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APR - 18/TE/Insem. - 106

T.E. (Mechanical/Automobile)

NUMERICAL METHODS AND OPTIMIZATION

(2015 Course) (Semester - II) (302047)

Time: 1 Hour] [Max. Marks: 30

Instructions to the candidates:

- 1) Solve Q1 or Q2, Q3 or Q4, Q5 or Q6.
- 2) Neat diagrams must be drawn wherever necessary.
- 3) Figures to the right indicate full marks.
- 4) Use of programmable calculator is not permitted.
- 5) Assume suitable data, if necessary.
- Q1) a) In a cam follower system the displacement 'd' of the follower tip in term of angle of rotation ' θ ' is given by [6]

$$d = \theta + \sin(\theta) \quad 0 \le \theta \le 2\pi$$
.

Determine value of ' θ ' which produces displacement d = 1 cm. Check convergence and solve upto 4 decimal place accuracy. Take initial guess 0.

b) Define the following terms

[4]

- i) Error propagation.
- ii) Significant digits.
- iii) Relative error.
- iv) Truncation error

OR

Q2) a) Draw the flowchart for Bisection method.

[6]

- b) Round off the number 8.74350 to three significant digits and compute relative error, absolute error and percentage error. [4]
- Q3) Solve by Gauss Seidal method for four decimal accuracy for the following system of equations:[10]

$$28x + 4y - z = 32$$

$$x + 3y + 10z = 24$$

$$2x + 17y + 4z = 35$$

OR

Solve the following equations with Thomas algorithm. *Q4*) a)

[6]

$$x_1 + 2x_2 = 4$$

$$-x_1 + x_2 + 2x_3 = 1$$

$$x_2 + 3x_3 + x_4 = 7$$

$$2x_3 + 2x_4 = 8$$

- Explain step by step procedure for Gauss Jacobi method to compute b) solution of simultaneous equations. Comment on convergence of Gauss Jacobi method and Gauss Seidal method.
- **Q5)** Minimize $Z = 600x_1 + 500x_2$

[10]

Subjected to condition

$$2x_1 + x_2 \ge 80$$

$$x_1 + 2x_2 \ge 60$$

$$x_1, x_2 \ge 0$$

Use Simplex method.

Maximize Z = x + (y/2)**Q6)** a)

Subjected to condition

$$3x + 2y < 12$$

$$5x \le 10$$

$$x + y \le 18$$

$$-x + y \ge 4$$

$$x, y \ge 0$$

Solve by graphical method

Define the following terms: b)

[6]

- Feasible solution. i)
- ii) Non negativity condition.
- Constraints. iii)
- Optimal solution. iv)