## PROGRAM DOCUMENTATION

MAIN PROGRAM NAME: Coll\_Detect\_BVH - laughing\_buddha\_right.py

**PURPOSE**: Check for collision detection between two complex 3D object meshes by creating and traversing through the octrees

**SOURCE LANGUAGE**: This version of the program was written in "Python"

**COMPILING**: The program can be compiled and run using the Pycharm compiler

**DESCRIPTION**: The program consists of four function declarations and one class declaration :

# def is\_colliding():

To check for overlap collision between the AABB created

#### > def check collision():

To check for collision between the 3D objects

## def get\_AABB\_List():

To fetch the Axis Aligned Bounding Box of each leaf node

### def get\_leaf\_node\_list():

To traverse through the octree and return a list of leaf nodes

#### Class Traversal():

Brute-force algorithm for traversing

**FILES**: Coll\_Detect\_BVH - laughing\_buddha\_right.h - contains the main program Stanford\_Bunny.ply - contains the ply version of Stanford Bunny file happyStandRight 240.ply - contains the ply (stand right) version of Happy Buddha file