Modeling: Mesh Representations

Thomas A. Funkhouser

Where Are We Now?

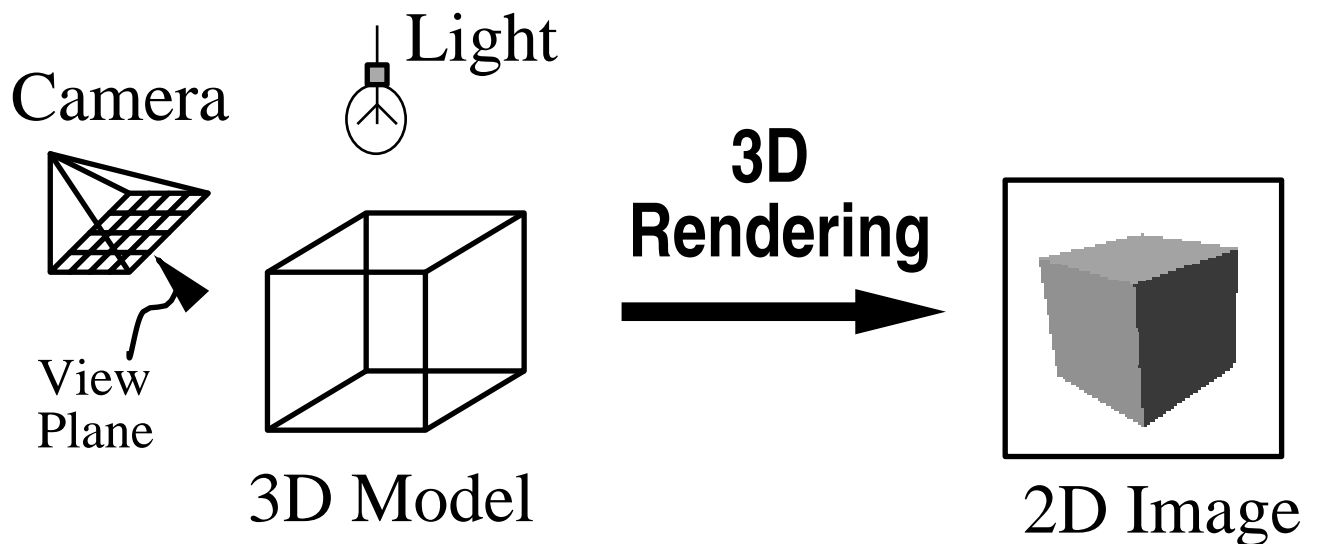- **Image Processing**

- **Rendering**
  - Direct illumination
  - Global illumination

  ⬅

- **Modeling**

- **Animation**

3D Rendering

♦ **How do we ...**
  – draw 3D objects
    with a computer?
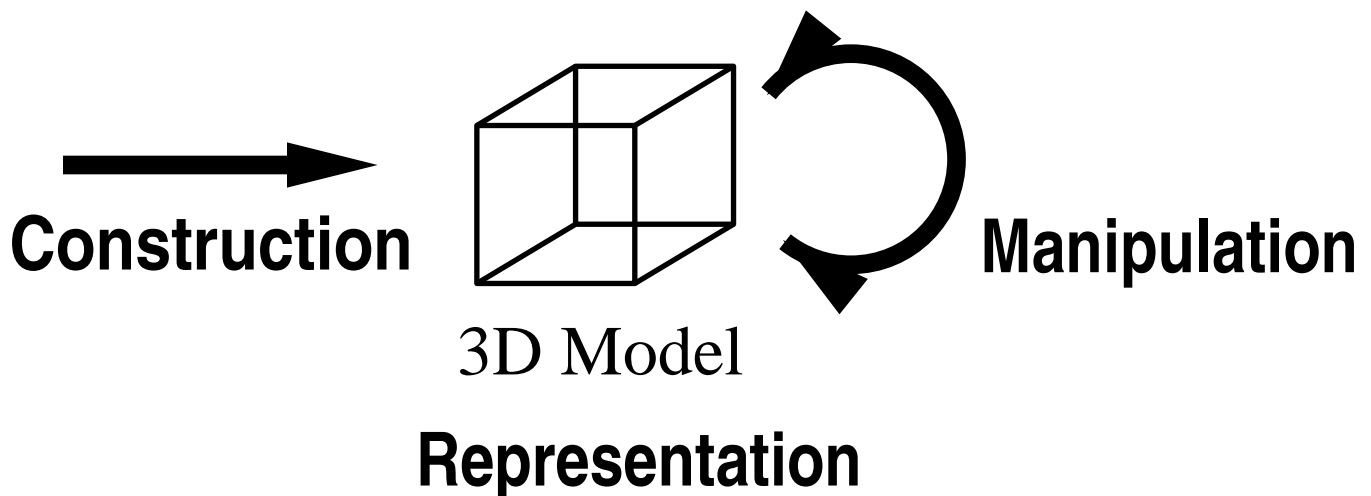
Light

Camera

View
Plane

3D Model

3D Rendering

2D Image

3D Modeling

♦ **How do we ...**
- – represent 3D objects
  in a computer?

- – construct such representations
  quickly and/or automatically
  with a computer?

- – manipulate, analyze, verify, ...
  3D geometrical objects
  with a computer?

Construction   **Manipulation**

3D Model

Representation

3D Representations

♦ **Boundary representations**
  – Mesh representations
  – Parametric surfaces
  – Subdivision surfaces

♦ **Solid representations**
  – Voxels & Octrees
  – BSP trees
  – Constructive solid geometry
  – Algebraic surfaces

♦ **Image–based representations**
  – Images & panoramas
  – Light field & lumigraph

♦ **Composite representations**
  – Scene graphs

3D Representations

- ♦ **Accuracy**
  - – How well does the representation approximate the object?

- ♦ **Computational Efficiency**
  - – How quickly can we generate images from the representation?
  - – How quickly can we compute intersections with the rep?

- ♦ **Storage Efficiency**
  - – How much data is required to store the representation?

- ♦ **Construction Efficiency**
  - – How easy is it to construct the repesentation from available input data?

Today's Lecture

- ◆ **Mesh Representations**
  - – Set of Faces
  - – Triangle strips
  - – Vertex tables
  - – Adjacency lists
  - – Winged–edge

- ◆ **Mesh Operations**
  - – Traversal operations
  - – Euler operations
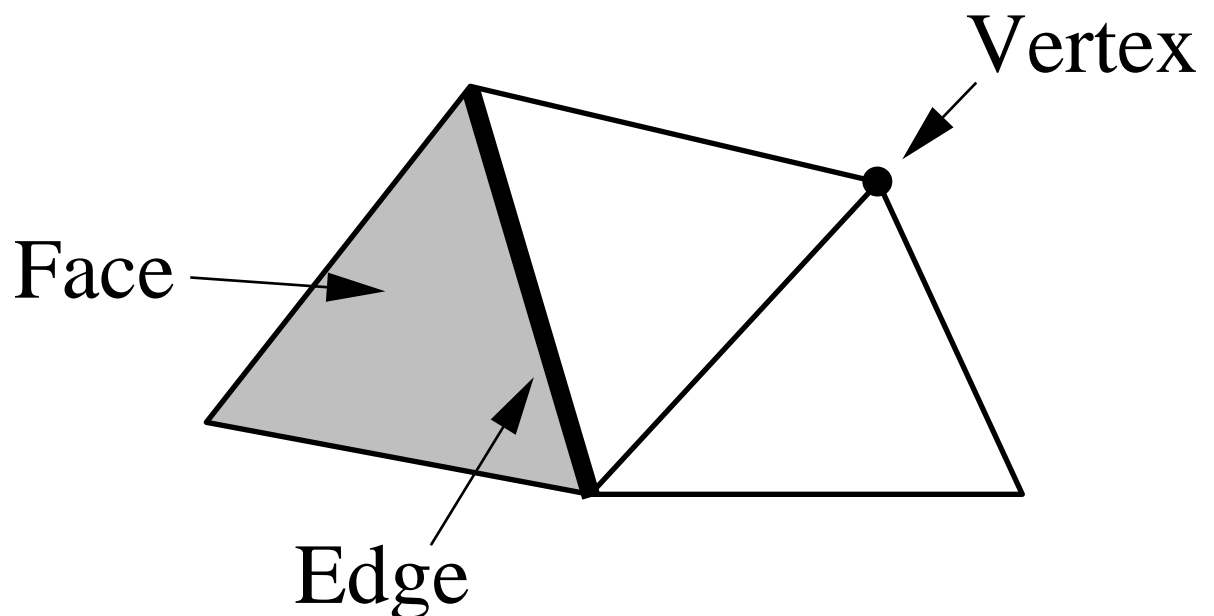 - – Compound operations

Mesh Representations

♦ **Properties:**
  – Boundary representation, so solids not explicitly represented
  – Piecewise linear, so approximate curved surfaces

♦ **Mesh Descriptions**
  • Vertex and Face tables
  • Triangle strips
  • Adjacency lists
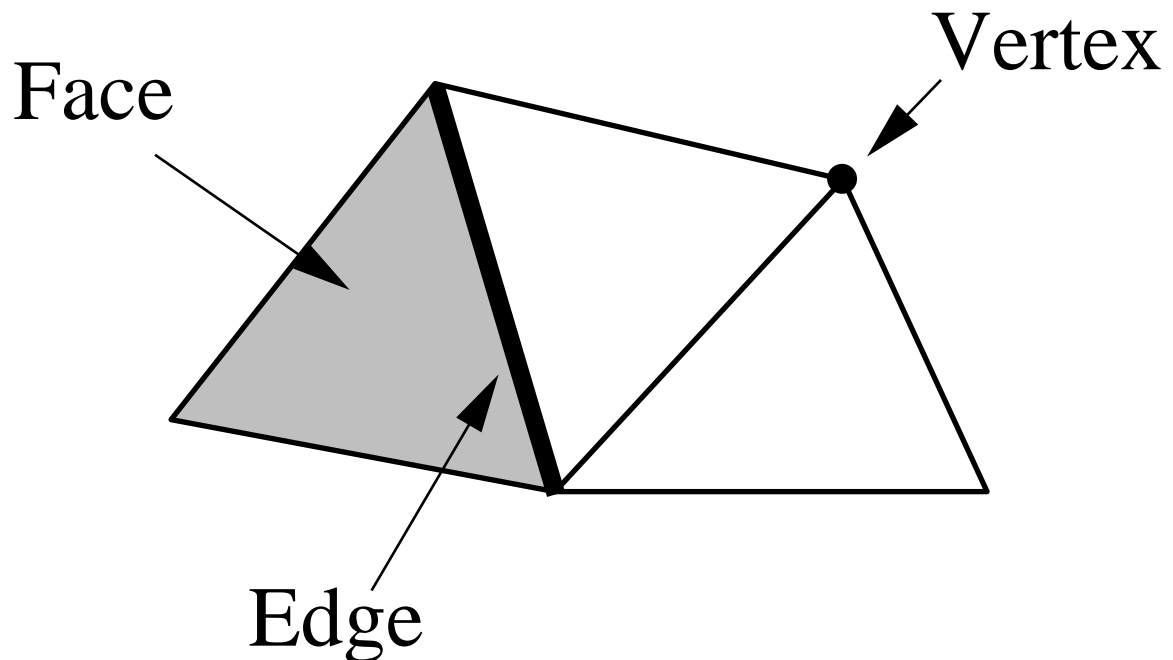 • Winged–edge
  • Multiresolution

Vertex

Face

Edge

Mesh Representations

- **Boundary representation**
  - Describes surface of object
  - Solids not explicitly represented

- **Piecewise linear**
  - Set of polygons
  - Approximate curved surfaces

Vertex

Face

Edge

Mesh Representations
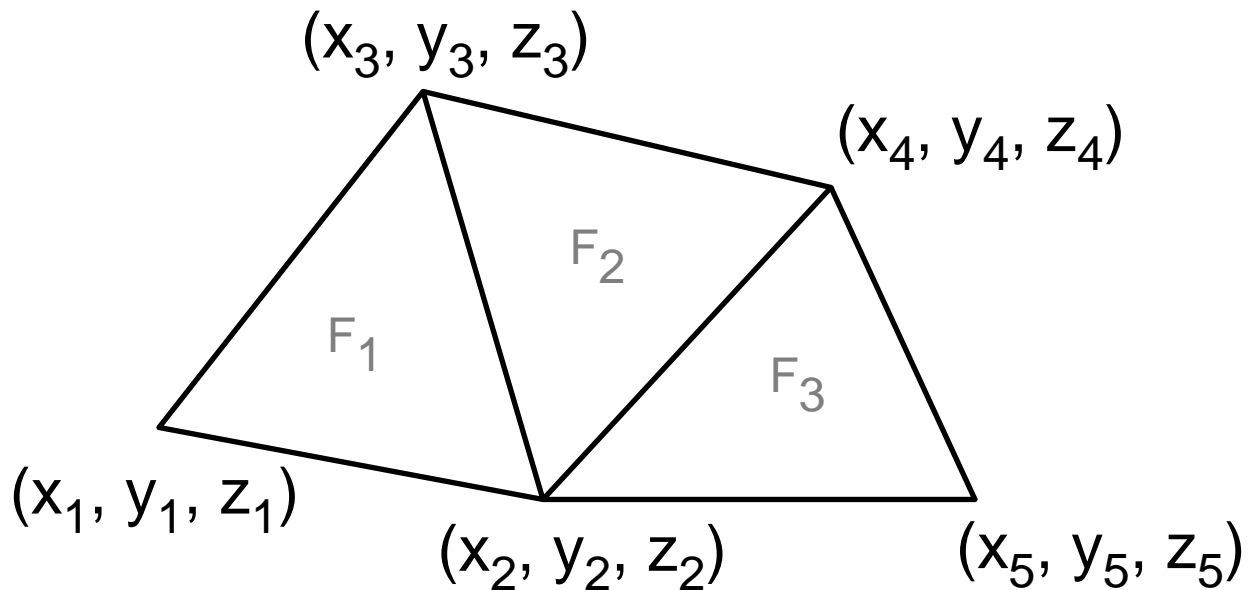
◆ **Possible representations**
  - List of Faces
  - Triangle strips
  - Vertex tables
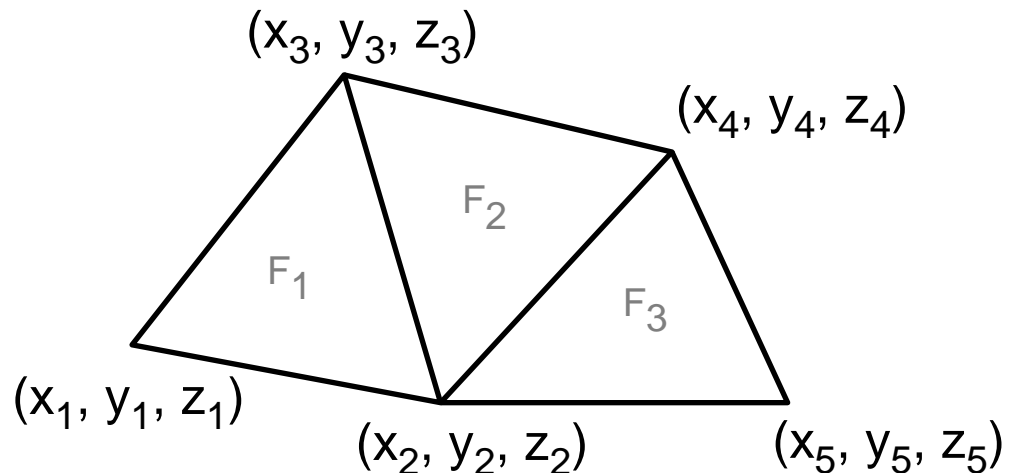 - Adjacency lists
  - Winged–edge

List of Faces

♦ **Each face lists vertex coordinates ...**
   – Redundant vertices
   – No topology information
   – Not hierarchical or multiresolution

(x_3, y_3, z_3)

(x_4, y_4, z_4)

F_2

F_1

F_3

(x_1, y_1, z_1)

(x_2, y_2, z_2)

(x_5, y_5, z_5)

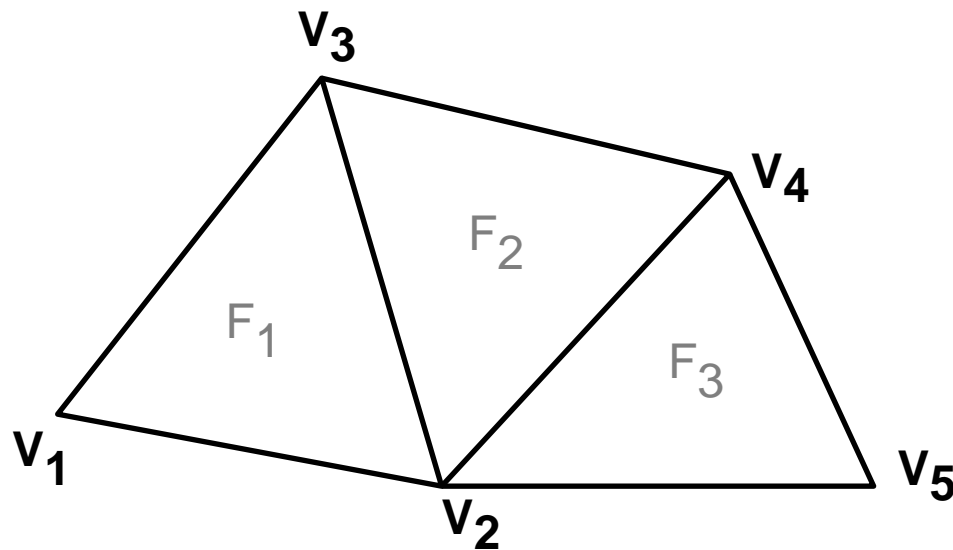| FACE TABLE	
F_1	(x_1, y_1, z_1) (x_2, y_2, z_2) (x_3, y_3, z_3)
F_2	(x_2, y_2, z_2) (x_4, y_4, z_4) (x_3, y_3, z_3)
F_3	(x_2, y_2, z_2) (x_5, y_5, z_5) (x_4, y_4, z_4)

Triangle Strips

♦ **F_i is triangle (V_i, V_{i+1}, V_{i+2})**
  – Faces are implicit
  – Only k–sided faces
  – Limited vertex sharing
  – Limited adjacency information
  – Not hierarchical or multi–resolution

(x_3, y_3, z_3)

(x_4, y_4, z_4)

F_2

F_1

F_3

(x_1, y_1, z_1)

(x_2, y_2, z_2)

(x_5, y_5, z_5)

TRI STRIP
(x_1, y_1, z_1)
(x_2, y_2, z_2)
(x_3, y_3, z_3)
(x_4, y_4, z_4)
(x_2, y_2, z_2)
(x_5, y_5, z_5)

F_1

F_2

F_3

Vertex Tables

♦ **Each face lists vertex references ...**
  + Shared vertices
  – No adjacency information
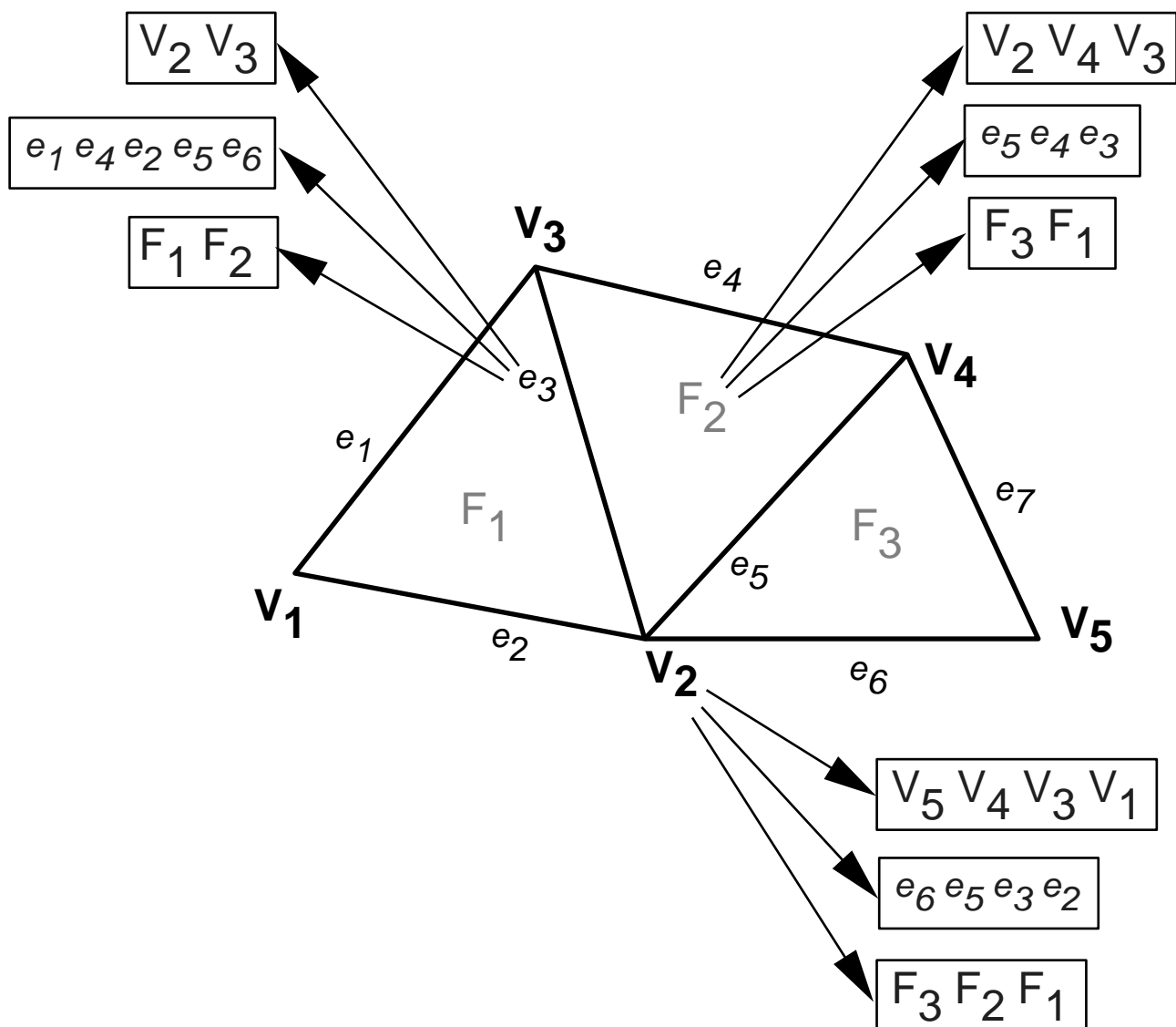 – Not hierarchical or multiresolution
  – Adjacency in O(n) time, generally

VERTEX TABLE

V_1	X_1	Y_1	Z_1
V_2	X_2	Y_2	Z_2
V_3	X_3	Y_3	Z_3
V_4	X_4	Y_4	Z_4
V_5	X_5	Y_5	Z_5

FACE TABLE

F_1	V_1	V_2	V_3
F_2	V_2	V_4	V_3
F_3	V_2	V_5	V_4

Adjacency Lists

- **Store all adjacency relationships**
  - Adjacency in one lookup
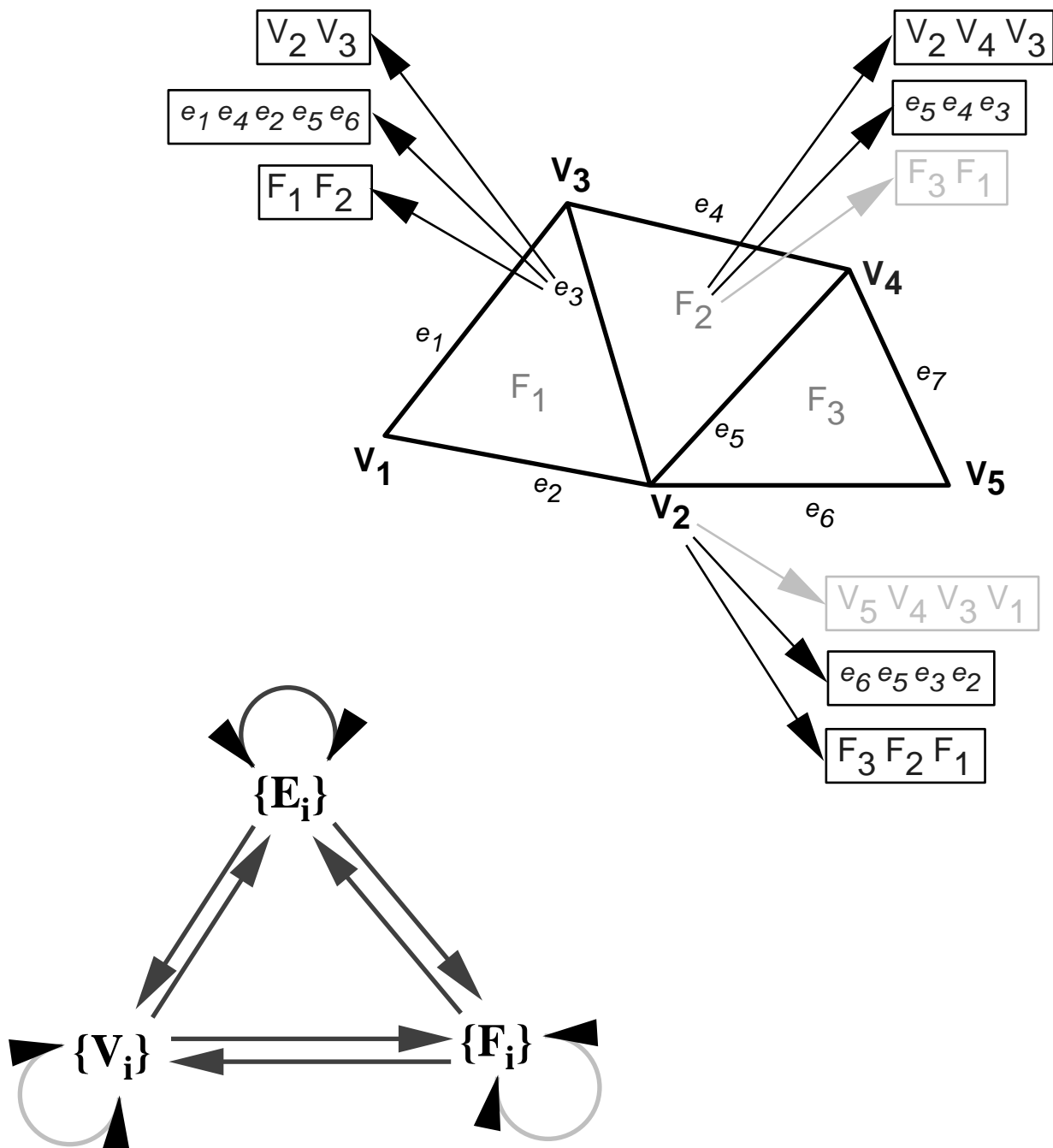 - Efficient topology traversal
  - Extra storage

$V_2\ V_3$

$e_1\ e_4\ e_2\ e_5\ e_6$

$F_1\ F_2$

$V_2\ V_4\ V_3$

$e_5\ e_4\ e_3$

$F_3\ F_1$

V_3

e_4

V_4

e_3

F_2

e_1

F_1

e_7

F_3

e_5

V_1

e_2

V_2

V_5

e_6

$V_5\ V_4\ V_3\ V_1$

$e_6\ e_5\ e_3\ e_2$

$F_3\ F_2\ F_1$

Adjacency Lists

♦ **Directed Graph Schematic** (Woo '85)
   – Directed edge = explicit relation
   – Directed path = implicit relation

$$\{E_i\}$$

$$\{V_i\} \qquad \{F_i\}$$

Partial Adjacency Lists

◆ **Store some adjacency relationships and derive others**

Partial Adjacency Lists

♦ **Which relations should be stored?**
  – Maintain fast adjacency queries
  – Use least storage

Winged Edge

- **Adjacency encoded in edges** (Baumgart '72)
  - Adjacency in O(1) time
  - Little extra storage (fixed records)

Winged Edge

EDGE TABLE

					11	12	21	22
e_1	V_1	V_3		F_1	e_2	e_2	e_4	e_3
e_2	V_1	V_2	F_1		e_1	e_1	e_3	e_6
e_3	V_2	V_3	F_1	F_2	e_2	e_5	e_1	e_4
e_4	V_3	V_4		F_2	e_1	e_3	e_7	e_5
e_5	V_2	V_4	F_2	F_3	e_3	e_6	e_4	e_7
e_6	V_2	V_5	F_3		e_5	e_2	e_7	e_7
e_7	V_4	V_5		F_3	e_4	e_5	e_6	e_6

VERTEX TABLE

V_1	X_1	Y_1	Z_1	e_1
V_2	X_2	Y_2	Z_2	e_6
V_3	X_3	Y_3	Z_3	e_3
V_4	X_4	Y_4	Z_4	e_5
V_5	X_5	Y_5	Z_5	e_6

FACE TABLE

F_1	e_1
F_2	e_3
F_3	e_5

Winged Edge

♦ **Deriving adjacency relationships**

F –> e₁:
return F.Edge();

F, eᵢ –> eᵢ₊₁:
if (e_i.Face(1) == F) return e_i.Edge(2,1);
else return e_i.Edge(1,2);

F, eᵢ –> Vᵢ:
if (e_i.Face(1) == F) return e_i.Vertex(1);
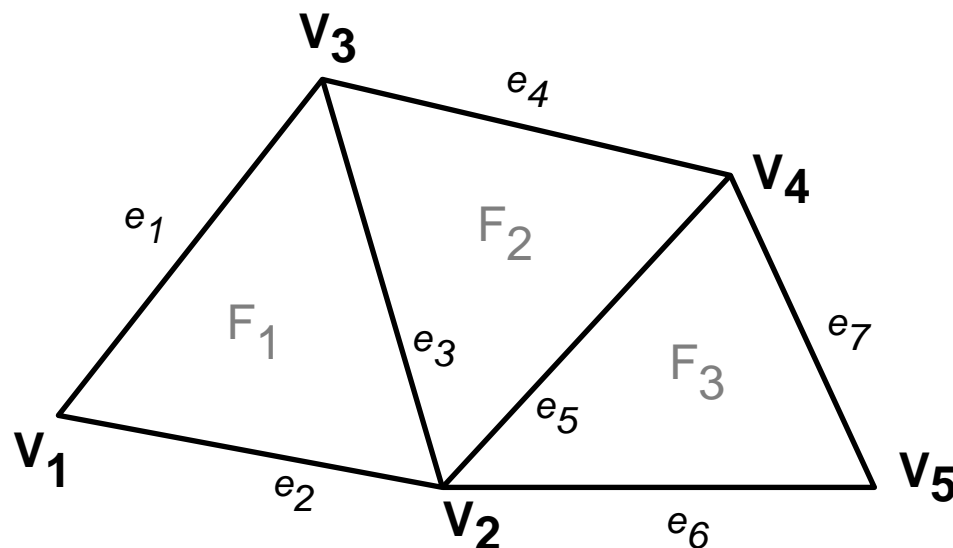else return e_i.Vertex(2);

Mesh Operations

- **Topological traversal**
  - For each face, enumerate vertices
  - For a face, find adjacent faces
  - For an edge, find adjacent edges
  - For a vertex, find adjacent faces

- **Topological surgery**
  - Insert vertex on edge
  - Insert edge splitting a face

Euler Operations

♦ **Maintain topological integrity**
  – Insure Euler–Pontcare formula
    for 3D polyhedra

$$V - E + F - H = 2(M - G)$$

V = # Vertices   *E = # Edges*
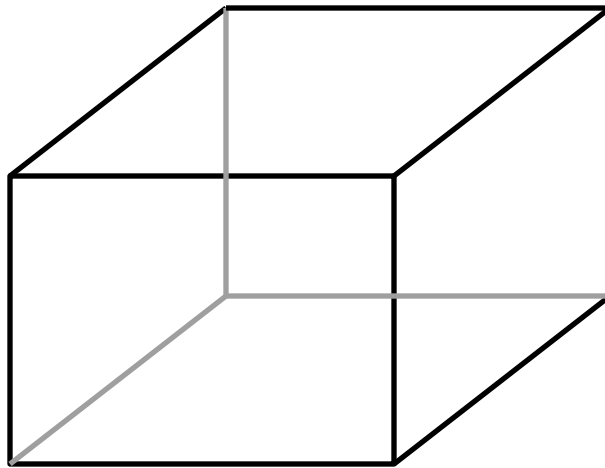*F = # Faces*   *H = # Hole loops*
G = # Handles   *M = # Objects*

Example:

V = 8
E = 12
F = 6
H = 0
G = 0
M = 1

$$8 - 12 + 6 = 2$$

Euler Operations

mbfv: Makes object, face, and vertex
mev: Creates vertex and edge
splite: Splits edge into two by inserting vertex
mfe: Makes face and edge

kbfv: Removes object, face, and vertex
kev: Removes vertex and edge
joine: Joins two edges by removing vertex
kfe: Removes face and edge

me–kh: Makes edge, kills hole loop
me–kbf: Makes edge, kills object and face
mhr–kf: Makes hole loop and handle, kills face
mh–kbf: Makes hole loop, kills object and face

$$V - E + F - H = 2(\,M - G\,)$$

V = # Vertices   *E = # Edges*
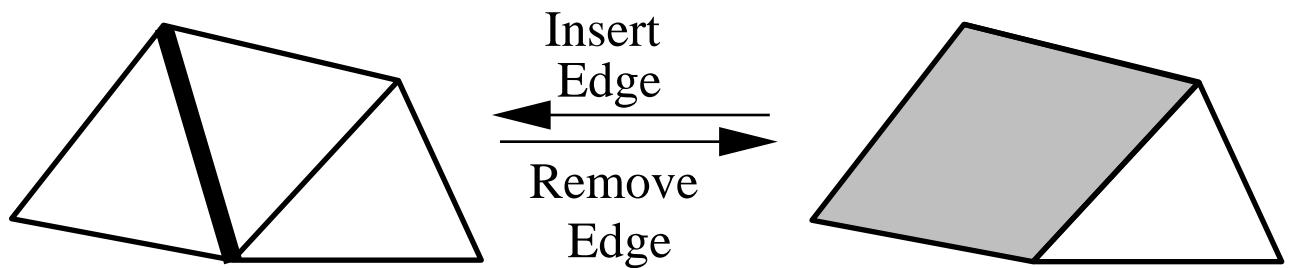*F = # Faces*   *H = # Hole loops*
G = # Handles   *M = # Objects*
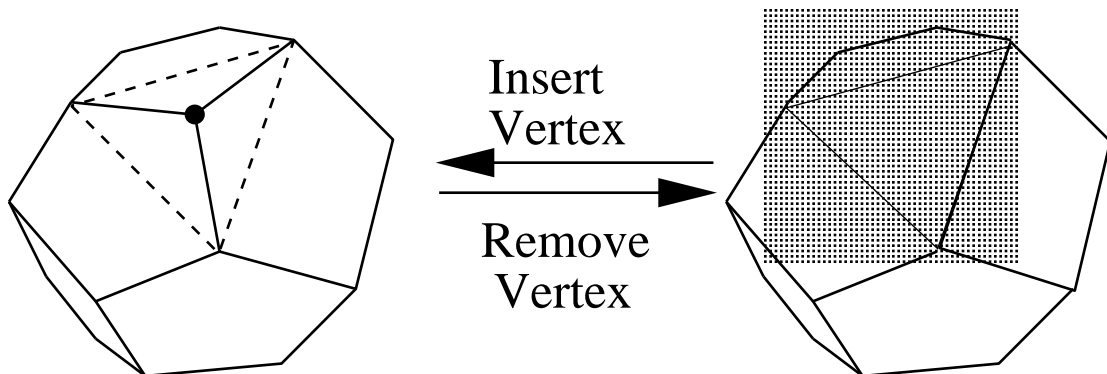
Compound Operations

Insert edge: Inserts edge across face
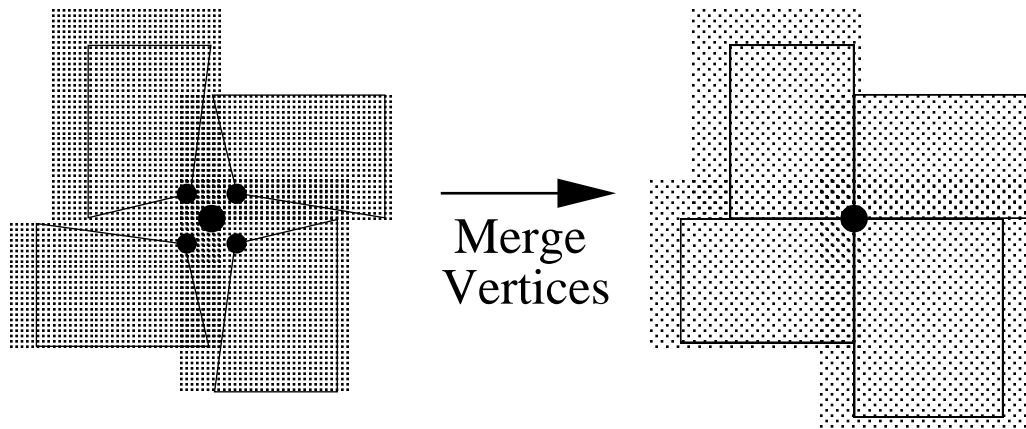**Remove edge:** Removes edge while joining two faces

Insert
Edge

Remove
Edge

Insert vertex on face: Splits face into many
Remove vertex: Creates face, or joins adjacent faces

Insert
Vertex

Remove
Vertex

Merge vertices: Collapses n vertices into one
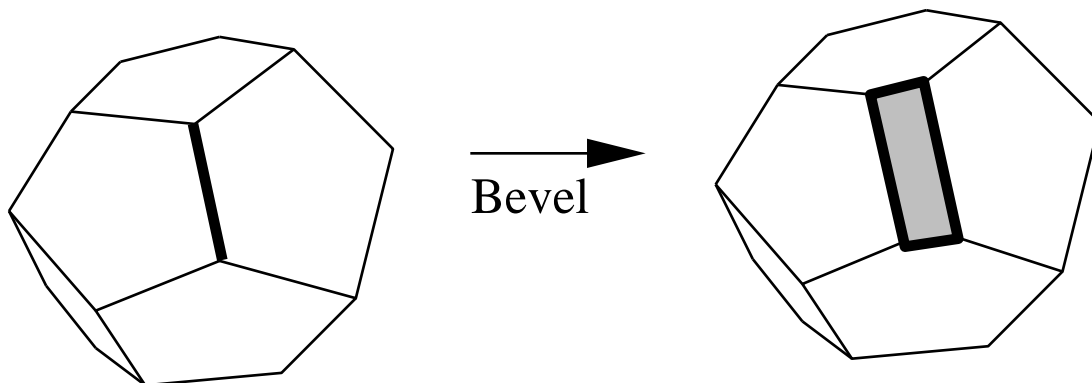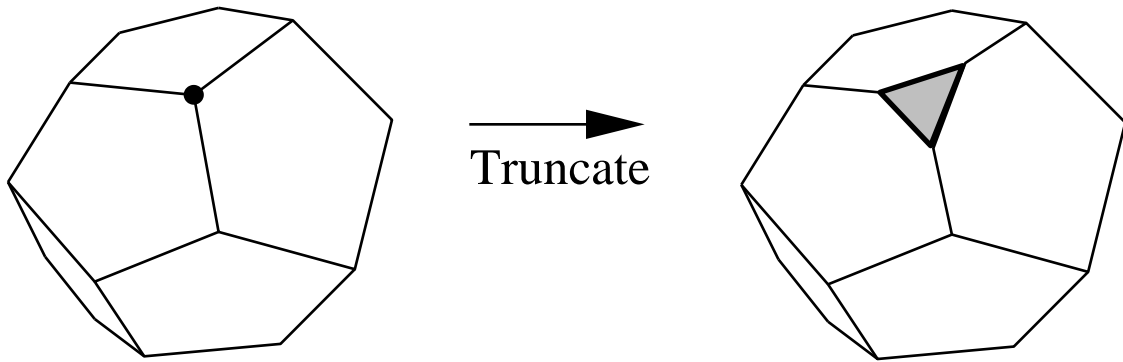
Merge
Vertices

High–Level Operations

Truncate: Replaces vertex by face
Bevel: Replaces edge by face

Truncate

Bevel

Summary

- **Mesh Considerations**
  - Storage requirements
  - Computational efficiency
  - Ease of specification

- **Mesh Representations**
  - List of Faces
  - Triangle strips
  - Vertex tables
  - Adjacency lists
  - Winged–edge

- **Mesh Operations**
  - Traversal operations
  - Euler operations
  - Compound operations