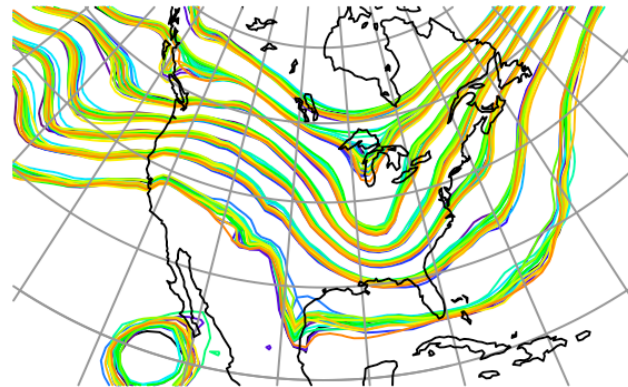


Data
Assimilation
Research
Testbed



DART Tutorial Section 16: Diagnostic Output



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UCAR | Atmospheric Research

DART Diagnostic Output Categories:

- State-Space:
Values of model's state vector and inflation.
Output using netCDF format.
- Observation-Space:
Values of the observations.
DART-specific *obs_sequence* format for now.
- Regression confidence factor:
Values for state vector / observation pairs.
Output as flat ASCII (soon to be netCDF).
- Program diagnostic output:
Identification for source code version and namelist values.
Error, warning, message output from modules.

State-Space Diagnostic Files:

Available in netCDF (a common data format)

<http://www.unidata.ucar.edu/software/netcdf>

DART outputs up to four state space diagnostic files.

These files are selected by listing their names for the *stages_to_write* entry in the `&filter_nml`.

The *stages_to_write* namelist entry and resulting netCDF file names are:

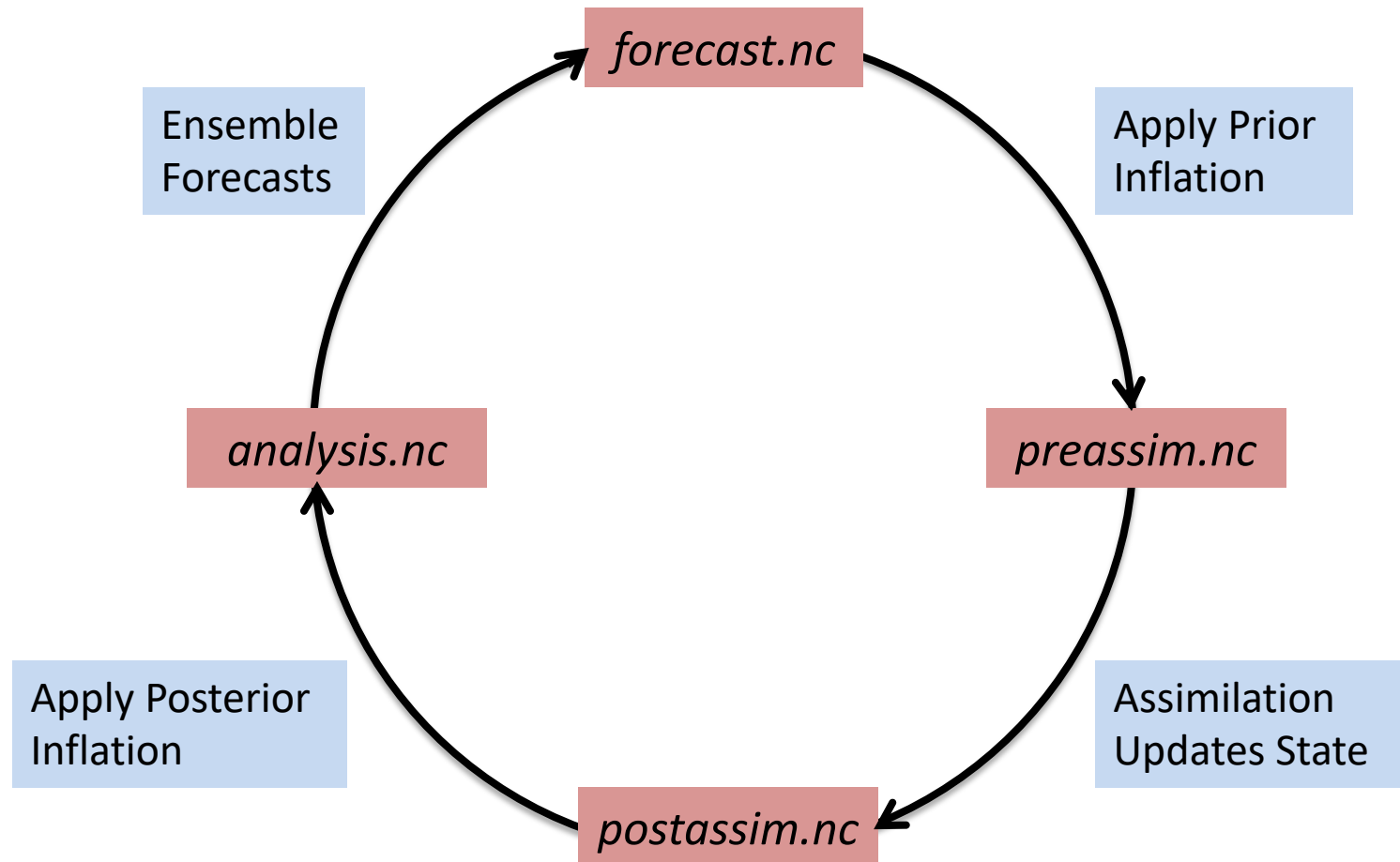
| | |
|-------------|---------------------|
| 'forecast' | <i>forecast.nc</i> |
| 'preassim' | <i>preassim.nc</i> |
| 'postassim' | <i>postassim.nc</i> |
| 'analysis' | <i>analysis.nc</i> |

In addition, *stages_to_write* can also include:

| | | |
|----------|------------------|---|
| 'input' | <i>input.nc</i> | Copy of initial conditions, same format as <i>output.nc</i> |
| 'output' | <i>output.nc</i> | Output file for restart of subsequent filter steps. |

State-Space Diagnostic Files:

Location of each diagnostic file in the filter cycle.



State-Space Diagnostic Files:

Contents of state space diagnostic files are controlled by `&filter_nml`:

```
&filter_nml
...
output_mean           = .true.    (include ensemble mean)
output_sd             = .true.    (include ensemble spread)
num_output_state_members = ##      (include this many individual ensemble members)
output_interval       = N         (only output every  $N^{\text{th}}$  assimilation time)
...
```

Note: `output_interval` for *true_state.nc* is in the `&perfect_model_obs_nml` namelist.

In *input.nml* for *lorenz_96*, make sure all diagnostic files are listed as *stages_to_write*.

Run the filter to generate all files.

Try some Matlab diagnostics.

You can change the diagnostic file for a single plot by typing the file at the prompt, or...

You can change the file for all subsequent plots by setting Matlab variable *diag_file*.

For instance, *diag_file* = 'postassim.nc';

State-Space Diagnostic Files:

Trying out different diagnostic files:

In *input.nml* for *lorenz_96*, the default has been to output the *preassim.nc* and *analysis.nc* diagnostic files.

You could also add '*postassim*' and '*forecast*' to the list in *stages_to_write*.

So far, have only looked at diagnostics for *preassim.nc*

Two ways to change the diagnostic file in Matlab tools like *plot_total_err*:

1). Change for a single plot by entering diagnostic filename at Matlab prompt:

```
>> plot_total_err
Input name of ensemble trajectory file:
<cr> for preassim.nc
analysis.nc
Comparing true_state.nc and
      analysis.nc
```

2). You can change the file for all subsequent plots by setting Matlab variable *diagn_file*.

```
>> diagn_file = 'analysis.nc';
```

Try looking at diagnostics for *analysis.nc*, *forecast.nc*, and *postassim.nc*

Some of these will be the same unless you have both prior and posterior inflation on.

DART State-Space Diagnostic functions

See the DART website section titled: “Configuring Matlab to work with DART”

https://dart.ucar.edu/pages/Getting_Started.html#matlab

ALL the DART Matlab state-space diagnostic functions are in *diagnostics/matlab*

This **must** be in your *matlabpath*.

Only focus on the files that start with *plot_*

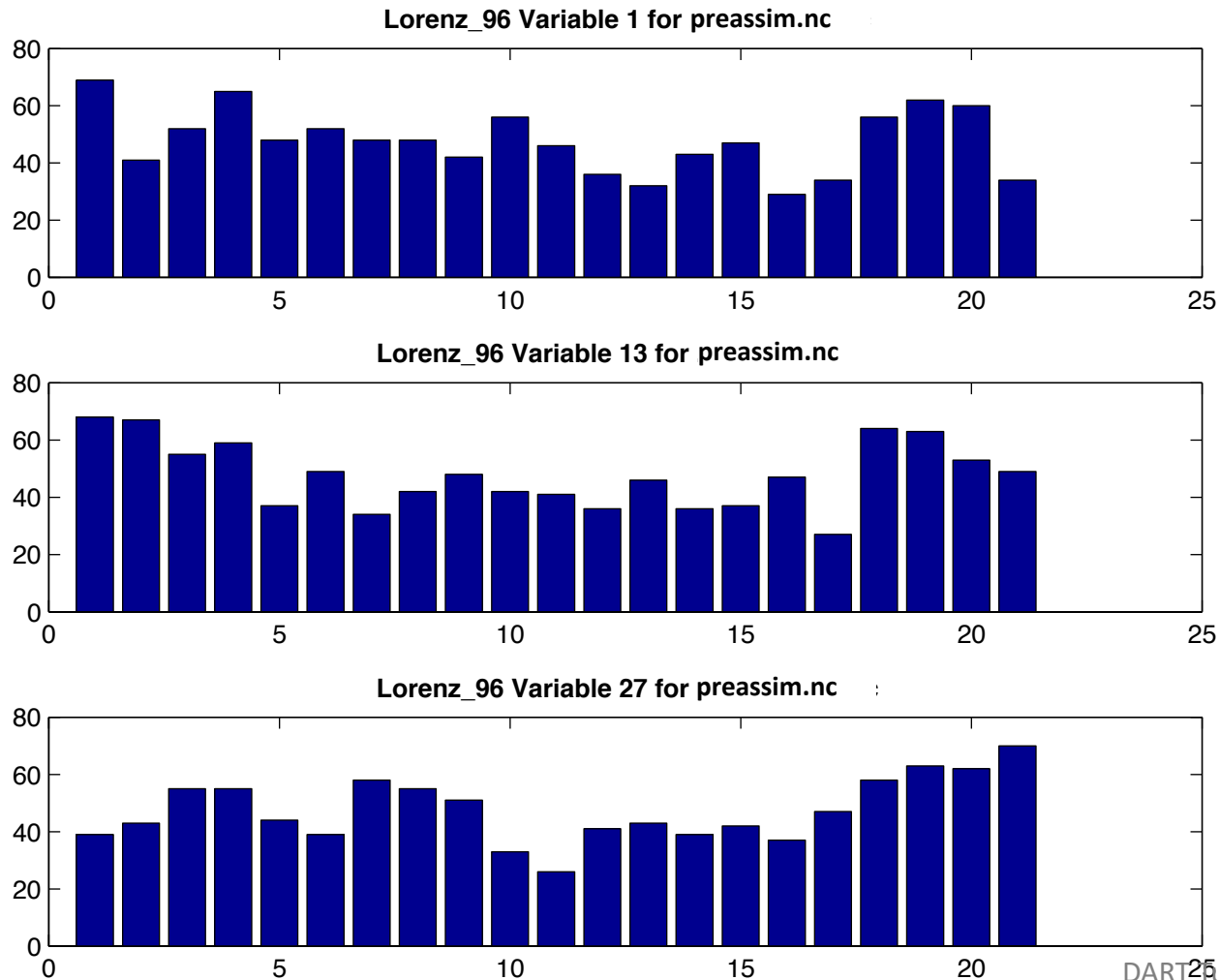
- plot_bins.m
- plot_correl.m
- plot_ens_err_spread.m
- plot_ens_mean_time_series.m
- plot_ens_time_series.m
- plot_phase_space.m
- plot_reg_factor.m
- plot_sawtooth.m
- plot_smoother_err.m
- plot_total_err.m
- plot_var_var_correl.m
- ...

Some, but not all, described here.
All functions have a ‘help’ section
available in the standard Matlab way.

Viewing the State-Space netCDF files:

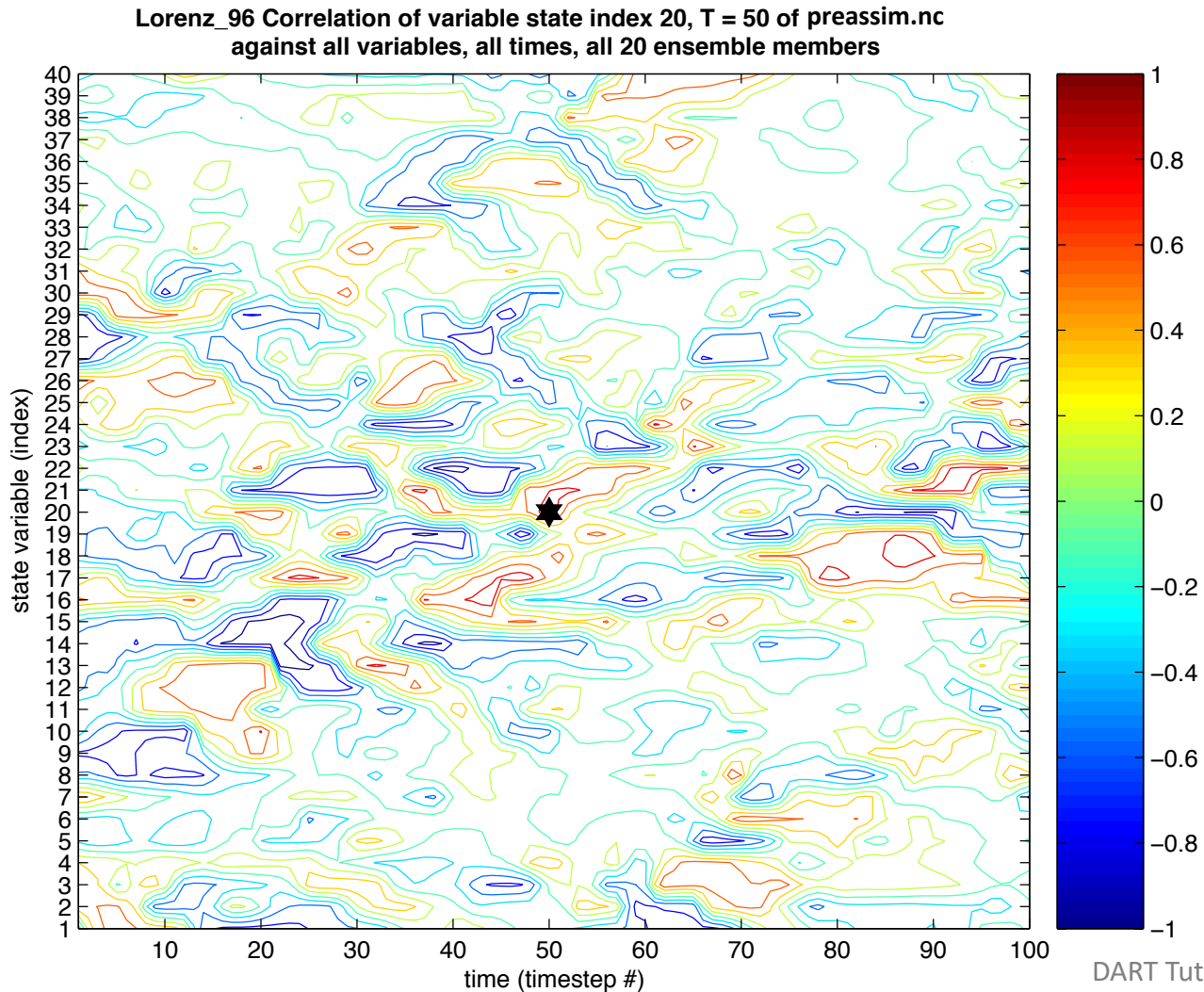
1. Standard DART matlab diagnostics:

a. `plot_bins`: rank histograms,



Viewing the State-Space netCDF files:

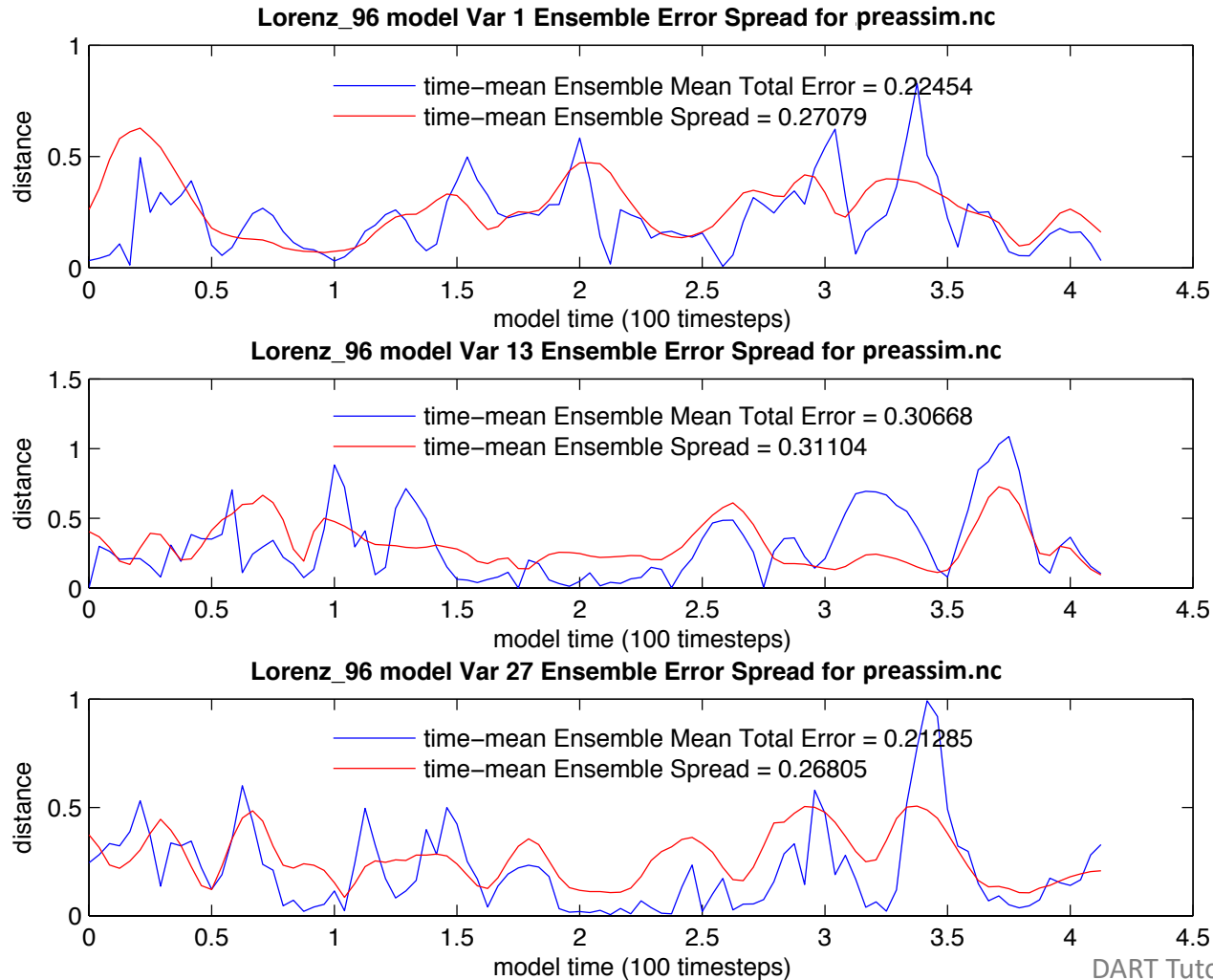
1. Standard DART matlab diagnostics:
 - b. `plot_correl`: correlation $x(t)$ with all other state vars at all times,



Viewing the State-Space netCDF files:

1. Standard DART matlab diagnostics:

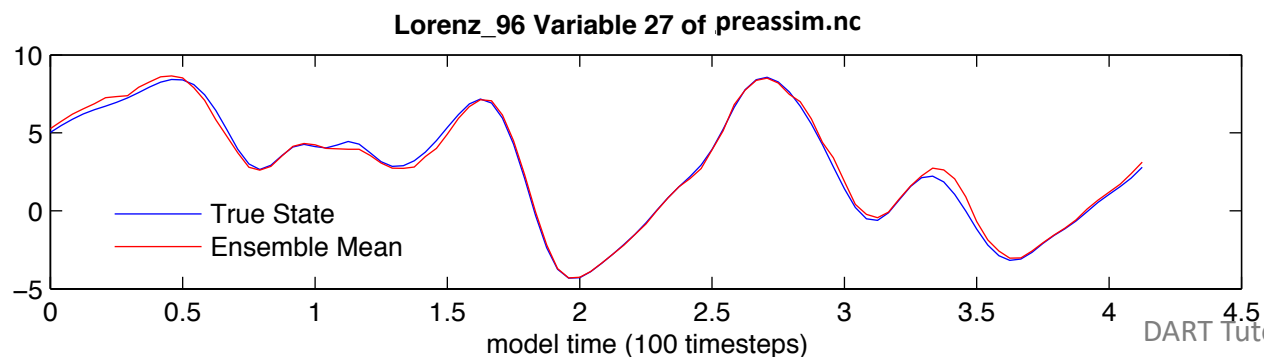
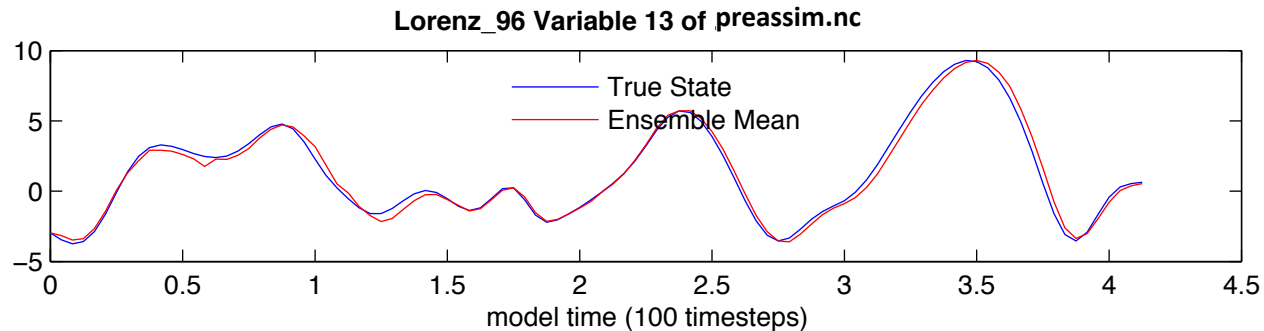
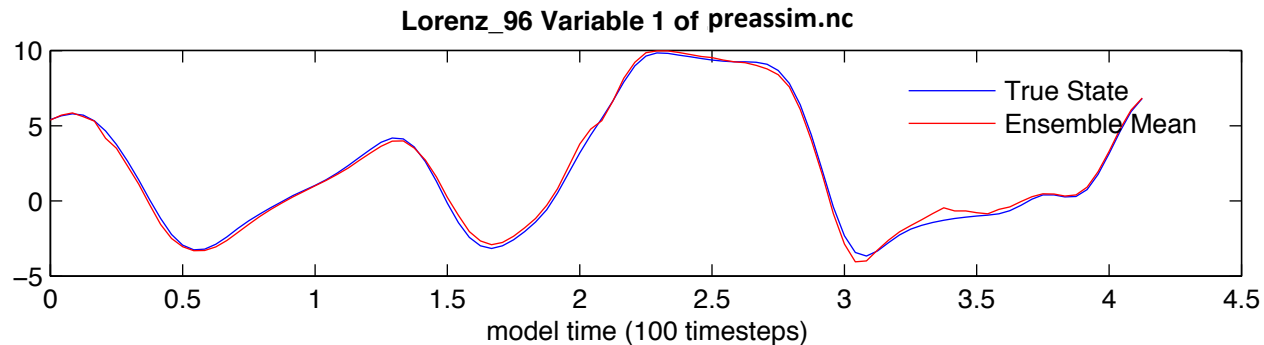
c. `plot_ens_err_spread`: rms error and spread,



Viewing the State-Space netCDF files:

1. Standard DART matlab diagnostics:

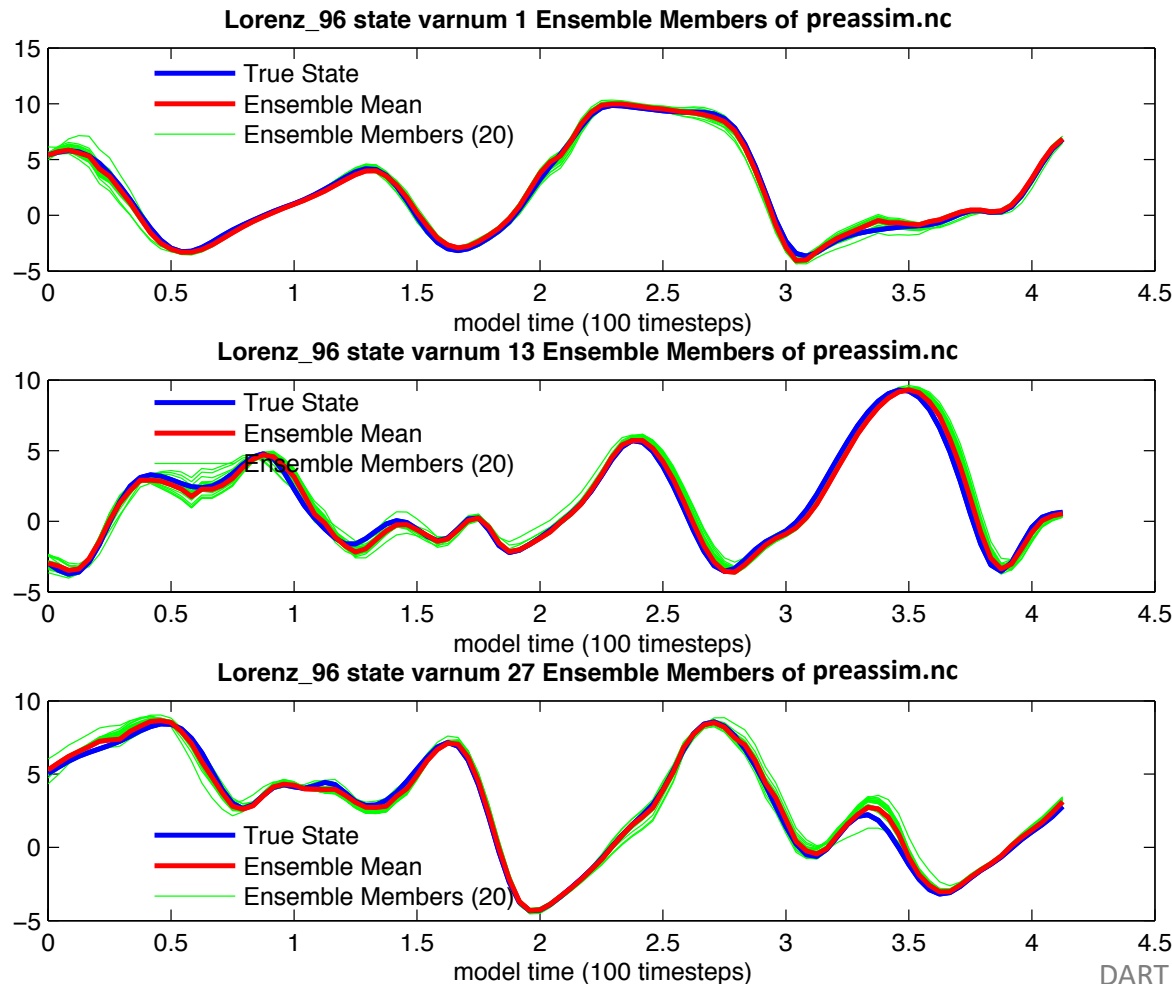
d. `plot_ens_mean_time_series`: just like the name says,



Viewing the State-Space netCDF files:

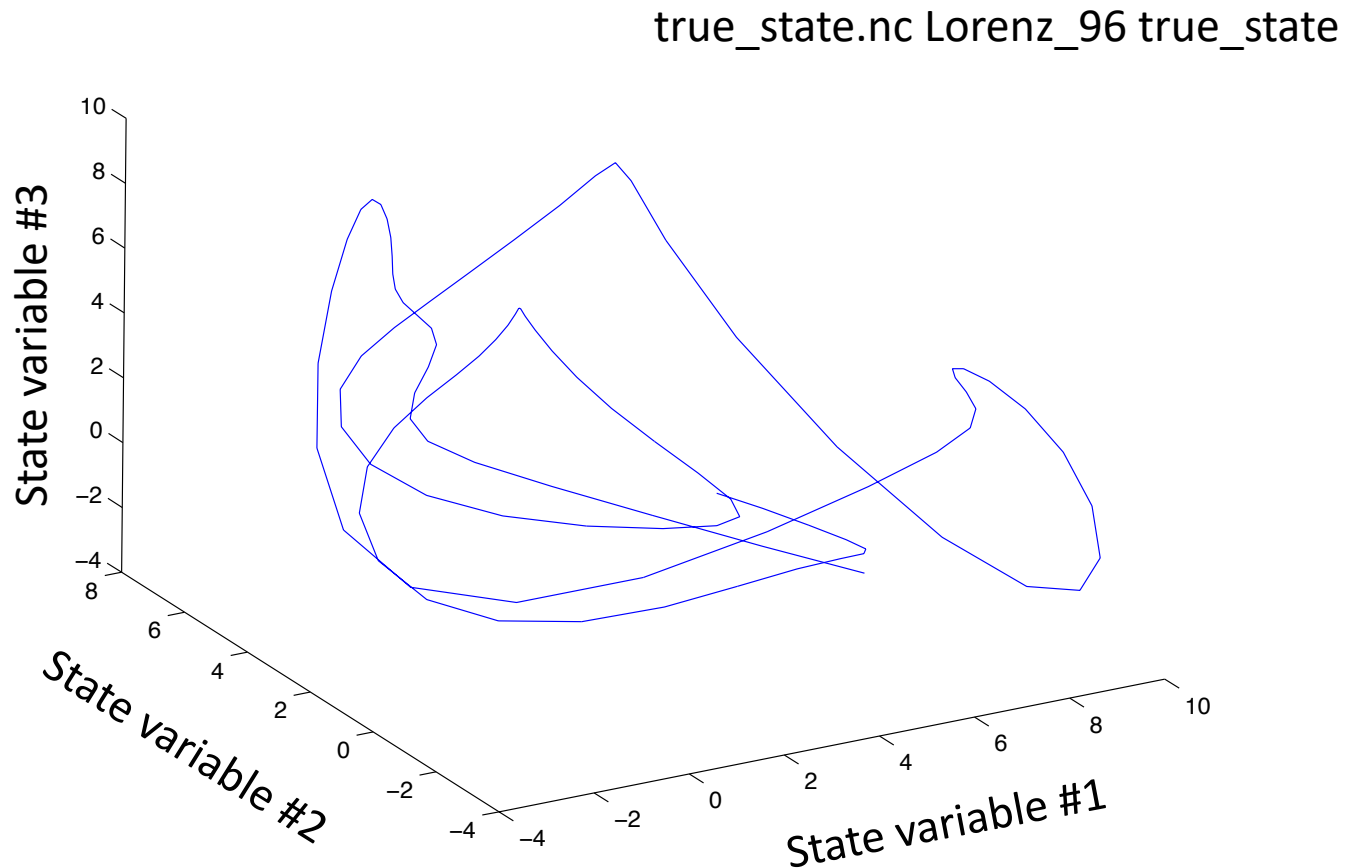
1. Standard DART matlab diagnostics:

- e. `plot_ens_time_series`: plots the ensemble
(as available from `num_output_state_members`),



Viewing the State-Space netCDF files:

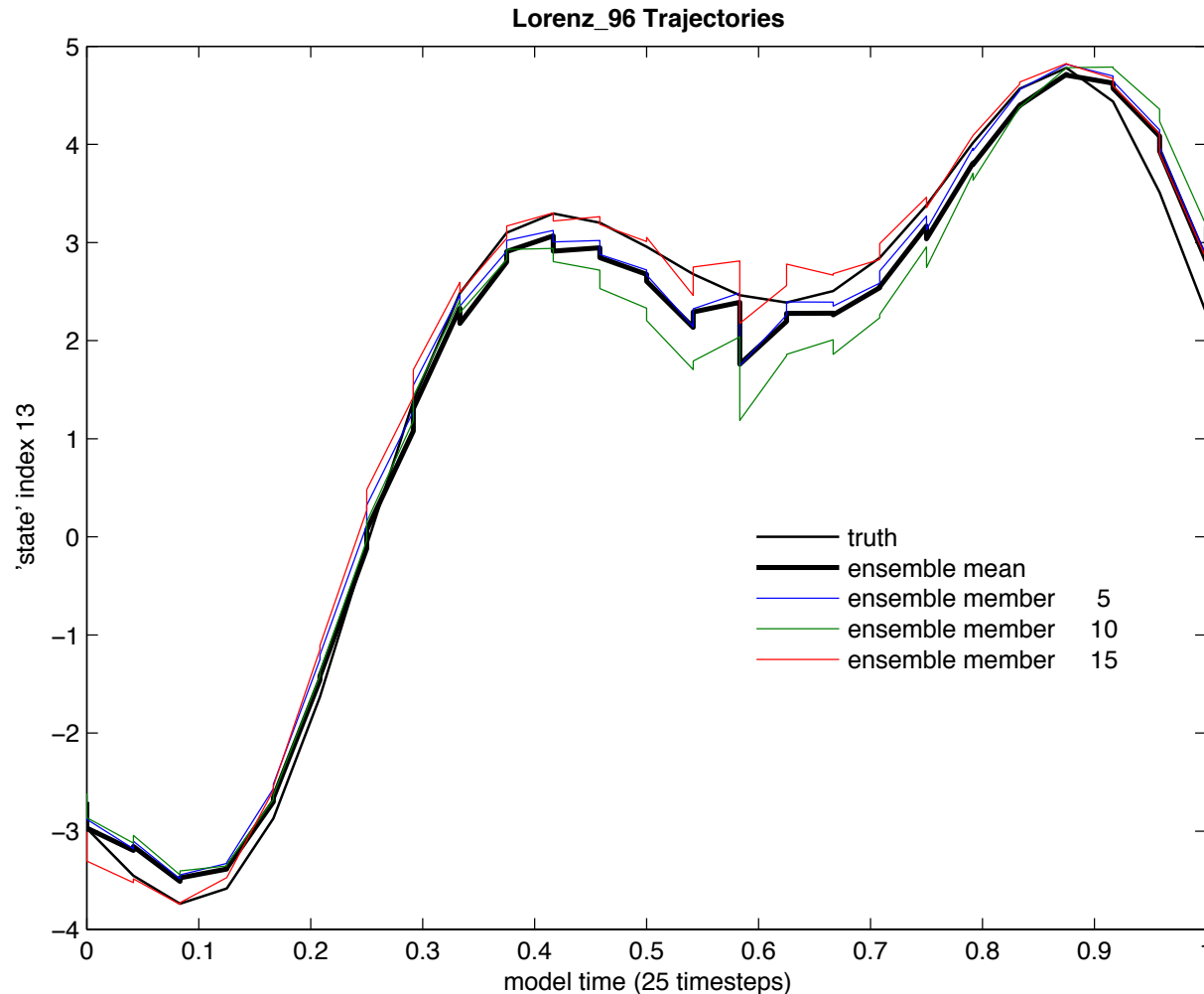
1. Standard DART matlab diagnostics:
 - f. `plot_phase_space`: 3D phase space time evolution.



Viewing the State-Space netCDF files:

1. Standard DART matlab diagnostics:

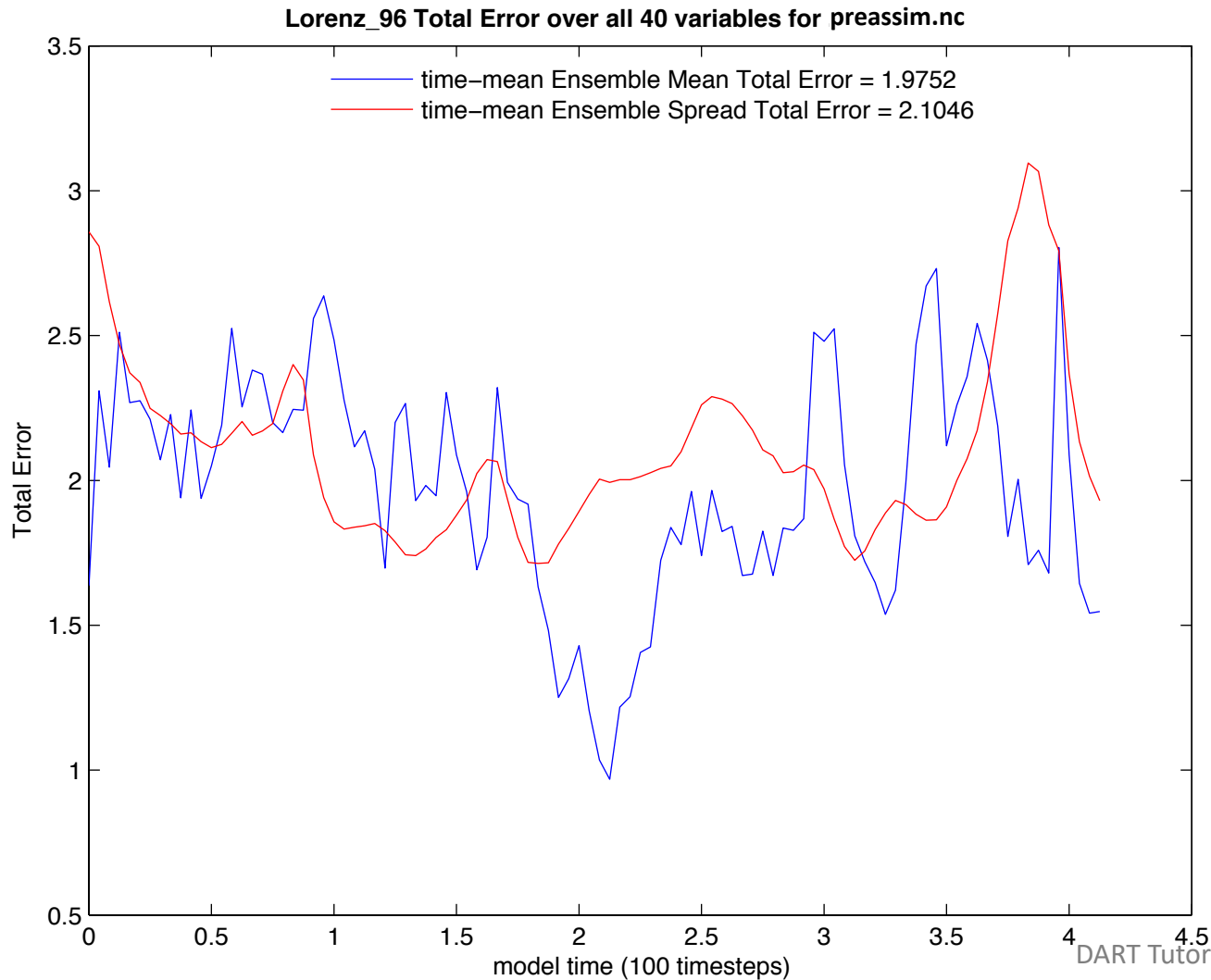
g. `plot_sawtooth`: truth, prior and posterior time series.



Viewing the State-Space netCDF files:

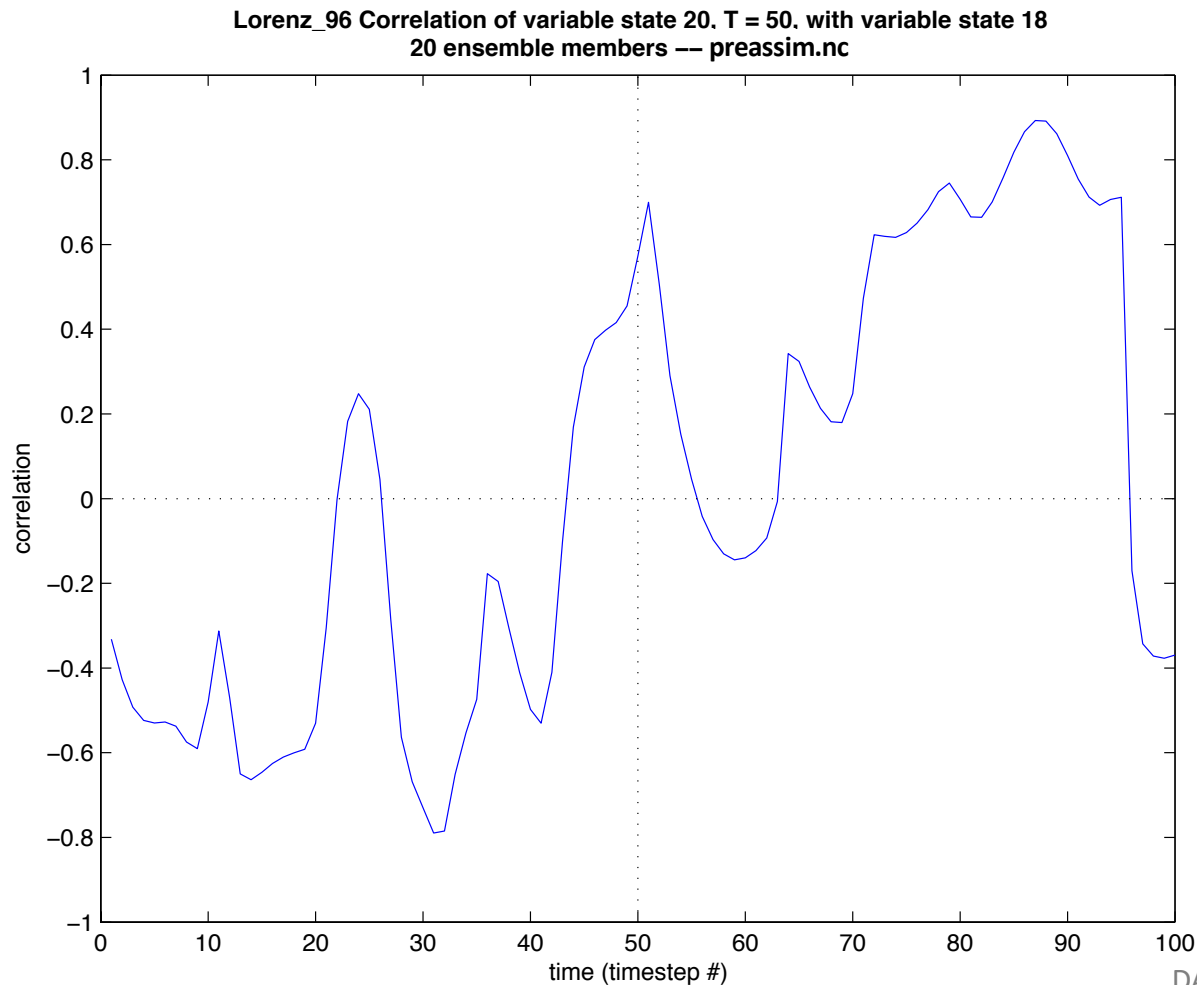
1. Standard DART matlab diagnostics:

h. `plot_total_err`: total error for different fields,



Viewing the State-Space netCDF files:

1. Standard DART matlab diagnostics:
 - i. `plot_var_var_correl`: $x(t)$ correlation to single variable, all times.

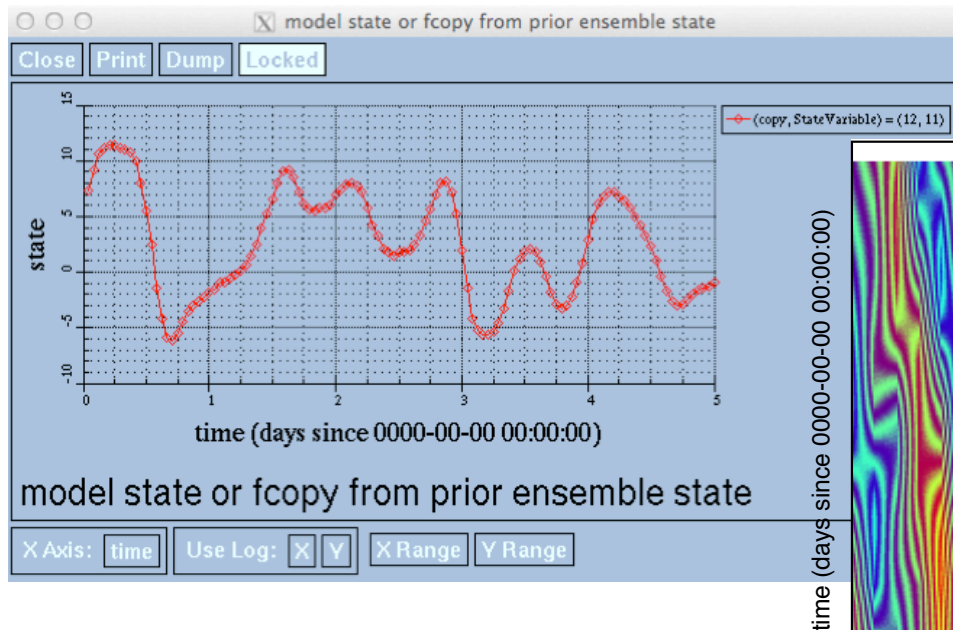


Viewing the State-Space netCDF files:

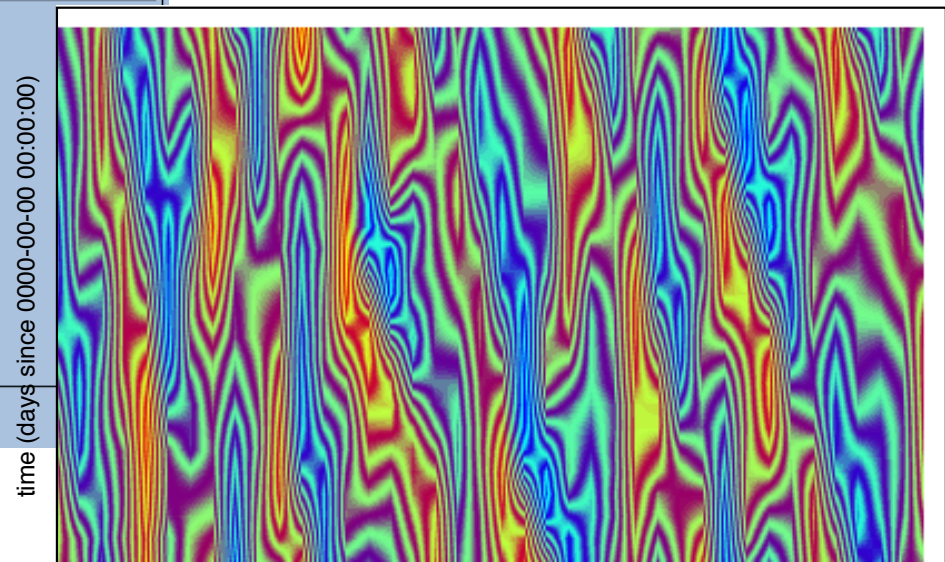
2. ncview: a quick and surprisingly useful netCDF viewer.

http://meteora.ucsd.edu/~pierce/ncview_home_page.html

Displays spatial slices, animations, time series ...



model state or fcopy



jla Sun Jun 5 13:41:44 2005

prior ensemble state

Range of model state or fcopy: -6.18328 to 11.6954 (null)

Range of State Variable ID: 1 to 40 indexical

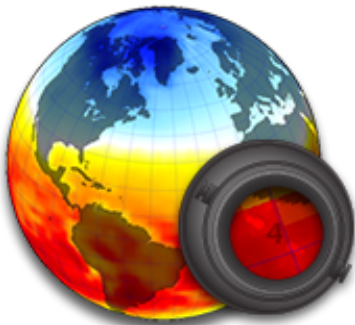
Range of time: 0 to 1 days since 0000-00-00 00:00:00

Current ensemble member or copy: 1 nondimensional

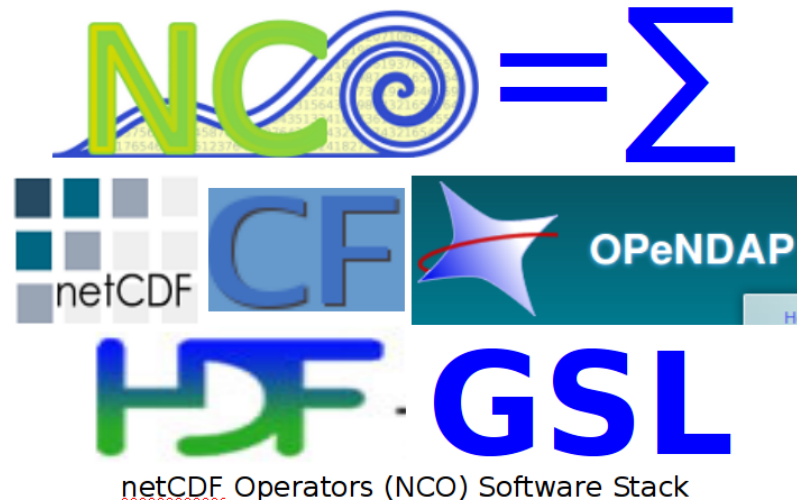
Frame 1 in File preassim.nc

Viewing the State-Space netCDF files:

3. Many other graphical/analysis programs can read netCDF.
(Note that we use *udunits* metadata convention.)
4. netCDF Operator (NCO) tools allow operations on netCDF files:
(<http://nco.sourceforge.net>)
Selecting hyperslices of fields,
Differencing netCDF file,
Averaging, etc.



NASA GISS: Panoply



Inflation Diagnostics in State-Space netCDF files:

The subroutine-callable models ***usually*** have a single netCDF file (*filter_output.nc*) that contains the the entire ensemble as well as the inflation values. The variables with the inflation have names like:

- *state_priorinf_mean*,
- *state_priorinf_sd*,
- *state_postinf_mean*, and
- *state_postinf_sd*

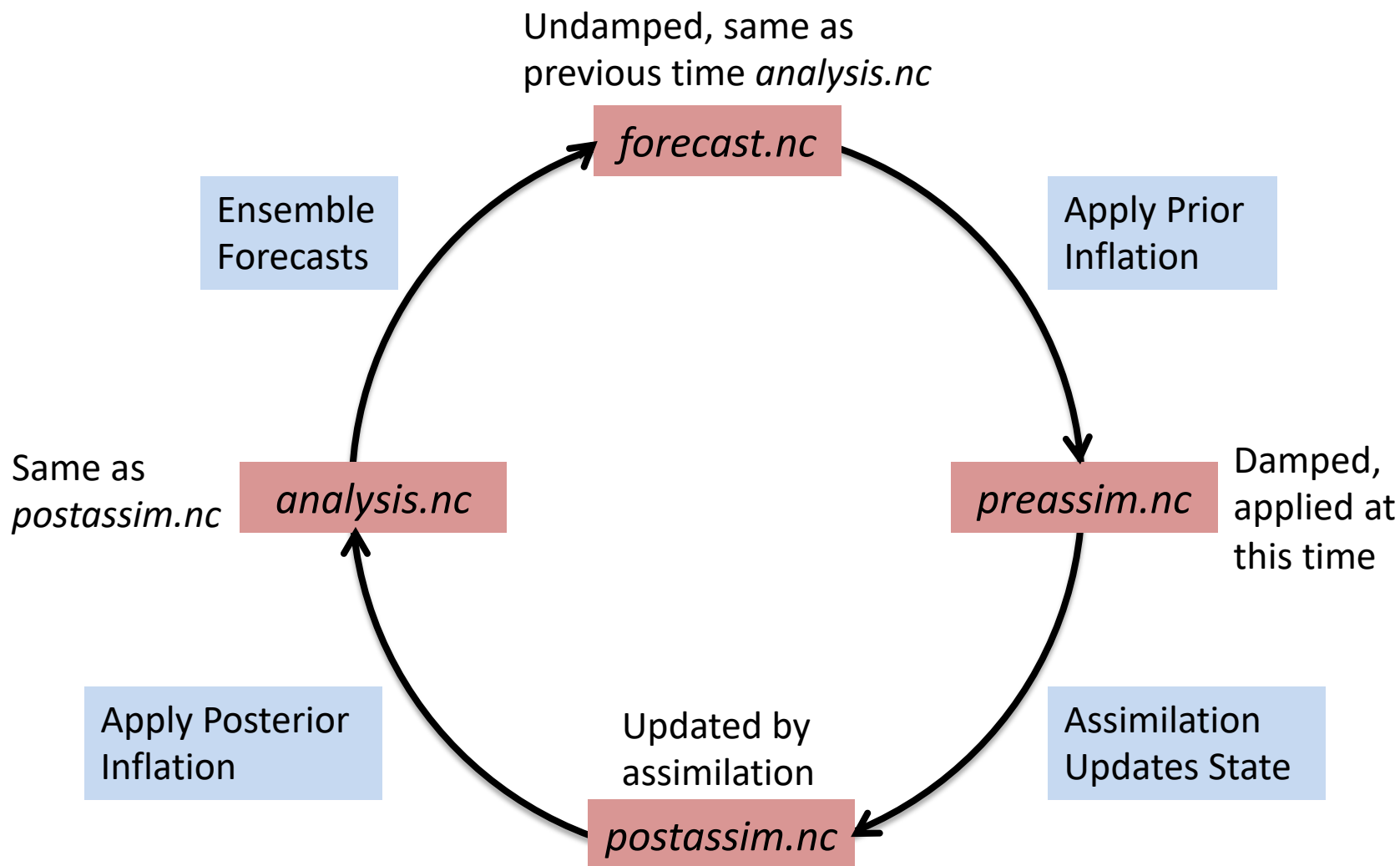
The state-space inflation values for other models are stored in netCDF files:

- *input_priorinf_mean.nc*
- *input_priorinf_sd.nc*
- *input_postinf_mean.nc*
- *input_postinf_sd.nc*

with variable names that are identical to the variables in the DART state. These files only have a single timestep in them and must be managed during a cycling experiment that uses adaptive inflation.

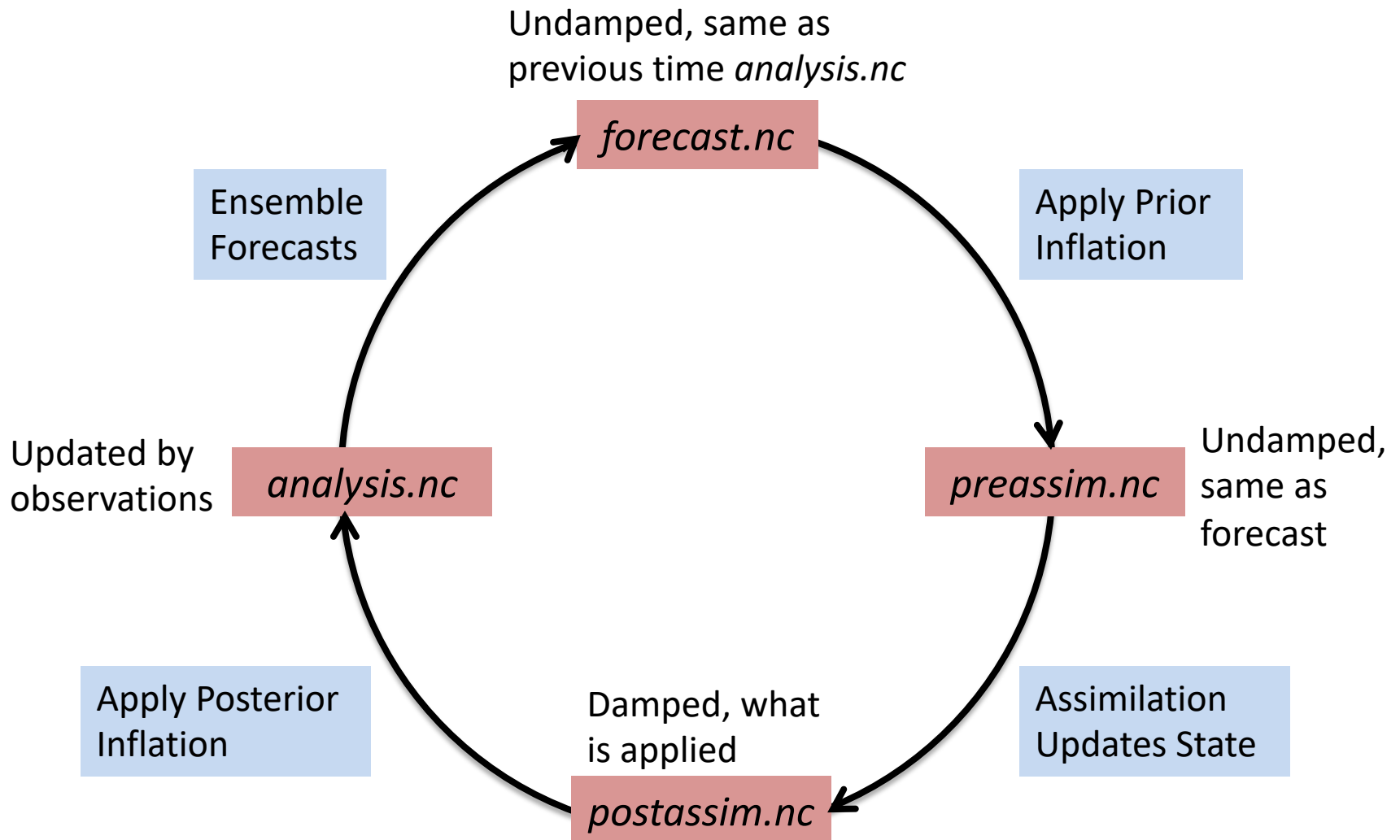
Prior Inflation State-Space Diagnostic Files:

Contents of prior inflation fields for each diagnostic file in the filter cycle.



Posterior Inflation State-Space Diagnostic Files:

Contents of posterior inflation fields for each diagnostic file in the filter cycle.



Observation-space files:

Quick recap of 'standard' observation sequence file names
(all names are actually specified in namelists):

- *obs_seq.in* input to ***perfect_model_obs***
- *obs_seq.out* **output** from ***perfect_model_obs***, also **input** to ***filter***
- *obs_seq.final* output from ***filter***

Observation sequence files output by ***filter*** have prior, posterior, observed value (and truth for OSSEs). For an overview, check out the DART section:

<https://dart.ucar.edu/pages/Observations.html>

Contents of *obs_seq.final* controlled by `&filter_nml`:

`&filter_nml`

| | | |
|-------------------------------------|--------------------------------|---|
| <code>obs_sequence_in_name</code> | <code>= 'obs_seq.out'</code> | Name of input observation sequence file. |
| <code>obs_sequence_out_name</code> | <code>= 'obs_seq.final'</code> | Name of output observation sequence file. |
| <code>num_output_obs_members</code> | <code>= ##</code> | Output this many individual ensemble estimates. |
| <code>...</code> | | |

Observation-space diagnostics:

The observation sequence file is not in a particularly user-friendly format.

To aid in the evaluation and interpretation, a program named ***obs_diag*** must be run to produce a netCDF file with results that can be plotted in a manner of your choosing. DART has Matlab functions/scripts that create high-quality graphics.

See tutorial section 18 for full coverage of viewing, diagnosing obs sequences.

Here are a few of the Matlab functions available in *diagnostics/matlab*

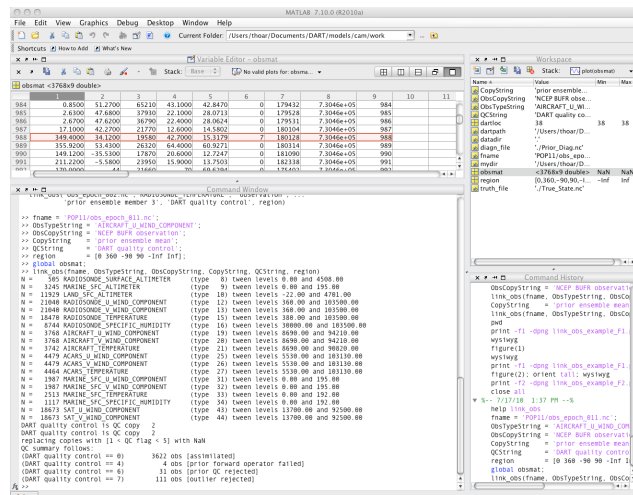
- `plot_rank_histogram.m`
- `plot_evolution.m`
- `plot_rmse_xxx_evolution.m`
- `two_experiments_evolution.m` (works with more than two, actually)
- `plot_profile.m`
- `plot_bias_xxx_profile.m`
- `plot_rmse_xxx_profile.m`
- `two_experiments_profile.m` (works with more than two, actually)

Observation-space diagnostics:

SOME of the information in the observation sequence files can be converted to netCDF and easily plotted. A program named ***obs_seq_to_netcdf*** must be run to produce the netCDF.

Here are a few of the Matlab functions available in *diagnostics/matlab*.

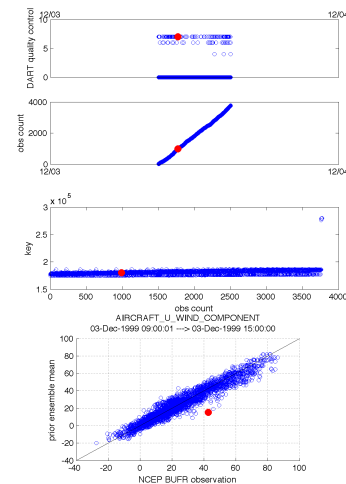
- link_obs.m
- plot_obs_netcdf.m
- plot_obs_netcdf_diffs.m



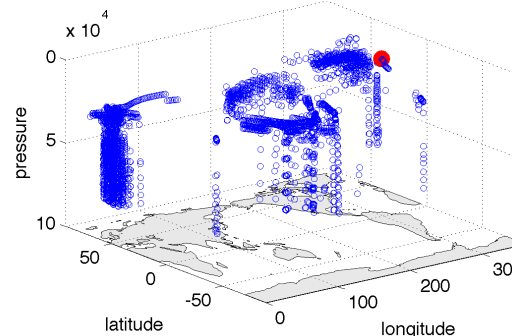
```
link_obs.m
% link_obs.m: Link observation sequence files to netCDF
% Usage: link_obs('obs_seq', 'netcdf_dir', 'var_name', 'qc_level')
% Example: link_obs('obs_seq', 'netcdf_dir', 'AIRCRAFT_U_WIND_COMPONENT', 4)

% Define variables
obs_seq_dir = 'obs_seq';
netcdf_dir = 'netcdf_dir';
var_name = 'AIRCRAFT_U_WIND_COMPONENT';
qc_level = 4;

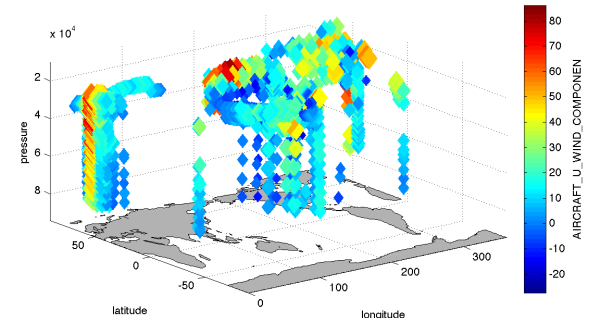
% Link observation sequence files to netCDF
link_obs(obs_seq_dir, netcdf_dir, var_name, qc_level);
```



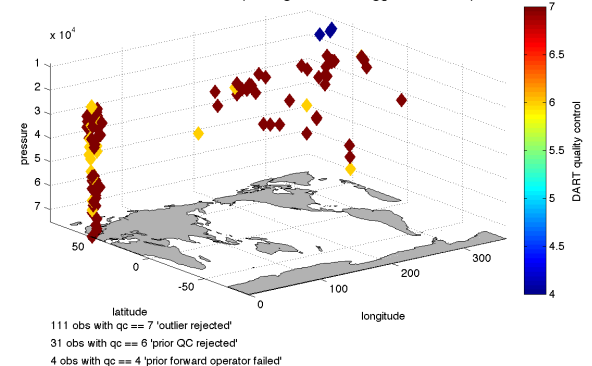
AIRCRAFT_U_WIND_COMPONENT
03-Dec-1999 09:00:01 ---> 03-Dec-1999 15:00:00



AIRCRAFT_U_WIND_COMPONENT level (10040.00 - 94210.00)
03-Dec-1999 09:00:01 - 03-Dec-1999 15:00:00
NCEP BUFR observation (3622 locations)



AIRCRAFT_U_WIND_COMPONENT level (8690.00 - 75270.00)
03-Dec-1999 09:00:01 - 03-Dec-1999 15:00:00
NCEP BUFR observation (3622 'good', 146 'flagged' -- 3.87 %)



111 obs with qc == 7 'outlier rejected'
31 obs with qc == 6 'prior QC rejected'
4 obs with qc == 4 'prior forward operator failed'

Regression confidence factor output:

Reminder: `reg_factor` α introduced in Tutorial Section 13 – when running the group filter (with more than 1 group!).

Controlled by `®_factor_nml`:

| | |
|---|------------------------|
| <code>&reg_factor_nml</code> | |
| <code>save_reg_diagnostics = .true.</code> | Should file be output? |
| <code>reg_diagnostics_file = 'reg_diagnostics'</code> | Name of output file. |
| <code>...</code> | |

File size could be (model size) X (number of obs.) X (number of assim times).

Very big, even for small models (only first 4 obs output default).

Normally, modify code in *reg_factor_mod.f90* to control:

Output is at end of `select_regression = 1` code block.

Format is ASCII:

time in days, time in seconds, `obs_index`, `state_index`, α

Plot with Matlab *plot_reg_factor*.

File *dart_log.out*

All DART executables ***append*** to this file!

Contains:

- registration information
- Program start time,
- version of code for each module used
- Namelist values for each module*
- Names of output files,
- Diagnostic output for modules (through `error_handler()`),
- Warnings and fatal errors from DART code.

Fair Warning: This file is ***not*** cleared by DART. Can get very longggggggg ...
You should feel free to delete/rename it before starting the next experiment.

*may be in a separate file, depending on `&utilities_nml` setting

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4. How should observations of a state variable impact an unobserved state variable?
Multivariate assimilation.
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6. Other Updates for An Observed Variable
7. Some Additional Low-Order Models
8. Dealing with Sampling Error
9. More on Dealing with Error; Inflation
10. Regression and Nonlinear Effects
11. Creating DART Executables
12. Adaptive Inflation
13. Hierarchical Group Filters and Localization
14. Quality Control
15. DART Experiments: Control and Design
16. Diagnostic Output
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18. **Lost in Phase Space: The Challenge of Not Knowing the Truth**
19. **DART-Compliant Models and Making Models Compliant**
20. **Model Parameter Estimation**
21. **Observation Types and Observing System Design**
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24. Fixed lag smoother (not available)
25. **A simple 1D advection model: Tracer Data Assimilation**