# 8 PUZZLE SOLVER

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# **PROBLEM STATEMENT**

The 8-puzzle is a classic sliding puzzle that consists of a 3x3 grid with 8 numbered tiles (1 through 8) and one empty space (represented as 0). The objective is to rearrange the tiles from a given initial configuration to reach the goal configuration by sliding the tiles into the empty space.

- 1. Initial State: A scrambled 3x3 grid of tiles.
- 2.Goal State: The solved configuration of the puzzle:
  - 123
  - 456
  - 780
- 3. Valid Moves: The empty space can move up, down, left, or right into an adjacent tile, provided the move is within the bounds of the grid.
- 4. Objective: Find the shortest sequence of moves to transform the initial state into the goal state.

# **Approach**

To solve the 8-puzzle problem, you can use one of the following algorithms:

#### 1.Breadth-First Search (BFS):

Guarantees the shortest path.

Explores all possible states level by level.

Uses a queue to manage states and a set to track visited states.

#### 2.A Algorithm\*:

Uses a heuristic function to guide the search.

#### 3. Common heuristics include:

Manhattan Distance: Sum of the distances of each tile from its goal position.

Hamming Distance: Number of tiles in the wrong position.

Prioritizes states with the lowest cost (f(n) = g(n) + h(n)), where:

g(n) = cost to reach the current state.

h(n) = heuristic estimate of the cost to reach the goal.

### **Key Challenges**

- 1.State Space Explosion: The 8-puzzle has 9! (362,880) possible states, so efficient algorithms and data structures are required.
- 2. Heuristic Design: For A\*, the heuristic must be admissible (never overestimates the cost) to guarantee optimality.
- 3. Memory Management: BFS and A\* can consume significant memory for large state spaces.

#### CODE

from heapq import heappush, heappop # Function to calculate the Manhattan Distance heuristic def manhattan\_distance(state, goal): """Calculate the Manhattan Distance heuristic between the current state and goal.""" distance = 0 for i in range(9): # Iterate through all tiles if state[i] != 0: # Skip the empty tile # Calculate current position (x1, y1) x1, y1 = i % 3, i // 3# Calculate goal position (x2, y2) x2, y2 = (goal.index(state[i])) % 3, (goal.index(state[i])) // 3 # Add the Manhattan distance for the current tile distance += abs(x1 - x2) + abs(y1 - y2) return distance # Function to generate neighboring states def get\_neighbors(state): """Generate valid neighboring states by moving the empty tile (0).""" neighbors = [] zero\_idx = state.index(0) # Find the position of the empty tile x, y = zero\_idx % 3, zero\_idx // 3 # Get its coordinates # Define possible movements (Left, Right, Up, Down) for dx, dy in [(-1, 0), (1, 0), (0, -1), (0, 1)]: nx, ny = x + dx, y + dy # New coordinates after movementif  $0 \le nx \le 3$  and  $0 \le ny \le 3$ : # Check boundaries swap\_idx = ny \* 3 + nx # Get the 1D index after movement neighbor = list(state) # Copy the current state # Swap the empty tile with the target tile neighbor[zero\_idx], neighbor[swap\_idx] = neighbor[swap\_idx], neighbor[zero\_idx] neighbors.append(tuple(neighbor)) # Add the new state to neighbors return neighbors # Function to check if the puzzle is solvable def is\_solvable(state, goal=(1, 2, 3, 4, 5, 6, 7, 8, 0)):

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"""Check solvability using the inversion count."""
 inversions = 0
  # Remove the empty tile and count inversions in the remaining tiles
  state = [num for num in state if num != 0]
 for i in range(len(state)):
   for j in range(i + 1, len(state)):
     if state[i] > state[j]:
        inversions += 1
 return inversions % 2 == 0 # Puzzle is solvable if inversions are even
# A* Search algorithm to solve the 8-puzzle
def a_star_solver(initial, goal=(1, 2, 3, 4, 5, 6, 7, 8, 0)):
  """Solve the 8-puzzle using A* Search with Manhattan Distance heuristic."""
 if not is_solvable(initial, goal): # Check if the puzzle is solvable
    return None # Return None if unsolvable
 heap = [] # Priority queue for A* search
  # Push the initial state with priority based on heuristic
 heappush(heap, (manhattan_distance(initial, goal), 0, initial, []))
 visited = set() # Keep track of visited states to avoid loops
 while heap: # While there are states to explore
   _, cost, current, path = heappop(heap) # Get the state with the lowest priority
   if current == goal: # Check if the goal state is reached
      return path + [current] # Return the solution path
    if current in visited: # Skip already visited states
      continue
    visited.add(current) # Mark the state as visited
    for neighbor in get_neighbors(current): # Explore all neighbors
     if neighbor not in visited: # Only consider unvisited states
       # Calculate priority for the neighbor state
        priority = cost + 1 + manhattan_distance(neighbor, goal)
        # Add the neighbor to the heap
        heappush(heap, (priority, cost + 1, neighbor, path + [current]))
 return None # Return None if no solution is found
# Prompt user to input the initial state
print("Enter the initial state as 9 space-separated numbers (use 0 for the blank):")
initial_input = input().strip().split() # Read input from the user
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initial_state = tuple(map(int, initial_input)) # Convert input to a tuple of integers
# Solve the puzzle
solution = a_star_solver(initial_state) # Call the A* solver
if solution:
    print(f"Solution found in {len(solution) - 1} moves:")
    for step, state in enumerate(solution): # Print each step of the solution
    print(f"Step {step}:")
        # Format the state as a 3x3 grid
        print("\n".join(" ".join(map(str, state[i*3:(i+1)*3])) for i in range(3)))
        print()
else:
        print("No solution exists.") # Notify the user if the puzzle is unsolvable
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# **OUTPUT**

Enter the initial state as 9 space-separated numbers (use 0 for the blank): Solution found in 2 moves: Step 0: Step 1: Step 2: