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# ciphart

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## memory-hard key derivation with easier measurable security

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*argon2*<sup>2</sup> is mostly nice, but trying to interpret its contribution to the protection against password brute-forcing attacks remains more difficult than it should be. this vagueness is a problem that is not limited to *argon2*, but also shared with every other key derivation function that i've known so far.

when one uses *argon2*, his derived key will surely have superior protection against password brute-forcing attacks, but by how much? to answer this, one would need to survey the industry that manufactures application-specific integrated circuits (asics) to obtain a map between *time* and *money*, in order to get an estimation on how much would it cost the adversary to discover the password in a given time window.

while the approach of surveying the asics industry is not wrong, it is largely subjective, with expensive housekeeping, and practically leads the user to rely on vague foundations to build his security on. this vagueness is not nice, and it would be better if we had an objective measure to quantify the security of our memory-hard key derivation functions.

resolving this vagueness is not a mere luxury to have, but a necessity for maximising survival, because it hinders the process of studying the cost-value of memory-hard key derivation functions, which, effectively, increases the risk of having a false sense of security.

so i propose *ciphart* — a memory-hard key derivation function with a security contribution that is measured in a unit that i call *relative entropy bits*. this unit is measured objectively and is guaranteed to be true irrespective of whatever alien technology that the adversary might have.

**libciphart**<sup>3</sup> is a library that implements *ciphart* very closely to this paper, without much fluff. this should make integrating *ciphart* into other systems more convenient.

**ciphart**<sup>4</sup> is an application for encrypting and decrypting files that makes use of **libciphart**. this application is intended for use by end-users or scripts, henceforth it has some fluff to treat mankind with dignity.

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## 1 ciphart

### 1.1 parameters

<i>enc</i>	encryption function.
<i>p</i>	password.
<i>s</i>	salt.
<i>M</i>	total memory in bytes.
<i>L</i>	number of memory lanes for concurrency.
<i>T</i>	number of tasks per lane segment.
<i>R</i>	number of rounds per task.
<i>B</i>	minimum quantity of increased protection against password brute-forcing attacks in the unit of <i>relative entropy bits</i> .
<i>K<sub>out</sub></i>	output key size in bytes.

### 1.2 internal variables

$C$	$\leftarrow \begin{cases} 64 \text{ bytes} & \text{if } enc \text{ is } xchacha20 \\ 16 \text{ bytes} & \text{if } enc \text{ is } aes \\ \dots \end{cases}$ this to reflect the block size of the encryption algorithm that implements <i>enc</i> .
$K_{in}$	$\leftarrow \begin{cases} 32 \text{ bytes} & \text{if } enc \text{ is } xchacha20 \\ 16 \text{ bytes} & \text{if } enc \text{ is } aes-128 \\ \dots \end{cases}$ this is the size of the encryption key that's used to solve <i>ciphart</i> 's tasks. this is different than the <i>enc</i> -independent <i>K<sub>out</sub></i> which is possibly used by other encryption algorithms in later stages <sup>5</sup> .
$\hat{T}$	$\leftarrow \max(\lceil K_{in}/C \rceil, T)$ . this is to ensure that we have enough encrypted bytes for new keys.
$\hat{T}$	$\leftarrow T - (T \bmod 2) + 2$ . this is to ensure that there is an even number of tasks in a segment. why? because we need a buffer for storing the clear-text and another for storing the output cipher-text.

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<sup>2</sup><https://github.com/P-H-C/phc-winner-argon2>

<sup>3</sup><https://github.com/Al-Caveman/libciphart>

<sup>4</sup><https://github.com/Al-Caveman/ciphart>

<sup>5</sup>at the expense of losing the meaning of *relative entropy bits*.

$\hat{M} \leftarrow M - (M \bmod C\hat{T}L) + C\hat{T}L$ . this is to ensure that it is in multiples of  $C\hat{T}L$ . why? so that all segments are of equal lengths in order to simplify *ciphart*'s logic. e.g. it wouldn't be nice if the last segments were of unequal sizes.  
 $G \leftarrow \hat{M}C^{-1}\hat{T}^{-1}L^{-1}$ . total number of segments per lane.  
 $\hat{B} \leftarrow \max(\hat{M}C^{-1}R, 2^B)$ . this is to ensure that  $\hat{B}$  is large enough to have at least one pass over the  $\hat{M}$ -bytes memory.  
 $\hat{B} \leftarrow \hat{B} - (\hat{B} \bmod L\hat{T}R) + L\hat{T}R$ . this is to reflect the reality that, with *ciphart*, segments must complete. i.e. when the user asks for  $B$  relative entropy bits, he gets  $\log_2 \hat{B}$  bits instead, where  $\log_2 \hat{B} \geq B$ .  
 $m_i$   $C$ -bytes memory for  $i^{th}$  task in the  $\hat{M}$ -bytes pad.  
 $n_l$   $\leftarrow lG\hat{T}R$ . nonce variable for  $l^{th}$  lane with at least 64 bits.  
 $f \leftarrow 0$ . a flag indicating whether the  $\hat{M}$ -bytes pad is filled.

### 1.3 output

$k$   $K_{\text{out}}$ -bytes key with  $\geq B$  relative entropy bits.

### 1.4 steps

steps of *ciphart* is shown in algorithm 1. this corresponds to *argon2d*. adding a *ciphart-i* variant is a trivial matter, i just didn't do it yet because my threat model currently doesn't benefit from a password independent variant.

## 2 parallelism

since iterations of the loop in line 4 in algorithm 1 are fully independent of one other, they can quite happily utilise  $L$  cpu cores, specially when segment sizes,  $T$ , are larger.

other lines are not easily independent, so i didn't even bother to try to parallelise them. specially since this is not a problem, since the cpu-heavy part is in the easily-parallelise-able part.

with *argon2*, if one wants to increase the cpu load without increasing memory pad's use, one can increase the number of passes over the pad. this feature is supported by *ciphart* via the *relative entropy bits* parameter  $B$ .

but, simply increasing number of passes on the pad may not be the best option for all cases. e.g. what if someone has a small pad, and small segments? in such case, a higher percentage of the cpu will be wasted in the non-parallelise-able steps, which is a waste.

this is why *ciphart* has an additional parameter  $R$ . this parameter can allow to increase the load on the cpu without even requiring to go through the non-parallelise-able steps. *argon2* lacks this parameter. this is not the main reason *ciphart* was made, but it's one of the incremental improvements.

philosophically, i think that *argon2* does have the  $R$  parameter, except that it assumes that  $R = 1$ , and does not allow the user to change it. i don't agree with this assumption, which is why i made *ciphart* to allow the user to set  $R$  more freely.

however, i think that  $R = 1$  is best for the first pass to ensure that the memory is filled soonest possible. this is why *ciphart* assumes  $R = 1$  in the first pass, just to fill the memory as soon as possible. but in subsequent passes, user's value for  $R$  will be chosen. i.e. if  $R = 5$ , then each task in later passes will be solved recursively 5 times.

## 3 memory-hardness

## 4 security interpretation

## 5 comparison

## 6 summary

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**algorithm 1:** ciphart

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```
1 while 1 do
2   if  $f = 0$  then  $\hat{R} \leftarrow 1$  else  $\hat{R} \leftarrow R$ ;
3   for  $g = 0, 1, \dots, G - 1$  do
4     for  $l = 0, 1, \dots, L - 1$  do
5       for  $t = 0, 1, \dots, T - 1$  do
6          $i \leftarrow gLT + t$ ;
7         if  $t < T - 1$  then
8            $j \leftarrow i + 1$ ;
9         else if  $t = T - 1$  then
10           $j \leftarrow i - T + 1$ ;
11        for  $r = 0, 1, \dots, \hat{R} - 1$  do
12           $m_j \leftarrow \text{enc}(m_i, n_l, k)$ ;
13           $\hat{i} \leftarrow i$ ;
14           $i \leftarrow j$ ;
15           $j \leftarrow \hat{i}$ ;
16           $n_l \leftarrow n_l + 1$ ;
17          if  $f = 0$  then
18             $v \leftarrow m_j \bmod (gLT + t)$ ;
19            if  $v \geq gLT$  then
20               $v \leftarrow v + lT$ ;
21          else
22             $v \leftarrow m_j \bmod (GLT - LT + t)$ ;
23            if  $v \geq gLT + t$  then
24               $v \leftarrow v + LT$ ;
25            else if  $v \geq gLT$  then
26               $v \leftarrow v + lT$ ;
27           $k \leftarrow m_v[0 : K_{\text{in}}]$ ;
28        if  $n_1 L = \hat{B}$  then
29           $g_{\text{last}} = g$ ;
30          go to line 32;
31       $f \leftarrow 1$ ;
32 while 1 do
33   for  $l = 1, 2, \dots, L$  do
34     if  $\text{len}(k) \geq K_{\text{out}}$  then return  $k[0 : K_{\text{out}}]$ ;
35      $n \leftarrow n + 1$ ;
36      $k \leftarrow k \parallel \text{enc}(m_{l,S,T}[1], n, k)$ 
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