Assignment 5 HDL

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Q1.4 bit right shift register using behavioral modeling non blocking statement

Test Operator code:

```
// 4- bit right shift register using behavioral modeling
// a

module right_shift( in,out,reset,clk);
  input in;
  input clk;
  output reg [3:0] out;
  input reset;
  always @(posedge clk)
  begin
    if(reset)
        out <= 4'b0000;
    else
        out <= {out[2:0],in};
  end

endmodule</pre>
```

Q2.4 bit right shift register using behavioral modeling blocking statement

```
// 4- bit right shift register using behavioral modeling
// a
```

```
module right_shift( in,out,reset,clk);
  input in;
  input clk;
  output reg [3:0] out;
  input reset;
  always @(posedge clk)
  begin
    if(reset)
        out = 4'b0000;
    else
        out = {out[2:0],in};
  end
endmodule
```

Testbench code:

```
// Test bench
timescale lns/lps
include "right_shift.v"

module right_shift_tb;

// Inputs
  reg in;
  reg reset;
  reg clk;

// Outputs
  wire [3:0] out;

// Instantiate the Unit Under Test (UUT)
  right_shift uut (
    .in(in),
    .out(out),
    .clk(clk),
    .reset(reset)
);
initial begin
  // Initialize Inputs
```

```
$dumpfile("right_shift_tb.vcd");
$dumpvars(0,right_shift_tb);
   $display("out = %b",out);
    $display("out = %b",out);
   $display("out = %b",out);
   $display("out = %b",out);
   $display("out = %b",out);
   $display("out = %b",out);
    $display("out = %b",out);
```

endmodule

