

# Home Assignment 4, CMPE 252, Section 01, Fall 2023.

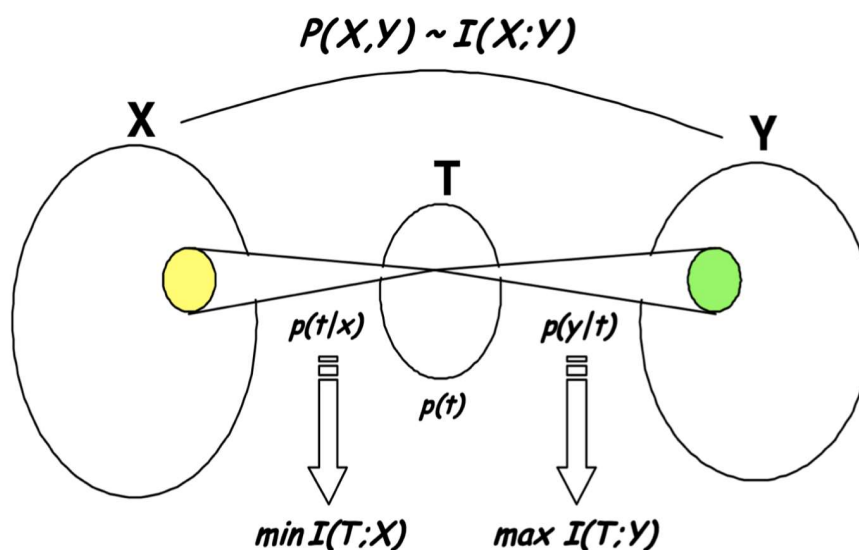
In this assignment you will get experience with the information bottleneck method, and its efficient implementation using broadcasting.

It is a team assignment. You can discuss your solutions but do not to share your code between the teams.

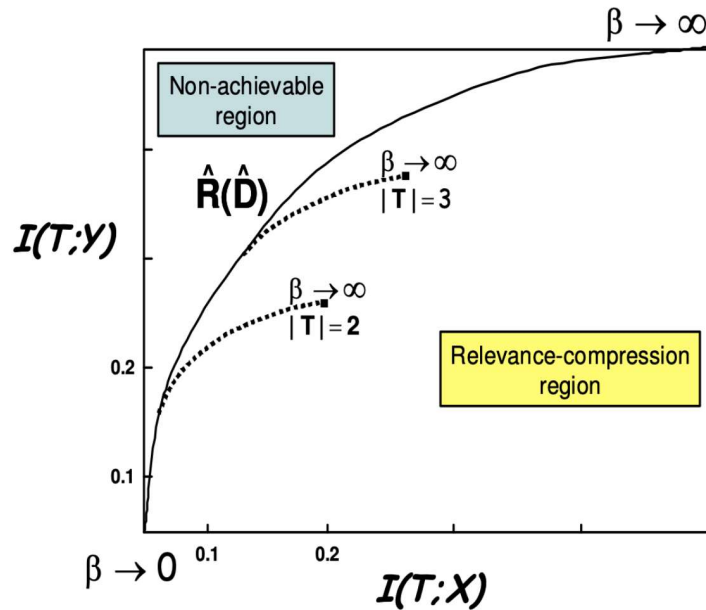
What to submit in Canvas: a working notebook with the full solution, and its corresponding PDF in two separate files (not a zip file).

Due: Dec 6, 11:59PM

## Information Bottleneck



# Information Bottleneck Curve



## Information Bottleneck Self-Consistent equations

INIT

$$p(x, y) \leftarrow \text{given}$$

$$p(t | x) \leftarrow \text{random init}$$

$$p(t) \leftarrow \sum_x p(t | x) p(x)$$

$$p(y | t) \leftarrow \frac{1}{p(t)} \sum_x p(t | x) p(x, y)$$

DO UNTIL CONVERGENCE

$$p(t | x) \leftarrow \frac{p(t) \exp(-\beta D_{kl}[p(Y | x) || p(Y | t)])}{Z}$$

$$p(t) \leftarrow \sum_x p(t | x) p(x)$$

$$p(y | t) \leftarrow \frac{1}{p(t)} \sum_x p(t | x) p(x, y)$$

RETURN

$$p^*(t | x)$$

```
In [1]: import numpy as np
from matplotlib import pyplot as plt
import math
from scipy.special import rel_entr
```

```
In [2]: def DKL(A, B):
        """
        Kulback-Leibler divergence  $D(A||B)$ 
        :param A:  $p_A(x)$ , target distribution
        :param B:  $p_B(x)$ , other distribution
        :return: component-wise  $DKL(p_A(x) || p_B(x))$ , which is a tensor of the same dimension
        :         each entry in the tensor is  $A_i * \ln(A_i / B_i)$ , which means the  $i$ -th component
        :         this code structure, to return the component-wise  $D_{kl}$ , rather than  $\sum$ 
        :         simplifies the update equations and the calculation of MI.
        :         you will use it in the calculation of mutual information and in the update
        """
        epsilon = 1e-10
        A = np.clip(A, epsilon, 1 - epsilon)
        B = np.clip(B, epsilon, 1 - epsilon)

        # Calculate KL divergence component-wise
        d = A * np.log(A / B)

        # Handling numerical issues with inf/nan
        d[np.isnan(d)] = 0
        d[np.isinf(d)] = 0

        return d
```

```
In [3]: def I(pA, pB, pAB):
        """mutual information  $I(X,Y) = DKL(P(x,y) || P_X \times P_Y)$ 
        :param pA: A -  $p(a)$ : marginal probability of X
        :param pB: B -  $p(b)$ : marginal probability of Y
        :param pAB:  $p(a,b)$ : joint probability of X and Y"""

        # your code (use your DKL function above)
        mutual_info = np.sum(DKL(pAB, pA * pB))

        return mutual_info
```

```
In [4]: def entropy(p):
        """entropy of a discrete distribution"""
        ### example for the vectorized calculation of the entropy ###
        return -np.sum(p * np.log(p))
```

```
In [5]: def make_probs(*dims):
        XY = np.random.rand(*dims)
        # normalize to a probability
        XY = XY / XY.sum()
        return XY
```

```
In [6]: def iterative_information_bottleneck(
        Xdim, Ydim, Mmax, Mmin,
        n_iters=100, # iteration of the equations until convergence
        n_tries=3, # number of trials from random initial conditions with n_iters
        n_betas=100, # number of different beta values to create the IB curve
        beta_min=0.1, # the above results in 30000 iterations
        beta_max=100):

        # working with probabilities as tensors makes it easier to
        # read/write code and lets us utilize numpy broadcasting.
        # e.g, in this function we are working with discrete random
        # variables X, Y, and T. We can represent all probabilities as
        # tensors, where each dimension represents a random variable.
```

```

# e.g. p(x,y) is a tensor of shape (Xdim, Ydim, 1)
pXY = make_probs(Xdim, Ydim, 1)
# p(x) is a tensor of shape (Xdim, 1, 1)
pX = np.sum(pXY, axis=1, keepdims=True)/np.sum(pXY)
#print(pX.shape)
pY = np.sum(pXY, axis=0, keepdims=True)/np.sum(pXY)
#print("true")

# p(y | x) is a tensor of shape (Xdim, Ydim, 1), calculate it from pXY and Px
pY_X = pXY / pX

hX = entropy(pX)

target_MI = I(pX, pY, pXY)
print("The MI between generated X and Y is:", target_MI)
print("The entropy of X is:", hX)

# place holder for the Lagrangian = I_TXs - beta I_TYs
Ls = np.zeros((Mmax - Mmin+1, n_betas))
#epsilon = 1e-8
# relevance I(T;Y)
I_TYs = np.zeros((Mmax - Mmin+1, n_betas))
#epsilon = 1e-8
# compression I(T;X)
I_TXs = np.zeros((Mmax - Mmin+1, n_betas))

# betas
betas = np.zeros((Mmax - Mmin+1, n_betas))
# change the cardinality of the features, starting from |T| == |X|/m and decreasing
for m, M in enumerate(range(Mmax, Mmin-1, -2)):
    for i, beta in enumerate(np.linspace(beta_min, beta_max, n_betas)[::-1]):

        L = np.inf
        I_TX = np.nan
        I_TY = np.nan
        for _ in range(n_tries):

            pTX = make_probs(Xdim, 1, M)

            pT_X = pTX / np.sum(pTX, axis=2, keepdims=True) # Normalize to get p(t|x)

            pT = np.sum(pT_X * pX, axis=0, keepdims=True) # Calculate p(t) using p(x)

            pY_T = np.sum(pY_X * (pT_X * pX / pT) , axis=0, keepdims=True)

            for _ in range(n_iters):

                unnormalized_pT_X = pT * np.exp((-1) * beta * np.sum(DKL(pY_X, pT_X), axis=2))

                sum_unnormalized_pT_X = np.sum(unnormalized_pT_X, axis=2, keepdims=True)

                pT_X = unnormalized_pT_X / sum_unnormalized_pT_X

```

```

pT = np.sum(pT_X * pX, axis=0, keepdims=True) # Recalculate p(t

pY_T = np.sum(pY_X * (pT_X * pX / pT), axis=0, keepdims=True)
#print(pY_T.shape)
I_TX_ = I(pT, pX, pT_X * pX)
I_TY_ = I(pT, pY, pY_T * pT)

L_ = I_TX_ - I_TY_ * beta # calculate the objective of IB

if L_ < L: # find find the minimum within n_iters. we need it be
    L = L_
    I_TX = I_TX_
    I_TY = I_TY_

# save minimum L, corresponding beta, and mutual information tx and ty
Ls[m, i] = L
I_TXs[m, i] = I_TX
I_TYs[m, i] = I_TY
betas[m, i] = beta

fig, axs = plt.subplots(1, 3, figsize=(15, 5))

# relevance-compression curves
axs[0].set_title("Lagrangian Temperature Relevance-Compression Curves")
axs[0].set_xlabel("I(T;X)/H(X)")
axs[0].set_ylabel("I(T;Y)/I(Y;X)")
for i, (itx, ity, ls) in enumerate(zip(I_TXs, I_TYs, Ls)):
    axs[0].scatter(itx / hX, ity / target_MI, label=f"M:{Mmax - i}", s=5, c=ls,

axs[1].set_title("Beta Temperature Relevance-Compression Curves")
axs[1].set_xlabel("I(T;X)/H(X)")
axs[1].set_ylabel("I(T;Y)/I(Y;X)")
for i, (itx, ity, bs) in enumerate(zip(I_TXs, I_TYs, betas)):
    axs[1].scatter(itx / hX, ity / target_MI, label=f"M:{Mmax - i}", s=5, c=bs,

axs[2].set_title("Relevance-Compression Curves")
axs[2].set_xlabel("I(T;X)/H(X)")
axs[2].set_ylabel("I(T;Y)/I(Y;X)")
for i, (itx, ity) in enumerate(zip(I_TXs, I_TYs)):
    axs[2].scatter(itx / hX, ity / target_MI, label=f"M:{Mmax - i}", s=5)
axs[2].legend()

fig.tight_layout()
plt.show()

```

```

In [7]: if __name__ == '__main__':
        iterative_information_bottleneck(
            Xdim=10,
            Ydim=5,
            Mmax=10, # the same cardinality as in the original X
            Mmin=1, # everything is collapsed to a single cluster
            n_iters=100,
            n_tries=100,
            n_betas=1000,
            beta_min=0.1,
            beta_max=1000
        )

```

The MI between generated X and Y is: 0.10646865253266291  
 The entropy of X is: 2.2506336580637005

