for node in nodes.T]
u_hat = cp.fit_quadrature(P, nodes, weights, samples_u)
mean, var = cp.E(u_hat, dist), cp.Var(u_hat, dist)
```

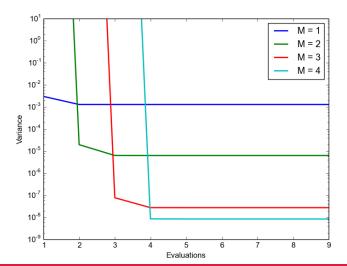
The curse of dimensionality



Gibb's Phenomena: discontinuities give oscillations



Higher number of samples justifies higher number of collocation nodes



Thank you



A very basic introduction to scientific Python programming: http://hplgit.github.io/bumpy/doc/pub/sphinx-basics/index.html

Installation instructions:

https://github.com/hplgit/chaospy