

Phys 225
HW #9

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Q1 a) $|\vec{A} + \vec{B}| = \sqrt{(\vec{A} + \vec{B}) \cdot (\vec{A} + \vec{B})} = \sqrt{A^2 + B^2 + 2\vec{A} \cdot \vec{B}} = \sqrt{A^2 + B^2 + 2AB \cos \theta}$

b) $|B| = 2|A|$

$$\begin{aligned} |\vec{A} + \vec{B}| &= \sqrt{(\vec{A} + \vec{B}) \cdot (\vec{A} + \vec{B})} = \sqrt{\vec{A} \cdot \vec{A} + \vec{A} \cdot \vec{B} + \vec{B} \cdot \vec{A} + \vec{B} \cdot \vec{B}} \\ &= \sqrt{A^2 + 4A^2 + 2 \cdot |A| \cdot 2|A| \cos 45^\circ} \\ &= \sqrt{5A^2 + 4A^2 \cdot 1} \\ &= \sqrt{9A^2} = 3|A| \end{aligned}$$

c) $\vec{A} = \sum_{i=1}^n A_i \hat{e}_i$, $\vec{B} = \sum_{i=1}^n B_i \hat{e}_i$, where \hat{e}_i are the orthonormal basis.

$$\vec{A} \cdot \vec{B} = \left(\sum_{i=1}^n A_i \hat{e}_i \right) \cdot \left(\sum_{i=1}^n B_i \hat{e}_i \right)$$

$$= (A_1 \hat{e}_1 + A_2 \hat{e}_2 + A_3 \hat{e}_3 + \dots) \cdot (B_1 \hat{e}_1 + B_2 \hat{e}_2 + B_3 \hat{e}_3 + \dots)$$

$$= (A_1 \hat{e}_1 \cdot B_1 \hat{e}_1 + A_2 \hat{e}_2 \cdot B_2 \hat{e}_2 + A_3 \hat{e}_3 \cdot B_3 \hat{e}_3 + \dots)$$

Because basis are orthogonal

$$= A_1 B_1 + A_2 B_2 + \dots$$

$$\vec{A} \cdot \vec{B} = \sum_{i=1}^n A_i B_i$$

d) $|\vec{A}| = \sqrt{\vec{A} \cdot \vec{A}}, \vec{A} = \sum_{i=1}^n A_i \hat{e}_i$
 from part (c) we know

$$\begin{aligned} \vec{A} \cdot \vec{A} &= A_1 A_1 + A_2 A_2 + \dots \\ &= A_1^2 + A_2^2 + \dots \\ &= \sum_{i=1}^n (A_i)^2 \end{aligned}$$

$$\Rightarrow |\vec{A}| = \sqrt{\sum_{i=1}^n A_i^2}$$

e) $f(r, \theta, \phi) = |2\hat{r} + 3\hat{\theta}|$
 $= \sqrt{(2\hat{r} + 3\hat{\theta}) \cdot (2\hat{r} + 3\hat{\theta})}$
 $= \sqrt{4 + 6\hat{r} \cdot \hat{\theta} + 6\hat{r} \cdot \hat{\theta} + 9\hat{\theta} \cdot \hat{\theta}}$
 $= \sqrt{13}$

f) $f(s, \phi, z) = |z\hat{z} + s\hat{s}|$
 $= |z\hat{z} + s\cos\phi\hat{s}|$
 $= \sqrt{(z\hat{z} + s\cos\phi\hat{s}) \cdot (z\hat{z} + s\cos\phi\hat{s})}$
 $= \sqrt{z^2 + s^2\cos^2\phi}$



g) $f(r, \theta, \phi) = |2\hat{z} + \hat{r}|$
 $= |2\cos\theta\hat{z} + \hat{r}|$
 $= \sqrt{4\cos^2\theta + 1}$



$$h) \quad A = (3, \pi/2, \pi/2) \quad B = (4, 0, 0)$$

$$\Rightarrow x =$$

$$x = \rho \sin \theta \cos \phi$$

$$y = \rho \sin \theta \sin \phi$$

$$z = \rho \cos \theta$$

$$A = (0, 3, 0)$$

$$B = (0, 0, 4)$$

$$|(\vec{B} - \vec{A})| = \sqrt{9 + 16} = 5$$

$$i) \quad A = (3, 60^\circ, 90^\circ) \quad B = (4, 45^\circ, 0)$$

$$A = (0, \frac{3\sqrt{3}}{2}, \frac{3}{2})$$

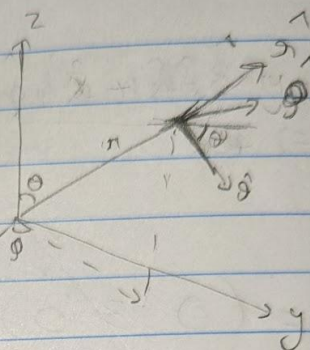
$$B = (2\sqrt{2}, 0, 2\sqrt{2})$$

$$|B - A| = \sqrt{(2\sqrt{2})^2 + (\frac{3\sqrt{3}}{2})^2 + (2\sqrt{2} - \frac{3}{2})^2}$$

$$= 4.0638$$

HN# 9

Q2 $\hat{\theta} \cdot \hat{x} = \cos \theta \cos \phi$
 $\hat{\theta} \cdot \hat{y} = \cos \theta \sin \phi$
 $\hat{\theta} \cdot \hat{z} = -\sin \theta$



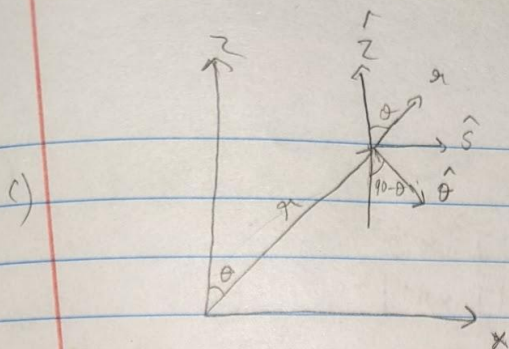
$\hat{n} \cdot \hat{x} = \sin \theta \cos \phi$
 $\hat{n} \cdot \hat{y} = \sin \theta \sin \phi$
 $\hat{n} \cdot \hat{z} = \cos \theta$

$\hat{n} = \sin \theta \cos \phi \hat{x} + \sin \theta \sin \phi \hat{y} + \cos \theta \hat{z}$

$\hat{\theta} \cdot \hat{x} = -\sin \phi$
 $\hat{\theta} \cdot \hat{y} = \cos \phi$
 $\hat{\theta} \cdot \hat{z} = 0$

$\hat{\theta} = \cos \phi \cos \theta \hat{x} + \cos \phi \sin \theta \hat{y} - \sin \phi \hat{z}$
 $\hat{\phi} = -\sin \phi \hat{x} + \cos \phi \hat{y}$

b) $\hat{x} = \cos \theta \cos \phi \hat{\theta} + \sin \theta \cos \phi \hat{n} - \sin \phi \hat{\phi}$
 $\hat{y} = \sin \theta \sin \phi \hat{n} + \cos \theta \sin \phi \hat{\theta} + \cos \phi \hat{\phi}$
 $\hat{z} = \cos \theta \hat{n} - \sin \theta \hat{\theta}$



$$\hat{z} \cdot \hat{n} = \cos \theta$$

$$\hat{z} \cdot \hat{s} = -\sin \theta$$

$$\hat{z} \cdot \hat{\phi} = 0$$

$$\hat{s} \cdot \hat{n} = \sin \theta$$

$$\hat{s} \cdot \hat{s} = \cos \theta$$

$$\hat{s} \cdot \hat{\phi} = 0$$

$$\hat{\phi} \cdot \hat{n} = 0$$

$$\hat{\phi} \cdot \hat{s} = 0$$

$$\hat{\phi} \cdot \hat{\phi} = 1$$

$$\hat{n} = \cos \theta \hat{z} + \sin \theta \hat{s} + 0 \hat{\phi}$$

$$\hat{s} = -\sin \theta \hat{z} + \cos \theta \hat{s}$$

$$\hat{\phi} = \hat{\phi}$$

$$\hat{z} = \cos \theta \hat{n} - \sin \theta \hat{s}$$

$$\hat{s} = \sin \theta \hat{n} + \cos \theta \hat{s}$$

$$\hat{\phi} = \hat{\phi}$$

$$d) \frac{\partial \hat{n}}{\partial \theta} = \frac{\partial (\sin \theta \cos \phi \hat{x} + \sin \theta \sin \phi \hat{y} + \cos \theta \hat{z})}{\partial \theta}$$

$$= \cos \theta \cos \phi \hat{x} + \cos \theta \sin \phi \hat{y} - \sin \theta \hat{z}$$

$$= \hat{\phi}$$

$$\frac{\partial \hat{s}}{\partial \theta} = \frac{\partial (\cos \theta \cos \phi \hat{x} + \cos \theta \sin \phi \hat{y} - \sin \theta \hat{z})}{\partial \theta}$$

$$= -\sin \theta \cos \phi \hat{x} - \sin \theta \sin \phi \hat{y} - \cos \theta \hat{z}$$

$$= -\hat{n}$$

$$\frac{\partial \hat{\phi}}{\partial \theta} = \frac{\partial (-\sin \phi \hat{x} + \cos \phi \hat{y})}{\partial \theta}$$

$$= -\cos \phi \hat{x} - \sin \phi \hat{y}$$

Q3

a)

$$\vec{B}(\vec{r}) = \frac{\mu_0}{2\pi} \frac{\vec{I} \times \vec{r}}{|\vec{I} \times \vec{r}|^2}$$

$$\vec{B}(\vec{r}) \cdot \vec{r} = z\hat{z} + S\hat{s}$$

$$\vec{B}(\vec{r}) = \frac{\mu_0}{2\pi} \frac{\vec{I} \times (z\hat{z} + S\hat{s})}{|\vec{I} \times (z\hat{z} + S\hat{s})|^2}$$

$$= \frac{\mu_0}{2\pi} \frac{\vec{I} \hat{z} \times (z\hat{z} + S\hat{s})}{|\vec{I} \times (z\hat{z} + S\hat{s})|^2}$$

$$= \frac{\mu_0}{2\pi} \frac{I \cdot S \cdot \hat{z} \times \hat{s}}{|S\hat{z} \times \hat{s}|^2} = \frac{\mu_0 I S \hat{\phi}}{2\pi |S\hat{\phi}|^2}$$

$$= \frac{\mu_0 I S \hat{\phi}}{2\pi S^2} = \frac{\mu_0 I}{2\pi S} \hat{\phi}$$

$$b) \quad B(\vec{r}) = \frac{\mu_0}{2\pi} \frac{\vec{I} \times \vec{r}}{|\vec{I} \times \vec{r}|^2}$$

$$= \frac{\mu_0}{2\pi} \frac{I \hat{z} \times (r \hat{r})}{|\hat{z} \times r \hat{r}|^2} = \frac{\mu_0 I r}{2\pi |r \hat{z} \times \hat{r}|^2}$$

$$\text{Now } \hat{z} = \cos\theta \hat{r} - \sin\theta \hat{\theta} \quad (\text{from 82})$$

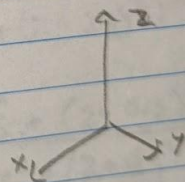
$$\Rightarrow \frac{\mu_0 I R}{2\pi} \frac{(\cos\theta \hat{r} - \sin\theta \hat{\theta}) \times \hat{r}}{R^2 |\hat{z} \times \hat{r}|^2}$$

$$= \frac{\mu_0 I R \sin\theta \hat{\phi}}{2\pi R^2 \sin^2\theta} = \frac{\mu_0 I \hat{\phi}}{2\pi R \sin\theta}$$

$$c) \quad \vec{I} = I \hat{x}$$

$$B(\vec{r}) = \frac{\mu_0}{2\pi} \frac{\vec{I} \times \vec{r}}{|\vec{I} \times \vec{r}|^2}$$

$$= \frac{\mu_0}{2\pi} \frac{I \hat{x} \times (x \hat{x} + y \hat{y} + z \hat{z})}{|\hat{x} \times (x \hat{x} + y \hat{y} + z \hat{z})|^2}$$

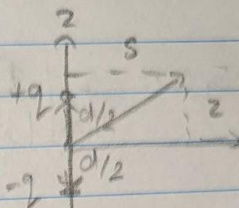


$$= \frac{\mu_0}{2\pi} \frac{I(\hat{y}\hat{z} - z\hat{y})}{|y\hat{z} - z\hat{y}|^2}$$

$$= \frac{\mu_0}{2\pi} \frac{I(\hat{y}\hat{z} - z\hat{y})}{(y^2 + z^2)}$$

Phy 225 ARROW Method
HW #9

Q4 $\vec{E}(\vec{r}) = \frac{q}{4\pi\epsilon_0} \frac{\vec{r} - \vec{r}_q}{|\vec{r} - \vec{r}_q|^3}$



$$\vec{E}_1(\vec{r}) = \frac{q(\vec{s} + z\hat{z} - z_1\hat{z})}{4\pi\epsilon_0 |\vec{s} + z\hat{z} - z_1\hat{z}|^3}$$

$$\vec{E}_2(\vec{r}) = \frac{q(\vec{s} + z\hat{z} + z_2\hat{z})}{4\pi\epsilon_0 |\vec{s} + z\hat{z} + z_2\hat{z}|^3}$$

$$\vec{E} = \vec{E}_1 + \vec{E}_2 = \frac{q}{4\pi\epsilon_0} \left[\frac{(\vec{s} + (z - z_1)\hat{z})}{|\vec{s} + (z - z_1)\hat{z}|^3} + \frac{(\vec{s} + (z + z_2)\hat{z})}{|\vec{s} + (z + z_2)\hat{z}|^3} \right]$$

$$= \frac{q}{4\pi\epsilon_0} \left[\frac{\vec{s} + (z - z_1)\hat{z}}{(\sqrt{s^2 + (z - z_1)^2})^{3/2}} + \frac{\vec{s} + (z + z_2)\hat{z}}{(\sqrt{s^2 + (z + z_2)^2})^{3/2}} \right]$$

$$= \frac{p}{d 4\pi\epsilon_0} \left[\frac{\vec{s} + (z - d/2)\hat{z}}{(\sqrt{s^2 + (z - d/2)^2})^{3/2}} + \frac{\vec{s} + (z + d/2)\hat{z}}{(\sqrt{s^2 + (z + d/2)^2})^{3/2}} \right]$$

$$= \frac{p}{d 4\pi\epsilon_0} \left[\frac{s \cos \phi \hat{x} + (z - d/2)\hat{z}}{(\sqrt{s^2 + (z - d/2)^2})^{3/2}} \right]$$