## Algorithm parameters: step size $\alpha \in (0,1]$ , small $\varepsilon > 0$ Initialize $Q_1(s, a)$ and $Q_2(s, a)$ , for all $s \in S^+$ , $a \in A(s)$ , such that $Q(terminal, \cdot) = 0$

Double Q-learning, for estimating  $Q_1 \approx Q_2 \approx q_*$ 

Loop for each episode: Initialize S

Loop for each step of episode:

Choose A from S using the policy  $\varepsilon$ -greedy in  $Q_1 + Q_2$ Take action A, observe R, S'

With 0.5 probabilility:
$$O(G,A) \leftarrow O(G,A)$$

else: 
$$Q_2(S,A) \leftarrow$$

 $S \leftarrow S'$ until S is terminal

 $Q_1(S, A) \leftarrow Q_1(S, A) + \alpha \left(R + \gamma Q_2(S', \operatorname{arg\,max}_a Q_1(S', a)) - Q_1(S, A)\right)$ 

 $Q_2(S, A) \leftarrow Q_2(S, A) + \alpha \Big( R + \gamma Q_1 \big( S', \operatorname{arg\,max}_a Q_2(S', a) \big) - Q_2(S, A) \Big)$