

Data Assimilation Research Testbed Tutorial

Section 16: Diagnostic Output

Version 1.0: June, 2005

DART Diagnostic Output Categories:

1. State space:

Values of models state vector.

Output using netCDF format.

2. Observation space:

Values of the observations.

DART specific obs_sequence format for now.

3. Regression confidence factor:

Values for state vector / observation pairs.

Output as flat ascii.

4. Program diagnostic output:

Identification for source code version and namelist values.

Error, warning, message output from modules.

State Space Diagnostic Files:

Available in netCDF (common data format)

(<http://my.unidata.ucar.edu/content/software/netcdf/index.html>)

1. Prior state (Prior_Diag.nc): state before assimilation.
2. Posterior state (Posterior_Diag.nc): state after assimilation.
3. Truth (True_State.nc): truth for OSSEs.

Contents of prior and posterior controlled by filter_nml:

1. *output_state_ens_mean* = *.true.*, (include ensemble mean);
2. *output_state_ens_spread* = *.true.*, (include ensemble spread);
3. *num_output_state_members* = 20,
(include this many of the individual ensemble members);
4. *output_interval* = 2, (only output every nth assimilation time);

Output interval for True_State.nc in perfect_model_obs_nml.

Viewing the State Space netCDF files:

1. Standard DART matlab diagnostics:

- a. [plot_bin](#): rank histograms,
- b. [plot_correl](#): correlation $x(t)$ with all other state vars at all times,
- c. [plot_ens_err_spread](#): rms error and spread,
- d. [plot_ens_mean_time_series](#): time series of ens. mean,
- e. [plot_ens_time_series](#): time series all available ensembles,
- f. [plot_phase_space](#): 3D phase space time evolution,
- g. [plot_sawtooth](#): truth, prior and posterior time series,
- h. [plot_total_err](#): total error for different fields,
- i. [plot_var_var_correl](#): $x(t)$ correlation to single variable, all times.

Viewing the State Space netCDF files:

2. ncview: a quick, dirty, but surprisingly useful netCDF viewer
(http://meteora.ucsd.edu:80/~pierce/ncview_home_page.html)
Displays spatial slices, time series,...
3. Many other graphical/analysis programs can read netCDF
(Note that we use udunits metadata convention)

Observation Space netCDF files:

Observation sequence file output by filter has prior, posterior, observed value, (and truth for OSSEs)

Contents of *obs_sequence.final* controlled by filter_nml:

1. `obs_sequence_in_name = "obs_seq.out"`,
Name of input observation sequence file.
2. `obs_sequence_out_name = "obs_seq.final"`,
Name of output final observation sequence.
3. `output_obs_ens_mean = .true.`,
Output the ensemble mean observation estimate.
4. `output_obs_ens_spread = .true.`,
Output the ensemble spread.
5. `num_output_obs_members = 0`,
Output this many individual ensemble estimates.

(See section 18 for viewing obs_sequence files).

Regression confidence factor output:

Controlled by `reg_factor_nml`:

1. `save_reg_diagnostics = .true.`, should file be output?
2. `save_reg_diagnostics = .false.`, name of output file

File size could be (model size) x (number obs.) x (number assim times).
Very big, even for small models.

Normally, modify code in `reg_factor_mod.f90` to control:
Output is at end of `select_regression = 1` code block.
Format?

Plotting tools?