IE 411: Operating Systems

Practice questions: synchronization

Q1(a) - True or False

For any problem you can solve with semaphores, you can also solve using condition variables (with a corresponding lock for the condition variable).

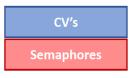
Q1(a) - True or False

For any problem you can solve with semaphores, you can also solve using condition variables (with a corresponding lock for the condition variable).

TRUE FALSE

Recap

Locks Semaphores





Q1(b) - True or False

A critical section of code is a section of the program that must not be interrupted by the scheduler.

Q1(b) - True or False

A critical section of code is a section of the program that must not be interrupted by the scheduler.

TRUE FALSE

Q1(c) - True or False

The function pthread_cond_signal never causes its caller to block.

Q1(c) - True or False

The function $pthread_cond_signal$ never causes its caller to block.

TRUE FALSE

Q1(d) - True or False

To implement a thread_join() operation with a condition variable, the thread_exit() code will call cond_wait().

Q1(d) - True or False

To implement a thread_join() operation with a condition variable, the thread_exit() code will call cond_wait().

TRUE FALSE

```
void thr_exit() {
  mutex_lock(&m);
  pthread_cond_signal(&c);
  mutex_unlock(&m);
}

void thr_join() {
  mutex_lock(&m);
  pthread_cond_wait(&c, &m);
  mutex_unlock(&m);
}
```

Which is the interleaving for which one of the threads would wait forever?

- First, the child runs the code of thr_exit. Second, the parent runs thr_join.
- First, the parent runs the code of thr_join. Second, the child runs thr_exit.

Answer

Child thread

Parent thread

```
void thr_exit() {
  mutex_lock(&m);
  pthread_cond_signal(&c);
  mutex_unlock(&m);
}

void thr_join() {
    mutex_lock(&m);
    pthread_cond_wait(&c, &m);
    mutex_unlock(&m);
}
```

- After child finishes the code of thr_exit(), parent thread runs the code of thr_join()
- When parent calls pthread_cond_wait(), it sleeps forever

Use an execution sequence to show that it sem_wait() is not atomic then mutual exclusion cannot be maintained.

Answer

On the whiteboard

How to prove correctness?

 Critical section: a section of code that only a single process/thread may be executing at a time

Entry code (preamble)

Critical Section code;

Exit code (postscript)

Proving mutual exclusion

- \bullet One process in critical section, another process tries to enter \to Show that second process will block in entry code
- ullet Two (or more) processes are in the entry code o Show that at most one will enter critical section

How to prove correctness?

Proving progress

- ullet No process in critical section, P1 arrives ightarrow P1 enters
- \bullet Two (or more) processes are in the entry code \to Show that at least one will enter critical section

How to prove correctness?

Proving progress

- ullet No process in critical section, P1 arrives ightarrow P1 enters
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Proving bounded waiting

ullet One process in critical section, another process is waiting to enter ightarrow show that if first process exits the critical section and attempts to re-enter, then the waiting process will be get in

- One in CS → another that tries to enter fails
- ullet Two or more try to enter ightarrow at most one can succeed

Progress

- Nobody waiting and one arrives → it will succeed
- $\hbox{ Two or more try to enter} \rightarrow \\ \hbox{ at least one will succeed}$

Bounded wait

 One inside and one waiting, 1st exits → 2nd will enter before 1st

```
Entry code:
   while (Note) {};
   Note = 1;

Critical section:
   foo();

Exit code:
```

Note = 0

- One in CS → another that tries to enter fails
- Two or more try to enter → at most one can succeed

Progress

- Nobody waiting and one arrives → it will succeed
- $\hbox{ Two or more try to enter} \rightarrow \\ \hbox{ at least one will succeed}$

Bounded wait

 One inside and one waiting, 1st exits → 2nd will enter before 1st

```
flag [2] = {0,0};
Entry code:
    while (flag[them]) {};
    flag[me] = 1;

Critical section:
    foo();
```

```
\frac{\text{Exit code:}}{\text{flag [me]}} = 0;
```

- One in CS → another that tries to enter fails
- Two or more try to enter \rightarrow at most one can succeed

Progress

- Nobody waiting and one arrives \rightarrow it will succeed
- ullet Two or more try to enter ightarrow at least one will succeed

Bounded wait

 One inside and one waiting, 1st exits → 2nd will enter before 1st

```
\mathsf{flag}\,[2] \ = \ \{0\,,\!0\};
```

Entry code:

```
flag[me] = 1;
while (flag[them]) \{\};
```

Critical section:

Exit code:

$$flag[me] = 0;$$

- One in CS → another that tries to enter fails
- Two or more try to enter → at most one can succeed

Progress

- Nobody waiting and one arrives → it will succeed
- $\hbox{ Two or more try to enter} \rightarrow \\ \hbox{ at least one will succeed}$

Bounded wait

 One inside and one waiting, 1st exits → 2nd will enter before 1st

```
turn = 0;
Entry code:
    while (turn != me) {};
Critical section:
    foo();
Exit code:
    turn = them;
```

- REQ1: At most one thread at a time may be running funcB.
- REQ2: At most two threads at a time may be running any combination of funcA or funcB.

	funcA	funcB
funcA	OK	OK
funcB	OK	NO

- List the semaphores that you will use in your solution. For each semaphore, state what its initial value should be.
- Show the semaphore P and V operations that threads should perform before and after each call to funcA and funcB to enforce the synchronization requirements.

```
/* show P, V calls here */
funcA();

/* show P, V calls here */
funcB();

/* show P, V calls here */

/* show P, V calls here */
```

Answer

- REQ2: At most two threads at a time may be running any combination of funcA or funcB.
- To enforce REQ2, let us use a semaphore Sem2 with initial value 2

```
P(Sem2);
funcA();
funcB();
V(Sem2);
V(Sem2);
```

Answer

- REQ1: At most one thread at a time may be running funcB.
- To enforce REQ1, let us use a semaphore Sem1 with initial value 1

```
P(Sem1);
P(Sem2);
funcA();
funcB();
V(Sem2);
V(Sem1);
```