

**ENSURING MACHINES ARE WELL BEHAVED**



# TODAY'S CLASS

## GOALS

1. Constraining Models and Providing Guarantees
2. Confidence Intervals
3. Approaches to find models that guarantee:
  - Bias and Fairness (balancing accuracy/outcomes for protected groups)
  - Performance (overall accuracy/performance/money)
  - Minimize adverse outcomes



# QUIZ



# THREE LAWS OF ROBOTICS

## GOALS

1. A robot may not injure a human being or, through inaction, allow a human being to come to harm.
2. A robot must obey the orders given it by human beings except where such orders would conflict with the First Law.
3. A robot must protect its own existence as long as such protection does not conflict with the First or Second Law.



# THREE LAWS OF ROBOTICS

## GOALS

1. A robot may not injure a human being or, through inaction, allow a human being to come to harm.
2. A robot must obey the orders given it, provided that such orders would not conflict with the First Law.
3. A robot must protect its own existence, provided that such protection does not conflict with the First or Second Law.

What if we cannot guarantee these laws?



# ENSURING INTELLIGENT MACHINES ARE WELL-BEHAVED

Overview and guide to one approach on constraining model/agent behavior with gaurantees.

<https://aisafety.cs.umass.edu/>

Paper in Science: <https://www.science.org/doi/10.1126/science.aag3311>

Science papers are readable and understandable by general audiance.



# ORIGINAL OBJECTIVE

FINDING AN APPROXIMATION

Constraining the error:

$$\forall x \in \mathcal{X}, |f(x) - f_*(x)| \leq \epsilon$$



# AVERAGE ERROR

FINDING AN APPROXIMATION

Objective function:

$$l(\theta) = \mathbf{E} \left[ (f(X, \theta) - Y)^2 \right]$$



# AVERAGE ERROR

## FINDING AN APPROXIMATION

Objective function:

$$l(\theta) = \mathbf{E} \left[ (f(X, \theta) - Y)^2 \right]$$

Can we guarantee

$$l(\theta) \leq \epsilon$$



# EVALUATING $l(\theta)$

Evaluation of  $l(\theta)$

$$\hat{\theta}^* \leftarrow \arg \min_{\theta} l_{D_{train}}(\theta)$$

$$l(\theta) \approx l_{D_{test}}(\hat{\theta}^*)$$



# EVALUATING $l(\theta)$

Evaluation of  $l(\theta)$

$$\hat{\theta}^* \leftarrow \arg \min_{\theta} l_{D_{train}}(\theta)$$

$$l(\theta) \approx l_{D_{test}}(\hat{\theta}^*)$$

Need infinite data to have an accurate evaluation

$$\lim_{|D_{test}| \rightarrow \infty} |l_{D_{test}}(\theta) - l(\theta)| \rightarrow 0$$



# CONSTRAINING LOSS

If  $l_{D_{test}}(\hat{\theta}^*) < \epsilon$  is  $l(\hat{\theta}^*) < \epsilon$ ?



# CONSTRAINING LOSS

If  $l_{D_{test}}(\hat{\theta}^*) < \epsilon$  is  $l(\hat{\theta}^*) < \epsilon$ ?

Not necessarily:

Due to noise  $l_{D_{test}}(\hat{\theta}^*) < \epsilon$  , but  $l(\hat{\theta}^*) > \epsilon$  or vice versa

We also may not be able to find a  $\hat{\theta}^*$  such that  $l(\hat{\theta}^*) < \epsilon$



# UPPER BOUNDING LOSS

Idea: Find an upper-bound estimate  $l_{upper}(\theta)$  on  $l(\theta)$

$$l(\theta) \leq l_{upper}(\theta)$$

If  $l_{upper}(\theta) < \epsilon$  then  $l(\theta) < \epsilon$



# UPPER BOUNDING LOSS

$n$  number of samples in  $D_{test}$

Find a function  $C : \mathbb{N} \rightarrow \mathbb{R}$  such that

$$\forall \theta, l(\theta) \leq l_{D_{test}}(\theta) + C(n)$$



# UPPER BOUNDING LOSS

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$$\forall \theta, l(\theta) \leq l_{D_{test}}(\theta) + C(n)$$

$C(n)$  provides a worst-case upper bound on the loss function

Worst-case:

- Any model parameters  $\theta$
- Any data  $D_{test}$



# UPPER BOUNDING LOSS

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Worst-case:

- Any model parameters  $\theta$
- Any data  $D_{test}$

Problems with this approach?



# UPPER BOUNDING LOSS

Worst-case bounds are usually very conservative:

$$l(\theta) \ll l_{D_{test}}(\theta) + C(n) \text{ — upper bound is much larger than } l(\theta)$$

We will often say we cannot guarantee  $\theta$  satisfies  $l(\theta) < \epsilon$  even if it does

Reason:

$C(n)$  has to work for both good and bad  $\theta$

Has to work for any data distribution  $D_{test}$



# PROBABILISTIC CONSTRAINTS

Idea: Guarantee with a high probability that a model satisfies the constraint.

With 99% confidence, we know that  $\hat{\theta}^*$  satisfies  $l(\hat{\theta}^*) \leq \epsilon$

We trade certainty in the upper bound for a better estimate.

Note: We cannot guarantee that we will find a  $\hat{\theta}^*$  that satisfies this guarantee.



# PROBABILISTIC CONSTRAINTS

Upper confidence bound:  $l_{upper}: \Theta \times \mathbb{D} \rightarrow \mathbb{R}$

$\alpha \in (0,1)$  — confidence level

$$\Pr \left( l(\theta) \leq l_{upper}(\theta, D_{test}) \right) \geq 1 - \alpha$$

$l_{upper}$  can adapt to  $\theta$  and  $D_{test}$

$\alpha$  specifies the failure rate of the limit

$\alpha = 0.05$  means we have 95% confidence

$l_{upper}$  is a confidence interval



# PROBLEM SETTING

ACCOUNTING FOR UNCERTIANITY

$X$  Random Variable from some unknown distribution  $F_X$

$\theta$  — parameter we care about, e.g.,  $\theta = \mathbf{E}[X]$

$D_n = X_1, X_2, \dots, X_n$  sample of  $n$  draws of  $X$

$$\bar{X} = \frac{1}{n} \sum_{i=1}^n X_i$$

Is  $\bar{X} \geq \theta$  or  $\bar{X} \leq \theta$ ?



# CONFIDENCE INTERVALS

WHAT ARE THEY?

$l: \mathbb{R}^n \rightarrow \mathbb{R}$  — lower confidence bound function

$u: \mathbb{R}^n \rightarrow \mathbb{R}$  — upper confidence bound function

$\alpha \in (0,1)$  — confidence level

$$\Pr \left( \theta \in \left[ l(D_n), u(D_n) \right] \right) \geq 1 - \alpha$$

One-sided Intervals

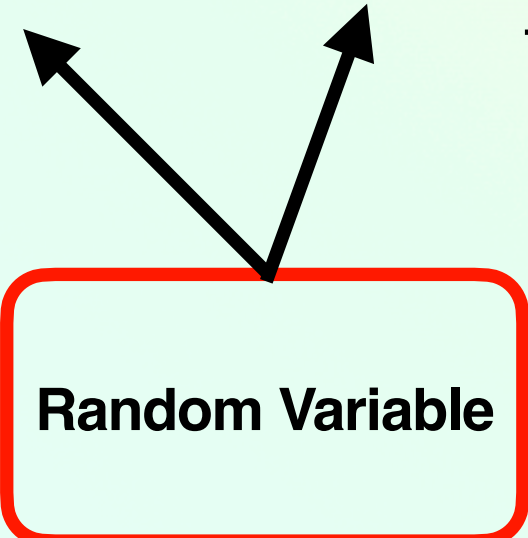
$$\Pr \left( \theta \leq u(D_n) \right) \geq 1 - \alpha$$

$$\Pr \left( \theta \geq l(D_n) \right) \geq 1 - \alpha$$



# CONFIDENCE INTERVALS

WHAT THEY ARE NOT

$$\Pr \left( \theta \in \left[ l(D_n), u(D_n) \right] \right) \geq 1 - \alpha$$


Random Variable

Not a statement that  $\theta$  falls in between two values

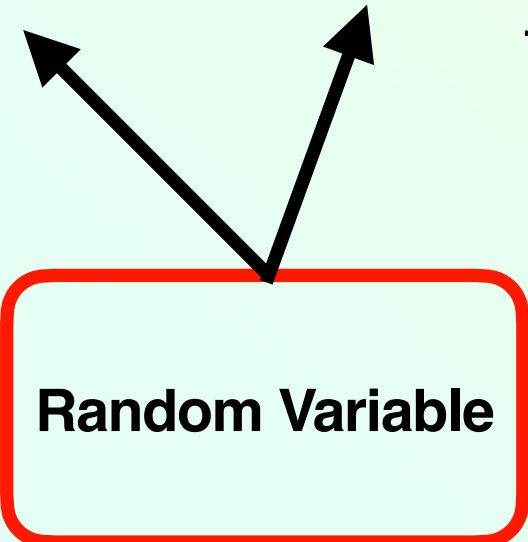
$$\Pr \left( \theta \in [0.7, 0.8] \right) \geq 1 - \alpha$$

No random variables



# CONFIDENCE INTERVALS

## WHAT THEY ARE

$$\Pr \left( \theta \in \left[ l(D_n), u(D_n) \right] \right) \geq 1 - \alpha$$


A red rectangular box with rounded corners contains the text "Random Variable". Two black arrows originate from the top corners of this box and point upwards towards the  $D_n$  terms in the confidence interval formula  $\left[ l(D_n), u(D_n) \right]$  in the equation above.

The probability that values constructed from the random sample will contain the parameter

For at least  $100 \times (1 - \alpha) \%$  of samples of  $D_n$ ,  $\theta \in \left[ l(D_n), u(D_n) \right]$



# CONFIDENCE INTERVALS

## HOW WE USE THEM

Compare the parameter to a constant, e.g., are heads more likely than tails?

$$X \in \{0,1\}, p = \Pr(X = 1)$$

$$\Pr\left(p \geq l(D_n)\right) \geq 1 - \alpha$$

If  $l(D_n) > 0.5$  then with confidence  $1 - \alpha$ , heads are more likely than tails



# CONFIDENCE INTERVALS

## HOW WE USE THEM

Comparing means of  $X$  and  $Y$

$$\Pr \left( \mathbf{E}[X] \geq l(D_n^X) \right) \geq 1 - \frac{\alpha}{2}$$

$$\Pr \left( \mathbf{E}[Y] \leq u(D_n^Y) \right) \geq 1 - \frac{\alpha}{2}$$

If  $l(D_n^X) > u(D_n^Y)$ , then with confidence  $1 - \alpha$ ,  $\mathbf{E}[X] > \mathbf{E}[Y]$



# CONFIDENCE INTERVALS

## HOW WE USE THEM

Comparing means of  $X$  and  $Y$

$$\Pr \left( \mathbf{E}[X] \geq l(D_n^X) \right) \geq 1 - \frac{\alpha}{2}$$

Reduce the failure rate so that both  
hold with the target rate  $\alpha$

$$\Pr \left( \mathbf{E}[Y] \leq u(D_n^Y) \right) \geq 1 - \frac{\alpha}{2}$$

If  $l(D_n^X) > u(D_n^Y)$ , then with confidence  $1 - \alpha$ ,  $\mathbf{E}[X] > \mathbf{E}[Y]$



# BOOLES INEQUALITY

CORRECTING FOR MULTIPLE COMPARISONS AND COMBINING INTERVALS

Events  $A_1, A_2, A_3, \dots$

$$\Pr \left( \bigcup_{i=1}^{\infty} A_i \right) \leq \sum_{i=1}^{\infty} \Pr (A_i)$$

[https://en.wikipedia.org/wiki/Boole%27s\\_inequality](https://en.wikipedia.org/wiki/Boole%27s_inequality)



# BOOLES INEQUALITY

CORRECTING FOR MULTIPLE COMPARISONS AND COMBINING INTERVALS

Let  $A_i$  be the event that a confidence interval with confidence level  $\alpha_i$  fails.

$$\Pr \left( \bigcup_{i=1}^k A_i \right) \leq \sum_{i=1}^k \Pr (A_i) = \sum_{i=1}^k \alpha_i$$

The probability that no confidence interval fails

$$1 - \Pr \left( \bigcup_{i=1}^k A_i \right) \geq 1 - \sum_{i=1}^k \alpha_i$$

$\alpha_i = \frac{1}{k}$  works, but we can distribute the uncertainty any way we want



# TWO-SIDED INTERVAL

TWO ONE-SIDED INTERVALS

If  $\Pr \left( \theta \leq u \left( D_n \right) \right) \geq 1 - \alpha/2$ , and  $\Pr \left( \theta \geq l \left( D_n \right) \right) \geq 1 - \alpha/2$ , then

$$\Pr \left( \theta \in \left[ l \left( D_n \right), u \left( D_n \right) \right] \right) \geq 1 - \alpha$$



# CI FOR THE MEAN

## T-TEST

Sample mean:  $\bar{X} = \frac{1}{n} \sum_{i=1}^n X_i$

Sample variance:  $\hat{\sigma}^2 = \frac{1}{n-1} \sum_{i=1}^n (X_i - \bar{X})^2$

If  $X$  is normally distributed:

$$\Pr \left( \mathbf{E}[X] \in \left[ \bar{X} + t_{n-1, \alpha/2} \frac{\hat{\sigma}}{\sqrt{n}}, \bar{X} + t_{n-1, 1-\alpha/2} \frac{\hat{\sigma}}{\sqrt{n}} \right] \right) = 1 - \alpha$$

$t_{v, \alpha}$  is the  $\alpha$  quantile of Student's t-distribution with  $n - 1$  degrees of freedom

$T = \frac{\bar{X} - \mathbf{E}[X]}{\hat{\sigma}/\sqrt{n}}$  random variable described by Student's t-distribution



# CI FOR THE MEAN

## T-TEST

### Central Limit Theorem:

For a large number of i.i.d. random variables,  $X_1, X_2, \dots, X_n$ , with finite variance,  $\bar{X}$  has approximately a normal distribution, no matter the distribution of  $X_i$

$$\lim_{n \rightarrow \infty} \Pr \left( \mathbf{E}[X] \in \left[ \bar{X} + t_{n-1, \alpha/2} \frac{\hat{\sigma}}{\sqrt{n}}, \bar{X} + t_{n-1, 1-\alpha/2} \frac{\hat{\sigma}}{\sqrt{n}} \right] \right) \geq 1 - \alpha$$



# CI FOR THE MEAN

## HOEFFDINGS INEQUALITY

$X_1, X_2, \dots, X_n$  be *independent* random variables such that  $X_i \in [a, b]$

$$l(D_n) = \bar{X} - (b - a)\sqrt{\frac{\ln(2/\alpha)}{2n}}$$

$$u(D_n) = \bar{X} + (b - a)\sqrt{\frac{\ln(2/\alpha)}{2n}}$$

Valid for all distributions and sample sizes  $n \geq 1$

Does not need i.i.d. data

Very loose intervals, probably need 1,000 samples to compare to random variables.



# UPPER CONFIDENCE INTERVAL FOR LOSS

BASED ON THE T-TEST

$$D_{test} = (x_1, y_1), (x_2, y_2), \dots, (x_n, y_n)$$

$$l_{D_{test}}(\theta) = \frac{1}{n} \sum_{i=1}^n l(x_i, y_i, \theta)$$

$$\hat{\sigma}_{D_{test}}^2 = \frac{1}{n-1} \sum_{i=1}^n \left( l(x_i, y_i, \theta) - l_{D_{test}}(\theta) \right)^2$$

$$l_{upper}(\hat{\theta}^*, D_{test}) = l_{D_{test}}(\hat{\theta}^*) + t_{n-1, 1-\alpha} \frac{\hat{\sigma}_{D_{test}}}{\sqrt{n}}$$



# PROBABILISTIC CONSTRAINTS

PROCESS

Find  $\hat{\theta}^*$  using  $D_{train}$

Test for the constraint

If  $l_{upper}(\hat{\theta}^*, D_{test}) \leq \epsilon$

Return  $\hat{\theta}^*$

Else

?



# PROBABILISTIC CONSTRAINTS

## PROCESS

Find  $\hat{\theta}^*$  using  $D_{train}$

Test for the constraint

If  $l_{upper}(\hat{\theta}^*, D_{test}) \leq \epsilon$

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Else

Return No Solution Found



# PROBABILISTIC CONSTRAINTS

## PROCESS

Find  $\hat{\theta}^*$  using  $D_{train}$

Test for the constraint

If  $l_{upper}(\hat{\theta}^*, D_{test}) \leq \epsilon$

Return  $\hat{\theta}^*$

Else

Return No Solution Found

Once we use it,  $D_{test}$  we cannot reuse it or we will not have a guarantee anymore.

**MUST collect new data.**



# SELDONIAN MACHINE LEARNING

## PROCESS

Search algorithm alg, e.g.,  $\hat{\theta}^* \leftarrow \text{alg}(D_{\text{train}})$

Constraint function  $g: \Theta \rightarrow \mathbb{R}$ ,  $g(\hat{\theta}^*) = l(\hat{\theta}^*) - \epsilon$

confidence level  $\alpha$

Find algorithm alg

$$\arg \max_{\text{alg}} f(\text{alg})$$

$$\text{s.t., } \Pr(g(\text{alg}(D)) \leq 0) \geq 1 - \alpha$$



# SELDONIAN MACHINE LEARNING

## PROCESS

General Process:

Split data  $D$  into  $D_{train}$ ,  $D_{test}$

Find candidate  $\theta_{candidate}$  using  $D_{train}$

Test candidate using upper confidence bound on  $g$

If:  $g(\theta_{candidate}, D_{test}) \leq 0$

Return  $\theta_{candidate}$

Else:

Return No Solution Found



# SELDONIAN MACHINE LEARNING

## PROCESS

General Process:

Split data  $D$  into  $D_{train}$ ,  $D_{test}$

Find candidate  $\theta_{candidate}$  using  $D_{train}$

Test candidate using upper confidence bound on  $g$

If:  $g(\theta_{candidate}, D_{test}) \leq 0$

Return  $\theta_{candidate}$

Else:

Return No Solution Found

Guarantees that if solutions return  
fail the constraint at most  
 $100 \times \alpha$  % of the time.



# SELDONIAN MACHINE LEARNING

## PROCESS

See <https://aisafety.cs.umass.edu/> for tutorials and code to implement these methods



# NEXT CLASS

Presentations

Everyone is required to attend.