Combine: Because the subarrays are already sorted, no work is needed to combine them: the entire array A[p..r] is now sorted.

The following procedure implements quicksort:

```
QUICKSORT(A, p, r)

1 if p < r

2 q = \text{PARTITION}(A, p, r)

3 QUICKSORT(A, p, q - 1)

4 QUICKSORT(A, q + 1, r)
```

To sort an entire array A, the initial call is QUICKSORT (A, 1, A. length).

Partitioning the array

The key to the algorithm is the PARTITION procedure, which rearranges the subarray A[p ... r] in place.

```
PARTITION(A, p, r)

1 x = A[r]

2 i = p - 1

3 for j = p to r - 1

4 if A[j] \le x

5 i = i + 1

6 exchange A[i] with A[j]

7 exchange A[i + 1] with A[r]

8 return i + 1
```

Figure 7.1 shows how PARTITION works on an 8-element array. PARTITION always selects an element x = A[r] as a *pivot* element around which to partition the subarray A[p..r]. As the procedure runs, it partitions the array into four (possibly empty) regions. At the start of each iteration of the **for** loop in lines 3–6, the regions satisfy certain properties, shown in Figure 7.2. We state these properties as a loop invariant:

At the beginning of each iteration of the loop of lines 3–6, for any array index k,

```
    If p ≤ k ≤ i, then A[k] ≤ x.
    If i + 1 ≤ k ≤ j - 1, then A[k] > x.
    If k = r, then A[k] = x.
```