#### Constrained Functions

Text: Chapter 6

There are some situations in which we want to include known restrictions about x(t).

- $\triangleright$  x(t) is always positive
- $\triangleright$  x(t) is always increasing (or decreasing)
- $\triangleright$  x(t) is a density

**Idea:** Enforce these conditions by transforming x(t).

# Positive Smoothing

We want to ensure that x(t) > 0.

Observation:

$$e^w:(-\infty,\infty)\to(0,\infty)$$

So try the transformation

$$x(t) = e^{W(t)}$$

with

$$W(t) = \Phi(t)\mathbf{c}$$

and penalize the roughness of W(t)

## Estimating a Positive Smooth

We now want to minimize

$$\mathsf{PENSSE}_{\lambda}(W) = \sum_{i=1}^{n} \left( y_i - e^{W(t_i)} \right)^2 + \lambda \int [LW(t)]^2 dt$$

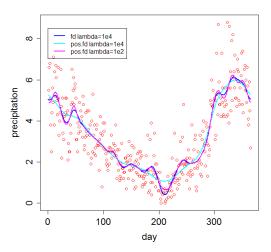
This does not have an explicit formula.

But it is convex – there is only one minimum.

Requires numerical optimization, but this is generally fast.

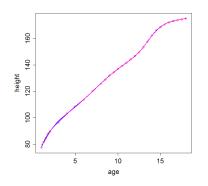
#### Positive Smoothing Vancouver Precipitation

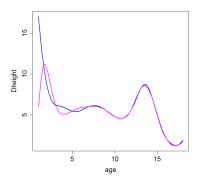
Constraints imply smoothness (of a certain type) – tend to need less smoothing on  $\mathcal{W}$ .



## Monotone Smoothing

#### Berkeley growth study - heights aged 1 - 18





# Monotone Smoothing

We need x(t) always increasing:

suggests

$$Dx(t) = e^{W(t)} \rightarrow x(t) = \alpha + \int_{t_0}^t e^{W(s)} ds$$

again, 
$$W(t) = \Phi(t)\mathbf{c}$$

## Estimating a Monotone Smooth

We now want to minimize

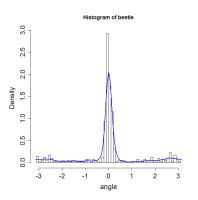
$$PENSSE_{\lambda}(W) = \sum_{i=1}^{n} \left( y_i - \alpha - \int_{t_0}^{t_i} e^{W(s)} ds \right)^2 + \lambda \int [LW(t)]^2 dt$$

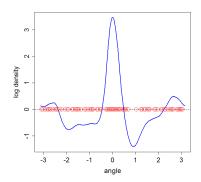
- No explicit formula
- No good formula for the integral
- Still a convex problem; numerics work fairly quickly

Note,  $LW(t) = D^2W(t)$  suggests that any  $x(t) = \alpha + e^{\beta t}$  is smooth.

### **Density Estimation**

#### Position of Beetles in Angles





## Density Estimation

x(t) a density  $\Rightarrow$  positive, integrates to 1

$$x(t) = e^{W(t)} / \int e^{W(t)} dt$$

But we observe only  $t_1, \ldots, t_n$ .

Need to find an objective to minimize.

#### Penalized Likelihood

Likelihood of W(t) is probability of seeing  $t_1, \ldots, t_n$  if W is true.

Easier to work with log likelihood

$$I(W|t_1,\ldots,t_n)=\sum_{i=1}^n\left(W(t_i)-\log\int e^{W(t)}dt\right)$$

Minimize the *penalized negative log likelihood*:

$$\mathsf{PENLOGLIK}_{\lambda}(W) = -\sum_{i=1}^n W(t_i) + n\log \int e^{W(t)} dt + \lambda \int [LW(t)]^2 dt$$

Usual comments about numerics apply.

## Thinking about Smoothness

What is an appropriate measure of smoothness for densities?

$$x(t) = Ce^{W(t)}$$

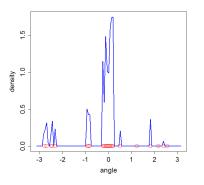
Compare to Normal density

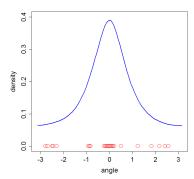
$$f(t) = \frac{1}{\sqrt{2\pi}\sigma} e^{-(t-\mu)^2/\sigma^2}$$

then  $W(t) = t^2$  should be smooth  $\Rightarrow LW(t) = D^3W(t)$ .

Alternatively,  $LW(t) = D^2W(t) \Rightarrow$  exponential distribution is smooth – useful for positive data.

# Rough to Smooth Densities





#### Summary

#### Can put constraints to force

- x(t) > 0 by  $x(t) = e^{W(t)}$
- x(t) monotone by  $x(t) = \alpha + \int_{t_0}^{t} e^{W(s)} ds$
- x(t) a density by  $x(t) = e^{W(t)} / \int e^{W(t)} dt$

Extension: penalized maximum likelihood for x(t) not directly observed.

Requires nonlinear optimization, but still relatively fast.