

CANH

SPI-CAN-FD2



+3V3

I2C1_SDA_ I2C1_SCL_

GPI009

UART1_RTS 11 SPI1_SCK 13

GPI012

SPI0_MOSI

SPI0_MISO

SPIO_SCK 2

I2CO_SDA

SPI1_MOSI__

GPI001 29

GPI011 31 GPI013 33

GND

NX Expansion

10 UART1_RXD

12 | 12S0_SCLK

18 SPI1_CS0

28 | 12C0_SCL

34 36 UART1_CTS

38 | 12SO_DIN

40 I2S0_DOUT

GND

SPI1_CS1

SPI1_MISO

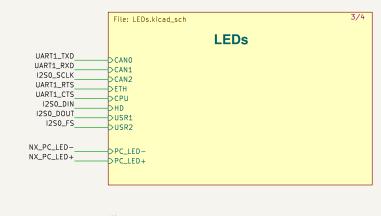
SPI0_CS0

SPI0_CS1

_GPI007

GPI001

GPI011



TNID

RX_INT TX_INT

- O H5 MountingHole



DESCRIPTON NX-Inte	rface (J15)	NX-Indicator	(J3)
NX_PC_LED-	1	1	
UART2_RXD	3	2	
UART1_TXD	4	3	
SYS_RST_RCV_RTN	7	4	
SYS_RESETn	8	5	
FORCE_RECOVERY_RTN	9	6	
FORCE_RECOVERYn	10	7	

- → Seeed Studio J401 Carrier Board
- → Seeed Studio J401 Carrier Board Schematic

1 J4 CAN2

- → Seeed Studio J401 Carrier Board Datasheet
- → J401 Measurements
- → Samtec 40 pin Elevated Socket

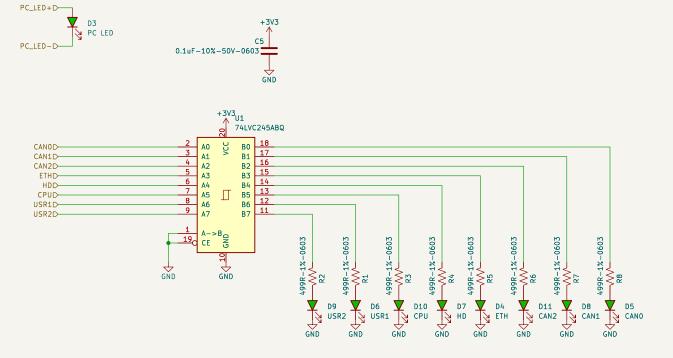


971 Spartan Robotics

File: NX-IndicatorBoard.kicad_sch

Title: NX Indicator Board V2

Size: B Date: 2024-07-14
KiCad E.D.A. 8.0.3 Rev: 2 Page: 1/4 NOTE: PULL DOWN RESITORS MUST BE GREATER THAN 50k
TO COMPLY WITH LEVEL TRANSLATOR







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Sheet: /LEDs/
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