AKSHAY.T 21105012

FINITE ELEMENT METHOD FOR FLUID
DUNAMICS

ASSIGNMENT-I

4>

$$\frac{\partial^2 u}{\partial x^2} = -f = -2x.$$

0 - - 9x0 + (1 => (1=0

C1+12= 216

cz= 8/8

2>

$$u \in \mathcal{S}$$
, $\omega \in \mathcal{N}$ $\mathcal{S} = \left\{ \alpha \left(\alpha \in \mathcal{H}^{1}, \alpha \left(z \right) = 9 \right) \right\}$

Jω, χ α, χ dx = J ωfdx + hω(0) V= { co|ω ε H², ω(1) = 0 }.

a(w,u) = (w, f) + h w(0) (wak form)

cob ∈ vh, vh ∈ 8h, oh ∈ vh

a(w, ap) = (cop, f) + pop(e) -a(cop, gp) (dalerkin form)

who E CANA

Nn+1(1)=9

20h = I dBNB.

a (ICANA, Z dBNB) = (ICANA, f) ILHWA(O) - a (ICANA, NO+1)9

Z (A[] a (NA, NB) dB] = Z (A((NA, F) + h NA (0) - a (NA, NO+1)g.

K = Q(NA, NB) F = (NA, F) + hNA(0) - Q (NA, ND+1) 9

U- I dons dn+1=9

$$\int_{0}^{\infty} \int_{0}^{\infty} \int_{$$

$$\frac{1}{30} = \frac{1}{3}, \quad h = \frac{1}{3}$$

$$\frac{1}{3} = \frac{1}{3} = \frac{1}{3} = \frac{1}{3} = \frac{1}{3}$$

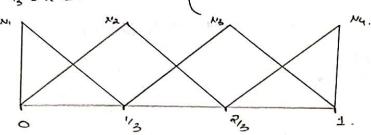
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$$\frac{1}{3} = \frac{1}{3}$$

$$\frac{1}$$



$$k_{13} = k_{51} = \frac{Q}{1}$$

$$k_{22} = Q(N_2, N_2) = \int_{0}^{1} 3x^3 dx + \int_{0}^{1} -3x^3 x dx = \frac{Q}{3} + \frac{Q}{3} = \frac{18}{3} = \frac{G}{3}$$

$$k_{23} = k_{52} = \int_{1}^{4} -3x \, 3 \, d\pi = -9 \times \frac{1}{3} = -\frac{3}{2}$$

$$k_{23} = k_{52} = \int -3x \cdot 3 \, dx = -4x \cdot 3 = 2$$
.
 $k_{33} = Q(N_5, N_5) = \int 3x \cdot 3 \, dx + \int -3x - 3 \, dx = \frac{9}{3} + \frac{9}{3} = \frac{6}{3}$.

$$K = \begin{bmatrix} 3 & -3 & 0 \\ -5 & 6 & -3 \\ 0 & -3 & 6 \end{bmatrix}$$

$$F_{1} = (N_{1}, q_{X}) + hN_{1}(0) - a(N_{1}, N_{4}) g$$

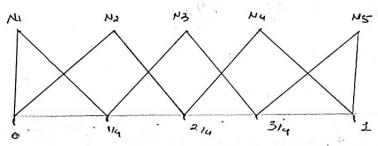
$$F_{1} = \int_{0}^{1/2} (x - 3x^{2}) q \, dx + hx \, d - 0 = Q \left(\frac{1}{2} x^{1/q} - \frac{3}{2} y^{2} \right) \frac{1}{2} q + h$$

$$F_{2} = \int_{0}^{1/2} 3q x^{2} \, dx + \int_{0}^{1/2} (2x - 3x^{2}) q \, dx + 0$$

$$F_{2} = \int_{0}^{1/2} 3q x^{2} \, dx + \int_{0}^{1/2} (2x - 3x^{2}) q \, dx + 0$$

$$F_{2} = \int_{0}^{1/2} 3q x^{2} \, dx + \int_{0}^{1/2} (2x - 3x^{2}) q \, dx + 0$$

$$F_{3} = 2 \int_{0}^{1/2} 4q + Q_{3} + + Q_{3$$



Kn= a (N1 / N)= 5-4x-4 dx = 1614 24

$$K_{13} = K_{14} = 0 = K_{31} = K_{41}$$

$$K_{22} = \alpha(N_{2}, N_{2}) = \int_{0}^{1/4} 4x4 \, dx + \int_{0}^{1/4} -4x - 4dx = 16/4 + \frac{16}{4} = \frac{8}{4}$$

$$K_{24} = K_{42} = 0$$
. v_{4}

$$K_{34} = K_{42} = 0$$
. v_{4}

$$V_{4}$$

$$V_{5}$$

$$V_{4}$$

$$V_{5}$$

$$V_{5}$$

$$V_{7}$$

$$K = \begin{bmatrix} 4 & -4 & 0 & 0 \\ -4 & 8 & -4 & 0 \\ 0 & -4 & 8 & -4 \\ 0 & 0 & -4 & 8 \end{bmatrix}$$

$$d = k^{7}F - \frac{1}{4} \begin{pmatrix} 4 & 3 & 2 & 1 \\ 3 & 3 & 2 & 1 \\ 2 & 8 & 2 & 1 \\ 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} 2/9c \\ 2/16 \\ 2/8 \\ 9/48 \end{pmatrix} = \begin{pmatrix} 12/26 \\ 2/26 \\ 3/48 \\ 3/48 \end{pmatrix} = \begin{pmatrix} 12/26 \\ 2/26 \\ 3/48 \\ 3/48 \end{pmatrix} = \begin{pmatrix} 12/26 \\ 2/26 \\ 3/48 \\ 3/48 \end{pmatrix}$$

uh d, N, +d, Ns + d, Ns + dq N4 . + 9 M5°

3> Yes the stiffness making is bonded (tridiagonal). No mothers what is the value of g and h shiffness making will be bonded. That is 'g' and 'h' has no influence in the bandedness of 'K'.

4> re, x = | uh, x - u, x | / 2/2.

Ch, x = 26 (-4) { 0 = x = 1/2 } + 212 { 4 0 = x = 1/4 + 48 } 4 1/4 = x = x/4 =

dexact, x = - 39x%.

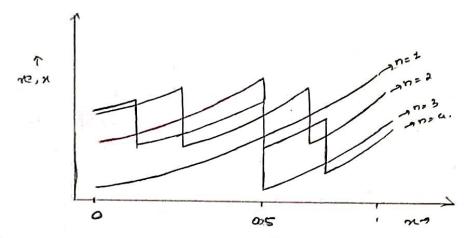
$$\frac{\left|(u_{1}^{h}x-u_{1}x)\right|_{x=V_{g}}}{\left|(u_{d}^{h})^{2}\right|_{x=V_{g}}} = \frac{\left|\left(-42/G + \frac{21x42}{128}\right) + \left(\frac{32}{6}(V_{64})\right)\right|}{2G} = \frac{5\cdot208\times10^{-3}}{2}$$

$$\frac{|u^{h}, x - u, x|}{(u_{h})} |_{x = 3/8} = \frac{|-a| \times u_{R}}{|a|} + \frac{4}{4} \frac{x}{4} \times u_{R} + \frac{3}{6} (8/64)|}{8/12} = \frac{5 \cdot 208 \times 10^{-5}}{8}$$

$$\frac{|u^{h}, x - u'x|}{(9u)} \Big|_{\pi = 5/8} = \Big| \frac{3x - 4x}{48} + \frac{34x4x}{384} + \frac{3x}{6} {25/64} \Big| = \frac{5 \cdot 208 \times 10^{-3}}{24}$$

They all ore equal

5) for the plot of ln(Ne,x) vs ln h for each h values the value of ln(re,x) will be some at the midnoint of each elements.



intercept ac = - Pn(2/2)

it gives on indication of magnitude of error when xeo. Slope gives an indication amount of roduction in delative error with x. Steeper slope indicates higher reduction.

Slopes are adjusted in such a way as to reduce the re, x for higher n values.

B)

```
###AKSHAY J
import numpy as np
from matplotlib import pyplot as plt
from scipy.integrate import quad
###GIVEN
n1=10
n2 = 50
n3=100
n4 = 3
h1=1/n1
h2=1/n2
h3=1/n3
h4=1/n4
q=1
Nder1=np.zeros((n1+1,1000))
Nder2=np.zeros((n2+1,1000))
Nder3=np.zeros((n3+1,1000))
Nder4=np.zeros((n4+1,1000))
x=np.linspace(0,1,1000)
xn1=np.linspace(0,1,n1+1)
xn2=np.linspace(0,1,n2+1)
xn3=np.linspace(0,1,n3+1)
xn4=np.linspace(0,1,n4+1)
K1=np.zeros((n1,n1))
K2=np.zeros((n2,n2))
K3=np.zeros((n3,n3))
K4=np.zeros((n4,n4))
F1=np.zeros((n1,1))
F2=np.zeros((n2,1))
F3=np.zeros((n3,1))
F4=np.zeros((n4,1))
ke=np.zeros((2,2))
fe=np.zeros((2,1))
d1=np.zeros((n1,1))
d2=np.zeros((n2,1))
d3=np.zeros((n3,1))
d4=np.zeros((n4,1))
u exact=np.zeros(1000)
```

```
uexact slope=np.zeros(1000)
N1=np.zeros((n1+1,1000))
N2=np.zeros((n2+1,1000))
N3=np.zeros((n3+1,1000))
N4 = np.zeros((n4+1,1000))
Re1=0
Re2=0
Re3=0
Re4=0
########SETTING THE BASIS FUNCTION VALUE
for A in range (1, n1):
      if x[i] <= h1:</pre>
       N1[0,i] = (xn1[1]-x[i])/h1
      if x[i] >= xn1[n1-1]:
       N1[n1,i] = (x[i]-xn1[n1-1])/h1
      if xn1[A-1] \le x[i] and x[i] \le xn1[A]:
        N1[A, i] = (x[i] - xn1[A-1])/h1
      if xn1[A] \le x[i] and x[i] \le xn1[A+1]:
        N1[A,i] = (xn1[A+1] - x[i]) / h1
for A in range(1,n2):
    for i in range (1000):
      if x[i] <= h2:</pre>
       N2[0,i] = (xn2[1]-x[i])/h2
      if x[i] >= xn2[n2-1]:
       N2[n2,i] = (x[i]-xn2[n2-1])/h2
      if xn2[A-1] \le x[i] and x[i] \le xn2[A]:
        N2[A,i] = (x[i]-xn2[A-1])/h2
      if xn2[A] \le x[i] and x[i] \le xn2[A+1]:
        N2[A,i] = (xn2[A+1] - x[i]) / h2
for A in range(1,n3):
    for i in range(1000):
      if x[i] <= h3:
       N3[0,i] = (xn3[1]-x[i])/h3
      if x[i] >= xn3[n3-1]:
       N3[n3,i] = (x[i]-xn3[n3-1])/h3
```

```
if xn3[A-1] \le x[i] and x[i] \le xn3[A]:
        N3[A, i] = (x[i] - xn3[A-1])/h3
      if xn3[A] \le x[i] and x[i] \le xn3[A+1]:
        N3[A,i] = (xn3[A+1] - x[i]) / h3
for A in range (1, n4):
      if x[i] <= h4:</pre>
       N4[0,i] = (xn4[1]-x[i])/h4
      if x[i] >= xn4[n4-1]:
      N4[n4,i] = (x[i]-xn4[n4-1])/h4
      if xn4[A-1] \le x[i] and x[i] \le xn4[A]:
        N4[A, i] = (x[i] - xn4[A-1])/h4
      if xn4[A] \le x[i] and x[i] \le xn4[A+1]:
        N4[A,i] = (xn4[A+1] - x[i]) / h4
####
for A in range (1, n1):
    for i in range (1000):
      if xn1[0] \le x[i] and x[i] \le xn1[1]:
      if xn1[n1 - 1] \le x[i] and x[i] \le xn1[n1]:
        Nder1[n1,i] = (1) / h1
      if xn1[A - 1] \le x[i] and x[i] \le xn1[A]:
                 Nder1[A,i] = (1) / h1
      if xn1[A] \le x[i] and x[i] \le xn1[A+1]:
                 Nder1[A,i] = (-1) / h1
for A in range (1, n2):
    for i in range (1000):
      if xn2[0] \le x[i] and x[i] \le xn2[1]:
        Nder2[0,i] = (-1) / h2
      if xn2[n2 - 1] \le x[i] and x[i] \le xn2[n2]:
        Nder2[n2,i] = (1) / h2
      if xn2[A - 1] \le x[i] and x[i] \le xn2[A]:
                Nder2[A,i] = (1) / h2
      if xn2[A] \le x[i] and x[i] \le xn2[A+1]:
                Nder2[A,i] = (-1) / h2
for A in range (1, n3):
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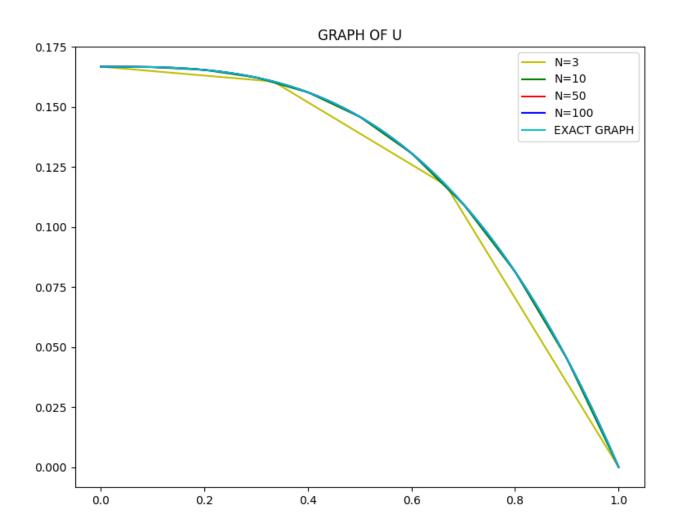
```
if xn3[0] \le x[i] and x[i] \le xn3[1]:
        Nder3[0,i] = (-1) / h3
      if xn3[n3 - 1] \le x[i] and x[i] \le xn3[n3]:
        Nder3[n3,i] = (1) / h3
      if xn3[A - 1] \le x[i] and x[i] \le xn3[A]:
                Nder3[A,i] = (1) / h3
      if xn3[A] \le x[i] and x[i] \le xn3[A+1]:
                Nder3[A,i] = (-1) / h3
for A in range (1, n4):
    for i in range(1000):
      if xn4[0] \le x[i] and x[i] \le xn4[1]:
        Nder4[0,i] = (-1) / h4
      if xn4[n4 - 1] \le x[i] and x[i] \le xn4[n4]:
        Nder4[n4,i] = (1) / h4
      if xn4[A - 1] \le x[i] and x[i] \le xn4[A]:
                Nder4[A,i] = (1) / h4
      if xn4[A] \le x[i] and x[i] \le xn4[A+1]:
                Nder4[A,i] = (-1) / h4
###########CALCULATING TE EXACT GRAPH
for i in range(len(x)):
   u = xact[i] = (q / 6) - ((q * x[i] ** 3) / 6)
for i in range (0, len(x)):
    uexact slope[i]=(-q*x[i]**2)/2
##########FINDING Ke AND Fe AND ASSEMBLING IT TO
for a in range (len(xn1)-1):
           ke[i][j] = ((-1)**(i+j))/h1
           f = lambda zeta: (h1/8) *q*
(h1*zeta+xn1[a]+xn1[a+1]) *(((-1)**(i+1) * zeta) +1)
           f=quad(f,-1,1)
           fe[i][0]=f[0]
    if a = = n1 - 1:
        K1[a][a] = K1[a][a] + ke[0][0]
        F1[a][0] = F1[a][0] + fe[0][0]
    else:
      K1[a][a] = K1[a][a] + ke[0][0]
      K1[a][a+1] = K1[a][a+1] + ke[0][1]
      K1[a+1][a] = K1[a+1][a] + ke[1][0]
```

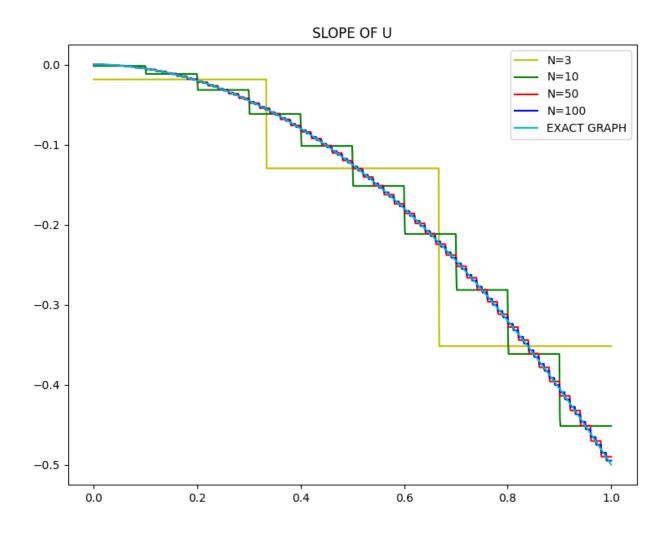
```
K1[a+1][a+1] = K1[a+1][a+1] + ke[1][1]
      F1[a][0] = F1[a][0] + fe[0][0]
      F1[a+1][0] = F1[a+1][0] + fe[1][0]
ke=np.zeros((2,2))
fe=np.zeros((2,1))
for a in range (len(xn2)-1):
           ke[i][j] = ((-1)**(i+j))/h2
           f = lambda zeta: (h2/8) *q*
(h2*zeta+xn2[a]+xn2[a+1]) *(((-1)**(i+1) * zeta) +1)
           f=quad(f,-1,1)
           fe[i][0]=f[0]
    if a == n2 - 1:
        K2[a][a] = K2[a][a] + ke[0][0]
        F2[a][0] = F2[a][0] + fe[0][0]
    else:
      K2[a][a] = K2[a][a] + ke[0][0]
      K2[a][a+1] = K2[a][a+1] + ke[0][1]
      K2[a+1][a] = K2[a+1][a] + ke[1][0]
      K2[a+1][a+1] = K2[a+1][a+1] + ke[1][1]
      F2[a][0] = F2[a][0] + fe[0][0]
      F2[a+1][0] = F2[a+1][0] + fe[1][0]
ke=np.zeros((2,2))
fe=np.zeros((2,1))
for a in range (len(xn3)-1):
    for i in range (0,2):
           ke[i][j] = ((-1)**(i+j))/h3
           f = lambda zeta: (h3/8) *q*
(h3*zeta+xn3[a]+xn3[a+1]) *(((-1)**(i+1) * zeta) +1)
           f=quad(f,-1,1)
           fe[i][0]=f[0]
    if a == n3 - 1:
        K3[a][a] = K3[a][a] + ke[0][0]
        F3[a][0] = F3[a][0] + fe[0][0]
    else:
      K3[a][a] = K3[a][a] + ke[0][0]
      K3[a][a+1] = K3[a][a+1] + ke[0][1]
      K3[a+1][a] = K3[a+1][a] + ke[1][0]
      K3[a+1][a+1] = K3[a+1][a+1] + ke[1][1]
      F3[a][0] = F3[a][0] + fe[0][0]
```

```
F3[a+1][0] = F3[a+1][0] + fe[1][0]
fe=np.zeros((2,1))
for a in range (len(xn4)-1):
    for i in range (0,2):
        for j in range (0,2):
           ke[i][j] = ((-1)**(i+j))/h4
           f = lambda zeta: (h4/8) *q*
(h4*zeta+xn4[a]+xn4[a+1]) *(((-1)**(i+1) * zeta) +1)
           f=quad(f,-1,1)
           fe[i][0]=f[0]
    if a = = n4 - 1:
        K4[a][a] = K4[a][a] + ke[0][0]
        F4[a][0] = F4[a][0] + fe[0][0]
    else:
      K4[a][a] = K4[a][a] + ke[0][0]
      K4[a][a+1] = K4[a][a+1] + ke[0][1]
      K4[a+1][a] = K4[a+1][a] + ke[1][0]
      K4[a+1][a+1] = K4[a+1][a+1] + ke[1][1]
      F4[a][0] = F4[a][0] + fe[0][0]
      F4[a+1][0] = F4[a+1][0] + fe[1][0]
############CALCULATING THE D VALUE
d1=np.linalq.pinv(K1) @ F1
d2=np.linalq.pinv(K2) @ F2
d3=np.linalq.pinv(K3) @ F3
d4=np.linalq.pinv(K4) @ F4
#############CALCULATING APPROXIMATE SOLUTION AND
SLOPE
uh1=np.zeros(1000)
for n in range (n1):
  for i in range(1000):
      uh1[i]=uh1[i]+d1[n]*N1[n,i]
uh slope1=np.zeros(1000)
      uh slope1[i]=uh slope1[i]+(uh1[i]-uh1[i-
1))/(x[i]-x[i-1])
      uh slope1[0]=uh slope1[1]
uh2=np.zeros(1000)
for n in range(n2):
      uh2[i]=uh2[i]+d2[n]*N2[n,i]
```

```
uh slope2=np.zeros(1000)
for i in range(1,1000):
      uh slope2[i]=uh slope2[i]+(uh2[i]-uh2[i-
1])/(x[i]-x[i-1])
      uh slope2[0]=uh slope2[1]
uh3=np.zeros(1000)
for n in range(n3):
  for i in range(1000):
      uh3[i]=uh3[i]+d3[n]*N3[n,i]
uh slope3=np.zeros(1000)
for i in range(1,1000):
      uh slope3[i]=uh slope3[i]+(uh3[i]-uh3[i-
1])/(x[i]-x[i-1])
      uh slope3[0]=uh slope3[1]
uh4=np.zeros(1000)
for n in range(n4):
  for i in range (1000):
      uh4[i]=uh4[i]+d4[n]*N4[n,i]
uh slope4=np.zeros(1000)
for i in range(1,1000):
      uh slope4[i]=uh slope4[i]+(uh4[i]-uh4[i-
1])/(x[i]-x[i-1])
      uh slope4[0]=uh slope4[1]
#############CALCULATING THE RELATIVE ERROR
for i in range(1000):
    Re1 = Re1 + np.abs(uh slope1[i] -
uexact slope[i]) / (q / 2)
    Re2 = Re2 + np.abs(uh slope2[i] -
uexact slope[i]) / (q / 2)
    Re3 = Re3 + np.abs(uh slope3[i] -
uexact slope[i]) / (q / 2)
print('SUM OF RELATIVE ERROR FOR N=10 : ', Re1)
print('SUM OF RELATIVE ERROR FOR N=50 : ', Re2)
print('SUM OF RELATIVE ERROR FOR N=100 : ',Re3)
############PLOTTING THE GRAPH
#PLOT FOR U
plt.plot(x,uh4,'y',label='N=3')
plt.plot(x,uh1,'g',label='N=10')
plt.plot(x,uh2,'r',label='N=50')
plt.plot(x,uh3,'b',label='N=100')
plt.plot(x,u exact,'c',label='EXACT GRAPH')
```

```
plt.legend()
plt.title('GRAPH OF U')
plt.show()
#PLOT OF SLOPE
plt.plot(x,uh_slope4,'y',label='N=3')
plt.plot(x,uh_slope1,'g',label='N=10')
plt.plot(x,uh_slope2,'r',label='N=50')
plt.plot(x,uh_slope3,'b',label='N=100')
plt.plot(x,uexact_slope,'c',label='EXACT GRAPH')
plt.legend()
plt.title('SLOPE OF U')
plt.show()
```





SUM OF RELATIVE ERROR FOR N=10 : 24.76415237058884 SUM OF RELATIVE ERROR FOR N=50 : 4.757501226148547 SUM OF RELATIVE ERROR FOR N=100 : 2.268513426517292 B> It can be seen the amount of point at which ah and exerci coincides increases with increase in increase with increase in in

for the slope graph of initially even at the nodes the walves are found to be different. With increase in 'n' walves are found to be different. With increase in 'n' walve the amount of point at which what coinades with walve the amount of point at which what coinades with use also increases. For n=100 the graph of wint is almost traced out by what.

It can be seen that coun increase in in value sum of relative error goes on decreasing. This is a clear indication that with contract in Mr value where can be a good and that with contesse in Mr value where a good and accorate approximation to dexact.