Total No.	of	Questions	:	10]
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SEAT No.	:	

[Total No. of Pages : 2

[5561]-678

B.E. (Computer Engineering)

ARTIFICIAL INTELLIGENCE AND ROBOTICS

(2015 Pattern) (410242) (Semester - I) (End Semester)

Time	: 21	[Max. Marks : 1	70
		ions to the candidates:	
	1)	Answer Q.1 or Q.2, Q.3 or Q.4, Q.5 or Q.6, Q.7 or Q.8, Q.9 or Q.10.	
	<i>2</i>)	Neat diagrams must be drawn wherever necessary.	
	<i>3</i>)	Figures to the right indicate full marks.	
	<i>4</i>)	Assume suitable data, if necessary.	
	<i>5</i>)	Justify your answer with an example wherever necessary.	
		6.	
<i>Q1</i>)	a)	With an example explain A star algorithm. State the properties of A st algorithm.	ar 6]
	b)	Compare and explain Depth First search and Breadth First search	
	U)		6]
		QR QR	נט
Q 2)	a)	Comment on Backtracking and look ahead strategies in constrain	nt
		satisfaction problems.	6]
	b)	Explain goal stack planning with an example of blocks world.	6]
<i>Q3</i>)	3)	What are the drawbacks of propositional logic used in representation	of
Q_{J}	α)		6]
	b)		_
	b)		
		, O.	6]
		OR OR	
Q4)	a)	Explain the process of resolution with proper example. [6]	6]
	b)	Describe PEAS for WUMPUS world problem. [6]	6]
Q 5)	a)	What is Artificial Neural Network? Give two applications of artifici	al
		neural networks in detail.	6]
	b)	Explain any two types of learning.	6]
	c)	Comment on the hardware components of a mobile robot.	6]
	,		•

Q6)	a)	Comment on the methodologies on which laser rangefinders are based	sed. [6]
	b)	Explain machine translation using natural language processing (NLP)). [6]
	c)	Comment on sonar sensing.	[6]
Q 7)	a)	Explain the architecture of information retrieval system.	[6]
	b)	Compare the various weighting functions used in pose estimation.	[4]
	c)	Comment on vertical decomposition in robotics. OR	[4]
Q8)	a)	Explain any two sensors used in robots.	[6]
	b)	Explain the applications of Natural Language Processing.	[4]
	c)	Comment on how robotics can be used to design intelligent vehicles	s. [4]
Q9)	a)	Explain localization and comment on any two types of localization.	[6]
	b)	Comment on the fundamental problem in robotics.	[4]
	c)	With the help of an architecture diagram explain feed forward artification neural network. OR	[4]
Q10)a)	Comment on how robots can be used for mining automation.	[6]
	b)	Comment on issues regarding natural language processing in informa retrieval.	tion [4]
	c)	Explain use of robots in agriculture and forestry.	[4]
		Comment on how robots can be used for mining automation. Comment on issues regarding natural language processing in information retrieval. Explain use of robots in agriculture and forestry.	