Winning Space Race with Data Science

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Outline

- Executive Summary
- Introduction
- Methodology
- Results
- Conclusion
- Appendix

Executive Summary

- Summary of methodologies: In this project, we used data collection from a CSV file, we preprocessed the data through Data Wrangling techniques, we performed Exploratory Data Analysis through SQL queries and visualization, and created four prediction models, namely SVM, Decision Tree, Logistic Regression and K-nearest Neighbor.
- Summary of all results: We found the best estimator came up to be our Decision Tree Classifier.

Introduction

- **SpaceX Falcon 9 first stage Landing Prediction**

- **Request to the SpaceX API**
- **Clean the requested data**

Section 1

Methodology

Methodology

Executive Summary

- Data collection methodology:
  - Qualitative Data Collection-Online Forum, Group Chat ,Web Survey Chat, Online Communication
  - Quantitative Data Collection- Face to Face, Phone ,Mail.
- Perform data wrangling
  - Data Acquisition: Identify and obtain access to the data within your sources.
  - Joining Data: Combine the edited data for further use and analysis.
  - Data Cleansing: Redesign the data into a usable and functional format and correct/remove any bad data.
- Performed exploratory data analysis (EDA) using visualization and SQL

Data Collection

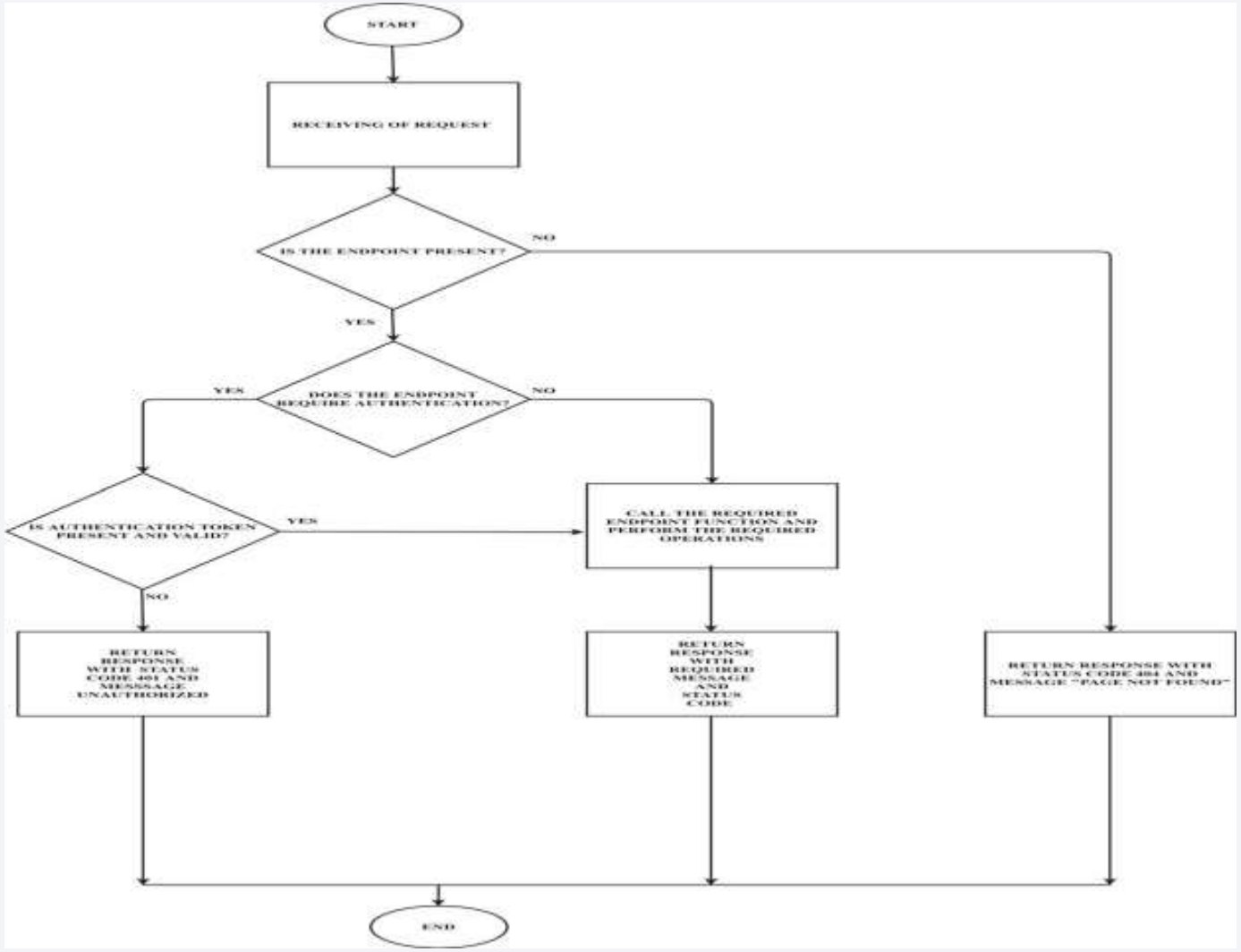
```
def getBoosterVersion(data): for x in data['rocket']:

   response = requests.get("https://api.spacexdata.com/v4/rockets/"+(x)).json()

   BoosterVersion.append(response['name'])
```

```
def getPayloadData(data):
  for load in data['payloads']:
     response = requests.get("https://api.spacexdata.com/v4/payloads/"+load).json()
     PayloadMass.append(response['mass_kg'])
     Orbit.append(response['orbit'])
```

Data Collection – SpaceX API

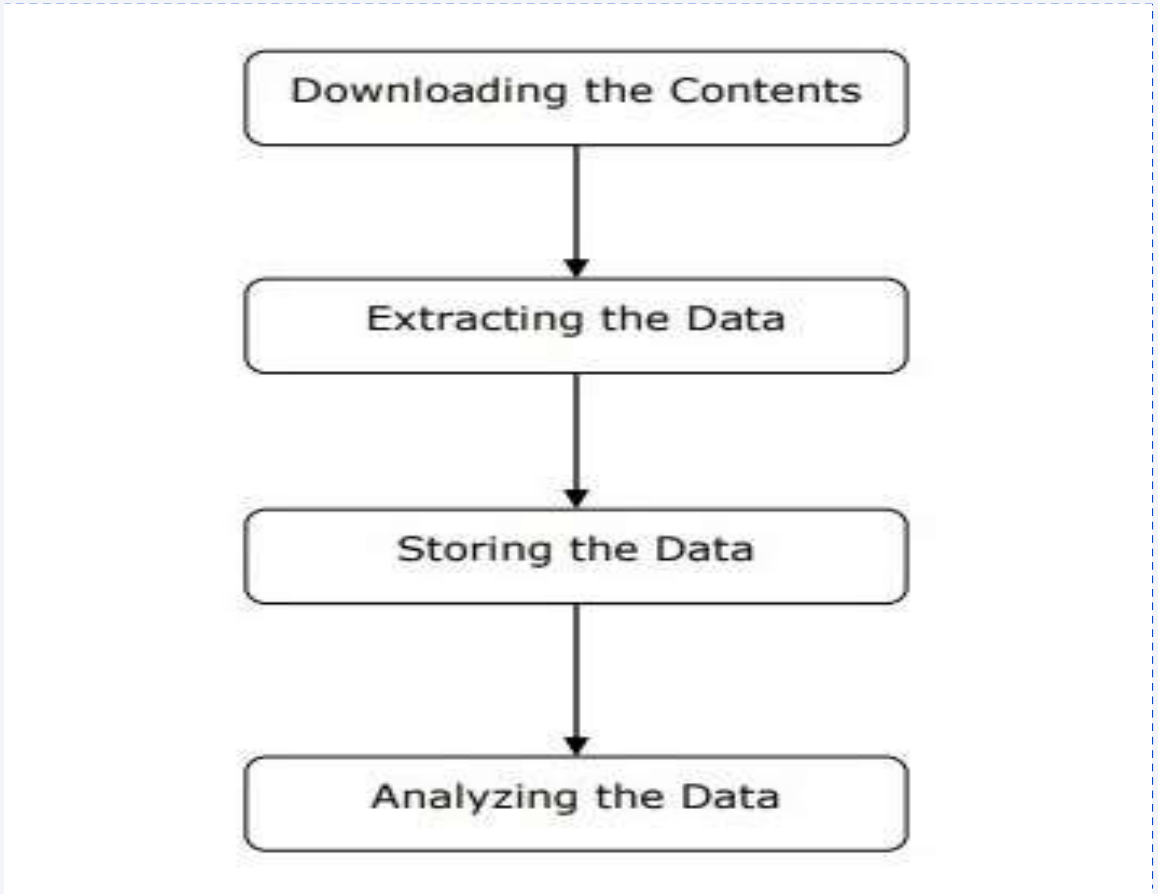
- SpaceX REST calls using key phrases and flowcharts

- https://github.com/Akshaymore55/Applied-Data-Science/blob/master/Jupyter-labs-SpaceX-data-collection-API.ipynb



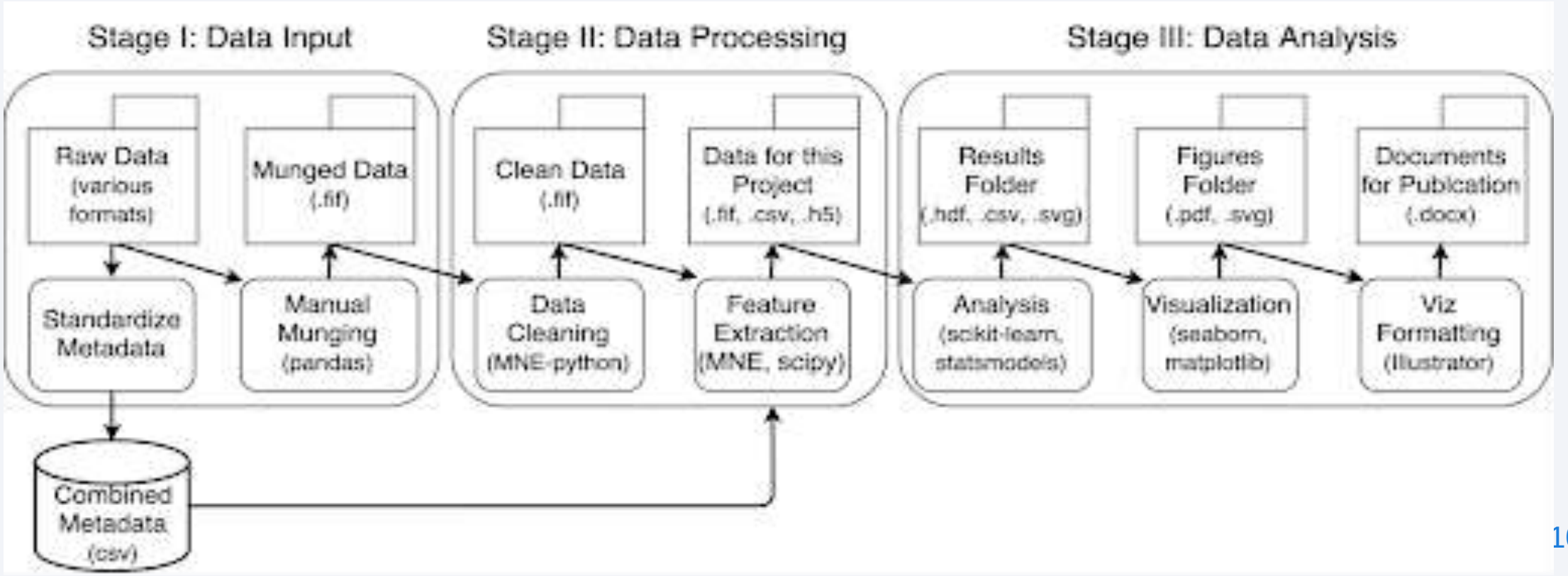
Data Collection - Scraping

- Present your web scraping process using key phrases and flowcharts



Data Wrangling

- **Data wrangling is the process of cleaning and unifying messy and complex data sets for easy access and analysis.**



Data Collection with API:-

1 .Getting Response from HTML

```
page = requests.get(static_url)
```

2. Creating BeautifulSoup Object

```
soup = BeautifulSoup(page.text, 'html.parser')
```

3. Finding tables

```
html_tables = soup.find_all('table')
```

4. Getting column names

```
column_names = []
temp = soup.find_all('th')
for x in range(len(temp)):
    try:
     name = extract_column_from_header(temp[x])
     if (name is not None and len(name) > 0):
        column_names.append(name)
    except:
     pass
```

5. Creation of dictionary

```
launch_dict= dict.fromkeys(column_names)

# Remove an irrelvant column
del launch_dict['Date and time ( )']


launch_dict['Flight No.'] = []
launch_dict['Launch site'] = []
launch_dict['Payload'] = []
launch_dict['Payload mass'] = []
launch_dict['Orbit'] = []
launch_dict['Customer'] = []
launch_dict['Launch outcome'] = []
launch_dict['Version Booster']=[]
launch_dict['Booster landing']=[]
launch_dict['Date']=[]
launch_dict['Time']=[]
```

6. Appending data to keys (refer) to notebook block 12

```
In [12]: extracted_row = 0
         #Extract each table
         for table_number,table in enumerate(
            # get table row
             for rows in table.find_all("tr"
                 #check to see if first tabl
```

7. Converting dictionary to dataframe

```
df = pd.DataFrame.from_dict(launch_dict)
```

8. Dataframe to .CSV

```
df.to_csv('spacex_web_scraped.csv', index=False)
```

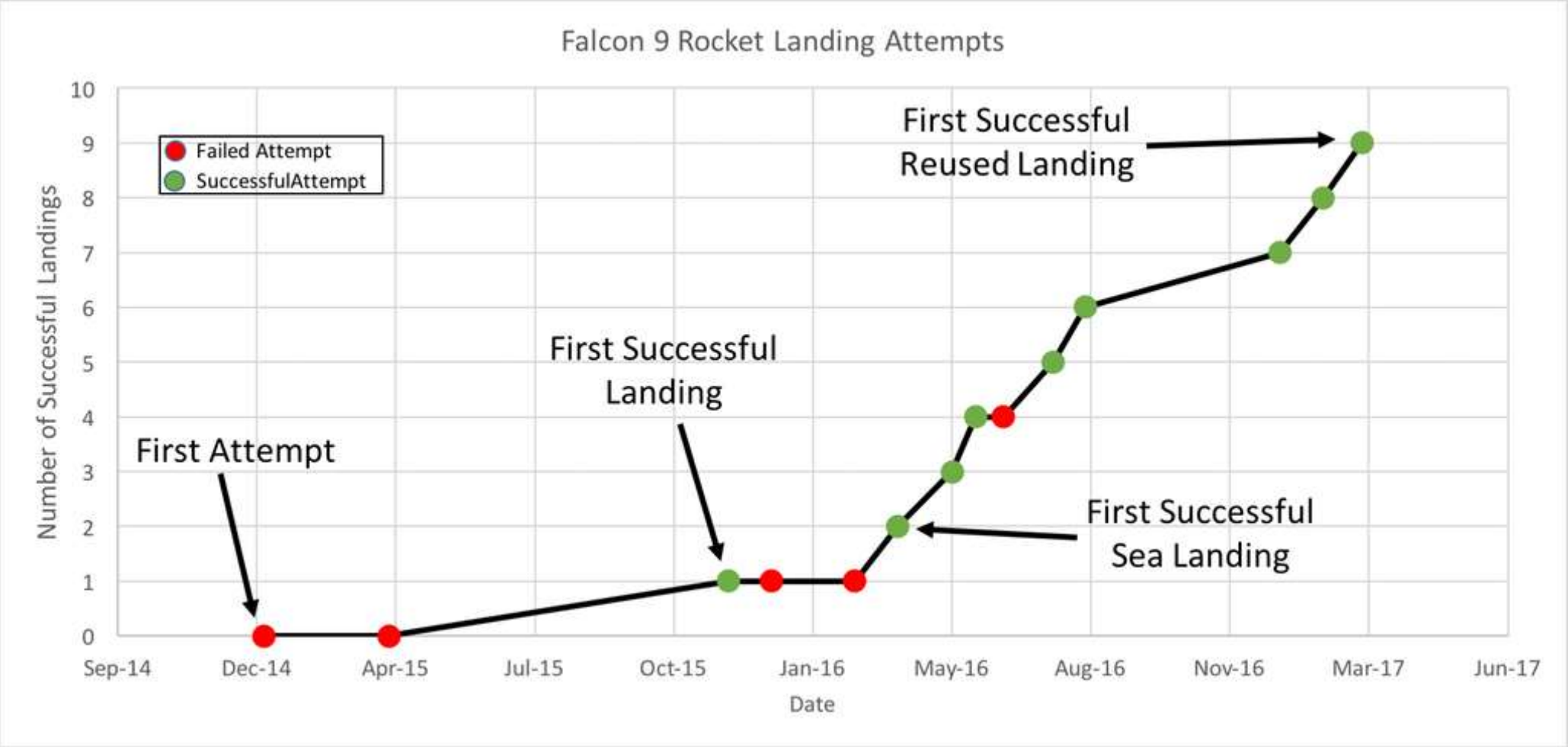
EDA SQL Describe:-

Performed SQL queries to gather information about the dataset.

For example of some questions we were asked about the data we needed information about. Which we are using SQL queries to get the answers in the dataset :

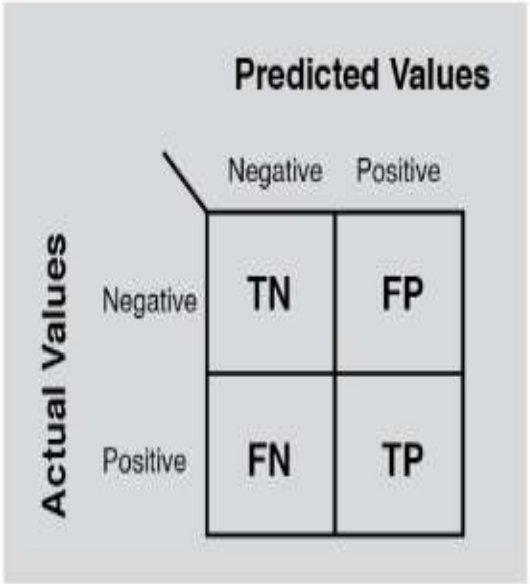
- Displaying the names of the unique launch sites in the space mission
- Displaying 5 records where launch sites begin with the string 'KSC'
- Displaying the total payload mass carried by boosters launched by NASA (CRS)
- Displaying average payload mass carried by booster version F9 v1.1
- Listing the date where the successful landing outcome in drone ship was achieved.
- Listing the names of the boosters which have success in ground pad and have payload mass greater than 4000 but less than 6000
- Listing the total number of successful and failure mission outcomes
- Listing the names of the booster_versions which have carried the maximum payload mass.
- Listing the records which will display the month names, successful landing_outcomes in ground pad ,booster versions, launch_site for the months in year 2017
- Ranking the count of successful landing_outcomes between the date 2010-06-04 and 2017-03-20 in descending order.

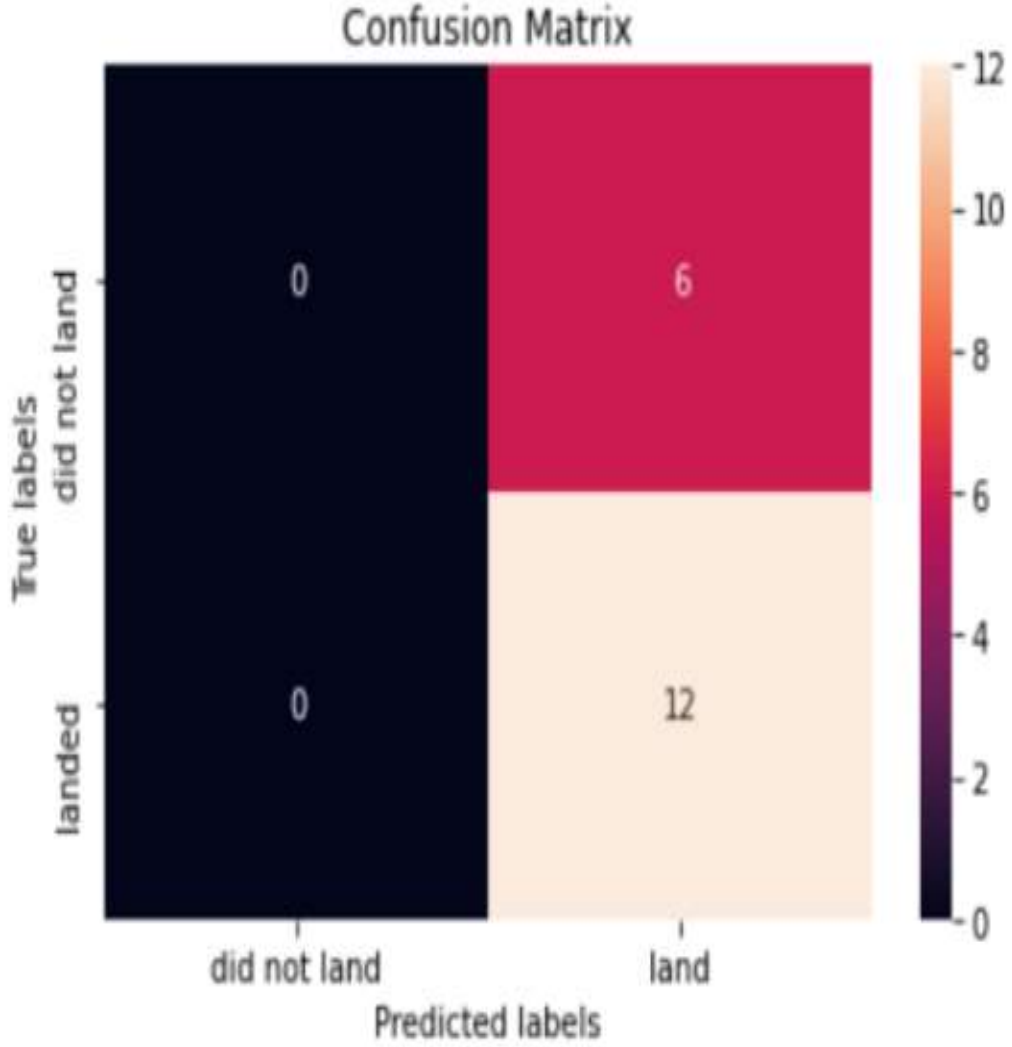
EDA with Data Visualization



Confusion Matrix for the Tree

Examining the confusion matrix, we see that Tree can distinguish between the different classes. We see that the major problem is false positives.





Predictive Analysis (Classification)

BUILDING MODEL

- Load our dataset into NumPy and Pandas
- Transform Data
- Split our data into training and test data sets
- Check how many test samples we have
- Decide which type of machine learning algorithms we want to use
- Set our parameters and algorithms to GridSearchCV
- Fit our datasets into the GridSearchCV objects and train our dataset.

EVALUATING MODEL

- Check accuracy for each model
- Get tuned hyperparameters for each type of algorithms
- Plot Confusion Matrix

IMPROVING MODEL

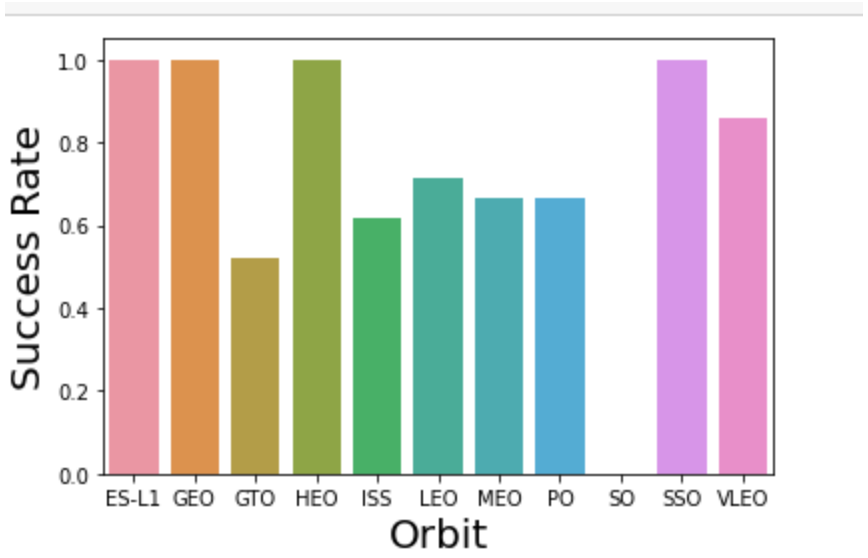
- Feature Engineering
- Algorithm Tuning

FINDING THE BEST PERFORMING CLASSIFICATION MODEL

- The model with the best accuracy score wins the best performing model
- In the notebook there is a dictionary of algorithms with scores at the bottom of the notebook.

Results

- Exploratory data analysis results, we processed the data, explored it, and applied one hot encoding:



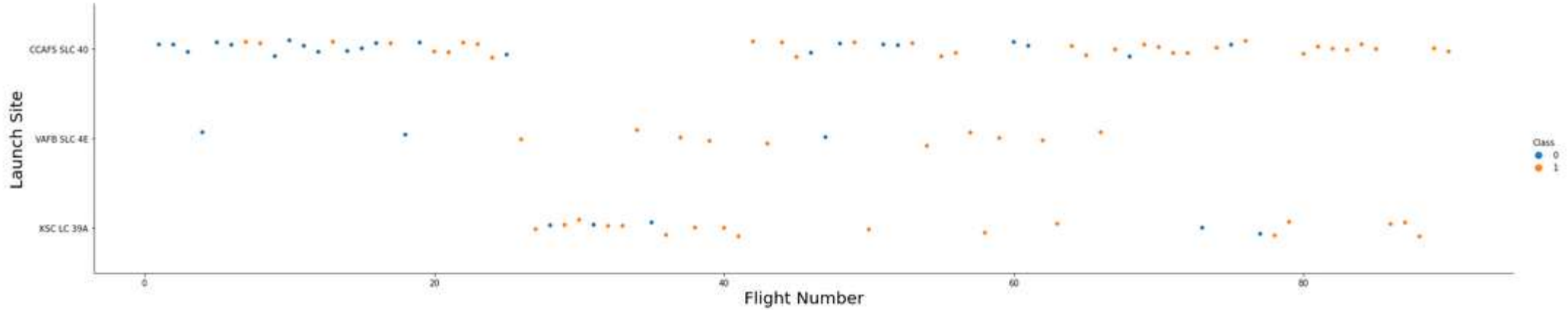
- The result of the predictive analysis tells us that We found the best estimator came up to be our Decision Tree Classifier, with a score of 0,8889.

Section 2

Insights drawn from EDA

Flight Number vs. Launch Site

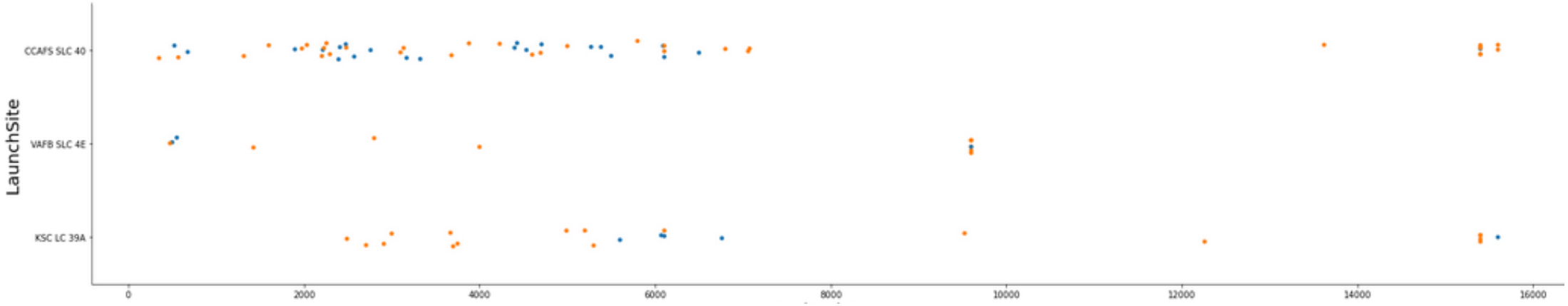
In [6]:
```
# Plot a scatter point chart with x axis to be Flight Number and y axis to be the launch site, and hue to be the class value
sns.catplot(y="LaunchSite", x="FlightNumber", hue="Class", data=df, aspect = 5)
plt.xlabel("Flight Number",fontsize=20)
plt.ylabel("Launch Site",fontsize=20)
plt.show()
```



- We can appreciate that with a higher flight number, there has been more success rate.

Payload vs. Launch Site

```
# Plot a scatter point chart with x axis to be Pay Load Mass (kg) and y axis to be the launch site, and hue to be the class value
sns.catplot(x="PayloadMass", y="LaunchSite", hue="Class", data=df, aspect = 5)
plt.xlabel("PayloadMass",fontsize=20)
plt.ylabel("LaunchSite",fontsize=20)
plt.show()
```

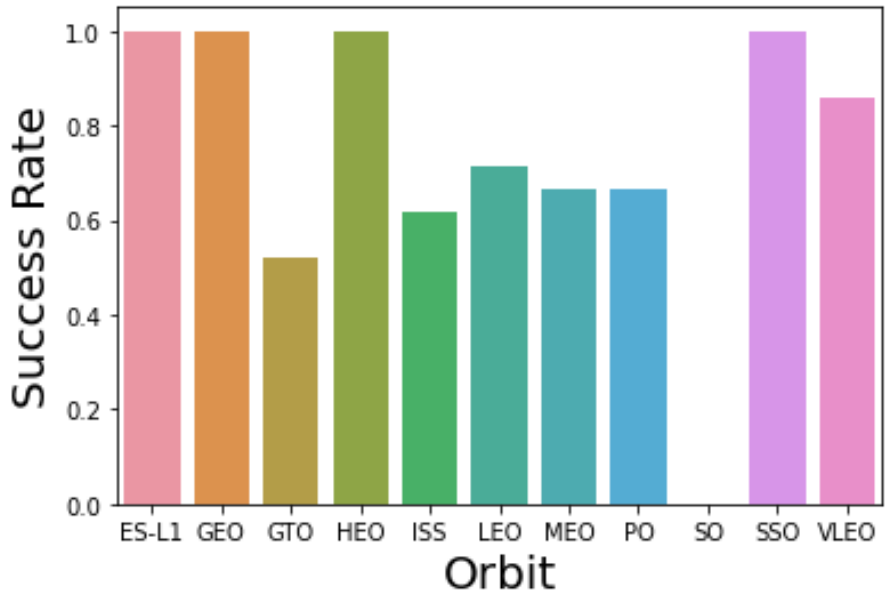


- We can see that in VAFB SLC 4E There hasn't been launchs with a higher payload tan 10000kg.
- Also, Launches with higher Payloads tend to have higher success rates.

Success Rate vs. Orbit Type

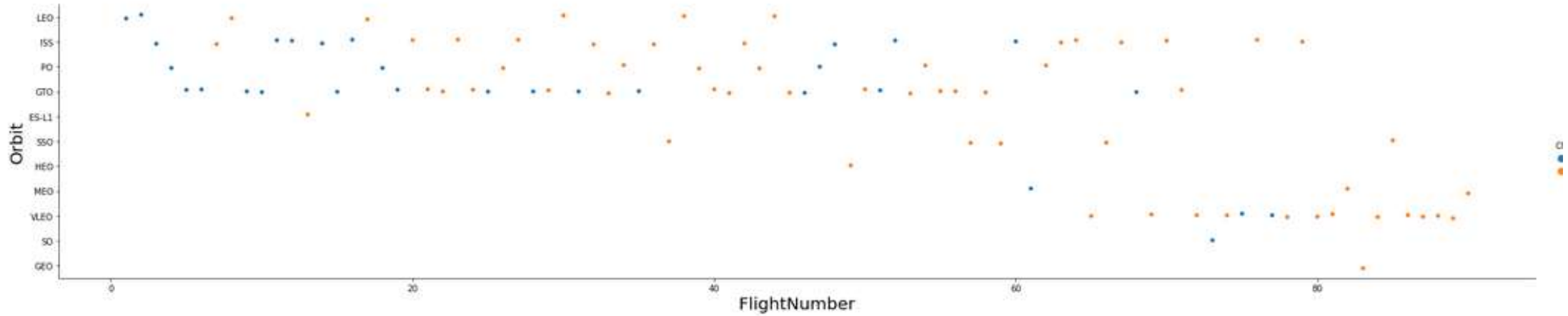
- GTO is the worst ORBIT for successful landings of first stage.

```
# HINT use groupby method on Orbit column and get the mean of Class column
df2=df[['Orbit','Class']].groupby('Orbit', as_index=False).mean()
#df2.plot(kind='bar')
sns.barplot(x='Orbit', y='Class' , data=df2)
plt.xlabel("Orbit",fontsize=20)
plt.ylabel("Success Rate",fontsize=20)
plt.show()
```



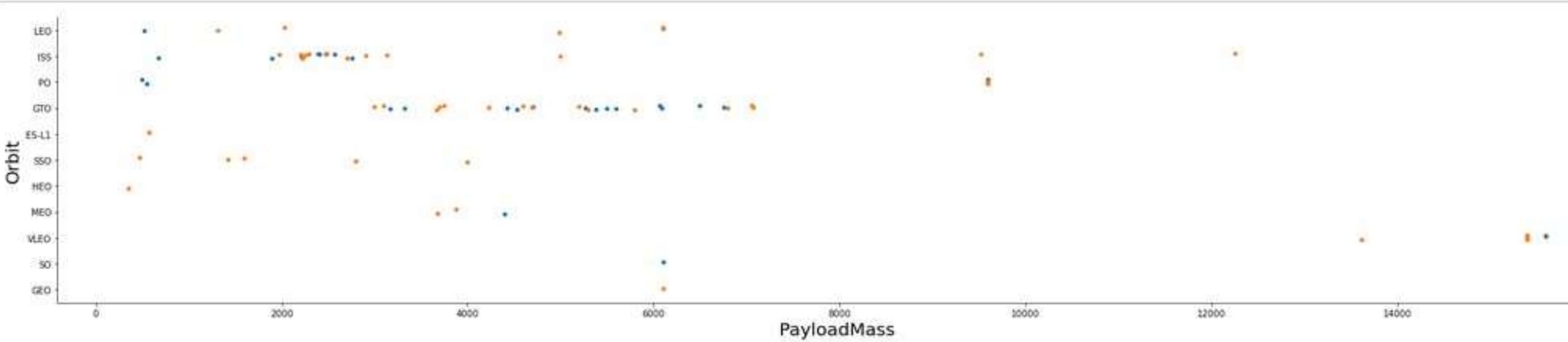
Flight Number vs. Orbit Type

```
# Plot a scatter point chart with x axis to be FlightNumber and y axis to be the Orbit, and hue to be the class value
sns.catplot(x="FlightNumber", y="Orbit", hue="Class", data=df, aspect = 5)
plt.xlabel("FlightNumber",fontsize=20)
plt.ylabel("Orbit",fontsize=20)
plt.show()
```



VLEO, SO, GEO and MEO have Little data, and only in more recent Flight Numbers.

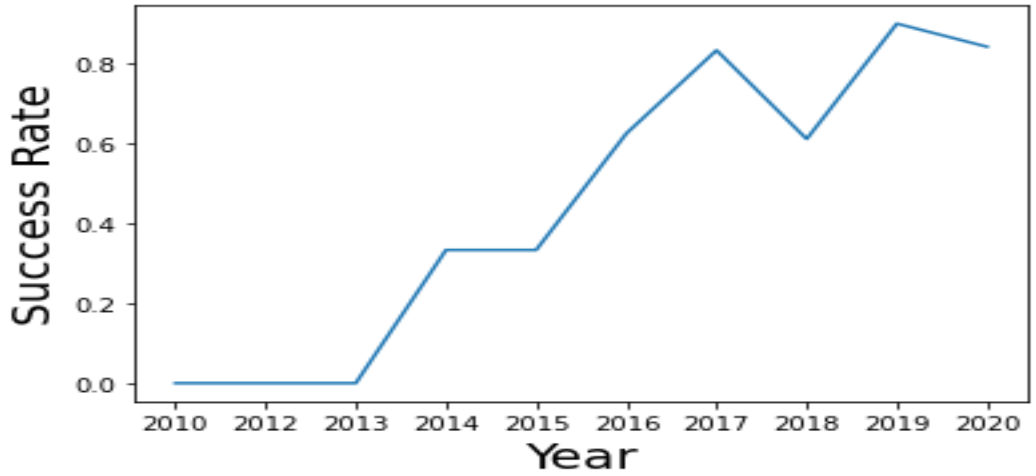
Payload vs. Orbit Type



- Most launches have low payloads, and the ones with the highest payloads go to a VLEO Orbit.

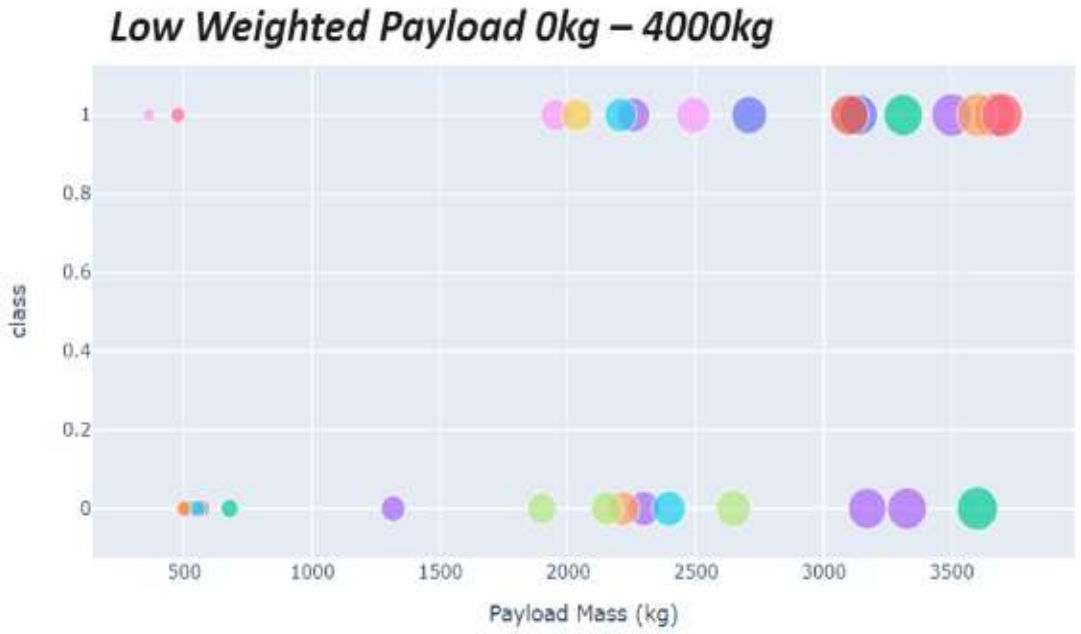
Launch Success Yearly Trend

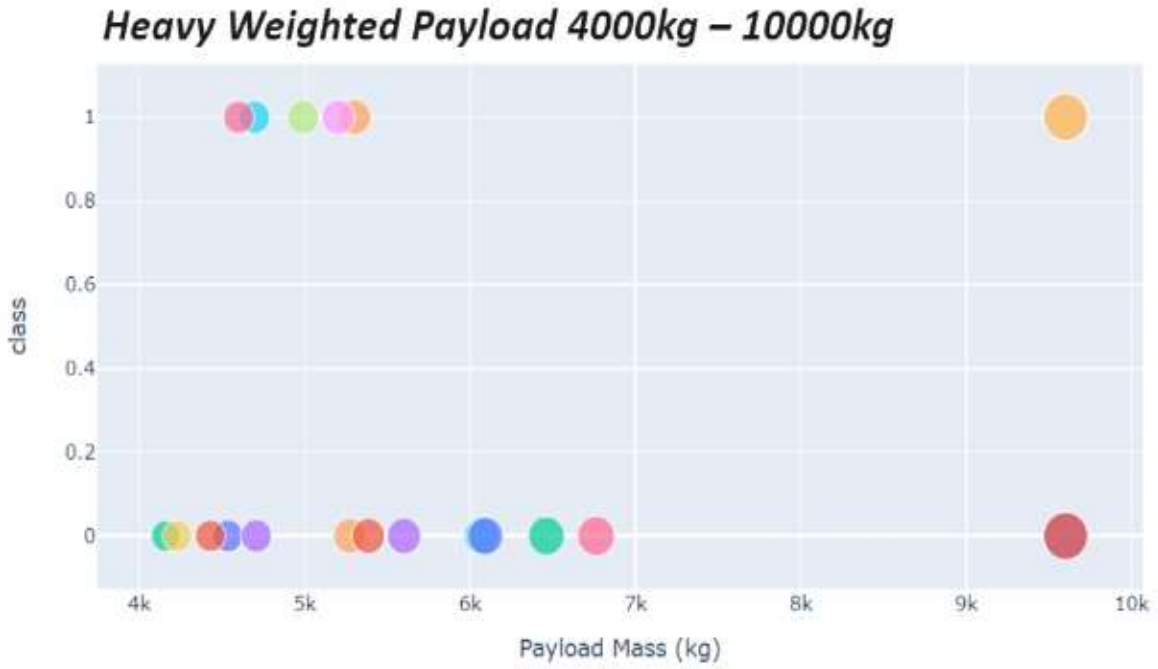
```
# Plot a line chart with x axis to be the extracted year and y axis to be the success rate
df2=df[['year','Class']].groupby('year', as_index=False).mean()
sns.lineplot(x='year', y='Class', data=df2)
plt.xlabel("Year",fontsize=20)
plt.ylabel("Success Rate",fontsize=20)
plt.show()
```



- Success Rate has skyrocketed with each passin year.

Low weighted payload vs Heavy payload





We can see the success rates for low weighted payloads is higher than the heavy weighted payloads

Section 4

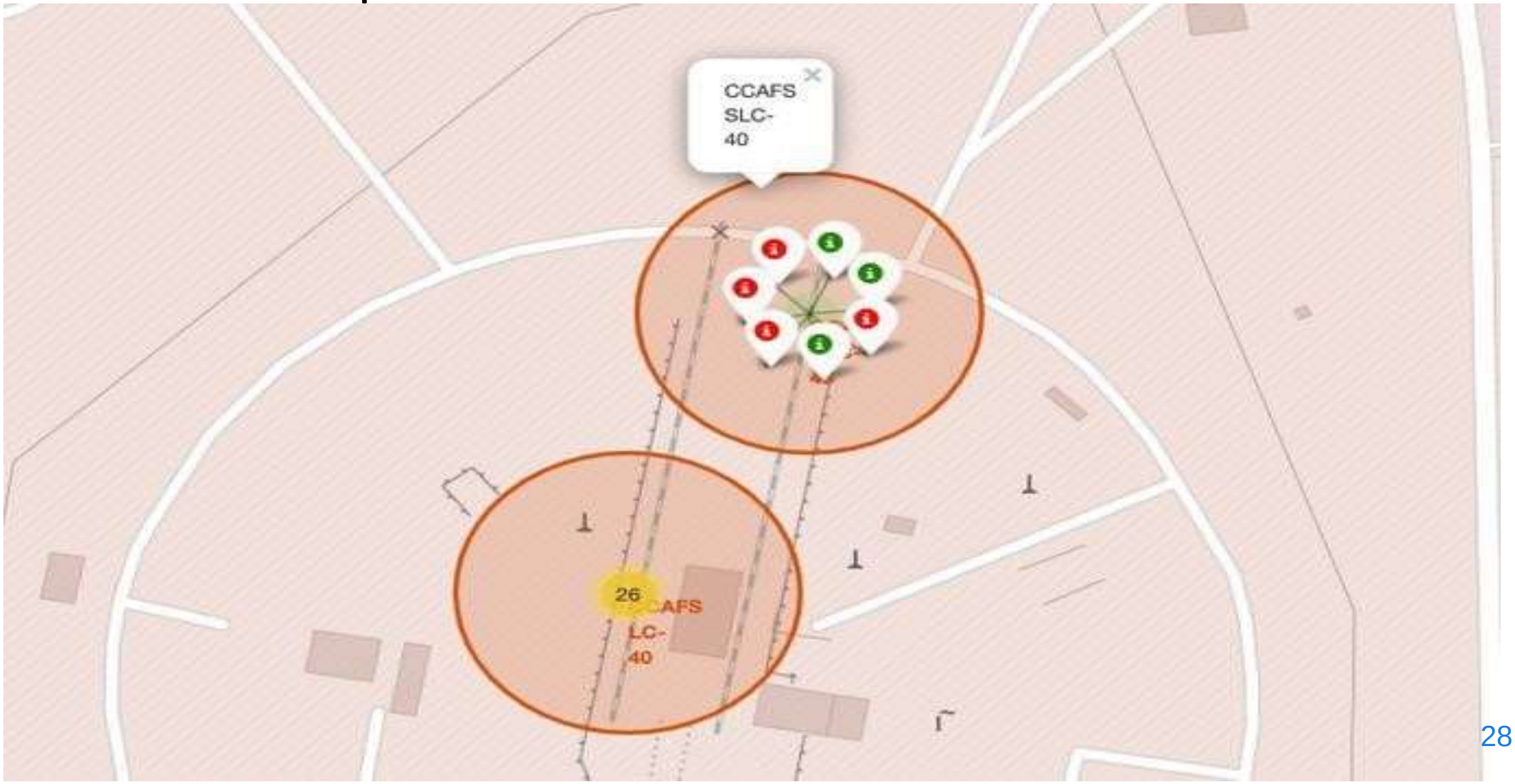
Launch Sites Proximities Analysis

Launch Sites

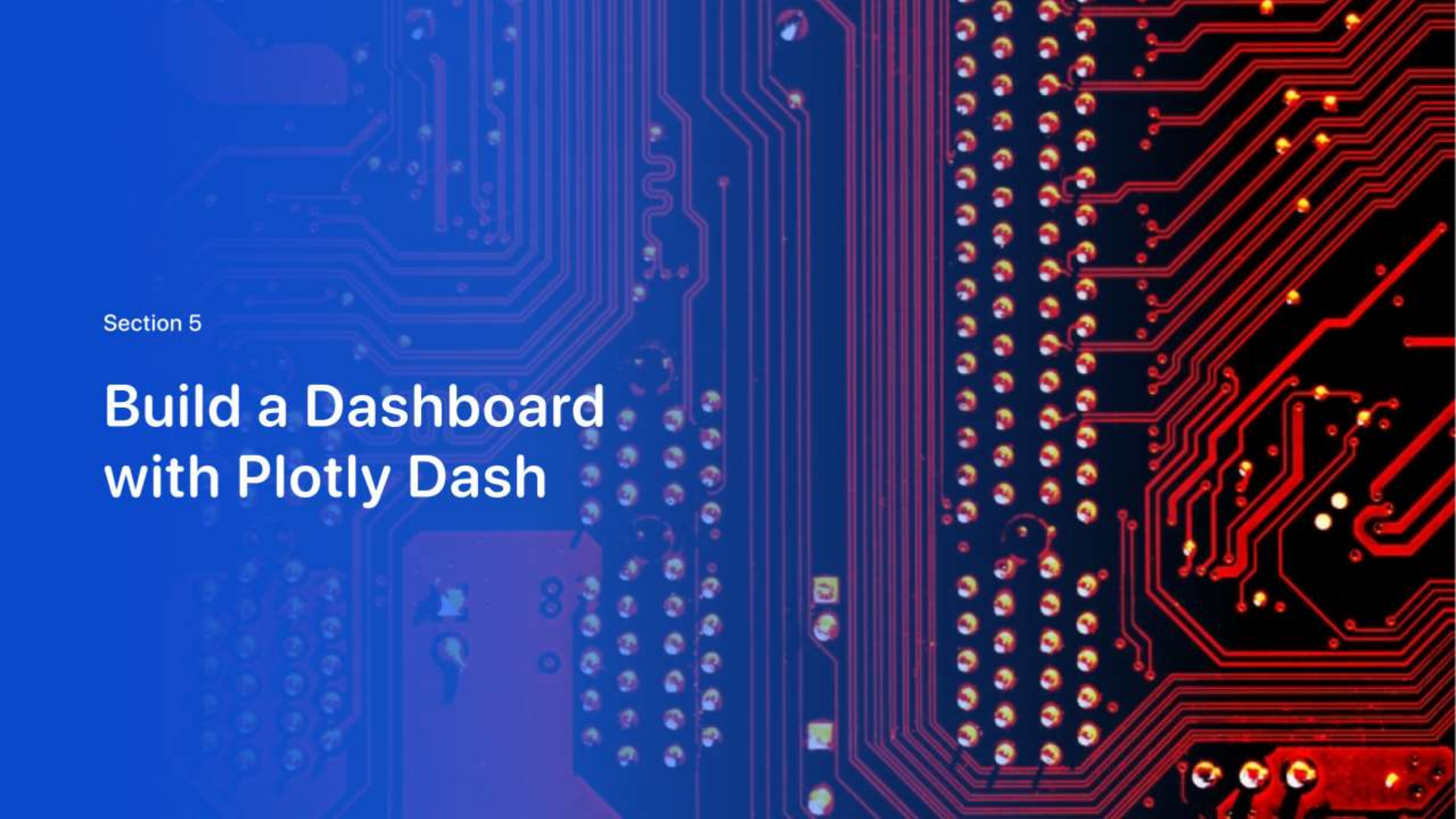
- In this map, we can see all the Launch Sites

Folium Map Screenshot

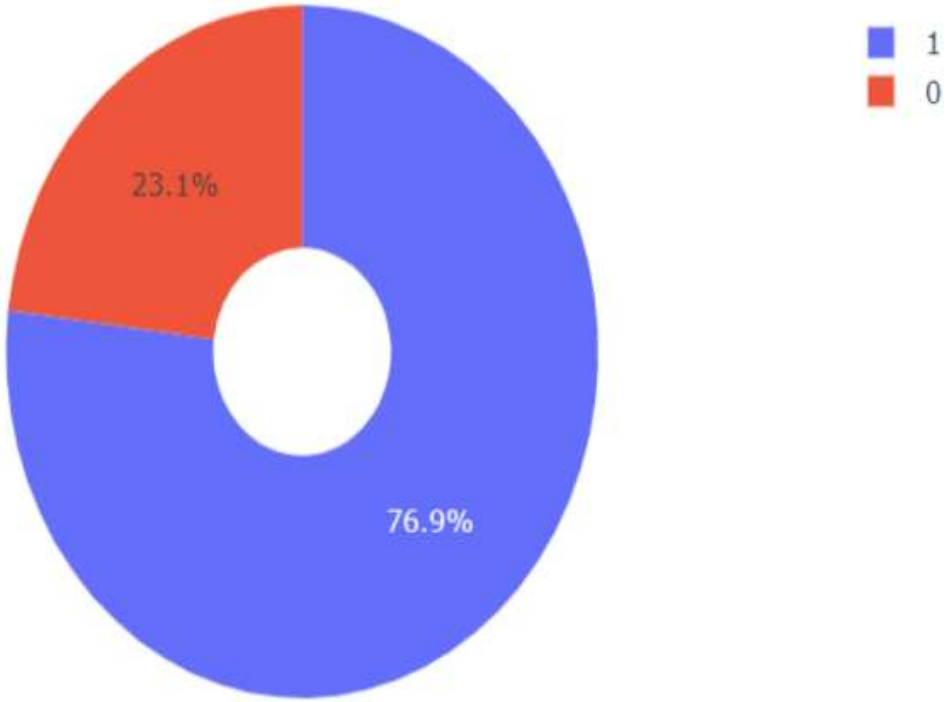
Folium Map Screenshot



All Launch sites:-

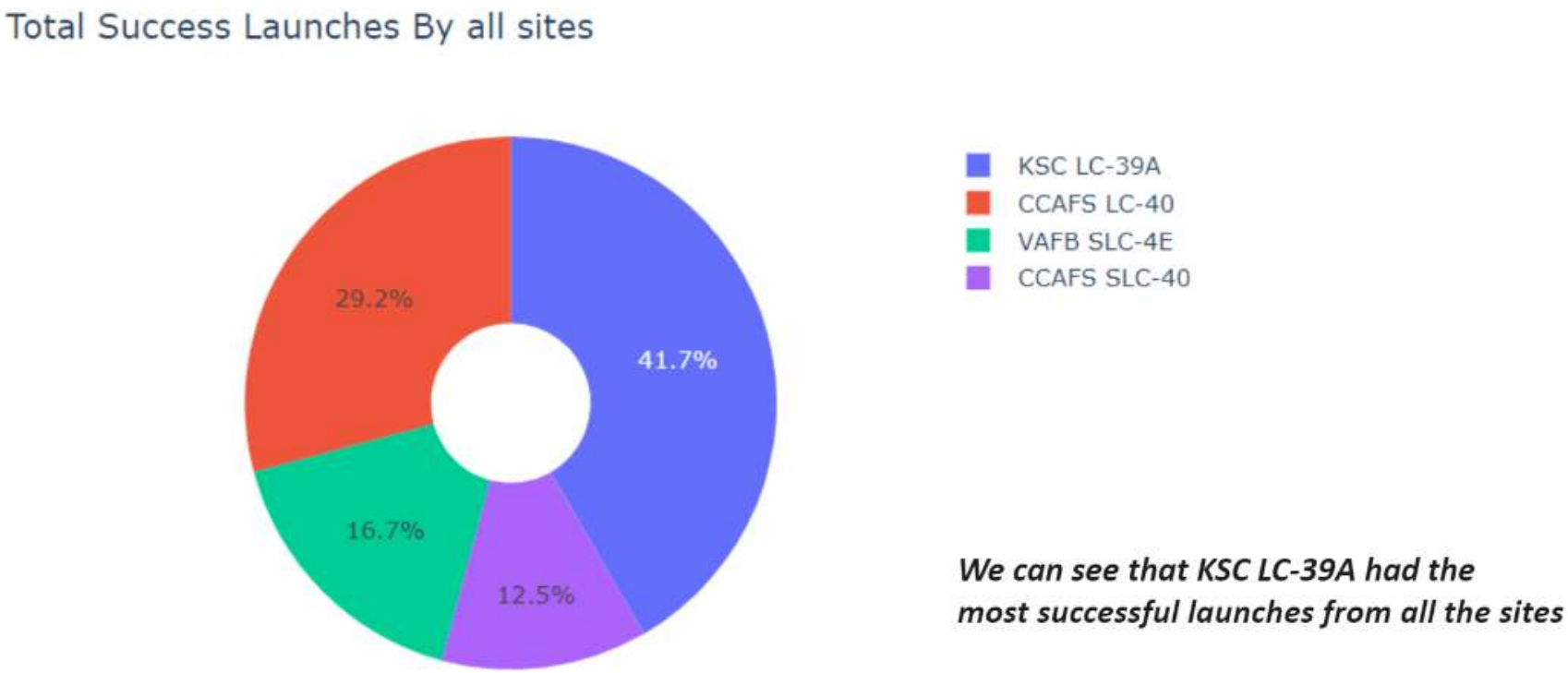

Section 5
Build a Dashboard with Plotly Dash

Total Success Launch Site:-



KSC LC-39A achieved a 76.9% success rate while getting a 23.1% failure rate

Highest Launch Site:-



We can see that KSC LC-39A had the most successful launches from all the sites

Section 6

Predictive Analysis (Classification)

Predative Analysis:-

BUILDING MODEL

- Load our dataset into NumPy and Pandas
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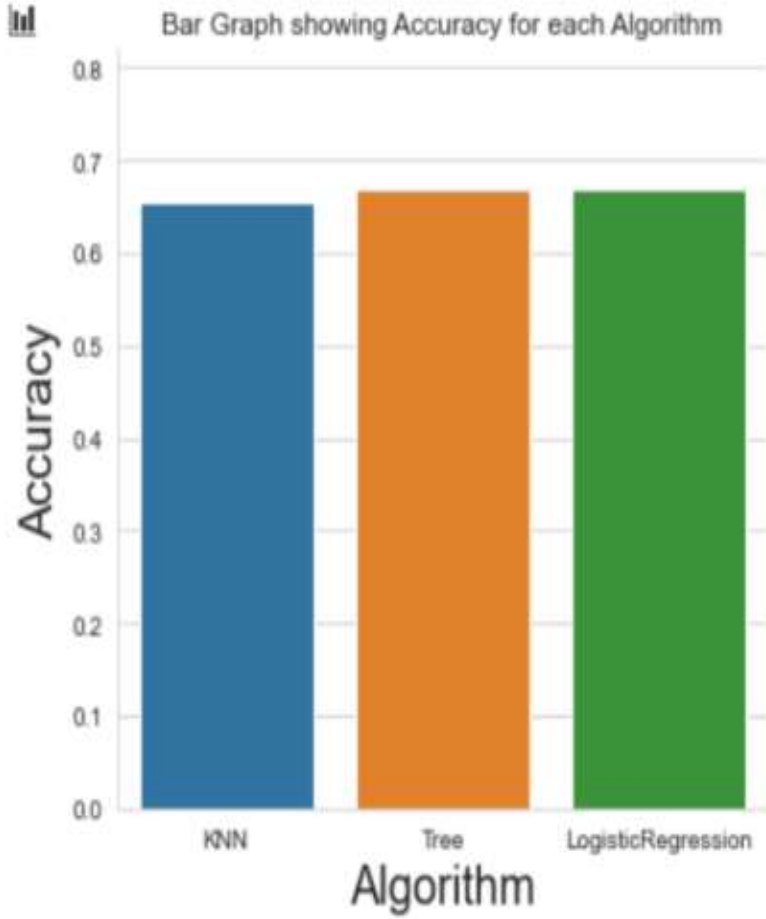
Classification Accuracy using training data

As you can see our accuracy is extremely close but we do have a winner its down to decimal places! using this function

```
bestalgorithm = max(algorithms, key=algorithms.get)
```

	Accuracy	Algorithm
0	0.653571	KNN
1	0.667857	Tree
2	0.667857	LogisticRegression



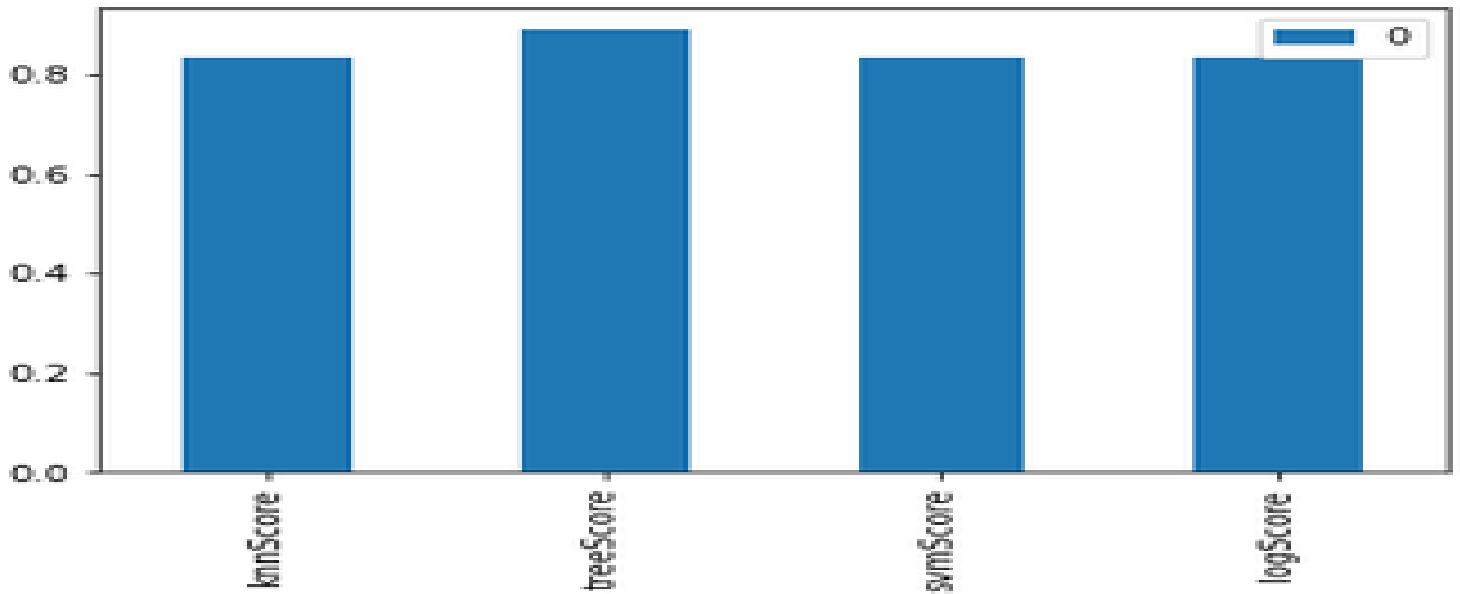
The tree algorithm wins!!

```
Best Algorithm is Tree with a score of 0.6678571428571429
Best Params is : {'criterion': 'gini', 'max_depth': 2, 'max_features': 'auto', 'min_samples_leaf': 1, 'min_samples_split': 2, 'splitter': 'best'}
```

After selecting the best hyperparameters for the decision tree classifier using the validation data, we achieved 83.33% accuracy on the test data.

Classification Accuracy

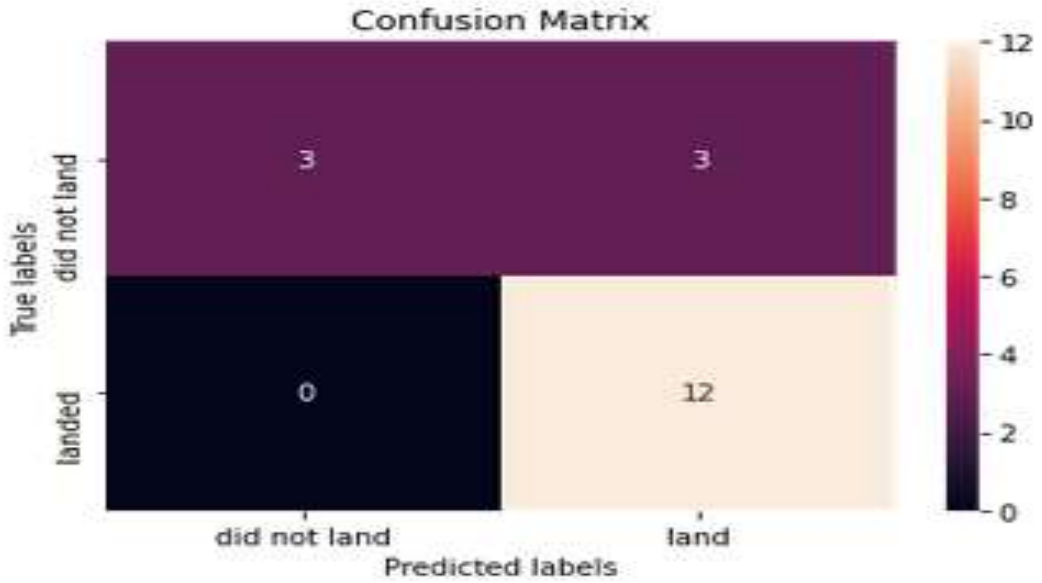
```
In [158]: df3.plot(kind='bar')
Out[158]: <AxesSubplot:>
```



- The model with the highest accuracy was Decission Tree

Confusion Matrix

```
n [118]: yhat = tree_cv.predict(X_test)
         plot_confusion_matrix(Y_test,yhat)
```



- For all the models, the confussion matrix showed 3 false possitives

Thank you!