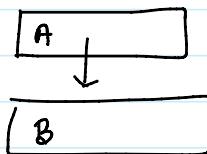
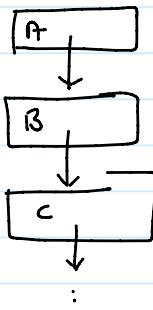


Types of Inheritance

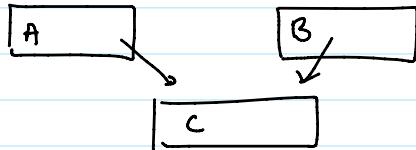
1. Single level inheritance



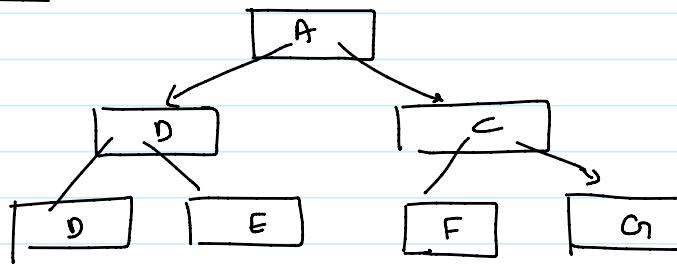
2. Multi level inheritance



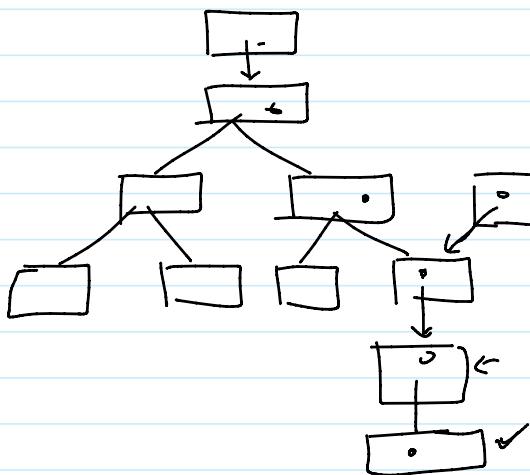
3. Multiple inheritance



4. (Tree) | Hierarchical inheritance



5. Hybrid Inheritance



```
#include<iostream>
using namespace std;
class A
{
    int x;
public:
    A()
    {
        cout<<"Default constructor of class A\n";
    }
    A(int x1)
    {
        x=x1;
        cout<<"Parameterized constructor of class A\n";
    }
    void output()
    {
        cout<<"X="<<x<<" ";
    }
};
class B:public A{
    int y;
public:
    B():A()
    {
```

```

        cout<<"Default constructor of class B\n";
    }
B(int x1, int y1):A(x1)
{
    y=y1;
    cout<<"Parameterized constructor of class B\n";
}
void output()
{
    A::output();
    cout<<"Y="<<y<<endl;
}
};

int main()
{
    B b1;
    B b2(10,20);
    b2.output();
}

```

```

.
.

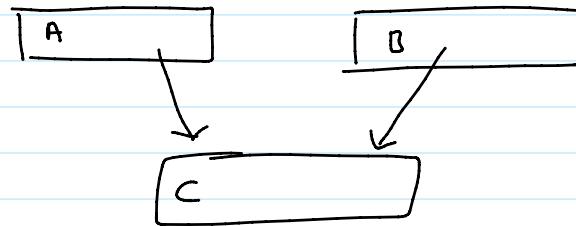
#include<iostream>
using namespace std;
class A
{
    int x;
public:
    A()
    {
        cout<<"Default constructor of class A\n";
    }
    A(int x1)
    {
        x=x1;
        cout<<"Parameterized constructor of class A\n";
    }
    void output()
    {
        cout<<"X="<<x<<" ";
    }
};
class B:public A{
    int y;
public:
    B():A()
    {
        cout<<"Default constructor of class B\n";
    }
    B(int x1, int y1):A(x1)
    {
        y=y1;
        cout<<"Parameterized constructor of class B\n";
    }
    void output()
    {
        A::output();
        cout<<"Y="<<y<<" ";
    }
};
class C:public B
{
    int z;
public:

```

```

C():B()
{
    cout<<"Default constructor of class C\n";
}
C(int x1, int y1, int z1):B(x1,y1)
{
    z=z1;
    cout<<"Parameterized constructor of class C\n";
}
void output()
{
    cout<<"Z="<<z<<endl;
};
int main()
{
    C c1;
    C c2(10,20,30);
    c2.output();
}

```



```

#include<iostream>
using namespace std;
class A
{
    int x;
public:
    A()
    {
        cout<<"Default constructor of class A\n";
    }
    A(int x1)
    {
        x=x1;
        cout<<"Parameterized constructor of class A\n";
    }
    void output()
    {
        cout<<"X="<<x<< " ";
    }
};
class B{
    int y;
public:
    B()
    {
        cout<<"Default constructor of class B\n";
    }
    B(int y1)
    {
        y=y1;
        cout<<"Parameterized constructor of class B\n";
    }
    void output()

```

```

    {
        cout<<"Y="<

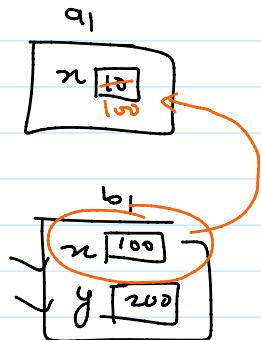
### Object slicing :-


```

C.O b₁ = a₁; P.O X

A a₁ = 10;

B b₁(100,200);



P.O a₁ = b₁; C.O ✓

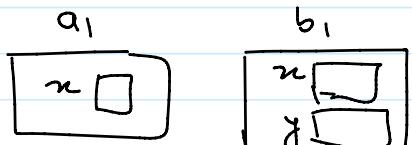
Pointer :-

A a₁;

B b₁;

A *P₁;

P₁ = &a₁;



B *P₂;

P₂ = &b₁;

$P_2 = f_{A_1}; \quad X$

$C.P = f P.O$ X

$P_1 = f_{B_1}; \quad \checkmark$

$P.P = f C.O$ ✓

-protected :-

```
#include<iostream>
using namespace std;
class A
{
protected:
    int x;
public:
    A()
    {
        cout<<"Default constructor of class A\n";
    }
    A(int x1)
    {
        x=x1;
        cout<<"Parameterized constructor of class A\n";
    }
    void output()
    {
        cout<<"X="<<x<<" ";
    }
};
class B:public A{
    int y;
public:
    B():A()
    {
        cout<<"Default constructor of class B\n";
    }
    B(int x1,int y1):A(x1)
    {
        y=y1;
        cout<<"Parameterized constructor of class B\n";
    }
    void output()
    {
        //A::output();
        cout<<"X="<<x<<endl;
        cout<<"Y="<<y<<endl;
    }
};
int main()
{
    B b1(10,20);
    b1.output();
    //b1.A::x;      error
}
```

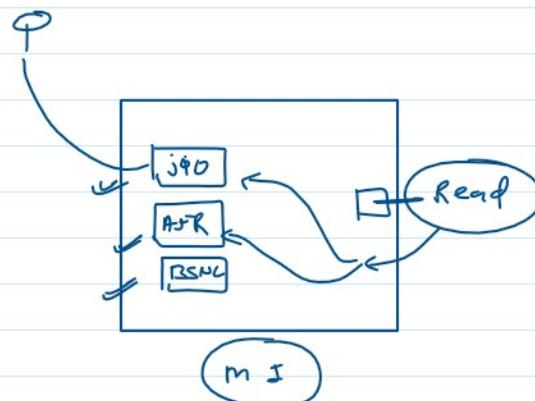
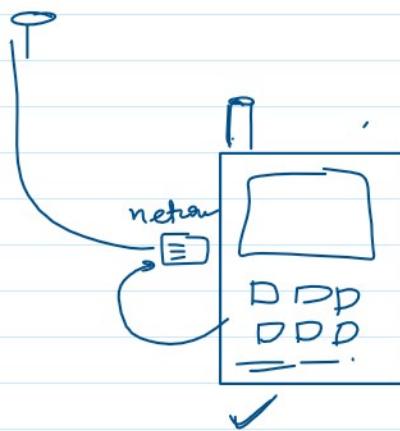
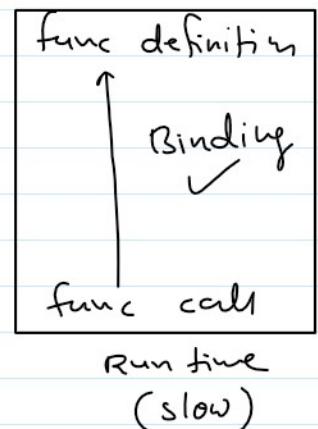
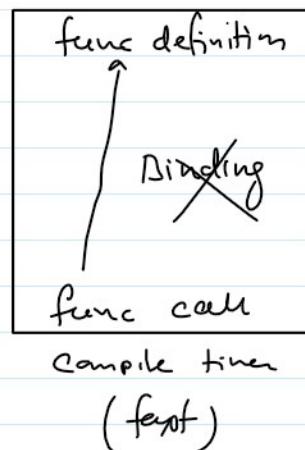
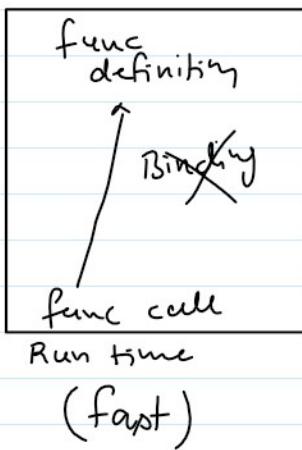
}

virtual function | Dynamic Binding ✓ | Run time polymorphism.

~~default~~ Compile time
Binding
(static Binding)

Run time Binding

(Dynamic Binding)



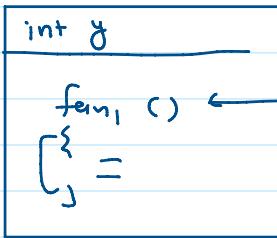
class A

```
int n
fun1()
{ = }
>
```

A obj

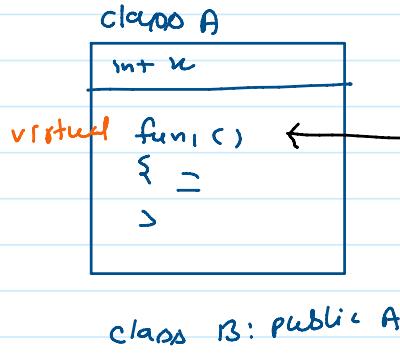
a1.fun1()

class B: public A



B b1;

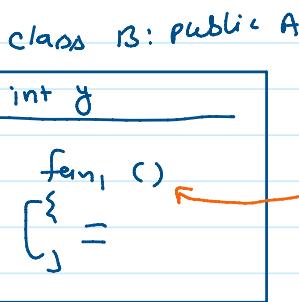
b1.fun1();



B b1; \rightarrow Compile \rightarrow class A
A *p; \rightarrow Run \rightarrow class B

p = &b1;

p->fun1();



Run time binding

static fun

```
#include<iostream>
using namespace std;
class A
{
public:
    virtual void fun1()
    {
        cout<<"fun1 of class A\n";
    }
};
class B:public A{
public:
    void fun1()
    {
        cout<<"fun1 of class B\n";
    }
};
int main()
{
    A *p;
    B b1;
    p=&b1;
    p->fun1();
}
```

a->fun1()

↑
obj

A::fun1()

↑
Class

```

#include<iostream>
using namespace std;
class mobile //abstract class
{
public:
    virtual void network()=0; //pure virtual function
};
class BSNL:public mobile
{
public:
    void network()
    {
        cout<<"Class BSNL\n";
    }
};
class jio:public mobile
{
public:
    void network()
    {
        cout<<"Class jio\n";
    }
};
int main()
{
    mobile *p;
    int n;
    cout<<"1. BSNL\n2. jio ";
    cin>>n;
    if(n==1)
        p=new BSNL;
    else
        p=new jio;
    p->network();
    //mobile mi;      error
    delete p;
}

```

STL (standard template library)

1. Iterator (Pointer)

2. Container (store) → vector, stack, queue, list, set, map

3. Algorithm

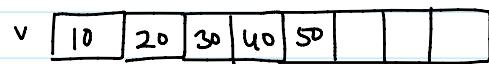
4. Functors

include <bits/stdc++.h>

vector :-

include <vector>

class → vector <int> v;
 template ↓ object
 v [10 20 30 40 50]



```

v.push_back(10);
v.push_back(20);
v.push_back(30);
v.push_back(40);
v.push_back(50);

→ v.size(); → 5
v.capacity(); → 8

```

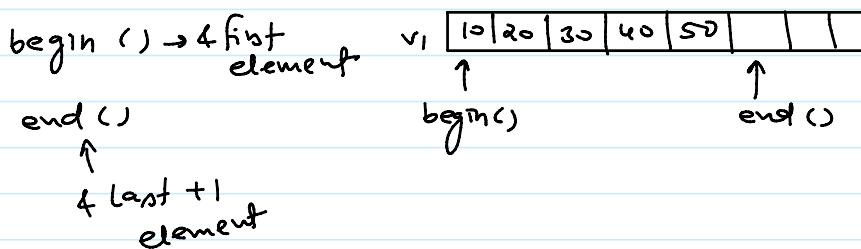
↑
No of elements

Iterator :-

- ① iterator begin(), end() | Read & write
- ② reverse iterator rbegin(), rend() | read & write
- ③ constant iterator cbegin(), cend() | read only
- ④ constant Reverse iterator crbegin(), crend() | read only

iterator :-

```
vector<int> :: iterator i;
```



```

#include<iostream>
#include<vector>
using namespace std;
int main()
{
    vector<int> v1;
    cout<<"Size="<<v1.size()<<endl;
    cout<<"Capacity="<<v1.capacity()<<endl;
    v1.push_back(10);
    v1.push_back(20);
    v1.push_back(30);
    v1.push_back(40);
}

```

```

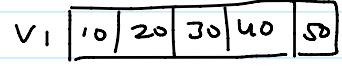
v1.push_back(50);
cout<<"Size="<<v1.size()<<endl;
cout<<"Capacity="<<v1.capacity()<<endl;
vector<int>::iterator i;
for(i=v1.begin();i!=v1.end();i++)
{
    *i += 2;
    cout<<*i<< " ";
}
cout<<endl;
vector<int>::reverse_iterator j;
for(j=v1.rbegin();j!=v1.rend();j++)
{
    *j -= 2;
    cout<<*j<< " ";
}
cout<<endl;
vector<int>::const_iterator k;
for(k=v1.cbegin();k!=v1.cend();k++)
{
    /*k += 2;
    cout<<*k<< " ";
}
cout<<endl;
vector<int>::const_reverse_iterator l;
for(l=v1.crbegin();l!=v1.crend();l++)
{
    /*l += 2;
    cout<<*l<< " ";
}
cout<<endl;
for(auto x=v1.crbegin();x!=v1.crend();x++)
{
    cout<<*x<< " ";
}
}

```

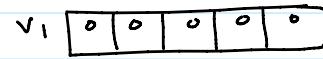
Vector :- (Dynamic Array)

vector<int> v1;

vector<int> v1 = {10, 20, 30, 40, 50};

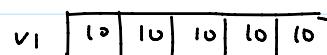


vector<int> v1(5);



vector<int> v1(5, 10);

↑
default
Value



#include<iostream>

```

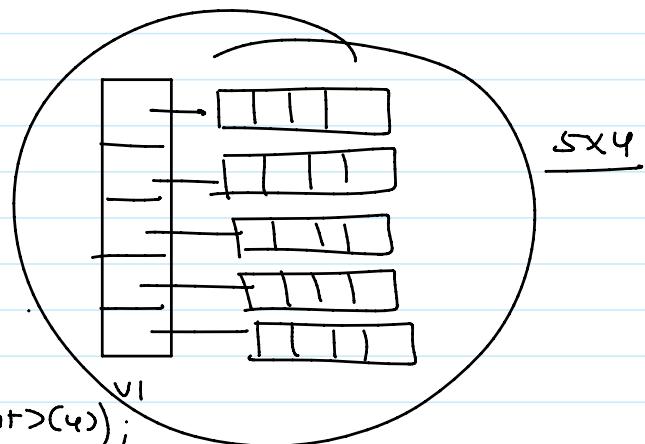
#include<vector>
using namespace std;
void output(vector<int> &v)
{
    // for(int i=0;i<v.size();i++)
    //     //cout<<v.at(i)<<" ";
    //     cout<<v[i]<<" ";
    for(int i:v)
        cout<<i<<" ";
    cout<<endl;
}
int main()
{
    vector<int> v1={10,20,30,40,50};
    cout<<"Size "<<v1.size()<<endl;
    cout<<"Capacity "<<v1.capacity()<<endl;
    v1.push_back(60);
    cout<<"Size "<<v1.size()<<endl;
    cout<<"Capacity "<<v1.capacity()<<endl;
    v1.shrink_to_fit();
    cout<<"Size "<<v1.size()<<endl;
    cout<<"Capacity "<<v1.capacity()<<endl;
    output(v1);
    v1.insert(v1.begin()+2,100);
    output(v1);
    v1.pop_back();
    output(v1);
    v1.erase(v1.begin()+3);
    output(v1);
    vector<int> v2={100,200,300};
    v1.swap(v2);
    output(v1);
    output(v2);
    v2.erase(v2.begin()+2,v2.end());
    output(v2);
}

```

}

vector < vector < int > > v1;

5x4



vector <vector <int>> v1(3, vector<int>(4));

3x4

Row

Col

```

#include<iostream>
#include<vector>
using namespace std;
void output(vector<int> &v)
{

```

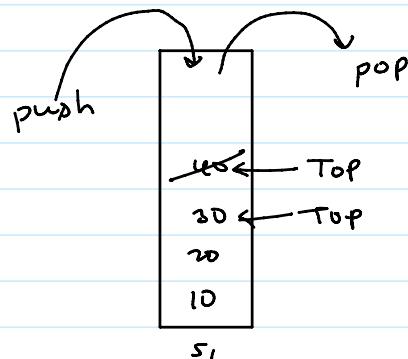
```

// for(int i=0;i<v.size();i++)
//     //cout<<v.at(i)<< " ";
//     cout<<v[i]<< " ";
for(int i:v)
    cout<<i<<" ";
cout<<endl;
}
int main()
{
    vector<vector<int>> v1={
        {10,20,30,40},
        {11,12,13,14},
        {21,22,23,24},
        {31,32,33,34}
    };
    for(vector<int> i:v1)
    {
        for(int j:i)
            cout<<j<<" ";
        cout<<endl;
    }
}

```

Stack : \rightarrow (LIFO)

stack <int> s1;

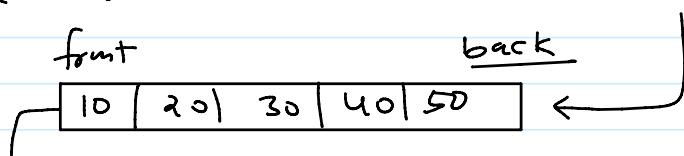


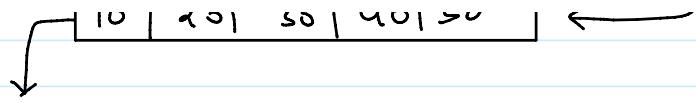
```

#include<iostream>
#include<stack>
using namespace std;
int main()
{
    stack<int> s1;
    s1.push(10);
    s1.push(20);
    s1.push(30);
    s1.push(40);
    s1.push(50);
    while(!s1.empty())
    {
        cout<<s1.top()<<endl;
        s1.pop();
    }
}

```

queue \rightarrow (FIFO)





```
#include<iostream>
#include<queue>
using namespace std;
int main()
{
    queue<int> q1;
    q1.push(10);
    q1.push(20);
    q1.push(30);
    q1.push(40);
    q1.push(50);
    cout<<q1.front()<<endl;
    cout<<q1.back()<<endl;
    q1.pop();
    q1.push(60);
    cout<<q1.front()<<endl;
    cout<<q1.back()<<endl;
}

#include<iostream>
#include<queue>
using namespace std;
int main()
{
    priority_queue<int> q1;
    q1.push(10);
    q1.push(50);
    q1.push(20);
    q1.push(30);
    while(!q1.empty())
    {
        cout<<q1.top()<<endl;
        q1.pop();
    }
}
```