

[5460] - 566

T.E. (Electrical) (Semester - II)

CONTROL SYSTEM - I

(2015 Pattern)

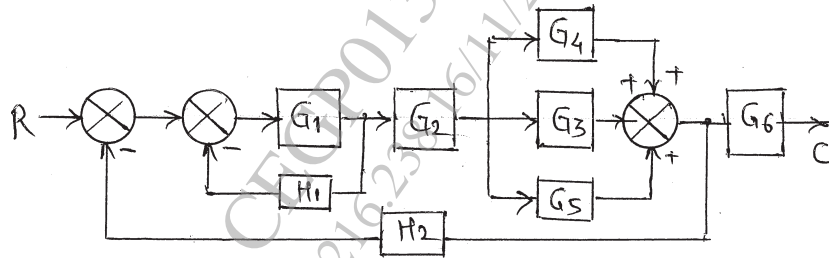
Time : 2½ Hours]

[Max. Marks : 70

Instructions to the candidates:

- 1) Answer any one question from each pair of questions : Q.1 or Q.2, Q.3 or Q.4, Q.5 or Q.6, Q.7 or Q.8.
- 2) Figures to the right indicate full marks.

- Q1)** a) Derive an expression for Force - voltage analogy in Translational and Rotational systems using simple R - L - C series circuit. [8]
- b) Draw signal flow graph and obtain the transfer function using Mason's Gain Formula for the block diagram shown below : [8]



- c) A unity feedback system having open loop transfer function. [4]

$$G(s) = \frac{100}{s(s+10)}$$

determine :

- i) Error constants  $k_p$ ,  $k_v$  and  $k_a$ .
- ii) Steady state error for unit step input.

OR

P.T.O.

- Q2)** a) Derive an expression for Rise time ( $T_r$ ) and Settling time ( $T_s$ ) for second order under damped system for unit step input. [8]
- b) Sketch the root locus and comment on the stability for a unity feedback system with open loop transfer function. [8]

$$G(s)H(s) = \frac{K}{s(s+1+j)(s+1-j)}$$

- c) For a system with  $F(s) = s^4 + 22s^3 + 10s^2 + s + k$ . Use Routh's criterion to obtain the marginal value of  $k$  and the frequency of oscillations of that value of  $k$ . [4]
- Q3)** a) Compare frequency domain specifications and time domain specifications of control system. [8]
- b) The specifications of standard second order unity feedback control system are that the maximum overshoot must not exceed 30% and rise time must be less than 0.2 second. Find the limiting values of resonant peak  $M_r$  and Bandwidth. [8]

OR

- Q4)** a) Derive an expression for resonant frequency ( $\omega_r$ ) for standard second order system. [8]
- b) Sketch the Polar plot and determine gain margin for a unity feedback system having open loop transfer function. [8]

$$G(s) = \frac{1}{s(s+1)(2s+1)}$$

- Q5)** a) State and explain Nyquist stability criterion. [6]
- b) The open loop transfer function of a unity feedback system is given by

$$G(s) = \frac{10}{s(1+0.5s)(1+0.1s)}$$

Draw Bode plot and determine GM, PM, gain cross over frequency and phase cross over frequency. Comment on stability of the system. [12]

OR

- Q6)** a) Define the terms : Cut - off frequency ( $\omega_c$ ), Resonance Peak Frequency ( $M_p$ ), Resonant Frequency ( $\omega_r$ ) [6]  
b) Draw Bode plot for a system having [12]

$$G(s)H(s) = \frac{100}{s(s+1)(s+2)}$$

Comment on stability of the system.

- Q7)** a) Draw block diagram and discuss PD controller. [8]  
b) Write short note on Synchros. [8]

OR

- Q8)** a) Differentiate between phase Lead and phase Lag compensation. [8]  
b) The system given below is so design to have damping ratio 0.707. Determine the required value of  $K_p$  for given damping ratio. [8]

