



# ETC3580: Advanced Statistical Modelling

Week 11: Additive models

# Outline

1 Additive models

2 Generalized additive models

# Additive models

Avoid curse of dimensionality by assuming additive surface:

$$y = \beta_0 + \sum_{j=1}^p f_j(x_j) + \varepsilon$$

where  $\varepsilon \sim N(0, \sigma^2)$ .

- Restricts complexity but a much richer class of surfaces than parametric models.
- Need to estimate  $p$  one-dimensional functions instead of one  $p$ -dimensional function.
- Usually set each  $f_j$  to have zero mean.
- Some  $f_j$  may be linear.

# Additive models

- Up to  $p$  different bandwidths to select.
- Generalization of multiple regression model

$$y = \beta_0 + \sum_{j=1}^p \beta_j x_j + \varepsilon$$

which is also additive in its predictors.

- Estimated functions,  $f_j$ , are analogues of coefficients in linear regression.
- Interpretation easy with additive structure.

# Additive models

- Categorical predictors: fit constant for each level as for linear models.
- Allow interaction between two continuous variables  $x_j$  and  $x_k$  by fitting a bivariate surface  $f_{j,k}(x_j, x_k)$ .
- Allow interaction between factor  $x_j$  and continuous  $x_k$  by fitting separate functions  $f_{j,k}(x_k)$  for each level of  $x_j$ .

# Additive models in R

- gam package: more smoothing approaches, uses a backfitting algorithm for estimation.
- mgcv package: simplest approach, with automated smoothing selection and wider functionality.
- gss package: smoothing splines only

# Estimation

## Back-fitting-algorithm (Hastie and Tibshirani, 1990)

- 1 Set  $\beta_0 = \bar{y}$ .
- 2 Set  $f_j(x) = \hat{\beta}_j x$  where  $\hat{\beta}_j$  is OLS estimate.
- 3 For  $j = 1, \dots, p, 1, \dots, p, 1, \dots, p, \dots$

$$f_j(x) = S(x_j, y - \beta_0 - \sum_{i \neq j} f_i(x_i))$$

where  $S(x, u)$  means univariate smooth of  $u$  on  $x$ .

Iterate step 3 until convergence.

# Estimation

## Back-fitting-algorithm (Hastie and Tibshirani, 1990)

- 1 Set  $\beta_0 = \bar{y}$ .
- 2 Set  $f_j(x) = \hat{\beta}_j x$  where  $\hat{\beta}_j$  is OLS estimate.
- 3 For  $j = 1, \dots, p, 1, \dots, p, 1, \dots, p, \dots$

$$f_j(x) = S(x_j, y - \beta_0 - \sum_{i \neq j} f_i(x_i))$$

where  $S(x, u)$  means univariate smooth of  $u$  on  $x$ .

Iterate step 3 until convergence.

- $S$  could be *any* univariate smoother.
- $y - \beta_0 - \sum_{i \neq j} f_i(x_i)$  is a “partial residual”



# Estimation

## Regression splines

No need for iterative back-fitting as the model can be written as a linear model.

## Penalized regression splines

No need for iterative back-fitting as the model can be written as a linear mixed-effects model.

# Inference for Additive Models

Each fitted function can be written as a linear smoother  $\hat{\mathbf{f}}_j = \mathbf{S}_j \mathbf{y}$  for some  $n \times n$  matrix  $\mathbf{S}_j$ .

$\hat{\mathbf{f}}(\mathbf{x})$  is a linear smoother. Denote smoothing matrix as  $\mathbf{S}$ :

$$\hat{\mathbf{f}}(\mathbf{x}) = \mathbf{S} \mathbf{y} = \beta_0 \mathbf{1} + \sum_{j=1}^p \mathbf{S}_j \mathbf{y}$$

where  $\mathbf{1} = [1, 1, \dots, 1]^T$ . Then  $\mathbf{S} = \sum_{j=0}^p \mathbf{S}_j$  where  $\mathbf{S}_0$  is such that  $\mathbf{S}_0 \mathbf{y} = \beta_0 \mathbf{1}$ .

Thus all inference results for linear smoothers may be applied to additive model.

# Outline

1 Additive models

2 Generalized additive models

# Generalised additive models

## Generalized Linear Model (GLM)

- Distribution of  $y$
- Link function  $g$
- $E(y \mid x_1, \dots, x_p) = \mu$  where  $g(\mu) = \beta_0 + \sum_{j=1}^p \beta_j x_j$ .

# Generalised additive models

## Generalized Linear Model (GLM)

- Distribution of  $y$
- Link function  $g$
- $E(y \mid x_1, \dots, x_p) = \mu$  where  $g(\mu) = \beta_0 + \sum_{j=1}^p \beta_j x_j$ .

## Generalised Additive Model (GAM)

- Distribution of  $y$
- Link function  $g$
- $E(y \mid x_1, \dots, x_p) = \mu$  where  $g(\mu) = \beta_0 + \sum_{j=1}^p f_j(x_j)$ .

# Generalised additive models

## Examples:

- $Y$  binary and  $g(\mu) = \log[\mu(1 - \mu)]$ . This is a logistic additive model.
- $Y$  normal and  $g(\mu) = \mu$ . This is a standard additive model.

## Estimation

Hastie and Tibshirani describe method for fitting GAMs using a method known as “local scoring” which is an extension of the Fisher scoring procedure.