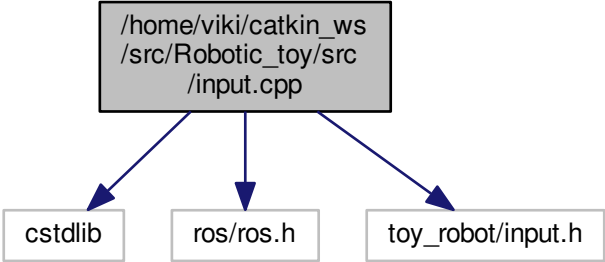


/home/viki/catkin_ws
/src/Robotic_toy/src
/input.cpp



```
graph TD; A["/home/viki/catkin_ws  
/src/Robotic_toy/src  
/input.cpp"] --> B["cstdlib"]; A --> C["ros/ros.h"]; A --> D["toy_robot/input.h"];
```

cstdlib

ros/ros.h

toy_robot/input.h