

# CS 1678/2078 HW Backprop

## Abstract

In this assignment you will be computing the gradients of the weights of multi-layered neural network by hand. This serves as a precursor to the next homework where you will be implementing backprop to train a multi-layered neural network. To submit this assignment, upload a .pdf to Gradescope containing your responses to the questions below. You are required to use L<sup>A</sup>T<sub>E</sub>X for your write up.

## 1 Partial Derivatives With a Single Sample (34 points)

Consider a neural network with two hidden layers and a linear output layer. The input to the network is a vector of length four, the first hidden layer has three hidden units, the second layer has two, and the last layer as a single unit. Each hidden layer uses the ReLU activation function.

For a single input  $x$  and target value  $y \in \mathbb{R}$ , the loss function for the network is

$$l(\theta) = \frac{1}{2} (f(x, \theta) - y)^2,$$

with each layer computing,

$$h^i = f^i(h^{i-1}, W^i) = \sigma(h^{i-1}W^{i\top}),$$

where  $h^i \in \mathbb{R}^{1 \times n_i}$  and  $W^i \in \mathbb{R}^{n_i \times n_{i-1}}$ . Note that we dropped the dataset  $D$  in notation for the loss function  $l_D(\theta)$ . This just makes notation simpler for the assignment. Let the partial derivative of the loss with respect to  $f(x, \theta)$  be  $\delta$ , e.g.

$$\delta = \frac{\partial l(\theta)}{\partial f(x, \theta)} = f(x, \theta) - y$$

1. What is the partial derivative of  $l(\theta)$  with respect to the weight  $W_{1,1}^3$ ?

$$\begin{aligned} \frac{\partial l(\theta)}{\partial W_{1,1}^3} &= \frac{\partial h^3}{\partial W_{1,1}^3} \frac{\partial l(\theta)}{\partial h^3} \\ &= \end{aligned}$$

2. What is the partial derivative of  $l(\theta)$  with respect to the weight  $W_{1,2}^3$ ?

$$\frac{\partial l(\theta)}{\partial W_{1,2}^3} =$$

3. What are the partial derivatives of  $l(\theta)$  with respect to  $W^3$ .

$$\begin{aligned} \frac{\partial l(\theta)}{\partial W^3} &= \begin{bmatrix} \frac{\partial l(\theta)}{\partial W_{1,1}^3} & \frac{\partial l(\theta)}{\partial W_{1,2}^3} \end{bmatrix} \\ &= \end{aligned}$$

4. What are the partial derivatives of  $l(\theta)$  with respect to  $h_{1,1}^2$ .

$$\frac{\partial l(\theta)}{\partial h_{1,1}^2} =$$

5. What are the partial derivatives of  $l(\theta)$  with respect to  $h^2$ .

$$\begin{aligned}\frac{\partial l(\theta)}{\partial h^2} &= \begin{bmatrix} \frac{\partial l(\theta)}{\partial h_{1,1}^2} & \frac{\partial l(\theta)}{\partial h_{1,2}^2} \end{bmatrix} \\ &= \delta \begin{bmatrix} ? & ? \end{bmatrix}\end{aligned}$$

6. What is the derivative for the ReLU activation function  $\sigma(x) = \max(x, 0)$ ? You can use the notation that  $x > y$  evaluates to 1 if true and 0 if false.

$$\frac{d\sigma(x)}{dx} = ?$$

7. What are the partial derivatives with respect to  $W_{1,j}^2$  for  $h_{1,1}^2 = f_1^2(h^1, W^2)$ ? You may use  $z^i = h^{i-1}W^{i\top}$  and  $z_{1,1}^i = h^{i-1}W_{1,\cdot}^{i\top}$  to simplify your answer.

$$\frac{\partial h_{1,1}^2}{\partial W_{1,j}^2} =$$

8. What are the partial derivatives with respect to  $W_{2,j}^2$  for  $h_{1,1}^2 = f_1^2(h^1, W^2)$ ?

$$\frac{\partial h_{1,1}^2}{\partial W_{2,j}^2} =$$

9. What are the partial derivatives with respect to  $W^2$  for  $h_{1,1}^2 = f_1^2(h^1, W^2)$ ?

$$\frac{\partial h_{1,1}^2}{\partial W^2} = \begin{bmatrix} \frac{\partial h_{1,1}^2}{\partial W_{1,1}^2} & \frac{\partial h_{1,1}^2}{\partial W_{1,2}^2} & \frac{\partial h_{1,1}^2}{\partial W_{1,3}^2} \\ \frac{\partial h_{1,1}^2}{\partial W_{2,1}^2} & \frac{\partial h_{1,1}^2}{\partial W_{2,2}^2} & \frac{\partial h_{1,1}^2}{\partial W_{2,3}^2} \end{bmatrix}$$

10. What are the partial derivatives of  $l(\theta)$  with respect to  $W_{i,j}^2$ ? Note that using scalar notation we express  $h^3$  as

$$h_{1,1}^3 = \sum_{q=1}^{n_2} h_{1,q}^2 W_{1,q}^3 = \sum_{q=1}^{n_2} \sigma \left( \sum_{r=1}^{n_1} h_{1,r}^1 W_{q,r}^2 \right) W_{1,q}^3.$$

You can use this expression as a starting point for the derivative if you are not comfortable with linear algebra.

$$\frac{\partial l(\theta)}{\partial W_{i,j}^2} =$$

11. What are the partial derivatives with respect to  $W^2$  for  $l(\theta)$ ?

$$\frac{\partial l(\theta)}{\partial W^2} = \begin{bmatrix} \frac{\partial l(\theta)}{\partial W_{1,1}^2} & \frac{\partial l(\theta)}{\partial W_{1,2}^2} & \frac{\partial l(\theta)}{\partial W_{1,3}^2} \\ \frac{\partial l(\theta)}{\partial W_{2,1}^2} & \frac{\partial l(\theta)}{\partial W_{2,2}^2} & \frac{\partial l(\theta)}{\partial W_{2,3}^2} \end{bmatrix} = \begin{bmatrix} ? & ? & ? \\ ? & ? & ? \end{bmatrix}$$

12. What are the partial derivatives of  $h_{1,1}^2$  with respect to  $h_{1,j}^1$ ?

$$\frac{\partial h_1^2}{\partial h_{1,j}^1} =$$

13. What are the partial derivatives of  $h_{1,i}^2$  with respect to  $h^1$ ?

$$\frac{\partial h_{1,i}^2}{\partial h^1} = \begin{bmatrix} ? & ? & ? \end{bmatrix}$$

14. What are the partial derivatives of  $l(\theta)$  with respect to  $h_{1,j}^1$ ?

$$\frac{\partial l(\theta)}{\partial h_{1,j}^1} =$$

15. What are the partial derivatives of  $l(\theta)$  with respect to  $h^1$ ?

$$\begin{aligned} \frac{\partial l(\theta)}{\partial h^1} &= \begin{bmatrix} \frac{\partial l(\theta)}{\partial h_{1,1}^1} & \frac{\partial l(\theta)}{\partial h_{1,2}^1} & \frac{\partial l(\theta)}{\partial h_{1,3}^1} \end{bmatrix} \\ &= \begin{bmatrix} ? & ? & ? \end{bmatrix} \end{aligned}$$

16. What is the partial derivative of  $l(\theta)$  with respect to  $W_{i,j}^1$ ?

$$\frac{\partial l(\theta)}{\partial W_{i,j}^1} =$$

17. What are the partial derivatives of  $l(\theta)$  with respect to  $W^1$ ? For conciseness you may use leave your answer in terms of  $\frac{\partial l(\theta)}{\partial h_{1,j}^2}$ . For further ease of notation, you can write these partial derivatives as  $\partial_{h_{1,j}^2} l(\theta)$ .

$$\begin{aligned} \frac{\partial l(\theta)}{\partial W^1} &= \begin{bmatrix} \frac{\partial l(\theta)}{\partial W_{1,1}^1} & \frac{\partial l(\theta)}{\partial W_{1,2}^1} & \frac{\partial l(\theta)}{\partial W_{1,3}^1} & \frac{\partial l(\theta)}{\partial W_{1,4}^1} \\ \frac{\partial l(\theta)}{\partial W_{2,1}^1} & \frac{\partial l(\theta)}{\partial W_{2,2}^1} & \frac{\partial l(\theta)}{\partial W_{2,3}^1} & \frac{\partial l(\theta)}{\partial W_{2,4}^1} \\ \frac{\partial l(\theta)}{\partial W_{3,1}^1} & \frac{\partial l(\theta)}{\partial W_{3,2}^1} & \frac{\partial l(\theta)}{\partial W_{3,3}^1} & \frac{\partial l(\theta)}{\partial W_{3,4}^1} \end{bmatrix} \\ &= \begin{bmatrix} ? & ? & ? & ? \\ ? & ? & ? & ? \\ ? & ? & ? & ? \end{bmatrix} \end{aligned}$$

## 2 Partial Derivatives for a Batch of Data (16 points)

Instead of computing derivatives for a single data point at a time, it is faster to compute a derivatives for a mini-batch of  $m$  data points. First consider a mini-batch size of  $m = 2$ , e.g.,  $x \in \mathbb{R}^{2 \times 4}$ ,  $y \in \mathbb{R}^{2 \times 1}$ ,  $h^1 \in \mathbb{R}^{2 \times 3}$ ,  $h^2 \in \mathbb{R}^{2 \times 2}$ ,  $h^3 \in \mathbb{R}^{2 \times 1}$ . Let

$$l_k(\theta) = \frac{1}{2} (h_{k,1}^3 - y_{k,1})^2.$$

The loss function is now

$$l(\theta) = \frac{1}{m} \sum_{k=1}^m l_k(\theta) = \frac{1}{2} \frac{1}{m} \sum_{k=1}^m (h_{k,1}^3 - y_{k,1})^2.$$

1. What is the partial derivative of  $l(\theta)$  with respect to  $h^3 = f(x, \theta)$ ? Express your final answer using vector notation.

$$\delta = \frac{\partial l(\theta)}{\partial h^3} = \begin{bmatrix} \frac{\partial l(\theta)}{\partial h_{1,1}^3} \\ \frac{\partial l(\theta)}{\partial h_{2,1}^3} \end{bmatrix}$$

$$=$$

2. What is the partial derivative of  $l(\theta)$  with respect to  $W_{1,1}^3$ ?

$$\frac{\partial l(\theta)}{\partial W_{1,1}^3} = ?$$

3. What are the partial derivatives of  $l(\theta)$  with respect to  $W^3$ ? Express the final answer using vector notation.

$$\frac{\partial l(\theta)}{\partial W^3} = \begin{bmatrix} \frac{\partial l(\theta)}{\partial W_{1,1}^3} & \frac{\partial l(\theta)}{\partial W_{1,2}^3} \end{bmatrix}$$

$$=$$

4. What are the partial derivatives  $l(\theta)$  with respect to  $h_{,1}^2$ ? Express the final answer using vector notation.

$$\frac{\partial l(\theta)}{\partial h_{,1}^2} = \begin{bmatrix} \frac{\partial l(\theta)}{\partial h_{1,1}^2} \\ \frac{\partial l(\theta)}{\partial h_{2,1}^2} \end{bmatrix}$$

$$=$$

5. What are the partial derivatives  $l(\theta)$  with respect to  $h^2$ ? Express the final answer using vector notation.

$$\frac{\partial l(\theta)}{\partial h^2} = \begin{bmatrix} \frac{\partial l(\theta)}{\partial h_{1,1}^2} & \frac{\partial l(\theta)}{\partial h_{1,2}^2} \\ \frac{\partial l(\theta)}{\partial h_{2,1}^2} & \frac{\partial l(\theta)}{\partial h_{2,2}^2} \end{bmatrix}$$

$$=$$

6. What is the partial derivative of  $l(\theta)$  with respect to  $W_{i,j}^2$ ?

$$\frac{\partial l(\theta)}{\partial W_{i,j}^2} =$$

7. What are the partial derivatives of  $l(\theta)$  with respect to  $W^2$ ? Express your answer using vector notation.

$$\frac{\partial l(\theta)}{\partial W^2} = \begin{bmatrix} \frac{\partial l(\theta)}{\partial W_{1,1}^2} & \frac{\partial l(\theta)}{\partial W_{1,2}^2} & \frac{\partial l(\theta)}{\partial W_{1,3}^2} \\ \frac{\partial l(\theta)}{\partial W_{2,1}^2} & \frac{\partial l(\theta)}{\partial W_{2,2}^2} & \frac{\partial l(\theta)}{\partial W_{2,3}^2} \end{bmatrix}$$

$$=$$

8. What are the partial derivatives of  $l(\theta)$  with respect to  $h^1$ ? Express your answer using vector notation. You can use  $\partial_{h^2} l(\theta) = \frac{\partial l(\theta)}{\partial h^2}$  to simplify your answer.

$$\frac{\partial l(\theta)}{\partial h^1} = \begin{bmatrix} \frac{\partial l(\theta)}{\partial h_{1,1}^1} & \frac{\partial l(\theta)}{\partial h_{1,2}^1} & \frac{\partial l(\theta)}{\partial h_{1,3}^1} \\ \frac{\partial l(\theta)}{\partial h_{2,1}^1} & \frac{\partial l(\theta)}{\partial h_{2,2}^1} & \frac{\partial l(\theta)}{\partial h_{2,3}^1} \end{bmatrix}$$

$$=$$