

$$P_t = E_t [m_{t+1} (d_{t+1} + P_{t+1})]$$

no

$\{d_t\}$  - dividends,  $\{P_t\}$

$m_{t+1}$  = stochastic discount factor

$$P_t = E_t [m_{t+1} (d_{t+1} + P_{t+1})] + \text{cov}_t(m_{t+1}, d_{t+1} + P_{t+1})$$

$\beta$

Markov setting

$$S = \{s_1, s_2, \dots, s_n\} \quad n \text{ states}$$

$$P = \text{Prob} \{ \lambda_{t+1} = s_j \mid \lambda_t = s_i \}$$

$$\lambda_t \in S.$$

examples:  $m_t$  — depend only on  $s_t$

$d_t \sim$  depend only on  $s_t$

$P_t \sim$  depend only on  $s_t$

← no bubbles

$$m_t \rightarrow \begin{pmatrix} m_1 \\ \vdots \\ m_n \end{pmatrix}$$

$$, m_i = m_t \text{ when } s_t = s_i.$$

$$m_t \rightarrow \begin{pmatrix} m_1 \\ \vdots \\ m_n \end{pmatrix}$$

$$d_t \rightarrow \begin{pmatrix} d_1 \\ \vdots \\ d_n \end{pmatrix}$$

$$P_t \rightarrow \begin{pmatrix} P_1 \\ \vdots \\ P_n \end{pmatrix}$$

$$\begin{matrix} \begin{pmatrix} m_n \end{pmatrix} & , & \begin{pmatrix} i_n \end{pmatrix} & , & \begin{pmatrix} j_n \end{pmatrix} \\ \pi_t = \begin{pmatrix} \pi_{1,t} \\ \pi_{2,t} \\ \vdots \\ \pi_{n,t} \end{pmatrix} & , & \pi_0 = \begin{pmatrix} \pi_{1,0} \\ \vdots \\ \pi_{n,0} \end{pmatrix} \end{matrix}$$

$$\pi_{j,t+1} = \sum_{i=1}^n P_{i,j} \pi_{i,t}$$

$$\pi'_{t+1} = P \pi'_t \quad \text{or} \quad \pi_{t+1} = P' \pi_t$$

$$\text{Prob} \{ m_{t+1} = m_j \mid s_t = s_i \} = P_{i,j}$$

What does

$$E_t x_{t+j} \quad \text{mean + how compute it.}$$

$$E_t x_{t+1} = \sum_{j=1}^n P_{ij} x_j$$

↑ a vector

whose  $i^{\text{th}}$  component is

$$E_t x_{t+1} = E [x_{t+1} \mid s_t = s_i], \quad i=1, 2, \dots, n$$

$$= \begin{pmatrix} \sum_{j=1}^n P_{1j}^{(h)} x_j \\ \sum_{j=1}^n P_{2j}^{(h)} x_j \\ \vdots \\ \sum_{j=1}^n P_{nj}^{(h)} x_j \end{pmatrix} \leftarrow \text{row today's state}$$

$$P = \begin{pmatrix} P_{11} & P_{12} & \dots & P_{1n} \\ P_{21} & P_{22} & \dots & P_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ P_{n1} & P_{n2} & \dots & P_{nn} \end{pmatrix}$$

$P_{ij}^{(h)}$  =  $i, j$  the element of the  $h^{\text{th}}$  power of  $P$

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Examples: let  $x = \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix}$

let  $P = \begin{matrix} n \times n \\ n \times n \end{matrix}$  stochastic matrix

let  $P^h$  be the  $h^{\text{th}}$  power of  $P$   
 $P^h = P P P \dots P$

tell me what the following  $n \times n$  vector means

$P X$  —  $i^{\text{th}}$  row is the mathematical expectation of  $X_{t+1}$  conditional on  $S_t = S_i$   
 $n \times n \quad n \times 1$

$P^h X$  —  $i^{\text{th}}$  row of — — — —

$$\begin{aligned}
 & \overset{n \times n}{\left( I + \beta P + \beta^2 P^2 + \dots \right)} \overset{n \times 1}{x} \\
 & \beta \text{-scalar } 0 < \beta < 1 \\
 & 1 + c + c^2 + c^3 + \dots = \frac{1}{1-c} \\
 & \left( I - \beta P \right)^{-1} = I + \beta P + \beta^2 P^2 + \dots
 \end{aligned}$$

Neuman series

$$\begin{aligned}
 & \overset{n \times n}{\left( I - \beta P \right)^{-1}} \overset{n \times 1}{x} \sim i\text{th row}
 \end{aligned}$$

is the mathematical expectation of

$$(x_t + \beta x_{t+1} + \beta^2 x_{t+2} + \dots)$$

conditional on  $s_t$  being  $s_i$  at  $t$ .

$$\overset{n \times 1}{\pi_t}$$

Let  $x_t$  be a random variable  $\rightarrow x^{n \times 1}$

$y_t$  be a random variable  $y^{n \times 1}$

Let  $p^{n \times 1}$  be the distribution over states

$$p_i \geq 0 \quad \sum p_i = 1$$

$$E p \cdot x = \sum_{i=1}^n p_i x_i$$

random variable

$$x + y = \begin{pmatrix} x_1, y_1 \\ x_2, y_2 \\ \vdots \\ x_n, y_n \end{pmatrix}$$

$$E x y = \sum_{i=1}^n p_i x_i y_i$$

Python

$$X = \begin{pmatrix} 1 \\ 2 \\ 2.5 \end{pmatrix}, \quad y = \begin{pmatrix} 2 \\ 3 \\ 0 \end{pmatrix} \quad \text{note}$$

$$Z = x y$$

Python

$$X = \text{np.array}((1, 2, 2.5))$$

$$y = \text{np.array}((2, 3, 0))$$

Want

$$Z = \begin{pmatrix} 1 \cdot 2 \\ 2 \cdot 3 \\ 2.5 \cdot 0 \end{pmatrix} \quad Z_i = x_i \cdot y_i$$

$$Z = x * y$$

Want  $E Z$  where  $E$  is w.r.t.  $p$

$$\sum_i p_i x_i y_i \quad E x y$$

Python: "  $\text{sum}(p * x * y)$  "  $\rightarrow E$

Conditional expectation

$i^{\text{th}}$  row of some  $P$   
or  $P^h$



$$E_e m_{t+1} d_{t+1} = \text{sum} (P_{i, \cdot} * m * d)$$



$i^{\text{th}}$  row  
of  $P$

$$\text{sum} (P_{i, \cdot} (m * d))$$

$P_{i, \cdot}$



probability distribution

state space,  $S = \{s_1, \dots, s_n\}$

$\pi_1, \dots, \pi_n$

$p_{11} \dots p_{1n} \uparrow$

$\vdots$   
 $p_{n1} \dots p_{nn}$

random variable — vector

random variable

$$E - \text{Sum}(\pi * X)$$

We are acting as if we know ~~nothing~~

• the probabilities

• the random variables as functions of the state.

Apply: - risk neutral

$$P_t = \beta E_t [d_{t+1} + P_{t+1}] \quad (\text{e})$$

$$d_{t+1} = \lambda_{t+1} d_t,$$

$\lambda_{t+1} \sim$  Markov on state space  
( $s_1, s_2, \dots, s_n$ )

$P$  - transition matrix

Problem: to solve (e) for something that  
tells me  $P_t$  as a function of stuff today.

Guess:

$$P_t = v(\lambda_t) d_t \quad \text{or}$$

$$\frac{P_t}{d_t} = v(\lambda_t)$$

$$d_{t+1} = \lambda_t d_t$$

$$P_t = \beta E_t [d_t + P_{t+1}]$$

$$P_t = \beta E_t [d_{t+1} + P_{t+1}]$$

$$v(\lambda_t) d_t = \beta E_t [\lambda_{t+1} d_t + v(\lambda_{t+1}) \lambda_{t+1} d_t]$$

Cancel & Solve