FYS-STK4155, Autumn 2019, Project 1

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Introduction

The project code can be found at my github: `https://github.com/Akselkg/FYS-STK4155-2019` The code is split into two python files. pro1.py is the "main" file, which sets everything up, and is what you run to execute the project. functions.py contains both helper functions and meatier functions that compute the more complicated methods. Plots and a sample run can be found in the results folder, and the data set I used is in the DataFiles folder.

The main goal for this project was to implement different regression methods and attempt to analyse them through examining statistics from the resulting regression lines. The methods were tested on the Franke function f, and attempted to be applied on some real geographical data. The Franke function is an exponential function that takes two parameters (x, y) as input and looks somewhat like a hilly landscape, making it a good choice for testing. The base regression method is OLS, using polynomials in x and y.

a)

The OLS model is $\tilde{z} = X\beta$, where I used z as my response variable since y is used as a parameter. X is the design matrix, with columns $[1, x, y, x^2, xy, y^2, ...]$, up to order 5. I implemented the model using a matrix inversion by

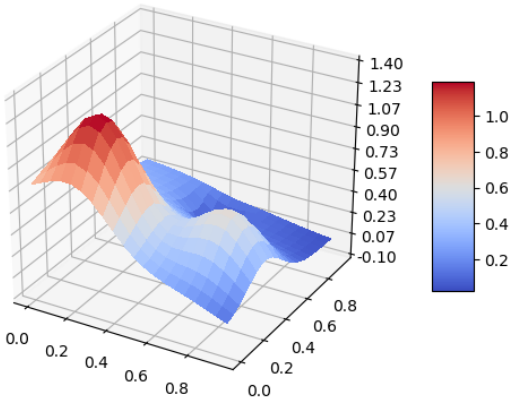
$$\beta = (X^T X)^{-1} X^T z$$

. The base data for the regression are $n = 20$ uniformly distributed x and y values, making 400 uniformly distributed points in the square $[0, 1] \times [0, 1]$ and corresponding true values $z = f(x, y)$. This gave me scores $R2 = 0.983$, $MSE = 0.00124$, certainly a good fit. With an added error term of $0.1N(0, 1)$ I got slightly worse values $R2 = 0.873$, $MSE = 0.0109$ as you would expect.

I plotted the randomly distributed points by triangulating them and plotting the resulting surface.

b)

My implementation of k-cross validation lets the order of the polynomial vary for comparison. The dataset is split into k parts, and a regression is ran using each of the k parts as a validation set in turn. This is done for all polynomial maximal orders. The result is values for the training and test error for each maximum order of the polynomial fit. On the plot you can see the test error deviating, increasing, from the training error as the complexity of the model increases as expected.



c)

$$E[(y-\tilde{y})^2] = E[(f+\epsilon-\tilde{y})^2] = E\left[((f-E[\tilde{y}])+\epsilon+(E[\tilde{y}]-\tilde{y}))^2\right]$$
$$= E[(f-E[\tilde{y}])^2] + E[\epsilon^2] + E[(E[\tilde{y}]-\tilde{y}))^2] + \text{cross terms}$$
$$\text{Bias}^2 + \sigma^2 + \text{Variance}$$

I skipped a bit of the calculation here, namely the cross terms. They all individually cancel out, mostly since the expected value of $\epsilon = 0$. In the end we are left with the wanted expression. The bias in the model is represented by the average distance between the model and the real value, and the variance is the expected difference within the model itself.

d

e

f, g)

I used the dataset contained in the file SRTM_data_Norway.tif, containing terrain data from the coast of Norway. As is the dataset was to big to carry out regression. If i ran a simple OLS on the set it would complete the calculation but the resulting image had some strange artifacts and looked little like the original. Cross validation would also take too long. My solution was to both look at a smaller area of the image, and also to pick out every fourth point. The area i chose was the last 1000 points in each direction, leaving me with a set of 250×250 points. I tried a few other resolutions, but my results did not seem to depend on it too much.