

## 0.1 Helper Morphisms

### 0.1.1 Diagonal and Twist Morphisms

In the definition and proofs (Especially of the the If cases), I make use of the morphisms twist and diagonal.

$$\tau_{A,B} : (A \times B) \rightarrow (B \times A) = \langle \pi_2, \pi_1 \rangle \quad (1)$$

$$\delta_A : A \rightarrow (A \times A) = \langle \text{Id}_A, \text{Id}_A \rangle \quad (2)$$

## 0.2 Denotations of Types

### 0.2.1 Denotation of Ground Types

The denotations of the default ground types, `Unit`, `Bool` should be as follows:

$$\llbracket \text{Unit} \rrbracket_M = 1 \quad (3)$$

$$\llbracket \text{Bool} \rrbracket_M = 1 + 1 \quad (4)$$

The mapping  $\llbracket - \rrbracket_M$  should then map each other ground type  $\gamma$  to an object in  $\mathbb{C}$ .

### 0.2.2 Denotation of Computation Type

Given a function  $\llbracket - \rrbracket_M$  mapping value types to objects in the category  $\mathbb{C}$ , we write the denotation of Computation types  $\mathbb{M}_\epsilon A$  as so:

$$\llbracket \mathbb{M}_\epsilon A \rrbracket_M = T_\epsilon \llbracket A \rrbracket_M$$

Since we can infer the denotation function, we can include it implicitly and drop the denotation sign.

$$\llbracket \mathbb{M}_\epsilon A \rrbracket_M = T_\epsilon A$$

### 0.2.3 Denotation of Function Types

Given a function  $\llbracket - \rrbracket_M$  mapping types to objects in the category  $\mathbb{C}$ , we write the denotation of a function type  $A \rightarrow \mathbb{M}_\epsilon B$  as so:

$$\llbracket A \rightarrow \mathbb{M}_\epsilon B \rrbracket_M = (T_\epsilon \llbracket B \rrbracket_M)^{\llbracket A \rrbracket_M}$$

Again, since we can infer the denotation function, Let us drop the notation.

$$\llbracket A \rightarrow \mathbb{M}_\epsilon B \rrbracket_M = (T_\epsilon B)^A$$

### 0.2.4 Denotation of Type Environments

Given a function  $\llbracket - \rrbracket_M$  mapping types to objects in the category  $\mathbb{C}$ , we can define the denotation of an `Ok` type environment  $\Gamma$ .

$$\llbracket \diamond \rrbracket_M = 1$$

$$\llbracket \Gamma, x : A \rrbracket_M = (\llbracket \Gamma \rrbracket_M \times \llbracket A \rrbracket_M)$$

For ease of notation, and since we normally only talk about one denotation function at a time, I shall typically drop the denotation notation when talking about the denotation of value types and type environments. Hence,

$$\llbracket \Gamma, x : A \rrbracket_M = \Gamma \times A$$

## 0.3 Denotation of Terms

Given the denotation of types and typing environments, we can now define denotations of well typed terms.

$$\llbracket \Gamma \vdash t : \tau \rrbracket_M : \Gamma \rightarrow \llbracket \tau \rrbracket_M$$

Denotations are defined recursively over the typing derivation of a term. Hence, they implicitly depend on the exact derivation used. Since, as proven in the chapter on the uniqueness of derivations, the denotations of all type derivations yielding the same type relation  $\Gamma \vdash t : \tau$  are equal, we need not refer to the derivation that yielded each denotation.

### 0.3.1 Denotation of Value Terms

- (Unit)  $\frac{\text{rOk}}{\llbracket \Gamma \vdash () : \text{Unit} \rrbracket_M = \langle \rangle_{\Gamma} : \Gamma \rightarrow 1}$
- (Const)  $\frac{\text{rOk}}{\llbracket \Gamma \vdash \mathbf{C}^A : A \rrbracket_M = \llbracket \mathbf{C}^A \rrbracket_M \circ \langle \rangle_{\Gamma} : \Gamma \rightarrow \llbracket A \rrbracket_M}$
- (True)  $\frac{\text{rOk}}{\llbracket \Gamma \vdash \mathbf{true} : \text{Bool} \rrbracket_M = \mathbf{inl} \circ \langle \rangle_{\Gamma} : \Gamma \rightarrow \llbracket \text{Bool} \rrbracket_M = 1 + 1}$
- (False)  $\frac{\text{rOk}}{\llbracket \Gamma \vdash \mathbf{false} : \text{Bool} \rrbracket_M = \mathbf{inr} \circ \langle \rangle_{\Gamma} : \Gamma \rightarrow \llbracket \text{Bool} \rrbracket_M = 1 + 1}$
- (Var)  $\frac{\text{rOk}}{\llbracket \Gamma, x : A \vdash x : A \rrbracket_M = \pi_2 : \Gamma \times A \rightarrow A}$
- (Weaken)  $\frac{f = \llbracket \Gamma \vdash x : A \rrbracket_M : \Gamma \rightarrow A}{\llbracket \Gamma, y : B \vdash x : A \rrbracket_M = f \circ \pi_1 : \Gamma \times B \rightarrow A}$
- (Lambda)  $\frac{f = \llbracket \Gamma, x : A \vdash C : \mathbf{M}_{\epsilon} B \rrbracket_M : \Gamma \times A \rightarrow T_{\epsilon} B}{\llbracket \Gamma \vdash \lambda x : A. C : A \rightarrow \mathbf{M}_{\epsilon} B \rrbracket_M = \mathbf{cur}(f) : \Gamma \rightarrow (T_{\epsilon} B)^A}$
- (Subtype)  $\frac{f = \llbracket \Gamma \vdash v : A \rrbracket_M : \Gamma \rightarrow A \quad g = \llbracket A \leq B \rrbracket_M}{\llbracket \Gamma \vdash v : B \rrbracket_M = g \circ f : \Gamma \rightarrow B}$

### 0.3.2 Denotation of Computation Terms

- (Return)  $\frac{f = \llbracket \Gamma \vdash v : A \rrbracket_M}{\llbracket \Gamma \vdash \mathbf{return} v : \mathbf{M}_1 A \rrbracket_M = \eta_A \circ f}$
- (If)  $\frac{f = \llbracket \Gamma \vdash v : \text{Bool} \rrbracket_M : \Gamma \rightarrow 1 + 1 \quad g = \llbracket \Gamma \vdash C_1 : \mathbf{M}_{\epsilon} A \rrbracket_M \quad h = \llbracket \Gamma \vdash C_2 : \mathbf{M}_{\epsilon} A \rrbracket_M}{\llbracket \Gamma \vdash \mathbf{if}_{\epsilon, A} v \text{ then } C_1 \text{ else } C_2 : \mathbf{M}_{\epsilon} A \rrbracket_M = \mathbf{app} \circ ((\mathbf{cur}(g \circ \pi_2), \mathbf{cur}(g \circ \pi_2)) \circ f) \times \mathbf{Id}_{\Gamma}) \circ \delta_{\Gamma} : \Gamma \rightarrow T_{\epsilon} A}$
- (Bind)  $\frac{f = \llbracket \Gamma \vdash C_1 : \mathbf{M}_{\epsilon_1} A : \Gamma \rightarrow T_{\epsilon_1} A \rrbracket_M \quad g = \llbracket \Gamma, x : A \vdash C_2 : \mathbf{M}_{\epsilon_2} B \rrbracket_M : \Gamma \times A \rightarrow T_{\epsilon_2} B}{\llbracket \Gamma \vdash \mathbf{do} \ x \leftarrow C_1 \ \mathbf{in} \ C_2 : \mathbf{M}_{\epsilon_1 \cdot \epsilon_2} B \rrbracket_M = \mu_{\epsilon_1, \epsilon_2, B} \circ T_{\epsilon_1} g \circ \mathbf{t}_{\Gamma, A, \epsilon_1} \circ \langle \mathbf{Id}_{\Gamma}, f \rangle : \Gamma \rightarrow T_{\epsilon_1 \cdot \epsilon_2} B}$
- (Subeffect)  $\frac{f = \llbracket \Gamma \vdash c : \mathbf{M}_{\epsilon_1} A \rrbracket_M : \Gamma \rightarrow T_{\epsilon_1} A \quad g = \llbracket A \leq B \rrbracket_M \quad h = \llbracket \epsilon_1 \leq \epsilon_2 \rrbracket}{\llbracket \Gamma \vdash C : \mathbf{M}_{\epsilon_2} B \rrbracket_M = h \circ T_{\epsilon_1} g \circ f}$
- (Apply)  $\frac{f = \llbracket \Gamma \vdash v_1 : A \rightarrow \mathbf{M}_{\epsilon} B \rrbracket_M : \Gamma \rightarrow (T_{\epsilon} B)^A \quad g = \llbracket \Gamma \vdash v_2 : A \rrbracket_M : \Gamma \rightarrow A}{\llbracket \Gamma \vdash v_1 \ v_2 : \mathbf{M}_{\epsilon} B \rrbracket_M = \mathbf{app} \circ \langle f, g \rangle : \Gamma \rightarrow T_{\epsilon} B}$