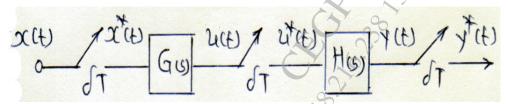
Total	No. o	of Questions : 6] SEAT No. :
P58	09	[Total No. of Pages : 2
		B.E/Insem/Oct560 B.E. (Electrical)
		Control System - II
		(2015 Pattern) (Semester - I)
		[Max. Marks: 30
Instr	uctio	ns to the candidates:
	1)	Answer any one question from each pair of questions: Q.1 or Q.2, Q.3 or Q.4, Q.5 or Q.6.
Q 1)	a)	Draw and explain configuration of Basic Digital Control System. [6]
	b)	What is holding device? Explain the operation of zero order hold circuit. [4]
Q 2)	a)	What are the advantages and limitations of Digital Control System? [6]
	b)	Discuss various practical aspects of choice of sampling rate. [4]
Q3)	a)	Calculate $y(k)$ if $y(0)=1$ and $y(1)=0$ and $y(k)$ satisfies the difference equation $Y(k+2)+3y(k+1)+2y(k)=u(k)$. Where $u(k)$ is unit step sequence. [6]

b)

State and prove Linearity and Time shifting property of Z-transform.[4]

OR

Find pulse transfer function of cascaded elements shown **Q4**) a) **[6]**



Derive an expression for Pulse Transfer Function of ZOH using transfer b) function of ZOH. **[4]**

- **Q5)** a) Explain 'Direct digital programming' of realization of digital controller. [6]
 - b) Illustrate stability analysis of closed loop system in Z-plane using Jury's test. [4]

OR

Q6) a) Determine the stability using Bilinear transformation of the system whose characteristic equation is [6]

 $5Z^2 - 2Z + 2 = 0$

b) Discuss mapping between S-Plane and Z-Plane.

[4]



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