



WebAssembly Specification

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WebAssembly Community Group

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1.1 Introduction

WebAssembly (abbreviated Wasm²) is a *safe, portable, low-level code format* designed for efficient execution and compact representation. Its main goal is to enable high performance applications on the Web, but it does not make any Web-specific assumptions or provide Web-specific features, so it can be employed in other environments as well.

WebAssembly is an open standard developed by a [W3C Community Group](https://www.w3.org/community/webassembly/)¹.

This document describes version 3.0 (Draft 2024-06-17) of the [core](#) WebAssembly standard. It is intended that it will be superseded by new incremental releases with additional features in the future.

1.1.1 Design Goals

The design goals of WebAssembly are the following:

- Fast, safe, and portable *semantics*:
 - **Fast**: executes with near native code performance, taking advantage of capabilities common to all contemporary hardware.
 - **Safe**: code is validated and executes in a memory-safe³, sandboxed environment preventing data corruption or security breaches.
 - **Well-defined**: fully and precisely defines valid programs and their behavior in a way that is easy to reason about informally and formally.
 - **Hardware-independent**: can be compiled on all modern architectures, desktop or mobile devices and embedded systems alike.
 - **Language-independent**: does not privilege any particular language, programming model, or object model.
 - **Platform-independent**: can be embedded in browsers, run as a stand-alone VM, or integrated in other environments.

² A contraction of “WebAssembly”, not an acronym, hence not using all-caps.

¹ <https://www.w3.org/community/webassembly/>

³ No program can break WebAssembly’s memory model. Of course, it cannot guarantee that an unsafe language compiling to WebAssembly does not corrupt its own memory layout, e.g. inside WebAssembly’s linear memory.

- **Open:** programs can interoperate with their environment in a simple and universal manner.
- Efficient and portable *representation*:
 - **Compact:** has a binary format that is fast to transmit by being smaller than typical text or native code formats.
 - **Modular:** programs can be split up in smaller parts that can be transmitted, cached, and consumed separately.
 - **Efficient:** can be decoded, validated, and compiled in a fast single pass, equally with either just-in-time (JIT) or ahead-of-time (AOT) compilation.
 - **Streamable:** allows decoding, validation, and compilation to begin as soon as possible, before all data has been seen.
 - **Parallelizable:** allows decoding, validation, and compilation to be split into many independent parallel tasks.
 - **Portable:** makes no architectural assumptions that are not broadly supported across modern hardware.

WebAssembly code is also intended to be easy to inspect and debug, especially in environments like web browsers, but such features are beyond the scope of this specification.

1.1.2 Scope

At its core, WebAssembly is a *virtual instruction set architecture (virtual ISA)*. As such, it has many use cases and can be embedded in many different environments. To encompass their variety and enable maximum reuse, the WebAssembly specification is split and layered into several documents.

This document is concerned with the core ISA layer of WebAssembly. It defines the instruction set, binary encoding, validation, and execution semantics, as well as a textual representation. It does not, however, define how WebAssembly programs can interact with a specific environment they execute in, nor how they are invoked from such an environment.

Instead, this specification is complemented by additional documents defining interfaces to specific embedding environments such as the Web. These will each define a WebAssembly *application programming interface (API)* suitable for a given environment.

1.1.3 Security Considerations

WebAssembly provides no ambient access to the computing environment in which code is executed. Any interaction with the environment, such as I/O, access to resources, or operating system calls, can only be performed by invoking [functions](#) provided by the [embedder](#) and imported into a WebAssembly [module](#). An embedder can establish security policies suitable for a respective environment by controlling or limiting which functional capabilities it makes available for import. Such considerations are an embedder's responsibility and the subject of [API definitions](#) for a specific environment.

Because WebAssembly is designed to be translated into machine code running directly on the host's hardware, it is potentially vulnerable to side channel attacks on the hardware level. In environments where this is a concern, an embedder may have to put suitable mitigations into place to isolate WebAssembly computations.

1.1.4 Dependencies

WebAssembly depends on two existing standards:

- [IEEE 754⁴](#), for the representation of [floating-point data](#) and the semantics of respective [numeric operations](#).
- [Unicode⁵](#), for the representation of [import/export names](#) and the [text format](#).

However, to make this specification self-contained, relevant aspects of the aforementioned standards are defined and formalized as part of this specification, such as the [binary representation](#) and [rounding](#) of floating-point values, and the [value range](#) and [UTF-8 encoding](#) of Unicode characters.

Note: The aforementioned standards are the authoritative source of all respective definitions. Formalizations given in this specification are intended to match these definitions. Any discrepancy in the syntax or semantics described is to be considered an error.

1.2 Overview

1.2.1 Concepts

WebAssembly encodes a low-level, assembly-like programming language. This language is structured around the following concepts.

Values

WebAssembly provides only four basic *number types*. These are integers and [IEEE 754⁶](#) numbers, each in 32 and 64 bit width. 32-bit integers also serve as Booleans and as memory addresses. The usual operations on these types are available, including the full matrix of conversions between them. There is no distinction between signed and unsigned integer types. Instead, integers are interpreted by respective operations as either unsigned or signed in two's complement representation.

In addition to these basic number types, there is a single 128 bit wide vector type representing different types of packed data. The supported representations are four 32-bit, or two 64-bit [IEEE 754⁷](#) numbers, or different widths of packed integer values, specifically two 64-bit integers, four 32-bit integers, eight 16-bit integers, or sixteen 8-bit integers.

Finally, values can consist of opaque *references* that represent pointers towards different sorts of entities. Unlike with other types, their size or representation is not observable.

Instructions

The computational model of WebAssembly is based on a *stack machine*. Code consists of sequences of *instructions* that are executed in order. Instructions manipulate values on an implicit *operand stack*⁸ and fall into two main categories. *Simple* instructions perform basic operations on data. They pop arguments from the operand stack and push results back to it. *Control* instructions alter control flow. Control flow is *structured*, meaning it is expressed with well-nested constructs such as blocks, loops, and conditionals. Branches can only target such constructs.

Traps

Under some conditions, certain instructions may produce a *trap*, which immediately aborts execution. Traps cannot be handled by WebAssembly code, but are reported to the outside environment, where they typically can be caught.

Functions

Code is organized into separate *functions*. Each function takes a sequence of values as parameters and returns

⁴ <https://ieeexplore.ieee.org/document/8766229>

⁵ <https://www.unicode.org/versions/latest/>

⁶ <https://ieeexplore.ieee.org/document/8766229>

⁷ <https://ieeexplore.ieee.org/document/8766229>

⁸ In practice, implementations need not maintain an actual operand stack. Instead, the stack can be viewed as a set of anonymous registers that are implicitly referenced by instructions. The [type system](#) ensures that the stack height, and thus any referenced register, is always known statically.

a sequence of values as results. Functions can call each other, including recursively, resulting in an implicit call stack that cannot be accessed directly. Functions may also declare mutable *local variables* that are usable as virtual registers.

Tables

A *table* is an array of opaque values of a particular *reference type*. It allows programs to select such values indirectly through a dynamic index operand. Thereby, for example, a program can call functions indirectly through a dynamic index into a table. This allows emulating function pointers by way of table indices.

Linear Memory

A *linear memory* is a contiguous, mutable array of raw bytes. Such a memory is created with an initial size but can be grown dynamically. A program can load and store values from/to a linear memory at any byte address (including unaligned). Integer loads and stores can specify a *storage size* which is smaller than the size of the respective value type. A trap occurs if an access is not within the bounds of the current memory size.

Modules

A WebAssembly binary takes the form of a *module* that contains definitions for functions, tables, and linear memories, as well as mutable or immutable *global variables*. Definitions can also be *imported*, specifying a module/name pair and a suitable type. Each definition can optionally be *exported* under one or more names. In addition to definitions, modules can define initialization data for their memories or tables that takes the form of *segments* copied to given offsets. They can also define a *start function* that is automatically executed.

Embedder

A WebAssembly implementation will typically be *embedded* into a *host* environment. This environment defines how loading of modules is initiated, how imports are provided (including host-side definitions), and how exports can be accessed. However, the details of any particular embedding are beyond the scope of this specification, and will instead be provided by complementary, environment-specific API definitions.

1.2.2 Semantic Phases

Conceptually, the semantics of WebAssembly is divided into three phases. For each part of the language, the specification specifies each of them.

Decoding

WebAssembly modules are distributed in a *binary format*. *Decoding* processes that format and converts it into an internal representation of a module. In this specification, this representation is modelled by *abstract syntax*, but a real implementation could compile directly to machine code instead.

Validation

A decoded module has to be *valid*. Validation checks a number of well-formedness conditions to guarantee that the module is meaningful and safe. In particular, it performs *type checking* of functions and the instruction sequences in their bodies, ensuring for example that the operand stack is used consistently.

Execution

Finally, a valid module can be *executed*. Execution can be further divided into two phases:

Instantiation. A module *instance* is the dynamic representation of a module, complete with its own state and execution stack. Instantiation executes the module body itself, given definitions for all its imports. It initializes globals, memories and tables and invokes the module's start function if defined. It returns the instances of the module's exports.

Invocation. Once instantiated, further WebAssembly computations can be initiated by *invoking* an exported function on a module instance. Given the required arguments, that executes the respective function and returns its results.

Instantiation and invocation are operations within the embedding environment.

2.1 Conventions

WebAssembly is a programming language that has multiple concrete representations (its [binary format](#) and the [text format](#)). Both map to a common structure. For conciseness, this structure is described in the form of an *abstract syntax*. All parts of this specification are defined in terms of this abstract syntax.

2.1.1 Grammar Notation

The following conventions are adopted in defining grammar rules for abstract syntax.

- Terminal symbols (atoms) are written in sans-serif font or in symbolic form: `i32`, `nop`, `→`, `[,]`.
- Nonterminal symbols are written in italic font: *valtype*, *instr*.
- A^n is a sequence of $n \geq 0$ iterations of A .
- A^* is a possibly empty sequence of iterations of A . (This is a shorthand for A^n used where n is not relevant.)
- A^+ is a non-empty sequence of iterations of A . (This is a shorthand for A^n where $n \geq 1$.)
- $A^?$ is an optional occurrence of A . (This is a shorthand for A^n where $n \leq 1$.)
- Productions are written $sym ::= A_1 \mid \dots \mid A_n$.
- Large productions may be split into multiple definitions, indicated by ending the first one with explicit ellipses, $sym ::= A_1 \mid \dots$, and starting continuations with ellipses, $sym ::= \dots \mid A_2$.
- Some productions are augmented with side conditions, “(if *condition*)”, that provide a shorthand for a combinatorial expansion of the production into many separate cases.
- If the same meta variable or non-terminal symbol appears multiple times in a production, then all those occurrences must have the same instantiation. (This is a shorthand for a side condition requiring multiple different variables to be equal.)

2.1.2 Auxiliary Notation

When dealing with syntactic constructs the following notation is also used:

- ϵ denotes the empty sequence.
- $|s|$ denotes the length of a sequence s .
- $s[i]$ denotes the i -th element of a sequence s , starting from 0.
- $s[i : n]$ denotes the sub-sequence $s[i] \dots s[i + n - 1]$ of a sequence s .
- $s[[i] = A]$ denotes the same sequence as s , except that the i -th element is replaced with A .
- $s[[i : n] = A^n]$ denotes the same sequence as s , except that the sub-sequence $s[i : n]$ is replaced with A^n .
- $\text{concat}(s^*)$ denotes the flat sequence formed by concatenating all sequences s_i in s^* .

Moreover, the following conventions are employed:

- The notation x^n , where x is a non-terminal symbol, is treated as a meta variable ranging over respective sequences of x (similarly for x^* , x^+ , $x^?$).
- When given a sequence x^n , then the occurrences of x in an iterated sequence $(\dots x \dots)^n$ are assumed to be in point-wise correspondence with x^n (similarly for x^* , x^+ , $x^?$). This implicitly expresses a form of mapping syntactic constructions over a sequence.

Productions of the following form are interpreted as *records* that map a fixed set of fields field_i to “values” A_i , respectively:

$$r ::= \{ \text{field}_1 A_1, \text{field}_2 A_2, \dots \}$$

The following notation is adopted for manipulating such records:

- $r.\text{field}$ denotes the contents of the field component of r .
- $r[\text{field} = A]$ denotes the same record as r , except that the contents of the field component is replaced with A .
- $r[\text{field} = ..A^n]$ denotes the same record as r , except that A^n is appended to the sequence of the field component, i.e, it is short for $r[\text{field} = r.\text{field} A^n]$.
- $r_1 \oplus r_2$ denotes the composition of two records with the same fields of sequences by appending each sequence point-wise:

$$\{ \text{field}_1 A_1^*, \text{field}_2 A_2^*, \dots \} \oplus \{ \text{field}_1 B_1^*, \text{field}_2 B_2^*, \dots \} = \{ \text{field}_1 A_1^* B_1^*, \text{field}_2 A_2^* B_2^*, \dots \}$$

- $\bigoplus r^*$ denotes the composition of a sequence of records, respectively; if the sequence is empty, then all fields of the resulting record are empty.

The update notation for sequences and records generalizes recursively to nested components accessed by “paths” $pth ::= ([i] \mid .\text{field})^+$:

- $s[[i]pth = A]$ is short for $s[[i] = s[i][pth = A]]$,
- $r[\text{field} pth = A]$ is short for $r[\text{field} = r.\text{field}[pth = A]]$.

2.1.3 Lists

Lists are bounded sequences of the form A^n (or A^*), where the A can either be values or complex constructions. A list can have at most $2^{32} - 1$ elements.

$$\text{list}(X) ::= X^* \quad \text{if } |X^*| < 2^{32}$$

2.2 Values

WebAssembly programs operate on primitive numeric *values*. Moreover, in the definition of programs, immutable sequences of values occur to represent more complex data, such as text strings or other vectors.

2.2.1 Bytes

The simplest form of value are raw uninterpreted *bytes*. In the abstract syntax they are represented as hexadecimal literals.

$$\text{byte} ::= 0x00 \mid \dots \mid 0xFF$$

Conventions

- The meta variable b ranges over bytes.
- Bytes are sometimes interpreted as natural numbers $n < 256$.

2.2.2 Integers

Different classes of *integers* with different value ranges are distinguished by their *bit width* N and by whether they are *unsigned* or *signed*.

$$\begin{aligned} uN &::= 0 \mid \dots \mid 2^N - 1 \\ sN &::= -2^{N-1} \mid \dots \mid -1 \mid 0 \mid +1 \mid \dots \mid 2^{N-1} - 1 \\ iN &::= uN \end{aligned}$$

The class i defines *uninterpreted* integers, whose signedness interpretation can vary depending on context. In the abstract syntax, they are represented as unsigned values. However, some operations [convert](#) them to signed based on a two's complement interpretation.

Note: The main integer types occurring in this specification are $u32$, $u64$, $s32$, $s64$, $i8$, $i16$, $i32$, $i64$. However, other sizes occur as auxiliary constructions, e.g., in the definition of [floating-point](#) numbers.

Conventions

- The meta variables m , n , i , j range over integers.
- Numbers may be denoted by simple arithmetics, as in the grammar above. In order to distinguish arithmetics like 2^N from sequences like $(1)^N$, the latter is distinguished with parentheses.

2.2.3 Floating-Point

Floating-point data represents 32 or 64 bit values that correspond to the respective binary formats of the IEEE 754⁹ standard (Section 3.3).

Every value has a *sign* and a *magnitude*. Magnitudes can either be expressed as *normal* numbers of the form $m_0 . m_1 m_2 \dots m_m \cdot 2^e$, where e is the exponent and m is the *significand* whose most significant bit m_0 is 1, or as a *subnormal* number where the exponent is fixed to the smallest possible value and m_0 is 0; among the subnormals are positive and negative zero values. Since the significands are binary values, normals are represented in the form $(1 + m \cdot 2^{-M}) \cdot 2^e$, where M is the bit width of m ; similarly for subnormals.

Possible magnitudes also include the special values ∞ (infinity) and nan (*NaN*, not a number). NaN values have a *payload* that describes the mantissa bits in the underlying [binary representation](#). No distinction is made between signalling and quiet NaNs.

$$\begin{aligned} fN &::= +f\text{mag}N \mid -f\text{mag}N \\ f\text{mag}N &::= \begin{array}{ll} (1 + m \cdot 2^{-M}) \cdot 2^n & \text{if } m < 2^M \wedge 2 - 2^{E-1} \leq n \leq 2^{E-1} - 1 \\ (0 + m \cdot 2^{-M}) \cdot 2^n & \text{if } m < 2^M \wedge 2 - 2^{E-1} = n \\ \infty & \\ \text{nan}(m) & \text{if } 1 \leq m < 2^M \end{array} \end{aligned}$$

where $M = \text{signif}(N)$ and $E = \text{expon}(N)$ with

$$\begin{aligned} \text{signif}(32) &= 23 \\ \text{signif}(64) &= 52 \\ \text{expon}(32) &= 8 \\ \text{expon}(64) &= 11 \end{aligned}$$

A *canonical NaN* is a floating-point value $\pm \text{nan}(\text{canon}_N)$ where canon_N is a payload whose most significant bit is 1 while all others are 0:

$$\text{canon}_N = 2^{\text{signif}(N)-1}$$

An *arithmetic NaN* is a floating-point value $\pm \text{nan}(m)$ with $m \geq \text{canon}_N$, such that the most significant bit is 1 while all others are arbitrary.

Note: In the abstract syntax, subnormals are distinguished by the leading 0 of the significand. The exponent of subnormals has the same value as the smallest possible exponent of a normal number. Only in the [binary representation](#) the exponent of a subnormal is encoded differently than the exponent of any normal number.

The notion of canonical NaN defined here is unrelated to the notion of canonical NaN that the IEEE 754¹⁰ standard (Section 3.5.2) defines for decimal interchange formats.

Conventions

- The meta variable z ranges over floating-point values where clear from context.
- Where clear from context, shorthands like $+1$ denote floating point values like $+(1 + 1 \cdot 2^{-M}) \cdot 2^0$.

⁹ <https://ieeexplore.ieee.org/document/8766229>

¹⁰ <https://ieeexplore.ieee.org/document/8766229>

2.2.4 Vectors

Numeric vectors are 128-bit values that are processed by vector instructions (also known as *SIMD* instructions, single instruction multiple data). They are represented in the abstract syntax using *i128*. The interpretation of lane types (*integer* or *floating-point* numbers) and lane sizes are determined by the specific instruction operating on them.

2.2.5 Names

Names are sequences of *characters*, which are *scalar values* as defined by [Unicode](#)¹¹ (Section 2.4).

$$\begin{aligned} \textit{name} &::= \textit{char}^* && \text{if } |\text{utf8}(\textit{char}^*)| < 2^{32} \\ \textit{char} &::= \text{U+00} \mid \dots \mid \text{U+D7FF} \mid \text{U+E000} \mid \dots \mid \text{U+10FFFF} \end{aligned}$$

Due to the limitations of the [binary format](#), the length of a name is bounded by the length of its [UTF-8](#) encoding.

Convention

- Characters (Unicode scalar values) are sometimes used interchangeably with natural numbers $n < 1114112$.

2.3 Types

Various entities in WebAssembly are classified by types. Types are checked during [validation](#), [instantiation](#), and possibly [execution](#).

2.3.1 Number Types

Number types classify numeric values.

$$\textit{numtype} ::= \textit{i32} \mid \textit{i64} \mid \textit{f32} \mid \textit{f64}$$

The types *i32* and *i64* classify 32 and 64 bit integers, respectively. Integers are not inherently signed or unsigned, their interpretation is determined by individual operations.

The types *f32* and *f64* classify 32 and 64 bit floating-point data, respectively. They correspond to the respective binary floating-point representations, also known as *single* and *double* precision, as defined by the [IEEE 754](#)¹² standard (Section 3.3).

Number types are *transparent*, meaning that their bit patterns can be observed. Values of number type can be stored in [memories](#).

Conventions

- The notation $|t|$ denotes the *bit width* of a number type t . That is, $|i32| = |f32| = 32$ and $|i64| = |f64| = 64$.

¹¹ <https://www.unicode.org/versions/latest/>

¹² <https://ieeexplore.ieee.org/document/8766229>

2.3.2 Vector Types

Vector types classify vectors of [numeric](#) values processed by vector instructions (also known as *SIMD* instructions, single instruction multiple data).

$$vetype ::= v128$$

The type `v128` corresponds to a 128 bit vector of packed integer or floating-point data. The packed data can be interpreted as signed or unsigned integers, single or double precision floating-point values, or a single 128 bit type. The interpretation is determined by individual operations.

Vector types, like [number types](#) are *transparent*, meaning that their bit patterns can be observed. Values of vector type can be stored in [memories](#).

Conventions

- The notation $|t|$ for [bit width](#) extends to vector types as well, that is, $|v128| = 128$.

2.3.3 Heap Types

Heap types classify objects in the runtime [store](#). There are three disjoint hierarchies of heap types:

- *function types* classify [functions](#),
- *aggregate types* classify dynamically allocated *managed* data, such as *structures*, *arrays*, or *unboxed scalars*,
- *external types* classify *external* references possibly owned by the [embedder](#).

The values from the latter two hierarchies are interconvertible by ways of the [extern.convert_any](#) and [any.convert_extern](#) instructions. That is, both type hierarchies are inhabited by an isomorphic set of values, but may have different, incompatible representations in practice.

$$\begin{aligned} absheaptype &::= \text{any} \mid \text{eq} \mid \text{i31} \mid \text{struct} \mid \text{array} \mid \text{none} \\ &\quad \mid \text{func} \mid \text{nofunc} \\ &\quad \mid \text{extern} \mid \text{noextern} \\ &\quad \mid \dots \\ heaptype &::= absheaptype \mid typeuse \\ typeuse &::= typeidx \mid \dots \end{aligned}$$

A heap type is either *abstract* or *concrete*. A concrete heap type consists of a *type use*, which is a [type index](#). It classifies an object of the respective [type](#) defined in a module. Abstract types are denoted by individual keywords.

The type `func` denotes the common supertype of all [function types](#), regardless of their concrete definition. Dually, the type `nofunc` denotes the common subtype of all [function types](#), regardless of their concrete definition. This type has no values.

The type `extern` denotes the common supertype of all external references received through the [embedder](#). This type has no concrete subtypes. Dually, the type `noextern` denotes the common subtype of all forms of external references. This type has no values.

The type `any` denotes the common supertype of all aggregate types, as well as possibly abstract values produced by *internalizing* an external reference of type `extern`. Dually, the type `none` denotes the common subtype of all forms of aggregate types. This type has no values.

The type `eqt` is a subtype of `any` that includes all types for which references can be compared, i.e., aggregate values and `i31`.

The types `struct` and `array` denote the common supertypes of all [structure](#) and [array](#) aggregates, respectively.

The type `i31` denotes *unboxed scalars*, that is, integers injected into references. Their observable value range is limited to 31 bits.

Note: An `i31` value is not actually allocated in the store, but represented in a way that allows them to be mixed with actual references into the store without ambiguity. Engines need to perform some form of *pointer tagging* to achieve this, which is why one bit is reserved.

Although the types `none`, `nofunc`, and `noextern` are not inhabited by any values, they can be used to form the types of all null [references](#) in their respective hierarchy. For example, `(ref null nofunc)` is the generic type of a null reference compatible with all function reference types.

The syntax of abstract heap types and type uses is [extended](#) with additional forms for the purpose of specifying [validation](#) and [execution](#).

2.3.4 Reference Types

Reference types classify [values](#) that are first-class references to objects in the runtime [store](#).

$$\text{ref type} ::= \text{ref null? } \text{heap type}$$

A reference type is characterised by the [heap type](#) it points to.

In addition, a reference type of the form `ref null ht` is *nullable*, meaning that it can either be a proper reference to `ht` or `null`. Other references are *non-null*.

Reference types are *opaque*, meaning that neither their size nor their bit pattern can be observed. Values of reference type can be stored in [tables](#).

Conventions

- The reference type `anyref` is an abbreviation for `(ref null any)`.
- The reference type `eqref` is an abbreviation for `(ref null eq)`.
- The reference type `i31ref` is an abbreviation for `(ref null i31)`.
- The reference type `structref` is an abbreviation for `(ref null struct)`.
- The reference type `arrayref` is an abbreviation for `(ref null array)`.
- The reference type `funcref` is an abbreviation for `(ref null func)`.
- The reference type `externref` is an abbreviation for `(ref null extern)`.
- The reference type `nullref` is an abbreviation for `(ref null none)`.
- The reference type `nullfuncref` is an abbreviation for `(ref null nofunc)`.
- The reference type `nullexternref` is an abbreviation for `(ref null noextern)`.

2.3.5 Value Types

Value types classify the individual values that WebAssembly code can compute with and the values that a variable accepts. They are either [number types](#), [vector types](#), or [reference types](#).

$$\begin{aligned} \text{const type} &::= \text{num type} \mid \text{vec type} \\ \text{val type} &::= \text{num type} \mid \text{vec type} \mid \text{ref type} \mid \dots \end{aligned}$$

The syntax of value types is [extended](#) with additional forms for the purpose of specifying [validation](#).

Conventions

- The meta variable t ranges over value types or subclasses thereof where clear from context.

2.3.6 Result Types

Result types classify the result of [executing instructions](#) or [functions](#), which is a sequence of values, written with brackets.

$$\text{resulttype} ::= \text{list}(\text{valtype})$$

2.3.7 Function Types

Function types classify the signature of [functions](#), mapping a list of parameters to a list of results. They are also used to classify the inputs and outputs of [instructions](#).

$$\text{functype} ::= \text{resulttype} \rightarrow \text{resulttype}$$

2.3.8 Aggregate Types

Aggregate types describe compound objects consisting of multiple values. These are either *structures* or *arrays*, which both consist of a list of possibly mutable and possibly packed *fields*. Structures are heterogeneous, but require static indexing, while arrays need to be homogeneous, but allow dynamic indexing.

$$\begin{aligned} \text{structtype} &::= \text{list}(\text{fieldtype}) \\ \text{arraytype} &::= \text{fieldtype} \\ \text{fieldtype} &::= \text{mut}^? \text{ storagetype} \\ \text{storagetype} &::= \text{valtype} \mid \text{packtype} \\ \text{packtype} &::= \text{i8} \mid \text{i16} \end{aligned}$$

Conventions

- The notation $|t|$ for [bit width](#) extends to packed types as well, that is, $|\text{i8}| = 8$ and $|\text{i16}| = 16$.
- The auxiliary function [unpack](#) maps a storage type to the [value type](#) obtained when accessing a field:

$$\begin{aligned} \text{unpack}(\text{valtype}) &= \text{valtype} \\ \text{unpack}(\text{packtype}) &= \text{i32} \end{aligned}$$

2.3.9 Composite Types

Composite types are all types composed from simpler types, including [function types](#) and [aggregate types](#).

$$\begin{aligned} \text{comptype} &::= \text{struct } \text{structtype} \\ &\mid \text{array } \text{arraytype} \\ &\mid \text{func } \text{functype} \end{aligned}$$

2.3.10 Recursive Types

Recursive types denote a group of mutually recursive [composite types](#), each of which can optionally declare a list of [type indices](#) of supertypes that it [matches](#). Each type can also be declared *final*, preventing further subtyping.

$$\begin{aligned} \text{rectype} &::= \text{rec list}(\text{subtype}) \\ \text{subtype} &::= \text{sub final? typeuse}^* \text{comptype} \end{aligned}$$

In a [module](#), each member of a recursive type is assigned a separate [type index](#).

2.3.11 Limits

Limits classify the size range of resizable storage associated with [memory types](#) and [table types](#).

$$\text{limits} ::= [\text{u32} .. \text{u32}]$$

2.3.12 Memory Types

Memory types classify linear [memories](#) and their size range.

$$\text{memtype} ::= \text{limits page}$$

The limits constrain the minimum and optionally the maximum size of a memory. The limits are given in units of [page size](#).

2.3.13 Table Types

Table types classify [tables](#) over elements of [reference type](#) within a size range.

$$\text{tabletype} ::= \text{limits reftype}$$

Like memories, tables are constrained by limits for their minimum and optionally maximum size. The limits are given in numbers of entries.

2.3.14 Global Types

Global types classify [global](#) variables, which hold a value and can either be mutable or immutable.

$$\text{globaltype} ::= \text{mut? valtype}$$

2.3.15 Element Types

Element types classify [element segments](#) by a [reference type](#) of its elements.

$$\text{elemtype} ::= \text{reftype}$$

2.3.16 Data Types

Data types classify [data segments](#). Since the contents of a data segment requires no further classification, they merely consist of a universal marker `ok` indicating well-formedness.

$$datatype ::= ok$$

2.3.17 External Types

External types classify [imports](#) and [external values](#) with their respective types.

$$externtype ::= func\ typeuse \mid global\ globaltype \mid table\ tabletype \mid mem\ memtype$$

Conventions

The following auxiliary notation is defined for sequences of external types. It filters out entries of a specific kind in an order-preserving fashion:

$funcs(\epsilon)$	$=$	ϵ	
$funcs((func\ dt)\ xt^*)$	$=$	$dt\ funcs(xt^*)$	
$funcs(externtype\ xt^*)$	$=$	$funcs(xt^*)$	otherwise
$tables(\epsilon)$	$=$	ϵ	
$tables((table\ tt)\ xt^*)$	$=$	$tt\ tables(xt^*)$	
$tables(externtype\ xt^*)$	$=$	$tables(xt^*)$	otherwise
$mems(\epsilon)$	$=$	ϵ	
$mems((mem\ mt)\ xt^*)$	$=$	$mt\ mems(xt^*)$	
$mems(externtype\ xt^*)$	$=$	$mems(xt^*)$	otherwise
$globals(\epsilon)$	$=$	ϵ	
$globals((global\ gt)\ xt^*)$	$=$	$gt\ globals(xt^*)$	
$globals(externtype\ xt^*)$	$=$	$globals(xt^*)$	otherwise

2.4 Instructions

WebAssembly code consists of sequences of *instructions*. Its computational model is based on a *stack machine* in that instructions manipulate values on an implicit *operand stack*, consuming (popping) argument values and producing or returning (pushing) result values.

In addition to dynamic operands from the stack, some instructions also have static *immediate* arguments, typically [indices](#) or type annotations, which are part of the instruction itself.

Some instructions are [structured](#) in that they contain nested sequences of instructions.

The following sections group instructions into a number of different categories.

The syntax of instruction is further [extended](#) with additional forms for the purpose of specifying [execution](#).

2.4.1 Parametric Instructions

Instructions in this group can operate on operands of any [value type](#).

```

instr ::= nop
      | unreachable
      | drop
      | select (valtype*)?
      | ...

```

The nop instruction does nothing.

The unreachable instruction causes an unconditional [trap](#).

The drop instruction simply throws away a single operand.

The select instruction selects one of its first two operands based on whether its third operand is zero or not. It may include a [value type](#) determining the type of these operands. If missing, the operands must be of [numeric type](#).

Note: In future versions of WebAssembly, the type annotation on select may allow for more than a single value being selected at the same time.

2.4.2 Numeric Instructions

Numeric instructions provide basic operations over numeric [values](#) of specific [type](#). These operations closely match respective operations available in hardware.

```

sz ::= 8 | 16 | 32 | 64
sx ::= u | s
numiN ::= iN
numfN ::= fN
instr ::= ...
      | numtype.const numnumtype
      | numtype.unopnumtype
      | numtype.binopnumtype
      | numtype.testopnumtype
      | numtype.relopnumtype
      | numtype1.cvtopnumtype2(numtype1)_numtype2-sx?   if numtype1 ≠ numtype2
      | ...
unopiN ::= clz | ctz | popcnt | extendsz_s                  if sz < N
unopfN ::= abs | neg | sqrt | ceil | floor | trunc | nearest
binopiN ::= add | sub | mul | divsx | remsx
      | and | or | xor | shl | shrsx | rotl | rotr
binopfN ::= add | sub | mul | div | min | max | copysign
testopiN ::= eqz
relopiN ::= eq | ne | ltsx | gtsx | lesx | gesx
relopfN ::= eq | ne | lt | gt | le | ge
cvtopnumtype1(numtype2) ::= convert
      | convert_sat                                          if numtype1 = iN ∧ numtype2 = f
      | reinterpret                                          if |numtype1| ≠ |numtype2|

```

Numeric instructions are divided by [number type](#). For each type, several subcategories can be distinguished:

- *Constants*: return a static constant.
- *Unary Operations*: consume one operand and produce one result of the respective type.
- *Binary Operations*: consume two operands and produce one result of the respective type.

- *Tests*: consume one operand of the respective type and produce a Boolean integer result.
- *Comparisons*: consume two operands of the respective type and produce a Boolean integer result.
- *Conversions*: consume a value of one type and produce a result of another (the source type of the conversion is the one after the “_”).

Some integer instructions come in two flavors, where a signedness annotation *sx* distinguishes whether the operands are to be interpreted as *unsigned* or *signed* integers. For the other integer instructions, the use of two’s complement for the signed interpretation means that they behave the same regardless of signedness.

2.4.3 Vector Instructions

Vector instructions (also known as *SIMD* instructions, *single instruction multiple data*) provide basic operations over *values* of *vector* type.

```

lanetype ::= numtype | packtype
dim       ::= 1 | 2 | 4 | 8 | 16
shape     ::= lanetype × dim
ishape    ::= iN × dim
half      ::= low | high
laneidx   ::= us
instr     ::= ...
            | vectype.const vecvectype
            | vectype.vvunop
            | vectype.vvbinop
            | vectype.vvternop
            | vectype.vvtestop
            | shape.vunopshape
            | shape.vbinopshape
            | shape.vtestopshape
            | shape.vrelopshape
            | ishape.vshiftopishape
            | ishape.bitmask
            | ishape.swizzle
            | ishape.shuffle laneidx*
            | ishape1.vertunopishape1—ishape2—sx
            | ishape1.vertbinopishape1—ishape2—sx
            | ishape1.narrowishape2—sx
            | shape1.vcvtshape2,shape1—sx?—shape2—halfshape2(shape1)?
            | shape.splat
            | shape.extract_lanesx? laneidx
            | shape.replace_lane laneidx
            | ...

```

if *ishape* = i8x16
if *ishape* = i8x16 ∧ |*laneidx**| = 16
if |lanetype(*ishape*₁)| = 2 · |lanetype(*ishape*₂)|
if |lanetype(*ishape*₁)| = 2 · |lanetype(*ishape*₂)|
if |lanetype(*ishape*₂)| = 2 · |lanetype(*ishape*₁)|
if lanetype(*shape*₁) ≠ lanetype(*shape*₂)
if lanetype(*shape*) = numtype ⇔ *sx*[?] = *ε*

$vvunop$::=	not	
$vbinop$::=	and andnot or xor	
$vternop$::=	bitselect	
$vtestop$::=	any_true	
$vunop_{iN \times M}$::=	abs neg popcnt	if $N = 8$
$vunop_{fN \times M}$::=	abs neg sqrt ceil floor trunc nearest	
$vbinop_{iN \times M}$::=	add sub add_sat_ sx sub_sat_ sx mul avgr_u q15mulr_sat_s min_ sx max_ sx	if $N \leq 16$ if $N \leq 16$ if $N \geq 16$ if $N \leq 16$ if $N = 16$ if $N \leq 32$ if $N \leq 32$
$vbinop_{fN \times M}$::=	add sub mul div min max pmin pmax	
$vtestop_{iN \times M}$::=	all_true	
$vrelop_{iN \times M}$::=	eq ne lt_ sx gt_ sx le_ sx ge_ sx	if $N \neq 64 \vee sx = s$ if $N \neq 64 \vee sx = s$ if $N \neq 64 \vee sx = s$ if $N \neq 64 \vee sx = s$
$vrelop_{fN \times M}$::=	eq ne lt gt le ge	
$vshifto_{iN \times M}$::=	shl shr_ sx	
$vextunop_{iN \times M}$::=	extadd_pairwise	if $16 \leq N \leq 32$
$vextbinop_{iN \times M}$::=	extmul_half dot	if $N = 32$
$vcvtop_{iN_1 \times M_1, iN_2 \times M_2}$::=	extend	if $N_2 = 2 \cdot N_1$
$vcvtop_{iN_1 \times M_1, fN_2 \times M_2}$::=	convert	if $N_2 \geq N_1 = 32$
$vcvtop_{fN_1 \times M_1, iN_2 \times M_2}$::=	trunc_sat	if $N_1 \geq N_2 = 32$
$vcvtop_{fN_1 \times M_1, fN_2 \times M_2}$::=	demote promote	if $N_1 > N_2$ if $N_1 < N_2$

Vector instructions have a naming convention involving a prefix that determines how their operands will be interpreted. This prefix describes the *shape* of the operand, written $t \times N$, and consisting of a *lane type* t , a possibly *packed numeric type*, and the number of *lanes* N of that type. Operations are performed point-wise on the values of each lane.

Note: For example, the shape $i32 \times 4$ interprets the operand as four $i32$ values, packed into an $i128$. The bit width of the lane type t times N always is 128.

Instructions prefixed with $v128$ do not involve a specific interpretation, and treat the $v128$ as either an $i128$ value or a vector of 128 individual bits.

Vector instructions can be grouped into several subcategories:

- *Constants*: return a static constant.
- *Unary Operations*: consume one $v128$ operand and produce one $v128$ result.
- *Binary Operations*: consume two $v128$ operands and produce one $v128$ result.
- *Ternary Operations*: consume three $v128$ operands and produce one $v128$ result.
- *Tests*: consume one $v128$ operand and produce a Boolean integer result.
- *Shifts*: consume a $v128$ operand and an $i32$ operand, producing one $v128$ result.

- *Splats*: consume a value of numeric type and produce a v128 result of a specified shape.
- *Extract lanes*: consume a v128 operand and return the numeric value in a given lane.
- *Replace lanes*: consume a v128 operand and a numeric value for a given lane, and produce a v128 result.

Some vector instructions have a signedness annotation *sx* which distinguishes whether the elements in the operands are to be interpreted as [unsigned](#) or [signed](#) integers. For the other vector instructions, the use of two's complement for the signed interpretation means that they behave the same regardless of signedness.

Conventions

- The function `lanetype(shape)` extracts the lane type of a shape.
- The function `dim(shape)` extracts the dimension of a shape.

2.4.4 Reference Instructions

Instructions in this group are concerned with accessing [references](#).

```
instr ::= ...  
        | ref.func funcidx  
        | ref.null heaptype  
        | ref.is_null  
        | ref.as_non_null  
        | ref.eq  
        | ref.test reftype  
        | ref.cast reftype  
        | ...
```

The `ref.null` and `ref.func` instructions produce a [null](#) value or a reference to a given function, respectively.

The instruction `ref.is_null` checks for null, while `ref.as_non_null` converts a [nullable](#) to a non-null one, and [traps](#) if it encounters null.

The `ref.eq` compares two references.

The instructions `ref.test` and `ref.cast` test the [dynamic type](#) of a reference operand. The former merely returns the result of the test, while the latter performs a downcast and [traps](#) if the operand's type does not match.

Note: The `br_on_null` and `br_on_non_null` instructions provide versions of `ref.as_null` that branch depending on the success or failure of a null test instead of trapping. Similarly, the `br_on_cast` and `br_on_cast_fail` instructions provide versions of `ref.cast` that branch depending on the success of the downcast instead of trapping.

An additional instruction operating on function references is the [control instruction](#) `call_ref`.

2.4.5 Aggregate Instructions

Instructions in this group are concerned with creating and accessing [references](#) to [aggregate](#) types.

```

instr ::= ...
        | struct.new typeidx
        | struct.new_default typeidx
        | struct.get_sx? typeidx u32
        | struct.set typeidx u32
        | array.new typeidx
        | array.new_default typeidx
        | array.new_fixed typeidx u32
        | array.new_data typeidx dataidx
        | array.new_elem typeidx elemidx
        | array.get_sx? typeidx
        | array.set typeidx
        | array.len
        | array.fill typeidx
        | array.copy typeidx typeidx
        | array.init_data typeidx dataidx
        | array.init_elem typeidx elemidx
        | ref.i31
        | i31.get_sx
        | extern.convert_any
        | any.convert_extern
        | ...

```

The instructions `struct.new` and `struct.new_default` allocate a new [structure](#), initializing them either with operands or with default values. The remaining instructions on structs access individual fields, allowing for different sign extension modes in the case of [packed](#) storage types.

Similarly, [arrays](#) can be allocated either with an explicit initialization operand or a default value. Furthermore, `array.new_fixed` allocates an array with statically fixed size, and `array.new_data` and `array.new_elem` allocate an array and initialize it from a [data](#) or [element](#) segment, respectively. The instructions `array.get`, `array.get sx`, and `array.set` access individual slots, again allowing for different sign extension modes in the case of a [packed](#) storage type; `array.len` produces the length of an array; `array.fill` fills a specified slice of an array with a given value and `array.copy`, `array.init_data`, and `array.init_elem` copy elements to a specified slice of an array from a given array, data segment, or element segment, respectively.

The instructions `ref.i31` and `i31.get sx` convert between type `i32` and an unboxed [scalar](#).

The instructions `any.convert_extern` and `extern.convert_any` allow lossless conversion between references represented as type `(ref null extern)` and as `(ref null any)`.

2.4.6 Variable Instructions

Variable instructions are concerned with access to [local](#) or [global](#) variables.

```

instr ::= ...
        | local.get localidx
        | local.set localidx
        | local.tee localidx
        | global.get globalidx
        | global.set globalidx
        | ...

```

These instructions get or set the values of respective variables. The `local.tee` instruction is like `local.set` but also returns its argument.

2.4.7 Table Instructions

Instructions in this group are concerned with tables `table`.

```

instr ::= ...
        | table.get tableidx
        | table.set tableidx
        | table.size tableidx
        | table.grow tableidx
        | table.fill tableidx
        | table.copy tableidx tableidx
        | table.init tableidx elemidx
        | elem.drop elemidx
        | ...

```

The `table.get` and `table.set` instructions load or store an element in a table, respectively.

The `table.size` instruction returns the current size of a table. The `table.grow` instruction grows table by a given delta and returns the previous size, or -1 if enough space cannot be allocated. It also takes an initialization value for the newly allocated entries.

The `table.fill` instruction sets all entries in a range to a given value. The `table.copy` instruction copies elements from a source table region to a possibly overlapping destination region; the first index denotes the destination. The `table.init` instruction copies elements from a [passive element segment](#) into a table.

The `elem.drop` instruction prevents further use of a passive element segment. This instruction is intended to be used as an optimization hint. After an element segment is dropped its elements can no longer be retrieved, so the memory used by this segment may be freed.

Note: An additional instruction that accesses a table is the [control instruction](#) `call_indirect`.

2.4.8 Memory Instructions

Instructions in this group are concerned with linear [memory](#).

```

memarg ::= {align u32, offset u32}
loadopiN ::= sz sz                                     if sz < N
vloadopvectype ::= szxM sz                               if sz · M = |vectype|/2
                  | sz_splat
                  | sz_zero                               if sz ≥ 32
instr ::= ...
        | numtype.loadloadopnumtype? memidx memarg
        | numtype.storesz? memidx memarg
        | vectype.loadvloadopvectype? memidx memarg
        | vectype.loadsz_lane memidx memarg laneidx
        | vectype.store memidx memarg
        | vectype.storesz_lane memidx memarg laneidx
        | memory.size memidx
        | memory.grow memidx
        | memory.fill memidx
        | memory.copy memidx memidx
        | memory.init memidx dataidx
        | data.drop dataidx
        | ...

```

Memory is accessed with load and store instructions for the different [number types](#) and [vector types](#) `<syntax-vectype>`. They all take a [memory index](#) and a [memory argument](#) `memarg` that contains an address *offset* and the expected *alignment* (expressed as the exponent of a power of 2).

Integer loads and stores can optionally specify a *storage size* *sz* that is smaller than the *bit width* of the respective value type. In the case of loads, a sign extension mode *sx* is then required to select appropriate behavior.

Vector loads can specify a shape that is half the *bit width* of `v128`. Each lane is half its usual size, and the sign extension mode *sx* then specifies how the smaller lane is extended to the larger lane. Alternatively, vector loads can perform a *splat*, such that only a single lane of the specified storage size is loaded, and the result is duplicated to all lanes.

The static address offset is added to the dynamic address operand, yielding a 33 bit *effective address* that is the zero-based index at which the memory is accessed. All values are read and written in *little endian*¹³ byte order. A *trap* results if any of the accessed memory bytes lies outside the address range implied by the memory's current size.

Note: Future versions of WebAssembly might provide memory instructions with 64 bit address ranges.

The `memory.size` instruction returns the current size of a memory. The `memory.grow` instruction grows a memory by a given delta and returns the previous size, or `-1` if enough memory cannot be allocated. Both instructions operate in units of *page size*.

The `memory.fill` instruction sets all values in a region of a memory to a given byte. The `memory.copy` instruction copies data from a source memory region to a possibly overlapping destination region in another or the same memory; the first index denotes the destination. The `memory.init` instruction copies data from a *passive data segment* into a memory.

The `data.drop` instruction prevents further use of a passive data segment. This instruction is intended to be used as an optimization hint. After a data segment is dropped its data can no longer be retrieved, so the memory used by this segment may be freed.

Note: In the current version of WebAssembly, all memory instructions implicitly operate on *memory index* 0. This restriction may be lifted in future versions.

2.4.9 Control Instructions

Instructions in this group affect the flow of control.

```

blocktype ::= valtype?
              | funcidx

instr ::= ...
          | block blocktype instr*
          | loop blocktype instr*
          | if blocktype instr* else instr*
          | br labelidx
          | br_if labelidx
          | br_table labelidx* labelidx
          | br_on_null labelidx
          | br_on_non_null labelidx
          | br_on_cast labelidx reftype reftype
          | br_on_cast_fail labelidx reftype reftype
          | call funcidx
          | call_ref typeuse
          | call_indirect tableidx typeuse
          | return
          | return_call funcidx
          | return_call_ref typeuse
          | return_call_indirect tableidx typeuse
          | ...

```

¹³ <https://en.wikipedia.org/wiki/Endianness#Little-endian>

The block, loop and if instructions are *structured* instructions. They bracket nested sequences of instructions, called *blocks*, terminated with, or separated by, end or else pseudo-instructions. As the grammar prescribes, they must be well-nested.

A structured instruction can consume *input* and produce *output* on the operand stack according to its annotated *block type*. It is given either as a *type index* that refers to a suitable *function type* reinterpreted as an *instruction type*, or as an optional *value type* inline, which is a shorthand for the instruction type $\epsilon \rightarrow \text{valtype}^?$.

Each structured control instruction introduces an implicit *label*. Labels are targets for branch instructions that reference them with *label indices*. Unlike with other *index spaces*, indexing of labels is relative by nesting depth, that is, label 0 refers to the innermost structured control instruction enclosing the referring branch instruction, while increasing indices refer to those farther out. Consequently, labels can only be referenced from *within* the associated structured control instruction. This also implies that branches can only be directed outwards, “breaking” from the block of the control construct they target. The exact effect depends on that control construct. In case of block or if it is a *forward jump*, resuming execution after the matching end. In case of loop it is a *backward jump* to the beginning of the loop.

Note: This enforces *structured control flow*. Intuitively, a branch targeting a block or if behaves like a break statement in most C-like languages, while a branch targeting a loop behaves like a continue statement.

Branch instructions come in several flavors: *br* performs an unconditional branch, *br_if* performs a conditional branch, and *br_table* performs an indirect branch through an operand indexing into the label list that is an immediate to the instruction, or to a default target if the operand is out of bounds. The *br_on_null* and *br_on_non_null* instructions check whether a reference operand is *null* and branch if that is the case or not the case, respectively. Similarly, *br_on_cast* and *br_on_cast_fail* attempt a downcast on a reference operand and branch if that succeeds, or fails, respectively.

The return instruction is a shortcut for an unconditional branch to the outermost block, which implicitly is the body of the current function. Taking a branch *unwinds* the operand stack up to the height where the targeted structured control instruction was entered. However, branches may additionally consume operands themselves, which they push back on the operand stack after unwinding. Forward branches require operands according to the output of the targeted block’s type, i.e., represent the values produced by the terminated block. Backward branches require operands according to the input of the targeted block’s type, i.e., represent the values consumed by the restarted block.

The call instruction invokes another *function*, consuming the necessary arguments from the stack and returning the result values of the call. The *call_ref* instruction invokes a function indirectly through a *function reference* operand. The *call_indirect* instruction calls a function indirectly through an operand indexing into a *table* that is denoted by a *table index* and must contain *function references*. Since it may contain functions of heterogeneous type, the callee is dynamically checked against the *function type* indexed by the instruction’s second immediate, and the call is aborted with a *trap* if it does not match.

The *return_call*, *return_call_ref*, and *return_call_indirect* instructions are *tail-call* variants of the previous ones. That is, they first return from the current function before actually performing the respective call. It is guaranteed that no sequence of nested calls using only these instructions can cause resource exhaustion due to hitting an *implementation’s limit* on the number of active calls.

2.4.10 Expressions

Function bodies, initialization values for *globals*, elements and offsets of *element* segments, and offsets of *data* segments are given as expressions, which are sequences of *instructions*.

$$\text{expr} ::= \text{instr}^*$$

In some places, validation *restricts* expressions to be *constant*, which limits the set of allowable instructions.

2.5 Modules

WebAssembly programs are organized into *modules*, which are the unit of deployment, loading, and compilation. A module collects definitions for *types*, *functions*, *tables*, *memories*, and *globals*. In addition, it can declare *imports* and *exports* and provide initialization in the form of *data* and *element* segments, or a *start* function.

$$\text{module} ::= \text{module } \text{type}^* \text{ import}^* \text{ func}^* \text{ global}^* \text{ table}^* \text{ mem}^* \text{ elem}^* \text{ data}^* \text{ start}^* \text{ export}^*$$

Each of the lists — and thus the entire module — may be empty.

2.5.1 Indices

Definitions are referenced with zero-based *indices*. Each class of definition has its own *index space*, as distinguished by the following classes.

<i>typeid</i>	::=	<i>u32</i>
<i>funcidx</i>	::=	<i>u32</i>
<i>globalidx</i>	::=	<i>u32</i>
<i>tableidx</i>	::=	<i>u32</i>
<i>memidx</i>	::=	<i>u32</i>
<i>elemidx</i>	::=	<i>u32</i>
<i>dataidx</i>	::=	<i>u32</i>
<i>labelidx</i>	::=	<i>u32</i>
<i>localidx</i>	::=	<i>u32</i>
<i>fieldidx</i>	::=	<i>u32</i>

The index space for *functions*, *tables*, *memories* and *globals* includes respective *imports* declared in the same module. The indices of these imports precede the indices of other definitions in the same index space.

Element indices reference *element segments* and data indices reference *data segments*.

The index space for *locals* is only accessible inside a *function* and includes the parameters of that function, which precede the local variables.

Label indices reference *structured control instructions* inside an instruction sequence.

Each *aggregate type* provides an index space for its *fields*.

Conventions

- The meta variable *l* ranges over label indices.
- The meta variables *x*, *y* range over indices in any of the other index spaces.
- For every index space *abcidx*, the notation *abcidx*(*A*) denotes the set of indices from that index space occurring free in *A*. Sometimes this set is reinterpreted as the *list* of its elements.

Note: For example, if *instr** is *(data.drop 1) (memory.init 2 3)*, then *dataidx(instr*)* = 1 3, or equivalently, the set {1, 3}.

2.5.2 Types

The *type* section of a module defines a list of *recursive types*, each consisting of a list of *sub types* referenced by individual *type indices*. All *function* or *aggregate* types used in a module must be defined in this section.

$$type ::= type\ rectype$$

2.5.3 Functions

The *func* section of a module defines a list of *functions* with the following structure:

$$\begin{aligned} func &::= func\ typeidx\ local^*\ expr \\ local &::= local\ valtype \end{aligned}$$

The *type index* of a function declares its signature by reference to a *function type* defined in the module. The parameters of the function are referenced through 0-based *local indices* in the function's body; they are mutable.

The locals declare a list of mutable local variables and their types. These variables are referenced through *local indices* in the function's body. The index of the first local is the smallest index not referencing a parameter.

A function's *expression* is an *instruction* sequence that represents the body of the function. Upon termination it must produce a stack matching the function type's *result type*.

Functions are referenced through *function indices*, starting with the smallest index not referencing a function *import*.

2.5.4 Tables

The *table* section of a module defines a list of *tables* described by their *table type*:

$$table ::= table\ tabletype\ expr$$

A table is an array of opaque values of a particular *reference type* that is specified by the *table type*. Each table slot is initialized with a value given by a *constant* initializer *expression*. Tables can further be initialized through *element segments*.

The minimum size in the *limits* of the table type specifies the initial size of that table, while its maximum restricts the size to which it can grow later.

Tables are referenced through *table indices*, starting with the smallest index not referencing a table *import*. Most constructs implicitly reference table index 0.

2.5.5 Memories

The *mem* section of a module defines a list of *linear memories* (or *memories* for short) as described by their *memory type*:

$$mem ::= memory\ memtype$$

A memory is a list of raw uninterpreted bytes. The minimum size in the *limits* of its *memory type* specifies the initial size of that memory, while its maximum, if present, restricts the size to which it can grow later. Both are in units of *page size*.

Memories can be initialized through *data segments*.

Memories are referenced through *memory indices*, starting with the smallest index not referencing a memory *import*. Most constructs implicitly reference memory index 0.

2.5.6 Globals

The *global* section of a module defines a list of *global variables* (or *globals* for short):

$$global ::= global\ globaltype\ expr$$

Each global stores a single value of the type specified in the *global type*. It also specifies whether a global is immutable or mutable. Moreover, each global is initialized with a value given by a *constant initializer expression*.

Globals are referenced through *global indices*, starting with the smallest index not referencing a global *import*.

2.5.7 Element Segments

The *elem* section of a module defines a list of *element segments*, which can be used to initialize a subrange of a table from a static *list* of elements.

$$\begin{aligned} elem &::= elem\ reftype\ expr^*\ elemmode \\ elemmode &::= active\ tableidx\ expr \mid passive \mid declare \end{aligned}$$

Each element segment defines a *reference type* and a corresponding list of *constant element expressions*.

Element segments have a mode that identifies them as either *active*, *passive*, or *declarative*. A passive element segment's elements can be copied to a table using the `table.init` instruction. An active element segment copies its elements into a table during *instantiation*, as specified by a *table index* and a *constant expression* defining an offset into that table. A declarative element segment is not available at runtime but merely serves to forward-declare references that are formed in code with instructions like `ref.func`. The offset is given by another *constant expression*.

Element segments are referenced through *element indices*.

2.5.8 Data Segments

The *data* section of a module defines a list of *data segments*, which can be used to initialize a range of memory from a static *list* of *bytes*.

$$\begin{aligned} data &::= data\ byte^*\ datamode \\ datamode &::= active\ memidx\ expr \mid passive \end{aligned}$$

Similar to element segments, data segments have a mode that identifies them as either *active* or *passive*. A passive data segment's contents can be copied into a memory using the `memory.init` instruction. An active data segment copies its contents into a memory during *instantiation*, as specified by a *memory index* and a *constant expression* defining an offset into that memory.

Data segments are referenced through *data indices*.

2.5.9 Start Function

The *start* section of a module declares the *function index* of a *start function* that is automatically invoked when the module is *instantiated*, after *tables* and *memories* have been initialized.

$$start ::= start\ funcidx$$

Note: The start function is intended for initializing the state of a module. The module and its exports are not accessible externally before this initialization has completed.

2.5.10 Exports

The *export* section of a module defines a set of *exports* that become accessible to the host environment once the module has been *instantiated*.

$$\begin{aligned} \text{export} &::= \text{export name externidx} \\ \text{externidx} &::= \text{func funcidx} \mid \text{global globalidx} \mid \text{table tableidx} \mid \text{memory memidx} \end{aligned}$$

Each export is labeled by a unique *name*. Exportable definitions are *functions*, *tables*, *memories*, and *globals*, which are referenced through a respective index.

Conventions

The following auxiliary notation is defined for sequences of exports, filtering out indices of a specific kind in an order-preserving fashion:

$$\begin{aligned} \text{funcs}(\epsilon) &= \epsilon \\ \text{funcs}((\text{func } x) \, xx^*) &= x \, \text{funcs}(xx^*) \\ \text{funcs}(\text{externidx } xx^*) &= \text{funcs}(xx^*) && \text{otherwise} \\ \text{tables}(\epsilon) &= \epsilon \\ \text{tables}((\text{table } x) \, xx^*) &= x \, \text{tables}(xx^*) \\ \text{tables}(\text{externidx } xx^*) &= \text{tables}(xx^*) && \text{otherwise} \\ \text{mems}(\epsilon) &= \epsilon \\ \text{mems}((\text{memory } x) \, xx^*) &= x \, \text{mems}(xx^*) \\ \text{mems}(\text{externidx } xx^*) &= \text{mems}(xx^*) && \text{otherwise} \\ \text{globals}(\epsilon) &= \epsilon \\ \text{globals}((\text{global } x) \, xx^*) &= x \, \text{globals}(xx^*) \\ \text{globals}(\text{externidx } xx^*) &= \text{globals}(xx^*) && \text{otherwise} \end{aligned}$$

2.5.11 Imports

The *import* section of a module defines a set of *imports* that are required for *instantiation*.

$$\text{import} ::= \text{import name name externtype}$$

Each import is labeled by a two-level *name* space, consisting of a *module name* and an *item name* for an entity within that module. Importable definitions are *functions*, *tables*, *memories*, and *globals*. Each import is specified by a descriptor with a respective type that a definition provided during instantiation is required to match.

Every import defines an index in the respective *index space*. In each index space, the indices of imports go before the first index of any definition contained in the module itself.

Note: Unlike export names, import names are not necessarily unique. It is possible to import the same module/item name pair multiple times; such imports may even have different type descriptions, including different kinds of entities. A module with such imports can still be instantiated depending on the specifics of how an *embedder* allows resolving and supplying imports. However, embedders are not required to support such overloading, and a WebAssembly module itself cannot implement an overloaded name.

3.1 Conventions

Validation checks that a WebAssembly module is well-formed. Only valid modules can be *instantiated*.

Validity is defined by a *type system* over the *abstract syntax* of a *module* and its contents. For each piece of abstract syntax, there is a typing rule that specifies the constraints that apply to it. All rules are given in two *equivalent* forms:

1. In *prose*, describing the meaning in intuitive form.
2. In *formal notation*, describing the rule in mathematical form.¹⁴

Note: The prose and formal rules are equivalent, so that understanding of the formal notation is *not* required to read this specification. The formalism offers a more concise description in notation that is used widely in programming languages semantics and is readily amenable to mathematical proof.

In both cases, the rules are formulated in a *declarative* manner. That is, they only formulate the constraints, they do not define an algorithm. The skeleton of a sound and complete algorithm for type-checking instruction sequences according to this specification is provided in the *appendix*.

3.1.1 Types

To define the semantics, the definition of some sorts of types is extended to include additional forms. By virtue of not being representable in either the *binary format* or the *text format*, these forms cannot be used in a program; they only occur during *validation* or *execution*.

$$\begin{aligned} \text{valtype} &::= \dots \mid \text{bot} \\ \text{absheapttype} &::= \dots \mid \text{bot} \\ \text{typeuse} &::= \dots \mid \text{deftype} \mid \text{rec } n \end{aligned}$$

The unique *value type* *bot* is a *bottom type* that *matches* all value types. Similarly, *bot* is also used as a bottom type of all *heap types*.

¹⁴ The semantics is derived from the following article: Andreas Haas, Andreas Rossberg, Derek Schuff, Ben Titze, Dan Gohman, Luke Wagner, Alon Zakai, JF Bastien, Michael Holman. *Bringing the Web up to Speed with WebAssembly*¹⁵. Proceedings of the 38th ACM SIGPLAN Conference on Programming Language Design and Implementation (PLDI 2017). ACM 2017.

¹⁵ <https://dl.acm.org/citation.cfm?doid=3062341.3062363>

Note: No validation rule uses bottom types explicitly, but various rules can pick any value or heap type, including bottom. This ensures the existence of [principal types](#), and thus a [validation algorithm](#) without back tracking.

A [type use](#) can consist directly of a [defined type](#). This occurs as the result of [substituting](#) a [type index](#) with its definition.

A type use may also be a *recursive type index*. Such an index refers to the i -th component of a surrounding [recursive type](#). It occurs as the result of [rolling up](#) the definition of a [recursive type](#).

Both extensions affect the occurrence of type uses in concrete [heap types](#), in [sub types](#) and in [instructions](#).

Note: It is an invariant of the semantics that sub types occur only in one of two forms: either as “syntactic” types as in a source module, where all supertypes are type indices, or as “semantic” types, where all supertypes are resolved to either defined types or recursive type indices.

A type of any form is *closed* when it does not contain a heap type that is a [type index](#) or a recursive type index without a surrounding [recursive type](#), i.e., all [type indices](#) have been [substituted](#) with their [defined type](#) and all free recursive type indices have been [unrolled](#).

Note: Recursive type indices are internal to a recursive type. They are distinguished from regular type indices and represented such that two closed types are syntactically equal if and only if they have the same recursive structure.

Convention

- The *difference* $rt_1 \setminus rt_2$ between two [reference types](#) is defined as follows:

$$\begin{aligned} (\text{ref null}_1^? ht_1) \setminus (\text{ref null } ht_2) &= (\text{ref } ht_1) \\ (\text{ref null}_1^? ht_1) \setminus (\text{ref } ht_2) &= (\text{ref null}_1^? ht_1) \end{aligned}$$

Note: This definition computes an approximation of the reference type that is inhabited by all values from rt_1 except those from rt_2 . Since the type system does not have general union types, the definition only affects the presence of null and cannot express the absence of other values.

3.1.2 Defined Types

Defined types denote the individual types defined in a [module](#). Each such type is represented as a projection from the [recursive type](#) group it originates from, indexed by its position in that group.

$$\text{deftype} ::= \text{rectype}.n$$

Defined types do not occur in the [binary](#) or [text](#) format, but are formed by [rolling up](#) the [recursive types](#) defined in a module.

It is hence an invariant of the semantics that all [recursive types](#) occurring in defined types are [rolled up](#).

Conventions

- $t[x^* := dt^*]$ denotes the parallel *substitution* of *type indices* x^* with *defined types* dt^* in type t , provided $|x^*| = |dt^*|$.
- $t[(\text{rec } i)^* := dt^*]$ denotes the parallel substitution of *recursive type indices* $(\text{rec } i)^*$ with *defined types* dt^* in type t , provided $|(\text{rec } i)^*| = |dt^*|$.
- $t[dt^*]$ is shorthand for the substitution $t[x^* := dt^*]$, where $x^* = 0 \dots (|dt^*| - 1)$.

3.1.3 Rolling and Unrolling

In order to allow comparing *recursive types* for *equivalence*, their representation is changed such that all *type indices* internal to the same recursive type are replaced by *recursive type indices*.

Note: This representation is independent of the type index space, so that it is meaningful across module boundaries. Moreover, this representation ensures that types with equivalent recursive structure are also syntactically equal, hence allowing a simple equality check on (closed) types. It gives rise to an *iso-recursive* interpretation of types.

The representation change is performed by two auxiliary operations on the syntax of *recursive types*:

- *Rolling up* a recursive type *substitutes* its internal *type indices* with corresponding *recursive type indices*.
- *Unrolling* a recursive type *substitutes* its *recursive type indices* with the corresponding *defined types*.

These operations are extended to *defined types* and defined as follows:

$$\begin{aligned}
 \text{roll}_x(\text{rectype}) &= \text{rec } (\text{subtype}[(x + i)^{i < n} := (\text{rec } i)^{i < n}])^n && \text{if } \text{rectype} = \text{rec subtype}^n \\
 \text{unroll}(\text{rectype}) &= \text{rec } (\text{subtype}[(\text{rec } i)^{i < n} := (\text{rectype}.i)^{i < n}])^n && \text{if } \text{rectype} = \text{rec subtype}^n \\
 \text{roll}_x^*(\text{rectype}) &= ((\text{rec subtype}^n).i)^{i < n} && \text{if } \text{roll}_x(\text{rectype}) = \text{rec subtype}^n \\
 \text{unroll}(\text{rectype}.i) &= \text{subtype}^*[i] && \text{if } \text{unroll}(\text{rectype}) = \text{rec subtype}^*
 \end{aligned}$$

In addition, the following auxiliary relation denotes the *expansion* of a *defined type*:

$$\text{deftype} \approx \text{comptype} \quad \text{if } \text{unroll}(\text{deftype}) = \text{sub final? } \text{typeuse}^* \text{comptype}$$

3.1.4 Instruction Types

Instruction types classify the behaviour of *instructions* or instruction sequences, by describing how they manipulate the *operand stack* and the initialization status of *locals*:

$$\text{instrtype} ::= \text{resulttype} \rightarrow \text{localidx}^* \text{resulttype}$$

An instruction type $t_1^* \rightarrow (x^*) t_2^*$ describes the required input stack with argument values of types t_1^* that an instruction pops off and the provided output stack with result values of types t_2^* that it pushes back. Moreover, it enumerates the *indices* x^* of locals that have been set by the instruction or sequence.

Note: Instruction types are only used for *validation*, they do not occur in programs.

3.1.5 Local Types

Local types classify *locals*, by describing their *value type* as well as their *initialization status*:

$$\begin{aligned} \text{localtype} &::= \text{init valtype} \\ \text{init} &::= \text{set} \mid \text{unset} \end{aligned}$$

Note: Local types are only used for *validation*, they do not occur in programs.

3.1.6 Contexts

Validity of an individual definition is specified relative to a *context*, which collects relevant information about the surrounding *module* and the definitions in scope:

- *Types*: the list of *types* defined in the current module.
- *Recursive Types*: the list of *sub types* in the current group of recursive types.
- *Functions*: the list of *functions* declared in the current module, represented by a *defined type* that *expands* to their *function type*.
- *Tables*: the list of *tables* declared in the current module, represented by their *table type*.
- *Memories*: the list of *memories* declared in the current module, represented by their *memory type*.
- *Globals*: the list of *globals* declared in the current module, represented by their *global type*.
- *Element Segments*: the list of *element segments* declared in the current module, represented by the elements' *reference type*.
- *Data Segments*: the list of *data segments* declared in the current module, each represented by an *ok* entry.
- *Locals*: the list of *locals* declared in the current *function* (including parameters), represented by their *local type*.
- *Labels*: the stack of *labels* accessible from the current position, represented by their *result type*.
- *Return*: the return type of the current *function*, represented as an optional *result type* that is absent when no return is allowed, as in free-standing expressions.
- *References*: the list of *function indices* that occur in the module outside functions and can hence be used to form references inside them.

In other words, a context contains a sequence of suitable *types* for each *index space*, describing each defined entry in that space. Locals, labels and return type are only used for validating *instructions* in *function bodies*, and are left empty elsewhere. The label stack is the only part of the context that changes as validation of an instruction sequence proceeds.

More concretely, contexts are defined as *records* *C* with abstract syntax:

$$\text{context} ::= \{ \text{types } \text{deftype}^*, \\ \text{recs } \text{subtype}^*, \\ \text{funcs } \text{deftype}^*, \\ \text{globals } \text{globaltype}^*, \\ \text{tables } \text{tabletype}^*, \\ \text{mems } \text{memtype}^*, \\ \text{elems } \text{elemtype}^*, \\ \text{datas } \text{datatype}^*, \\ \text{locals } \text{localtype}^*, \\ \text{labels } \text{resulttype}^*, \\ \text{return } \text{resulttype}^? \}$$

In addition to field access written *C*.field, the following notation is adopted for manipulating contexts:

- When spelling out a context, empty fields are omitted.
- $C, \text{field } A^*$ denotes the same context as C but with the elements A^* prepended to its field component sequence.

Note: [Indexing notation](#) like $C.\text{labels}[i]$ is used to look up indices in their respective [index space](#) in the context. Context extension notation $C, \text{field } A$ is primarily used to locally extend *relative* index spaces, such as [label indices](#). Accordingly, the notation is defined to append at the *front* of the respective sequence, introducing a new relative index 0 and shifting the existing ones.

Convention

A type of any shape can be *closed* to bring it into [closed](#) form relative to a context it is [valid](#) in by [substituting](#) each type index x occurring in it with its own corresponding [defined type](#) $C.\text{types}[x]$, after first closing the the types in $C.\text{types}$ themselves.

$$\begin{aligned} \text{clos}_C(t) &= t[:= dt^*] && \text{if } dt^* = \text{clos}^*(C.\text{types}) \\ \text{clos}^*(\epsilon) &= \epsilon \\ \text{clos}^*(dt^* dt_n) &= dt'^* dt_n[:= dt'^*] && \text{if } dt'^* = \text{clos}^*(dt^*) \end{aligned}$$

3.1.7 Prose Notation

Validation is specified by stylised rules for each relevant part of the [abstract syntax](#). The rules not only state constraints defining when a phrase is valid, they also classify it with a type. The following conventions are adopted in stating these rules.

- A phrase A is said to be “valid with type T ” if and only if all constraints expressed by the respective rules are met. The form of T depends on the syntactic class of A .

Note: For example, if A is a [function](#), then T is a [function type](#); for an A that is a [global](#), T is a [global type](#); and so on.

- The rules implicitly assume a given [context](#) C .
- In some places, this context is locally extended to a context C' with additional entries. The formulation “Under context C' , ... *statement* ...” is adopted to express that the following statement must apply under the assumptions embodied in the extended context.

3.1.8 Formal Notation

Note: This section gives a brief explanation of the notation for specifying typing rules formally. For the interested reader, a more thorough introduction can be found in respective text books.¹⁶

The proposition that a phrase A has a respective type T is written $A : T$. In general, however, typing is dependent on a context C . To express this explicitly, the complete form is a *judgement* $C \vdash A : T$, which says that $A : T$ holds under the assumptions encoded in C .

The formal typing rules use a standard approach for specifying type systems, rendering them into *deduction rules*. Every rule has the following general form:

$$\frac{\text{premise}_1 \quad \text{premise}_2 \quad \dots \quad \text{premise}_n}{\text{conclusion}}$$

¹⁶ For example: Benjamin Pierce. [Types and Programming Languages](#)^{Page 31, 17}. The MIT Press 2002

¹⁷ <https://www.cis.upenn.edu/~bcpierce/tapl/>

Such a rule is read as a big implication: if all premises hold, then the conclusion holds. Some rules have no premises; they are *axioms* whose conclusion holds unconditionally. The conclusion always is a judgment $C \vdash A : T$, and there is one respective rule for each relevant construct A of the abstract syntax.

Note: For example, the typing rule for the `i32.add` instruction can be given as an axiom:

$$\overline{C \vdash \text{i32.add} : \text{i32 } \text{i32} \rightarrow \text{i32}}$$

The instruction is always valid with type $\text{i32 } \text{i32} \rightarrow \text{i32}$ (saying that it consumes two `i32` values and produces one), independent of any side conditions.

An instruction like `global.get` can be typed as follows:

$$\frac{C.\text{globals}[x] = \text{mut}^? t}{C \vdash \text{global.get } x : \epsilon \rightarrow t}$$

Here, the premise enforces that the immediate `global index` x exists in the context. The instruction produces a value of its respective type t (and does not consume any values). If $C.\text{globals}[x]$ does not exist then the premise does not hold, and the instruction is ill-typed.

Finally, a `structured` instruction requires a recursive rule, where the premise is itself a typing judgement:

$$\frac{C \vdash \text{blocktype} : t_1^* \rightarrow t_2^* \quad C, \text{labels } (t_2^*) \vdash \text{instr}^* : t_1^* \rightarrow t_2^*}{C \vdash \text{block } \text{blocktype } \text{instr}^* : t_1^* \rightarrow t_2^*}$$

A block instruction is only valid when the instruction sequence in its body is. Moreover, the result type must match the block's annotation `blocktype`. If so, then the block instruction has the same type as the body. Inside the body an additional label of the corresponding result type is available, which is expressed by extending the context C with the additional label information for the premise.

3.2 Types

Simple `types`, such as `number types` are universally valid. However, restrictions apply to most other types, such as `reference types`, `function types`, as well as the `limits` of `table types` and `memory types`, which must be checked during validation.

Moreover, `block types` are converted to plain `function types` for ease of processing.

3.2.1 Number Types

`Number types` are always valid.

$$\overline{C \vdash \text{numtype} : \text{ok}}$$

3.2.2 Vector Types

`Vector types` are always valid.

$$\overline{C \vdash \text{vectype} : \text{ok}}$$

3.2.3 Heap Types

Concrete **Heap** types are only valid when the **type index** is.

absheaptypes

- The heap type is valid.

$$\overline{C \vdash \text{absheaptypes} : \text{ok}}$$

typeid

- The type $C.\text{types}[\text{typeid}]$ must be defined in the context.
- Then the heap type is valid.

$$\frac{C.\text{types}[\text{typeid}] = dt}{C \vdash \text{typeid} : \text{ok}}$$

3.2.4 Reference Types

Reference types are valid when the referenced **heap type** is.

ref null? heaptypes

- The heap type *heaptypes* must be **valid**.
- Then the reference type is valid.

$$\frac{C \vdash \text{heaptypes} : \text{ok}}{C \vdash \text{ref null? heaptypes} : \text{ok}}$$

3.2.5 Value Types

Valid **value types** are either valid **number types**, valid **vector types**, or valid **reference types**.

3.2.6 Block Types

Block types may be expressed in one of two forms, both of which are converted to **instruction types** by the following rules.

typeid

- The type $C.\text{types}[\text{typeid}]$ must be defined in the context.
- The expansion of $C.\text{funcs}[\text{typeid}]$ must be a function type $\text{func } [t_1^*] \rightarrow [t_2^*]$.
- Then the block type is valid as **instruction type** $[t_1^*] \rightarrow [t_2^*]$.

$$\frac{C.\text{types}[\text{typeid}] \approx \text{func } (t_1^* \rightarrow t_2^*)}{C \vdash \text{typeid} : t_1^* \rightarrow t_2^*}$$

$[valtype^?]$

- The value type $valtype$ must either be absent, or valid.
- Then the block type is valid as instruction type $[] \rightarrow [valtype^?]$.

$$\frac{(C \vdash valtype : ok)^?}{C \vdash valtype^? : \epsilon \rightarrow valtype^?}$$

3.2.7 Result Types

$[t^*]$

- Each value type t_i in the type sequence t^* must be valid.
- Then the result type is valid.

$$\frac{(C \vdash t : ok)^*}{C \vdash t^* : ok}$$

3.2.8 Instruction Types

$[t_1^*] \rightarrow_{x^*} [t_2^*]$

- The result type $[t_1^*]$ must be valid.
- The result type $[t_2^*]$ must be valid.
- Each local index x_i in x^* must be defined in the context.
- Then the instruction type is valid.

$$\frac{C \vdash t_1^* : ok \quad C \vdash t_2^* : ok \quad (C.local[x] = lt)^*}{C \vdash t_1^* \rightarrow (x^*) t_2^* : ok}$$

3.2.9 Function Types

$[t_1^*] \rightarrow [t_2^*]$

- The result type $[t_1^*]$ must be valid.
- The result type $[t_2^*]$ must be valid.
- Then the function type is valid.

$$\frac{C \vdash t_1^* : ok \quad C \vdash t_2^* : ok}{C \vdash t_1^* \rightarrow t_2^* : ok}$$

3.2.10 Composite Types

func functype

- The function type *functype* must be valid.
- Then the composite type is valid.

$$\frac{C \vdash \text{functype} : \text{ok}}{C \vdash \text{func functype} : \text{ok}}$$

*struct fieldtype**

- For each field type *fieldtype_i* in *fieldtype**:
 - The field type *fieldtype_i* must be valid.
- Then the composite type is valid.

$$\frac{(C \vdash \text{fieldtype} : \text{ok})^*}{C \vdash \text{struct fieldtype}^* : \text{ok}}$$

array fieldtype

- The field type *fieldtype* must be valid.
- Then the composite type is valid.

$$\frac{C \vdash \text{fieldtype} : \text{ok}}{C \vdash \text{array fieldtype} : \text{ok}}$$

3.2.11 Field Types

mut storagetype

- The storage type *storagetype* must be valid.
- Then the field type is valid.

$$\frac{C \vdash \text{storagetype} : \text{ok}}{C \vdash \text{mut}^? \text{ storagetype} : \text{ok}}$$

packtype

- The packed type is valid.

$$\overline{C \vdash \text{packtype} : \text{ok}}$$

3.2.12 Recursive Types

Recursive types are validated for a specific *type index* that denotes the index of the type defined by the recursive group.

*rec subtype**

- Either the sequence *subtype** is empty.
- Or:
 - The first *sub type* of the sequence *subtype** must be *valid* for the *type index* *x*.
 - The remaining sequence *subtype** must be *valid* for the *type index* *x + 1*.
- Then the recursive type is valid for the *type index* *x*.

$$\frac{}{C \vdash \text{rec } \epsilon : \text{ok}(x)} \quad \frac{C \vdash \text{subtype}_1 : \text{ok}(x) \quad C \vdash \text{rec } \text{subtype}^* : \text{ok}(x+1)}{C \vdash \text{rec } (\text{subtype}_1 \text{ subtype}^*) : \text{ok}(x)}$$

sub final? y comptime*

- The *composite type* *comptime* must be *valid*.
- The sequence *y** may be no longer than 1.
- For every *type index* *y_i* in *y**:
 - The *type index* *y_i* must be smaller than *x*.
 - The *type index* *y_i* must exist in the context *C*.
 - Let *subtype_i* be the *unrolling* of the *defined type* *C.types[y_i]*.
 - The *sub type* *subtype_i* must not contain *final*.
 - Let *comptime'_i* be the *composite type* in *subtype_i*.
 - The *composite type* *comptime* must *match* *comptime'_i*.
- Then the sub type is valid for the *type index* *x*.

$$\frac{|x^*| \leq 1 \quad (x < x_0)^* \quad (\text{unroll}(C.\text{types}[x]) = \text{sub } x'^* \text{ comptime}')^* \quad C \vdash \text{comptime} : \text{ok} \quad (C \vdash \text{comptime} \leq \text{comptime}')^*}{C \vdash \text{sub final? } \text{typeid}x^* \text{ comptime} : \text{ok}(x_0)}$$

Note: The side condition on the index ensures that a declared supertype is a previously defined types, preventing cyclic subtype hierarchies.

Future versions of WebAssembly may allow more than one supertype.

3.2.13 Defined Types

rectype.i

- The *recursive type* *rectype* must be *valid* for some *type index* *x*.
- Let *rec subtype** be the *defined type* *rectype*.
- The number *i* must be smaller than the length of the sequence *subtype** of *sub types*.
- Then the defined type is *valid*.

$$\frac{C \vdash \text{rectype} : \text{ok}(x) \quad \text{rectype} = \text{rec subtype}^n \quad i < n}{C \vdash \text{rectype}.i : \text{ok}}$$

3.2.14 Limits

Limits must have meaningful bounds that are within a given range.

$\{\min n, \max m^?\}$

- The value of n must not be larger than k .
- If the maximum $m^?$ is not empty, then:
 - Its value must not be larger than k .
 - Its value must not be smaller than n .
- Then the limit is valid within range k .

$$\frac{n \leq m \leq k}{C \vdash [n..m] : k}$$

3.2.15 Table Types

limits reftype

- The limits *limits* must be **valid** within range $2^{32} - 1$.
- The reference type *reftype* must be **valid**.
- Then the table type is valid.

$$\frac{C \vdash \text{limits} : 2^{32} - 1 \quad C \vdash \text{reftype} : \text{ok}}{C \vdash \text{limits reftype} : \text{ok}}$$

3.2.16 Memory Types

limits

- The limits *limits* must be **valid** within range 2^{16} .
- Then the memory type is valid.

$$\frac{C \vdash \text{limits} : 2^{16}}{C \vdash \text{limits page} : \text{ok}}$$

3.2.17 Global Types

mut valtype

- The value type *valtype* must be valid.
- Then the global type is valid.

$$\frac{C \vdash t : \text{ok}}{C \vdash \text{mut}^? t : \text{ok}}$$

3.2.18 External Types

func deftype

- The defined type *deftype* must be valid.
- The defined type *deftype* must be a function type.
- Then the external type is valid.

$$\frac{C \vdash \text{deftype} : \text{ok} \quad \text{deftype} \approx \text{func functype}}{C \vdash \text{func deftype} : \text{ok}}$$

table tabletype

- The table type *tabletype* must be valid.
- Then the external type is valid.

$$\frac{C \vdash \text{tabletype} : \text{ok}}{C \vdash \text{table tabletype} : \text{ok}}$$

mem memtype

- The memory type *memtype* must be valid.
- Then the external type is valid.

$$\frac{C \vdash \text{memtype} : \text{ok}}{C \vdash \text{mem memtype} : \text{ok}}$$

global globaltype

- The global type *globaltype* must be valid.
- Then the external type is valid.

$$\frac{C \vdash \text{globaltype} : \text{ok}}{C \vdash \text{global globaltype} : \text{ok}}$$

3.3 Matching

On most types, a notion of *subtyping* is defined that is applicable in [validation](#) rules, during [module instantiation](#) when checking the types of imports, or during [execution](#), when performing casts.

3.3.1 Number Types

A number type $numtype_1$ matches a number type $numtype_2$ if and only if:

- Both $numtype_1$ and $numtype_2$ are the same.

$$\overline{C \vdash numtype \leq numtype}$$

3.3.2 Vector Types

A vector type $vectype_1$ matches a vector type $vectype_2$ if and only if:

- Both $vectype_1$ and $vectype_2$ are the same.

$$\overline{C \vdash vectype \leq vectype}$$

3.3.3 Heap Types

A heap type $heaptypes_1$ matches a heap type $heaptypes_2$ if and only if:

- Either both $heaptypes_1$ and $heaptypes_2$ are the same.
- Or there exists a valid heap type $heaptypes'$, such that $heaptypes_1$ matches $heaptypes'$ and $heaptypes'$ matches $heaptypes_2$.
- Or $heaptypes_1$ is `eq` and $heaptypes_2$ is `any`.
- Or $heaptypes_1$ is one of `i31`, `struct`, or `array` and $heaptypes_2$ is `eq`.
- Or $heaptypes_1$ is a defined type which expands to a structure type and $heaptypes_2$ is `struct`.
- Or $heaptypes_1$ is a defined type which expands to an array type and $heaptypes_2$ is `array`.
- Or $heaptypes_1$ is a defined type which expands to a function type and $heaptypes_2$ is `func`.
- Or $heaptypes_1$ is a defined type $deftype_1$ and $heaptypes_2$ is a defined type $deftype_2$, and $deftype_1$ matches $deftype_2$.
- Or $heaptypes_1$ is a type index x_1 , and the defined type $C.types[x_1]$ matches $heaptypes_2$.
- Or $heaptypes_2$ is a type index x_2 , and $heaptypes_1$ matches the defined type $C.types[x_2]$.
- Or $heaptypes_1$ is `none` and $heaptypes_2$ matches `any`.
- Or $heaptypes_1$ is `nofunc` and $heaptypes_2$ matches `func`.
- Or $heaptypes_1$ is `noextern` and $heaptypes_2$ matches `extern`.
- Or $heaptypes_1$ is `bot`.

$$\begin{array}{c}
\frac{}{C \vdash \text{heapt} \leq \text{heapt}} \quad \frac{C \vdash \text{heapt}' : \text{ok} \quad C \vdash \text{heapt}_1 \leq \text{heapt}' \quad C \vdash \text{heapt}' \leq \text{heapt}_2}{C \vdash \text{heapt}_1 \leq \text{heapt}_2} \\
\\
\frac{}{C \vdash \text{eq} \leq \text{any}} \quad \frac{}{C \vdash \text{i31} \leq \text{eq}} \quad \frac{}{C \vdash \text{struct} \leq \text{eq}} \quad \frac{}{C \vdash \text{array} \leq \text{eq}} \\
\frac{\text{deft} \approx \text{struct } \text{fieldt}^*}{C \vdash \text{deft} \leq \text{struct}} \quad \frac{\text{deft} \approx \text{array } \text{fieldt}}{C \vdash \text{deft} \leq \text{array}} \quad \frac{\text{deft} \approx \text{func } \text{funct}}{C \vdash \text{deft} \leq \text{func}} \\
\frac{C \vdash C.\text{types}[\text{typeid}] \leq \text{heapt}}{C \vdash \text{typeid} \leq \text{heapt}} \quad \frac{C \vdash \text{heapt} \leq C.\text{types}[\text{typeid}]}{C \vdash \text{heapt} \leq \text{typeid}} \\
\frac{C.\text{recs}[i] = \text{sub final? } \text{typeuse}^* \text{ ct}}{C \vdash \text{rec } i \leq \text{typeuse}^*[j]} \\
\frac{C \vdash \text{heapt} \leq \text{any}}{C \vdash \text{none} \leq \text{heapt}} \quad \frac{C \vdash \text{heapt} \leq \text{func}}{C \vdash \text{nofunc} \leq \text{heapt}} \quad \frac{C \vdash \text{heapt} \leq \text{extern}}{C \vdash \text{noextern} \leq \text{heapt}} \\
\frac{}{C \vdash \text{bot} \leq \text{heapt}}
\end{array}$$

3.3.4 Reference Types

A reference type $\text{ref null}_1^? \text{heapt}_1$ matches a reference type $\text{ref null}_2^? \text{heapt}_2$ if and only if:

- The heap type heapt_1 matches heapt_2 .
- null_1 is absent or null_2 is present.

$$\frac{C \vdash \text{ht}_1 \leq \text{ht}_2}{C \vdash \text{ref } \text{ht}_1 \leq \text{ref } \text{ht}_2} \quad \frac{C \vdash \text{ht}_1 \leq \text{ht}_2}{C \vdash \text{ref null? } \text{ht}_1 \leq \text{ref null } \text{ht}_2}$$

3.3.5 Value Types

A value type valtype_1 matches a value type valtype_2 if and only if:

- Either both valtype_1 and valtype_2 are number types and valtype_1 matches valtype_2 .
- Or both valtype_1 and valtype_2 are reference types and valtype_1 matches valtype_2 .
- Or valtype_1 is `bot`.

$$\frac{}{C \vdash \text{bot} \leq \text{valtype}}$$

3.3.6 Result Types

Subtyping is lifted to **result types** in a pointwise manner. That is, a **result type** t_1^* matches a **result type** t_2^* if and only if:

- Every value type t_1 in $[t_1^*]$ matches the corresponding value type t_2 in $[t_2^*]$.

$$\frac{(C \vdash t_1 \leq t_2)^*}{C \vdash t_1^* \leq t_2^*}$$

3.3.7 Instruction Types

Subtyping is further lifted to **instruction types**. An instruction type $t_{11}^* \rightarrow (x_1^*) t_{12}^*$ matches a type $t_{21}^* \rightarrow (x_2^*) t_{22}^*$ if and only if:

- There is a common sequence of **value types** t^* such that t_{21}^* equals $t^* t_{21}'^*$ and t_{22}^* equals $t^* t_{22}'^*$.
- The **result type** $[t_{21}'^*]$ matches $[t_{11}^*]$.
- The **result type** $[t_{12}^*]$ matches $[t_{22}'^*]$.
- For every **local index** x that is in x_2^* but not in x_1^* , the **local type** $C.\text{locals}[x]$ is **set** t_x for some **value type** t_x .

$$\frac{C \vdash t_{21}^* \leq t_{11}^* \quad C \vdash t_{12}^* \leq t_{22}^* \quad x^* = x_2^* \setminus x_1^* \quad (C.\text{locals}[x] = \text{set } t)^*}{C \vdash t_{11}^* \rightarrow (x_1^*) t_{12}^* \leq t_{21}^* \rightarrow (x_2^*) t_{22}^*}$$

Note: Instruction types are contravariant in their input and covariant in their output. Subtyping also incorporates a sort of “frame” condition, which allows adding arbitrary invariant stack elements on both sides in the super type.

Finally, the supertype may ignore variables from the init set x_1^* . It may also *add* variables to the init set, provided these are already set in the context, i.e., are vacuously initialized.

3.3.8 Function Types

A **function type** $t_{11}^* \rightarrow t_{12}^*$ matches a type $t_{21}^* \rightarrow t_{22}^*$ if and only if:

- The **result type** $[t_{21}^*]$ matches $[t_{11}^*]$.
- The **result type** $[t_{12}^*]$ matches $[t_{22}^*]$.

$$\frac{C \vdash t_{21}^* \leq t_{11}^* \quad C \vdash t_{12}^* \leq t_{22}^*}{C \vdash t_{11}^* \rightarrow t_{12}^* \leq t_{21}^* \rightarrow t_{22}^*}$$

3.3.9 Composite Types

A **composite type** comptype_1 matches a type comptype_2 if and only if:

- Either the composite type comptype_1 is **func** functype_1 and comptype_2 is **func** functype_2 and:
 - The function type functype_1 matches functype_2 .
- Or the composite type comptype_1 is **struct** $\text{fieldtype}_1^{n_1}$ and comptype_2 is **struct** fieldtype_2 and:
 - The arity n_1 is greater than or equal to n_2 .
 - For every field type fieldtype_{2i} in $\text{fieldtype}_2^{n_2}$ and corresponding fieldtype_{1i} in $\text{fieldtype}_1^{n_1}$
 - * The field type fieldtype_{1i} matches fieldtype_{2i} .
- Or the composite type comptype_1 is **array** fieldtype_1 and comptype_2 is **array** fieldtype_2 and:
 - The field type fieldtype_1 matches fieldtype_2 .

$$\frac{(C \vdash yt_1 \leq yt_2)^*}{C \vdash \text{struct } (yt_1^* yt_1') \leq \text{struct } yt_2^*} \quad \frac{C \vdash yt_1 \leq yt_2}{C \vdash \text{array } yt_1 \leq \text{array } yt_2} \quad \frac{C \vdash ft_1 \leq ft_2}{C \vdash \text{func } ft_1 \leq \text{func } ft_2}$$

3.3.10 Field Types

A field type $(\text{mut}_1^? \text{storage_type}_1)$ matches a type $(\text{mut}_2^? \text{storage_type}_2)$ if and only if:

- Storage type storage_type_1 matches storage_type_2 .
- Either both mut_1 and mut_2 are `const`.
- Or both mut_1 and mut_2 are `var` and storage_type_2 matches storage_type_1 as well.

$$\frac{C \vdash \text{zt}_1 \leq \text{zt}_2}{C \vdash \text{zt}_1 \leq \text{zt}_2} \quad \frac{C \vdash \text{zt}_1 \leq \text{zt}_2 \quad C \vdash \text{zt}_2 \leq \text{zt}_1}{C \vdash \text{mut } \text{zt}_1 \leq \text{mut } \text{zt}_2}$$

A storage type storage_type_1 matches a type storage_type_2 if and only if:

- Either storage_type_1 is a value type valtype_1 and storage_type_2 is a value type valtype_2 and valtype_1 matches valtype_2 .
- Or storage_type_1 is a packed type packtype_1 and storage_type_2 is a packed type packtype_2 and packtype_1 matches packtype_2 .

A packed type packtype_1 matches a type packtype_2 if and only if:

- The packed type packtype_1 is the same as packtype_2 .

$$\overline{C \vdash \text{packtype} \leq \text{packtype}}$$

3.3.11 Defined Types

A defined type deftype_1 matches a type deftype_2 if and only if:

- Either deftype_1 and deftype_2 are equal when closed under context C .
- Or:
 - Let the sub type $\text{sub final}^? \text{heaptypes}^* \text{comptype}$ be the result of unrolling deftype_1 .
 - Then there must exist a heap type heaptypes_i in heaptypes^* that matches deftype_2 .

$$\frac{\text{clos}_C(\text{deftype}_1) = \text{clos}_C(\text{deftype}_2)}{C \vdash \text{deftype}_1 \leq \text{deftype}_2}$$

$$\frac{\text{unroll}(\text{deftype}_1) = \text{sub final}^? \text{typeuse}^* \text{ct} \quad C \vdash \text{typeuse}^*[i] \leq \text{deftype}_2}{C \vdash \text{deftype}_1 \leq \text{deftype}_2}$$

Note: Note that there is no explicit definition of type *equivalence*, since it coincides with syntactic equality, as used in the premise of the former rule above.

3.3.12 Limits

Limits $[n_1 .. m_1]$ match limits $[n_2 .. m_2]$ if and only if:

- n_1 is larger than or equal to n_2 .
- Either:
 - $m_2^?$ is empty.
- Or:
 - Both $m_1^?$ and $m_2^?$ are non-empty.
 - m_1 is smaller than or equal to m_2 .

$$\frac{n_1 \geq n_2 \quad m_1 \leq m_2}{C \vdash [n_1 .. m_1] \leq [n_2 .. m_2]}$$

3.3.13 Table Types

A table type $(limits_1 \text{ reftype}_1)$ matches $(limits_2 \text{ reftype}_2)$ if and only if:

- Limits $limits_1$ match $limits_2$.
- The reference type $reftype_1$ matches $reftype_2$, and vice versa.

$$\frac{C \vdash limits_1 \leq limits_2 \quad C \vdash reftype_1 \leq reftype_2 \quad C \vdash reftype_2 \leq reftype_1}{C \vdash limits_1 \text{ reftype}_1 \leq limits_2 \text{ reftype}_2}$$

3.3.14 Memory Types

A memory type $(limits_1 \text{ page})$ matches $(limits_2 \text{ page})$ if and only if:

- Limits $limits_1$ match $limits_2$.

$$\frac{C \vdash limits_1 \leq limits_2}{C \vdash limits_1 \text{ page} \leq limits_2 \text{ page}}$$

3.3.15 Global Types

A global type $(mut_1^? \text{ valtype}_1)$ matches $(mut_2^? \text{ valtype}_2)$ if and only if:

- Either both mut_1 and mut_2 are `var` and t_1 matches t_2 and vice versa.
- Or both mut_1 and mut_2 are `const` and t_1 matches t_2 .

$$\frac{C \vdash valtype_1 \leq valtype_2}{C \vdash valtype_1 \leq valtype_2} \quad \frac{C \vdash valtype_1 \leq valtype_2 \quad C \vdash valtype_2 \leq valtype_1}{C \vdash mut \text{ valtype}_1 \leq mut \text{ valtype}_2}$$

3.3.16 External Types

Functions

An external type $\text{func } deftype_1$ matches $\text{func } deftype_2$ if and only if:

- The defined type $deftype_1$ matches $deftype_2$.

$$\frac{C \vdash deftype_1 \leq deftype_2}{C \vdash \text{func } deftype_1 \leq \text{func } deftype_2}$$

Tables

An external type $\text{table } tabletype_1$ matches $\text{table } tabletype_2$ if and only if:

- Table type $tabletype_1$ matches $tabletype_2$.

$$\frac{C \vdash tabletype_1 \leq tabletype_2}{C \vdash \text{table } tabletype_1 \leq \text{table } tabletype_2}$$

Memories

An external type `mem memtype1` matches `mem memtype2` if and only if:

- Memory type `memtype1` matches `memtype2`.

$$\frac{C \vdash \text{memtype}_1 \leq \text{memtype}_2}{C \vdash \text{mem memtype}_1 \leq \text{mem memtype}_2}$$

Globals

An external type `global globaltype1` matches `global globaltype2` if and only if:

- Global type `globaltype1` matches `globaltype2`.

$$\frac{C \vdash \text{globaltype}_1 \leq \text{globaltype}_2}{C \vdash \text{global globaltype}_1 \leq \text{global globaltype}_2}$$

3.4 Instructions

Instructions are classified by **instruction types** that describe how they manipulate the **operand stack** and initialize **locals**: A type $t_1^* \rightarrow (x^*) t_2^*$ describes the required input stack with argument values of types t_1^* that an instruction pops off and the provided output stack with result values of types t_2^* that it pushes back. Moreover, it enumerates the **indices** x^* of locals that have been set by the instruction. In most cases, this is empty.

Note: For example, the instruction `binop i32 add` has type $i32 \ i32 \rightarrow i32$, consuming two `i32` values and producing one. The instruction `local.set x` has type $t \rightarrow (x) \epsilon$, provided t is the type declared for the local x .

Typing extends to **instruction sequences** $instr^*$. Such a sequence has an instruction type $t_1^* \rightarrow (x^*) t_2^*$ if the accumulative effect of executing the instructions is consuming values of types t_1^* off the operand stack, pushing new values of types t_2^* , and setting all locals x^* .

For some instructions, the typing rules do not fully constrain the type, and therefore allow for multiple types. Such instructions are called *polymorphic*. Two degrees of polymorphism can be distinguished:

- value-polymorphic*: the **value type** t of one or several individual operands is unconstrained. That is the case for all **parametric instructions** like `drop` and `select`.
- stack-polymorphic*: the entire (or most of the) **instruction type** $t_1^* \rightarrow t_2^*$ of the instruction is unconstrained. That is the case for all **control instructions** that perform an *unconditional control transfer*, such as `unreachable`, `br`, or `return`.

In both cases, the unconstrained types or type sequences can be chosen arbitrarily, as long as they meet the constraints imposed for the surrounding parts of the program.

Note: For example, the `select` instruction is valid with type $t \ t \ i32 \rightarrow t$, for any possible **number type** t . Consequently, both instruction sequences

(const i32 1) (const i32 2) (const i32 3) select

and

(const f64 1.0) (const f64 2.0) (const f64 3.0) select

are valid, with t in the typing of `select` being instantiated to `i32` or `f64`, respectively.

The `unreachable` instruction is stack-polymorphic, and hence valid with type $t_1^* \rightarrow t_2^*$ for any possible sequences of value types t_1^* and t_2^* . Consequently,

unreachable binop i32 add

is valid by assuming type $\epsilon \rightarrow \text{i32}$ for the unreachable instruction. In contrast,

unreachable (const i64 0) binop i32 add

is invalid, because there is no possible type to pick for the unreachable instruction that would make the sequence well-typed.

The [Appendix](#) describes a type checking [algorithm](#) that efficiently implements validation of instruction sequences as prescribed by the rules given here.

3.4.1 Parametric Instructions

`nop`

- The instruction is valid with type $[] \rightarrow []$.

$$\overline{C \vdash \text{nop} : \epsilon \rightarrow \epsilon}$$

`unreachable`

- The instruction is valid with any [valid](#) type of the form $[t_1^*] \rightarrow [t_2^*]$.

$$\frac{C \vdash t_1^* \rightarrow t_2^* : \text{ok}}{C \vdash \text{unreachable} : t_1^* \rightarrow t_2^*}$$

Note: The unreachable instruction is [stack-polymorphic](#).

`drop`

- The instruction is valid with type $[t] \rightarrow []$, for any [valid value type](#) t .

$$\frac{C \vdash t : \text{ok}}{C \vdash \text{drop} : t \rightarrow \epsilon}$$

Note: Both drop and select without annotation are [value-polymorphic](#) instructions.

`select (t*)?`

- If t^* is present, then:
 - The [result type](#) $[t^*]$ must be [valid](#).
 - The length of t^* must be 1.
 - Then the instruction is valid with type $[t^* \ t^* \ \text{i32}] \rightarrow [t^*]$.
- Else:
 - The instruction is valid with type $[t \ t \ \text{i32}] \rightarrow [t]$, for any [valid value type](#) t that [matches](#) some [number type](#) or [vector type](#).

$$\frac{C \vdash t : \text{ok}}{C \vdash \text{select } t : t \ t \ \text{i32} \rightarrow t} \quad \frac{C \vdash t : \text{ok} \quad C \vdash t \leq t' \quad t' = \text{numtype} \vee t' = \text{vectype}}{C \vdash \text{select} : t \ t \ \text{i32} \rightarrow t}$$

Note: In future versions of WebAssembly, select may allow more than one value per choice.

3.4.2 Numeric Instructions

t.const c

- The instruction is valid with type $[] \rightarrow [t]$.

$$\overline{C \vdash nt.\text{const } c_{nt} : \epsilon \rightarrow nt}$$

t.unop

- The instruction is valid with type $[t] \rightarrow [t]$.

$$\overline{C \vdash nt.\text{unop}_{nt} : nt \rightarrow nt}$$

t.binop

- The instruction is valid with type $[t \ t] \rightarrow [t]$.

$$\overline{C \vdash nt.\text{binop}_{nt} : nt \ nt \rightarrow nt}$$

t.testop

- The instruction is valid with type $[t] \rightarrow [\text{i32}]$.

$$\overline{C \vdash nt.\text{testop}_{nt} : nt \rightarrow \text{i32}}$$

t.relop

- The instruction is valid with type $[t \ t] \rightarrow [\text{i32}]$.

$$\overline{C \vdash nt.\text{relop}_{nt} : nt \ nt \rightarrow \text{i32}}$$

t2.cvtop_t1_sx?

- The instruction is valid with type $[t_1] \rightarrow [t_2]$.

$$\frac{|nt_1| = |nt_2|}{C \vdash nt_1.\text{reinterpret_nt2} : nt_2 \rightarrow nt_1} \quad \frac{sx^? = \epsilon \Leftrightarrow nt_1 = iN_1 \wedge nt_2 = iN_2 \wedge |nt_1| > |nt_2| \vee nt_1 = fN_1 \wedge nt_2 = fN_2}{C \vdash nt_1.\text{convert_nt2_sx}^? : nt_2 \rightarrow nt_1}$$

3.4.3 Reference Instructions

ref.null ht

- The [heap type](#) *ht* must be valid.
- Then the instruction is valid with type $[] \rightarrow [(\text{ref null } ht)]$.

$$\frac{C \vdash ht : \text{ok}}{C \vdash \text{ref.null } ht : \epsilon \rightarrow (\text{ref null } ht)}$$

`ref.func x`

- The function $C.\text{funcs}[x]$ must be defined in the context.
- Let dt be the defined type $C.\text{funcs}[x]$.
- The function index x must be contained in $C.\text{refs}$.
- The instruction is valid with type $[] \rightarrow [(\text{ref } dt)]$.

$$\frac{C.\text{funcs}[x] = dt}{C \vdash \text{ref.func } x : \epsilon \rightarrow (\text{ref } dt)}$$

`ref.is_null`

- The instruction is valid with type $[(\text{ref null } ht)] \rightarrow [\text{i32}]$, for any valid heap type ht .

$$\frac{C \vdash ht : \text{ok}}{C \vdash \text{ref.is_null} : (\text{ref null } ht) \rightarrow \text{i32}}$$

`ref.as_non_null`

- The instruction is valid with type $[(\text{ref null } ht)] \rightarrow [(\text{ref } ht)]$, for any valid heap type ht .

$$\frac{C \vdash ht : \text{ok}}{C \vdash \text{ref.as_non_null} : (\text{ref null } ht) \rightarrow (\text{ref } ht)}$$

`ref.eq`

- The instruction is valid with type $[(\text{ref null eq})(\text{ref null eq})] \rightarrow [\text{i32}]$.

$$C \vdash \text{ref.eq} : (\text{ref null eq}) (\text{ref null eq}) \rightarrow \text{i32}$$

`ref.test rt`

- The reference type rt must be valid.
- Then the instruction is valid with type $[rt'] \rightarrow [\text{i32}]$ for any valid reference type rt' for which rt matches rt' .

$$\frac{C \vdash rt : \text{ok} \quad C \vdash rt' : \text{ok} \quad C \vdash rt \leq rt'}{C \vdash \text{ref.test } rt : rt' \rightarrow \text{i32}}$$

Note: The liberty to pick a supertype rt' allows typing the instruction with the least precise super type of rt as input, that is, the top type in the corresponding heap subtyping hierarchy.

`ref.cast rt`

- The reference type rt must be valid.
- Then the instruction is valid with type $[rt'] \rightarrow [rt]$ for any valid reference type rt' for which rt matches rt' .

$$\frac{C \vdash rt : \text{ok} \quad C \vdash rt' : \text{ok} \quad C \vdash rt \leq rt'}{C \vdash \text{ref.cast } rt : rt' \rightarrow rt}$$

Note: The liberty to pick a supertype rt' allows typing the instruction with the least precise super type of rt as input, that is, the top type in the corresponding heap subtyping hierarchy.

3.4.4 Aggregate Reference Instructions

`struct.new` x

- The defined type $C.types[x]$ must exist.
- The expansion of $C.types[x]$ must be a structure type $\text{struct } fieldtype^*$.
- For each field type $fieldtype_i$ in $fieldtype^*$:
 - Let $fieldtype_i$ be $mut \ storagetype_i$.
 - Let t_i be the value type $\text{unpack}(storagetype_i)$.
- Let t^* be the concatenation of all t_i .
- Then the instruction is valid with type $[t^*] \rightarrow [(\text{ref } x)]$.

$$\frac{C.types[x] \approx \text{struct } (mut^? \ zt)^*}{C \vdash \text{struct.new } x : \text{unpack}(zt)^* \rightarrow (\text{ref } x)}$$

`struct.new_default` x

- The defined type $C.types[x]$ must exist.
- The expansion of $C.types[x]$ must be a structure type $\text{struct } fieldtype^*$.
- For each field type $fieldtype_i$ in $fieldtype^*$:
 - Let $fieldtype_i$ be $mut \ storagetype_i$.
 - Let t_i be the value type $\text{unpack}(storagetype_i)$.
 - The type t_i must be defaultable.
- Let t^* be the concatenation of all t_i .
- Then the instruction is valid with type $[] \rightarrow [(\text{ref } x)]$.

$$\frac{C.types[x] \approx \text{struct } (mut^? \ zt)^* \quad (\text{default}_{\text{unpack}(zt)} = \text{val})^*}{C \vdash \text{struct.new_default } x : \epsilon \rightarrow (\text{ref } x)}$$

`struct.get_` $_{sx^?} \ x \ y$

- The defined type $C.types[x]$ must exist.
- The expansion of $C.types[x]$ must be a structure type $\text{struct } fieldtype^*$.
- Let the field type $mut \ storagetype$ be $fieldtype^*[y]$.
- Let t be the value type $\text{unpack}(storagetype)$.
- The extension sx must be present if and only if $storagetype$ is a packed type.
- Then the instruction is valid with type $[(\text{ref null } x)] \rightarrow [t]$.

$$\frac{C.types[x] \approx \text{struct } yt^* \quad yt^*[i] = mut^? \ zt \quad sx^? = \epsilon \Leftrightarrow zt = \text{unpack}(zt)}{C \vdash \text{struct.get_}_{sx^?} \ x \ i : (\text{ref null } x) \rightarrow \text{unpack}(zt)}$$

`struct.set x y`

- The defined type $C.\text{types}[x]$ must exist.
- The expansion of $C.\text{types}[x]$ must be a structure type $\text{struct } \text{fieldtype}^*$.
- Let the field type mut storagetype be $\text{fieldtype}^*[y]$.
- The prefix mut must be `var`.
- Let t be the value type $\text{unpack}(\text{storagetype})$.
- Then the instruction is valid with type $[(\text{ref null } x) t] \rightarrow []$.

$$\frac{C.\text{types}[x] \approx \text{struct } yt^* \quad yt^*[i] = \text{mut } zt}{C \vdash \text{struct.set } x \ i : (\text{ref null } x) \text{ unpack}(zt) \rightarrow \epsilon}$$

`array.new x`

- The defined type $C.\text{types}[x]$ must exist.
- The expansion of $C.\text{types}[x]$ must be an array type $\text{array } \text{fieldtype}$.
- Let fieldtype be mut storagetype .
- Let t be the value type $\text{unpack}(\text{storagetype})$.
- Then the instruction is valid with type $[t \text{ i32}] \rightarrow [(\text{ref } x)]$.

$$\frac{C.\text{types}[x] \approx \text{array } (\text{mut}^? \text{ } zt)}{C \vdash \text{array.new } x : \text{unpack}(zt) \text{ i32} \rightarrow (\text{ref } x)}$$

`array.new_default x`

- The defined type $C.\text{types}[x]$ must exist.
- The expansion of $C.\text{types}[x]$ must be an array type $\text{array } \text{fieldtype}$.
- Let fieldtype be mut storagetype .
- Let t be the value type $\text{unpack}(\text{storagetype})$.
- The type t must be defaultable.
- Then the instruction is valid with type $[\text{i32}] \rightarrow [(\text{ref } x)]$.

$$\frac{C.\text{types}[x] \approx \text{array } (\text{mut}^? \text{ } zt) \quad \text{default}_{\text{unpack}(zt)} = \text{val}}{C \vdash \text{array.new_default } x : \text{i32} \rightarrow (\text{ref } x)}$$

`array.new_fixed x n`

- The defined type $C.\text{types}[x]$ must exist.
- The expansion of $C.\text{types}[x]$ must be an array type $\text{array } \text{fieldtype}$.
- Let fieldtype be mut storagetype .
- Let t be the value type $\text{unpack}(\text{storagetype})$.
- Then the instruction is valid with type $[t^n] \rightarrow [(\text{ref } x)]$.

$$\frac{C.\text{types}[x] \approx \text{array } (\text{mut}^? \text{ } zt)}{C \vdash \text{array.new_fixed } x \ n : \text{unpack}(zt)^n \rightarrow (\text{ref } x)}$$

`array.new_elem x y`

- The defined type $C.types[x]$ must exist.
- The expansion of $C.types[x]$ must be an array type $array\ fieldtype$.
- Let $fieldtype$ be $mut\ storagetype$.
- The storage type $storagetype$ must be a reference type rt .
- The element segment $C.elems[y]$ must exist.
- Let rt' be the reference type $C.elems[y]$.
- The reference type rt' must match rt .
- Then the instruction is valid with type $[i32\ i32] \rightarrow [(ref\ x)]$.

$$\frac{C.types[x] \approx array\ (mut^? \ rt) \quad C \vdash C.elems[y] \leq rt}{C \vdash array.new_elem\ x\ y : i32\ i32 \rightarrow (ref\ x)}$$

`array.new_data x y`

- The defined type $C.types[x]$ must exist.
- The expansion of $C.types[x]$ must be an array type $array\ fieldtype$.
- Let $fieldtype$ be $mut\ storagetype$.
- Let t be the value type $unpack(storagetype)$.
- The type t must be a numeric type or a vector type.
- The data segment $C.datas[y]$ must exist.
- Then the instruction is valid with type $[i32\ i32] \rightarrow [(ref\ x)]$.

$$\frac{C.types[x] \approx array\ (mut^? \ zt) \quad unpack(zt) = numtype \vee unpack(zt) = vectype \quad C.datas[y] = ok}{C \vdash array.new_data\ x\ y : i32\ i32 \rightarrow (ref\ x)}$$

`array.get_sx? x`

- The defined type $C.types[x]$ must exist.
- The expansion of $C.types[x]$ must be an array type $array\ fieldtype$.
- Let the field type $mut\ storagetype$ be $fieldtype$.
- Let t be the value type $unpack(storagetype)$.
- The extension sx must be present if and only if $storagetype$ is a packed type.
- Then the instruction is valid with type $[(ref\ null\ x)\ i32] \rightarrow [t]$.

$$\frac{C.types[x] \approx array\ (mut^? \ zt) \quad sx^? = \epsilon \Leftrightarrow zt = unpack(zt)}{C \vdash array.get_sx^? \ x : (ref\ null\ x)\ i32 \rightarrow unpack(zt)}$$

`array.set x`

- The defined type $C.types[x]$ must exist.
- The expansion of $C.types[x]$ must be an array type $array\ fieldtype$.
- Let the field type $mut\ storagetype$ be $fieldtype$.
- The prefix mut must be `var`.
- Let t be the value type $unpack(storagetype)$.
- Then the instruction is valid with type $[(ref\ null\ x)\ i32\ t] \rightarrow []$.

$$\frac{C.types[x] \approx array\ (mut\ zt)}{C \vdash array.set\ x : (ref\ null\ x)\ i32\ unpack(zt) \rightarrow \epsilon}$$

`array.len`

- The the instruction is valid with type $[(ref\ null\ array)] \rightarrow [i32]$.

$$\frac{C.types[x] \approx array\ (mut\ zt)}{C \vdash array.len : (ref\ null\ array) \rightarrow i32}$$

`array.fill x`

- The defined type $C.types[x]$ must exist.
- The expansion of $C.types[x]$ must be an array type $array\ fieldtype$.
- Let the field type $mut\ storagetype$ be $fieldtype$.
- The prefix mut must be `var`.
- Let t be the value type $unpack(storagetype)$.
- Then the instruction is valid with type $[(ref\ null\ x)\ i32\ t\ i32] \rightarrow []$.

$$\frac{C.types[x] \approx array\ (mut\ zt)}{C \vdash array.fill\ x : (ref\ null\ x)\ i32\ unpack(zt)\ i32 \rightarrow \epsilon}$$

`array.copy x y`

- The defined type $C.types[x]$ must exist.
- The expansion of $C.types[x]$ must be an array type $array\ fieldtype_1$.
- Let the field type $mut_1\ storagetype_1$ be $fieldtype_1$.
- The prefix mut_1 must be `var`.
- The defined type $C.types[y]$ must exist.
- The expansion of $C.types[y]$ must be an array type $array\ fieldtype_2$.
- Let the field type $mut_2\ storagetype_2$ be $fieldtype_2$.
- The storage type $storagetype_2$ must match $storagetype_1$.
- Then the instruction is valid with type $[(ref\ null\ x)\ i32\ (ref\ null\ y)\ i32\ i32] \rightarrow []$.

$$\frac{C.types[x_1] \approx array\ (mut\ zt_1) \quad C.types[x_2] \approx array\ (mut^? \ zt_2) \quad C \vdash zt_2 \leq zt_1}{C \vdash array.copy\ x_1\ x_2 : (ref\ null\ x_1)\ i32\ (ref\ null\ x_2)\ i32\ i32 \rightarrow \epsilon}$$

`array.init_elem x y`

- The defined type $C.types[x]$ must exist.
- The expansion of $C.types[x]$ must be an array type $array\ fieldtype$.
- Let the field type $mut\ storagetype$ be $fieldtype$.
- The prefix mut must be `var`.
- The storage type $storagetype$ must be a reference type rt .
- The element segment $C.elems[y]$ must exist.
- Let rt' be the reference type $C.elems[y]$.
- The reference type rt' must match rt .
- Then the instruction is valid with type $[(ref\ null\ x)\ i32\ i32\ i32] \rightarrow []$.

$$\frac{C.types[x] \approx array\ (mut\ zt) \quad C \vdash C.elems[y] \leq zt}{C \vdash array.init_elem\ x\ y : (ref\ null\ x)\ i32\ i32\ i32 \rightarrow \epsilon}$$

`array.init_data x y`

- The defined type $C.types[x]$ must exist.
- The expansion of $C.types[x]$ must be an array type $array\ fieldtype$.
- Let the field type $mut\ storagetype$ be $fieldtype$.
- The prefix mut must be `var`.
- Let t be the value type $unpack(storagetype)$.
- The value type t must be a numeric type or a vector type.
- The data segment $C.datas[y]$ must exist.
- Then the instruction is valid with type $[(ref\ null\ x)\ i32\ i32\ i32] \rightarrow []$.

$$\frac{C.types[x] \approx array\ (mut\ zt) \quad unpack(zt) = numtype \vee unpack(zt) = vectype \quad C.datas[y] = ok}{C \vdash array.init_data\ x\ y : (ref\ null\ x)\ i32\ i32\ i32 \rightarrow \epsilon}$$

3.4.5 Scalar Reference Instructions

`ref.i31`

- The instruction is valid with type $[i32] \rightarrow [(ref\ i31)]$.

$$\overline{C \vdash ref.i31 : i32 \rightarrow (ref\ i31)}$$

`i31.get_sx`

- The instruction is valid with type $[(ref\ null\ i31)] \rightarrow [i32]$.

$$\overline{C \vdash i31.get_sx : (ref\ null\ i31) \rightarrow i32}$$

3.4.6 External Reference Instructions

`any.convert_extern`

- The instruction is valid with type $[(\text{ref null}_1^? \text{extern})] \rightarrow [(\text{ref null}_2^? \text{any})]$ for any $\text{null}_1^?$ that equals $\text{null}_2^?$.

$$\overline{C \vdash \text{any.convert_extern} : (\text{ref null}^? \text{extern}) \rightarrow (\text{ref null}^? \text{any})}$$

`extern.convert_any`

- The instruction is valid with type $[(\text{ref null}_1^? \text{any})] \rightarrow [(\text{ref null}_2^? \text{extern})]$ for any $\text{null}_1^?$ that equals $\text{null}_2^?$.

$$\overline{C \vdash \text{extern.convert_any} : (\text{ref null}^? \text{any}) \rightarrow (\text{ref null}^? \text{extern})}$$

3.4.7 Vector Instructions

Vector instructions can have a prefix to describe the [shape](#) of the operand. Packed numeric types, `i8` and `i16`, are not [value types](#). An auxiliary function maps such packed type shapes to value types:

$$\text{unpack}(iN \times N) = \text{unpack}(iN)$$

`v128.const c`

- The instruction is valid with type $[] \rightarrow [v128]$.

$$\overline{C \vdash \text{v128.const } c : \epsilon \rightarrow v128}$$

`v128.vvunop`

- The instruction is valid with type $[v128] \rightarrow [v128]$.

$$\overline{C \vdash \text{v128.vvunop} : v128 \rightarrow v128}$$

`v128.vvbinop`

- The instruction is valid with type $[v128 \ v128] \rightarrow [v128]$.

`v128.vvternop`

- The instruction is valid with type $[v128 \ v128 \ v128] \rightarrow [v128]$.

$$\overline{C \vdash \text{v128.vvternop} : v128 \ v128 \ v128 \rightarrow v128}$$

v128.vtestop

- The instruction is valid with type $[v128] \rightarrow [i32]$.

$$\overline{C \vdash v128.vtestop : v128 \rightarrow i32}$$

shape.vunop

- The instruction is valid with type $[v128] \rightarrow [v128]$.

$$\overline{C \vdash sh.vunop : v128 \rightarrow v128}$$

shape.vbinop

- The instruction is valid with type $[v128 \ v128] \rightarrow [v128]$.

$$\overline{C \vdash sh.vbinop : v128 \ v128 \rightarrow v128}$$

shape.vtestop

- The instruction is valid with type $[v128] \rightarrow [i32]$.

$$\overline{C \vdash sh.vtestop : v128 \rightarrow i32}$$

shape.vrelop

- The instruction is valid with type $[v128 \ v128] \rightarrow [v128]$.

$$\overline{C \vdash sh.vrelop : v128 \ v128 \rightarrow v128}$$

ishape.vshiftop

- The instruction is valid with type $[v128 \ i32] \rightarrow [v128]$.

$$\overline{C \vdash sh.vshiftop : v128 \ i32 \rightarrow v128}$$

ishape.bitmask

- The instruction is valid with type $[v128] \rightarrow [i32]$.

$$\overline{C \vdash sh.bitmask : v128 \rightarrow i32}$$

i8x16.swizzle

- The instruction is valid with type $[v128 \ v128] \rightarrow [v128]$.

$$\overline{C \vdash sh.swizzle : v128 \ v128 \rightarrow v128}$$

*i8x16.shuffle laneidx*¹⁶

- For all $laneidx_i$, in $laneidx$ ¹⁶, $laneidx_i$ must be smaller than 32.
- The instruction is valid with type $[v128\ v128] \rightarrow [v128]$.

$$\frac{(i < 2 \cdot \dim(sh))^*}{C \vdash sh.shuffle\ i^* : v128\ v128 \rightarrow v128}$$

shape.splat

- Let t be $unpack(shape)$.
- The instruction is valid with type $[t] \rightarrow [v128]$.

$$\overline{C \vdash sh.splat : unpack(sh) \rightarrow v128}$$

shape.extract_lane_sx[?] laneidx

- The lane index $laneidx$ must be smaller than $\dim(shape)$.
- Let t be $unpack(shape)$.
- The instruction is valid with type $[v128] \rightarrow [t]$.

$$\frac{i < \dim(sh)}{C \vdash sh.extract_lane_sx^? i : v128 \rightarrow unpack(sh)}$$

shape.replace_lane laneidx

- The lane index $laneidx$ must be smaller than $\dim(shape)$.
- Let t be $unpack(shape)$.
- The instruction is valid with type $[v128\ t] \rightarrow [v128]$.

$$\frac{i < \dim(sh)}{C \vdash sh.replace_lane\ i : v128\ unpack(sh) \rightarrow v128}$$

ishape₁.extadd_pairwise_ishape₂_sx

- The instruction is valid with type $[v128] \rightarrow [v128]$.

$$\overline{C \vdash sh_1.vextunop_sh2_sx : v128 \rightarrow v128}$$

ishape₁.extmul_half_ishape₂_sx

- The instruction is valid with type $[v128\ v128] \rightarrow [v128]$.

$$\overline{C \vdash sh_1.vextbinop_sh2_sx : v128\ v128 \rightarrow v128}$$

ishape₁.narrow_ishape₂_sx

- The instruction is valid with type $[v128\ v128] \rightarrow [v128]$.

$$\frac{}{C \vdash sh_1.narrow_sh2_sx : v128\ v128 \rightarrow v128}$$

shape.vcvttop_half?_shape_sx?_zero?

- The instruction is valid with type $[v128] \rightarrow [v128]$.

$$\frac{sx^? = \epsilon \Leftrightarrow \text{lanetype}(sh_1) = imm_1 \wedge \text{lanetype}(sh_2) = imm_2 \wedge |imm_1| > |imm_2| \vee \text{lanetype}(sh_1) = fN_1 \wedge \text{lanetype}(sh_2) = f}{C \vdash sh_1.vcvttop_sx_sh2_hf^? : v128 \rightarrow v128}$$

3.4.8 Variable Instructions

local.get x

- The local $C.\text{locals}[x]$ must be defined in the context.
- Let *init* t be the local type $C.\text{locals}[x]$.
- The initialization status *init* must be set.
- Then the instruction is valid with type $[] \rightarrow [t]$.

$$\frac{C.\text{locals}[x] = \text{set } t}{C \vdash \text{local.get } x : \epsilon \rightarrow t}$$

local.set x

- The local $C.\text{locals}[x]$ must be defined in the context.
- Let *init* t be the local type $C.\text{locals}[x]$.
- Then the instruction is valid with type $[t] \rightarrow_x []$.

$$\frac{C.\text{locals}[x] = \text{init } t}{C \vdash \text{local.set } x : t \rightarrow (x) \epsilon}$$

local.tee x

- The local $C.\text{locals}[x]$ must be defined in the context.
- Let *init* t be the local type $C.\text{locals}[x]$.
- Then the instruction is valid with type $[t] \rightarrow_x [t]$.

$$\frac{C.\text{locals}[x] = \text{init } t}{C \vdash \text{local.tee } x : t \rightarrow (x) t}$$

`global.get x`

- The global $C.\text{globals}[x]$ must be defined in the context.
- Let $\text{mut } t$ be the global type $C.\text{globals}[x]$.
- Then the instruction is valid with type $[] \rightarrow [t]$.

$$\frac{C.\text{globals}[x] = \text{mut}^? t}{C \vdash \text{global.get } x : \epsilon \rightarrow t}$$

`global.set x`

- The global $C.\text{globals}[x]$ must be defined in the context.
- Let $\text{mut } t$ be the global type $C.\text{globals}[x]$.
- The mutability mut must be `var`.
- Then the instruction is valid with type $[t] \rightarrow []$.

$$\frac{C.\text{globals}[x] = \text{mut } t}{C \vdash \text{global.set } x : t \rightarrow \epsilon}$$

3.4.9 Table Instructions

`table.get x`

- The table $C.\text{tables}[x]$ must be defined in the context.
- Let $\text{limits } t$ be the table type $C.\text{tables}[x]$.
- Then the instruction is valid with type $[\text{i32}] \rightarrow [t]$.

$$\frac{C.\text{tables}[x] = \text{lim } rt}{C \vdash \text{table.get } x : \text{i32} \rightarrow rt}$$

`table.set x`

- The table $C.\text{tables}[x]$ must be defined in the context.
- Let $\text{limits } t$ be the table type $C.\text{tables}[x]$.
- Then the instruction is valid with type $[\text{i32 } t] \rightarrow []$.

$$\frac{C.\text{tables}[x] = \text{lim } rt}{C \vdash \text{table.set } x : \text{i32 } rt \rightarrow \epsilon}$$

`table.size x`

- The table $C.\text{tables}[x]$ must be defined in the context.
- Then the instruction is valid with type $[] \rightarrow [\text{i32}]$.

$$\frac{C.\text{tables}[x] = \text{lim } rt}{C \vdash \text{table.size } x : \epsilon \rightarrow \text{i32}}$$

`table.grow x`

- The table $C.tables[x]$ must be defined in the context.
- Let $limits\ t$ be the `table type` $C.tables[x]$.
- Then the instruction is valid with type $[t\ i32] \rightarrow [i32]$.

$$\frac{C.tables[x] = lim\ rt}{C \vdash \text{table.grow } x : rt\ i32 \rightarrow i32}$$

`table.fill x`

- The table $C.tables[x]$ must be defined in the context.
- Let $limits\ t$ be the `table type` $C.tables[x]$.
- Then the instruction is valid with type $[i32\ t\ i32] \rightarrow []$.

$$\frac{C.tables[x] = lim\ rt}{C \vdash \text{table.fill } x : i32\ rt\ i32 \rightarrow \epsilon}$$

`table.copy $x\ y$`

- The table $C.tables[x]$ must be defined in the context.
- Let $limits_1\ t_1$ be the `table type` $C.tables[x]$.
- The table $C.tables[y]$ must be defined in the context.
- Let $limits_2\ t_2$ be the `table type` $C.tables[y]$.
- The `reference type` t_2 must match t_1 .
- Then the instruction is valid with type $[i32\ i32\ i32] \rightarrow []$.

$$\frac{C.tables[x_1] = lim_1\ rt_1 \quad C.tables[x_2] = lim_2\ rt_2 \quad C \vdash rt_2 \leq rt_1}{C \vdash \text{table.copy } x_1\ x_2 : i32\ i32\ i32 \rightarrow \epsilon}$$

`table.init $x\ y$`

- The table $C.tables[x]$ must be defined in the context.
- Let $limits\ t_1$ be the `table type` $C.tables[x]$.
- The element segment $C.elems[y]$ must be defined in the context.
- Let t_2 be the `reference type` $C.elems[y]$.
- The `reference type` t_2 must match t_1 .
- Then the instruction is valid with type $[i32\ i32\ i32] \rightarrow []$.

$$\frac{C.tables[x] = lim\ rt_1 \quad C.elems[y] = rt_2 \quad C \vdash rt_2 \leq rt_1}{C \vdash \text{table.init } x\ y : i32\ i32\ i32 \rightarrow \epsilon}$$

elem.drop x

- The element segment $C.\text{elems}[x]$ must be defined in the context.
- Then the instruction is valid with type $[] \rightarrow []$.

$$\frac{C.\text{elems}[x] = rt}{C \vdash \text{elem.drop } x : \epsilon \rightarrow \epsilon}$$

3.4.10 Memory Instructions

t.load x *memarg*

- The memory $C.\text{mems}[x]$ must be defined in the context.
- The alignment $2^{\text{memarg.align}}$ must not be larger than the **bit width** of t divided by 8.
- Then the instruction is valid with type $[i32] \rightarrow [t]$.

$$\frac{C.\text{mems}[x] = mt \quad 2^{\text{memarg.align}} \leq |nt|/8}{C \vdash nt.\text{load } x \text{ memarg} : i32 \rightarrow nt}$$

t.loadN_sx x *memarg*

- The memory $C.\text{mems}[x]$ must be defined in the context.
- The alignment $2^{\text{memarg.align}}$ must not be larger than $N/8$.
- Then the instruction is valid with type $[i32] \rightarrow [t]$.

$$\frac{C.\text{mems}[x] = mt \quad 2^{\text{memarg.align}} \leq M/8}{C \vdash iN.\text{loadM } sx \text{ } x \text{ memarg} : i32 \rightarrow iN}$$

t.store x *memarg*

- The memory $C.\text{mems}[x]$ must be defined in the context.
- The alignment $2^{\text{memarg.align}}$ must not be larger than the **bit width** of t divided by 8.
- Then the instruction is valid with type $[i32 \ t] \rightarrow []$.

$$\frac{C.\text{mems}[x] = mt \quad 2^{\text{memarg.align}} \leq |nt|/8}{C \vdash nt.\text{store } x \text{ memarg} : i32 \ nt \rightarrow \epsilon}$$

t.storeN x *memarg*

- The memory $C.\text{mems}[x]$ must be defined in the context.
- The alignment $2^{\text{memarg.align}}$ must not be larger than $N/8$.
- Then the instruction is valid with type $[i32 \ t] \rightarrow []$.

$$\frac{C.\text{mems}[x] = mt \quad 2^{\text{memarg.align}} \leq M/8}{C \vdash iN.\text{storeM } x \text{ memarg} : i32 \ iN \rightarrow \epsilon}$$

v128.load x memarg

- The memory $C.\text{mems}[x]$ must be defined in the context.
- The alignment $2^{\text{memarg.align}}$ must not be larger than the bit width of t divided by 8.
- Then the instruction is valid with type $[i32] \rightarrow [t]$.

$$\frac{C.\text{mems}[x] = mt \quad 2^{\text{memarg.align}} \leq |v128|/8}{C \vdash v128.\text{load } x \text{ memarg} : i32 \rightarrow v128}$$

v128.loadNxM_sx x memarg

- The memory $C.\text{mems}[x]$ must be defined in the context.
- The alignment $2^{\text{memarg.align}}$ must not be larger than $N/8 \cdot M$.
- Then the instruction is valid with type $[i32] \rightarrow [v128]$.

$$\frac{C.\text{mems}[x] = mt \quad 2^{\text{memarg.align}} \leq M/8 \cdot N}{C \vdash v128.\text{load } M \times N_sx \text{ memarg} : i32 \rightarrow v128}$$

v128.loadN_splat x memarg

- The memory $C.\text{mems}[x]$ must be defined in the context.
- The alignment $2^{\text{memarg.align}}$ must not be larger than $N/8$.
- Then the instruction is valid with type $[i32] \rightarrow [v128]$.

$$\frac{C.\text{mems}[x] = mt \quad 2^{\text{memarg.align}} \leq N/8}{C \vdash v128.\text{load } N_splat \text{ memarg} : i32 \rightarrow v128}$$

v128.loadN_zero x memarg

- The memory $C.\text{mems}[x]$ must be defined in the context.
- The alignment $2^{\text{memarg.align}}$ must not be larger than $N/8$.
- Then the instruction is valid with type $[i32] \rightarrow [v128]$.

$$\frac{C.\text{mems}[x] = mt \quad 2^{\text{memarg.align}} < N/8}{C \vdash v128.\text{load } N_zero \text{ memarg} : i32 \rightarrow v128}$$

v128.loadN_lane x memarg laneidx

- The memory $C.\text{mems}[x]$ must be defined in the context.
- The alignment $2^{\text{memarg.align}}$ must not be larger than $N/8$.
- The lane index *laneidx* must be smaller than $128/N$.
- Then the instruction is valid with type $[i32 \ v128] \rightarrow [v128]$.

$$\frac{C.\text{mems}[x] = mt \quad 2^{\text{memarg.align}} < N/8 \quad i < 128/N}{C \vdash v128.\text{load } N_lane \text{ memarg } i : i32 \ v128 \rightarrow v128}$$

v128.store x memarg

- The memory $C.\text{mems}[x]$ must be defined in the context.
- The alignment $2^{\text{memarg.align}}$ must not be larger than the bit width of t divided by 8.
- Then the instruction is valid with type $[i32\ t] \rightarrow []$.

$$\frac{C.\text{mems}[x] = mt \quad 2^{\text{memarg.align}} \leq |v128|/8}{C \vdash \text{v128.store } x \text{ memarg} : i32\ v128 \rightarrow \epsilon}$$

v128.storeN_lane x memarg laneidx

- The memory $C.\text{mems}[x]$ must be defined in the context.
- The alignment $2^{\text{memarg.align}}$ must not be larger than $N/8$.
- The lane index *laneidx* must be smaller than $128/N$.
- Then the instruction is valid with type $[i32\ v128] \rightarrow [v128]$.

$$\frac{C.\text{mems}[x] = mt \quad 2^{\text{memarg.align}} < N/8 \quad i < 128/N}{C \vdash \text{v128.storeN_lane } x \text{ memarg } i : i32\ v128 \rightarrow \epsilon}$$

memory.size x

- The memory $C.\text{mems}[x]$ must be defined in the context.
- Then the instruction is valid with type $[] \rightarrow [i32]$.

$$\frac{C.\text{mems}[x] = mt}{C \vdash \text{memory.size } x : \epsilon \rightarrow i32}$$

memory.grow x

- The memory $C.\text{mems}[x]$ must be defined in the context.
- Then the instruction is valid with type $[i32] \rightarrow [i32]$.

$$\frac{C.\text{mems}[x] = mt}{C \vdash \text{memory.grow } x : i32 \rightarrow i32}$$

memory.fill x

- The memory $C.\text{mems}[x]$ must be defined in the context.
- Then the instruction is valid with type $[i32\ i32\ i32] \rightarrow []$.

$$\frac{C.\text{mems}[x] = mt}{C \vdash \text{memory.fill } x : i32\ i32\ i32 \rightarrow \epsilon}$$

`memory.copy x y`

- The memory $C.\text{mems}[x]$ must be defined in the context.
- The memory $C.\text{mems}[y]$ must be defined in the context.
- Then the instruction is valid with type $[i32\ i32\ i32] \rightarrow []$.

$$\frac{C.\text{mems}[x_1] = mt_1 \quad C.\text{mems}[x_2] = mt_2}{C \vdash \text{memory.copy } x_1\ x_2 : i32\ i32\ i32 \rightarrow \epsilon}$$

`memory.init x y`

- The memory $C.\text{mems}[x]$ must be defined in the context.
- The data segment $C.\text{datas}[y]$ must be defined in the context.
- Then the instruction is valid with type $[i32\ i32\ i32] \rightarrow []$.

$$\frac{C.\text{mems}[x] = mt \quad C.\text{datas}[y] = \text{ok}}{C \vdash \text{memory.init } x\ y : i32\ i32\ i32 \rightarrow \epsilon}$$

`data.drop x`

- The data segment $C.\text{datas}[x]$ must be defined in the context.
- Then the instruction is valid with type $[] \rightarrow []$.

$$\frac{C.\text{datas}[x] = \text{ok}}{C \vdash \text{data.drop } x : \epsilon \rightarrow \epsilon}$$

3.4.11 Control Instructions

`block blocktype instr* end`

- The `block` type must be `valid` as some `instruction` type $[t_1^*] \rightarrow [t_2^*]$.
- Let C' be the same `context` as C , but with the `result` type $[t_2^*]$ prepended to the `labels` list.
- Under context C' , the instruction sequence instr^* must be `valid` with type $[t_1^*] \rightarrow [t_2^*]$.
- Then the compound instruction is valid with type $[t_1^*] \rightarrow [t_2^*]$.

$$\frac{C \vdash bt : t_1^* \rightarrow t_2^* \quad C, \text{labels } (t_2^*) \vdash \text{instr}^* : t_1^* \rightarrow (x^*) t_2^*}{C \vdash \text{block } bt\ \text{instr}^* : t_1^* \rightarrow t_2^*}$$

Note: The notation $C, \text{labels } (t^*)$ inserts the new label type at index 0, shifting all others.

`loop blocktype instr* end`

- The `block` type must be `valid` as some `instruction` type $[t_1^*] \rightarrow_{x^*} [t_2^*]$.
- Let C' be the same `context` as C , but with the `result` type $[t_1^*]$ prepended to the `labels` list.
- Under context C' , the instruction sequence instr^* must be `valid` with type $[t_1^*] \rightarrow [t_2^*]$.
- Then the compound instruction is valid with type $[t_1^*] \rightarrow [t_2^*]$.

$$\frac{C \vdash bt : t_1^* \rightarrow t_2^* \quad C, \text{labels}(t_1^*) \vdash instr^* : t_1^* \rightarrow (x^*) t_2^*}{C \vdash \text{loop } bt \text{ } instr^* : t_1^* \rightarrow t_2^*}$$

Note: The notation $C, \text{labels}(t^*)$ inserts the new label type at index 0, shifting all others.

if *blocktype* $instr_1^*$ else $instr_2^*$ end

- The **block type** must be **valid** as some **instruction type** $[t_1^*] \rightarrow [t_2^*]$.
- Let C' be the same **context** as C , but with the **result type** $[t_2^*]$ prepended to the **labels** list.
- Under context C' , the instruction sequence $instr_1^*$ must be **valid** with type $[t_1^*] \rightarrow [t_2^*]$.
- Under context C' , the instruction sequence $instr_2^*$ must be **valid** with type $[t_1^*] \rightarrow [t_2^*]$.
- Then the compound instruction is valid with type $[t_1^* \text{ i32}] \rightarrow [t_2^*]$.

$$\frac{C \vdash bt : t_1^* \rightarrow t_2^* \quad C, \text{labels}(t_2^*) \vdash instr_1^* : t_1^* \rightarrow (x_1^*) t_2^* \quad C, \text{labels}(t_2^*) \vdash instr_2^* : t_1^* \rightarrow (x_2^*) t_2^*}{C \vdash \text{if } bt \text{ } instr_1^* \text{ else } instr_2^* : t_1^* \text{ i32} \rightarrow t_2^*}$$

Note: The notation $C, \text{labels}(t^*)$ inserts the new label type at index 0, shifting all others.

br l

- The label $C.\text{labels}[l]$ must be defined in the context.
- Let $[t^*]$ be the **result type** $C.\text{labels}[l]$.
- Then the instruction is valid with any **valid** type of the form $[t_1^* t^*] \rightarrow [t_2^*]$.

$$\frac{C.\text{labels}[l] = t^* \quad C \vdash t_1^* \rightarrow t_2^* : \text{ok}}{C \vdash \text{br } l : t_1^* t^* \rightarrow t_2^*}$$

Note: The **label index** space in the **context** C contains the most recent label first, so that $C.\text{label}[l]$ performs a relative lookup as expected.

The br instruction is **stack-polymorphic**.

br_if l

- The label $C.\text{labels}[l]$ must be defined in the context.
- Let $[t^*]$ be the **result type** $C.\text{labels}[l]$.
- Then the instruction is valid with type $[t^* \text{ i32}] \rightarrow [t^*]$.

$$\frac{C.\text{labels}[l] = t^*}{C \vdash \text{br_if } l : t^* \text{ i32} \rightarrow t^*}$$

Note: The **label index** space in the **context** C contains the most recent label first, so that $C.\text{label}[l]$ performs a relative lookup as expected.

`br_table` $l^* l_N$

- The label $C.\text{labels}[l_N]$ must be defined in the context.
- For each label l_i in l^* , the label $C.\text{labels}[l_i]$ must be defined in the context.
- There must be a sequence t^* of value types, such that:
 - The result type $[t^*]$ matches $C.\text{labels}[l_N]$.
 - For all l_i in l^* , the result type $[t^*]$ matches $C.\text{labels}[l_i]$.
- Then the instruction is valid with any valid type of the form $[t_1^* t^* i32] \rightarrow [t_2^*]$.

$$\frac{(C \vdash t^* \leq C.\text{labels}[l])^* \quad C \vdash t^* \leq C.\text{labels}[l'] \quad C \vdash t_1^* \rightarrow t_2^* : \text{ok}}{C \vdash \text{br_table } l^* l' : t_1^* t^* \rightarrow t_2^*}$$

Note: The label index space in the context C contains the most recent label first, so that $C.\text{label}[l]$ performs a relative lookup as expected.

The `br_table` instruction is *stack-polymorphic*.

Furthermore, the result type t^* is also chosen non-deterministically in this rule. Although it may seem necessary to compute t^* as the greatest lower bound of all label types in practice, a simple *linear algorithm* does not require this.

`br_on_null` l

- The label $C.\text{labels}[l]$ must be defined in the context.
- Let $[t^*]$ be the result type $C.\text{labels}[l]$.
- Then the instruction is valid with type $[t^* (\text{ref null } ht)] \rightarrow [t^* (\text{ref } ht)]$ for any valid heap type ht .

$$\frac{C.\text{labels}[l] = t^* \quad C \vdash ht : \text{ok}}{C \vdash \text{br_on_null } l : t^* (\text{ref null } ht) \rightarrow t^* (\text{ref } ht)}$$

`br_on_non_null` l

- The label $C.\text{labels}[l]$ must be defined in the context.
- Let $[t'^*]$ be the result type $C.\text{labels}[l]$.
- The result type $[t'^*]$ must contain at least one type.
- Let the value type t_l be the last element in the sequence t'^* , and $[t^*]$ the remainder of the sequence preceding it.
- The value type t_l must be a reference type of the form `ref null2 ht`.
- Then the instruction is valid with type $[t^* (\text{ref null } ht)] \rightarrow [t^*]$.

$$\frac{C.\text{labels}[l] = t^* (\text{ref } ht)}{C \vdash \text{br_on_non_null } l : t^* (\text{ref null } ht) \rightarrow t^*}$$

`br_on_cast l rt1 rt2`

- The label $C.\text{labels}[l]$ must be defined in the context.
- Let $[t_l^*]$ be the **result type** $C.\text{labels}[l]$.
- The type sequence t_l^* must be of the form $t^* rt'$.
- The **reference type** rt_1 must be **valid**.
- The **reference type** rt_2 must be **valid**.
- The **reference type** rt_2 must **match** rt_1 .
- The **reference type** rt_2 must **match** rt' .
- Let rt'_1 be the **type difference** between rt_1 and rt_2 .
- Then the instruction is valid with type $[t^* rt_1] \rightarrow [t^* rt'_1]$.

$$\frac{C.\text{labels}[l] = t^* rt \quad C \vdash rt_1 : \text{ok} \quad C \vdash rt_2 : \text{ok} \quad C \vdash rt_2 \leq rt_1 \quad C \vdash rt_2 \leq rt}{C \vdash \text{br_on_cast } l \ rt_1 \ rt_2 : t^* rt_1 \rightarrow t^* (rt_1 \setminus rt_2)}$$

`br_on_cast_fail l rt1 rt2`

- The label $C.\text{labels}[l]$ must be defined in the context.
- Let $[t_l^*]$ be the **result type** $C.\text{labels}[l]$.
- The type sequence t_l^* must be of the form $t^* rt'$.
- The **reference type** rt_1 must be **valid**.
- The **reference type** rt_2 must be **valid**.
- The **reference type** rt_2 must **match** rt_1 .
- Let rt'_1 be the **type difference** between rt_1 and rt_2 .
- The **reference type** rt'_1 must **match** rt' .
- Then the instruction is valid with type $[t^* rt_1] \rightarrow [t^* rt_2]$.

$$\frac{C.\text{labels}[l] = t^* rt \quad C \vdash rt_1 : \text{ok} \quad C \vdash rt_2 : \text{ok} \quad C \vdash rt_2 \leq rt_1 \quad C \vdash rt_1 \setminus rt_2 \leq rt}{C \vdash \text{br_on_cast_fail } l \ rt_1 \ rt_2 : t^* rt_1 \rightarrow t^* rt_2}$$

`call x`

- The function $C.\text{funcs}[x]$ must be defined in the context.
- The **expansion** of $C.\text{funcs}[x]$ must be a **function type** $\text{func } [t_1^*] \rightarrow [t_2^*]$.
- Then the instruction is valid with type $[t_1^*] \rightarrow [t_2^*]$.

$$\frac{C.\text{funcs}[x] \approx \text{func } (t_1^* \rightarrow t_2^*)}{C \vdash \text{call } x : t_1^* \rightarrow t_2^*}$$

`call_ref x`

- The type $C.\text{types}[x]$ must be defined in the context.
- The expansion of $C.\text{funcs}[x]$ must be a function type $\text{func } [t_1^*] \rightarrow [t_2^*]$.
- Then the instruction is valid with type $[t_1^* (\text{ref null } x)] \rightarrow [t_2^*]$.

$$\frac{C.\text{types}[x] \approx \text{func } (t_1^* \rightarrow t_2^*)}{C \vdash \text{call_ref } x : t_1^* (\text{ref null } x) \rightarrow t_2^*}$$

`call_indirect x y`

- The table $C.\text{tables}[x]$ must be defined in the context.
- Let $\text{limits } t$ be the table type $C.\text{tables}[x]$.
- The reference type t must match type `ref null func`.
- The type $C.\text{types}[y]$ must be defined in the context.
- The expansion of $C.\text{types}[y]$ must be a function type $\text{func } [t_1^*] \rightarrow [t_2^*]$.
- Then the instruction is valid with type $[t_1^* \text{ i32}] \rightarrow [t_2^*]$.

$$\frac{C.\text{tables}[x] = \text{lim } rt \quad C \vdash rt \leq (\text{ref null func}) \quad C.\text{types}[y] \approx \text{func } (t_1^* \rightarrow t_2^*)}{C \vdash \text{call_indirect } x \ y : t_1^* \text{ i32} \rightarrow t_2^*}$$

`return`

- The return type $C.\text{return}$ must not be absent in the context.
- Let $[t^*]$ be the result type of $C.\text{return}$.
- Then the instruction is valid with any valid type of the form $[t_1^*] \rightarrow [t_2^*]$.

$$\frac{C.\text{return} = (t^*) \quad C \vdash t_1^* \rightarrow t_2^* : \text{ok}}{C \vdash \text{return} : t_1^* t^* \rightarrow t_2^*}$$

Note: The return instruction is **stack-polymorphic**.

$C.\text{return}$ is absent (set to ϵ) when validating an **expression** that is not a function body. This differs from it being set to the empty result type (ϵ), which is the case for functions not returning anything.

`return_call x`

- The return type $C.\text{return}$ must not be absent in the context.
- The function $C.\text{funcs}[x]$ must be defined in the context.
- The expansion of $C.\text{funcs}[x]$ must be a function type $\text{func } [t_1^*] \rightarrow [t_2^*]$.
- The result type $[t_2^*]$ must match $C.\text{return}$.
- Then the instruction is valid with any valid type $[t_3^* t_1^*] \rightarrow [t_4^*]$.

$$\frac{C.\text{funcs}[x] \approx \text{func } (t_1^* \rightarrow t_2^*) \quad C.\text{return} = (t_2^*) \quad C \vdash t_2^* \leq t_2'^* \quad C \vdash t_3^* \rightarrow t_4^* : \text{ok}}{C \vdash \text{return_call } x : t_3^* t_1^* \rightarrow t_4^*}$$

Note: The return_call instruction is **stack-polymorphic**.

`return_call_ref x`

- The type $C.\text{types}[x]$ must be defined in the context.
- The expansion of $C.\text{types}[x]$ must be a function type $\text{func } [t_1^*] \rightarrow [t_2^*]$.
- The result type $[t_2^*]$ must match $C.\text{return}$.
- Then the instruction is valid with any valid type $[t_3^* t_1^* (\text{ref null } x)] \rightarrow [t_4^*]$.

$$\frac{C.\text{types}[x] \approx \text{func } (t_1^* \rightarrow t_2^*) \quad C.\text{return} = (t_2'^*) \quad C \vdash t_2^* \leq t_2'^* \quad C \vdash t_3^* \rightarrow t_4^* : \text{ok}}{C \vdash \text{return_call_ref } x : t_3^* t_1^* (\text{ref null } x) \rightarrow t_4^*}$$

Note: The `return_call_ref` instruction is stack-polymorphic.

`return_call_indirect x y`

- The return type $C.\text{return}$ must not be empty in the context.
- The table $C.\text{tables}[x]$ must be defined in the context.
- Let *limits* t be the table type $C.\text{tables}[x]$.
- The reference type t must match type `ref null func`.
- The type $C.\text{types}[y]$ must be defined in the context.
- The expansion of $C.\text{types}[y]$ must be a function type $\text{func } [t_1^*] \rightarrow [t_2^*]$.
- The result type $[t_2^*]$ must match $C.\text{return}$.
- Then the instruction is valid with type $[t_3^* t_1^* \text{i}32] \rightarrow [t_4^*]$, for any sequences of value types t_3^* and t_4^* .

$$\frac{C.\text{tables}[x] = \text{lim } rt \quad C \vdash rt \leq (\text{ref null func}) \quad C.\text{types}[y] \approx \text{func } (t_1^* \rightarrow t_2^*) \quad C.\text{return} = (t_2'^*) \quad C \vdash t_2^* \leq t_2'^* \quad C \vdash t_3^* \rightarrow t_4^* : \text{ok}}{C \vdash \text{return_call_indirect } x \ y : t_3^* t_1^* \text{i}32 \rightarrow t_4^*}$$

Note: The `return_call_indirect` instruction is stack-polymorphic.

3.4.12 Instruction Sequences

Typing of instruction sequences is defined recursively.

Empty Instruction Sequence: ϵ

- The empty instruction sequence is valid with type $[] \rightarrow []$.

$$\overline{C \vdash \epsilon : \epsilon \rightarrow \epsilon}$$

Non-empty Instruction Sequence: $instr\ instr'^*$

- The instruction $instr$ must be valid with some type $[t_1^*] \rightarrow_{x_1^*} [t_2^*]$.
- Let C' be the same context as C , but with:
 - **locals** the same as in C , except that for every local index x in x_1^* , the local type $locals[x]$ has been updated to **initialization status set**.
- Under the context C' , the instruction sequence $instr'^*$ must be valid with some type $[t_2^*] \rightarrow_{x_2^*} [t_3^*]$.
- Then the combined instruction sequence is valid with type $[t_1^*] \rightarrow_{x_1^* x_2^*} [t_3^*]$.

$$\frac{C \vdash instr_1 : t_1^* \rightarrow (x_1^*) t_2^* \quad (C.local[x_1] = init\ t)^* \quad C[.local[x_1] = (set\ t)^*] \vdash instr_2^* : t_2^* \rightarrow (x_2^*) t_3^*}{C \vdash instr_1\ instr_2^* : t_1^* \rightarrow (x_1^* x_2^*) t_3^*}$$

Subsumption for $instr^*$

- The instruction sequence $instr^*$ must be valid with some type $instrtype$.
- The instruction type $instrtype'$: must be a **valid**
- The instruction type $instrtype$ must **match** the type $instrtype'$.
- Then the instruction sequence $instr^*$ is also valid with type $instrtype'$.

$$\frac{C \vdash instr^* : it \quad C \vdash it \leq it' \quad C \vdash it' : ok}{C \vdash instr^* : it'}$$

$$\frac{C \vdash instr^* : t_1^* \rightarrow (x^*) t_2^* \quad C \vdash t^* : ok}{C \vdash instr^* : (t^* t_1^*) \rightarrow (x^*) (t^* t_2^*)}$$

Note: In combination with the previous rule, subsumption allows to compose instructions whose types would not directly fit otherwise. For example, consider the instruction sequence

(const i31 1) (const i32 2) binop i32 add
 (i32.const 1) (i32.const 2) i32.add

To type this sequence, its subsequence (const i32 2) binop i32 add needs to be valid with an intermediate type. But the direct type of (const i32 2) is $\epsilon \rightarrow i32$, not matching the two inputs expected by binop i32 add. The subsumption rule allows to weaken the type of (const i32 2) to the supertype $i32 \rightarrow i32\ i32$, such that it can be composed with add i32 and yields the intermediate type $i32 \rightarrow i32\ i32$ for the subsequence. That can in turn be composed with the first constant.

Furthermore, subsumption allows to drop init variables x^* from the instruction type in a context where they are not needed, for example, at the end of the body of a **block**.

3.4.13 Expressions

Expressions $expr$ are classified by result types t^* .

*instr** end

- The instruction sequence *instr** must be valid with type $[] \rightarrow [t^*]$.
- Then the expression is valid with result type $[t^*]$.

$$\frac{C \vdash \text{instr}^* : \epsilon \rightarrow (\epsilon) t^*}{C \vdash \text{instr}^* : t^*}$$

Constant Expressions

- In a *constant* expression *instr** end all instructions in *instr** must be constant.
- A constant instruction *instr* must be:
 - either of the form *t.const* *c*,
 - or of the form *inn.ibinop*, where *ibinop* is limited to *add*, *sub*, or *mul*.
 - or of the form *ref.null*,
 - or of the form *ref.i31*,
 - or of the form *ref.func* *x*,
 - or of the form *struct.new* *x*,
 - or of the form *struct.new_default* *x*,
 - or of the form *array.new* *x*,
 - or of the form *array.new_default* *x*,
 - or of the form *array.new_fixed* *x*,
 - or of the form *any.convert_extern*,
 - or of the form *extern.convert_any*,
 - or of the form *global.get* *x*, in which case *C.globals[x]* must be a *global* type of the form *const t*.

$$\frac{(C \vdash \text{instr} \text{ const})^*}{C \vdash \text{instr}^* \text{ const}}$$

$$\frac{}{C \vdash (\text{nt.const } c_{nt}) \text{ const}} \quad \frac{}{C \vdash (\text{vt.const } c_{vt}) \text{ const}} \quad \frac{iN \in i32 \ i64 \quad \text{binop} \in \text{add sub mul}}{C \vdash (iN.\text{binop}) \text{ const}}$$

$$\frac{}{C \vdash (\text{ref.null } ht) \text{ const}} \quad \frac{}{C \vdash (\text{ref.i31}) \text{ const}} \quad \frac{}{C \vdash (\text{ref.func } x) \text{ const}}$$

$$\frac{}{C \vdash (\text{struct.new } x) \text{ const}} \quad \frac{}{C \vdash (\text{struct.new_default } x) \text{ const}}$$

$$\frac{}{C \vdash (\text{array.new } x) \text{ const}} \quad \frac{}{C \vdash (\text{array.new_default } x) \text{ const}} \quad \frac{}{C \vdash (\text{array.new_fixed } x \ n) \text{ const}}$$

$$\frac{}{C \vdash (\text{any.convert_extern}) \text{ const}} \quad \frac{}{C \vdash (\text{extern.convert_any}) \text{ const}}$$

$$\frac{C.\text{globals}[x] = t}{C \vdash (\text{global.get } x) \text{ const}}$$

Note: Currently, constant expressions occurring in *globals* are further constrained in that contained *global.get* instructions are only allowed to refer to *imported* or *previously defined* globals. Constant expressions occurring in *tables* may only have *global.get* instructions that refer to *imported* globals. This is enforced in the [validation rule for modules](#) by constraining the context *C* accordingly.

The definition of constant expression may be extended in future versions of WebAssembly.

3.5 Modules

Modules are valid when all the components they contain are valid. Furthermore, most definitions are themselves classified with a suitable type.

3.5.1 Types

The sequence of **types** defined in a module is validated incrementally, yielding a sequence of **defined types** representing them individually.

type

$$\frac{x = |C.\text{types}| \quad dt^* = \text{roll}_x^*(\text{rectype}) \quad C[.\text{types} = ..dt^*] \vdash \text{rectype} : \text{ok}(x)}{C \vdash \text{type } \text{rectype} : dt^*}$$

*type**

- If the sequence is empty, then:
 - The **context** C must be empty.
 - Then the type sequence is valid.
- Otherwise:
 - Let the **recursive type** rectype be the last element in the sequence.
 - The sequence without rectype must be valid for some context C' .
 - Let the **type index** x be the length of $C'.C'$.
 - Let the sequence of **defined types** deftype^* be the result $\text{roll}_x^*(\text{rectype})$ of **rolling up** into its sequence of **defined types**.
 - The **recursive type** rectype must be **valid** under the context C for **type index** x .
 - The current **context** C be the same as C' , but with deftype^* appended to **types**.
 - Then the type sequence is valid.

$$\frac{}{C \vdash \epsilon : \epsilon} \quad \frac{C \vdash \text{type}_1 : dt_1^* \quad C[.\text{types} = ..dt_1^*] \vdash \text{type}^* : dt^*}{C \vdash \text{type}_1 \text{ type}^* : dt_1^* dt^*}$$

3.5.2 Functions

Functions *func* are classified by **defined types** that expand to **function types** of the form $\text{func } (t_1^* \rightarrow t_2^*)$.

$\{\text{type } x, \text{locals } t^*, \text{body } \text{expr}\}$

- The **defined type** $C.\text{types}[x]$ must be a **function type**.
- Let $\text{func } [t_1^*] \rightarrow [t_2^*]$ be the **expansion** of the **defined type** $C.\text{types}[x]$.
- For each local declared by a **value type** t in t^* :
 - The local for type t must be **valid** with **local type** localtype_i .
- Let localtype^* be the concatenation of all localtype_i .
- Let C' be the same **context** as C , but with:

- **locals** set to the sequence of **value types** $(\text{set } t_1)^* \text{ localtype}^*$, concatenating parameters and locals,
- **labels** set to the singular sequence containing only **result type** $[t_2^*]$.
- **return** set to the **result type** $[t_2^*]$.
- Under the context C' , the expression *expr* must be valid with type $[t_2^*]$.
- Then the function definition is valid with type $C.\text{types}[x]$.

$$\frac{C.\text{types}[x] \approx \text{func } (t_1^* \rightarrow t_2^*) \quad (C \vdash \text{local} : lt)^* \quad C, \text{locals } (\text{set } t_1)^* lt^*, \text{labels } (t_2^*), \text{return } (t_2^*) \vdash \text{expr} : t_2^*}{C \vdash \text{func } x \text{ local}^* \text{ expr} : C.\text{types}[x]}$$

$$\frac{\text{default}_t \neq \epsilon}{C \vdash \text{local } t : \text{set } t} \quad \frac{\text{default}_t = \epsilon}{C \vdash \text{local } t : \text{unset } t}$$

3.5.3 Locals

Locals *local* are classified with **local types**.

{type *valtype*}

- The value type *valtype* must be valid.
- If *valtype* is defaultable, then:
 - The local is valid with **local type set** *valtype*.
- Else:
 - The local is valid with **local type unset** *valtype*.

$$\frac{\text{default}_t \neq \epsilon}{C \vdash \text{local } t : \text{set } t} \quad \frac{\text{default}_t = \epsilon}{C \vdash \text{local } t : \text{unset } t}$$

Note: For cases where both rules are applicable, the former yields the more permissable type.

3.5.4 Tables

Tables *table* are classified by **table types**.

{type *tabletype*, init *expr*}

- The table type *tabletype* must be valid.
- Let t be the element **reference type** of *tabletype*.
- The expression *expr* must be valid with **result type** $[t]$.
- The expression *expr* must be **constant**.
- Then the table definition is valid with type *tabletype*.

$$\frac{C \vdash tt : \text{ok} \quad \text{tabletype} = \text{lim } rt \quad C \vdash \text{expr} : rt \text{ const}}{C \vdash \text{table } \text{tabletype } \text{expr} : \text{tabletype}}$$

3.5.5 Memories

Memories *mem* are classified by memory types.

{type *memtype*}

- The memory type *memtype* must be valid.
- Then the memory definition is valid with type *memtype*.

$$\frac{C \vdash \text{memtype} : \text{ok}}{C \vdash \text{memory } \text{memtype} : \text{memtype}}$$

3.5.6 Globals

Globals *global* are classified by global types.

Sequences of globals are handled incrementally, such that each definition has access to previous definitions.

{type *mut t*, init *expr*}

- The global type *mut t* must be valid.
- The expression *expr* must be valid with result type $[t]$.
- The expression *expr* must be constant.
- Then the global definition is valid with type *mut t*.

$$\frac{C \vdash \text{gt} : \text{ok} \quad \text{globaltype} = \text{mut}^? t \quad C \vdash \text{expr} : t \text{ const}}{C \vdash \text{global } \text{globaltype } \text{expr} : \text{globaltype}}$$

*global**

- If the sequence is empty, then it is valid with the empty sequence of global types.
- Else:
 - The first global definition must be valid with some type global type gt_1 .
 - Let C' be the same context as C , but with the global type gt_1 appended to the globals list.
 - Under context C' , the remainder of the sequence must be valid with some sequence gt^* of global types.
 - Then the sequence is valid with the sequence of global types consisting of gt_1 prepended to gt^* .

$$\frac{}{C \vdash \epsilon : \epsilon} \quad \frac{C \vdash \text{global} : gt_1 \quad C[\text{globals} = ..gt_1] \vdash \text{global}^* : gt^*}{C \vdash \text{global}_1 \text{ global}^* : gt_1 gt^*}$$

3.5.7 Element Segments

Element segments *elem* are classified by the [reference type](#) of their elements.

$\{\text{type } t, \text{init } e^*, \text{mode } \textit{elemmode}\}$

- The [reference type](#) t must be [valid](#).
- For each e_i in e^* ,
 - The expression e_i must be [valid](#) with some [result type](#) $[t]$.
 - The expression e_i must be [constant](#).
- The element mode *elemmode* must be [valid](#) with some [reference type](#) t' .
- The [reference type](#) t must [match](#) the [reference type](#) t' .
- Then the element segment is [valid](#) with [reference type](#) t .

$$\frac{C \vdash \textit{elemtype} : \text{ok} \quad (C \vdash \textit{expr} : \textit{elemtype} \text{ const})^* \quad C \vdash \textit{elemmode} : \textit{elemtype}}{C \vdash \text{elem } \textit{elemtype} \textit{ expr}^* \textit{ elemmode} : \textit{elemtype}}$$

[passive](#)

- The element mode is [valid](#) with any [valid reference type](#).

$$\overline{C \vdash \text{passive} : rt}$$

[active](#) $\{\text{table } x, \text{offset } \textit{expr}\}$

- The table $C.\text{tables}[x]$ must be defined in the context.
- Let *limits* t be the [table type](#) $C.\text{tables}[x]$.
- The expression *expr* must be [valid](#) with [result type](#) $[i32]$.
- The expression *expr* must be [constant](#).
- Then the element mode is [valid](#) with [reference type](#) t .

$$\frac{C.\text{tables}[x] = \textit{lim } rt' \quad C \vdash rt \leq rt' \quad C \vdash \textit{expr} : i32 \text{ const}}{C \vdash \text{active } x \textit{ expr} : rt}$$

[declare](#)

- The element mode is [valid](#) with any [valid reference type](#).

$$\overline{C \vdash \text{declare} : rt}$$

3.5.8 Data Segments

Data segments *data* are not classified by any type but merely checked for well-formedness.

$\{\text{init } b^*, \text{mode } \textit{datamode}\}$

- The data mode *datamode* must be valid.
- Then the data segment is valid.

$$\frac{C \vdash \textit{datamode} : \text{ok}}{C \vdash \text{data } b^* \textit{datamode} : \text{ok}}$$

passive

- The data mode is valid.

$$\overline{C \vdash \text{passive} : \text{ok}}$$

active $\{\text{memory } x, \text{offset } \textit{expr}\}$

- The memory $C.\text{mems}[x]$ must be defined in the context.
- The expression *expr* must be valid with result type $[i32]$.
- The expression *expr* must be constant.
- Then the data mode is valid.

$$\frac{C.\text{mems}[x] = mt \quad C \vdash \textit{expr} : i32 \text{ const}}{C \vdash \text{active } x \textit{expr} : \text{ok}}$$

3.5.9 Start Function

Start function declarations *start* are not classified by any type.

$\{\text{func } x\}$

- The function $C.\text{funcs}[x]$ must be defined in the context.
- The expansion of $C.\text{funcs}[x]$ must be a function type $\text{func } [] \rightarrow []$.
- Then the start function is valid.

$$\frac{C.\text{funcs}[x] \approx \text{func } (\epsilon \rightarrow \epsilon)}{C \vdash \text{start } x : \text{ok}}$$

3.5.10 Exports

Exports *export* are classified by their external type.

{name *name*, desc *exportdesc*}

- The export description *exportdesc* must be valid with external type *externtype*.
- Then the export is valid with external type *externtype*.

$$\frac{C \vdash \text{externid}x : xt}{C \vdash \text{export name } \text{externid}x : xt}$$

func *x*

- The function $C.\text{funcs}[x]$ must be defined in the context.
- Let *dt* be the defined type $C.\text{funcs}[x]$.
- Then the export description is valid with external type func *dt*.

$$\frac{C.\text{funcs}[x] = dt}{C \vdash \text{func } x : \text{func } dt}$$

table *x*

- The table $C.\text{tables}[x]$ must be defined in the context.
- Then the export description is valid with external type table $C.\text{tables}[x]$.

$$\frac{C.\text{tables}[x] = tt}{C \vdash \text{table } x : \text{table } tt}$$

mem *x*

- The memory $C.\text{mems}[x]$ must be defined in the context.
- Then the export description is valid with external type mem $C.\text{mems}[x]$.

$$\frac{C.\text{mems}[x] = mt}{C \vdash \text{memory } x : \text{mem } mt}$$

global *x*

- The global $C.\text{globals}[x]$ must be defined in the context.
- Then the export description is valid with external type global $C.\text{globals}[x]$.

$$\frac{C.\text{globals}[x] = gt}{C \vdash \text{global } x : \text{global } gt}$$

3.5.11 Imports

Imports *import* are classified by external types.

$\{\text{module } name_1, \text{name } name_2, \text{desc } importdesc\}$

- The import description *importdesc* must be valid with type *externtype*.
- Then the import is valid with type *externtype*.

$$\frac{C \vdash xt : ok}{C \vdash \text{import } name_1 \ name_2 \ xt : xt}$$

3.5.12 Modules

Modules are classified by their mapping from the **external types** of their **imports** to those of their **exports**.

A module is entirely *closed*, that is, its components can only refer to definitions that appear in the module itself. Consequently, no initial **context** is required. Instead, the **context** *C* for validation of the module's content is constructed from the definitions in the module.

The **external types** classifying a module may contain free **type indices** that refer to types defined within the module.

- Let *module* be the module to validate.
- The **types** *module.types* must be **valid** yielding a **context** *C*₀.
- Let *C* be a **context** where:
 - *C.types* is *C*₀.types,
 - *C.funcs* is **funcs**(*it*^{*}) concatenated with *dt*^{*}, with the import's **external types** *it*^{*} and the internal **defined types** *dt*^{*} as determined below,
 - *C.tables* is **tables**(*it*^{*}) concatenated with *tt*^{*}, with the import's **external types** *it*^{*} and the internal **table types** *tt*^{*} as determined below,
 - *C.mems* is **mems**(*it*^{*}) concatenated with *mt*^{*}, with the import's **external types** *it*^{*} and the internal **memory types** *mt*^{*} as determined below,
 - *C.globals* is **globals**(*it*^{*}) concatenated with *gt*^{*}, with the import's **external types** *it*^{*} and the internal **global types** *gt*^{*} as determined below,
 - *C.elems* is *rt*^{*} as determined below,
 - *C.datas* is *ok*^{*} as determined below,
 - *C.locals* is empty,
 - *C.labels* is empty,
 - *C.return* is empty.
 - *C.refs* is the set **funcidx**(*module* with **funcs** = ϵ with **start** = ϵ), i.e., the set of **function indices** occurring in the module, except in its **functions** or **start function**.
- Let *C'* be the **context** where:
 - *C'.globals* is the sequence **globals**(*it*^{*}),
 - *C'.types* is the same as *C.types*,
 - *C'.funcs* is the same as *C.funcs*,
 - *C'.tables* is the same as *C.tables*,
 - *C'.mems* is the same as *C.mems*,
 - *C'.refs* is the same as *C.refs*,
 - all other fields are empty.
- Under the context *C'*:

- The sequence `module.globals` of `globals` must be `valid` with a sequence gt^* of `global types`.
- For each $table_i$ in `module.tables`, the definition $table_i$ must be `valid` with a `table type` tt_i .
- For each mem_i in `module.mems`, the definition mem_i must be `valid` with a `memory type` mt_i .
- Under the context C :
 - For each $func_i$ in `module.funcs`, the definition $func_i$ must be `valid` with a `defined type` dt_i .
 - For each $elem_i$ in `module.elms`, the segment $elem_i$ must be `valid` with `reference type` rt_i .
 - For each $data_i$ in `module.datas`, the segment $data_i$ must be `valid` with `data type` ok_i .
 - If `module.start` is non-empty, then `module.start` must be `valid`.
 - For each $import_i$ in `module.imports`, the segment $import_i$ must be `valid` with an `external type` it_i .
 - For each $export_i$ in `module.exports`, the segment $export_i$ must be `valid` with `external type` et_i .
- Let dt^* be the concatenation of the internal `function types` dt_i , in index order.
- Let tt^* be the concatenation of the internal `table types` tt_i , in index order.
- Let mt^* be the concatenation of the internal `memory types` mt_i , in index order.
- Let rt^* be the concatenation of the `reference types` rt_i , in index order.
- Let ok^* be the concatenation of the `data types` ok_i , in index order.
- Let it^* be the concatenation of `external types` it_i of the imports, in index order.
- Let et^* be the concatenation of `external types` et_i of the exports, in index order.
- The length of `C.mems` must not be larger than 1.
- All export names $export_i.name$ must be different.
- Then the module is `valid` with `external types` $it^* \rightarrow et^*$.

$$\begin{array}{c}
 \{\} \vdash type^* : dt'^* \quad (\{types\ dt'^*\} \vdash import : xt_i)^* \\
 C' \vdash global^* : gt^* \quad (C' \vdash table : tt)^* \quad (C' \vdash mem : mt)^* \quad (C \vdash func : dt)^* \\
 (C \vdash elem : rt)^* \quad (C \vdash data : ok)^* \quad (C \vdash start : ok)^? \quad (C \vdash export : xt_e)^* \\
 C = \{types\ dt'^*,\ funcs\ dt_i^*\ dt^*,\ globals\ gt_i^*\ gt^*,\ tables\ tt_i^*\ tt^*,\ mems\ mt_i^*\ mt^*,\ elems\ rt^*,\ datas\ ok^*\} \\
 C' = \{types\ dt'^*,\ funcs\ dt_i^*\ dt^*,\ globals\ gt_i^*\} \\
 dt_i^* = funcs(xt_i^*) \quad gt_i^* = globals(xt_i^*) \quad tt_i^* = tables(xt_i^*) \quad mt_i^* = mems(xt_i^*) \\
 \hline
 \vdash module\ type^*\ import^*\ func^*\ global^*\ table^*\ mem^*\ elem^*\ data^*\ start^?\ export^* : clos_C(xt_i^* \rightarrow xt_e^*)
 \end{array}$$

Todo: Check refs; check export names

Note: All functions in a module are mutually recursive. Consequently, the definition of the `context` C in this rule is recursive: it depends on the outcome of validation of the function, table, memory, and global definitions contained in the module, which itself depends on C . However, this recursion is just a specification device. All types needed to construct C can easily be determined from a simple pre-pass over the module that does not perform any actual validation.

Globals, however, are not recursive but evaluated sequentially, such that each `constant expressions` only has access to imported or previously defined globals.

Note: The restriction on the number of memories may be lifted in future versions of WebAssembly.

4.1 Conventions

WebAssembly code is *executed* when *instantiating* a module or *invoking* an *exported* function on the resulting module *instance*.

Execution behavior is defined in terms of an *abstract machine* that models the *program state*. It includes a *stack*, which records operand values and control constructs, and an abstract *store* containing global state.

For each instruction, there is a rule that specifies the effect of its execution on the program state. Furthermore, there are rules describing the instantiation of a module. As with *validation*, all rules are given in two *equivalent* forms:

1. In *prose*, describing the execution in intuitive form.
2. In *formal notation*, describing the rule in mathematical form.¹⁸

Note: As with validation, the prose and formal rules are equivalent, so that understanding of the formal notation is *not* required to read this specification. The formalism offers a more concise description in notation that is used widely in programming languages semantics and is readily amenable to mathematical proof.

4.1.1 Prose Notation

Execution is specified by stylised, step-wise rules for each *instruction* of the *abstract syntax*. The following conventions are adopted in stating these rules.

- The execution rules implicitly assume a given *store* *S*.
- The execution rules also assume the presence of an implicit *stack* that is modified by *pushing* or *popping* values, labels, and frames.
- Certain rules require the stack to contain at least one frame. The most recent frame is referred to as the *current* frame.

¹⁸ The semantics is derived from the following article: Andreas Haas, Andreas Rossberg, Derek Schuff, Ben Titze, Dan Gohman, Luke Wagner, Alon Zakai, JF Bastien, Michael Holman. *Bringing the Web up to Speed with WebAssembly*^{Page 79, 19}. Proceedings of the 38th ACM SIGPLAN Conference on Programming Language Design and Implementation (PLDI 2017). ACM 2017.

¹⁹ <https://dl.acm.org/citation.cfm?doid=3062341.3062363>

- Both the store and the current frame are mutated by *replacing* some of their components. Such replacement is assumed to apply globally.
- The execution of an instruction may *trap*, in which case the entire computation is aborted and no further modifications to the store are performed by it. (Other computations can still be initiated afterwards.)
- The execution of an instruction may also end in a *jump* to a designated target, which defines the next instruction to execute.
- Execution can *enter* and *exit* [instruction sequences](#) that form [blocks](#).
- [Instruction sequences](#) are implicitly executed in order, unless a trap or jump occurs.
- In various places the rules contain *assertions* expressing crucial invariants about the program state.

4.1.2 Formal Notation

Note: This section gives a brief explanation of the notation for specifying execution formally. For the interested reader, a more thorough introduction can be found in respective text books.²⁰

The formal execution rules use a standard approach for specifying operational semantics, rendering them into *reduction rules*. Every rule has the following general form:

$$\text{configuration} \hookrightarrow \text{configuration}$$

A *configuration* is a syntactic description of a program state. Each rule specifies one *step* of execution. As long as there is at most one reduction rule applicable to a given configuration, reduction – and thereby execution – is *deterministic*. WebAssembly has only very few exceptions to this, which are noted explicitly in this specification.

For WebAssembly, a configuration typically is a tuple $(s; f; \text{instr}^*)$ consisting of the current [store](#) s , the [call frame](#) f of the current function, and the sequence of [instructions](#) that is to be executed. (A more precise definition is given [later](#).)

To avoid unnecessary clutter, the store s and the frame f are often combined into a *state* z , which is a pair $(s; f)$. Moreover, z is omitted from reduction rules that do not touch them.

There is no separate representation of the [stack](#). Instead, it is conveniently represented as part of the configuration’s instruction sequence. In particular, [values](#) are defined to coincide with `const` instructions, and a sequence of `const` instructions can be interpreted as an operand “stack” that grows to the right.

Note: For example, the [reduction rule](#) for the `i32.add` instruction can be given as follows:

$$(\text{i32.const } n_1) (\text{i32.const } n_2) \text{i32.add} \hookrightarrow (\text{i32.const } (n_1 + n_2) \bmod 2^{32})$$

Per this rule, two `const` instructions and the `add` instruction itself are removed from the instruction stream and replaced with one new `const` instruction. This can be interpreted as popping two values off the stack and pushing the result.

When no result is produced, an instruction reduces to the empty sequence:

$$\text{nop} \hookrightarrow \epsilon$$

[Labels](#) and [frames](#) are similarly [defined](#) to be part of an instruction sequence.

The order of reduction is determined by the details of the reduction rules. Usually, the left-most instruction that is not a constant will be the subject of the next reduction *step*.

²⁰ For example: Benjamin Pierce. [Types and Programming Languages](#)^{Page 80, 21}. The MIT Press 2002

²¹ <https://www.cis.upenn.edu/~bcpierce/tapl/>

Reduction *terminates* when no more reduction rules are applicable. [Soundness](#) of the WebAssembly type system guarantees that this is only the case when the original instruction sequence has either been reduced to a sequence of const instructions, which can be interpreted as the [values](#) of the resulting operand stack, or if a [trap](#) occurred.

Note: For example, the following instruction sequence,

$$(f64.const\ q_1)\ (f64.const\ q_2)\ f64.neg\ (f64.const\ q_3)\ f64.add\ f64.mul$$

terminates after three steps:

$$\begin{aligned} &\hookrightarrow (f64.const\ q_1)\ (f64.const\ q_4)\ (f64.const\ q_3)\ f64.add\ f64.mul \\ &\hookrightarrow (f64.const\ q_1)\ (f64.const\ q_5)\ f64.mul \\ &\hookrightarrow (f64.const\ q_6) \end{aligned}$$

where $q_4 = -q_2$ and $q_5 = -q_2 + q_3$ and $q_6 = q_1 \cdot (-q_2 + q_3)$.

4.2 Runtime Structure

[Store](#), [stack](#), and other *runtime structure* forming the WebAssembly abstract machine, such as [values](#) or [module instances](#), are made precise in terms of additional auxiliary syntax.

4.2.1 Values

WebAssembly computations manipulate *values* of either the four basic [number types](#), i.e., [integers](#) and [floating-point data](#) of 32 or 64 bit width each, or [vectors](#) of 128 bit width, or of [reference type](#).

In most places of the semantics, values of different types can occur. In order to avoid ambiguities, values are therefore represented with an abstract syntax that makes their type explicit. It is convenient to reuse the same notation as for the const [instructions](#) and [ref.null](#) producing them.

References other than null are represented with additional [administrative instructions](#). They either are *scalar references*, containing a 31-bit [integer](#), *structure references*, pointing to a specific [structure address](#), *array references*, pointing to a specific [array address](#), *function references*, pointing to a specific [function address](#), or *host references* pointing to an uninterpreted form of [host address](#) defined by the [embedder](#). Any of the aforementioned references can furthermore be wrapped up as an *external reference*.

$$\begin{aligned} val &::= num \mid vec \mid ref \\ num &::= numtype.const\ num_{numtype} \\ vec &::= vectype.const\ vec_{vectype} \\ ref &::= addrref \\ &\quad \mid ref.null\ heapttype \\ addrref &::= ref.i31\ u31 \\ &\quad \mid ref.struct\ structaddr \\ &\quad \mid ref.array\ arrayaddr \\ &\quad \mid ref.func\ funcaddr \\ &\quad \mid ref.host\ hostaddr \\ &\quad \mid ref.extern\ addrref \end{aligned}$$

Note: Future versions of WebAssembly may add additional forms of values.

[Value types](#) can have an associated *default value*; it is the respective value 0 for [number types](#), 0 for [vector types](#), and null for nullable [reference types](#). For other references, no default value is defined, $default_t$ hence is an optional

value *val*[?].

$$\begin{aligned} \text{default}_{iN} &= (iN.\text{const } 0) \\ \text{default}_{fN} &= (fN.\text{const } +0) \\ \text{default}_{vN} &= (vN.\text{const } 0) \\ \text{default}_{\text{ref null } ht} &= (\text{ref.null } ht) \\ \text{default}_{\text{ref } ht} &= \epsilon \end{aligned}$$

Convention

- The meta variable *r* ranges over reference values where clear from context.

4.2.2 Results

A *result* is the outcome of a computation. It is either a sequence of *values* or a *trap*.

$$\text{result} ::= \text{val}^* \mid \text{trap}$$

4.2.3 Store

The *store* represents all global state that can be manipulated by WebAssembly programs. It consists of the runtime representation of all *instances* of *functions*, *tables*, *memories*, and *globals*, *element segments*, *data segments*, and *structures* or *arrays* that have been *allocated* during the life time of the abstract machine.²²

It is an invariant of the semantics that no element or data instance is *addressed* from anywhere else but the owning module instances.

Syntactically, the store is defined as a *record* listing the existing instances of each category:

$$\text{store} ::= \{ \text{funcs } \text{funcinst}^*, \\ \text{globals } \text{globalinst}^*, \\ \text{tables } \text{tableinst}^*, \\ \text{mems } \text{meminst}^*, \\ \text{elems } \text{eleminst}^*, \\ \text{datas } \text{datainst}^*, \\ \text{structs } \text{structinst}^*, \\ \text{arrays } \text{arrayinst}^* \}$$

Convention

- The meta variable *s* ranges over stores where clear from context.

4.2.4 Addresses

Function instances, table instances, memory instances, and global instances, element instances, data instances and structure or array instances in the *store* are referenced with abstract *addresses*. These are simply indices into the

²² In practice, implementations may apply techniques like garbage collection to remove objects from the store that are no longer referenced. However, such techniques are not semantically observable, and hence outside the scope of this specification.

respective store component. In addition, an **embedder** may supply an uninterpreted set of *host addresses*.

$$\begin{aligned} \text{addr} &::= \mathbb{N} \\ \text{funcaddr} &::= \text{addr} \\ \text{tableaddr} &::= \text{addr} \\ \text{memaddr} &::= \text{addr} \\ \text{globaladdr} &::= \text{addr} \\ \text{elemaddr} &::= \text{addr} \\ \text{dataaddr} &::= \text{addr} \\ \text{structaddr} &::= \text{addr} \\ \text{arrayaddr} &::= \text{addr} \\ \text{hostaddr} &::= \text{addr} \end{aligned}$$

An **embedder** may assign identity to **exported** store objects corresponding to their addresses, even where this identity is not observable from within WebAssembly code itself (such as for **function instances** or immutable **globals**).

Note: Addresses are *dynamic*, globally unique references to runtime objects, in contrast to **indices**, which are *static*, module-local references to their original definitions. A *memory address* **memaddr** denotes the abstract address *of* a memory *instance* in the store, not an offset *inside* a memory instance.

There is no specific limit on the number of allocations of store objects, hence logical addresses can be arbitrarily large natural numbers.

Conventions

- The notation $\text{addr}(A)$ denotes the set of addresses from address space **addr** occurring free in A . We sometimes reinterpret this set as the **list** of its elements.

4.2.5 Module Instances

A *module instance* is the runtime representation of a **module**. It is created by **instantiating** a module, and collects runtime representations of all entities that are imported, defined, or exported by the module.

$$\text{moduleinst} ::= \{\text{types } \text{deftype}^*, \\ \text{funcs } \text{funcaddr}^*, \\ \text{globals } \text{globaladdr}^*, \\ \text{tables } \text{tableaddr}^*, \\ \text{mems } \text{memaddr}^*, \\ \text{elems } \text{elemaddr}^*, \\ \text{datas } \text{dataaddr}^*, \\ \text{exports } \text{exportinst}^*\}$$

Each component references runtime instances corresponding to respective declarations from the original module – whether imported or defined – in the order of their static **indices**. **Function instances**, **table instances**, **memory instances**, and **global instances** are referenced with an indirection through their respective **addresses** in the **store**.

It is an invariant of the semantics that all **export instances** in a given module instance have different **names**.

4.2.6 Function Instances

A *function instance* is the runtime representation of a [function](#). It effectively is a *closure* of the original function over the runtime [module instance](#) of its originating [module](#). The module instance is used to resolve references to other definitions during execution of the function.

$$\begin{aligned} \text{funcinst} &::= \{\text{type } \text{deftype}, \text{module } \text{moduleinst}, \text{code } \text{code}\} \\ \text{code} &::= \text{func} \mid \text{hostfunc} \end{aligned}$$

A *host function* is a function expressed outside WebAssembly but passed to a [module](#) as an [import](#). The definition and behavior of host functions are outside the scope of this specification. For the purpose of this specification, it is assumed that when [invoked](#), a host function behaves non-deterministically, but within certain [constraints](#) that ensure the integrity of the runtime.

Note: Function instances are immutable, and their identity is not observable by WebAssembly code. However, the [embedder](#) might provide implicit or explicit means for distinguishing their [addresses](#).

4.2.7 Table Instances

A *table instance* is the runtime representation of a [table](#). It records its [type](#) and holds a list of [reference values](#).

$$\text{tableinst} ::= \{\text{type } \text{tabletype}, \text{elem } \text{ref}^*\}$$

Table elements can be mutated through [table instructions](#), the execution of an active [element segment](#), or by external means provided by the [embedder](#).

It is an invariant of the semantics that all table elements have a type [matching](#) the element type of [tabletype](#). It also is an invariant that the length of the element list never exceeds the maximum size of [tabletype](#), if present.

4.2.8 Memory Instances

A *memory instance* is the runtime representation of a linear [memory](#). It records its [type](#) and holds a list of [bytes](#).

$$\text{meminst} ::= \{\text{type } \text{memtype}, \text{bytes } \text{byte}^*\}$$

The length of the list always is a multiple of the WebAssembly *page size*, which is defined to be the constant 65536 – abbreviated 64* Ki.

The bytes can be mutated through [memory instructions](#), the execution of an active [data segment](#), or by external means provided by the [embedder](#).

It is an invariant of the semantics that the length of the byte list, divided by page size, never exceeds the maximum size of [memtype](#).

4.2.9 Global Instances

A *global instance* is the runtime representation of a [global](#) variable. It records its [type](#) and holds an individual value.

$$\text{globalinst} ::= \{\text{type } \text{globaltype}, \text{value } \text{val}\}$$

The value of mutable globals can be mutated through [variable instructions](#) or by external means provided by the [embedder](#).

It is an invariant of the semantics that the value has a type [matching](#) the value type of [globaltype](#).

4.2.10 Element Instances

An *element instance* is the runtime representation of an [element segment](#). It holds a list of references and their common [type](#).

$$eleminst ::= \{\text{type } elemtype, \text{elem ref}^*\}$$

4.2.11 Data Instances

An *data instance* is the runtime representation of a [data segment](#). It holds a list of [bytes](#).

$$datainst ::= \{\text{bytes } byte^*\}$$

4.2.12 Export Instances

An *export instance* is the runtime representation of an [export](#). It defines the export's [name](#) and the associated [external value](#).

$$exportinst ::= \{\text{name } name, \text{value } externval\}$$

4.2.13 External Values

An *external value* is the runtime representation of an entity that can be imported or exported. It is an [address](#) denoting either a [function instance](#), [table instance](#), [memory instance](#), or [global instances](#) in the shared [store](#).

$$externval ::= \text{func } funcaddr \mid \text{global } globaladdr \mid \text{table } tableaddr \mid \text{mem } memaddr$$

Conventions

The following auxiliary notation is defined for sequences of external values. It filters out entries of a specific kind in an order-preserving fashion:

$\text{funcs}(\epsilon)$	$=$	ϵ	
$\text{funcs}((\text{func } fa) \, xv^*)$	$=$	$fa \, \text{funcs}(xv^*)$	
$\text{funcs}(externval \, xv^*)$	$=$	$\text{funcs}(xv^*)$	otherwise
$\text{tables}(\epsilon)$	$=$	ϵ	
$\text{tables}((\text{table } ta) \, xv^*)$	$=$	$ta \, \text{tables}(xv^*)$	
$\text{tables}(externval \, xv^*)$	$=$	$\text{tables}(xv^*)$	otherwise
$\text{mems}(\epsilon)$	$=$	ϵ	
$\text{mems}((\text{mem } ma) \, xv^*)$	$=$	$ma \, \text{mems}(xv^*)$	
$\text{mems}(externval \, xv^*)$	$=$	$\text{mems}(xv^*)$	otherwise
$\text{globals}(\epsilon)$	$=$	ϵ	
$\text{globals}((\text{global } ga) \, xv^*)$	$=$	$ga \, \text{globals}(xv^*)$	
$\text{globals}(externval \, xv^*)$	$=$	$\text{globals}(xv^*)$	otherwise

4.2.14 Aggregate Instances

A *structure instance* is the runtime representation of a heap object allocated from a [structure type](#). Likewise, an *array instance* is the runtime representation of a heap object allocated from an [array type](#). Both record their respective [defined type](#) and hold a list of the values of their *fields*.

$$\begin{aligned} \text{structinst} &::= \{\text{type } \text{deftype}, \text{fields } \text{fieldval}^*\} \\ \text{arrayinst} &::= \{\text{type } \text{deftype}, \text{fields } \text{fieldval}^*\} \\ \text{fieldval} &::= \text{val} \mid \text{packval} \\ \text{packval} &::= \text{packtype.pack } iN \end{aligned}$$

Conventions

- Conversion of a regular [value](#) to a [field value](#) is defined as follows:

$$\begin{aligned} \text{pack}_{\text{valtype}}(\text{val}) &= \text{val} \\ \text{pack}_{\text{packtype}}(\text{i32.const } i) &= \text{packtype.pack wrap}_{32,|\text{packtype}|}(i) \end{aligned}$$

- The inverse conversion of a [field value](#) to a regular [value](#) is defined as follows:

$$\begin{aligned} \text{unpack}_{\text{valtype}}^e(\text{val}) &= \text{val} \\ \text{unpack}_{\text{packtype}}^{sx}(\text{packtype.pack } i) &= \text{i32.const extend}_{|\text{packtype}|,32}^{sx}(i) \end{aligned}$$

4.2.15 Stack

Besides the [store](#), most [instructions](#) interact with an implicit *stack*. The stack contains three kinds of entries:

- *Values*: the *operands* of instructions.
- *Labels*: active [structured control instructions](#) that can be targeted by branches.
- *Frames*: the *call frames* of active [function](#) calls.

These entries can occur on the stack in any order during the execution of a program. Stack entries are described by abstract syntax as follows.

Note: It is possible to model the WebAssembly semantics using separate stacks for operands, control constructs, and calls. However, because the stacks are interdependent, additional book keeping about associated stack heights would be required. For the purpose of this specification, an interleaved representation is simpler.

Values

Values are represented by [themselves](#).

Labels

Labels carry an argument arity n and their associated branch *target*, which is expressed syntactically as an [instruction](#) sequence:

$$\text{label} ::= \text{label}_n \{ \text{instr}^* \}$$

Intuitively, instr^* is the *continuation* to execute when the branch is taken, in place of the original control construct.

Note: For example, a loop label has the form

$$\text{label}_n \{ (\text{loop } bt \dots) \}$$

When performing a branch to this label, this executes the loop, effectively restarting it from the beginning. Conversely, a simple block label has the form

$$\text{label}_n\{\epsilon\}$$

When branching, the empty continuation ends the targeted block, such that execution can proceed with consecutive instructions.

Call Frames

Call frames carry the return arity n of the respective function, hold the values of its **locals** (including arguments) in the order corresponding to their static **local indices**, and a reference to the function's own **module instance**:

$$\begin{aligned} \text{callframe} &::= \text{frame}_n\{\text{frame}\} \\ \text{frame} &::= \{\text{locals } (val^?)^*, \text{ module } \text{moduleinst}\} \end{aligned}$$

Locals may be uninitialized, in which case they are empty. Locals are mutated by respective **variable instructions**.

Conventions

- The meta variable L ranges over labels where clear from context.
- The meta variable f ranges over frame states where clear from context.
- The following auxiliary definition takes a **block type** and looks up the **instruction type** that it denotes in the current frame:

$$\begin{aligned} \text{instrtype}_z(x) &= ft && \text{if } z.\text{types}[x] \approx \text{func } ft \\ \text{instrtype}_z(t^?) &= \epsilon \rightarrow t^? \end{aligned}$$

4.2.16 Administrative Instructions

Note: This section is only relevant for the **formal notation**.

In order to express the reduction of **traps**, **calls**, and **control instructions**, the syntax of instructions is extended to include the following *administrative instructions*:

$$\text{instr} ::= \begin{array}{l} \dots \\ | \text{addrref} \\ | \text{label}_n\{\text{instr}^*\} \text{instr}^* \\ | \text{frame}_n\{\text{frame}\} \text{instr}^* \\ | \text{trap} \end{array}$$

An **address reference** represents an allocated **reference** value of respective form “on the stack”.

The label and frame instructions model **labels** and **frames** “on the stack”. Moreover, the administrative syntax maintains the nesting structure of the original **structured control instruction** or **function body** and their **instruction sequences**.

The trap instruction represents the occurrence of a trap. Traps are bubbled up through nested instruction sequences, ultimately reducing the entire program to a single trap instruction, signalling abrupt termination.

Note: For example, the **reduction rule** for block is:

$$(\text{block } bt \text{ instr}^*) \hookrightarrow (\text{label}_n\{\epsilon\} \text{ instr}^*)$$

if the **block type** bt denotes a **function type** $t_1^m \rightarrow t_2^n$, such that n is the block’s result arity. This rule replaces the block with a label instruction, which can be interpreted as “pushing” the label on the stack. When its end is reached, i.e., the inner instruction sequence has been reduced to the empty sequence – or rather, a sequence of n **values** representing the results – then the label instruction is eliminated courtesy of its own **reduction rule**:

$$(\text{label}_n \{instr^*\} val^*) \hookrightarrow val^*$$

This can be interpreted as removing the label from the stack and only leaving the locally accumulated operand values. Validation guarantees that n matches the number $|val^*|$ of resulting values at this point.

Configurations

A *configuration* describes the current computation. It consists of the computations’s *state* and the sequence of **instructions** left to execute. The state in turn consists of a global **store** and a current **frame** referring to the **module instance** in which the computation runs, i.e., where the current function originates from.

$$\begin{aligned} config &::= state; instr^* \\ state &::= store; frame \end{aligned}$$

Note: The current version of WebAssembly is single-threaded, but configurations with multiple threads may be supported in the future.

4.3 Numerics

Numeric primitives are defined in a generic manner, by operators indexed over a bit width N .

Some operators are *non-deterministic*, because they can return one of several possible results (such as different NaN values). Technically, each operator thus returns a *set* of allowed values. For convenience, deterministic results are expressed as plain values, which are assumed to be identified with a respective singleton set.

Some operators are *partial*, because they are not defined on certain inputs. Technically, an empty set of results is returned for these inputs.

In formal notation, each operator is defined by equational clauses that apply in decreasing order of precedence. That is, the first clause that is applicable to the given arguments defines the result. In some cases, similar clauses are combined into one by using the notation \pm or \mp . When several of these placeholders occur in a single clause, then they must be resolved consistently: either the upper sign is chosen for all of them or the lower sign.

Note: For example, the **fcopysign** operator is defined as follows:

$$\begin{aligned} \text{fcopysign}_N(\pm p_1, \pm p_2) &= \pm p_1 \\ \text{fcopysign}_N(\pm p_1, \mp p_2) &= \mp p_1 \end{aligned}$$

This definition is to be read as a shorthand for the following expansion of each clause into two separate ones:

$$\begin{aligned} \text{fcopysign}_N(+p_1, +p_2) &= +p_1 \\ \text{fcopysign}_N(-p_1, -p_2) &= -p_1 \\ \text{fcopysign}_N(+p_1, -p_2) &= -p_1 \\ \text{fcopysign}_N(-p_1, +p_2) &= +p_1 \end{aligned}$$

Numeric operators are lifted to input sequences by applying the operator element-wise, returning a sequence of results. When there are multiple inputs, they must be of equal length.

$$op(c_1^n, \dots, c_k^n) = op(c_1^n[0], \dots, c_k^n[0]) \dots op(c_1^n[n-1], \dots, c_k^n[n-1])$$

Note: For example, the unary operator `fabs`, when given a sequence of floating-point values, return a sequence of floating-point results:

$$\text{fabs}_N(z^n) = \text{fabs}_N(z[0]) \dots \text{fabs}_N(z[n])$$

The binary operator `iadd`, when given two sequences of integers of the same length, n , return a sequence of integer results:

$$\text{iadd}_N(i_1^n, i_2^n) = \text{iadd}_N(i_1[0], i_2[0]) \dots \text{iadd}_N(i_1[n], i_2[n])$$

Conventions:

- The meta variable d is used to range over single bits.
- The meta variable p is used to range over (signless) *magnitudes* of floating-point values, including `nan` and ∞ .
- The meta variable q is used to range over (signless) *rational magnitudes*, excluding `nan` or ∞ .
- The notation f^{-1} denotes the inverse of a bijective function f .
- Truncation of rational values is written `trunc`($\pm q$), with the usual mathematical definition:

$$\text{trunc}(\pm q) = \pm i \quad (\text{if } i \in \mathbb{N} \wedge +q - 1 < i \leq +q)$$

- Saturation of integers is written `sat_uN`(i) and `sat_sN`(i). The arguments to these two functions range over arbitrary signed integers.

- Unsigned saturation, `sat_uN`(i) clamps i to between 0 and $2^N - 1$:

$$\begin{aligned} \text{sat_u}_N(i) &= 2^N - 1 && (\text{if } i > 2^N - 1) \\ \text{sat_u}_N(i) &= 0 && (\text{if } i < 0) \\ \text{sat_u}_N(i) &= i && (\text{otherwise}) \end{aligned}$$

- Signed saturation, `sat_sN`(i) clamps i to between -2^{N-1} and $2^{N-1} - 1$:

$$\begin{aligned} \text{sat_s}_N(i) &= \text{signed}_N^{-1}(-2^{N-1}) && (\text{if } i < -2^{N-1}) \\ \text{sat_s}_N(i) &= \text{signed}_N^{-1}(2^{N-1} - 1) && (\text{if } i > 2^{N-1} - 1) \\ \text{sat_s}_N(i) &= i && (\text{otherwise}) \end{aligned}$$

4.3.1 Representations

Numbers and numeric vectors have an underlying binary representation as a sequence of bits:

$$\begin{aligned} \text{bits}_{iN}(i) &= \text{ibits}_N(i) \\ \text{bits}_{fN}(z) &= \text{fbits}_N(z) \\ \text{bits}_{vN}(i) &= \text{ibits}_N(i) \end{aligned}$$

The first case of these applies to representations of both integer *value types* and *packed types*.

Each of these functions is a bijection, hence they are invertible.

Integers

Integers are represented as base two unsigned numbers:

$$\text{ibits}_N(i) = d_{N-1} \dots d_0 \quad (i = 2^{N-1} \cdot d_{N-1} + \dots + 2^0 \cdot d_0)$$

Boolean operators like \wedge , \vee , or $\underline{\vee}$ are lifted to bit sequences of equal length by applying them pointwise.

Floating-Point

Floating-point values are represented in the respective binary format defined by IEEE 754²³ (Section 3.4):

$$\begin{aligned} \text{fbits}_N(\pm(1 + m \cdot 2^{-M}) \cdot 2^e) &= \text{fsign}(\pm) \text{ibits}_E(e + \text{fbias}_N) \text{ibits}_M(m) \\ \text{fbits}_N(\pm(0 + m \cdot 2^{-M}) \cdot 2^e) &= \text{fsign}(\pm) (0)^E \text{ibits}_M(m) \\ \text{fbits}_N(\pm\infty) &= \text{fsign}(\pm) (1)^E (0)^M \\ \text{fbits}_N(\pm\text{nan}(n)) &= \text{fsign}(\pm) (1)^E \text{ibits}_M(n) \\ \text{fbias}_N &= 2^{E-1} - 1 \\ \text{fsign}(+) &= 0 \\ \text{fsign}(-) &= 1 \end{aligned}$$

where $M = \text{signif}(N)$ and $E = \text{expon}(N)$.

Vectors

Numeric vectors of type `vn` have the same underlying representation as an `iv`. They can also be interpreted as a sequence of numeric values packed into a `vn` with a particular *shape* $t \times M$, provided that $N = |t| \cdot M$.

$$\begin{aligned} \text{lanes}_{t \times M}(c) &= c_0 \dots c_{M-1} \\ (\text{where } w &= |t|/8 \\ &\wedge b^* = \text{bytes}_{iN}(c) \\ &\wedge c_i = \text{bytes}_t^{-1}(b^*[i \cdot w : w])) \end{aligned}$$

This function is a bijection on `iv`, hence it is invertible.

Todo: pack/unpacknum

Storage

When a number is stored into `memory`, it is converted into a sequence of `bytes` in `little endian`²⁴ byte order:

$$\begin{aligned} \text{bytes}_t(i) &= \text{littleendian}(\text{bits}_t(i)) \\ \text{littleendian}(\epsilon) &= \epsilon \\ \text{littleendian}(d^8 \ d'^*) &= \text{littleendian}(d'^*) \text{ibits}_8^{-1}(d^8) \end{aligned}$$

Again these functions are invertible bijections.

²³ <https://ieeexplore.ieee.org/document/8766229>

²⁴ <https://en.wikipedia.org/wiki/Endianness#Little-endian>

4.3.2 Integer Operations

Sign Interpretation

Integer operators are defined on i_N values. Operators that use a signed interpretation convert the value using the following definition, which takes the two's complement when the value lies in the upper half of the value range (i.e., its most significant bit is 1):

$$\begin{aligned}\text{signed}_N(i) &= i & (0 \leq i < 2^{N-1}) \\ \text{signed}_N(i) &= i - 2^N & (2^{N-1} \leq i < 2^N)\end{aligned}$$

This function is bijective, and hence invertible.

Boolean Interpretation

The integer result of predicates – i.e., [tests](#) and [relational](#) operators – is defined with the help of the following auxiliary function producing the value 1 or 0 depending on a condition.

$$\begin{aligned}\text{bool}(C) &= 1 & (\text{if } C) \\ \text{bool}(C) &= 0 & (\text{otherwise})\end{aligned}$$

$\text{iadd}_N(i_1, i_2)$

- Return the result of adding i_1 and i_2 modulo 2^N .

$$\text{iadd}_N(i_1, i_2) = (i_1 + i_2) \bmod 2^N$$

$\text{isub}_N(i_1, i_2)$

- Return the result of subtracting i_2 from i_1 modulo 2^N .

$$\text{isub}_N(i_1, i_2) = (i_1 - i_2 + 2^N) \bmod 2^N$$

$\text{imul}_N(i_1, i_2)$

- Return the result of multiplying i_1 and i_2 modulo 2^N .

$$\text{imul}_N(i_1, i_2) = (i_1 \cdot i_2) \bmod 2^N$$

$\text{idiv}_u(i_1, i_2)$

- If i_2 is 0, then the result is undefined.
- Else, return the result of dividing i_1 by i_2 , truncated toward zero.

$$\begin{aligned}\text{idiv}_u(i_1, 0) &= \{\} \\ \text{idiv}_u(i_1, i_2) &= \text{trunc}(i_1/i_2)\end{aligned}$$

Note: This operator is [partial](#).

$\text{idiv}_{sN}(i_1, i_2)$

- Let j_1 be the [signed interpretation](#) of i_1 .
- Let j_2 be the [signed interpretation](#) of i_2 .
- If j_2 is 0, then the result is undefined.
- Else if j_1 divided by j_2 is 2^{N-1} , then the result is undefined.
- Else, return the result of dividing j_1 by j_2 , truncated toward zero.

$$\begin{aligned}\text{idiv}_{sN}(i_1, 0) &= \{\} \\ \text{idiv}_{sN}(i_1, i_2) &= \{\} && (\text{if } \text{signed}_N(i_1)/\text{signed}_N(i_2) = 2^{N-1}) \\ \text{idiv}_{sN}(i_1, i_2) &= \text{signed}_N^{-1}(\text{trunc}(\text{signed}_N(i_1)/\text{signed}_N(i_2)))\end{aligned}$$

Note: This operator is [partial](#). Besides division by 0, the result of $(-2^{N-1})/(-1) = +2^{N-1}$ is not representable as an N -bit signed integer.

 $\text{irem}_{uN}(i_1, i_2)$

- If i_2 is 0, then the result is undefined.
- Else, return the remainder of dividing i_1 by i_2 .

$$\begin{aligned}\text{irem}_{uN}(i_1, 0) &= \{\} \\ \text{irem}_{uN}(i_1, i_2) &= i_1 - i_2 \cdot \text{trunc}(i_1/i_2)\end{aligned}$$

Note: This operator is [partial](#).

As long as both operators are defined, it holds that $i_1 = i_2 \cdot \text{idiv}_u(i_1, i_2) + \text{irem}_u(i_1, i_2)$.

 $\text{irem}_{sN}(i_1, i_2)$

- Let j_1 be the [signed interpretation](#) of i_1 .
- Let j_2 be the [signed interpretation](#) of i_2 .
- If i_2 is 0, then the result is undefined.
- Else, return the remainder of dividing j_1 by j_2 , with the sign of the dividend j_1 .

$$\begin{aligned}\text{irem}_{sN}(i_1, 0) &= \{\} \\ \text{irem}_{sN}(i_1, i_2) &= \text{signed}_N^{-1}(j_1 - j_2 \cdot \text{trunc}(j_1/j_2)) \\ &\quad (\text{where } j_1 = \text{signed}_N(i_1) \wedge j_2 = \text{signed}_N(i_2))\end{aligned}$$

Note: This operator is [partial](#).

As long as both operators are defined, it holds that $i_1 = i_2 \cdot \text{idiv}_s(i_1, i_2) + \text{irem}_s(i_1, i_2)$.

$\text{inot}_N(i)$

- Return the bitwise negation of i .

$$\text{inot}_N(i) = \text{ibits}_N^{-1}(\text{ibits}_N(i) \vee \text{ibits}_N(2^N - 1))$$

$\text{iand}_N(i_1, i_2)$

- Return the bitwise conjunction of i_1 and i_2 .

$$\text{iand}_N(i_1, i_2) = \text{ibits}_N^{-1}(\text{ibits}_N(i_1) \wedge \text{ibits}_N(i_2))$$

$\text{iandnot}_N(i_1, i_2)$

- Return the bitwise conjunction of i_1 and the bitwise negation of i_2 .

$$\text{iandnot}_N(i_1, i_2) = \text{iand}_N(i_1, \text{inot}_N(i_2))$$

$\text{ior}_N(i_1, i_2)$

- Return the bitwise disjunction of i_1 and i_2 .

$$\text{ior}_N(i_1, i_2) = \text{ibits}_N^{-1}(\text{ibits}_N(i_1) \vee \text{ibits}_N(i_2))$$

$\text{ixor}_N(i_1, i_2)$

- Return the bitwise exclusive disjunction of i_1 and i_2 .

$$\text{ixor}_N(i_1, i_2) = \text{ibits}_N^{-1}(\text{ibits}_N(i_1) \vee \text{ibits}_N(i_2))$$

$\text{ishl}_N(i_1, i_2)$

- Let k be i_2 modulo N .
- Return the result of shifting i_1 left by k bits, modulo 2^N .

$$\text{ishl}_N(i_1, i_2) = \text{ibits}_N^{-1}(d_2^{N-k} 0^k) \quad (\text{if } \text{ibits}_N(i_1) = d_1^k d_2^{N-k} \wedge k = i_2 \bmod N)$$

$\text{ishr_u}_N(i_1, i_2)$

- Let k be i_2 modulo N .
- Return the result of shifting i_1 right by k bits, extended with 0 bits.

$$\text{ishr_u}_N(i_1, i_2) = \text{ibits}_N^{-1}(0^k d_1^{N-k}) \quad (\text{if } \text{ibits}_N(i_1) = d_1^{N-k} d_2^k \wedge k = i_2 \bmod N)$$

$\text{ishr}_{\text{S}_N}(i_1, i_2)$

- Let k be i_2 modulo N .
- Return the result of shifting i_1 right by k bits, extended with the most significant bit of the original value.

$$\text{ishr}_{\text{S}_N}(i_1, i_2) = \text{ibits}_N^{-1}(d_0^{k+1} d_1^{N-k-1}) \quad (\text{if } \text{ibits}_N(i_1) = d_0 d_1^{N-k-1} d_2^k \wedge k = i_2 \bmod N)$$

$\text{irotl}_N(i_1, i_2)$

- Let k be i_2 modulo N .
- Return the result of rotating i_1 left by k bits.

$$\text{irotl}_N(i_1, i_2) = \text{ibits}_N^{-1}(d_2^{N-k} d_1^k) \quad (\text{if } \text{ibits}_N(i_1) = d_1^k d_2^{N-k} \wedge k = i_2 \bmod N)$$

$\text{irotr}_N(i_1, i_2)$

- Let k be i_2 modulo N .
- Return the result of rotating i_1 right by k bits.

$$\text{irotr}_N(i_1, i_2) = \text{ibits}_N^{-1}(d_2^k d_1^{N-k}) \quad (\text{if } \text{ibits}_N(i_1) = d_1^{N-k} d_2^k \wedge k = i_2 \bmod N)$$

$\text{iclz}_N(i)$

- Return the count of leading zero bits in i ; all bits are considered leading zeros if i is 0.

$$\text{iclz}_N(i) = k \quad (\text{if } \text{ibits}_N(i) = 0^k (1 d^*)^?)$$

$\text{ictz}_N(i)$

- Return the count of trailing zero bits in i ; all bits are considered trailing zeros if i is 0.

$$\text{ictz}_N(i) = k \quad (\text{if } \text{ibits}_N(i) = (d^* 1)^? 0^k)$$

$\text{ipopcnt}_N(i)$

- Return the count of non-zero bits in i .

$$\text{ipopcnt}_N(i) = k \quad (\text{if } \text{ibits}_N(i) = (0^* 1)^k 0^*)$$

$\text{ieqz}_N(i)$

- Return 1 if i is zero, 0 otherwise.

$$\text{ieqz}_N(i) = \text{bool}(i = 0)$$

$\text{ieq}_N(i_1, i_2)$

- Return 1 if i_1 equals i_2 , 0 otherwise.

$$\text{ieq}_N(i_1, i_2) = \text{bool}(i_1 = i_2)$$

$\text{ine}_N(i_1, i_2)$

- Return 1 if i_1 does not equal i_2 , 0 otherwise.

$$\text{ine}_N(i_1, i_2) = \text{bool}(i_1 \neq i_2)$$

$\text{ilt}_N(i_1, i_2)$

- Return 1 if i_1 is less than i_2 , 0 otherwise.

$$\text{ilt}_N(i_1, i_2) = \text{bool}(i_1 < i_2)$$

$\text{ilt}_{sN}(i_1, i_2)$

- Let j_1 be the signed interpretation of i_1 .
- Let j_2 be the signed interpretation of i_2 .
- Return 1 if j_1 is less than j_2 , 0 otherwise.

$$\text{ilt}_{sN}(i_1, i_2) = \text{bool}(\text{signed}_N(i_1) < \text{signed}_N(i_2))$$

$\text{igt}_N(i_1, i_2)$

- Return 1 if i_1 is greater than i_2 , 0 otherwise.

$$\text{igt}_N(i_1, i_2) = \text{bool}(i_1 > i_2)$$

$\text{igt}_{sN}(i_1, i_2)$

- Let j_1 be the signed interpretation of i_1 .
- Let j_2 be the signed interpretation of i_2 .
- Return 1 if j_1 is greater than j_2 , 0 otherwise.

$$\text{igt}_{sN}(i_1, i_2) = \text{bool}(\text{signed}_N(i_1) > \text{signed}_N(i_2))$$

$\text{ile}_N(i_1, i_2)$

- Return 1 if i_1 is less than or equal to i_2 , 0 otherwise.

$$\text{ile}_N(i_1, i_2) = \text{bool}(i_1 \leq i_2)$$

$\text{ile}_{sN}(i_1, i_2)$

- Let j_1 be the [signed interpretation](#) of i_1 .
- Let j_2 be the [signed interpretation](#) of i_2 .
- Return 1 if j_1 is less than or equal to j_2 , 0 otherwise.

$$\text{ile}_{sN}(i_1, i_2) = \text{bool}(\text{signed}_N(i_1) \leq \text{signed}_N(i_2))$$

$\text{ige}_{uN}(i_1, i_2)$

- Return 1 if i_1 is greater than or equal to i_2 , 0 otherwise.

$$\text{ige}_{uN}(i_1, i_2) = \text{bool}(i_1 \geq i_2)$$

$\text{ige}_{sN}(i_1, i_2)$

- Let j_1 be the [signed interpretation](#) of i_1 .
- Let j_2 be the [signed interpretation](#) of i_2 .
- Return 1 if j_1 is greater than or equal to j_2 , 0 otherwise.

$$\text{ige}_{sN}(i_1, i_2) = \text{bool}(\text{signed}_N(i_1) \geq \text{signed}_N(i_2))$$

$\text{iextend}_{M,sN}(i)$

- Let j be the result of computing $\text{wrap}_{N,M}(i)$.
- Return $\text{extend}_{M,N}^s(j)$.

$$\text{iextend}_{M,sN}(i) = \text{extend}_{M,N}^s(\text{wrap}_{N,M}(i))$$

$\text{ibitselect}_N(i_1, i_2, i_3)$

- Let j_1 be the bitwise conjunction of i_1 and i_3 .
- Let j'_3 be the bitwise negation of i_3 .
- Let j_2 be the bitwise conjunction of i_2 and j'_3 .
- Return the bitwise disjunction of j_1 and j_2 .

$$\text{ibitselect}_N(i_1, i_2, i_3) = \text{ior}_N(\text{iand}_N(i_1, i_3), \text{iand}_N(i_2, \text{inot}_N(i_3)))$$

$\text{iabs}_N(i)$

- Let j be the [signed interpretation](#) of i .
- If j is greater than or equal to 0, then return i .
- Else return the negation of j , modulo 2^N .

$$\begin{aligned} \text{iabs}_N(i) &= i && \text{(if } \text{signed}_N(i) \geq 0 \text{)} \\ \text{iabs}_N(i) &= -\text{signed}_N(i) \bmod 2^N && \text{(otherwise)} \end{aligned}$$

$\text{ineg}_N(i)$

- Return the result of negating i , modulo 2^N .

$$\text{ineg}_N(i) = (2^N - i) \bmod 2^N$$

$\text{imin}_{u_N}(i_1, i_2)$

- Return i_1 if $\text{ilt}_{u_N}(i_1, i_2)$ is 1, return i_2 otherwise.

$$\begin{aligned} \text{imin}_{u_N}(i_1, i_2) &= i_1 && (\text{if } \text{ilt}_{u_N}(i_1, i_2) = 1) \\ \text{imin}_{u_N}(i_1, i_2) &= i_2 && (\text{otherwise}) \end{aligned}$$

$\text{imin}_{s_N}(i_1, i_2)$

- Return i_1 if $\text{ilt}_{s_N}(i_1, i_2)$ is 1, return i_2 otherwise.

$$\begin{aligned} \text{imin}_{s_N}(i_1, i_2) &= i_1 && (\text{if } \text{ilt}_{s_N}(i_1, i_2) = 1) \\ \text{imin}_{s_N}(i_1, i_2) &= i_2 && (\text{otherwise}) \end{aligned}$$

$\text{imax}_{u_N}(i_1, i_2)$

- Return i_1 if $\text{igt}_{u_N}(i_1, i_2)$ is 1, return i_2 otherwise.

$$\begin{aligned} \text{imax}_{u_N}(i_1, i_2) &= i_1 && (\text{if } \text{igt}_{u_N}(i_1, i_2) = 1) \\ \text{imax}_{u_N}(i_1, i_2) &= i_2 && (\text{otherwise}) \end{aligned}$$

$\text{imax}_{s_N}(i_1, i_2)$

- Return i_1 if $\text{igt}_{s_N}(i_1, i_2)$ is 1, return i_2 otherwise.

$$\begin{aligned} \text{imax}_{s_N}(i_1, i_2) &= i_1 && (\text{if } \text{igt}_{s_N}(i_1, i_2) = 1) \\ \text{imax}_{s_N}(i_1, i_2) &= i_2 && (\text{otherwise}) \end{aligned}$$

$\text{iadd}_{\text{sat}_{u_N}}(i_1, i_2)$

- Let i be the result of adding i_1 and i_2 .
- Return $\text{sat}_{u_N}(i)$.

$$\text{iadd}_{\text{sat}_{u_N}}(i_1, i_2) = \text{sat}_{u_N}(i_1 + i_2)$$

$\text{iadd}_{\text{sat}_{s_N}}(i_1, i_2)$

- Let j_1 be the signed interpretation of i_1
- Let j_2 be the signed interpretation of i_2
- Let j be the result of adding j_1 and j_2 .
- Return $\text{sat}_{s_N}(j)$.

$$\text{iadd}_{\text{sat}_{s_N}}(i_1, i_2) = \text{sat}_{s_N}(\text{signed}_N(i_1) + \text{signed}_N(i_2))$$

$\text{isub_sat_u}_N(i_1, i_2)$

- Let i be the result of subtracting i_2 from i_1 .
- Return $\text{sat_u}_N(i)$.

$$\text{isub_sat_u}_N(i_1, i_2) = \text{sat_u}_N(i_1 - i_2)$$

$\text{isub_sat_s}_N(i_1, i_2)$

- Let j_1 be the signed interpretation of i_1
- Let j_2 be the signed interpretation of i_2
- Let j be the result of subtracting j_2 from j_1 .
- Return $\text{sat_s}_N(j)$.

$$\text{isub_sat_s}_N(i_1, i_2) = \text{sat_s}_N(\text{signed}_N(i_1) - \text{signed}_N(i_2))$$

$\text{iavgr_u}_N(i_1, i_2)$

- Let j be the result of adding i_1 , i_2 , and 1.
- Return the result of dividing j by 2, truncated toward zero.

$$\text{iavgr_u}_N(i_1, i_2) = \text{trunc}((i_1 + i_2 + 1)/2)$$

$\text{iq15mulrsat_s}_N(i_1, i_2)$

- Return the result of $\text{sat_s}_N(\text{ishr_s}_N(i_1 \cdot i_2 + 2^{14}, 15))$.

$$\text{iq15mulrsat_s}_N(i_1, i_2) = \text{sat_s}_N(\text{ishr_s}_N(i_1 \cdot i_2 + 2^{14}, 15))$$

4.3.3 Floating-Point Operations

Floating-point arithmetic follows the [IEEE 754²⁵](#) standard, with the following qualifications:

- All operators use round-to-nearest ties-to-even, except where otherwise specified. Non-default directed rounding attributes are not supported.
- Following the recommendation that operators propagate NaN payloads from their operands is permitted but not required.
- All operators use “non-stop” mode, and floating-point exceptions are not otherwise observable. In particular, neither alternate floating-point exception handling attributes nor operators on status flags are supported. There is no observable difference between quiet and signalling NaNs.

Note: Some of these limitations may be lifted in future versions of WebAssembly.

²⁵ <https://ieeexplore.ieee.org/document/8766229>

Rounding

Rounding always is round-to-nearest ties-to-even, in correspondence with IEEE 754²⁶ (Section 4.3.1).

An *exact* floating-point number is a rational number that is exactly representable as a *floating-point number* of given bit width N .

A *limit* number for a given floating-point bit width N is a positive or negative number whose magnitude is the smallest power of 2 that is not exactly representable as a floating-point number of width N (that magnitude is 2^{128} for $N = 32$ and 2^{1024} for $N = 64$).

A *candidate* number is either an exact floating-point number or a positive or negative limit number for the given bit width N .

A *candidate pair* is a pair z_1, z_2 of candidate numbers, such that no candidate number exists that lies between the two.

A real number r is converted to a floating-point value of bit width N as follows:

- If r is 0, then return $+0$.
- Else if r is an exact floating-point number, then return r .
- Else if r greater than or equal to the positive limit, then return $+\infty$.
- Else if r is less than or equal to the negative limit, then return $-\infty$.
- Else if z_1 and z_2 are a candidate pair such that $z_1 < r < z_2$, then:
 - If $|r - z_1| < |r - z_2|$, then let z be z_1 .
 - Else if $|r - z_1| > |r - z_2|$, then let z be z_2 .
 - Else if $|r - z_1| = |r - z_2|$ and the *significand* of z_1 is even, then let z be z_1 .
 - Else, let z be z_2 .
- If z is 0, then:
 - If $r < 0$, then return -0 .
 - Else, return $+0$.
- Else if z is a limit number, then:
 - If $r < 0$, then return $-\infty$.
 - Else, return $+\infty$.

- Else, return z .

$\text{float}_N(0)$	$=$	$+0$	
$\text{float}_N(r)$	$=$	r	(if $r \in \text{exact}_N$)
$\text{float}_N(r)$	$=$	$+\infty$	(if $r \geq +\text{limit}_N$)
$\text{float}_N(r)$	$=$	$-\infty$	(if $r \leq -\text{limit}_N$)
$\text{float}_N(r)$	$=$	$\text{closest}_N(r, z_1, z_2)$	(if $z_1 < r < z_2 \wedge (z_1, z_2) \in \text{candidatepair}_N$)
$\text{closest}_N(r, z_1, z_2)$	$=$	$\text{rectify}_N(r, z_1)$	(if $ r - z_1 < r - z_2 $)
$\text{closest}_N(r, z_1, z_2)$	$=$	$\text{rectify}_N(r, z_2)$	(if $ r - z_1 > r - z_2 $)
$\text{closest}_N(r, z_1, z_2)$	$=$	$\text{rectify}_N(r, z_1)$	(if $ r - z_1 = r - z_2 \wedge \text{even}_N(z_1)$)
$\text{closest}_N(r, z_1, z_2)$	$=$	$\text{rectify}_N(r, z_2)$	(if $ r - z_1 = r - z_2 \wedge \text{even}_N(z_2)$)
$\text{rectify}_N(r, \pm\text{limit}_N)$	$=$	$\pm\infty$	
$\text{rectify}_N(r, 0)$	$=$	$+0$	($r \geq 0$)
$\text{rectify}_N(r, 0)$	$=$	-0	($r < 0$)
$\text{rectify}_N(r, z)$	$=$	z	

²⁶ <https://ieeexplore.ieee.org/document/8766229>

where:

$$\begin{aligned}
 \text{exact}_N &= fN \cap \mathbb{Q} \\
 \text{limit}_N &= 2^{2^{\text{expon}(N)} - 1} \\
 \text{candidate}_N &= \text{exact}_N \cup \{+\text{limit}_N, -\text{limit}_N\} \\
 \text{candidatepair}_N &= \{(z_1, z_2) \in \text{candidate}_N^2 \mid z_1 < z_2 \wedge \forall z \in \text{candidate}_N, z \leq z_1 \vee z \geq z_2\} \\
 \text{even}_N((d + m \cdot 2^{-M}) \cdot 2^e) &\Leftrightarrow m \bmod 2 = 0 \\
 \text{even}_N(\pm \text{limit}_N) &\Leftrightarrow \text{true}
 \end{aligned}$$

NaN Propagation

When the result of a floating-point operator other than `fneg`, `fabs`, or `fcopysign` is a NaN, then its sign is non-deterministic and the `payload` is computed as follows:

- If the payload of all NaN inputs to the operator is `canonical` (including the case that there are no NaN inputs), then the payload of the output is canonical as well.
- Otherwise the payload is picked non-deterministically among all `arithmetic NaNs`; that is, its most significant bit is 1 and all others are unspecified.

This non-deterministic result is expressed by the following auxiliary function producing a set of allowed outputs from a set of inputs:

$$\begin{aligned}
 \text{nans}_N\{z^*\} &= \{+\text{nan}(n), -\text{nan}(n) \mid n = \text{canon}_N\} && (\text{if } \forall \text{nan}(n) \in z^*, n = \text{canon}_N) \\
 \text{nans}_N\{z^*\} &= \{+\text{nan}(n), -\text{nan}(n) \mid n \geq \text{canon}_N\} && (\text{otherwise})
 \end{aligned}$$

`faddN(z1, z2)`

- If either z_1 or z_2 is a NaN, then return an element of $\text{nans}_N\{z_1, z_2\}$.
- Else if both z_1 and z_2 are infinities of opposite signs, then return an element of $\text{nans}_N\{\}$.
- Else if both z_1 and z_2 are infinities of equal sign, then return that infinity.
- Else if either z_1 or z_2 is an infinity, then return that infinity.
- Else if both z_1 and z_2 are zeroes of opposite sign, then return positive zero.
- Else if both z_1 and z_2 are zeroes of equal sign, then return that zero.
- Else if either z_1 or z_2 is a zero, then return the other operand.
- Else if both z_1 and z_2 are values with the same magnitude but opposite signs, then return positive zero.
- Else return the result of adding z_1 and z_2 , `rounded` to the nearest representable value.

$$\begin{aligned}
 \text{fadd}_N(\pm \text{nan}(n), z_2) &= \text{nans}_N\{\pm \text{nan}(n), z_2\} \\
 \text{fadd}_N(z_1, \pm \text{nan}(n)) &= \text{nans}_N\{z_1, \pm \text{nan}(n)\} \\
 \text{fadd}_N(\pm\infty, \mp\infty) &= \text{nans}_N\{\} \\
 \text{fadd}_N(\pm\infty, \pm\infty) &= \pm\infty \\
 \text{fadd}_N(z_1, \pm\infty) &= \pm\infty \\
 \text{fadd}_N(\pm\infty, z_2) &= \pm\infty \\
 \text{fadd}_N(\pm 0, \mp 0) &= +0 \\
 \text{fadd}_N(\pm 0, \pm 0) &= \pm 0 \\
 \text{fadd}_N(z_1, \pm 0) &= z_1 \\
 \text{fadd}_N(\pm 0, z_2) &= z_2 \\
 \text{fadd}_N(\pm q, \mp q) &= +0 \\
 \text{fadd}_N(z_1, z_2) &= \text{float}_N(z_1 + z_2)
 \end{aligned}$$

$\text{fsub}_N(z_1, z_2)$

- If either z_1 or z_2 is a NaN, then return an element of $\text{nans}_N\{z_1, z_2\}$.
- Else if both z_1 and z_2 are infinities of equal signs, then return an element of $\text{nans}_N\{\}$.
- Else if both z_1 and z_2 are infinities of opposite sign, then return z_1 .
- Else if z_1 is an infinity, then return that infinity.
- Else if z_2 is an infinity, then return that infinity negated.
- Else if both z_1 and z_2 are zeroes of equal sign, then return positive zero.
- Else if both z_1 and z_2 are zeroes of opposite sign, then return z_1 .
- Else if z_2 is a zero, then return z_1 .
- Else if z_1 is a zero, then return z_2 negated.
- Else if both z_1 and z_2 are the same value, then return positive zero.
- Else return the result of subtracting z_2 from z_1 , **rounded** to the nearest representable value.

$$\begin{aligned}
 \text{fsub}_N(\pm\text{nan}(n), z_2) &= \text{nans}_N\{\pm\text{nan}(n), z_2\} \\
 \text{fsub}_N(z_1, \pm\text{nan}(n)) &= \text{nans}_N\{\pm\text{nan}(n), z_1\} \\
 \text{fsub}_N(\pm\infty, \pm\infty) &= \text{nans}_N\{\} \\
 \text{fsub}_N(\pm\infty, \mp\infty) &= \pm\infty \\
 \text{fsub}_N(z_1, \pm\infty) &= \mp\infty \\
 \text{fsub}_N(\pm\infty, z_2) &= \pm\infty \\
 \text{fsub}_N(\pm 0, \pm 0) &= +0 \\
 \text{fsub}_N(\pm 0, \mp 0) &= \pm 0 \\
 \text{fsub}_N(z_1, \pm 0) &= z_1 \\
 \text{fsub}_N(\pm 0, \pm q_2) &= \mp q_2 \\
 \text{fsub}_N(\pm q, \pm q) &= +0 \\
 \text{fsub}_N(z_1, z_2) &= \text{float}_N(z_1 - z_2)
 \end{aligned}$$

Note: Up to the non-determinism regarding NaNs, it always holds that $\text{fsub}_N(z_1, z_2) = \text{fadd}_N(z_1, \text{fneg}_N(z_2))$.

$\text{fmul}_N(z_1, z_2)$

- If either z_1 or z_2 is a NaN, then return an element of $\text{nans}_N\{z_1, z_2\}$.
- Else if one of z_1 and z_2 is a zero and the other an infinity, then return an element of $\text{nans}_N\{\}$.
- Else if both z_1 and z_2 are infinities of equal sign, then return positive infinity.
- Else if both z_1 and z_2 are infinities of opposite sign, then return negative infinity.
- Else if either z_1 or z_2 is an infinity and the other a value with equal sign, then return positive infinity.
- Else if either z_1 or z_2 is an infinity and the other a value with opposite sign, then return negative infinity.
- Else if both z_1 and z_2 are zeroes of equal sign, then return positive zero.
- Else if both z_1 and z_2 are zeroes of opposite sign, then return negative zero.
- Else return the result of multiplying z_1 and z_2 , **rounded** to the nearest representable value.

$\text{fmul}_N(\pm\text{nan}(n), z_2)$	$= \text{nans}_N\{\pm\text{nan}(n), z_2\}$
$\text{fmul}_N(z_1, \pm\text{nan}(n))$	$= \text{nans}_N\{\pm\text{nan}(n), z_1\}$
$\text{fmul}_N(\pm\infty, \pm 0)$	$= \text{nans}_N\{\}$
$\text{fmul}_N(\pm\infty, \mp 0)$	$= \text{nans}_N\{\}$
$\text{fmul}_N(\pm 0, \pm\infty)$	$= \text{nans}_N\{\}$
$\text{fmul}_N(\pm 0, \mp\infty)$	$= \text{nans}_N\{\}$
$\text{fmul}_N(\pm\infty, \pm\infty)$	$= +\infty$
$\text{fmul}_N(\pm\infty, \mp\infty)$	$= -\infty$
$\text{fmul}_N(\pm q_1, \pm\infty)$	$= +\infty$
$\text{fmul}_N(\pm q_1, \mp\infty)$	$= -\infty$
$\text{fmul}_N(\pm\infty, \pm q_2)$	$= +\infty$
$\text{fmul}_N(\pm\infty, \mp q_2)$	$= -\infty$
$\text{fmul}_N(\pm 0, \pm 0)$	$= +0$
$\text{fmul}_N(\pm 0, \mp 0)$	$= -0$
$\text{fmul}_N(z_1, z_2)$	$= \text{float}_N(z_1 \cdot z_2)$

$\text{fdiv}_N(z_1, z_2)$

- If either z_1 or z_2 is a NaN, then return an element of $\text{nans}_N\{z_1, z_2\}$.
- Else if both z_1 and z_2 are infinities, then return an element of $\text{nans}_N\{\}$.
- Else if both z_1 and z_2 are zeroes, then return an element of $\text{nans}_N\{z_1, z_2\}$.
- Else if z_1 is an infinity and z_2 a value with equal sign, then return positive infinity.
- Else if z_1 is an infinity and z_2 a value with opposite sign, then return negative infinity.
- Else if z_2 is an infinity and z_1 a value with equal sign, then return positive zero.
- Else if z_2 is an infinity and z_1 a value with opposite sign, then return negative zero.
- Else if z_1 is a zero and z_2 a value with equal sign, then return positive zero.
- Else if z_1 is a zero and z_2 a value with opposite sign, then return negative zero.
- Else if z_2 is a zero and z_1 a value with equal sign, then return positive infinity.
- Else if z_2 is a zero and z_1 a value with opposite sign, then return negative infinity.
- Else return the result of dividing z_1 by z_2 , **rounded** to the nearest representable value.

$\text{fdiv}_N(\pm\text{nan}(n), z_2)$	$= \text{nans}_N\{\pm\text{nan}(n), z_2\}$
$\text{fdiv}_N(z_1, \pm\text{nan}(n))$	$= \text{nans}_N\{\pm\text{nan}(n), z_1\}$
$\text{fdiv}_N(\pm\infty, \pm\infty)$	$= \text{nans}_N\{\}$
$\text{fdiv}_N(\pm\infty, \mp\infty)$	$= \text{nans}_N\{\}$
$\text{fdiv}_N(\pm 0, \pm 0)$	$= \text{nans}_N\{\}$
$\text{fdiv}_N(\pm 0, \mp 0)$	$= \text{nans}_N\{\}$
$\text{fdiv}_N(\pm\infty, \pm q_2)$	$= +\infty$
$\text{fdiv}_N(\pm\infty, \mp q_2)$	$= -\infty$
$\text{fdiv}_N(\pm q_1, \pm\infty)$	$= +0$
$\text{fdiv}_N(\pm q_1, \mp\infty)$	$= -0$
$\text{fdiv}_N(\pm 0, \pm q_2)$	$= +0$
$\text{fdiv}_N(\pm 0, \mp q_2)$	$= -0$
$\text{fdiv}_N(\pm q_1, \pm 0)$	$= +\infty$
$\text{fdiv}_N(\pm q_1, \mp 0)$	$= -\infty$
$\text{fdiv}_N(z_1, z_2)$	$= \text{float}_N(z_1 / z_2)$

$\text{fmin}_N(z_1, z_2)$

- If either z_1 or z_2 is a NaN, then return an element of $\text{nans}_N\{z_1, z_2\}$.
- Else if either z_1 or z_2 is a negative infinity, then return negative infinity.
- Else if either z_1 or z_2 is a positive infinity, then return the other value.
- Else if both z_1 and z_2 are zeroes of opposite signs, then return negative zero.
- Else return the smaller value of z_1 and z_2 .

$$\begin{aligned}
 \text{fmin}_N(\pm\text{nan}(n), z_2) &= \text{nans}_N\{\pm\text{nan}(n), z_2\} \\
 \text{fmin}_N(z_1, \pm\text{nan}(n)) &= \text{nans}_N\{\pm\text{nan}(n), z_1\} \\
 \text{fmin}_N(+\infty, z_2) &= z_2 \\
 \text{fmin}_N(-\infty, z_2) &= -\infty \\
 \text{fmin}_N(z_1, +\infty) &= z_1 \\
 \text{fmin}_N(z_1, -\infty) &= -\infty \\
 \text{fmin}_N(\pm 0, \mp 0) &= -0 \\
 \text{fmin}_N(z_1, z_2) &= z_1 && (\text{if } z_1 \leq z_2) \\
 \text{fmin}_N(z_1, z_2) &= z_2 && (\text{if } z_2 \leq z_1)
 \end{aligned}$$

$\text{fmax}_N(z_1, z_2)$

- If either z_1 or z_2 is a NaN, then return an element of $\text{nans}_N\{z_1, z_2\}$.
- Else if either z_1 or z_2 is a positive infinity, then return positive infinity.
- Else if either z_1 or z_2 is a negative infinity, then return the other value.
- Else if both z_1 and z_2 are zeroes of opposite signs, then return positive zero.
- Else return the larger value of z_1 and z_2 .

$$\begin{aligned}
 \text{fmax}_N(\pm\text{nan}(n), z_2) &= \text{nans}_N\{\pm\text{nan}(n), z_2\} \\
 \text{fmax}_N(z_1, \pm\text{nan}(n)) &= \text{nans}_N\{\pm\text{nan}(n), z_1\} \\
 \text{fmax}_N(+\infty, z_2) &= +\infty \\
 \text{fmax}_N(-\infty, z_2) &= z_2 \\
 \text{fmax}_N(z_1, +\infty) &= +\infty \\
 \text{fmax}_N(z_1, -\infty) &= z_1 \\
 \text{fmax}_N(\pm 0, \mp 0) &= +0 \\
 \text{fmax}_N(z_1, z_2) &= z_1 && (\text{if } z_1 \geq z_2) \\
 \text{fmax}_N(z_1, z_2) &= z_2 && (\text{if } z_2 \geq z_1)
 \end{aligned}$$

$\text{fcopysign}_N(z_1, z_2)$

- If z_1 and z_2 have the same sign, then return z_1 .
- Else return z_1 with negated sign.

$$\begin{aligned}
 \text{fcopysign}_N(\pm p_1, \pm p_2) &= \pm p_1 \\
 \text{fcopysign}_N(\pm p_1, \mp p_2) &= \mp p_1
 \end{aligned}$$

$\text{fabs}_N(z)$

- If z is a NaN, then return z with positive sign.
- Else if z is an infinity, then return positive infinity.
- Else if z is a zero, then return positive zero.
- Else if z is a positive value, then z .
- Else return z negated.

$$\begin{aligned}
 \text{fabs}_N(\pm\text{nan}(n)) &= +\text{nan}(n) \\
 \text{fabs}_N(\pm\infty) &= +\infty \\
 \text{fabs}_N(\pm 0) &= +0 \\
 \text{fabs}_N(\pm q) &= +q
 \end{aligned}$$

 $\text{fneg}_N(z)$

- If z is a NaN, then return z with negated sign.
- Else if z is an infinity, then return that infinity negated.
- Else if z is a zero, then return that zero negated.
- Else return z negated.

$$\begin{aligned}
 \text{fneg}_N(\pm\text{nan}(n)) &= \mp\text{nan}(n) \\
 \text{fneg}_N(\pm\infty) &= \mp\infty \\
 \text{fneg}_N(\pm 0) &= \mp 0 \\
 \text{fneg}_N(\pm q) &= \mp q
 \end{aligned}$$

 $\text{fsqrt}_N(z)$

- If z is a NaN, then return an element of $\text{nans}_N\{z\}$.
- Else if z is negative infinity, then return an element of $\text{nans}_N\{\}$.
- Else if z is positive infinity, then return positive infinity.
- Else if z is a zero, then return that zero.
- Else if z has a negative sign, then return an element of $\text{nans}_N\{\}$.
- Else return the square root of z .

$$\begin{aligned}
 \text{fsqrt}_N(\pm\text{nan}(n)) &= \text{nans}_N\{\pm\text{nan}(n)\} \\
 \text{fsqrt}_N(-\infty) &= \text{nans}_N\{\} \\
 \text{fsqrt}_N(+\infty) &= +\infty \\
 \text{fsqrt}_N(\pm 0) &= \pm 0 \\
 \text{fsqrt}_N(-q) &= \text{nans}_N\{\} \\
 \text{fsqrt}_N(+q) &= \text{float}_N(\sqrt{q})
 \end{aligned}$$

$\text{fceil}_N(z)$

- If z is a NaN, then return an element of $\text{nans}_N\{z\}$.
- Else if z is an infinity, then return z .
- Else if z is a zero, then return z .
- Else if z is smaller than 0 but greater than -1 , then return negative zero.
- Else return the smallest integral value that is not smaller than z .

$$\begin{aligned}
 \text{fceil}_N(\pm\text{nan}(n)) &= \text{nans}_N\{\pm\text{nan}(n)\} \\
 \text{fceil}_N(\pm\infty) &= \pm\infty \\
 \text{fceil}_N(\pm 0) &= \pm 0 \\
 \text{fceil}_N(-q) &= -0 && (\text{if } -1 < -q < 0) \\
 \text{fceil}_N(\pm q) &= \text{float}_N(i) && (\text{if } \pm q \leq i < \pm q + 1)
 \end{aligned}$$

$\text{ffloor}_N(z)$

- If z is a NaN, then return an element of $\text{nans}_N\{z\}$.
- Else if z is an infinity, then return z .
- Else if z is a zero, then return z .
- Else if z is greater than 0 but smaller than 1, then return positive zero.
- Else return the largest integral value that is not larger than z .

$$\begin{aligned}
 \text{ffloor}_N(\pm\text{nan}(n)) &= \text{nans}_N\{\pm\text{nan}(n)\} \\
 \text{ffloor}_N(\pm\infty) &= \pm\infty \\
 \text{ffloor}_N(\pm 0) &= \pm 0 \\
 \text{ffloor}_N(+q) &= +0 && (\text{if } 0 < +q < 1) \\
 \text{ffloor}_N(\pm q) &= \text{float}_N(i) && (\text{if } \pm q - 1 < i \leq \pm q)
 \end{aligned}$$

$\text{ftrunc}_N(z)$

- If z is a NaN, then return an element of $\text{nans}_N\{z\}$.
- Else if z is an infinity, then return z .
- Else if z is a zero, then return z .
- Else if z is greater than 0 but smaller than 1, then return positive zero.
- Else if z is smaller than 0 but greater than -1 , then return negative zero.
- Else return the integral value with the same sign as z and the largest magnitude that is not larger than the magnitude of z .

$$\begin{aligned}
 \text{ftrunc}_N(\pm\text{nan}(n)) &= \text{nans}_N\{\pm\text{nan}(n)\} \\
 \text{ftrunc}_N(\pm\infty) &= \pm\infty \\
 \text{ftrunc}_N(\pm 0) &= \pm 0 \\
 \text{ftrunc}_N(+q) &= +0 && (\text{if } 0 < +q < 1) \\
 \text{ftrunc}_N(-q) &= -0 && (\text{if } -1 < -q < 0) \\
 \text{ftrunc}_N(\pm q) &= \text{float}_N(\pm i) && (\text{if } +q - 1 < i \leq +q)
 \end{aligned}$$

$\text{fnearest}_N(z)$

- If z is a NaN, then return an element of $\text{nans}_N\{z\}$.
- Else if z is an infinity, then return z .
- Else if z is a zero, then return z .
- Else if z is greater than 0 but smaller than or equal to 0.5, then return positive zero.
- Else if z is smaller than 0 but greater than or equal to -0.5 , then return negative zero.
- Else return the integral value that is nearest to z ; if two values are equally near, return the even one.

$$\begin{aligned}
 \text{fnearest}_N(\pm\text{nan}(n)) &= \text{nans}_N\{\pm\text{nan}(n)\} \\
 \text{fnearest}_N(\pm\infty) &= \pm\infty \\
 \text{fnearest}_N(\pm 0) &= \pm 0 \\
 \text{fnearest}_N(+q) &= +0 && (\text{if } 0 < +q \leq 0.5) \\
 \text{fnearest}_N(-q) &= -0 && (\text{if } -0.5 \leq -q < 0) \\
 \text{fnearest}_N(\pm q) &= \text{float}_N(\pm i) && (\text{if } |i - q| < 0.5) \\
 \text{fnearest}_N(\pm q) &= \text{float}_N(\pm i) && (\text{if } |i - q| = 0.5 \wedge i \text{ even})
 \end{aligned}$$

 $\text{feq}_N(z_1, z_2)$

- If either z_1 or z_2 is a NaN, then return 0.
- Else if both z_1 and z_2 are zeroes, then return 1.
- Else if both z_1 and z_2 are the same value, then return 1.
- Else return 0.

$$\begin{aligned}
 \text{feq}_N(\pm\text{nan}(n), z_2) &= 0 \\
 \text{feq}_N(z_1, \pm\text{nan}(n)) &= 0 \\
 \text{feq}_N(\pm 0, \mp 0) &= 1 \\
 \text{feq}_N(z_1, z_2) &= \text{bool}(z_1 = z_2)
 \end{aligned}$$

 $\text{fne}_N(z_1, z_2)$

- If either z_1 or z_2 is a NaN, then return 1.
- Else if both z_1 and z_2 are zeroes, then return 0.
- Else if both z_1 and z_2 are the same value, then return 0.
- Else return 1.

$$\begin{aligned}
 \text{fne}_N(\pm\text{nan}(n), z_2) &= 1 \\
 \text{fne}_N(z_1, \pm\text{nan}(n)) &= 1 \\
 \text{fne}_N(\pm 0, \mp 0) &= 0 \\
 \text{fne}_N(z_1, z_2) &= \text{bool}(z_1 \neq z_2)
 \end{aligned}$$

 $\text{flt}_N(z_1, z_2)$

- If either z_1 or z_2 is a NaN, then return 0.
- Else if z_1 and z_2 are the same value, then return 0.
- Else if z_1 is positive infinity, then return 0.
- Else if z_1 is negative infinity, then return 1.
- Else if z_2 is positive infinity, then return 1.
- Else if z_2 is negative infinity, then return 0.

- Else if both z_1 and z_2 are zeroes, then return 0.
- Else if z_1 is smaller than z_2 , then return 1.
- Else return 0.

$$\begin{aligned}
\text{flt}_N(\pm\text{nan}(n), z_2) &= 0 \\
\text{flt}_N(z_1, \pm\text{nan}(n)) &= 0 \\
\text{flt}_N(z, z) &= 0 \\
\text{flt}_N(+\infty, z_2) &= 0 \\
\text{flt}_N(-\infty, z_2) &= 1 \\
\text{flt}_N(z_1, +\infty) &= 1 \\
\text{flt}_N(z_1, -\infty) &= 0 \\
\text{flt}_N(\pm 0, \mp 0) &= 0 \\
\text{flt}_N(z_1, z_2) &= \text{bool}(z_1 < z_2)
\end{aligned}$$

$\text{fgt}_N(z_1, z_2)$

- If either z_1 or z_2 is a NaN, then return 0.
- Else if z_1 and z_2 are the same value, then return 0.
- Else if z_1 is positive infinity, then return 1.
- Else if z_1 is negative infinity, then return 0.
- Else if z_2 is positive infinity, then return 0.
- Else if z_2 is negative infinity, then return 1.
- Else if both z_1 and z_2 are zeroes, then return 0.
- Else if z_1 is larger than z_2 , then return 1.
- Else return 0.

$$\begin{aligned}
\text{fgt}_N(\pm\text{nan}(n), z_2) &= 0 \\
\text{fgt}_N(z_1, \pm\text{nan}(n)) &= 0 \\
\text{fgt}_N(z, z) &= 0 \\
\text{fgt}_N(+\infty, z_2) &= 1 \\
\text{fgt}_N(-\infty, z_2) &= 0 \\
\text{fgt}_N(z_1, +\infty) &= 0 \\
\text{fgt}_N(z_1, -\infty) &= 1 \\
\text{fgt}_N(\pm 0, \mp 0) &= 0 \\
\text{fgt}_N(z_1, z_2) &= \text{bool}(z_1 > z_2)
\end{aligned}$$

$\text{fle}_N(z_1, z_2)$

- If either z_1 or z_2 is a NaN, then return 0.
- Else if z_1 and z_2 are the same value, then return 1.
- Else if z_1 is positive infinity, then return 0.
- Else if z_1 is negative infinity, then return 1.
- Else if z_2 is positive infinity, then return 1.
- Else if z_2 is negative infinity, then return 0.
- Else if both z_1 and z_2 are zeroes, then return 1.
- Else if z_1 is smaller than or equal to z_2 , then return 1.
- Else return 0.

$\text{fle}_N(\pm\text{nan}(n), z_2)$	$=$	0
$\text{fle}_N(z_1, \pm\text{nan}(n))$	$=$	0
$\text{fle}_N(z, z)$	$=$	1
$\text{fle}_N(+\infty, z_2)$	$=$	0
$\text{fle}_N(-\infty, z_2)$	$=$	1
$\text{fle}_N(z_1, +\infty)$	$=$	1
$\text{fle}_N(z_1, -\infty)$	$=$	0
$\text{fle}_N(\pm 0, \mp 0)$	$=$	1
$\text{fle}_N(z_1, z_2)$	$=$	$\text{bool}(z_1 \leq z_2)$

$\text{fge}_N(z_1, z_2)$

- If either z_1 or z_2 is a NaN, then return 0.
- Else if z_1 and z_2 are the same value, then return 1.
- Else if z_1 is positive infinity, then return 1.
- Else if z_1 is negative infinity, then return 0.
- Else if z_2 is positive infinity, then return 0.
- Else if z_2 is negative infinity, then return 1.
- Else if both z_1 and z_2 are zeroes, then return 1.
- Else if z_1 is smaller than or equal to z_2 , then return 1.
- Else return 0.

$\text{fge}_N(\pm\text{nan}(n), z_2)$	$=$	0
$\text{fge}_N(z_1, \pm\text{nan}(n))$	$=$	0
$\text{fge}_N(z, z)$	$=$	1
$\text{fge}_N(+\infty, z_2)$	$=$	1
$\text{fge}_N(-\infty, z_2)$	$=$	0
$\text{fge}_N(z_1, +\infty)$	$=$	0
$\text{fge}_N(z_1, -\infty)$	$=$	1
$\text{fge}_N(\pm 0, \mp 0)$	$=$	1
$\text{fge}_N(z_1, z_2)$	$=$	$\text{bool}(z_1 \geq z_2)$

$\text{fpmin}_N(z_1, z_2)$

- If z_2 is less than z_1 then return z_2 .
- Else return z_1 .

$\text{fpmin}_N(z_1, z_2)$	$=$	z_2	(if $\text{flt}_N(z_2, z_1) = 1$)
$\text{fpmin}_N(z_1, z_2)$	$=$	z_1	(otherwise)

$\text{fpmax}_N(z_1, z_2)$

- If z_1 is less than z_2 then return z_2 .
- Else return z_1 .

$\text{fpmax}_N(z_1, z_2)$	$=$	z_2	(if $\text{flt}_N(z_1, z_2) = 1$)
$\text{fpmax}_N(z_1, z_2)$	$=$	z_1	(otherwise)

4.3.4 Conversions

Todo: ext or extend?

$\text{extend}^u_{M,N}(i)$

- Return i .

$$\text{extend}^u_{M,N}(i) = i$$

Note: In the abstract syntax, unsigned extension just reinterprets the same value.

$\text{extend}^s_{M,N}(i)$

- Let j be the [signed interpretation](#) of i of size M .
- Return the two's complement of j relative to size N .

$$\text{extend}^s_{M,N}(i) = \text{signed}_N^{-1}(\text{signed}_M(i))$$

$\text{wrap}_{M,N}(i)$

- Return i modulo 2^N .

$$\text{wrap}_{M,N}(i) = i \bmod 2^N$$

$\text{trunc}^u_{M,N}(z)$

- If z is a NaN, then the result is undefined.
- Else if z is an infinity, then the result is undefined.
- Else if z is a number and $\text{trunc}(z)$ is a value within range of the target type, then return that value.
- Else the result is undefined.

$$\begin{aligned} \text{trunc}^u_{M,N}(\pm\text{nan}(n)) &= \{\} \\ \text{trunc}^u_{M,N}(\pm\infty) &= \{\} \\ \text{trunc}^u_{M,N}(\pm q) &= \text{trunc}(\pm q) && (\text{if } -1 < \text{trunc}(\pm q) < 2^N) \\ \text{trunc}^u_{M,N}(\pm q) &= \{\} && (\text{otherwise}) \end{aligned}$$

Note: This operator is [partial](#). It is not defined for NaNs, infinities, or values for which the result is out of range.

$\text{trunc}_{M,N}^s(z)$

- If z is a NaN, then the result is undefined.
- Else if z is an infinity, then the result is undefined.
- If z is a number and $\text{trunc}(z)$ is a value within range of the target type, then return that value.
- Else the result is undefined.

$$\begin{aligned} \text{trunc}_{M,N}^s(\pm\text{nan}(n)) &= \{\} \\ \text{trunc}_{M,N}^s(\pm\infty) &= \{\} \\ \text{trunc}_{M,N}^s(\pm q) &= \text{trunc}(\pm q) && (\text{if } -2^{N-1} - 1 < \text{trunc}(\pm q) < 2^{N-1}) \\ \text{trunc}_{M,N}^s(\pm q) &= \{\} && (\text{otherwise}) \end{aligned}$$

Note: This operator is **partial**. It is not defined for NaNs, infinities, or values for which the result is out of range.

$\text{trunc_sat_u}_{M,N}(z)$

- If z is a NaN, then return 0.
- Else if z is negative infinity, then return 0.
- Else if z is positive infinity, then return $2^N - 1$.
- Else, return $\text{sat_u}_N(\text{trunc}(z))$.

$$\begin{aligned} \text{trunc_sat_u}_{M,N}(\pm\text{nan}(n)) &= 0 \\ \text{trunc_sat_u}_{M,N}(-\infty) &= 0 \\ \text{trunc_sat_u}_{M,N}(+\infty) &= 2^N - 1 \\ \text{trunc_sat_u}_{M,N}(z) &= \text{sat_u}_N(\text{trunc}(z)) \end{aligned}$$

$\text{trunc_sat_s}_{M,N}(z)$

- If z is a NaN, then return 0.
- Else if z is negative infinity, then return -2^{N-1} .
- Else if z is positive infinity, then return $2^{N-1} - 1$.
- Else, return $\text{sat_s}_N(\text{trunc}(z))$.

$$\begin{aligned} \text{trunc_sat_s}_{M,N}(\pm\text{nan}(n)) &= 0 \\ \text{trunc_sat_s}_{M,N}(-\infty) &= -2^{N-1} \\ \text{trunc_sat_s}_{M,N}(+\infty) &= 2^{N-1} - 1 \\ \text{trunc_sat_s}_{M,N}(z) &= \text{sat_s}_N(\text{trunc}(z)) \end{aligned}$$

$\text{promote}_{M,N}(z)$

- If z is a canonical NaN, then return an element of $\text{nans}_N\{\}$ (i.e., a canonical NaN of size N).
- Else if z is a NaN, then return an element of $\text{nans}_N\{\pm\text{nan}(1)\}$ (i.e., any arithmetic NaN of size N).
- Else, return z .

$$\begin{aligned} \text{promote}_{M,N}(\pm\text{nan}(n)) &= \text{nans}_N\{\} && (\text{if } n = \text{canon}_N) \\ \text{promote}_{M,N}(\pm\text{nan}(n)) &= \text{nans}_N\{+\text{nan}(1)\} && (\text{otherwise}) \\ \text{promote}_{M,N}(z) &= z \end{aligned}$$

$\text{demote}_{M,N}(z)$

- If z is a canonical NaN, then return an element of $\text{nans}_N\{\}$ (i.e., a canonical NaN of size N).
- Else if z is a NaN, then return an element of $\text{nans}_N\{\pm\text{nan}(1)\}$ (i.e., any NaN of size N).
- Else if z is an infinity, then return that infinity.
- Else if z is a zero, then return that zero.
- Else, return $\text{float}_N(z)$.

$$\begin{aligned}\text{demote}_{M,N}(\pm\text{nan}(n)) &= \text{nans}_N\{\} && (\text{if } n = \text{canon}_N) \\ \text{demote}_{M,N}(\pm\text{nan}(n)) &= \text{nans}_N\{+\text{nan}(1)\} && (\text{otherwise}) \\ \text{demote}_{M,N}(\pm\infty) &= \pm\infty \\ \text{demote}_{M,N}(\pm 0) &= \pm 0 \\ \text{demote}_{M,N}(\pm q) &= \text{float}_N(\pm q)\end{aligned}$$

$\text{convert}^u_{M,N}(i)$

- Return $\text{float}_N(i)$.

$$\text{convert}^u_{M,N}(i) = \text{float}_N(i)$$

$\text{convert}^s_{M,N}(i)$

- Let j be the signed interpretation of i .
- Return $\text{float}_N(j)$.

$$\text{convert}^s_{M,N}(i) = \text{float}_N(\text{signed}_M(i))$$

$\text{reinterpret}_{t_1,t_2}(c)$

- Let d^* be the bit sequence $\text{bits}_{t_1}(c)$.
- Return the constant c' for which $\text{bits}_{t_2}(c') = d^*$.

$$\text{reinterpret}_{t_1,t_2}(c) = \text{bits}_{t_2}^{-1}(\text{bits}_{t_1}(c))$$

$\text{narrow}^s_{M,N}(i)$

- Let j be the signed interpretation of i of size M .
- Return $\text{sat}_{sN}(j)$.

$$\text{narrow}^s_{M,N}(i) = \text{sat}_{sN}(\text{signed}_M(i))$$

$\text{narrow}^u_{M,N}(i)$

- Let j be the signed interpretation of i of size M .
- Return $\text{sat}_{uN}(j)$.

$$\text{narrow}^u_{M,N}(i) = \text{sat}_{uN}(\text{signed}_M(i))$$

4.4 Types

Execution has to check and compare **types** in a few places, such as **executing** `call_indirect` or **instantiating** modules. It is an invariant of the semantics that all types occurring during execution are **closed**.

Note: Runtime type checks generally involve types from multiple modules or types not defined by a module at all, such that module-local **type indices** are not meaningful.

4.4.1 Instantiation

Any form of **type** can be *instantiated* into a **closed** type inside a **module instance** by **substituting** each **type index** x occurring in it with the corresponding **defined type** `moduleinst.types[x]`.

$$\text{clos}_{\text{moduleinst}}(t) = t[:= dt^*] \quad \text{if } dt^* = \text{moduleinst.types}$$

Note: This is the runtime equivalent to **type closure**.

4.5 Values

4.5.1 Value Typing

For the purpose of checking argument **values** against the parameter types of exported **functions**, values are classified by **value types**. The following auxiliary typing rules specify this typing relation relative to a **store** S in which possibly referenced addresses live.

Numeric Values `t.const c`

- The value is valid with **number type** t .

$$\overline{S \vdash t.\text{const } c : t}$$

Vector Values `t.const c`

- The value is valid with **vector type** t .

$$\overline{S \vdash t.\text{const } c : t}$$

Null References `ref.null t`

- The **heap type** must be **valid** under the empty context.
- Then the value is valid with **reference type** (`ref null t'`), where the **heap type** t' is the least type that **matches** t .

$$\frac{\vdash t : \text{ok} \quad t' \in \{\text{none}, \text{nofunc}, \text{noextern}\} \quad \vdash t' \leq t}{S \vdash \text{ref.null } t : (\text{ref null } t')}$$

Note: A null reference is typed with the least type in its respective hierarchy. That ensures that it is compatible with any nullable type in that hierarchy.

Scalar References $\text{ref.i31 } i$

- The value is valid with reference type (ref i31).

$$\frac{}{S \vdash \text{ref.i31 } i : \text{ref i31}}$$

Structure References $\text{ref.struct } a$

- The structure address a must exist in the store.
- Let structinst be the structure instance $S.\text{structs}[a]$.
- Let deftype be the defined type structinst.type .
- The expansion of deftype must be a struct type.
- Then the value is valid with reference type (ref deftype).

$$\frac{\text{deftype} = S.\text{structs}[a].\text{type} \quad \text{expand}(\text{deftype}) = \text{struct structtype}}{S \vdash \text{ref.struct } a : \text{ref } \text{deftype}}$$

Array References $\text{ref.array } a$

- The array address a must exist in the store.
- Let arrayinst be the array instance $S.\text{arrays}[a]$.
- Let deftype be the defined type arrayinst.type .
- The expansion of deftype must be an array type.
- Then the value is valid with reference type (ref arraytype).

$$\frac{\text{deftype} = S.\text{arrays}[a].\text{type} \quad \text{expand}(\text{deftype}) = \text{array arraytype}}{S \vdash \text{ref.array } a : \text{ref } \text{deftype}}$$

Function References $\text{ref.func } a$

- The function address a must exist in the store.
- Let funcinst be the function instance $S.\text{funcs}[a]$.
- Let deftype be the defined type funcinst.type .
- The expansion of deftype must be a function type.
- Then the value is valid with reference type (ref func type).

$$\frac{\text{deftype} = S.\text{funcs}[a].\text{type} \quad \text{expand}(\text{deftype}) = \text{func func type}}{S \vdash \text{ref.func } a : \text{ref } \text{deftype}}$$

Host References $\text{ref.host } a$

- The value is valid with reference type (ref any).

$$\frac{}{S \vdash \text{ref.host } a : \text{ref any}}$$

Note: A host reference is considered internalized by this rule.

External References *ref.extern ref*

- The reference value *ref* must be valid with some reference type (*ref null?* *t*).
- The heap type *t* must match the heap type *any*.
- Then the value is valid with reference type (*ref null?* *extern*).

$$\frac{S \vdash \text{ref} : \text{ref null? } t \quad \vdash t \leq \text{any}}{S \vdash \text{ref.extern } \text{ref} : \text{ref null? } \text{extern}}$$

Subsumption

- The value must be valid with some value type *t*.
- The value type *t* matches another valid type *t'*.
- Then the value is valid with type *t'*.

$$\frac{S \vdash \text{val} : t \quad \vdash t' : \text{ok} \quad \vdash t \leq t'}{S \vdash \text{val} : t'}$$

4.5.2 External Typing

For the purpose of checking external values against imports, such values are classified by external types. The following auxiliary typing rules specify this typing relation relative to a store *S* in which the referenced instances live.

func a

- The store entry *S.funcs[a]* must exist.
- Then *func a* is valid with external type *func S.funcs[a].type*.

$$\overline{S \vdash \text{func } a : \text{func } S.\text{funcs}[a].\text{type}}$$

table a

- The store entry *S.tables[a]* must exist.
- Then *table a* is valid with external type *table S.tables[a].type*.

$$\overline{S \vdash \text{table } a : \text{table } S.\text{tables}[a].\text{type}}$$

mem a

- The store entry *S.mems[a]* must exist.
- Then *mem a* is valid with external type *mem S.mems[a].type*.

$$\overline{S \vdash \text{mem } a : \text{mem } S.\text{mems}[a].\text{type}}$$

global a

- The store entry $S.\text{globals}[a]$ must exist.
- Then `global a` is valid with `external type global $S.\text{globals}[a].\text{type}$` .

$$\frac{}{S \vdash \text{global } a : \text{global } S.\text{globals}[a].\text{type}}$$

Subsumption

- The external value must be valid with some external type et .
- The external type et `matches` another `valid` type et' .
- Then the external value is valid with type et' .

$$\frac{S \vdash \text{externval} : et \quad \vdash et' : \text{ok} \quad \vdash et \leq et'}{S \vdash \text{externval} : et'}$$

4.6 Instructions

WebAssembly computation is performed by executing individual `instructions`.

4.6.1 Parametric Instructions

`nop`

1. Do nothing.

$$\text{nop} \hookrightarrow \epsilon$$

`unreachable`

1. Trap.

$$\text{unreachable} \hookrightarrow \text{trap}$$

`drop`

1. Assert: Due to validation, a value is on the top of the stack.
2. Pop the value `val` from the stack.
3. Do nothing.

Todo:

- (1) Remove trailing “Do nothing.”
-

$$\text{val drop} \hookrightarrow \epsilon$$

`select (t*)?`

1. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
2. Pop the value `(i32.const c)` from the stack.
3. Assert: Due to validation, a value is on the top of the stack.
4. Pop the value `val2` from the stack.
5. Assert: Due to validation, a value is on the top of the stack.
6. Pop the value `val1` from the stack.
7. If `c` is not 0, then:
 - a. Push the value `val1` to the stack.
8. Else:
 - a. Push the value `val2` to the stack.

$$\begin{aligned} val_1 \ val_2 \ (i32.const \ c) \ (select \ (t^*)?) &\hookrightarrow val_1 && \text{if } c \neq 0 \\ val_1 \ val_2 \ (i32.const \ c) \ (select \ (t^*)?) &\hookrightarrow val_2 && \text{if } c = 0 \end{aligned}$$

Note: In future versions of WebAssembly, `select` may allow more than one value per choice.

4.6.2 Numeric Instructions

Numeric instructions are defined in terms of the generic [numeric operators](#). The mapping of numeric instructions to their underlying operators is expressed by the following definition:

$$\begin{aligned} op_{iN}(i_1, \dots, i_k) &= iop_N(i_1, \dots, i_k) \\ op_{fN}(z_1, \dots, z_k) &= fop_N(z_1, \dots, z_k) \end{aligned}$$

And for [conversion operators](#):

$$cvtop_{t_1, t_2}^{sx?}(c) = cvtop_{|t_1|, |t_2|}^{sx?}(c)$$

Where the underlying operators are partial, the corresponding instruction will [trap](#) when the result is not defined. Where the underlying operators are non-deterministic, because they may return one of multiple possible NaN values, so are the corresponding instructions.

Note: For example, the result of instruction `i32.add` applied to operands i_1, i_2 invokes `addi32(i1, i2)`, which maps to the generic `iadd32(i1, i2)` via the above definition. Similarly, `i64.trunc_f32_s` applied to z invokes `truncf32, i64s(z)`, which maps to the generic `trunc32, 64s(z)`.

`t.const c`

1. Push the value `t.const c` to the stack.

Note: No formal reduction rule is required for this instruction, since `const` instructions already are [values](#).

nt.unop

1. Assert: Due to validation, a value of value type *nt* is on the top of the stack.
2. Pop the value (*nt.const* c_1) from the stack.
3. If $|unop_{nt}(c_1)|$ is 1, then:
 - a. Let c be $unop_{nt}(c_1)$.
 - b. Push the value (*nt.const* c) to the stack.
4. If $unop_{nt}(c_1)$ is ϵ , then:
 - a. Trap.

Todo:

- (2) SpecTec currently defines the image of *unop* as a sequence, not a set.

$$\begin{array}{ll}
 (nt.const\ c_1)\ (nt.unop) \hookrightarrow (nt.const\ c) & \text{if } unop_{nt}(c_1) = c \\
 (nt.const\ c_1)\ (nt.unop) \hookrightarrow \text{trap} & \text{if } unop_{nt}(c_1) = \epsilon
 \end{array}$$

nt.binop

1. Assert: Due to validation, a value of value type *nt* is on the top of the stack.
2. Pop the value (*nt.const* c_2) from the stack.
3. Assert: Due to validation, a value of value type *nt* is on the top of the stack.
4. Pop the value (*nt.const* c_1) from the stack.
5. If $|binop_{nt}(c_1, c_2)|$ is 1, then:
 - a. Let c be $binop_{nt}(c_1, c_2)$.
 - b. Push the value (*nt.const* c) to the stack.
6. If $binop_{nt}(c_1, c_2)$ is ϵ , then:
 - a. Trap.

Todo:

- (2) SpecTec currently defines the image of *binop* as a sequence, not a set.

$$\begin{array}{ll}
 (nt.const\ c_1)\ (nt.const\ c_2)\ (nt.binop) \hookrightarrow (nt.const\ c) & \text{if } binop_{nt}(c_1, c_2) = c \\
 (nt.const\ c_1)\ (nt.const\ c_2)\ (nt.binop) \hookrightarrow \text{trap} & \text{if } binop_{nt}(c_1, c_2) = \epsilon
 \end{array}$$

nt.testop

1. Assert: Due to validation, a value of value type *nt* is on the top of the stack.
2. Pop the value (*nt.const* c_1) from the stack.
3. Let c be $testop_{nt}(c_1)$.
4. Push the value (*i32.const* c) to the stack.

Todo:

- (2) SpecTec currently defines the image of *testop* as a sequence, not a set.

$$(nt.\text{const } c_1) (nt.\text{testop}) \hookrightarrow (i32.\text{const } c) \quad \text{if } c = \text{testop}_{nt}(c_1)$$

nt.relop

1. Assert: Due to validation, a value of value type *nt* is on the top of the stack.
2. Pop the value $(nt.\text{const } c_2)$ from the stack.
3. Assert: Due to validation, a value of value type *nt* is on the top of the stack.
4. Pop the value $(nt.\text{const } c_1)$ from the stack.
5. Let *c* be $\text{relop}_{nt}(c_1, c_2)$.
6. Push the value $(i32.\text{const } c)$ to the stack.

Todo:

- (2) SpecTec currently defines the image of testop as a sequence, not a set.
-

$$(nt.\text{const } c_1) (nt.\text{const } c_2) (nt.\text{relop}) \hookrightarrow (i32.\text{const } c) \quad \text{if } c = \text{relop}_{nt}(c_1, c_2)$$

nt₂.cvtop_nt₁_sx?

1. Assert: Due to validation, a value of value type *nt₁* is on the top of the stack.
2. Pop the value $(nt_1.\text{const } c_1)$ from the stack.
3. If $|\text{cvtop}_{nt_1, nt_2}^{sx?}(c_1)|$ is 1, then:
 - a. Let *c* be $\text{cvtop}_{nt_1, nt_2}^{sx?}(c_1)$.
 - b. Push the value $(nt_2.\text{const } c)$ to the stack.
4. If $\text{cvtop}_{nt_1, nt_2}^{sx?}(c_1)$ is ϵ , then:
 - a. Trap.

Todo:

- (2) SpecTec currently defines the image of testop as a sequence, not a set.
-

$$\begin{aligned} (nt_1.\text{const } c_1) (nt_2.\text{cvtop_nt}_1\text{_sx}?) &\hookrightarrow (nt_2.\text{const } c) && \text{if } \text{cvtop}_{nt_1, nt_2}^{sx?}(c_1) = c \\ (nt_1.\text{const } c_1) (nt_2.\text{cvtop_nt}_1\text{_sx}?) &\hookrightarrow \text{trap} && \text{if } \text{cvtop}_{nt_1, nt_2}^{sx?}(c_1) = \epsilon \end{aligned}$$

4.6.3 Reference Instructions

ref.null x

1. Let *F* be the [current frame](#).
2. Assert: due to [validation](#), the [defined type](#) *F.module.types*[*x*] exists.
3. Let *deftype* be the [defined type](#) *F.module.types*[*x*].
4. Push the value *ref.null* *deftype* to the stack.

$$z; (\text{ref.null } x) \hookrightarrow (\text{ref.null } z.\text{types}[x])$$

Note: No formal reduction rule is required for the case `ref.null absheaptype`, since the instruction form is already a *value*.

`ref.func x`

1. Let *z* be the current state.
2. Assert: Due to validation, *x* is less than $|z.\text{module.funcs}|$.
3. Push the value $(\text{ref.func } z.\text{module.funcs}[x])$ to the stack.

$$z; (\text{ref.func } x) \hookrightarrow (\text{ref.func } z.\text{module.funcs}[x])$$

`ref.is_null`

1. Assert: Due to validation, a value is on the top of the stack.
2. Pop the value *ref* from the stack.
3. If *ref* is of the case `ref.null`, then:
 - a. Push the value $(\text{i32.const } 1)$ to the stack.
4. Else:
 - a. Push the value $(\text{i32.const } 0)$ to the stack.

Todo:

- (3) Introduce if-let instruction instead of “is of the case”.
-

$$\begin{array}{ll} \text{ref } \text{ref.is_null} & \hookrightarrow (\text{i32.const } 1) & \text{if } \text{ref} = (\text{ref.null } ht) \\ \text{ref } \text{ref.is_null} & \hookrightarrow (\text{i32.const } 0) & \text{otherwise} \end{array}$$

`ref.as_non_null`

1. Assert: Due to validation, a value is on the top of the stack.
2. Pop the value *ref* from the stack.
3. If *ref* is of the case `ref.null`, then:
 - a. Trap.
4. Push the value *ref* to the stack.

Todo:

- (3) Introduce if-let instruction instead of “is of the case”.
-

$$\begin{array}{ll} \text{ref } \text{ref.as_non_null} & \hookrightarrow \text{trap} & \text{if } \text{ref} = (\text{ref.null } ht) \\ \text{ref } \text{ref.as_non_null} & \hookrightarrow \text{ref} & \text{otherwise} \end{array}$$

`ref.eq`

1. Assert: Due to validation, a value is on the top of the stack.
2. Pop the value ref_2 from the stack.
3. Assert: Due to validation, a value is on the top of the stack.
4. Pop the value ref_1 from the stack.
5. If ref_1 is of the case `ref.null` and ref_2 is of the case `ref.null`, then:
 - a. Push the value (`i32.const 1`) to the stack.
6. Else if ref_1 is ref_2 , then:
 - a. Push the value (`i32.const 1`) to the stack.
7. Else:
 - a. Push the value (`i32.const 0`) to the stack.

Todo:

- (3) Introduce if-let instruction instead of “is of the case”.

$$\begin{array}{lll}
 ref_1 \ ref_2 \ ref.eq & \hookrightarrow & (i32.const \ 1) \quad \text{if } ref_1 = (ref.null \ ht_1) \wedge ref_2 = (ref.null \ ht_2) \\
 ref_1 \ ref_2 \ ref.eq & \hookrightarrow & (i32.const \ 1) \quad \text{otherwise, if } ref_1 = ref_2 \\
 ref_1 \ ref_2 \ ref.eq & \hookrightarrow & (i32.const \ 0) \quad \text{otherwise}
 \end{array}$$
`ref.test rt`

1. Let f be the current frame.
2. Assert: Due to validation, a value is on the top of the stack.
3. Pop the value ref from the stack.
4. Let rt' be $ref_{type_of}(ref)$.
5. If rt' matches $close_{f.module}(rt)$, then:
 - a. Push the value (`i32.const 1`) to the stack.
6. Else:
 - a. Push the value (`i32.const 0`) to the stack.

Todo: Below is the actual prose. (9) Need to handle RulePr s |- ref : rt properly in prose instead of \$ref_type_of

1. Let F be the **current frame**.
2. Let rt_1 be the **reference type** $close_{F.module}(rt)$.
3. Assert: due to **validation**, rt_1 is **closed**.
4. Assert: due to **validation**, a **reference value** is on the top of the stack.
5. Pop the value ref from the stack.
6. Assert: due to validation, the **reference value** is **valid** with some **reference type**.
7. Let rt_2 be the **reference type** of ref .
8. If the **reference type** rt_2 **matches** rt_1 , then:
 - a. Push the value `i32.const 1` to the stack.

9. Else:

a. Push the value `i32.const 0` to the stack.

$$\begin{array}{ll} s; f; \text{ref} (\text{ref.test } rt) \hookrightarrow (\text{i32.const } 1) & \text{if } s \vdash \text{ref} : rt' \\ & \wedge \{\} \vdash rt' \leq \text{clos}_{f.\text{module}}(rt) \\ s; f; \text{ref} (\text{ref.test } rt) \hookrightarrow (\text{i32.const } 0) & \text{otherwise} \end{array}$$

`ref.cast rt`

1. Let f be the current frame.
2. Assert: Due to validation, a value is on the top of the stack.
3. Pop the value ref from the stack.
4. Let rt' be $\text{ref}_{\text{type_of}}(\text{ref})$.
5. If rt' does not match $\text{clos}_{f.\text{module}}(rt)$, then:
 - a. Trap.
6. Push the value ref to the stack.

Todo: Below is the actual prose. (9) Need to handle RulePr $s \vdash \text{ref} : rt$ properly in prose instead of $\$ref_type_of$

1. Let F be the **current frame**.
2. Let rt_1 be the **reference type** $\text{clos}_{F.\text{module}}(rt)$.
3. Assert: due to **validation**, rt_1 is **closed**.
4. Assert: due to **validation**, a **reference value** is on the top of the stack.
5. Pop the value ref from the stack.
6. Assert: due to validation, the **reference value** is **valid** with some **reference type**.
7. Let rt_2 be the **reference type** of ref .
8. If the **reference type** rt_2 **matches** rt_1 , then:
 - a. Push the value ref back to the stack.
9. Else:
 - a. Trap.

$$\begin{array}{ll} s; f; \text{ref} (\text{ref.cast } rt) \hookrightarrow \text{ref} & \text{if } s \vdash \text{ref} : rt' \\ & \wedge \{\} \vdash rt' \leq \text{clos}_{f.\text{module}}(rt) \\ s; f; \text{ref} (\text{ref.cast } rt) \hookrightarrow \text{trap} & \text{otherwise} \end{array}$$

`ref.i31`

1. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
2. Pop the value `(i32.const i)` from the stack.
3. Push the value `(ref.i31 wrap32,31(i))` to the stack.

$$(i32.\text{const } i) \text{ ref.i31} \hookrightarrow (\text{ref.i31 wrap}_{32,31}(i))$$

`i31.get_sx`

1. Assert: Due to validation, a value is on the top of the stack.
2. Pop the value `instru0` from the stack.
3. If `instru0` is of the case `ref.null`, then:
 - a. Trap.
4. If `instru0` is of the case `ref.i31`, then:
 - a. Let `(ref.i31 i)` be `instru0`.
 - b. Push the value `(i32.const extend31,32sx(i))` to the stack.

Todo: Below is the actual prose. (3) Introduce if-let instruction instead of “is of the case”. (4) Guarantees from validation can help simplify the prose.

1. Assert: due to `validation`, a value of type `(ref null i31)` is on the top of the stack.
2. Pop the value `ref` from the stack.
3. If `ref` is `ref.null t`, then:
 - a. Trap.
4. Assert: due to `validation`, a `ref` is a `scalar reference`.
5. Let `ref.i31 i` be the reference value `ref`.
6. Let `j` be the result of computing `extend31,32sx(i)`.
7. Push the value `i32.const j` to the stack.

$$\begin{aligned} (\text{ref.null } ht) \text{ (i31.get_sx)} &\hookrightarrow \text{trap} \\ (\text{ref.i31 } i) \text{ (i31.get_sx)} &\hookrightarrow (\text{i32.const extend}_{31,32}^{\text{sx}}(i)) \end{aligned}$$
`struct.new x`

1. Let `z` be the current state.
2. Let `a` be `|z.structs|`.
3. Assert: Due to validation, `expand(z.types[x])` is of the case `struct`.
4. Let `(struct y0)` be `expand(z.types[x])`.
5. Let `(mut?, zt)n` be `y0`.
6. Assert: Due to validation, there are at least `n` values on the top of the stack.
7. Pop the values `valn` from the stack.
8. Let `si` be `{type z.types[x], fields packzt(val)n}`.
9. Push the value `(ref.struct a)` to the stack.
10. Perform `z[.structs = ..si]`.

Todo: Below is the actual prose. (3') Introduce let binding instead of “is of the case”. (5) Use “the expansion of” instead of `$expand` function application.

1. Let `F` be the `current frame`.
2. Assert: due to `validation`, the `defined type F.module.types[x]` exists.
3. Let `deftype` be the `defined type F.module.types[x]`.

4. Assert: due to **validation**, the **expansion** of *deftype* is a **structure type**.
 5. Let *struct ft** be the **expanded structure type** of *deftype*.
 6. Let *n* be the length of the **field type** sequence *ft**.
 7. Assert: due to **validation**, *n* **values** are on the top of the stack.
 8. Pop the *n* values *val** from the stack.
 9. For every value *val_i* in *val** and corresponding **field type** *ft_i* in *ft**:
 - a. Let *fieldval_i* be the result of computing $\text{pack}_{ft_i}(val_i)$.
 10. Let *fieldval** the concatenation of all field values *fieldval_i*.
 11. Let *si* be the **structure instance** $\{\text{type } deftype, \text{fields } fieldval^*\}$.
 12. Let *a* be the length of *S.structs*.
 13. Append *si* to *S.structs*.
 14. Push the **structure reference** *ref.struct a* to the stack.
- $z; val^n (\text{struct.new } x) \hookrightarrow z[\text{.structs} = \dots si]; (\text{ref.struct } a)$

 if $z.\text{types}[x] \approx \text{struct } (\text{mut}^? \text{ } zt)^n$
 $\wedge a = |z.\text{structs}|$
 $\wedge si = \{\text{type } z.\text{types}[x], \text{fields } (\text{pack}_{zt}(val))^n\}$

struct.new_default *x*

1. Let *z* be the current state.
2. Assert: Due to **validation**, $\text{expand}(z.\text{types}[x])$ is of the case **struct**.
3. Let *(struct y₀)* be $\text{expand}(z.\text{types}[x])$.
4. Let *(mut[?], zt)** be *y₀*.
5. Assert: Due to **validation**, $|mut^{?^*}|$ is $|zt^*|$.
6. Assert: Due to **validation**, for all *(zt)**, $\text{default}_{\text{unpack}(zt)}$ is defined.
7. Let *val** be $\text{default}_{\text{unpack}(zt)}^*$.
8. Assert: Due to **validation**, $|val^*|$ is $|zt^*|$.
9. Push the values *val** to the stack.
10. Execute the instruction **(struct.new x)**.

Todo: Below is the actual prose. (3') Introduce let binding instead of “is of the case”. (5) Use “the expansion of” instead of \$expand function application.

1. Let *F* be the **current frame**.
2. Assert: due to **validation**, the **defined type** *F.module.types[x]* exists.
3. Let *deftype* be the **defined type** *F.module.types[x]*.
4. Assert: due to **validation**, the **expansion** of *deftype* is a **structure type**.
5. Let *struct ft** be the **expanded structure type** of *deftype*.
6. Let *n* be the length of the **field type** sequence *ft**.
7. For every **field type** *ft_i* in *ft**:
 - a. Let *t_i* be the **value type** $\text{unpack}(ft_i)$.
 - b. Assert: due to **validation**, default_{t_i} is defined.

c. Push the value default_{t_i} to the stack.

8. Execute the instruction $(\text{struct.new } x)$.

$$z; (\text{struct.new_default } x) \hookrightarrow \text{val}^* (\text{struct.new } x) \quad \text{if } z.\text{types}[x] \approx \text{struct } (\text{mut}^? \text{ } zt)^* \wedge (\text{default}_{\text{unpack}(zt)} = \text{val})^*$$

$\text{struct.get_sx}^? \text{ } x \text{ } i$

1. Let z be the current state.
2. Assert: Due to validation, a value is on the top of the stack.
3. Pop the value instr_{u0} from the stack.
4. If instr_{u0} is of the case ref.null , then:
 - a. Trap.
5. Assert: Due to validation, $\text{expand}(z.\text{types}[x])$ is of the case struct .
6. Let $(\text{struct } y_0)$ be $\text{expand}(z.\text{types}[x])$.
7. Let $(\text{mut}^?, zt)^*$ be y_0 .
8. If instr_{u0} is of the case ref.struct , then:
 - a. Let $(\text{ref.struct } a)$ be instr_{u0} .
 - b. If i is less than $|z.\text{structs}[a].\text{fields}|$ and a is less than $|z.\text{structs}|$ and $|\text{mut}^?*|$ is $|zt^*|$ and i is less than $|zt^*|$, then:
 - 1) Push the value $\text{unpack}_{zt^*}^{\text{sx}^?}(z.\text{structs}[a].\text{fields}[i])$ to the stack.

Todo: Below is the actual prose. (3) Introduce if-let instruction instead of “is of the case”. (5) Use “the expansion of” instead of \$expand function application.

1. Let F be the **current frame**.
2. Assert: due to **validation**, the **defined type** $F.\text{module.types}[x]$ exists.
3. Let deftype be the **defined type** $F.\text{module.types}[x]$.
4. Assert: due to **validation**, the **expansion** of deftype is a **structure type** with at least $y + 1$ fields.
5. Let **struct** ft^* be the **expanded structure type** of deftype .
6. Let ft_y be the y -th **field type** of ft^* .
7. Assert: due to **validation**, a **value** of type $(\text{ref null } x)$ is on the top of the stack.
8. Pop the value ref from the stack.
9. If ref is $\text{ref.null } t$, then:
 - a. Trap.
10. Assert: due to **validation**, a ref is a **structure reference**.
11. Let $\text{ref.struct } a$ be the reference value ref .
12. Assert: due to **validation**, the **structure instance** $S.\text{structs}[a]$ exists and has at least $y + 1$ fields.
13. Let fieldval be the **field value** $S.\text{structs}[a].\text{fields}[y]$.
14. Let val be the result of computing $\text{unpack}_{ft_y}^{\text{sx}^?}(\text{fieldval})$.
15. Push the value val to the stack.

$$z; (\text{ref.null } ht) (\text{struct.get_sx}^? x i) \hookrightarrow \text{trap}$$

$$z; (\text{ref.struct } a) (\text{struct.get_sx}^? x i) \hookrightarrow \text{unpack}_{zt^*[i]}^{sx^?} (z.\text{structs}[a].\text{fields}[i]) \quad \text{if } z.\text{types}[x] \approx \text{struct } (\text{mut}^? zt)^*$$

`struct.set x i`

1. Let z be the current state.
2. Assert: Due to validation, a value is on the top of the stack.
3. Pop the value val from the stack.
4. Assert: Due to validation, a value is on the top of the stack.
5. Pop the value $instr_{u0}$ from the stack.
6. If $instr_{u0}$ is of the case `ref.null`, then:
 - a. Trap.
7. Assert: Due to validation, $\text{expand}(z.\text{types}[x])$ is of the case `struct`.
8. Let $(\text{struct } y_0)$ be $\text{expand}(z.\text{types}[x])$.
9. Let $(\text{mut}^?, zt)^*$ be y_0 .
10. If $instr_{u0}$ is of the case `ref.struct`, then:
 - a. Let $(\text{ref.struct } a)$ be $instr_{u0}$.
 - b. If $|\text{mut}^?|$ is $|zt^*|$ and i is less than $|zt^*|$, then:
 - 1) Perform $z[\text{structs}[a].\text{fields}[i]] = \text{pack}_{zt^*[i]}(val)$.

Todo: Below is the actual prose. (3) Introduce if-let instruction instead of “is of the case”. (5) Use “the expansion of” instead of \$expand function application.

1. Let F be the `current frame`.
 2. Assert: due to `validation`, the `defined type` $F.\text{module.types}[x]$ exists.
 3. Let $deftype$ be the `defined type` $F.\text{module.types}[x]$.
 4. Assert: due to `validation`, the `expansion` of $deftype$ is a `structure type` with at least $y + 1$ fields.
 5. Let $\text{struct } ft^*$ be the `expanded structure type` of $deftype$.
 6. Let ft_y be the y -th `field type` of ft^* .
 7. Assert: due to `validation`, a `value` is on the top of the stack.
 8. Pop the value val from the stack.
 9. Assert: due to `validation`, a `value` of `type` $(\text{ref null } x)$ is on the top of the stack.
 10. Pop the value ref from the stack.
 11. If ref is `ref.null` t , then:
 - a. Trap.
 12. Assert: due to `validation`, a ref is a `structure reference`.
 13. Let $\text{ref.struct } a$ be the reference value ref .
 14. Assert: due to `validation`, the `structure instance` $S.\text{structs}[a]$ exists and has at least $y + 1$ fields.
 15. Let $fieldval$ be the result of computing $\text{pack}_{ft_y}(val)$.
 16. Replace the `field value` $S.\text{structs}[a].\text{fields}[y]$ with $fieldval$.
- $$z; (\text{ref.null } ht) \text{ val } (\text{struct.set } x i) \hookrightarrow z; \text{trap}$$
- $$z; (\text{ref.struct } a) \text{ val } (\text{struct.set } x i) \hookrightarrow z[\text{structs}[a].\text{fields}[i]] = \text{pack}_{zt^*[i]}(val); \epsilon \quad \text{if } z.\text{types}[x] \approx \text{struct } (\text{mut}^? zt)^*$$

`array.new x`

1. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
2. Pop the value `(i32.const n)` from the stack.
3. Assert: Due to validation, a value is on the top of the stack.
4. Pop the value `val` from the stack.
5. Push the values `valn` to the stack.
6. Execute the instruction `(array.new_fixed x n)`.

$$val\ (i32.const\ n)\ (array.new\ x) \hookrightarrow val^n\ (array.new_fixed\ x\ n)$$

`array.new_default x`

1. Let z be the current state.
2. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
3. Pop the value `(i32.const n)` from the stack.
4. Assert: Due to validation, `expand(z.types[x])` is of the case `array`.
5. Let `(array y0)` be `expand(z.types[x])`.
6. Let `(mut?, zt)` be y_0 .
7. Assert: Due to validation, `defaultunpack(zt)` is defined.
8. Let `val` be `defaultunpack(zt)`.
9. Push the values `valn` to the stack.
10. Execute the instruction `(array.new_fixed x n)`.

Todo: Below is the actual prose. (3') Introduce let binding instead of “is of the case”. (5) Use “the expansion of” instead of `$expand` function application.

1. Let F be the `current frame`.
 2. Assert: due to `validation`, the `defined type F.module.types[x]` exists.
 3. Let `deftype` be the `defined type F.module.types[x]`.
 4. Assert: due to `validation`, the `expansion of deftype` is an `array type`.
 5. Let `array ft` be the `expanded array type of deftype`.
 6. Assert: due to `validation`, a `value of type i32` is on the top of the stack.
 7. Pop the value `i32.const n` from the stack.
 8. Let t be the `value type unpack(ft)`.
 9. Assert: due to `validation`, `defaultt` is defined.
 10. Push the `value defaultt` to the stack n times.
 11. Execute the instruction `(array.new_fixed x n)`.
- $$z; (i32.const\ n)\ (array.new_default\ x) \hookrightarrow val^n\ (array.new_fixed\ x\ n) \quad \text{if } z.types[x] \approx \text{array } (mut^? \ zt) \wedge \text{default}_{unpack(zt)} = val$$

`array.new_fixed x n`

1. Let z be the current state.
2. Assert: Due to validation, there are at least n values on the top of the stack.
3. Pop the values val^n from the stack.
4. Let a be $|z.arrays|$.
5. Assert: Due to validation, $\text{expand}(z.types[x])$ is of the case `array`.
6. Let $(array\ y_0)$ be $\text{expand}(z.types[x])$.
7. Let $(mut^?, zt)$ be y_0 .
8. Let ai be $\{type\ z.types[x],\ fields\ pack_{zt}(val)^n\}$.
9. Push the value $(ref.array\ a)$ to the stack.
10. Perform $z[.arrays = ..ai]$.

Todo: Below is the actual prose. (3') Introduce let binding instead of “is of the case”. (5) Use “the expansion of” instead of \$expand function application.

1. Let F be the `current frame`.
2. Assert: due to `validation`, the `defined type` $F.module.types[x]$ exists.
3. Let $deftype$ be the `defined type` $F.module.types[x]$.
4. Assert: due to `validation`, the `expansion` of $deftype$ is a `array type`.
5. Let $array\ ft$ be the `expanded array type` of $deftype$.
6. Assert: due to `validation`, n `values` are on the top of the stack.
7. Pop the n values val^* from the stack.
8. For every value val_i in val^* :
 - a. Let $fieldval_i$ be the result of computing $pack_{ft}(val_i)$.
9. Let $fieldval^*$ be the concatenation of all field values $fieldval_i$.
10. Let ai be the `array instance` $\{type\\ deftype,\ fields\ fieldval^*\}$.
11. Let a be the length of $S.arrays$.
12. Append ai to $S.arrays$.
13. Push the `array reference` $ref.array\ a$ to the stack.

$$z; val^n (\text{array.new_fixed } x\ n) \hookrightarrow z[.arrays = ..ai]; (ref.array\ a) \\ \text{if } z.types[x] \approx \text{array } (mut^? zt) \\ \wedge a = |z.arrays| \wedge ai = \{type\ z.types[x],\ fields\ (pack_{zt}(val))^n\}$$

`array.new_data` $x\ y$

1. Let z be the current state.
2. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
3. Pop the value (const `i32` n) from the stack.
4. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
5. Pop the value (const `i32` i) from the stack.
6. If `expand($z.types[x]$)` is of the case `array`, then:
 - a. Let (array y_0) be `expand($z.types[x]$)`.
 - b. Let ($mut^?$, zt) be y_0 .
 - c. If $i + n \cdot |zt|/8$ is greater than $|z.datas[y].bytes|$, then:
 - 1) Trap.
 - d. Let cnn be `unpack(zt)`.
 - e. Let b^* be $z.datas[y].bytes[i : n \cdot |zt|/8]$.
 - f. Let gb^* be `groupbytesby($|zt|/8, b^*$)`.
 - g. Let c^n be `inverseofibytes($|zt|, gb^*$)`.
 - h. Push the values (const $cnn\ c$) n to the stack.
 - i. Execute the instruction (array.new_fixed $x\ n$).

Todo: Below is the actual prose. (7) Render `$inverse_` with display hint.

1. Let F be the `current frame`.
2. Assert: due to `validation`, the `defined type` $F.module.types[x]$ exists.
3. Let $deftype$ be the `defined type` $F.module.types[x]$.
4. Assert: due to `validation`, the `expansion` of $deftype$ is an `array type`.
5. Let `array ft` be the `expanded array type` of $deftype$.
6. Assert: due to `validation`, the `data address` $F.module.datas[y]$ exists.
7. Let da be the `data address` $F.module.datas[y]$.
8. Assert: due to `validation`, the `data instance` $S.datas[da]$ exists.
9. Let $datainst$ be the `data instance` $S.datas[da]$.
10. Assert: due to `validation`, two `values` of type `i32` are on the top of the stack.
11. Pop the value `i32.const` n from the stack.
12. Pop the value `i32.const` s from the stack.
13. Assert: due to `validation`, the `field type` ft has a defined `bit width`.
14. Let z be the `bit width` of `field type` ft divided by eight.
15. If the sum of s and n times z is larger than the length of $datainst.bytes$, then:
 - a. Trap.
16. Let b^* be the `byte sequence` $datainst.bytes[s : n \cdot z]$.
17. Let t be the `value type` `unpack(ft)`.
18. For each consecutive subsequence b'^n of b^* :

- a. Assert: due to **validation**, bytes_{ft} is defined.
- b. Let c_i be the constant for which $\text{bytes}_{ft}(c_i)$ is b'^n .
- c. Push the value $t.\text{const } c_i$ to the stack.

19. Execute the instruction `(array.new_fixed x n)`.

$$\begin{aligned}
 z; (i32.\text{const } i) (i32.\text{const } n) (\text{array.new_data } x y) &\hookrightarrow \text{trap} && \begin{aligned} &\text{if } z.\text{types}[x] \approx \text{array } (\text{mut}^? zt) \\ &\wedge i + n \cdot |zt|/8 > |z.\text{datas}[y].\text{bytes}| \end{aligned} \\
 z; (i32.\text{const } i) (i32.\text{const } n) (\text{array.new_data } x y) &\hookrightarrow (\text{unpack}(zt).\text{const } \text{unpack}_{zt}(c))^n (\text{array.new_fixed } x n) && \begin{aligned} &\text{if } z.\text{types}[x] \approx \text{array } (\text{mut}^? zt) \\ &\wedge \text{concat}(\text{bytes}_{zt}(c)^n) = z.\text{datas}[y].\text{bytes}[i : n \cdot |zt|/8] \end{aligned}
 \end{aligned}$$

`array.new_elem x y`

1. Let z be the current state.
2. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
3. Pop the value `(i32.const n)` from the stack.
4. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
5. Pop the value `(i32.const i)` from the stack.
6. If $i + n$ is greater than $|z.\text{elems}[y].\text{elem}|$, then:
 - a. Trap.
7. Let ref^n be $z.\text{elems}[y].\text{elem}[i : n]$.
8. Push the values ref^n to the stack.
9. Execute the instruction `(array.new_fixed x n)`.

$$\begin{aligned}
 z; (i32.\text{const } i) (i32.\text{const } n) (\text{array.new_elem } x y) &\hookrightarrow \text{trap} && \text{if } i + n > |z.\text{elems}[y].\text{elem}| \\
 z; (i32.\text{const } i) (i32.\text{const } n) (\text{array.new_elem } x y) &\hookrightarrow \text{ref}^n (\text{array.new_fixed } x n) && \text{if } \text{ref}^n = z.\text{elems}[y].\text{elem}[i : n]
 \end{aligned}$$

`array.get_sx? x`

1. Let z be the current state.
2. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
3. Pop the value `(i32.const i)` from the stack.
4. Assert: Due to validation, a value is on the top of the stack.
5. Pop the value instr_{u0} from the stack.
6. If instr_{u0} is of the case `ref.null`, then:
 - a. Trap.
7. If instr_{u0} is of the case `ref.array`, then:
 - a. Let `(ref.array a)` be instr_{u0} .
 - b. If a is less than $|z.\text{arrays}|$ and i is greater than or equal to $|z.\text{arrays}[a].\text{fields}|$, then:
 - 1) Trap.
8. Assert: Due to validation, $\text{expand}(z.\text{types}[x])$ is of the case `array`.
9. Let `(array y0)` be $\text{expand}(z.\text{types}[x])$.
10. Let $(\text{mut}^?, zt)$ be y_0 .

11. If $instr_{u0}$ is of the case `ref.array`, then:
 - a. Let $(ref.array\ a)$ be $instr_{u0}$.
 - b. If i is less than $|z.arrays[a].fields|$ and a is less than $|z.arrays|$, then:
 - 1) Push the value $unpack_{zt}^{sx?}(z.arrays[a].fields[i])$ to the stack.

Todo: Below is the actual prose. (3) Introduce if-let instruction instead of “is of the case”. (5) Use “the expansion of” instead of $\$expand$ function application.

1. Let F be the current frame.
 2. Assert: due to validation, the defined type $F.module.types[x]$ exists.
 3. Let $deftype$ be the defined type $F.module.types[x]$.
 4. Assert: due to validation, the expansion of $deftype$ is an array type.
 5. Let $array\ ft$ be the expanded array type of $deftype$.
 6. Assert: due to validation, a value of type `i32` is on the top of the stack.
 7. Pop the value `i32.const i` from the stack.
 8. Assert: due to validation, a value of type $(ref\ null\ x)$ is on the top of the stack.
 9. Pop the value ref from the stack.
 10. If ref is `ref.null t`, then:
 - a. Trap.
 11. Assert: due to validation, ref is an array reference.
 12. Let $ref.array\ a$ be the reference value ref .
 13. Assert: due to validation, the array instance $S.arrays[a]$ exists.
 14. If n is larger than or equal to the length of $S.arrays[a].fields$, then:
 - a. Trap.
 15. Let $fieldval$ be the field value $S.arrays[a].fields[i]$.
 16. Let val be the result of computing $unpack_{ft}^{sx?}(fieldval)$.
 17. Push the value val to the stack.
- $$\begin{array}{ll}
z; (ref.null\ ht) (i32.const\ i) (array.get_{sx?}\ x) & \hookrightarrow \text{trap} \\
z; (ref.array\ a) (i32.const\ i) (array.get_{sx?}\ x) & \hookrightarrow \text{trap} \quad \text{if } i \geq |z.arrays[a].fields| \\
z; (ref.array\ a) (i32.const\ i) (array.get_{sx?}\ x) & \hookrightarrow unpack_{zt}^{sx?}(z.arrays[a].fields[i]) \\
& \quad \text{if } z.types[x] \approx array\ (mut? \ zt)
\end{array}$$

`array.set x`

1. Let z be the current state.
2. Assert: Due to validation, a value is on the top of the stack.
3. Pop the value val from the stack.
4. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
5. Pop the value $(i32.const\ i)$ from the stack.
6. Assert: Due to validation, a value is on the top of the stack.
7. Pop the value $instr_{u0}$ from the stack.

8. If $instr_{u0}$ is of the case `ref.null`, then:
 - a. Trap.
9. If $instr_{u0}$ is of the case `ref.array`, then:
 - a. Let $(ref.array\ a)$ be $instr_{u0}$.
 - b. If a is less than $|z.arrays|$ and i is greater than or equal to $|z.arrays[a].fields|$, then:
 - 1) Trap.
10. Assert: Due to validation, $expand(z.types[x])$ is of the case `array`.
11. Let $(array\ y_0)$ be $expand(z.types[x])$.
12. Let $(mut^?, zt)$ be y_0 .
13. If $instr_{u0}$ is of the case `ref.array`, then:
 - a. Let $(ref.array\ a)$ be $instr_{u0}$.
 - b. Perform $z.arrays[a].fields[i] = pack_{zt}(val)$.

Todo: Below is the actual prose. (3) Introduce if-let instruction instead of “is of the case”. (5) Use “the expansion of” instead of \$expand function application.

1. Let F be the `current frame`.
2. Assert: due to `validation`, the `defined type` $F.module.types[x]$ exists.
3. Let $deftype$ be the `defined type` $F.module.types[x]$.
4. Assert: due to `validation`, the `expansion` of $deftype$ is an `array type`.
5. Let $array\ ft$ be the `expanded array type` of $deftype$.
6. Assert: due to `validation`, a `value` is on the top of the stack.
7. Pop the `value` val from the stack.
8. Assert: due to `validation`, a `value` of `type` `i32` is on the top of the stack.
9. Pop the `value` `i32.const` i from the stack.
10. Assert: due to `validation`, a `value` of `type` `(ref null x)` is on the top of the stack.
11. Pop the `value` ref from the stack.
12. If ref is `ref.null` t , then:
 - a. Trap.
13. Assert: due to `validation`, ref is an `array reference`.
14. Let $ref.array\ a$ be the `reference value` ref .
15. Assert: due to `validation`, the `array instance` $S.arrays[a]$ exists.
16. If n is larger than or equal to the length of $S.arrays[a].fields$, then:
 - a. Trap.
17. Let $fieldval$ be the result of computing $pack_{ft}(val)$.
18. Replace the `field value` $S.arrays[a].fields[i]$ with $fieldval$.

$$\begin{aligned}
 z; (ref.null\ ht)\ (i32.const\ i)\ val\ (array.set\ x) &\hookrightarrow z; trap \\
 z; (ref.array\ a)\ (i32.const\ i)\ val\ (array.set\ x) &\hookrightarrow z; trap \quad \text{if } i \geq |z.arrays[a].fields| \\
 z; (ref.array\ a)\ (i32.const\ i)\ val\ (array.set\ x) &\hookrightarrow z.arrays[a].fields[i] = pack_{zt}(val); \epsilon \\
 &\quad \text{if } z.types[x] \approx array\ (mut^?\ zt)
 \end{aligned}$$

`array.len`

1. Let z be the current state.
2. Assert: Due to validation, a value is on the top of the stack.
3. Pop the value $instr_{u0}$ from the stack.
4. If $instr_{u0}$ is of the case `ref.null`, then:
 - a. Trap.
5. If $instr_{u0}$ is of the case `ref.array`, then:
 - a. Let $(ref.array\ a)$ be $instr_{u0}$.
 - b. If a is less than $|z.arrays|$, then:
 - 1) Push the value $(i32.const\ |z.arrays[a].fields|)$ to the stack.

Todo:

- (3) Introduce if-let instruction instead of “is of the case”.

$$\begin{aligned} z; (ref.null\ ht)\ array.len &\hookrightarrow trap \\ z; (ref.array\ a)\ array.len &\hookrightarrow (i32.const\ |z.arrays[a].fields|) \end{aligned}$$
`array.fill x`

1. Let z be the current state.
2. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
3. Pop the value $(i32.const\ n)$ from the stack.
4. Assert: Due to validation, a value is on the top of the stack.
5. Pop the value val from the stack.
6. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
7. Pop the value $(i32.const\ i)$ from the stack.
8. Assert: Due to validation, a value is on the top of the stack.
9. Pop the value $instr_{u0}$ from the stack.
10. If $instr_{u0}$ is of the case `ref.null`, then:
 - a. Trap.
11. If $instr_{u0}$ is of the case `ref.array`, then:
 - a. Let $(ref.array\ a)$ be $instr_{u0}$.
 - b. If a is less than $|z.arrays|$ and $i + n$ is greater than $|z.arrays[a].fields|$, then:
 - 1) Trap.
 - c. If n is 0, then:
 - 1) Do nothing.
 - d. Else:
 - 1) Let $(ref.array\ a)$ be $instr_{u0}$.
 - 2) Push the value $(ref.array\ a)$ to the stack.
 - 3) Push the value $(i32.const\ i)$ to the stack.

- 4) Push the value *val* to the stack.
- 5) Execute the instruction (`array.set x`).
- 6) Push the value (`ref.array a`) to the stack.
- 7) Push the value (`i32.const i + 1`) to the stack.
- 8) Push the value *val* to the stack.
- 9) Push the value (`i32.const n - 1`) to the stack.
- 10) Execute the instruction (`array.fill x`).

Todo:

- (3) Introduce if-let instruction instead of “is of the case”.

<code>z; (ref.null ht) (i32.const i) val (i32.const n) (array.fill x)</code>	\hookrightarrow	trap	
<code>z; (ref.array a) (i32.const i) val (i32.const n) (array.fill x)</code>	\hookrightarrow	trap	if $i + n > z.arrays[a].fields $
<code>z; (ref.array a) (i32.const i) val (i32.const n) (array.fill x)</code>	\hookrightarrow	ϵ	otherwise, if $n = 0$
<code>z; (ref.array a) (i32.const i) val (i32.const n) (array.fill x)</code>	\hookrightarrow		
<code>(ref.array a) (i32.const i) val (array.set x)</code>			otherwise
<code>(ref.array a) (i32.const i + 1) val (i32.const n - 1) (array.fill x)</code>			

array.copy $x_1 x_2$

1. Let z be the current state.
2. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
3. Pop the value (`i32.const n`) from the stack.
4. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
5. Pop the value (`i32.const i2`) from the stack.
6. Assert: Due to validation, a value is on the top of the stack.
7. Pop the value *instr_{u1}* from the stack.
8. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
9. Pop the value (`i32.const i1`) from the stack.
10. Assert: Due to validation, a value is on the top of the stack.
11. Pop the value *instr_{u0}* from the stack.
12. If *instr_{u0}* is of the case `ref.null` and the type of *instr_{u1}* is ref, then:
 - a. Trap.
13. If *instr_{u1}* is of the case `ref.null` and the type of *instr_{u0}* is ref, then:
 - a. Trap.
14. If *instr_{u0}* is of the case `ref.array`, then:
 - a. Let (`ref.array a1`) be *instr_{u0}*.
 - b. If *instr_{u1}* is of the case `ref.array`, then:
 - 1) If a_1 is less than $|z.arrays|$ and $i_1 + n$ is greater than $|z.arrays[a_1].fields|$, then:
 - a) Trap.
 - 2) Let (`ref.array a2`) be *instr_{u1}*.
 - 3) If a_2 is less than $|z.arrays|$ and $i_2 + n$ is greater than $|z.arrays[a_2].fields|$, then:

- a) Trap.
- c. If n is 0, then:
 - 1) If $instr_{u1}$ is of the case `ref.array`, then:
 - a) Do nothing.
- d. Else if i_1 is greater than i_2 , then:
 - 1) Assert: Due to validation, `expand($z.types[x_2]$)` is of the case `array`.
 - 2) Let `(array y_0)` be `expand($z.types[x_2]$)`.
 - 3) Let `(mut?, zt_2)` be y_0 .
 - 4) Let `(ref.array a_1)` be $instr_{u0}$.
 - 5) If $instr_{u1}$ is of the case `ref.array`, then:
 - a) Let `(ref.array a_2)` be $instr_{u1}$.
 - b) Let $sx^?$ be $sx(zt_2)$.
 - c) Push the value `(ref.array a_1)` to the stack.
 - d) Push the value `(i32.const $i_1 + n - 1$)` to the stack.
 - e) Push the value `(ref.array a_2)` to the stack.
 - f) Push the value `(i32.const $i_2 + n - 1$)` to the stack.
 - g) Execute the instruction `(array.get_ $sx^?$ x_2)`.
 - h) Execute the instruction `(array.set x_1)`.
 - i) Push the value `(ref.array a_1)` to the stack.
 - j) Push the value `(i32.const i_1)` to the stack.
 - k) Push the value `(ref.array a_2)` to the stack.
 - l) Push the value `(i32.const i_2)` to the stack.
 - m) Push the value `(i32.const $n - 1$)` to the stack.
 - n) Execute the instruction `(array.copy x_1 x_2)`.
- e. Else:
 - 1) Assert: Due to validation, `expand($z.types[x_2]$)` is of the case `array`.
 - 2) Let `(array y_0)` be `expand($z.types[x_2]$)`.
 - 3) Let `(mut?, zt_2)` be y_0 .
 - 4) Let `(ref.array a_1)` be $instr_{u0}$.
 - 5) If $instr_{u1}$ is of the case `ref.array`, then:
 - a) Let `(ref.array a_2)` be $instr_{u1}$.
 - b) Let $sx^?$ be $sx(zt_2)$.
 - c) Push the value `(ref.array a_1)` to the stack.
 - d) Push the value `(i32.const i_1)` to the stack.
 - e) Push the value `(ref.array a_2)` to the stack.
 - f) Push the value `(i32.const i_2)` to the stack.
 - g) Execute the instruction `(array.get_ $sx^?$ x_2)`.
 - h) Execute the instruction `(array.set x_1)`.
 - i) Push the value `(ref.array a_1)` to the stack.

- j) Push the value (`i32.const` $i_1 + 1$) to the stack.
- k) Push the value (`ref.array` a_2) to the stack.
- l) Push the value (`i32.const` $i_2 + 1$) to the stack.
- m) Push the value (`i32.const` $n - 1$) to the stack.
- n) Execute the instruction (`array.copy` x_1 x_2).

Todo: Below is the actual prose. (3) Introduce if-let instruction instead of “is of the case”. (5) Use “the expansion of” instead of \$expand function application.

1. Let F be the `current frame`.
2. Assert: due to `validation`, the defined type $F.module.types[y]$ exists.
3. Let $deftype$ be the defined type $F.module.types[y]$.
4. Assert: due to `validation`, the expansion of $deftype$ is an `array type`.
5. Let `array mut st` be the expanded array type $deftype$.
6. Assert: due to `validation`, a value of type `i32` is on the top of the stack.
7. Pop the value `i32.const` n from the stack.
8. Assert: due to `validation`, a value of type `i32` is on the top of the stack.
9. Pop the value `i32.const` s from the stack.
10. Assert: due to `validation`, a value of type (`ref null` y) is on the top of the stack.
11. Pop the value ref_2 from the stack.
12. Assert: due to `validation`, a value of type `i32` is on the top of the stack.
13. Pop the value `i32.const` d from the stack.
14. Assert: due to `validation`, a value of type (`ref null` x) is on the top of the stack.
15. Pop the value ref_1 from the stack.
16. If ref_1 is `ref.null` t , then:
 - a. Trap.
17. Assert: due to `validation`, ref_1 is an `array reference`.
18. Let `ref.array` a_1 be the reference value ref_1 .
19. If ref_2 is `ref.null` t , then:
 - a. Trap.
20. Assert: due to `validation`, ref_2 is an `array reference`.
21. Let `ref.array` a_2 be the reference value ref_2 .
22. Assert: due to `validation`, the array instance $S.arrays[a_1]$ exists.
23. Assert: due to `validation`, the array instance $S.arrays[a_2]$ exists.
24. If $d + n$ is larger than the length of $S.arrays[a_1].fields$, then:
 - a. Trap.
25. If $s + n$ is larger than the length of $S.arrays[a_2].fields$, then:
 - a. Trap.
26. If $n = 0$, then:
 - a. Return.

27. If $d \leq s$, then:

- a. Push the value `ref.array` a_1 to the stack.
- b. Push the value `i32.const` d to the stack.
- c. Push the value `ref.array` a_2 to the stack.
- d. Push the value `i32.const` s to the stack.
- e. Execute `getfield(st)`.
- f. Execute the instruction `array.set x`.
- g. Push the value `ref.array` a_1 to the stack.
- h. Assert: due to the earlier check against the array size, $d + 1 < 2^{32}$.
- i. Push the value `i32.const` $(d + 1)$ to the stack.
- j. Push the value `ref.array` a_2 to the stack.
- k. Assert: due to the earlier check against the array size, $s + 1 < 2^{32}$.
- l. Push the value `i32.const` $(s + 1)$ to the stack.

28. Else:

- a. Push the value `ref.array` a_1 to the stack.
- b. Assert: due to the earlier check against the memory size, $d + n - 1 < 2^{32}$.
- c. Push the value `i32.const` $(d + n - 1)$ to the stack.
- d. Push the value `ref.array` a_2 to the stack.
- e. Assert: due to the earlier check against the memory size, $s + n - 1 < 2^{32}$.
- f. Push the value `i32.const` $(s + n - 1)$ to the stack.
- g. Execute `getfield(st)`.
- h. Execute the instruction `array.set x`.
- i. Push the value `ref.array` a_1 to the stack.
- j. Push the value `i32.const` d to the stack.
- k. Push the value `ref.array` a_2 to the stack.
- l. Push the value `i32.const` s to the stack.

29. Push the value `i32.const` $(n - 1)$ to the stack.

30. Execute the instruction `array.copy x y`.

$$\begin{aligned}
& z; (\text{ref.null } ht_1) \text{ (i32.const } i_1) \text{ ref (i32.const } i_2) \text{ (i32.const } n) \text{ (array.copy } x_1 \text{ } x_2) \quad \hookrightarrow \text{ trap} \\
& z; \text{ref (i32.const } i_1) \text{ (ref.null } ht_2) \text{ (i32.const } i_2) \text{ (i32.const } n) \text{ (array.copy } x_1 \text{ } x_2) \quad \hookrightarrow \text{ trap} \\
& z; (\text{ref.array } a_1) \text{ (i32.const } i_1) \text{ (ref.array } a_2) \text{ (i32.const } i_2) \text{ (i32.const } n) \text{ (array.copy } x_1 \text{ } x_2) \quad \hookrightarrow \text{ trap} \\
& \quad \text{if } i_1 + n > |z.\text{arrays}[a_1].\text{fields}| \\
& z; (\text{ref.array } a_1) \text{ (i32.const } i_1) \text{ (ref.array } a_2) \text{ (i32.const } i_2) \text{ (i32.const } n) \text{ (array.copy } x_1 \text{ } x_2) \quad \hookrightarrow \text{ trap} \\
& \quad \text{if } i_2 + n > |z.\text{arrays}[a_2].\text{fields}| \\
& z; (\text{ref.array } a_1) \text{ (i32.const } i_1) \text{ (ref.array } a_2) \text{ (i32.const } i_2) \text{ (i32.const } n) \text{ (array.copy } x_1 \text{ } x_2) \quad \hookrightarrow \epsilon \\
& \quad \text{otherwise, if } n = 0 \\
& z; (\text{ref.array } a_1) \text{ (i32.const } i_1) \text{ (ref.array } a_2) \text{ (i32.const } i_2) \text{ (i32.const } n) \text{ (array.copy } x_1 \text{ } x_2) \quad \hookrightarrow \\
& \quad (\text{ref.array } a_1) \text{ (i32.const } i_1) \\
& \quad (\text{ref.array } a_2) \text{ (i32.const } i_2) \\
& \quad (\text{array.get}_{sx}^? x_2) \text{ (array.set } x_1) \\
& \quad (\text{ref.array } a_1) \text{ (i32.const } i_1 + 1) \text{ (ref.array } a_2) \text{ (i32.const } i_2 + 1) \text{ (i32.const } n - 1) \text{ (array.copy } x_1 \text{ } x_2) \\
& \quad \text{otherwise, if } z.\text{types}[x_2] \approx \text{array (mut}^? zt_2) \\
& \quad \wedge i_1 \leq i_2 \wedge sx^? = sx(zt_2) \\
& z; (\text{ref.array } a_1) \text{ (i32.const } i_1) \text{ (ref.array } a_2) \text{ (i32.const } i_2) \text{ (i32.const } n) \text{ (array.copy } x_1 \text{ } x_2) \quad \hookrightarrow \\
& \quad (\text{ref.array } a_1) \text{ (i32.const } i_1 + n - 1) \\
& \quad (\text{ref.array } a_2) \text{ (i32.const } i_2 + n - 1) \\
& \quad (\text{array.get}_{sx}^? x_2) \text{ (array.set } x_1) \\
& \quad (\text{ref.array } a_1) \text{ (i32.const } i_1) \text{ (ref.array } a_2) \text{ (i32.const } i_2) \text{ (i32.const } n - 1) \text{ (array.copy } x_1 \text{ } x_2) \\
& \quad \text{otherwise, if } z.\text{types}[x_2] \approx \text{array (mut}^? zt_2) \\
& \quad \wedge sx^? = sx(zt_2)
\end{aligned}$$

Where:

$$\begin{aligned}
sx(consttype) &= \epsilon \\
sx(packtype) &= s
\end{aligned}$$

`array.init_data` $x \ y$

1. Let z be the current state.
2. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
3. Pop the value `(i32.const n)` from the stack.
4. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
5. Pop the value `(i32.const j)` from the stack.
6. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
7. Pop the value `(i32.const i)` from the stack.
8. Assert: Due to validation, a value is on the top of the stack.
9. Pop the value `$instr_{u0}$` from the stack.
10. If `$instr_{u0}$` is of the case `ref.null`, then:
 - a. Trap.
11. If `$instr_{u0}$` is of the case `ref.array`, then:
 - a. Let `(ref.array a)` be `$instr_{u0}$` .
 - b. If a is less than `|z.arrays|` and $i + n$ is greater than `|z.arrays[a].fields|`, then:
 - 1) Trap.
12. If `expand($z.\text{types}[x]$)` is not of the case `array`, then:
 - a. If n is 0 and `$instr_{u0}$` is of the case `ref.array`, then:
 - 1) Do nothing.

13. Else:
 - a. Let $(array\ y_0)$ be $expand(z.types[x])$.
 - b. Let $(mut^?, zt)$ be y_0 .
 - c. If $instr_{u0}$ is of the case $ref.array$, then:
 - 1) If $j + n \cdot |zt|/8$ is greater than $|z.datas[y].bytes|$, then:
 - a) Trap.
 - 2) If n is 0, then:
 - a) Do nothing.
 - 3) Else:
 - a) Let $(array\ y_0)$ be $expand(z.types[x])$.
 - b) Let $(mut^?, zt)$ be y_0 .
 - c) Let $(ref.array\ a)$ be $instr_{u0}$.
 - d) Let c be $inverse_{of\ zbytes}(zt, z.datas[y].bytes[j : |zt|/8])$.
 - e) Push the value $(ref.array\ a)$ to the stack.
 - f) Push the value $(i32.const\ i)$ to the stack.
 - g) Push the value $unpack(zt).const\ unpack_{zt}(c)$ to the stack.
 - h) Execute the instruction $(array.set\ x)$.
 - i) Push the value $(ref.array\ a)$ to the stack.
 - j) Push the value $(i32.const\ i + 1)$ to the stack.
 - k) Push the value $(i32.const\ j + |zt|/8)$ to the stack.
 - l) Push the value $(i32.const\ n - 1)$ to the stack.
 - m) Execute the instruction $(array.init_data\ x\ y)$.

Todo: Below is the actual prose. (7) Render $\$inverse_$ with display hint.

1. Let F be the **current frame**.
2. Assert: due to **validation**, the **defined type** $F.module.types[x]$ exists.
3. Let $deftype$ be the **defined type** $F.module.types[x]$.
4. Assert: due to **validation**, the **expansion** of $deftype$ is an **array type**.
5. Let $array\ ft$ be the **expanded array type** $deftype$.
6. Assert: due to **validation**, the **data address** $F.module.datas[y]$ exists.
7. Let da be the **data address** $F.module.datas[y]$.
8. Assert: due to **validation**, the **data instance** $S.datas[da]$ exists.
9. Let $datainst$ be the **data instance** $S.datas[da]$.
10. Assert: due to **validation**, three values of type **i32** are on the top of the stack.
11. Pop the value $i32.const\ n$ from the stack.
12. Pop the value $i32.const\ s$ from the stack.
13. Pop the value $i32.const\ d$ from the stack.
14. Assert: due to **validation**, a value of type **(ref null x)** is on the top of the stack.
15. Pop the value ref from the stack.

16. If ref is $ref.null\ t$, then:
 - a. Trap.
17. Assert: due to **validation**, ref is an array reference.
18. Let $ref.array\ a$ be the reference value ref .
19. Assert: due to **validation**, the array instance $S.arrays[a]$ exists.
20. Assert: due to **validation**, the field type ft has a defined bit width.
21. Let z be the bit width of field type ft divided by eight.
22. If $d + n$ is larger than the length of $S.arrays[a].fields$, or the sum of s and n times z is larger than the length of $datainst.bytes$, then:
 - a. Trap.
23. If $n = 0$, then:
 - a. Return.
24. Let b^* be the byte sequence $datainst.bytes[s : z]$.
25. Let t be the value type $unpack(ft)$.
26. Assert: due to **validation**, $bytes_{ft}$ is defined.
27. Let c be the constant for which $bytes_{ft}(c)$ is b^* .
28. Push the value $ref.array\ a$ to the stack.
29. Push the value $i32.const\ d$ to the stack.
30. Push the value $t.const\ c$ to the stack.
31. Execute the instruction `array.set` x .
32. Push the value $ref.array\ a$ to the stack.
33. Push the value $i32.const\ (d + 1)$ to the stack.
34. Push the value $i32.const\ (s + z)$ to the stack.
35. Push the value $i32.const\ (n - 1)$ to the stack.
36. Execute the instruction `array.init_data` $x\ y$.

$$\begin{aligned}
 & z; (ref.null\ ht) (i32.const\ i) (i32.const\ j) (i32.const\ n) (array.init_data\ x\ y) \hookrightarrow \text{trap} \\
 & z; (ref.array\ a) (i32.const\ i) (i32.const\ j) (i32.const\ n) (array.init_data\ x\ y) \hookrightarrow \text{trap} \\
 & \quad \text{if } i + n > |z.arrays[a].fields| \\
 & z; (ref.array\ a) (i32.const\ i) (i32.const\ j) (i32.const\ n) (array.init_data\ x\ y) \hookrightarrow \text{trap} \\
 & \quad \text{if } z.types[x] \approx \text{array } (mut^? zt) \\
 & \quad \quad \wedge j + n \cdot |zt|/8 > |z.datas[y].bytes| \\
 & z; (ref.array\ a) (i32.const\ i) (i32.const\ j) (i32.const\ n) (array.init_data\ x\ y) \hookrightarrow \epsilon \\
 & \quad \text{otherwise, if } n = 0 \\
 & z; (ref.array\ a) (i32.const\ i) (i32.const\ j) (i32.const\ n) (array.init_data\ x\ y) \hookrightarrow \\
 & \quad (ref.array\ a) (i32.const\ i) (unpack(zt).const\ unpack_{zt}(c)) (array.set\ x) \\
 & \quad (ref.array\ a) (i32.const\ i + 1) (i32.const\ j + |zt|/8) (i32.const\ n - 1) (array.init_data\ x\ y) \\
 & \quad \text{otherwise, if } z.types[x] \approx \text{array } (mut^? zt) \\
 & \quad \quad \wedge bytes_{zt}(c) = z.datas[y].bytes[j : |zt|/8]
 \end{aligned}$$

`array.init_elem x y`

1. Let z be the current state.
2. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
3. Pop the value `(i32.const n)` from the stack.
4. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
5. Pop the value `(i32.const j)` from the stack.
6. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
7. Pop the value `(i32.const i)` from the stack.
8. Assert: Due to validation, a value is on the top of the stack.
9. Pop the value `instru0` from the stack.
10. If `instru0` is of the case `ref.null`, then:
 - a. Trap.
11. If `instru0` is of the case `ref.array`, then:
 - a. Let `(ref.array a)` be `instru0`.
 - b. If a is less than $|z.arrays|$ and $i + n$ is greater than $|z.arrays[a].fields|$, then:
 - 1) Trap.
12. If $j + n$ is greater than $|z.elems[y].elem|$, then:
 - a. If `instru0` is of the case `ref.array`, then:
 - 1) Trap.
 - b. If n is 0 and j is less than $|z.elems[y].elem|$, then:
 - 1) Let `ref` be `z.elems[y].elem[j]`.
 - 2) If `instru0` is of the case `ref.array`, then:
 - a) Let `(ref.array a)` be `instru0`.
 - b) Push the value `(ref.array a)` to the stack.
 - c) Push the value `(i32.const i)` to the stack.
 - d) Push the value `ref` to the stack.
 - e) Execute the instruction `(array.set x)`.
 - f) Push the value `(ref.array a)` to the stack.
 - g) Push the value `(i32.const i + 1)` to the stack.
 - h) Push the value `(i32.const j + 1)` to the stack.
 - i) Push the value `(i32.const n - 1)` to the stack.
 - j) Execute the instruction `(array.init_elem x y)`.
13. Else if n is 0, then:
 - a. If `instru0` is of the case `ref.array`, then:
 - 1) Do nothing.
14. Else:
 - a. If j is less than $|z.elems[y].elem|$, then:
 - 1) Let `ref` be `z.elems[y].elem[j]`.
 - 2) If `instru0` is of the case `ref.array`, then:

- a) Let $(\text{ref.array } a)$ be instr_{u0} .
- b) Push the value $(\text{ref.array } a)$ to the stack.
- c) Push the value $(\text{i32.const } i)$ to the stack.
- d) Push the value ref to the stack.
- e) Execute the instruction $(\text{array.set } x)$.
- f) Push the value $(\text{ref.array } a)$ to the stack.
- g) Push the value $(\text{i32.const } i + 1)$ to the stack.
- h) Push the value $(\text{i32.const } j + 1)$ to the stack.
- i) Push the value $(\text{i32.const } n - 1)$ to the stack.
- j) Execute the instruction $(\text{array.init_elem } x y)$.

Todo:

- (3) Introduce if-let instruction instead of “is of the case”.

```

z; (ref.null ht) (i32.const i) (i32.const j) (i32.const n) (array.init_elem x y)  ↪ trap
z; (ref.array a) (i32.const i) (i32.const j) (i32.const n) (array.init_elem x y)  ↪ trap
    if  $i + n > |z.\text{arrays}[a].\text{fields}|$ 
z; (ref.array a) (i32.const i) (i32.const j) (i32.const n) (array.init_elem x y)  ↪ trap
    if  $j + n > |z.\text{elems}[y].\text{elem}|$ 
z; (ref.array a) (i32.const i) (i32.const j) (i32.const n) (array.init_elem x y)  ↪  $\epsilon$ 
    otherwise, if  $n = 0$ 
z; (ref.array a) (i32.const i) (i32.const j) (i32.const n) (array.init_elem x y)  ↪
    (ref.array a) (i32.const i)  $\text{ref}$  (array.set x)
    (ref.array a) (i32.const i + 1) (i32.const j + 1) (i32.const n - 1) (array.init_elem x y)
    otherwise, if  $\text{ref} = z.\text{elems}[y].\text{elem}[j]$ 

```

any.convert_extern

1. Assert: Due to validation, a value is on the top of the stack.
2. Pop the value instr_{u0} from the stack.
3. If instr_{u0} is of the case **ref.null**, then:
 - a. Push the value (ref.null any) to the stack.
4. If instr_{u0} is of the case **ref.extern**, then:
 - a. Let $(\text{ref.extern } \text{addrref})$ be instr_{u0} .
 - b. Push the value addrref to the stack.

Todo:

- (3) Introduce if-let instruction instead of “is of the case”.

```

(ref.null ht) any.convert_extern  ↪ (ref.null any)
(ref.extern addrref) any.convert_extern  ↪ addrref

```

extern.convert_any

1. Assert: Due to validation, a value is on the top of the stack.
2. Pop the value *instr_{u0}* from the stack.
3. If *instr_{u0}* is of the case *ref.null*, then:
 - a. Push the value (*ref.null extern*) to the stack.
4. If the type of *instr_{u0}* is *addrref*, then:
 - a. Let *addrref* be *instr_{u0}*.
 - b. Push the value (*ref.extern addrref*) to the stack.

Todo:

- (3) Introduce if-let instruction instead of “is of the case”.

$$\begin{aligned} (\text{ref.null } ht) \text{ extern.convert_any} &\hookrightarrow (\text{ref.null extern}) \\ \text{addrref extern.convert_any} &\hookrightarrow (\text{ref.extern addrref}) \end{aligned}$$

4.6.4 Vector Instructions

Vector instructions that operate bitwise are handled as integer operations of respective width.

$$op_{vN}(i_1, \dots, i_k) = iop_N(i_1, \dots, i_k)$$

Most other vector instructions are defined in terms of numeric operators that are applied lane-wise according to the given *shape*.

$$op_{t \times N}(n_1, \dots, n_k) = \text{lanes}_{t \times N}^{-1}(op_t(i_1, \dots, i_k)^*) \quad (\text{if } i_1^* = \text{lanes}_{t \times N}(n_1) \wedge \dots \wedge i_k^* = \text{lanes}_{t \times N}(n_k))$$

Note: For example, the result of instruction *i32x4.add* applied to operands *v₁*, *v₂* invokes *add_{i32x4}(v₁, v₂)*, which maps to *lanes_{i32x4}⁻¹(add_{i32}(i₁, i₂)*)*, where *i₁^{*}* and *i₂^{*}* are sequences resulting from invoking *lanes_{i32x4}(v₁)* and *lanes_{i32x4}(v₂)* respectively.

v128.const c

1. Push the value *v128.const c* to the stack.

Note: No formal reduction rule is required for this instruction, since *const* instructions coincide with *values*.

v128.vvunop

1. Assert: Due to validation, a value is on the top of the stack.
2. Pop the value (*v128.const c₁*) from the stack.
3. Let *c* be *vvunop_{v128}(c₁)*.
4. Push the value (*v128.const c*) to the stack.

$$(\text{v128.const } c_1) (\text{v128.vvunop}) \hookrightarrow (\text{v128.const } c) \quad \text{if } c = \text{vvunop}_{v128}(c_1)$$

v128.vbinop

1. Assert: Due to validation, a value is on the top of the stack.
2. Pop the value (*v128.const* c_2) from the stack.
3. Assert: Due to validation, a value is on the top of the stack.
4. Pop the value (*v128.const* c_1) from the stack.
5. Let c be *vbinop*_{v128}(c_1, c_2).
6. Push the value (*v128.const* c) to the stack.

$$(\text{v128.const } c_1) (\text{v128.const } c_2) (\text{v128.vbinop}) \hookrightarrow (\text{v128.const } c) \quad \text{if } c = \text{vbinop}_{\text{v128}}(c_1, c_2)$$

v128.vternop

1. Assert: Due to validation, a value is on the top of the stack.
2. Pop the value (*v128.const* c_3) from the stack.
3. Assert: Due to validation, a value is on the top of the stack.
4. Pop the value (*v128.const* c_2) from the stack.
5. Assert: Due to validation, a value is on the top of the stack.
6. Pop the value (*v128.const* c_1) from the stack.
7. Let c be *vternop*_{v128}(c_1, c_2, c_3).
8. Push the value (*v128.const* c) to the stack.

$$(\text{v128.const } c_1) (\text{v128.const } c_2) (\text{v128.const } c_3) (\text{v128.vternop}) \hookrightarrow (\text{v128.const } c) \\ \text{if } c = \text{vternop}_{\text{v128}}(c_1, c_2, c_3)$$

v128.any_true

1. Assert: Due to validation, a value is on the top of the stack.
2. Pop the value (*v128.const* c_1) from the stack.
3. Let c be *ine*_{v128}($c_1, 0$).
4. Push the value (*i32.const* c) to the stack.

$$(\text{v128.const } c_1) (\text{v128.any_true}) \hookrightarrow (\text{i32.const } c) \quad \text{if } c = \text{ine}_{\text{v128}}(c_1, 0)$$

sh.vunop

1. Assert: Due to validation, a value is on the top of the stack.
2. Pop the value (*v128.const* c_1) from the stack.
3. Let c be *vunop*_{sh}(c_1).
4. Push the value (*v128.const* c) to the stack.

$$(\text{v128.const } c_1) (\text{sh.vunop}) \hookrightarrow (\text{v128.const } c) \quad \text{if } c = \text{vunop}_{\text{sh}}(c_1)$$

sh.vbinop

1. Assert: Due to validation, a value is on the top of the stack.
2. Pop the value (`v128.const` c_2) from the stack.
3. Assert: Due to validation, a value is on the top of the stack.
4. Pop the value (`v128.const` c_1) from the stack.
5. If $|vbinop_{sh}(c_1, c_2)|$ is 1, then:
 - a. Let c be $vbinop_{sh}(c_1, c_2)$.
 - b. Push the value (`v128.const` c) to the stack.
6. If $vbinop_{sh}(c_1, c_2)$ is ϵ , then:
 - a. Trap.

Todo:

- (2) SpecTec currently defines the image of `vbinop` as a sequence, not a set.

$$\begin{array}{ll}
 (\text{v128.const } c_1) (\text{v128.const } c_2) (\text{sh.vbinop}) \hookrightarrow (\text{v128.const } c) & \text{if } vbinop_{sh}(c_1, c_2) = c \\
 (\text{v128.const } c_1) (\text{v128.const } c_2) (\text{sh.vbinop}) \hookrightarrow \text{trap} & \text{if } vbinop_{sh}(c_1, c_2) = \epsilon
 \end{array}$$

iNxN.all_true

1. Assert: Due to validation, a value is on the top of the stack.
2. Pop the value (`v128.const` c) from the stack.
3. Let ci_1^* be $\text{lanes}_{iNxN}(c)$.
4. If for all $(ci_1)^*$, ci_1 is not 0, then:
 - a. Push the value (`i32.const` 1) to the stack.
5. Else:
 - a. Push the value (`i32.const` 0) to the stack.

$$\begin{array}{ll}
 (\text{v128.const } c) (\text{iNxN.all_true}) \hookrightarrow (\text{i32.const } 1) & \text{if } ci_1^* = \text{lanes}_{iNxN}(c) \\
 & \wedge (ci_1 \neq 0)^* \\
 (\text{v128.const } c) (\text{iNxN.all_true}) \hookrightarrow (\text{i32.const } 0) & \text{otherwise}
 \end{array}$$

sh.vrelop

1. Assert: Due to validation, a value is on the top of the stack.
2. Pop the value (`v128.const` c_2) from the stack.
3. Assert: Due to validation, a value is on the top of the stack.
4. Pop the value (`v128.const` c_1) from the stack.
5. Let c be $vrelop_{sh}(c_1, c_2)$.
6. Push the value (`v128.const` c) to the stack.

Todo: Below is the actual prose.

1. Assert: due to [validation](#), two values of [value type](#) `v128` are on the top of the stack.
2. Pop the value `v128.const` c_2 from the stack.

3. Pop the value `v128.const` c_1 from the stack.
4. Let i_1^* be the result of computing $\text{lanes}_{txN}(c_1)$.
5. Let i_2^* be the result of computing $\text{lanes}_{txN}(c_2)$.
6. Let i^* be the result of computing $\text{vrellop}_t(i_1^*, i_2^*)$.
7. Let j^* be the result of computing $\text{extend}_{1,|t|}^5(i^*)$.
8. Let c be the result of computing $\text{lanes}_{txN}^{-1}(j^*)$.
9. Push the value `v128.const` c to the stack.

$$\begin{aligned}
 (\text{v128.const } c_1) (\text{v128.const } c_2) (\text{sh.vrellop}) &\hookrightarrow (\text{v128.const } c) \quad \text{if } \text{vrellop}_{sh}(c_1, c_2) = c \\
 (\text{v128.const } c_1) (\text{v128.const } c_2) \text{txN.vrellop} &\hookrightarrow (\text{v128.const } c) \\
 (\text{if } c = \text{lanes}_{txN}^{-1}(\text{extend}_{1,|t|}^5(\text{vrellop}_t(\text{lanes}_{txN}(c_1), \text{lanes}_{txN}(c_2)))))) &
 \end{aligned}$$

$iN \times N$.vshiftop

1. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
2. Pop the value `(i32.const` n `)` from the stack.
3. Assert: Due to validation, a value is on the top of the stack.
4. Pop the value `(v128.const` c_1 `)` from the stack.
5. Let c'^* be $\text{lanes}_{iN \times N}(c_1)$.
6. Let c be $\text{lanes}_{iN \times N}^{-1}(\text{vshiftop}_{iN \times N}(c', n)^*)$.
7. Push the value `(v128.const` c `)` to the stack.

Todo: Below is the actual prose.

1. Assert: due to `validation`, a value of value type `i32` is on the top of the stack.
2. Pop the value `i32.const` s from the stack.
3. Assert: due to `validation`, a value of value type `v128` is on the top of the stack.
4. Pop the value `v128.const` c_1 from the stack.
5. Let i^* be the result of computing $\text{lanes}_{txN}(c_1)$.
6. Let j^* be the result of computing $\text{vshiftop}_t(i^*, s^N)$.
7. Let c be the result of computing $\text{lanes}_{txN}^{-1}(j^*)$.
8. Push the value `v128.const` c to the stack.

$$\begin{aligned}
 (\text{v128.const } c_1) (\text{i32.const } s) (iN \times N.\text{vshiftop}) &\hookrightarrow (\text{v128.const } c) \quad \text{if } c'^* = \text{lanes}_{iN \times N}(c_1) \\
 &\quad \wedge c = \text{lanes}_{iN \times N}^{-1}(\text{vshiftop}_{iN \times N}(c', n)^*) \\
 (\text{v128.const } c_1) (\text{i32.const } s) \text{txN.vshiftop} &\hookrightarrow (\text{v128.const } c) \\
 (\text{if } i^* = \text{lanes}_{txN}(c_1) & \\
 \wedge c = \text{lanes}_{txN}^{-1}(\text{vshiftop}_t(i^*, s^N))) &
 \end{aligned}$$

$iN \times N$.bitmask

1. Assert: Due to validation, a value is on the top of the stack.
2. Pop the value ($v128.\text{const } c$) from the stack.
3. Let ci_1^* be $\text{lanes}_{iN \times N}(c)$.
4. Let ci be $\text{inverse}_{\text{of_ibits}}(32, \text{ilt}_{|iN|}^s(ci_1, 0)^*)$.
5. Push the value ($i32.\text{const } ci$) to the stack.

Todo: Below is the actual prose.

1. Assert: due to [validation](#), a value of [value type v128](#) is on the top of the stack.
2. Pop the value $v128.\text{const } c$ from the stack.
3. Let i_1^N be the result of computing $\text{lanes}_{t \times N}(c)$.
4. Let B be the [bit width](#) $|t|$ of [value type](#) t .
5. Let i_2^N be the result of computing $\text{ilt_s}_B(i_1^N, 0^N)$.
6. Let j^* be the concatenation of the two sequences i_2^N and 0^{32-N} .
7. Let i be the result of computing $\text{ibits}_{32}^{-1}(j^*)$.
8. Push the value $i32.\text{const } i$ onto the stack.

$$\begin{aligned}
 (v128.\text{const } c) (iN \times N.\text{bitmask}) &\hookrightarrow (i32.\text{const } ci) \quad \text{if } ci_1^* = \text{lanes}_{iN \times N}(c) \\
 &\quad \wedge \text{bits}_{32}(ci) = \text{ilt}_{|iN|}^s(ci_1, 0)^* \\
 (v128.\text{const } c) t \times N.\text{bitmask} &\hookrightarrow (i32.\text{const } i) \quad (\text{if } i = \text{ibits}_{32}^{-1}(\text{ilt_s}_{|t|}(\text{lanes}_{t \times N}(c), 0^N)))
 \end{aligned}$$

 $iN \times N$.swizzle

1. Assert: Due to validation, a value is on the top of the stack.
2. Pop the value ($v128.\text{const } c_2$) from the stack.
3. Assert: Due to validation, a value is on the top of the stack.
4. Pop the value ($v128.\text{const } c_1$) from the stack.
5. Let c^* be $\text{lanes}_{iN \times N}(c_1) 0^{256-N}$.
6. Let ci^* be $\text{lanes}_{iN \times N}(c_2)$.
7. Assert: Due to validation, for all $(k)^{k < N}$, $ci^*[k]$ is less than $|c^*|$.
8. Assert: Due to validation, for all $(k)^{k < N}$, k is less than $|ci^*|$.
9. Let c' be $\text{lanes}_{iN \times N}^{-1}(c^*[ci^*[k]]^{k < N})$.
10. Push the value ($v128.\text{const } c'$) to the stack.

Todo: Below is the actual prose.

1. Assert: due to [validation](#), two values of [value type v128](#) are on the top of the stack.
2. Pop the value $v128.\text{const } c_2$ from the stack.
3. Let i^* be the result of computing $\text{lanes}_{i8 \times 16}(c_2)$.
4. Pop the value $v128.\text{const } c_1$ from the stack.
5. Let j^* be the result of computing $\text{lanes}_{i8 \times 16}(c_1)$.

6. Let c^* be the concatenation of the two sequences j^* and 0^{240} .

7. Let c' be the result of computing $\text{lanes}_{i8 \times 16}^{-1}(c^*[i^*[0]] \dots c^*[i^*[15]])$.

8. Push the value `v128.const c'` onto the stack.

$$\begin{aligned}
 (\text{v128.const } c_1) (\text{v128.const } c_2) (iN \times N.\text{swizzle}) &\hookrightarrow (\text{v128.const } c') && \begin{aligned} &\text{if } ci^* = \text{lanes}_{iN \times N}(c_2) \\ &\wedge c^* = \text{lanes}_{iN \times N}(c_1) 0^{256-N} \\ &\wedge c' = \text{lanes}_{iN \times N}^{-1}(c^*[ci^*[k]]^{k < N}) \end{aligned} \\
 (\text{v128.const } c_1) (\text{v128.const } c_2) i8 \times 16.\text{swizzle} &\hookrightarrow (\text{v128.const } c') && \begin{aligned} &(\text{if } i^* = \text{lanes}_{i8 \times 16}(c_2) \\ &\wedge c^* = \text{lanes}_{i8 \times 16}(c_1) 0^{240} \\ &\wedge c' = \text{lanes}_{i8 \times 16}^{-1}(c^*[i^*[0]] \dots c^*[i^*[15]])) \end{aligned}
 \end{aligned}$$

`iN x N.shuffle i*`

1. Assert: Due to validation, a value is on the top of the stack.
2. Pop the value `(v128.const c2)` from the stack.
3. Assert: Due to validation, a value is on the top of the stack.
4. Pop the value `(v128.const c1)` from the stack.
5. Assert: Due to validation, for all $(k)^{k < N}$, k is less than $|i^*|$.
6. Let c'^* be $\text{lanes}_{iN \times N}(c_1) \text{lanes}_{iN \times N}(c_2)$.
7. Assert: Due to validation, for all $(k)^{k < N}$, $i^*[k]$ is less than $|c'^*|$.
8. Let c be $\text{lanes}_{iN \times N}^{-1}(c'^*[i^*[k]]^{k < N})$.
9. Push the value `(v128.const c)` to the stack.

Todo: Below is the actual prose.

1. Assert: due to [validation](#), two values of [value type v128](#) are on the top of the stack.
 2. Assert: due to [validation](#), for all x_i in x^* it holds that $x_i < 32$.
 3. Pop the value `v128.const c2` from the stack.
 4. Let i_2^* be the result of computing $\text{lanes}_{i8 \times 16}(c_2)$.
 5. Pop the value `v128.const c1` from the stack.
 6. Let i_1^* be the result of computing $\text{lanes}_{i8 \times 16}(c_1)$.
 7. Let i^* be the concatenation of the two sequences i_1^* and i_2^* .
 8. Let c be the result of computing $\text{lanes}_{i8 \times 16}^{-1}(i^*[x^*[0]] \dots i^*[x^*[15]])$.
 9. Push the value `v128.const c` onto the stack.
- $$\begin{aligned}
 (\text{v128.const } c_1) (\text{v128.const } c_2) (iN \times N.\text{shuffle } i^*) &\hookrightarrow (\text{v128.const } c) && \begin{aligned} &\text{if } c'^* = \text{lanes}_{iN \times N}(c_1) \text{lanes}_{iN \times N}(c_2) \\ &\wedge c = \text{lanes}_{iN \times N}^{-1}(c'^*[i^*[k]]^{k < N}) \end{aligned} \\
 (\text{v128.const } c_1) (\text{v128.const } c_2) (i8 \times 16.\text{shuffle } x^*) &\hookrightarrow (\text{v128.const } c) && \begin{aligned} &(\text{if } i^* = \text{lanes}_{i8 \times 16}(c_1) \text{lanes}_{i8 \times 16}(c_2) \\ &\wedge c = \text{lanes}_{i8 \times 16}^{-1}(i^*[x^*[0]] \dots i^*[x^*[15]])) \end{aligned}
 \end{aligned}$$

$iN \times N$.splat

1. Assert: Due to validation, a value of value type `unpack(iN)` is on the top of the stack.
2. Pop the value $(nt_0.\text{const } c_1)$ from the stack.
3. Let c be $\text{lanes}_{iN \times N}^{-1}(\text{pack}_{iN}(c_1)^N)$.
4. Push the value $(\text{v128}.\text{const } c)$ to the stack.

Todo: Below is the actual prose.

1. Let t be the type `unpack($shape$)`.
2. Assert: due to `validation`, a value of value type t is on the top of the stack.
3. Pop the value $t.\text{const } c_1$ from the stack.
4. Let N be the integer $\text{dim}(shape)$.
5. Let c be the result of computing $\text{lanes}_{shape}^{-1}(c_1^N)$.
6. Push the value `v128.const` c to the stack.

$$\begin{aligned}
 (\text{unpack}(iN).\text{const } c_1) (iN \times N.\text{splat}) &\hookrightarrow (\text{v128}.\text{const } c) \quad \text{if } c = \text{lanes}_{iN \times N}^{-1}(\text{pack}_{iN}(c_1)^N) \\
 (t.\text{const } c_1) shape.\text{splat} &\hookrightarrow (\text{v128}.\text{const } c) \quad (\text{if } t = \text{unpack}(shape) \wedge c = \text{lanes}_{shape}^{-1}(c_1^{\text{dim}(shape)}))
 \end{aligned}$$

 $lanet_{u0} \times N$.extract_lane_ $sx_{u1}^?$ i

1. Assert: Due to validation, a value is on the top of the stack.
2. Pop the value $(\text{v128}.\text{const } c_1)$ from the stack.
3. If $sx_{u1}^?$ is not defined and the type of $lanet_{u0}$ is numtype, then:
 - a. Let nt be $lanet_{u0}$.
 - b. If i is less than $|\text{lanes}_{nt \times N}(c_1)|$, then:
 - 1) Let c_2 be $\text{lanes}_{nt \times N}(c_1)[i]$.
 - 2) Push the value $(nt.\text{const } c_2)$ to the stack.
4. If the type of $lanet_{u0}$ is packtype, then:
 - a. Let pt be $lanet_{u0}$.
 - b. If $sx_{u1}^?$ is defined, then:
 - 1) Let sx be $sx_{u1}^?$.
 - 2) If i is less than $|\text{lanes}_{pt \times N}(c_1)|$, then:
 - a) Let c_2 be $\text{extend}_{|pt|,32}^{sx}(\text{lanes}_{pt \times N}(c_1)[i])$.
 - b) Push the value $(\text{i32}.\text{const } c_2)$ to the stack.

Todo: Below is the actual prose.

1. Assert: due to `validation`, $x < N$.
2. Assert: due to `validation`, a value of value type `v128` is on the top of the stack.
3. Pop the value `v128.const` c_1 from the stack.
4. Let i^* be the result of computing $\text{lanes}_{t_1 \times N}(c_1)$.

5. Let t_2 be the type `unpack($t_1 \times N$)`.
6. Let c_2 be the result of computing `extend $_{t_1, t_2}^{sx}$ ($i^*[x]$)`.
7. Push the value $t_2.\text{const } c_2$ to the stack.

$$\begin{aligned}
 (\text{v128.const } c_1) (nt \times N.\text{extract_lane } i) &\hookrightarrow (nt.\text{const } c_2) && \text{if } c_2 = \text{lanes}_{nt \times N}(c_1)[i] \\
 (\text{v128.const } c_1) (pt \times N.\text{extract_lane_sx } i) &\hookrightarrow (i32.\text{const } c_2) && \text{if } c_2 = \text{extend}_{[pt], 32}^{sx}(\text{lanes}_{pt \times N}(c_1)[i]) \\
 (\text{v128.const } c_1) (t_1 \times N.\text{extract_lane } x) &\hookrightarrow (t_2.\text{const } c_2) \\
 &(\text{if } t_2 = \text{unpack}(t_1 \times N) \\
 &\quad \wedge c_2 = \text{extend}_{t_1, t_2}^{sx}(\text{lanes}_{t_1 \times N}(c_1)[x]))
 \end{aligned}$$

`iN × N.replace_lane i`

1. Assert: Due to validation, a value of value type `unpack(iN)` is on the top of the stack.
2. Pop the value $(nt_0.\text{const } c_2)$ from the stack.
3. Assert: Due to validation, a value is on the top of the stack.
4. Pop the value $(\text{v128.const } c_1)$ from the stack.
5. Let c be $\text{lanes}_{iN \times N}^{-1}(\text{lanes}_{iN \times N}(c_1)[[i] = \text{pack}_{iN}(c_2)])$.
6. Push the value $(\text{v128.const } c)$ to the stack.

Todo: Below is the actual prose.

1. Assert: due to `validation`, $x < \text{dim}(\text{shape})$.
2. Let t_2 be the type `unpack(shape)`.
3. Assert: due to `validation`, a value of value type t_1 is on the top of the stack.
4. Pop the value $t_2.\text{const } c_2$ from the stack.
5. Assert: due to `validation`, a value of value type `v128` is on the top of the stack.
6. Pop the value $\text{v128.const } c_1$ from the stack.
7. Let i^* be the result of computing $\text{lanes}_{\text{shape}}(c_1)$.
8. Let c be the result of computing $\text{lanes}_{\text{shape}}^{-1}(i^* \text{ with } [x] = c_2)$.
9. Push $\text{v128.const } c$ on the stack.

$$\begin{aligned}
 (\text{v128.const } c_1) (\text{unpack}(iN).\text{const } c_2) (iN \times N.\text{replace_lane } i) &\hookrightarrow (\text{v128.const } c) && \text{if } c = \text{lanes}_{iN \times N}^{-1}(\text{lanes}_{iN \times N}(c_1)[[i] = \text{pack}_{iN}(c_2)]) \\
 (\text{v128.const } c_1) (t_2.\text{const } c_2) (\text{shape.replace_lane } x) &\hookrightarrow (\text{v128.const } c) \\
 &(\text{if } i^* = \text{lanes}_{\text{shape}}(c_1) \\
 &\quad \wedge c = \text{lanes}_{\text{shape}}^{-1}(i^* \text{ with } [x] = c_2))
 \end{aligned}$$

`sh1.vextunop_sh2_sx`

1. Assert: Due to validation, a value is on the top of the stack.
2. Pop the value $(\text{v128.const } c_1)$ from the stack.
3. Let c be `vextunop(sh1, sh2, vextunop, sx, c1)`.
4. Push the value $(\text{v128.const } c)$ to the stack.

Todo: Below is the actual prose.

1. Assert: due to **syntax**, $N = M/2$.
2. Assert: due to **validation**, a value of **value type** `v128` is on the top of the stack.
3. Pop the value `v128.const` c_1 from the stack.
4. Let i^* be the result of computing `lanes` _{$t_1 \times M$} (c_1).
5. Let $(j_1 \ j_2)^*$ be the result of computing `extend` ^{sx} _{$|t_1|, |t_2|$} (i^*).
6. Let k^* be the result of computing `iadd` _{$|t_2|$} (j_1, j_2)^{*}.
7. Let c be the result of computing `lanes` _{$t_2 \times N$} ⁻¹(k^*).
8. Push the value `v128.const` c to the stack.

$$\begin{aligned}
 (\text{v128.const } c_1) \ (sh_1.\text{vextunop_sh2_sx}) &\hookrightarrow (\text{v128.const } c) \quad \text{if } \text{vextunop}(sh_1, sh_2, \text{vextunop}, sx, c_1) = c \\
 (\text{v128.const } c_1) \ t_2 \times N.\text{extadd_pairwise_t1} \times M_sx &\hookrightarrow (\text{v128.const } c) \\
 &\quad (\text{if } (i_1 \ i_2)^* = \text{extend}^{sx}_{|t_1|, |t_2|}(\text{lanes}_{t_1 \times M}(c_1)) \\
 &\quad \wedge j^* = \text{iadd}_{|t_2|}(i_1, i_2)^* \\
 &\quad \wedge c = \text{lanes}_{t_2 \times N}^{-1}(j^*))
 \end{aligned}$$

sh1.vextbinop_sh2_sx

1. Assert: Due to **validation**, a value is on the top of the stack.
2. Pop the value (`v128.const` c_2) from the stack.
3. Assert: Due to **validation**, a value is on the top of the stack.
4. Pop the value (`v128.const` c_1) from the stack.
5. Let c be `vextbinop`($sh_1, sh_2, \text{vextbinop}, sx, c_1, c_2$).
6. Push the value (`v128.const` c) to the stack.

Todo: Below is the actual prose.

1. Assert: due to **syntax**, $N = M/2$.
2. Assert: due to **validation**, two values of **value type** `v128` are on the top of the stack.
3. Pop the value `v128.const` c_2 from the stack.
4. Pop the value `v128.const` c_1 from the stack.
5. Let i_1^* be the result of computing `lanes` _{$t_1 \times M$} (c_1).
6. Let i_2^* be the result of computing `lanes` _{$t_1 \times M$} (c_2).
7. If **half** is low, then:
 - a. Let j_1^* be the sequence $i_1^*[0 : N]$.
 - b. Let j_2^* be the sequence $i_2^*[0 : N]$.
8. Else:
 - a. Let j_1^* be the sequence $i_1^*[N : N]$.
 - b. Let j_2^* be the sequence $i_2^*[N : N]$.
9. Let k_1^* be the result of computing `extend` ^{sx} _{$|t_1|, |t_2|$} (j_1^*).
10. Let k_2^* be the result of computing `extend` ^{sx} _{$|t_1|, |t_2|$} (j_2^*).
11. Let k^* be the result of computing `imul` _{$|t_2|$} (k_1^*, k_2^*).
12. Let c be the result of computing `lanes` _{$t_2 \times N$} ⁻¹(k^*).

13. Push the value `v128.const c` onto the stack.

$$\begin{aligned}
 (\text{v128.const } c_1) (\text{v128.const } c_2) (sh_1.\text{vextbinop_sh2_sx}) &\hookrightarrow (\text{v128.const } c) \quad \text{if } \text{vextbinop}(sh_1, sh_2, \text{vextbinop}, sx, c_1, c_2) = c \\
 (\text{v128.const } c_1) (\text{v128.const } c_2) t_2 \times N.\text{extmul_half_t}_1 \times M_sx &\hookrightarrow (\text{v128.const } c) \\
 &\quad (\text{if } i^* = \text{lanes}_{t_1 \times M}(c_1)[\text{half}(0, N) : N] \\
 &\quad \wedge j^* = \text{lanes}_{t_1 \times M}(c_2)[\text{half}(0, N) : N] \\
 &\quad \wedge c = \text{lanes}_{t_2 \times N}^{-1}(\text{imul}_{|t_2|}(\text{extend}_{|t_1|, |t_2|}^{sx}(i^*), \text{extend}_{|t_1|, |t_2|}^{sx}(j^*))))
 \end{aligned}$$

where:

$$\begin{aligned}
 \text{low}(x, y) &= x \\
 \text{high}(x, y) &= y
 \end{aligned}$$

`i32x4.dot_i16x8_s`

Todo: (*) Prose not spliced, for this seems to be WIP on @Andreas.

1. Assert: due to [validation](#), two values of [value type v128](#) are on the top of the stack.
2. Pop the value `v128.const c2` from the stack.
3. Pop the value `v128.const c1` from the stack.
4. Let i_1^* be the result of computing `lanesi16x8(c1)`.
5. Let j_1^* be the result of computing `extends16,32(i1*)`.
6. Let i_2^* be the result of computing `lanesi16x8(c2)`.
7. Let j_2^* be the result of computing `extends16,32(i2*)`.
8. Let $(k_1 \ k_2)^*$ be the result of computing `imul32(j1*, j2*)`.
9. Let k^* be the result of computing `iadd32(k1, k2)*`.
10. Let c be the result of computing `lanesi32x4-1(k*)`.
11. Push the value `v128.const c` onto the stack.

$$\begin{aligned}
 (\text{v128.const } c_1) (\text{v128.const } c_2) \text{i32x4.dot_i16x8_s} &\hookrightarrow (\text{v128.const } c) \\
 &\quad (\text{if } (i_1 \ i_2)^* = \text{imul}_{32}(\text{extend}_{16,32}^s(\text{lanes}_{i16x8}(c_1)), \text{extend}_{16,32}^s(\text{lanes}_{i16x8}(c_2))) \\
 &\quad \wedge j^* = \text{iadd}_{32}(i_1, i_2)^* \\
 &\quad \wedge c = \text{lanes}_{i32x4}^{-1}(j^*))
 \end{aligned}$$

`iN2×N2.narrow_iN1×N1_sx`

1. Assert: Due to validation, a value is on the top of the stack.
2. Pop the value `(v128.const c2)` from the stack.
3. Assert: Due to validation, a value is on the top of the stack.
4. Pop the value `(v128.const c1)` from the stack.
5. Let ci_1^* be `lanesiN1×N1(c1)`.
6. Let ci_2^* be `lanesiN1×N1(c2)`.
7. Let cj_1^* be `narrow|iN1|, |iN2|sx ci1*`.
8. Let cj_2^* be `narrow|iN1|, |iN2|sx ci2*`.
9. Let c be `lanesiN2×N2-1(cj1* cj2*)`.
10. Push the value `(v128.const c)` to the stack.

Todo: Below is the actual prose.

1. Assert: due to **syntax**, $N = 2 \cdot M$.
 2. Assert: due to **validation**, two values of **value type** **v128** are on the top of the stack.
 3. Pop the value **v128.const** c_2 from the stack.
 4. Let i_2^M be the result of computing $\text{lanes}_{t_1 \times M}(c_2)$.
 5. Let d_2^M be the result of computing $\text{narrow}_{|t_1|, |t_2|}^{sx}(i_2^M)$.
 6. Pop the value **v128.const** c_1 from the stack.
 7. Let i_1^M be the result of computing $\text{lanes}_{t_1 \times M}(c_1)$.
 8. Let d_1^M be the result of computing $\text{narrow}_{|t_1|, |t_2|}^{sx}(i_1^M)$.
 9. Let j^N be the concatenation of the two sequences d_1^M and d_2^M .
 10. Let c be the result of computing $\text{lanes}_{t_2 \times N}^{-1}(j^N)$.
 11. Push the value **v128.const** c onto the stack.
- $$(\text{v128.const } c_1) (\text{v128.const } c_2) (\text{iN}_2 \times \text{N}_2. \text{narrow_iN}_1 \times \text{N}_1 \text{_sx}) \hookrightarrow (\text{v128.const } c) \quad \begin{array}{l} \text{if } ci_1^* = \text{lanes}_{iN_1 \times N_1}(c_1) \\ \wedge ci_2^* = \text{lanes}_{iN_1 \times N_1}(c_2) \\ \wedge cj_1^* = \text{narrow}_{|iN_1|, |iN_2|}^{sx} ci_1^* \\ \wedge cj_2^* = \text{narrow}_{|iN_1|, |iN_2|}^{sx} ci_2^* \\ \wedge c = \text{lanes}_{iN_2 \times N_2}^{-1}(cj_1^* cj_2^*) \end{array}$$
- $$(\text{v128.const } c_1) (\text{v128.const } c_2) t_2 \times N. \text{narrow_t}_1 \times M \text{_sx} \hookrightarrow (\text{v128.const } c) \quad \begin{array}{l} (\text{if } d_1^M = \text{narrow}_{|t_1|, |t_2|}^{sx}(\text{lanes}_{t_1 \times M}(c_1)) \\ \wedge d_2^M = \text{narrow}_{|t_1|, |t_2|}^{sx}(\text{lanes}_{t_1 \times M}(c_2)) \\ \wedge c = \text{lanes}_{t_2 \times N}^{-1}(d_1^M d_2^M)) \end{array}$$

$t_2 \times N. \text{vcvtop_t}_1 \times M \text{_sx}$

Todo: (*) Prose not spliced, for it has merged multiple rules for vcvtop into one algorithm.

1. Assert: due to **syntax**, $N = M$.
 2. Assert: due to **validation**, a value of **value type** **v128** is on the top of the stack.
 3. Pop the value **v128.const** c_1 from the stack.
 4. Let i^* be the result of computing $\text{lanes}_{t_1 \times M}(c_1)$.
 5. Let j^* be the result of computing $\text{vcvtop}_{|t_1|, |t_2|}^{sx}(i^*)$.
 6. Let c be the result of computing $\text{lanes}_{t_2 \times N}^{-1}(j^*)$.
 7. Push the value **v128.const** c onto the stack.
- $$(\text{v128.const } c_1) (\text{iN}_2 \times \text{N}_2. \text{vcvtop_iN}_1 \times \text{N}_1 \text{_sx}?) \hookrightarrow (\text{v128.const } c) \quad \begin{array}{l} \text{if } c'^* = \text{lanes}_{iN_1 \times N_1}(c_1) \\ \wedge c = \text{lanes}_{iN_2 \times N_2}^{-1}(\text{vcvtop}(\text{iN}_1 \times \text{N}_1, \text{iN}_2 \times \text{N}_2, \text{vcvtop}, \text{sx})) \end{array}$$
- $$(\text{v128.const } c_1) t_2 \times N. \text{vcvtop_t}_1 \times M \text{_sx} \hookrightarrow (\text{v128.const } c) \quad \begin{array}{l} (\text{if } c = \text{lanes}_{t_2 \times N}^{-1}(\text{vcvtop}_{|t_1|, |t_2|}^{sx}(\text{lanes}_{t_1 \times M}(c_1)))) \end{array}$$

$t_2 \times N.vcvt_{top_half_t_1 \times M_sx}^?$

Todo: (*) Prose not spliced, for it has merged multiple rules for vcvt_{top} into one algorithm.

1. Assert: due to **syntax**, $N = M/2$.
2. Assert: due to **validation**, a value of **value type** **v128** is on the top of the stack.
3. Pop the value **v128.const** c_1 from the stack.
4. Let i^* be the result of computing $\text{lanes}_{t_1 \times M}(c_1)$.
5. If **half** is low, then:
 - a. Let j^* be the sequence $i^*[0 : N]$.
6. Else:
 - a. Let j^* be the sequence $i^*[N : N]$.
7. Let k^* be the result of computing $\text{vcvt}_{|t_1|, |t_2|}^{sx?}(j^*)$.
8. Let c be the result of computing $\text{lanes}_{t_2 \times N}^{-1}(k^*)$.
9. Push the value **v128.const** c onto the stack.

$$\begin{aligned}
 (\text{v128.const } c_1) (\text{iN}_{2 \times N_2}.vcvt_{top_sx}^? \text{iN}_{1 \times N_1} \text{half}) &\hookrightarrow (\text{v128.const } c) \quad \text{if } ci^* = \text{lanes}_{iN_1 \times N_1}(c_1)[\text{half}(\text{half}, 0, N_2) : N_2] \\
 &\quad \wedge c = \text{lanes}_{iN_2 \times N_2}^{-1}(\text{vcvt}(\text{iN}_{1 \times N_1}, \text{iN}_{2 \times N_2}, \text{vcvt}_{top_half_t_1 \times M_sx}^? \\
 &\quad (\text{v128.const } c_1) t_2 \times N.vcvt_{top_half_t_1 \times M_sx}^? \hookrightarrow (\text{v128.const } c) \\
 &\quad (\text{if } c = \text{lanes}_{t_2 \times N}^{-1}(\text{vcvt}_{|t_1|, |t_2|}^{sx?}(\text{lanes}_{t_1 \times M}(c_1)[\text{half}(0, N) : N])))
 \end{aligned}$$

where:

$$\begin{aligned}
 \text{low}(x, y) &= x \\
 \text{high}(x, y) &= y
 \end{aligned}$$

 $t_2 \times N.vcvt_{top_t_1 \times M_sx}^? \text{zero}$

Todo: (*) Prose not spliced, for it has merged multiple rules for vcvt_{top} into one algorithm.

1. Assert: due to **syntax**, $N = 2 \cdot M$.
2. Assert: due to **validation**, a value of **value type** **v128** is on the top of the stack.
3. Pop the value **v128.const** c_1 from the stack.
4. Let i^* be the result of computing $\text{lanes}_{t_1 \times M}(c_1)$.
5. Let j^* be the result of computing $\text{vcvt}_{|t_1|, |t_2|}^{sx?}(i^*)$.
6. Let k^* be the concatenation of the two sequences j^* and 0^M .
7. Let c be the result of computing $\text{lanes}_{t_2 \times N}^{-1}(k^*)$.
8. Push the value **v128.const** c onto the stack.

$$\begin{aligned}
 (\text{v128.const } c_1) (nt_2 \times N_2.vcvt_{top_zero_nt_1 \times N_1_sx}^?) &\hookrightarrow (\text{v128.const } c) \quad \text{if } ci^* = \text{lanes}_{nt_1 \times N_1}(c_1) \\
 &\quad \wedge c = \text{lanes}_{nt_2 \times N_2}^{-1}(\text{vcvt}(nt_1 \times N_1, nt_2 \times N_2, \text{vcvt}_{top_t_1 \times M_sx}^? \\
 &\quad (\text{v128.const } c_1) t_2 \times N.vcvt_{top_t_1 \times M_sx}^? \text{zero} \hookrightarrow (\text{v128.const } c) \\
 &\quad (\text{if } c = \text{lanes}_{t_2 \times N}^{-1}(\text{vcvt}_{|t_1|, |t_2|}^{sx?}(\text{lanes}_{t_1 \times M}(c_1)) 0^M))
 \end{aligned}$$

4.6.5 Variable Instructions

`local.get x`

1. Let z be the current state.
2. Assert: Due to validation, $z.\text{locals}[x]$ is defined.
3. Let val be $z.\text{locals}[x]$.
4. Push the value val to the stack.

$$z; (\text{local.get } x) \hookrightarrow val \quad \text{if } z.\text{locals}[x] = val$$

`local.set x`

1. Let z be the current state.
2. Assert: Due to validation, a value is on the top of the stack.
3. Pop the value val from the stack.
4. Perform $z[\text{locals}[x] = val]$.

$$z; val (\text{local.set } x) \hookrightarrow z[\text{locals}[x] = val]; \epsilon$$

`local.tee x`

1. Assert: Due to validation, a value is on the top of the stack.
2. Pop the value val from the stack.
3. Push the value val to the stack.
4. Push the value val to the stack.
5. Execute the instruction `(local.set x)`.

$$val (\text{local.tee } x) \hookrightarrow val \quad val (\text{local.set } x)$$

`global.get x`

1. Let z be the current state.
2. Let val be $z.\text{globals}[x].\text{value}$.
3. Push the value val to the stack.

$$z; (\text{global.get } x) \hookrightarrow val \quad \text{if } z.\text{globals}[x].\text{value} = val$$

`global.set x`

1. Let z be the current state.
2. Assert: Due to validation, a value is on the top of the stack.
3. Pop the value val from the stack.
4. Perform $z[\text{globals}[x].\text{value} = val]$.

$$z; val (\text{global.set } x) \hookrightarrow z[\text{globals}[x].\text{value} = val]; \epsilon$$

4.6.6 Table Instructions

`table.get x`

1. Let z be the current state.
2. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
3. Pop the value (`i32.const i`) from the stack.
4. If i is greater than or equal to $|z.tables[x].elem|$, then:
 - a. Trap.
5. Push the value $z.tables[x].elem[i]$ to the stack.

$$\begin{array}{ll} z; (i32.const\ i)\ (table.get\ x) & \hookrightarrow \text{trap} & \text{if } i \geq |z.tables[x].elem| \\ z; (i32.const\ i)\ (table.get\ x) & \hookrightarrow z.tables[x].elem[i] & \text{if } i < |z.tables[x].elem| \end{array}$$

`table.set x`

1. Let z be the current state.
2. Assert: Due to validation, a value is on the top of the stack.
3. Pop the value `ref` from the stack.
4. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
5. Pop the value (`i32.const i`) from the stack.
6. If i is greater than or equal to $|z.tables[x].elem|$, then:
 - a. Trap.
7. Perform $z.tables[x].elem[i] = ref$.

$$\begin{array}{ll} z; (i32.const\ i)\ ref\ (table.set\ x) & \hookrightarrow z; \text{trap} & \text{if } i \geq |z.tables[x].elem| \\ z; (i32.const\ i)\ ref\ (table.set\ x) & \hookrightarrow z.tables[x].elem[i] = ref; \epsilon & \text{if } i < |z.tables[x].elem| \end{array}$$

`table.size x`

1. Let z be the current state.
2. Let n be $|z.tables[x].elem|$.
3. Push the value (`i32.const n`) to the stack.

$$z; (table.size\ x) \hookrightarrow (i32.const\ n) \quad \text{if } |z.tables[x].elem| = n$$

`table.grow x`

1. Let z be the current state.
2. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
3. Pop the value (`i32.const n`) from the stack.
4. Assert: Due to validation, a value is on the top of the stack.
5. Pop the value `ref` from the stack.
6. Either:
 - a. Let ti be `growtable($z.tables[x]$, n , ref)`.
 - b. Push the value (`i32.const $|z.tables[x].elem|$`) to the stack.

c. Perform $z[\text{tables}[x] = ti]$.

7. Or:

a. Push the value $(i32.\text{const signed}_{32}^{-1}(-1))$ to the stack.

Todo:

(6) Maybe we want to be more precise than just saying “Either” in the prose, elaborating that it may succeed or fail non-deterministically.

$$\begin{aligned} z; \text{ref } (i32.\text{const } n) (\text{table.grow } x) &\hookrightarrow z[\text{tables}[x] = ti]; (i32.\text{const } |z.\text{tables}[x].\text{elem}|) \\ &\quad \text{if } ti = \text{growtable}(z.\text{tables}[x], n, \text{ref}) \\ z; \text{ref } (i32.\text{const } n) (\text{table.grow } x) &\hookrightarrow z; (i32.\text{const signed}_{32}^{-1}(-1)) \end{aligned}$$

Note: The `table.grow` instruction is non-deterministic. It may either succeed, returning the old table size sz , or fail, returning -1 . Failure *must* occur if the referenced table instance has a maximum size defined that would be exceeded. However, failure *can* occur in other cases as well. In practice, the choice depends on the `resources` available to the `embedder`.

`table.fill x`

1. Let z be the current state.
2. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
3. Pop the value $(i32.\text{const } n)$ from the stack.
4. Assert: Due to validation, a value is on the top of the stack.
5. Pop the value val from the stack.
6. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
7. Pop the value $(i32.\text{const } i)$ from the stack.
8. If $i + n$ is greater than $|z.\text{tables}[x].\text{elem}|$, then:
 - a. Trap.
9. If n is 0, then:
 - a. Do nothing.
10. Else:
 - a. Push the value $(i32.\text{const } i)$ to the stack.
 - b. Push the value val to the stack.
 - c. Execute the instruction `(table.set x)`.
 - d. Push the value $(i32.\text{const } i + 1)$ to the stack.
 - e. Push the value val to the stack.
 - f. Push the value $(i32.\text{const } n - 1)$ to the stack.
 - g. Execute the instruction `(table.fill x)`.

$$\begin{aligned} z; (i32.\text{const } i) \text{ val } (i32.\text{const } n) (\text{table.fill } x) &\hookrightarrow \text{trap} && \text{if } i + n > |z.\text{tables}[x].\text{elem}| \\ z; (i32.\text{const } i) \text{ val } (i32.\text{const } n) (\text{table.fill } x) &\hookrightarrow \epsilon && \text{otherwise, if } n = 0 \\ z; (i32.\text{const } i) \text{ val } (i32.\text{const } n) (\text{table.fill } x) &\hookrightarrow && \\ &\quad (i32.\text{const } i) \text{ val } (\text{table.set } x) && \text{otherwise} \\ &\quad (i32.\text{const } i + 1) \text{ val } (i32.\text{const } n - 1) (\text{table.fill } x) \end{aligned}$$

`table.copy x y`

1. Let z be the current state.
 2. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
 3. Pop the value $(i32.const\ n)$ from the stack.
 4. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
 5. Pop the value $(i32.const\ i)$ from the stack.
 6. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
 7. Pop the value $(i32.const\ j)$ from the stack.
 8. If $i + n$ is greater than $|z.tables[y].elem|$, then:
 - a. Trap.
 9. If $j + n$ is greater than $|z.tables[x].elem|$, then:
 - a. Trap.
 10. If n is 0, then:
 - a. Do nothing.
 11. Else:
 - a. If j is less than or equal to i , then:
 - 1) Push the value $(i32.const\ j)$ to the stack.
 - 2) Push the value $(i32.const\ i)$ to the stack.
 - 3) Execute the instruction $(table.get\ y)$.
 - 4) Execute the instruction $(table.set\ x)$.
 - 5) Push the value $(i32.const\ j + 1)$ to the stack.
 - 6) Push the value $(i32.const\ i + 1)$ to the stack.
 - b. Else:
 - 1) Push the value $(i32.const\ j + n - 1)$ to the stack.
 - 2) Push the value $(i32.const\ i + n - 1)$ to the stack.
 - 3) Execute the instruction $(table.get\ y)$.
 - 4) Execute the instruction $(table.set\ x)$.
 - 5) Push the value $(i32.const\ j)$ to the stack.
 - 6) Push the value $(i32.const\ i)$ to the stack.
 - c. Push the value $(i32.const\ n - 1)$ to the stack.
 - d. Execute the instruction $(table.copy\ x\ y)$.
- $z; (i32.const\ j)\ (i32.const\ i)\ (i32.const\ n)\ (table.copy\ x\ y) \hookrightarrow \text{trap}$
 if $i + n > |z.tables[y].elem| \vee j + n > |z.tables[x].elem|$
 $z; (i32.const\ j)\ (i32.const\ i)\ (i32.const\ n)\ (table.copy\ x\ y) \hookrightarrow \epsilon$ otherwise, if $n = 0$
 $z; (i32.const\ j)\ (i32.const\ i)\ (i32.const\ n)\ (table.copy\ x\ y) \hookrightarrow$
 $(i32.const\ j)\ (i32.const\ i)\ (table.get\ y)\ (table.set\ x)$ otherwise, if $j \leq i$
 $(i32.const\ j + 1)\ (i32.const\ i + 1)\ (i32.const\ n - 1)\ (table.copy\ x\ y)$
 $z; (i32.const\ j)\ (i32.const\ i)\ (i32.const\ n)\ (table.copy\ x\ y) \hookrightarrow$
 $(i32.const\ j + n - 1)\ (i32.const\ i + n - 1)\ (table.get\ y)\ (table.set\ x)$ otherwise
 $(i32.const\ j)\ (i32.const\ i)\ (i32.const\ n - 1)\ (table.copy\ x\ y)$

`table.init x y`

1. Let z be the current state.
2. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
3. Pop the value $(i32.const\ n)$ from the stack.
4. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
5. Pop the value $(i32.const\ i)$ from the stack.
6. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
7. Pop the value $(i32.const\ j)$ from the stack.
8. If $i + n$ is greater than $|z.elems[y].elem|$, then:
 - a. Trap.
9. If $j + n$ is greater than $|z.tables[x].elem|$, then:
 - a. Trap.
10. If n is 0, then:
 - a. Do nothing.
11. Else if i is less than $|z.elems[y].elem|$, then:
 - a. Push the value $(i32.const\ j)$ to the stack.
 - b. Push the value $z.elems[y].elem[i]$ to the stack.
 - c. Execute the instruction $(table.set\ x)$.
 - d. Push the value $(i32.const\ j + 1)$ to the stack.
 - e. Push the value $(i32.const\ i + 1)$ to the stack.
 - f. Push the value $(i32.const\ n - 1)$ to the stack.
 - g. Execute the instruction $(table.init\ x\ y)$.

$$z; (i32.const\ j) (i32.const\ i) (i32.const\ n) (table.init\ x\ y) \hookrightarrow \text{trap}$$

$$\text{if } i + n > |z.elems[y].elem| \vee j + n > |z.tables[x].elem|$$

$$z; (i32.const\ j) (i32.const\ i) (i32.const\ n) (table.init\ x\ y) \hookrightarrow \epsilon$$

otherwise, if $n = 0$

$$z; (i32.const\ j) (i32.const\ i) (i32.const\ n) (table.init\ x\ y) \hookrightarrow$$

$$(i32.const\ j) z.elems[y].elem[i] (table.set\ x)$$

otherwise

$$(i32.const\ j + 1) (i32.const\ i + 1) (i32.const\ n - 1) (table.init\ x\ y)$$

`elem.drop x`

1. Let z be the current state.
2. Perform $z[elems[x].elem] = \epsilon$.

$$z; (elem.drop\ x) \hookrightarrow z[elems[x].elem] = \epsilon; \epsilon$$

4.6.7 Memory Instructions

Note: The alignment `memory.align` in load and store instructions does not affect the semantics. It is an indication that the offset `ea` at which the memory is accessed is intended to satisfy the property $ea \bmod 2^{\text{memory.align}} = 0$. A WebAssembly implementation can use this hint to optimize for the intended use. Unaligned access violating that property is still allowed and must succeed regardless of the annotation. However, it may be substantially slower on some hardware.

numty_{u0}.loadload_{u2}? x ao

1. Let z be the current state.
2. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
3. Pop the value (`i32.const i`) from the stack.
4. If *load_{u2}?* is not defined, then:
 - a. Let nt be *numty_{u0}*.
 - b. If $i + ao.offset + |nt|/8$ is greater than $|z.mems[x].bytes|$, then:
 - 1) Trap.
 - c. Let c be $\text{inverse}_{of_nbytes}(nt, z.mems[x].bytes[i + ao.offset : |nt|/8])$.
 - d. Push the value (`nt.const c`) to the stack.
5. If the type of *numty_{u0}* is `Inn`, then:
 - a. If *load_{u2}?* is defined, then:
 - 1) Let y_0 be *load_{u2}?*.
 - 2) Let (n, sx) be y_0 .
 - 3) If $i + ao.offset + n/8$ is greater than $|z.mems[x].bytes|$, then:
 - a) Trap.
 - b. Let iN be *numty_{u0}*.
 - c. If *load_{u2}?* is defined, then:
 - 1) Let y_0 be *load_{u2}?*.
 - 2) Let (n, sx) be y_0 .
 - 3) Let c be $\text{inverse}_{of_ibytes}(n, z.mems[x].bytes[i + ao.offset : n/8])$.
 - 4) Push the value (`iN.const extendn, |iN|sx(c)`) to the stack.

Todo: Below is the actual prose. (7) Render `$inverse_of_nbytes` with display hint.

1. Let F be the `current frame`.
2. Assert: due to `validation`, $F.module.mems[x]$ exists.
3. Let a be the `memory address` $F.module.mems[x]$.
4. Assert: due to `validation`, $S.mems[a]$ exists.
5. Let mem be the `memory instance` $S.mems[a]$.
6. Assert: due to `validation`, a value of `value type i32` is on the top of the stack.
7. Pop the value `i32.const i` from the stack.

8. Let ea be the integer $i + memarg.offset$.
9. If N is not part of the instruction, then:
 - a. Let N be the bit width $|t|$ of number type t .
10. If $ea + N/8$ is larger than the length of $mem.bytes$, then:
 - a. Trap.
11. Let b^* be the byte sequence $mem.bytes[ea : N/8]$.
12. If N and sx are part of the instruction, then:
 - a. Let n be the integer for which $bytes_{iN}(n) = b^*$.
 - b. Let c be the result of computing $extend_{N,|t|}^{sx}(n)$.
13. Else:
 - a. Let c be the constant for which $bytes_t(c) = b^*$.
14. Push the value $t.const\ c$ to the stack.

$$\begin{aligned}
 z; (i32.const\ i)\ (nt.load\ x\ ao) &\hookrightarrow \text{trap} \\
 &\quad \text{if } i + ao.offset + |nt|/8 > |z.mems[x].bytes| \\
 z; (i32.const\ i)\ (nt.load\ x\ ao) &\hookrightarrow (nt.const\ c) \\
 &\quad \text{if } bytes_{nt}(c) = z.mems[x].bytes[i + ao.offset : |nt|/8] \\
 z; (i32.const\ i)\ (iN.loadn\ sx\ x\ ao) &\hookrightarrow \text{trap} \\
 &\quad \text{if } i + ao.offset + n/8 > |z.mems[x].bytes| \\
 z; (i32.const\ i)\ (iN.loadn\ sx\ x\ ao) &\hookrightarrow (iN.const\ extend_{n,|iN|}^{sx}(c)) \\
 &\quad \text{if } bytes_{in}(c) = z.mems[x].bytes[i + ao.offset : n/8]
 \end{aligned}$$

$v128.loadM \times N_sx\ x\ memarg$

Todo: (*) Rule and prose both not spliced.

1. Let F be the current frame.
2. Assert: due to validation, $F.module.mems[x]$ exists.
3. Let a be the memory address $F.module.mems[x]$.
4. Assert: due to validation, $S.mems[a]$ exists.
5. Let mem be the memory instance $S.mems[a]$.
6. Assert: due to validation, a value of value type $i32$ is on the top of the stack.
7. Pop the value $i32.const\ i$ from the stack.
8. Let ea be the integer $i + memarg.offset$.
9. If $ea + M \cdot N/8$ is larger than the length of $mem.bytes$, then:
 - a. Trap.
10. Let b^* be the byte sequence $mem.bytes[ea : M \cdot N/8]$.
11. Let m_k be the integer for which $bytes_{iM}(m_k) = b^*[k \cdot M/8 : M/8]$.
12. Let W be the integer $M \cdot 2$.
13. Let n_k be the result of computing $extend_{M,W}^{sx}(m_k)$.
14. Let c be the result of computing $lanes_{iW \times N}^{-1}(n_0 \dots n_{N-1})$.
15. Push the value $v128.const\ c$ to the stack.

$$\begin{aligned}
& S; F; (i32.\text{const } i) \text{ (v128.loadMxN_sx } x \text{ memarg)} \hookrightarrow S; F; (\text{v128.const } c) \\
& \quad (\text{if } ea = i + \text{memarg.offset} \\
& \quad \quad \wedge ea + M \cdot N/8 \leq |S.\text{mems}[F.\text{module.mems}[x]].\text{bytes}| \\
& \quad \quad \wedge \text{bytes}_{iM}(m_k) = S.\text{mems}[F.\text{module.mems}[x]].\text{bytes}[ea + k \cdot M/8 : M/8]) \\
& \quad \quad \wedge W = M \cdot 2 \\
& \quad \quad \wedge c = \text{lanes}_{iW \times N}^{-1}(\text{extend}_{M,W}^{sx}(m_0) \dots \text{extend}_{M,W}^{sx}(m_{N-1}))) \\
& S; F; (i32.\text{const } i) \text{ (v128.loadMxN_sx } x \text{ memarg)} \hookrightarrow S; F; \text{trap} \\
& \quad (\text{otherwise})
\end{aligned}$$

v128.loadN_splat x memarg

Todo: (*) Rule and prose both not spliced.

1. Let F be the [current frame](#).
2. Assert: due to [validation](#), $F.\text{module.mems}[x]$ exists.
3. Let a be the [memory address](#) $F.\text{module.mems}[x]$.
4. Assert: due to [validation](#), $S.\text{mems}[a]$ exists.
5. Let mem be the [memory instance](#) $S.\text{mems}[a]$.
6. Assert: due to [validation](#), a value of [value type](#) `i32` is on the top of the stack.
7. Pop the value `i32.const` i from the stack.
8. Let ea be the integer $i + \text{memarg.offset}$.
9. If $ea + N/8$ is larger than the length of $mem.\text{bytes}$, then:
 - a. Trap.
10. Let b^* be the byte sequence $mem.\text{bytes}[ea : N/8]$.
11. Let n be the integer for which $\text{bytes}_{iN}(n) = b^*$.
12. Let L be the integer $128/N$.
13. Let c be the result of computing $\text{lanes}_{iN \times L}^{-1}(n^L)$.
14. Push the value `v128.const` c to the stack.

$$\begin{aligned}
& S; F; (i32.\text{const } i) \text{ (v128.loadN_splat } x \text{ memarg)} \hookrightarrow S; F; (\text{v128.const } c) \\
& \quad (\text{if } ea = i + \text{memarg.offset} \\
& \quad \quad \wedge ea + N/8 \leq |S.\text{mems}[F.\text{module.mems}[x]].\text{bytes}| \\
& \quad \quad \wedge \text{bytes}_{iN}(n) = S.\text{mems}[F.\text{module.mems}[x]].\text{bytes}[ea : N/8] \\
& \quad \quad \wedge c = \text{lanes}_{iN \times L}^{-1}(n^L)) \\
& S; F; (i32.\text{const } i) \text{ (v128.loadN_splat } x \text{ memarg)} \hookrightarrow S; F; \text{trap} \\
& \quad (\text{otherwise})
\end{aligned}$$

`v128.loadN_zero x memarg`

Todo: (*) Rule and prose both not spliced.

1. Let F be the [current frame](#).
2. Assert: due to [validation](#), $F.\text{module.mems}[x]$ exists.
3. Let a be the [memory address](#) $F.\text{module.mems}[x]$.
4. Assert: due to [validation](#), $S.\text{mems}[a]$ exists.
5. Let mem be the [memory instance](#) $S.\text{mems}[a]$.
6. Assert: due to [validation](#), a value of [value type](#) `i32` is on the top of the stack.
7. Pop the value `i32.const` i from the stack.
8. Let ea be the integer $i + \text{memarg.offset}$.
9. If $ea + N/8$ is larger than the length of $mem.\text{bytes}$, then:
 - a. Trap.
10. Let b^* be the byte sequence $mem.\text{bytes}[ea : N/8]$.
11. Let n be the integer for which $\text{bytes}_{iN}(n) = b^*$.
12. Let c be the result of computing $\text{extend}_{N,128}^u(n)$.
13. Push the value `v128.const` c to the stack.

$$\begin{aligned}
 S; F; (i32.\text{const } i) (\text{v128.loadN_zero } x \text{ memarg}) &\hookrightarrow S; F; (\text{v128.const } c) \\
 &\quad (\text{if } ea = i + \text{memarg.offset} \\
 &\quad \wedge ea + N/8 \leq |S.\text{mems}[F.\text{module.mems}[x]].\text{bytes}| \\
 &\quad \wedge \text{bytes}_{iN}(n) = S.\text{mems}[F.\text{module.mems}[x]].\text{bytes}[ea : N/8] \\
 &\quad \wedge c = \text{extend}_{N,128}^u(n) \\
 S; F; (i32.\text{const } i) (\text{v128.loadN_zero } x \text{ memarg}) &\hookrightarrow S; F; \text{trap} \\
 &\quad (\text{otherwise})
 \end{aligned}$$

`v128.loadN_lane x memarg y`

Todo: (*) Rule and prose both not spliced.

1. Let F be the [current frame](#).
2. Assert: due to [validation](#), $F.\text{module.mems}[x]$ exists.
3. Let a be the [memory address](#) $F.\text{module.mems}[x]$.
4. Assert: due to [validation](#), $S.\text{mems}[a]$ exists.
5. Let mem be the [memory instance](#) $S.\text{mems}[a]$.
6. Assert: due to [validation](#), a value of [value type](#) `v128` is on the top of the stack.
7. Pop the value `v128.const` v from the stack.
8. Assert: due to [validation](#), a value of [value type](#) `i32` is on the top of the stack.
9. Pop the value `i32.const` i from the stack.
10. Let ea be the integer $i + \text{memarg.offset}$.
11. If $ea + N/8$ is larger than the length of $mem.\text{bytes}$, then:

a. Trap.

12. Let b^* be the byte sequence $mem.bytes[ea : N/8]$.
13. Let r be the constant for which $bytes_{iN}(r) = b^*$.
14. Let L be $128/N$.
15. Let j^* be the result of computing $lanes_{iN \times L}(v)$.
16. Let c be the result of computing $lanes_{iN \times L}^{-1}(j^* \text{ with } [y] = r)$.
17. Push the value `v128.const` c to the stack.

$$\begin{aligned}
 &S; F; (i32.const\ i) (v128.const\ v) (v128.loadN_lane\ x\ memarg\ y) \hookrightarrow S; F; (v128.const\ c) \\
 &\quad (\text{if } ea = i + memarg.offset \\
 &\quad \wedge ea + N/8 \leq |S.mems[F.module.mems[x]].bytes| \\
 &\quad \wedge bytes_{iN}(r) = S.mems[F.module.mems[x]].bytes[ea : N/8]) \\
 &\quad \wedge L = 128/N \\
 &\quad \wedge c = lanes_{iN \times L}^{-1}(lanes_{iN \times L}(v) \text{ with } [y] = r)) \\
 &S; F; (i32.const\ i) (v128.const\ v) (v128.loadN_lane\ x\ memarg\ y) \hookrightarrow S; F; trap \\
 &\quad (\text{otherwise})
 \end{aligned}$$

`nt.storeszu1? x ao`

1. Let z be the current state.
2. Assert: Due to validation, a value of value type $numty_{u0}$ is on the top of the stack.
3. Pop the value $(numty_{u0}.const\ c)$ from the stack.
4. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
5. Pop the value $(i32.const\ i)$ from the stack.
6. If $numty_{u0}$ is `nt`, then:
 - a. If $i + ao.offset + |nt|/8$ is greater than $|z.mems[x].bytes|$ and $sz_{u1}^?$ is not defined, then:
 - 1) Trap.
 - b. If $sz_{u1}^?$ is not defined, then:
 - 1) Let b^* be $bytes_{nt}(c)$.
 - 2) Perform $z[.mems[x].bytes[i + ao.offset : |nt|/8] = b^*]$.
7. If the type of $numty_{u0}$ is `Inn`, then:
 - a. If $sz_{u1}^?$ is defined, then:
 - 1) Let n be $sz_{u1}^?$.
 - 2) If $i + ao.offset + n/8$ is greater than $|z.mems[x].bytes|$, then:
 - a) Trap.
 - b. Let iN be $numty_{u0}$.
 - c. If $sz_{u1}^?$ is defined, then:
 - 1) Let n be $sz_{u1}^?$.
 - 2) Let b^* be $bytes_{in}(\text{wrap}_{|iN|,n}(c))$.
 - 3) Perform $z[.mems[x].bytes[i + ao.offset : n/8] = b^*]$.

$$\begin{aligned}
z; (i32.\text{const } i) (nt.\text{const } c) (nt.\text{store } x \text{ } ao) &\hookrightarrow z; \text{trap} \\
&\quad \text{if } i + ao.\text{offset} + |nt|/8 > |z.\text{mems}[x].\text{bytes}| \\
z; (i32.\text{const } i) (nt.\text{const } c) (nt.\text{store } x \text{ } ao) &\hookrightarrow z[\text{mems}[x].\text{bytes}[i + ao.\text{offset} : |nt|/8] = b^*]; \epsilon \\
&\quad \text{if } b^* = \text{bytes}_{nt}(c) \\
z; (i32.\text{const } i) (iN.\text{const } c) (nt.\text{storeN } x \text{ } ao) &\hookrightarrow z; \text{trap} \\
&\quad \text{if } i + ao.\text{offset} + n/8 > |z.\text{mems}[x].\text{bytes}| \\
z; (i32.\text{const } i) (iN.\text{const } c) (nt.\text{storeN } x \text{ } ao) &\hookrightarrow z[\text{mems}[x].\text{bytes}[i + ao.\text{offset} : n/8] = b^*]; \epsilon \\
&\quad \text{if } b^* = \text{bytes}_{in}(\text{wrap}_{|iN|,n}(c))
\end{aligned}$$

$v128.\text{storeN_lane } x \text{ } memarg \text{ } y$

Todo: (*) Rule and prose both not spliced.

1. Let F be the **current frame**.
2. Assert: due to **validation**, $F.\text{module.mems}[x]$ exists.
3. Let a be the **memory address** $F.\text{module.mems}[x]$.
4. Assert: due to **validation**, $S.\text{mems}[a]$ exists.
5. Let mem be the **memory instance** $S.\text{mems}[a]$.
6. Assert: due to **validation**, a value of **value type** $v128$ is on the top of the stack.
7. Pop the value $v128.\text{const } c$ from the stack.
8. Assert: due to **validation**, a value of **value type** $i32$ is on the top of the stack.
9. Pop the value $i32.\text{const } i$ from the stack.
10. Let ea be the integer $i + memarg.\text{offset}$.
11. If $ea + N/8$ is larger than the length of $mem.\text{bytes}$, then:
 - a. Trap.
12. Let L be $128/N$.
13. Let j^* be the result of computing $\text{lanes}_{iN \times L}(c)$.
14. Let b^* be the result of computing $\text{bytes}_{iN}(j^*[y])$.
15. Replace the bytes $mem.\text{bytes}[ea : N/8]$ with b^* .

$$\begin{aligned}
S; F; (i32.\text{const } i) (v128.\text{const } c) (v128.\text{storeN_lane } x \text{ } memarg \text{ } y) &\hookrightarrow S'; F; \epsilon \\
&\quad (\text{if } ea = i + memarg.\text{offset} \\
&\quad \wedge ea + N \leq |S.\text{mems}[F.\text{module.mems}[x]].\text{bytes}| \\
&\quad \wedge L = 128/N \\
&\quad \wedge S' = S \text{ with } \text{mems}[F.\text{module.mems}[x]].\text{bytes}[ea : N/8] = \text{bytes}_{iN}(\text{lanes}_{iN \times L}(c)[y])) \\
S; F; (i32.\text{const } i) (v128.\text{const } c) (v128.\text{storeN_lane } x \text{ } memarg \text{ } y) &\hookrightarrow S; F; \text{trap} \\
&\quad (\text{otherwise})
\end{aligned}$$

memory.size *x*

1. Let *z* be the current state.
2. Let $n \cdot 64 \text{ Ki}$ be $|z.\text{mems}[x].\text{bytes}|$.
3. Push the value (*i32.const* *n*) to the stack.

$$z; (\text{memory.size } x) \hookrightarrow (\text{i32.const } n) \quad \text{if } n \cdot 64 \text{ Ki} = |z.\text{mems}[x].\text{bytes}|$$
memory.grow *x*

1. Let *z* be the current state.
2. Assert: Due to validation, a value of value type *i32* is on the top of the stack.
3. Pop the value (*i32.const* *n*) from the stack.
4. Either:
 - a. Let *mi* be *growmem*(*z.mems*[*x*], *n*).
 - b. Push the value (*i32.const* $|z.\text{mems}[x].\text{bytes}|/64 \text{ Ki}$) to the stack.
 - c. Perform $z[\text{mems}[x]] = mi$.
5. Or:
 - a. Push the value (*i32.const* $\text{signed}_{32}^{-1}(-1)$) to the stack.

Todo:

- (6) Maybe we want to be more precise than just saying “Either” in the prose, elaborating that it may succeed or fail non-deterministically.

$$\begin{aligned} z; (\text{i32.const } n) (\text{memory.grow } x) &\hookrightarrow z[\text{mems}[x] = mi]; (\text{i32.const } |z.\text{mems}[x].\text{bytes}|/64 \text{ Ki}) \\ &\quad \text{if } mi = \text{growmem}(z.\text{mems}[x], n) \\ z; (\text{i32.const } n) (\text{memory.grow } x) &\hookrightarrow z; (\text{i32.const } \text{signed}_{32}^{-1}(-1)) \end{aligned}$$

Note: The *memory.grow* instruction is non-deterministic. It may either succeed, returning the old memory size *sz*, or fail, returning -1 . Failure *must* occur if the referenced memory instance has a maximum size defined that would be exceeded. However, failure *can* occur in other cases as well. In practice, the choice depends on the *resources* available to the *embedder*.

memory.fill *x*

1. Let *z* be the current state.
2. Assert: Due to validation, a value of value type *i32* is on the top of the stack.
3. Pop the value (*i32.const* *n*) from the stack.
4. Assert: Due to validation, a value is on the top of the stack.
5. Pop the value *val* from the stack.
6. Assert: Due to validation, a value of value type *i32* is on the top of the stack.
7. Pop the value (*i32.const* *i*) from the stack.
8. If *i* + *n* is greater than $|z.\text{mems}[x].\text{bytes}|$, then:
 - a. Trap.
9. If *n* is 0, then:

a. Do nothing.

10. Else:

a. Push the value $(i32.const\ i)$ to the stack.

b. Push the value val to the stack.

c. Execute the instruction $(i32.store8\ x)$.

d. Push the value $(i32.const\ i + 1)$ to the stack.

e. Push the value val to the stack.

f. Push the value $(i32.const\ n - 1)$ to the stack.

g. Execute the instruction $(memory.fill\ x)$.

$z; (i32.const\ i)\ val\ (i32.const\ n)\ (memory.fill\ x)$	\hookrightarrow trap	if $i + n > z.mems[x].bytes $
$z; (i32.const\ i)\ val\ (i32.const\ n)\ (memory.fill\ x)$	$\hookrightarrow \epsilon$	otherwise, if $n = 0$
$z; (i32.const\ i)\ val\ (i32.const\ n)\ (memory.fill\ x)$	\hookrightarrow	
$(i32.const\ i)\ val\ (i32.store8\ x)$		otherwise
$(i32.const\ i + 1)\ val\ (i32.const\ n - 1)\ (memory.fill\ x)$		

$memory.copy\ x_1\ x_2$

1. Let z be the current state.

2. Assert: Due to validation, a value of value type $i32$ is on the top of the stack.

3. Pop the value $(i32.const\ n)$ from the stack.

4. Assert: Due to validation, a value of value type $i32$ is on the top of the stack.

5. Pop the value $(i32.const\ i_2)$ from the stack.

6. Assert: Due to validation, a value of value type $i32$ is on the top of the stack.

7. Pop the value $(i32.const\ i_1)$ from the stack.

8. If $i_1 + n$ is greater than $|z.mems[x_1].bytes|$, then:

a. Trap.

9. If $i_2 + n$ is greater than $|z.mems[x_2].bytes|$, then:

a. Trap.

10. If n is 0, then:

a. Do nothing.

11. Else:

a. If i_1 is less than or equal to i_2 , then:

1) Push the value $(i32.const\ i_1)$ to the stack.

2) Push the value $(i32.const\ i_2)$ to the stack.

3) Execute the instruction $(i32.load(8, u)\ x_2)$.

4) Execute the instruction $(i32.store8\ x_1)$.

5) Push the value $(i32.const\ i_1 + 1)$ to the stack.

6) Push the value $(i32.const\ i_2 + 1)$ to the stack.

b. Else:

1) Push the value $(i32.const\ i_1 + n - 1)$ to the stack.

2) Push the value $(i32.const\ i_2 + n - 1)$ to the stack.

- 3) Execute the instruction (`i32.load(8, u) x2`).
 - 4) Execute the instruction (`i32.store8 x1`).
 - 5) Push the value (`i32.const i1`) to the stack.
 - 6) Push the value (`i32.const i2`) to the stack.
 - c. Push the value (`i32.const n - 1`) to the stack.
 - d. Execute the instruction (`memory.copy x1 x2`).
- $z; (i32.const\ i_1)\ (i32.const\ i_2)\ (i32.const\ n)\ (memory.copy\ x_1\ x_2) \hookrightarrow \text{trap}$
 if $i_1 + n > |z.mems[x_1].bytes| \vee i_2 + n > |z.mems[x_2].bytes|$
 $z; (i32.const\ i_1)\ (i32.const\ i_2)\ (i32.const\ n)\ (memory.copy\ x_1\ x_2) \hookrightarrow \epsilon$ otherwise, if $n = 0$
 $z; (i32.const\ i_1)\ (i32.const\ i_2)\ (i32.const\ n)\ (memory.copy\ x_1\ x_2) \hookrightarrow$
 $(i32.const\ i_1)\ (i32.const\ i_2)\ (i32.load8\ u\ x_2)\ (i32.store8\ x_1)$ otherwise, if $i_1 \leq i_2$
 $(i32.const\ i_1 + 1)\ (i32.const\ i_2 + 1)\ (i32.const\ n - 1)\ (memory.copy\ x_1\ x_2)$
 $z; (i32.const\ i_1)\ (i32.const\ i_2)\ (i32.const\ n)\ (memory.copy\ x_1\ x_2) \hookrightarrow$
 $(i32.const\ i_1 + n - 1)\ (i32.const\ i_2 + n - 1)\ (i32.load8\ u\ x_2)\ (i32.store8\ x_1)$ otherwise
 $(i32.const\ i_1)\ (i32.const\ i_2)\ (i32.const\ n - 1)\ (memory.copy\ x_1\ x_2)$

`memory.init x y`

1. Let z be the current state.
2. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
3. Pop the value (`i32.const n`) from the stack.
4. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
5. Pop the value (`i32.const i`) from the stack.
6. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
7. Pop the value (`i32.const j`) from the stack.
8. If $i + n$ is greater than $|z.datas[y].bytes|$, then:
 - a. Trap.
9. If $j + n$ is greater than $|z.mems[x].bytes|$, then:
 - a. Trap.
10. If n is 0, then:
 - a. Do nothing.
11. Else if i is less than $|z.datas[y].bytes|$, then:
 - a. Push the value (`i32.const j`) to the stack.
 - b. Push the value (`i32.const z.datas[y].bytes[i]`) to the stack.
 - c. Execute the instruction (`i32.store8 x`).
 - d. Push the value (`i32.const j + 1`) to the stack.
 - e. Push the value (`i32.const i + 1`) to the stack.
 - f. Push the value (`i32.const n - 1`) to the stack.
 - g. Execute the instruction (`memory.init x y`).

$$\begin{aligned}
 & z; (i32.\text{const } j) (i32.\text{const } i) (i32.\text{const } n) (\text{memory.init } x \ y) \hookrightarrow \text{trap} \\
 & \quad \text{if } i + n > |z.\text{datas}[y].\text{bytes}| \vee j + n > |z.\text{mems}[x].\text{bytes}| \\
 & z; (i32.\text{const } j) (i32.\text{const } i) (i32.\text{const } n) (\text{memory.init } x \ y) \hookrightarrow \epsilon \quad \text{otherwise, if } n = 0 \\
 & z; (i32.\text{const } j) (i32.\text{const } i) (i32.\text{const } n) (\text{memory.init } x \ y) \hookrightarrow \\
 & \quad (i32.\text{const } j) (i32.\text{const } z.\text{datas}[y].\text{bytes}[i]) (i32.\text{store8 } x) \quad \text{otherwise} \\
 & \quad (i32.\text{const } j + 1) (i32.\text{const } i + 1) (i32.\text{const } n - 1) (\text{memory.init } x \ y)
 \end{aligned}$$

data.drop x

1. Let z be the current state.
2. Perform $z[\text{datas}[x].\text{bytes}] = \epsilon$.

$$z; (\text{data.drop } x) \hookrightarrow z[\text{datas}[x].\text{bytes}] = \epsilon; \epsilon$$

4.6.8 Control Instructions

block $bt \text{ instr}^*$

1. Let z be the current state.
2. Let $t_1^m \rightarrow t_2^n$ be $\text{instrtype}_z(bt)$.
3. Assert: Due to validation, there are at least m values on the top of the stack.
4. Pop the values val^m from the stack.
5. Let L be the label whose arity is n and whose continuation is ϵ .
6. Enter $val^m \text{ instr}^*$ with label L .

$$z; val^m (\text{block } bt \text{ instr}^*) \hookrightarrow (\text{label}_n\{\epsilon\} val^m \text{ instr}^*) \quad \text{if } \text{instrtype}_z(bt) = t_1^m \rightarrow t_2^n$$

loop $bt \text{ instr}^*$

1. Let z be the current state.
2. Let $t_1^m \rightarrow t_2^n$ be $\text{instrtype}_z(bt)$.
3. Assert: Due to validation, there are at least m values on the top of the stack.
4. Pop the values val^m from the stack.
5. Let L be the label whose arity is m and whose continuation is $(\text{loop } bt \text{ instr}^*)$.
6. Enter $val^m \text{ instr}^*$ with label L .

$$z; val^m (\text{loop } bt \text{ instr}^*) \hookrightarrow (\text{label}_m\{\text{loop } bt \text{ instr}^*\} val^m \text{ instr}^*) \quad \text{if } \text{instrtype}_z(bt) = t_1^m \rightarrow t_2^n$$

if $bt \text{ instr}_1^* \text{ instr}_2^*$

1. Assert: Due to validation, a value of value type `i32` is on the top of the stack.
2. Pop the value $(i32.\text{const } c)$ from the stack.
3. If c is not 0, then:
 - a. Execute the instruction $(\text{block } bt \text{ instr}_1^*)$.
4. Else:
 - a. Execute the instruction $(\text{block } bt \text{ instr}_2^*)$.

$$\begin{aligned}
(i32.\text{const } c) (\text{if } bt \text{ } instr_1^* \text{ else } instr_2^*) &\hookrightarrow (\text{block } bt \text{ } instr_1^*) && \text{if } c \neq 0 \\
(i32.\text{const } c) (\text{if } bt \text{ } instr_1^* \text{ else } instr_2^*) &\hookrightarrow (\text{block } bt \text{ } instr_2^*) && \text{if } c = 0
\end{aligned}$$

br l

1. Pop all values val^* from the top of the stack.
2. Let L be the current label.
3. Let n be the arity of L .
4. Let $instr'^*$ be the continuation of L .
5. Pop the current label from the stack.
6. Let $instr_{u0}^*$ be val^* .
7. If l is 0 and $|instr_{u0}^*|$ is greater than or equal to n , then:
 - a. Let $val'^* \text{ } val^n$ be $instr_{u0}^*$.
 - b. Push the values val^n to the stack.
 - c. Execute the sequence $instr'^*$.
8. If l is greater than 0, then:
 - a. Let val^* be $instr_{u0}^*$.
 - b. Push the values val^* to the stack.
 - c. Execute the instruction $(br \ l - 1)$.

$$\begin{aligned}
(\text{label}_n \{ instr'^* \} \text{ } val'^* \text{ } val^n \text{ } (br \ l) \text{ } instr^*) &\hookrightarrow val^n \text{ } instr'^* && \text{if } l = 0 \\
(\text{label}_n \{ instr'^* \} \text{ } val^* \text{ } (br \ l) \text{ } instr^*) &\hookrightarrow val^* \text{ } (br \ l - 1) && \text{if } l > 0
\end{aligned}$$

br_if l

1. Assert: Due to validation, a value of value type *i32* is on the top of the stack.
2. Pop the value $(i32.\text{const } c)$ from the stack.
3. If c is not 0, then:
 - a. Execute the instruction $(br \ l)$.
4. Else:
 - a. Do nothing.

$$\begin{aligned}
(i32.\text{const } c) (br_if \ l) &\hookrightarrow (br \ l) && \text{if } c \neq 0 \\
(i32.\text{const } c) (br_if \ l) &\hookrightarrow \epsilon && \text{if } c = 0
\end{aligned}$$

br_table l l'*

1. Assert: Due to validation, a value of value type *i32* is on the top of the stack.
2. Pop the value $(i32.\text{const } i)$ from the stack.
3. If i is less than $|l^*|$, then:
 - a. Execute the instruction $(br \ l^*[i])$.
4. Else:
 - a. Execute the instruction $(br \ l')$.

$$\begin{aligned}
(i32.\text{const } i) (br_table \ l^* \ l') &\hookrightarrow (br \ l^*[i]) && \text{if } i < |l^*| \\
(i32.\text{const } i) (br_table \ l^* \ l') &\hookrightarrow (br \ l') && \text{if } i \geq |l^*|
\end{aligned}$$

br_on_null l

1. Assert: Due to validation, a value is on the top of the stack.
2. Pop the value val from the stack.
3. If val is of the case **ref.null**, then:
 - a. Execute the instruction **(br l)**.
4. Else:
 - a. Push the value val to the stack.

Todo:

- (3) Introduce if-let instruction instead of “is of the case”.
-

$$\begin{array}{lll} val\ (br_on_null\ l) & \hookrightarrow & (br\ l) \quad \text{if } val = \text{ref.null } ht \\ val\ (br_on_null\ l) & \hookrightarrow & val \quad \text{otherwise} \end{array}$$

br_on_non_null l

1. Assert: Due to validation, a value is on the top of the stack.
2. Pop the value val from the stack.
3. If val is of the case **ref.null**, then:
 - a. Do nothing.
4. Else:
 - a. Push the value val to the stack.
 - b. Execute the instruction **(br l)**.

Todo:

- (3) Introduce if-let instruction instead of “is of the case”.
-

$$\begin{array}{lll} val\ (br_on_non_null\ l) & \hookrightarrow & \epsilon \quad \text{if } val = \text{ref.null } ht \\ val\ (br_on_non_null\ l) & \hookrightarrow & val\ (br\ l) \quad \text{otherwise} \end{array}$$

br_on_cast $l\ rt_1\ rt_2$

1. Let f be the current frame.
2. Assert: Due to validation, a value is on the top of the stack.
3. Pop the value ref from the stack.
4. Let rt be $ref_{type_of}(ref)$.
5. If rt does not match $clos_{f.module}(rt_2)$, then:
 - a. Push the value ref to the stack.
6. Else:
 - a. Push the value ref to the stack.
 - b. Execute the instruction **(br l)**.

Todo: Below is the actual prose. (9) Need to handle RulePr s |- ref : rt properly in prose instead of \$ref_type_of

1. Let F be the **current frame**.
2. Let rt'_2 be the **reference type** $\text{clos}_{F.\text{module}}(rt_2)$.
3. Assert: due to **validation**, rt'_2 is **closed**.
4. Assert: due to **validation**, a **reference value** is on the top of the stack.
5. Pop the value ref from the stack.
6. Assert: due to validation, the **reference value** is **valid** with some **reference type**.
7. Let rt be the **reference type** of ref .
8. Push the value ref back to the stack.
9. If the **reference type** rt **matches** rt'_2 , then:

- a. **Execute** the instruction $(br\ l)$.

$$\begin{array}{ll}
 s; f; ref\ (br_on_cast\ l\ rt_1\ rt_2) \hookrightarrow ref\ (br\ l) & \text{if } s \vdash ref : rt \\
 & \wedge \{\} \vdash rt \leq \text{clos}_{f.\text{module}}(rt_2) \\
 s; f; ref\ (br_on_cast\ l\ rt_1\ rt_2) \hookrightarrow ref & \text{otherwise}
 \end{array}$$

$br_on_cast_fail\ l\ rt_1\ rt_2$

1. Let f be the **current frame**.
2. Assert: Due to validation, a value is on the top of the stack.
3. Pop the value ref from the stack.
4. Let rt be $ref_{type_of}(ref)$.
5. If rt **matches** $\text{clos}_{f.\text{module}}(rt_2)$, then:
 - a. Push the value ref to the stack.
6. Else:
 - a. Push the value ref to the stack.
 - b. **Execute** the instruction $(br\ l)$.

Todo: Below is the actual prose. (9) Need to handle RulePr s |- ref : rt properly in prose instead of \$ref_type_of

1. Let F be the **current frame**.
2. Let rt'_2 be the **reference type** $\text{clos}_{F.\text{module}}(rt_2)$.
3. Assert: due to **validation**, rt'_2 is **closed**.
4. Assert: due to **validation**, a **reference value** is on the top of the stack.
5. Pop the value ref from the stack.
6. Assert: due to validation, the **reference value** is **valid** with some **reference type**.
7. Let rt be the **reference type** of ref .
8. Push the value ref back to the stack.
9. If the **reference type** rt **does not match** rt'_2 , then:
 - a. **Execute** the instruction $(br\ l)$.

$$\begin{array}{ll}
 s; f; \text{ref}(\text{br_on_cast_fail } l \text{ } rt_1 \text{ } rt_2) \hookrightarrow \text{ref} & \text{if } s \vdash \text{ref} : rt \\
 & \wedge \{\} \vdash rt \leq \text{clos}_{f.\text{module}}(rt_2) \\
 s; f; \text{ref}(\text{br_on_cast_fail } l \text{ } rt_1 \text{ } rt_2) \hookrightarrow \text{ref}(\text{br } l) & \text{otherwise}
 \end{array}$$

return

1. Pop all values val^* from the top of the stack.
2. If a frame is now on the top of the stack, then:
 - a. Let F be the current frame.
 - b. Let n be the arity of F .
 - c. Pop the current frame from the stack.
 - d. Let $val'^* \text{ } val^n$ be val^* .
 - e. Push the values val^n to the stack.
3. Else if a label is now on the top of the stack, then:
 - a. Pop the current label from the stack.
 - b. Push the values val^* to the stack.
 - c. Execute the instruction **return**.

$$\begin{array}{ll}
 (\text{frame}_n\{f\} \text{ } val'^* \text{ } val^n \text{ return } instr^*) \hookrightarrow val^n & \\
 (\text{label}_n\{instr'^*\} \text{ } val^* \text{ return } instr^*) \hookrightarrow val^* \text{ return} &
 \end{array}$$

call x

1. Let z be the current state.
2. Assert: Due to validation, x is less than $|z.\text{module}.\text{funcs}|$.
3. Let a be $z.\text{module}.\text{funcs}[x]$.
4. Assert: Due to validation, a is less than $|z.\text{funcs}|$.
5. Push the value $(\text{ref}.\text{func } a)$ to the stack.
6. Execute the instruction $(\text{call_ref } z.\text{funcs}[a].\text{type})$.

$$z; (\text{call } x) \hookrightarrow (\text{ref}.\text{func } a) (\text{call_ref } z.\text{funcs}[a].\text{type}) \quad \text{if } z.\text{module}.\text{funcs}[x] = a$$

call_ref x

Todo: (*) Prose not spliced, for the prose merges the two cases of null and non-null references.

1. Assert: due to **validation**, a null or **function reference** is on the top of the stack.
2. Pop the reference value r from the stack.
3. If r is **ref.null ht** , then:
 - a. Trap.
4. Assert: due to **validation**, r is a **function reference**.
5. Let **ref.func a** be the reference r .
6. **Invoke** the function instance at address a .

$$z; (\text{ref.null } ht) (\text{call_ref } y) \hookrightarrow \text{trap}$$

Note: The formal rule for calling a non-null function reference is described [below](#).

`call_indirect x y`

1. Execute the instruction `(table.get x)`.
2. Execute the instruction `(ref.cast (ref (null ()) y))`.
3. Execute the instruction `(call_ref y)`.

Todo: Below is the actual prose. (11) `ref.cast (ref (null ()) y)` is rendered differently. Need to handle TERMINAL? case in AL-to-EL-expr phase.

1. Let F be the current frame.
2. Assert: due to [validation](#), $F.\text{module.tables}[x]$ exists.
3. Let ta be the table address $F.\text{module.tables}[x]$.
4. Assert: due to [validation](#), $S.\text{tables}[ta]$ exists.
5. Let tab be the table instance $S.\text{tables}[ta]$.
6. Assert: due to [validation](#), $F.\text{module.types}[y]$ is defined.
7. Let dt_{expect} be the defined type $F.\text{module.types}[y]$.
8. Assert: due to [validation](#), a value with value type `i32` is on the top of the stack.
9. Pop the value `i32.const i` from the stack.
10. If i is not smaller than the length of $tab.\text{elem}$, then:
 - a. Trap.
11. Let r be the reference $tab.\text{elem}[i]$.
12. If r is `ref.null ht` , then:
 - a. Trap.
13. Assert: due to [validation of table mutation](#), r is a function reference.
14. Let `ref.func a` be the function reference r .
15. Assert: due to [validation of table mutation](#), $S.\text{funcs}[a]$ exists.
16. Let f be the function instance $S.\text{funcs}[a]$.
17. Let dt_{actual} be the defined type $f.\text{type}$.
18. If dt_{actual} does not [match](#) dt_{expect} , then:
 - a. Trap.
19. [Invoke](#) the function instance at address a .

$$(\text{call_indirect } x \ y) \hookrightarrow (\text{table.get } x) (\text{ref.cast (ref null } y)) (\text{call_ref } y)$$

`return_call` x

1. Let z be the current state.
2. Assert: Due to validation, x is less than $|z.\text{module.functions}|$.
3. Let a be $z.\text{module.functions}[x]$.
4. Assert: Due to validation, a is less than $|z.\text{funcs}|$.
5. Push the value $(\text{ref.func } a)$ to the stack.
6. Execute the instruction $(\text{return_call_ref } z.\text{funcs}[a].\text{type})$.

$$z; (\text{return_call } x) \hookrightarrow (\text{ref.func } a) (\text{return_call_ref } z.\text{funcs}[a].\text{type}) \quad \text{if } z.\text{module.functions}[x] = a$$
`return_call_ref` x

Todo: (*) Prose not spliced, Sphinx cannot build the document with deeply nested ordered list. (mainly caused by spurious conditions that should be assertions)

1. Assert: due to validation, a function reference is on the top of the stack.
2. Pop the reference value r from the stack.
3. If r is `ref.null ht`, then:
 - a. Trap.
4. Assert: due to validation, r is a function reference.
5. Let $\text{ref.func } a$ be the reference r .
6. Tail-invoke the function instance at address a .

$$\begin{aligned} z; (\text{label}_k \{instr^*\} \text{ val}^* (\text{return_call_ref } y) \text{ instr}^*) &\hookrightarrow \text{val}^* (\text{return_call_ref } y) \\ z; (\text{frame}_k \{f\} \text{ val}^* (\text{ref.null } ht) (\text{return_call_ref } y) \text{ instr}^*) &\hookrightarrow \text{trap} \\ z; (\text{frame}_k \{f\} \text{ val}^* \text{ val}^n (\text{ref.func } a) (\text{return_call_ref } y) \text{ instr}^*) &\hookrightarrow \text{val}^n (\text{ref.func } a) (\text{call_ref } y) \\ &\quad \text{if } z.\text{funcs}[a].\text{type} \approx \text{func } (t_1^n \rightarrow t_2^m) \end{aligned}$$
`return_call_indirect` x y

1. Execute the instruction $(\text{table.get } x)$.
2. Execute the instruction $(\text{ref.cast } (\text{ref } (\text{null } ({})) y))$.
3. Execute the instruction $(\text{return_call_ref } y)$.

Todo: Below is the actual prose. (11) `ref.cast (ref (null ()) y)` is rendered differently. Need to handle TERMINAL? case in AL-to-EL-expr phase.

1. Let F be the current frame.
2. Assert: due to validation, $F.\text{module.tables}[x]$ exists.
3. Let ta be the table address $F.\text{module.tables}[x]$.
4. Assert: due to validation, $S.\text{tables}[ta]$ exists.
5. Let tab be the table instance $S.\text{tables}[ta]$.
6. Assert: due to validation, $F.\text{module.types}[y]$ exists.
7. Let dt_{expect} be the defined type $F.\text{module.types}[y]$.

8. Assert: due to **validation**, a value with **value type** `i32` is on the top of the stack.
9. Pop the value `i32.const i` from the stack.
10. If `i` is not smaller than the length of `tab.elem`, then:
 - a. Trap.
11. If `tab.elem[i]` is uninitialized, then:
 - a. Trap.
12. Let `a` be the **function address** `tab.elem[i]`.
13. Assert: due to **validation**, `S.funcs[a]` exists.
14. Let `f` be the **function instance** `S.funcs[a]`.
15. Let `dtactual` be the **defined type** `f.type`.
16. If `dtactual` does not **match** `dtexpect`, then:
 - a. Trap.
17. **Tail-invoke** the function instance at address `a`.

$$(\text{return_call_indirect } x \ y) \hookrightarrow (\text{table.get } x) (\text{ref.cast } (\text{ref null } y)) (\text{return_call_ref } y)$$

4.6.9 Blocks

The following auxiliary rules define the semantics of executing an **instruction sequence** that forms a **block**.

Entering *instr** with label *L*

1. Push `L` to the stack.
2. Jump to the start of the instruction sequence *instr**.

Note: No formal reduction rule is needed for entering an instruction sequence, because the label `L` is embedded in the **administrative instruction** that structured control instructions reduce to directly.

Exiting *instr** with label *L*

When the end of a block is reached without a jump or trap aborting it, then the following steps are performed.

1. Pop all values *val** from the top of the stack.
2. Assert: due to **validation**, the label `L` is now on the top of the stack.
3. Pop the label from the stack.
4. Push *val** back to the stack.
5. Jump to the position after the **end** of the **structured control instruction** associated with the label `L`.

$$(\text{label}_n \{ \text{instr}^* \} \text{ val}^*) \hookrightarrow \text{val}^*$$

Note: This semantics also applies to the instruction sequence contained in a **loop** instruction. Therefore, execution of a loop falls off the end, unless a backwards branch is performed explicitly.

4.6.10 Function Calls

The following auxiliary rules define the semantics of invoking a **function** instance through one of the **call instructions** and returning from it.

Invocation of function reference (ref.func *a*)

1. Assert: due to **validation**, $S.\text{funcs}[a]$ exists.
2. Let f be the **function** instance, $S.\text{funcs}[a]$.
3. Let $\text{func } [t_1^n] \rightarrow [t_2^m]$ be the composite type $\text{expand}(f.\text{type})$.
4. Let local^* be the list of **locals** $f.\text{code}.\text{locals}$.
5. Let $\text{instr}^* \text{ end}$ be the **expression** $f.\text{code}.\text{body}$.
6. Assert: due to **validation**, n values are on the top of the stack.
7. Pop the values val^n from the stack.
8. Let F be the **frame** $\{\text{module } f.\text{module}, \text{locals } \text{val}^n (\text{default}_t)^*\}$.
9. Push the activation of F with arity m to the stack.
10. Let L be the **label** whose arity is m and whose continuation is the end of the function.
11. **Enter** the instruction sequence instr^* with label L .

$$\begin{aligned} z; \text{val}^n (\text{ref.func } a) (\text{call_ref } y) &\hookrightarrow (\text{frame}_m\{f\} (\text{label}_m\{\epsilon\} \text{instr}^*)) \\ &\quad \text{if } z.\text{funcs}[a] = f \\ &\quad \wedge f.\text{type} \approx \text{func } (t_1^n \rightarrow t_2^m) \\ &\quad \wedge f.\text{code} = \text{func } x (\text{local } t)^* (\text{instr}^*) \\ &\quad \wedge f = \{\text{locals } \text{val}^n (\text{default}_t)^*, \text{module } f.\text{module}\} \end{aligned}$$

Note: For non-defaultable types, the respective local is left uninitialized by these rules.

Returning from a function

When the end of a function is reached without a jump (i.e., **return**) or trap aborting it, then the following steps are performed.

1. Let F be the **current frame**.
2. Let n be the arity of the activation of F .
3. Assert: due to **validation**, there are n values on the top of the stack.
4. Pop the results val^n from the stack.
5. Assert: due to **validation**, the frame F is now on the top of the stack.
6. Pop the frame from the stack.
7. Push val^n back to the stack.
8. Jump to the instruction after the original call.

$$(\text{frame}_n\{f\} \text{val}^n) \hookrightarrow \text{val}^n$$

Host Functions

Invoking a [host function](#) has non-deterministic behavior. It may either terminate with a [trap](#) or return regularly. However, in the latter case, it must consume and produce the right number and types of WebAssembly [values](#) on the stack, according to its [function type](#).

A host function may also modify the [store](#). However, all store modifications must result in an [extension](#) of the original store, i.e., they must only modify mutable contents and must not have instances removed. Furthermore, the resulting store must be [valid](#), i.e., all data and code in it is well-typed.

$$\begin{aligned}
 S; val^n (\text{invoke } a) &\hookrightarrow S'; result \\
 &(\text{if } S.\text{funcs}[a] = \{\text{type } deftype, \text{hostfunc } hf\} \\
 &\quad \wedge \text{expand}(deftype) = \text{func } [t_1^n] \rightarrow [t_2^m] \\
 &\quad \wedge (S'; result) \in hf(S; val^n)) \\
 S; val^n (\text{invoke } a) &\hookrightarrow S; val^n (\text{invoke } a) \\
 &(\text{if } S.\text{funcs}[a] = \{\text{type } deftype, \text{hostfunc } hf\} \\
 &\quad \wedge \text{expand}(deftype) = \text{func } [t_1^n] \rightarrow [t_2^m] \\
 &\quad \wedge \perp \in hf(S; val^n))
 \end{aligned}$$

Here, $hf(S; val^n)$ denotes the implementation-defined execution of host function hf in current store S with arguments val^n . It yields a set of possible outcomes, where each element is either a pair of a modified store S' and a [result](#) or the special value \perp indicating divergence. A host function is non-deterministic if there is at least one argument for which the set of outcomes is not singular.

For a WebAssembly implementation to be [sound](#) in the presence of host functions, every [host function instance](#) must be [valid](#), which means that it adheres to suitable pre- and post-conditions: under a [valid store](#) S , and given arguments val^n matching the ascribed parameter types t_1^n , executing the host function must yield a non-empty set of possible outcomes each of which is either divergence or consists of a valid store S' that is an [extension](#) of S and a result matching the ascribed return types t_2^m . All these notions are made precise in the [Appendix](#).

Note: A host function can call back into WebAssembly by [invoking](#) a function [exported](#) from a [module](#). However, the effects of any such call are subsumed by the non-deterministic behavior allowed for the host function.

4.6.11 Expressions

An [expression](#) is *evaluated* relative to a [current frame](#) pointing to its containing [module instance](#).

1. Jump to the start of the instruction sequence $instr^*$ of the expression.
2. Execute the instruction sequence.
3. Assert: due to [validation](#), the top of the stack contains a [value](#).
4. Pop the [value](#) val from the stack.

The value val is the result of the evaluation.

$$\begin{aligned}
 z; instr^* &\hookrightarrow^* z'; val^* && \text{if } z; instr^* \hookrightarrow^* z'; val^* \\
 S; F; instr^* &\hookrightarrow S'; F'; instr'^* && (\text{if } S; F; instr^* \text{ end} \hookrightarrow S'; F'; instr'^* \text{ end})
 \end{aligned}$$

Note: Evaluation iterates this reduction rule until reaching a value. Expressions constituting [function bodies](#) are executed during function [invocation](#).

4.7 Modules

For modules, the execution semantics primarily defines [instantiation](#), which [allocates](#) instances for a module and its contained definitions, initializes [tables](#) and [memories](#) from contained [element](#) and [data](#) segments, and invokes the [start function](#) if present. It also includes [invocation](#) of exported functions.

4.7.1 Allocation

New instances of [functions](#), [tables](#), [memories](#), and [globals](#) are *allocated* in a [store](#) s , as defined by the following auxiliary functions.

Functions

1. Let $func$ be the [function](#) to allocate and $moduleinst$ its [module instance](#).
2. Let $deftype$ be the defined type $moduleinst.types[func.type]$.
3. Let a be the first free [function address](#) in S .
4. Let $funcinst$ be the [function instance](#) $\{type\ deptype, module\ moduleinst, code\ func\}$.
6. Append $funcinst$ to the [funcs](#) of S .
7. Return a .

$$\begin{aligned} allocfunc(s, deptype, code, moduleinst) &= (s \oplus \{funcs\ funcinst\}, |s.funcs|) \\ &\text{if } funcinst = \{type\ deptype, module\ moduleinst, code\ code\} \end{aligned}$$

Note: Host functions are never allocated by the WebAssembly semantics itself, but may be allocated by the [embedder](#).

Tables

1. Let $tabletype$ be the [table type](#) of the table to allocate and ref the initialization value.
2. Let $(\{\min n, \max m^?\} \text{ } reftype)$ be the structure of [table type](#) $tabletype$.
3. Let a be the first free [table address](#) in S .
4. Let $tableinst$ be the [table instance](#) $\{type\ tabletype', elem\ ref^n\}$ with n elements set to ref .
5. Append $tableinst$ to the [tables](#) of S .
6. Return a .

$$\begin{aligned} alloctable(s, [i..j] \text{ } rt, ref) &= (s \oplus \{tables\ tableinst\}, |s.tables|) \\ &\text{if } tableinst = \{type\ ([i..j] \text{ } rt), elem\ ref^i\} \end{aligned}$$

Memories

1. Let $memtype$ be the [memory type](#) of the memory to allocate.
2. Let $\{\min n, \max m^?\}$ be the structure of [memory type](#) $memtype$.
3. Let a be the first free [memory address](#) in S .
4. Let $meminst$ be the [memory instance](#) $\{type\ memtype, bytes\ (0x00)^{n \cdot 64 \text{ Ki}}\}$ that contains n pages of zeroed bytes.
5. Append $meminst$ to the [mems](#) of S .

6. Return a .

$$\begin{aligned} \text{allocmem}(s, [i..j] \text{ page}) &= (s \oplus \{\text{mems } \text{meminst}\}, |s.\text{mems}|) \\ \text{if } \text{meminst} &= \{\text{type } ([i..j] \text{ page}), \text{bytes } (0x00)^{i \cdot 64 \text{ Ki}}\} \end{aligned}$$

Globals

1. Let globaltype be the global type of the global to allocate and val its initialization value.
2. Let a be the first free global address in S .
3. Let globalinst be the global instance $\{\text{type } \text{globaltype}, \text{value } \text{val}\}$.
4. Append globalinst to the globals of S .
5. Return a .

$$\begin{aligned} \text{allocglobal}(s, \text{globaltype}, \text{val}) &= (s \oplus \{\text{globals } \text{globalinst}\}, |s.\text{globals}|) \\ \text{if } \text{globalinst} &= \{\text{type } \text{globaltype}, \text{value } \text{val}\} \end{aligned}$$

Element segments

1. Let reftype be the elements' type and ref^* the list of references to allocate.
2. Let a be the first free element address in S .
3. Let eleminst be the element instance $\{\text{type } \text{reftype}, \text{elem } \text{ref}^*\}$.
4. Append eleminst to the elems of S .
5. Return a .

$$\begin{aligned} \text{allocelem}(s, \text{elemtype}, \text{ref}^*) &= (s \oplus \{\text{elems } \text{eleminst}\}, |s.\text{elems}|) \\ \text{if } \text{eleminst} &= \{\text{type } \text{elemtype}, \text{elem } \text{ref}^*\} \end{aligned}$$

Data segments

1. Let b^* be the list of bytes to allocate.
2. Let a be the first free data address in S .
3. Let datainst be the data instance $\{\text{bytes } b^*\}$.
4. Append datainst to the datas of S .
5. Return a .

$$\begin{aligned} \text{allocdata}(s, \text{ok}, \text{byte}^*) &= (s \oplus \{\text{datas } \text{datainst}\}, |s.\text{datas}|) \\ \text{if } \text{datainst} &= \{\text{bytes } \text{byte}^*\} \end{aligned}$$

Growing tables

1. Let tableinst be the table instance to grow, n the number of elements by which to grow it, and ref the initialization value.
2. Let len be n added to the length of tableinst.elem .
3. If len is larger than or equal to 2^{32} , then fail.
4. Let $\text{limits } t$ be the structure of table type tableinst.type .
5. Let limits' be limits with min updated to len .

6. If *limits'* is not **valid**, then fail.
7. Append *refⁿ* to *tableinst.elem*.
8. Set *tableinst.type* to the **table type** *limits' t*.

$$\text{growtable}(\text{tableinst}, n, r) = \text{tableinst}' \quad \begin{array}{l} \text{if } \text{tableinst} = \{\text{type } ([i \dots j] \text{ rt}), \text{ elem } r'^*\} \\ \wedge \text{tableinst}' = \{\text{type } ([i' \dots j] \text{ rt}), \text{ elem } r'^* r^n\} \\ \wedge i' = |r'^*| + n \leq j \end{array}$$

Growing memories

1. Let *meminst* be the **memory instance** to grow and *n* the number of **pages** by which to grow it.
2. Assert: The length of *meminst.bytes* is divisible by the **page size** 64 Ki.
3. Let *len* be *n* added to the length of *meminst.bytes* divided by the **page size** 64 Ki.
4. If *len* is larger than 2^{16} , then fail.
5. Let *limits* be the structure of **memory type** *meminst.type*.
6. Let *limits'* be *limits* with **min** updated to *len*.
7. If *limits'* is not **valid**, then fail.
8. Append *n* times 64 Ki **bytes** with value 0x00 to *meminst.bytes*.
9. Set *meminst.type* to the **memory type** *limits'*.

$$\text{growmem}(\text{meminst}, n) = \text{meminst}' \quad \begin{array}{l} \text{if } \text{meminst} = \{\text{type } ([i \dots j] \text{ page}), \text{ bytes } b^*\} \\ \wedge \text{meminst}' = \{\text{type } ([i' \dots j] \text{ page}), \text{ bytes } b^* (0x00)^{n \cdot 64 \text{ Ki}}\} \\ \wedge i' = |b^*| / (64 \text{ Ki}) + n \leq j \end{array}$$

Modules

Todo: update prose for types

The allocation function for **modules** requires a suitable list of **external values** that are assumed to **match** the **import** list of the module, a list of initialization **values** for the module's **globals**, and list of **reference** lists for the module's **element segments**.

1. Let *module* be the **module** to allocate and *externval_{im}^{*}* the list of **external values** providing the module's imports, *val_g^{*}* the initialization **values** of the module's **globals**, *ref_t^{*}* the initializer **reference** of the module's **tables**, and *(ref_e^{*})^{*}* the **reference** lists of the module's **element segments**.
2. For each **defined type** *deftype_i'* in *module.types*, do:
 - a. Let *deftype_i* be the **instantiation** *deftype_i'* in *moduleinst* defined below.
3. For each **function** *func_i* in *module.funcs*, do:
 - a. Let *funcaddr_i* be the **function address** resulting from allocating *func_i* for the **module instance** *moduleinst* defined below.
4. For each **table** *table_i* in *module.tables*, do:
 - a. Let *limits_i t_i* be the **table type** obtained by **instantiating** *table_i.type* in *moduleinst* defined below.
 - b. Let *tableaddr_i* be the **table address** resulting from allocating *table_i.type* with initialization value *ref_t^{*}[i]*.
5. For each **memory** *mem_i* in *module.mems*, do:
 - a. Let *memtype_i* be the **memory type** obtained by **insantiating** *mem_i.type* in *moduleinst* defined below.

- b. Let $memaddr_i$ be the memory address resulting from allocating $memtype_i$.
6. For each global $global_i$ in $module.globals$, do:
 - a. Let $globaltype_i$ be the global type obtained by instantiating $global_i.type$ in $moduleinst$ defined below.
 - b. Let $globaladdr_i$ be the global address resulting from allocating $globaltype_i$ with initializer value $val_g^*[i]$.
7. For each element segment $elem_i$ in $module.elms$, do:
 - a. Let $reftype_i$ be the element reference type obtained by instantiating $\langle type-inst \rangle elem_i.type$ in $moduleinst$ defined below.
 - b. Let $elemaddr_i$ be the element address resulting from allocating a element instance of reference type $reftype_i$ with contents $(ref_e^*)^*[i]$.
8. For each data segment $data_i$ in $module.datas$, do:
 - a. Let $dataaddr_i$ be the data address resulting from allocating a data instance with contents $data_i.init$.
9. Let $deftype^*$ be the concatenation of the defined types $deftype_i$ in index order.
10. Let $funcaddr^*$ be the concatenation of the function addresses $funcaddr_i$ in index order.
11. Let $tableaddr^*$ be the concatenation of the table addresses $tableaddr_i$ in index order.
12. Let $memaddr^*$ be the concatenation of the memory addresses $memaddr_i$ in index order.
13. Let $globaladdr^*$ be the concatenation of the global addresses $globaladdr_i$ in index order.
14. Let $elemaddr^*$ be the concatenation of the element addresses $elemaddr_i$ in index order.
15. Let $dataaddr^*$ be the concatenation of the data addresses $dataaddr_i$ in index order.
16. Let $funcaddr_{mod}^*$ be the list of function addresses extracted from $externval_{im}^*$, concatenated with $funcaddr^*$.
17. Let $tableaddr_{mod}^*$ be the list of table addresses extracted from $externval_{im}^*$, concatenated with $tableaddr^*$.
18. Let $memaddr_{mod}^*$ be the list of memory addresses extracted from $externval_{im}^*$, concatenated with $memaddr^*$.
19. Let $globaladdr_{mod}^*$ be the list of global addresses extracted from $externval_{im}^*$, concatenated with $globaladdr^*$.
20. For each export $export_i$ in $module.exports$, do:
 - a. If $export_i$ is a function export for function index x , then let $externval_i$ be the external value $func(funcaddr_{mod}^*[x])$.
 - b. Else, if $export_i$ is a table export for table index x , then let $externval_i$ be the external value $table(tableaddr_{mod}^*[x])$.
 - c. Else, if $export_i$ is a memory export for memory index x , then let $externval_i$ be the external value $mem(memaddr_{mod}^*[x])$.
 - d. Else, if $export_i$ is a global export for global index x , then let $externval_i$ be the external value $global(globaladdr_{mod}^*[x])$.
 - e. Let $exportinst_i$ be the export instance $\{name(export_i.name), value externval_i\}$.
21. Let $exportinst^*$ be the concatenation of the export instances $exportinst_i$ in index order.
22. Let $moduleinst$ be the module instance $\{types deftype^*, funcs funcaddr_{mod}^*, tables tableaddr_{mod}^*, mems memaddr_{mod}^*, globals globaladdr_{mod}^*, exports exportinst^*\}$.
23. Return $moduleinst$.

$$\begin{aligned}
\text{allocmodule}(s, \text{module}, \text{externval}^*, \text{val}_g^*, \text{ref}_t^*, (\text{ref}_e^*)^*) &= (s_6, \text{moduleinst}) \\
\text{if } \text{module} &= \text{module type}^* \text{ import}^* \text{ func}^* \text{ global}^* \text{ table}^* \text{ mem}^* \text{ elem}^* \text{ data}^* \text{ start}^? \text{ export}^* \\
\wedge \text{func}^* &= (\text{func } x \text{ local}^* \text{ expr}_f^*)^* \\
\wedge \text{global}^* &= (\text{global } \text{globaltype } \text{expr}_g^*)^* \\
\wedge \text{table}^* &= (\text{table } \text{tabletype } \text{expr}_t^*)^* \\
\wedge \text{mem}^* &= (\text{memory } \text{memtype})^* \\
\wedge \text{elem}^* &= (\text{elem } \text{elemtype } \text{expr}_e^* \text{ elemmode})^* \\
\wedge \text{data}^* &= (\text{data } \text{byte}^* \text{ datamode})^* \\
\wedge \text{fa}_i^* &= \text{funcs}(\text{externval}^*) \\
\wedge \text{ga}_i^* &= \text{globals}(\text{externval}^*) \\
\wedge \text{ta}_i^* &= \text{tables}(\text{externval}^*) \\
\wedge \text{ma}_i^* &= \text{mems}(\text{externval}^*) \\
\wedge \text{fa}^* &= (|s.\text{funcs}| + i_f)^{i_f < |func^*|} \\
\wedge \text{ga}^* &= (|s.\text{globals}| + i_g)^{i_g < |global^*|} \\
\wedge \text{ta}^* &= (|s.\text{tables}| + i_t)^{i_t < |table^*|} \\
\wedge \text{ma}^* &= (|s.\text{mems}| + i_m)^{i_m < |mem^*|} \\
\wedge \text{ea}^* &= (|s.\text{elems}| + i_e)^{i_e < |elem^*|} \\
\wedge \text{da}^* &= (|s.\text{datas}| + i_d)^{i_d < |data^*|} \\
\wedge \text{dt}^* &= \text{alloctype}^*(\text{type}^*) \\
\wedge (s_1, \text{fa}^*) &= \text{allocfunc}^*(s, \text{dt}^*[x]^*, (\text{func } x \text{ local}^* \text{ expr}_f^*)^*, \text{moduleinst}^{|func^*|}) \\
\wedge (s_2, \text{ga}^*) &= \text{allocglobal}^*(s_1, \text{globaltype}^*, \text{val}_g^*) \\
\wedge (s_3, \text{ta}^*) &= \text{alloctable}^*(s_2, \text{tabletype}^*, \text{ref}_t^*) \\
\wedge (s_4, \text{ma}^*) &= \text{allocmem}^*(s_3, \text{memtype}^*) \\
\wedge (s_5, \text{ea}^*) &= \text{allocelem}^*(s_4, \text{elemtype}^*, (\text{ref}_e^*)^*) \\
\wedge (s_6, \text{da}^*) &= \text{allocddata}^*(s_5, \text{ok}^{|data^*|}, (\text{byte}^*)^*) \\
\wedge \text{xi}^* &= \text{allocexport}^*(\{\text{funcs } \text{fa}_i^* \text{ fa}^*, \text{globals } \text{ga}_i^* \text{ ga}^*, \text{tables } \text{ta}_i^* \text{ ta}^*, \text{mems } \text{ma}_i^* \text{ ma}^*\}, \text{export}^*) \\
\wedge \text{moduleinst} &= \{\text{types } \text{dt}^*, \\
&\quad \text{funcs } \text{fa}_i^* \text{ fa}^*, \text{globals } \text{ga}_i^* \text{ ga}^*, \\
&\quad \text{tables } \text{ta}_i^* \text{ ta}^*, \text{mems } \text{ma}_i^* \text{ ma}^*, \\
&\quad \text{elems } \text{ea}^*, \text{datas } \text{da}^*, \\
&\quad \text{exports } \text{xi}^*\}
\end{aligned}$$

Here, the notation allocx^* is shorthand for multiple allocations of object kind X , defined as follows:

$$\begin{aligned}
\text{allocX}^*(s, \epsilon, \epsilon) &= (s, \epsilon) \\
\text{allocX}^*(s, X \text{ X}'^*, Y \text{ Y}'^*) &= (s_2, a \text{ a}'^*) \quad \text{if } (s_1, a) = \text{allocX}(X, Y, s, X, Y) \\
&\quad \wedge (s_2, a') = \text{allocX}^*(s_1, X', Y')
\end{aligned}$$

For types, however, allocation is defined in terms of [rolling](#) and [substitution](#) of all preceding types to produce a list of [closed defined types](#):

$$\begin{aligned}
\text{alloytype}^*(\epsilon) &= \epsilon \\
\text{alloytype}^*(\text{type}'^* \text{ type}) &= \text{deftype}'^* \text{ deftype}^* \quad \text{if } \text{deftype}'^* = \text{alloytype}^*(\text{type}'^*) \\
&\quad \wedge \text{type} = \text{type } \text{rectype} \\
&\quad \wedge \text{deftype}^* = \text{roll}_x^*(\text{rectype})[:= \text{deftype}'^*] \\
&\quad \wedge x = |\text{deftype}'^*|
\end{aligned}$$

Finally, export instances are produced with the help of the following definition:

$$\begin{aligned}
\text{allocexport}^*(\text{moduleinst}, \text{export}^*) &= \text{allocexport}(\text{moduleinst}, \text{export}^*)^* \\
\text{allocexport}(\text{moduleinst}, \text{export name } (\text{func } x)) &= \{\text{name name}, \text{value } (\text{func } \text{moduleinst}.\text{funcs}[x])\} \\
\text{allocexport}(\text{moduleinst}, \text{export name } (\text{global } x)) &= \{\text{name name}, \text{value } (\text{global } \text{moduleinst}.\text{globals}[x])\} \\
\text{allocexport}(\text{moduleinst}, \text{export name } (\text{table } x)) &= \{\text{name name}, \text{value } (\text{table } \text{moduleinst}.\text{tables}[x])\} \\
\text{allocexport}(\text{moduleinst}, \text{export name } (\text{memory } x)) &= \{\text{name name}, \text{value } (\text{mem } \text{moduleinst}.\text{mems}[x])\}
\end{aligned}$$

Note: The definition of module allocation is mutually recursive with the allocation of its associated functions, because the resulting module instance is passed to the allocators as an argument, in order to form the necessary closures. In an implementation, this recursion is easily unraveled by mutating one or the other in a secondary step.

4.7.2 Instantiation

Given a *store* s , a *module* is instantiated with a list of *external values* $externval^*$ supplying the required imports as follows.

Instantiation checks that the module is *valid* and the provided imports *match* the declared types, and may *fail* with an error otherwise. Instantiation can also result in a *trap* from initializing a table or memory from an active segment or from executing the start function. It is up to the *embedder* to define how such conditions are reported.

1. If *module* is not *valid*, then:
 - a. Fail.
2. Assert: *module* is *valid* with external types $externtype_{im}^m$ classifying its imports.
3. If the number m of imports is not equal to the number n of provided external values, then:
 - a. Fail.
4. For each external value $externval_i$ in $externval^n$ and external type $externtype'_i$ in $externtype_{im}^n$, do:
 - a. If $externval_i$ is not *valid* with an external type $externtype_i$ in store S , then:
 - i. Fail.
 - b. Let $externtype''_i$ be the external type obtained by instantiating $externtype'_i$ in *moduleinst* defined below.
 - c. If $externtype_i$ does not *match* $externtype''_i$, then:
 - i. Fail.
6. Let F be the auxiliary frame $\{\text{module } moduleinst, \text{locals } \epsilon\}$, that consists of the final module instance *moduleinst*, defined below.
7. Push the frame F to the stack.
8. Let val_g^* be the list of *global* initialization values determined by *module* and $externval^n$. These may be calculated as follows.
 - a. For each *global* $global_i$ in *module.globals*, do:
 - i. Let val_{gi} be the result of *evaluating* the initializer expression $global_i.init$.
 - b. Assert: due to *validation*, the frame F is now on the top of the stack.
 - c. Let val_g^* be the concatenation of val_{gi} in index order.
9. Let ref_t^* be the list of *table* initialization references determined by *module* and $externval^n$. These may be calculated as follows.
 - a. For each *table* $table_i$ in *module.tables*, do:
 - i. Let val_{ti} be the result of *evaluating* the initializer expression $table_i.init$.
 - ii. Assert: due to *validation*, val_{ti} is a *reference*.
 - iii. Let ref_{ti} be the reference val_{ti} .
 - b. Assert: due to *validation*, the frame F is now on the top of the stack.
 - c. Let ref_t^* be the concatenation of ref_{ti} in index order.
10. Let $(ref_e^*)^*$ be the list of *reference* lists determined by the *element* segments in *module*. These may be calculated as follows.
 - a. For each *element* segment $elem_i$ in *module elems*, and for each element expression $expr_{ij}$ in $elem_i.init$, do:
 - i. Let ref_{ij} be the result of *evaluating* the initializer expression $expr_{ij}$.
 - b. Let ref_i^* be the concatenation of function elements ref_{ij} in order of index j .
 - c. Let $(ref_e^*)^*$ be the concatenation of function element lists ref_i^* in order of index i .

11. Let *moduleinst* be a new module instance allocated from *module* in store *S* with imports *externvalⁿ*, global initializer values *val_g^{*}*, table initializer values *ref_t^{*}*, and element segment contents *(ref_e^{*})^{*}*, and let *S'* be the extended store produced by module allocation.
12. For each element segment *elem_i* in *module.elems* whose *mode* is of the form active {table *tableidx_i*, offset *instr_i^{*}* end}, do:
 - a. Let *n* be the length of the list *elem_i.init*.
 - b. Execute the instruction sequence *instr_i^{*}*.
 - c. Execute the instruction *i32.const 0*.
 - d. Execute the instruction *i32.const n*.
 - e. Execute the instruction *table.init tableidx_i i*.
 - f. Execute the instruction *elem.drop i*.
13. For each element segment *elem_i* in *module.elems* whose *mode* is of the form declare, do:
 - a. Execute the instruction *elem.drop i*.
14. For each data segment *data_i* in *module.datas* whose *mode* is of the form active {memory *memidx_i*, offset *dinstr_i^{*}* end}, do:
 - a. Assert: *memidx_i* is 0.
 - b. Let *n* be the length of the list *data_i.init*.
 - c. Execute the instruction sequence *dinstr_i^{*}*.
 - d. Execute the instruction *i32.const 0*.
 - e. Execute the instruction *i32.const n*.
 - f. Execute the instruction *memory.init i*.
 - g. Execute the instruction *data.drop i*.
15. If the start function *module.start* is not empty, then:
 - a. Let *start* be the start function *module.start*.
 - b. Execute the instruction *call start.func*.
16. Assert: due to validation, the frame *F* is now on the top of the stack.
17. Pop the frame *F* from the stack.

$$\begin{aligned}
 \text{instantiate}(s, \text{module}, \text{externval}^*) &= s'; f; \text{instr}_e^* \text{instr}_d^* \text{instr}_s^? \\
 &\text{if } \text{module} = \text{module type}^* \text{import}^* \text{func}^* \text{global}^* \text{table}^* \text{mem}^* \text{elem}^* \text{data}^* \text{start}^? \text{export}^* \\
 &\wedge \text{global}^* = (\text{global globaltype expr}_g)^* \\
 &\wedge \text{table}^* = (\text{table tabletype expr}_t)^* \\
 &\wedge \text{elem}^* = (\text{elem reftype expr}_e \text{elemmode})^* \\
 &\wedge \text{data}^* = (\text{data byte}^* \text{datamode})^* \\
 &\wedge \text{start}^? = (\text{start } x)^? \\
 &\wedge \text{moduleinst}_0 = \{\text{types alloctype}^*(\text{type}^*), \\
 &\quad \text{funcs funcs}(\text{externval}^*) (|s.\text{funcs}| + i_f)^{i_f < |func^*|}, \\
 &\quad \text{globals globals}(\text{externval}^*)\} \\
 &\wedge z = s; \{\text{module moduleinst}_0\} \\
 &\wedge (z; \text{expr}_g \hookrightarrow^* z; \text{val}_g)^* \\
 &\wedge (z; \text{expr}_t \hookrightarrow^* z; \text{ref}_t)^* \\
 &\wedge (z; \text{expr}_e \hookrightarrow^* z; \text{ref}_e)^{**} \\
 &\wedge (s', \text{moduleinst}) = \text{allocmodule}(s, \text{module}, \text{externval}^*, \text{val}_g^*, \text{ref}_t^*, (\text{ref}_e^*)^*) \\
 &\wedge f = \{\text{module moduleinst}\} \\
 &\wedge \text{instr}_e^* = \text{concat}(\text{runelem}_{i_e}(\text{elem}^*[i_e])^{i_e < |\text{elem}^*|}) \\
 &\wedge \text{instr}_d^* = \text{concat}(\text{rundata}_{i_d}(\text{data}^*[i_d])^{i_d < |\text{data}^*|}) \\
 &\wedge \text{instr}_s^? = (\text{call } x)^?
 \end{aligned}$$

where:

$$\begin{aligned}
 \text{runelem}_x(\text{elem } rt \ e^n \text{ (passive)}) &= \epsilon \\
 \text{runelem}_x(\text{elem } rt \ e^n \text{ (declare)}) &= (\text{elem.drop } x) \\
 \text{runelem}_x(\text{elem } rt \ e^n \text{ (active } y \text{ instr}^*)) &= \text{instr}^* \text{ (i32.const 0) (i32.const } n\text{) (table.init } y \text{ } x\text{) (elem.drop } x\text{)} \\
 \text{rundata}_x(\text{data } b^n \text{ (passive)}) &= \epsilon \\
 \text{rundata}_x(\text{data } b^n \text{ (active } y \text{ instr}^*)) &= \text{instr}^* \text{ (i32.const 0) (i32.const } n\text{) (memory.init } y \text{ } x\text{) (data.drop } x\text{)}
 \end{aligned}$$

Note: Checking import types assumes that the `module instance` has already been `allocated` to compute the respective `closed defined types`. However, this forward reference merely is a way to simplify the specification. In practice, implementations will likely allocate or canonicalize types beforehand, when *compiling* a module, in a stage before instantiation and before imports are checked.

Similarly, module `allocation` and the `evaluation` of `global` and `table` initializers as well as `element segments` are mutually recursive because the global initialization values val_g^* , ref_t , and element segment contents ref_e^{**} are passed to the module allocator while depending on the module instance `moduleinst` and store s' returned by allocation. Again, this recursion is just a specification device. In practice, the initialization values can be `determined` beforehand by staging module allocation such that first, the module's own `function instances` are pre-allocated in the store, then the initializer expressions are evaluated in order, allocating globals on the way, then the rest of the module instance is allocated, and finally the new function instances' module fields are set to that module instance. This is possible because `validation` ensures that initialization expressions cannot actually call a function, only take their reference.

All failure conditions are checked before any observable mutation of the store takes place. Store mutation is not atomic; it happens in individual steps that may be interleaved with other threads.

`Evaluation` of `constant expressions` does not affect the store.

4.7.3 Invocation

Once a `module` has been `instantiated`, any exported function can be *invoked* externally via its `function address` `funcaddr` in the `store` s and an appropriate list val^* of argument `values`.

Invocation may *fail* with an error if the arguments do not fit the `function type`. Invocation can also result in a `trap`. It is up to the `embedder` to define how such conditions are reported.

Note: If the `embedder` API performs type checks itself, either statically or dynamically, before performing an invocation, then no failure other than traps can occur.

The following steps are performed:

1. Assert: $S.\text{funcs}[\text{funcaddr}]$ exists.
2. Let `funcinst` be the `function instance` $S.\text{funcs}[\text{funcaddr}]$.
3. Let $\text{func } [t_1^n] \rightarrow [t_2^m]$ be the `composite type` $\text{expand}(\text{funcinst.type})$.
4. If the length $|val^*|$ of the provided argument values is different from the number n of expected arguments, then:
 - a. Fail.
5. For each `value type` t_i in t_1^n and corresponding `value` val_i in val^* , do:
 - a. If val_i is not `valid` with value type t_i , then:
 - i. Fail.
6. Let F be the dummy `frame` $\{\text{module } \{\}, \text{locals } \epsilon\}$.

7. Push the frame F to the stack.
8. Push the values val^* to the stack.
9. **Invoke** the function instance at address $funcaddr$.

Once the function has returned, the following steps are executed:

1. Assert: due to **validation**, m values are on the top of the stack.
2. Pop val_{res}^m from the stack.
3. Assert: due to **validation**, the frame F is now on the top of the stack.
4. Pop the frame F from the stack.

The values val_{res}^m are returned as the results of the invocation.

$$\begin{aligned} \text{invoke}(s, funcaddr, val^*) &= s; f; val^* (\text{ref.func } funcaddr) (\text{call_ref } s.\text{funcs}[funcaddr].\text{type}) \\ &\quad \text{if } s.\text{funcs}[funcaddr].\text{type} \approx \text{func } (t_1^* \rightarrow t_2^*) \\ &\quad \wedge f = \{\text{module } \{\}\} \end{aligned}$$

5.1 Conventions

The binary format for WebAssembly **modules** is a dense linear *encoding* of their **abstract syntax**.²⁸

The format is defined by an *attribute grammar* whose only terminal symbols are **bytes**. A byte sequence is a well-formed encoding of a module if and only if it is generated by the grammar.

Each production of this grammar has exactly one synthesized attribute: the abstract syntax that the respective byte sequence encodes. Thus, the attribute grammar implicitly defines a *decoding* function (i.e., a parsing function for the binary format).

Except for a few exceptions, the binary grammar closely mirrors the grammar of the abstract syntax.

Note: Some phrases of abstract syntax have multiple possible encodings in the binary format. For example, numbers may be encoded as if they had optional leading zeros. Implementations of decoders must support all possible alternatives; implementations of encoders can pick any allowed encoding.

The recommended extension for files containing WebAssembly modules in binary format is “.wasm” and the recommended **Media Type**²⁷ is “application/wasm”.

5.1.1 Grammar

The following conventions are adopted in defining grammar rules for the binary format. They mirror the conventions used for **abstract syntax**. In order to distinguish symbols of the binary syntax from symbols of the abstract syntax, **typewriter** font is adopted for the former.

- Terminal symbols are **bytes** expressed in hexadecimal notation: 0x0F.
- Nonterminal symbols are written in typewriter font: **valtype**, **instr**.
- B^n is a sequence of $n \geq 0$ iterations of B .
- B^* is a possibly empty sequence of iterations of B . (This is a shorthand for B^n used where n is not relevant.)

²⁸ Additional encoding layers – for example, introducing compression – may be defined on top of the basic representation defined here. However, such layers are outside the scope of the current specification.

²⁷ <https://www.iana.org/assignments/media-types/media-types.xhtml>

- $B^?$ is an optional occurrence of B . (This is a shorthand for B^n where $n \leq 1$.)
- $x:B$ denotes the same language as the nonterminal B , but also binds the variable x to the attribute synthesized for B . A pattern may also be used instead of a variable, e.g., $7:B$.
- Productions are written $\text{sym} ::= B_1 \Rightarrow A_1 \mid \dots \mid B_n \Rightarrow A_n$, where each A_i is the attribute that is synthesized for sym in the given case, usually from attribute variables bound in B_i .
- Some productions are augmented by side conditions in parentheses, which restrict the applicability of the production. They provide a shorthand for a combinatorial expansion of the production into many separate cases.
- If the same meta variable or non-terminal symbol appears multiple times in a production (in the syntax or in an attribute), then all those occurrences must have the same instantiation. (This is a shorthand for a side condition requiring multiple different variables to be equal.)

Note: For example, the [binary grammar](#) for [number types](#) is given as follows:

$$\begin{array}{lcl} \text{numtype} & ::= & 0x7C \Rightarrow \text{f64} \\ & & | \quad 0x7D \Rightarrow \text{f32} \\ & & | \quad 0x7E \Rightarrow \text{i64} \\ & & | \quad 0x7F \Rightarrow \text{i32} \end{array}$$

Consequently, the byte 0x7F encodes the type [i32](#), 0x7E encodes the type [i64](#), and so forth. No other byte value is allowed as the encoding of a number type.

The [binary grammar](#) for [limits](#) is defined as follows:

$$\begin{array}{lcl} \text{limits} & ::= & 0x00 \ n:\text{u32} \quad \Rightarrow \quad [n \dots 2^{32} - 1] \\ & & | \quad 0x01 \ n:\text{u32} \ m:\text{u32} \quad \Rightarrow \quad [n \dots m] \end{array}$$

That is, a limits pair is encoded as either the byte 0x00 followed by the encoding of a [u32](#) value, or the byte 0x01 followed by two such encodings. The variables n and m name the attributes of the respective [u32](#) nonterminals, which in this case are the actual [unsigned integers](#) those decode into. The attribute of the complete production then is the abstract syntax for the limit, expressed in terms of the former values.

5.1.2 Auxiliary Notation

When dealing with binary encodings the following notation is also used:

- ϵ denotes the empty byte sequence.
- $||B||$ is the length of the byte sequence generated from the production B in a derivation.

5.1.3 Lists

[Lists](#) are encoded with their [u32](#) length followed by the encoding of their element sequence.

$$\text{list}(X) ::= n:\text{u32} \ (el:X)^n \Rightarrow el^n$$

5.2 Values

5.2.1 Bytes

Bytes encode themselves.

$$\text{byte} ::= b:0x00 \mid \dots \mid b:0xFF \Rightarrow b$$

5.2.2 Integers

All integers are encoded using the LEB128²⁹ variable-length integer encoding, in either unsigned or signed variant.

Unsigned integers are encoded in unsigned LEB128³⁰ format. As an additional constraint, the total number of bytes encoding a uN value must not exceed $\text{ceil}(N/7)$ bytes.

$$\begin{aligned} uN ::= n:\text{byte} &\Rightarrow n && \text{if } n < 2^7 \wedge n < 2^N \\ &\mid n:\text{byte } m:\text{u}(N-7) &\Rightarrow 2^7 \cdot m + (n - 2^7) && \text{if } n \geq 2^7 \wedge N > 7 \end{aligned}$$

Signed integers are encoded in signed LEB128³¹ format, which uses a two's complement representation. As an additional constraint, the total number of bytes encoding an sN value must not exceed $\text{ceil}(N/7)$ bytes.

$$\begin{aligned} sN ::= n:\text{byte} &\Rightarrow n && \text{if } n < 2^6 \wedge n < 2^{N-1} \\ &\mid n:\text{byte} &\Rightarrow n - 2^7 && \text{if } 2^6 \leq n < 2^7 \wedge n \geq 2^7 - 2^{N-1} \\ &\mid n:\text{byte } i:\text{u}(N-7) &\Rightarrow 2^7 \cdot i + (n - 2^7) && \text{if } n \geq 2^7 \wedge N > 7 \end{aligned}$$

Uninterpreted integers are encoded as signed integers.

$$iN ::= i:sN \Rightarrow \text{signed}_N^{-1}(i)$$

Note: The side conditions $N > 7$ in the productions for non-terminal bytes of the uN and sN encodings restrict the encoding's length. However, “trailing zeros” are still allowed within these bounds. For example, `0x03` and `0x83 0x00` are both well-formed encodings for the value 3 as a us . Similarly, either of `0x7E` and `0xFE 0x7F` and `0xFE 0xFF 0x7F` are well-formed encodings of the value -2 as an $si6$.

The side conditions on the value n of terminal bytes further enforce that any unused bits in these bytes must be 0 for positive values and 1 for negative ones. For example, `0x83 0x10` is malformed as a us encoding. Similarly, both `0x83 0x3E` and `0xFF 0x7B` are malformed as ss encodings.

5.2.3 Floating-Point

Floating-point values are encoded directly by their IEEE 754³² (Section 3.4) bit pattern in little endian³³ byte order:

$$fN ::= b*:\text{byte}^{N/8} \Rightarrow \text{bytes}_{fN}^{-1}(b*)$$

²⁹ <https://en.wikipedia.org/wiki/LEB128>

³⁰ https://en.wikipedia.org/wiki/LEB128#Unsigned_LEB128

³¹ https://en.wikipedia.org/wiki/LEB128#Signed_LEB128

³² <https://ieeexplore.ieee.org/document/8766229>

³³ <https://en.wikipedia.org/wiki/Endianness#Little-endian>

5.2.4 Names

Names are encoded as a list of bytes containing the Unicode³⁴ (Section 3.9) UTF-8 encoding of the name's character sequence.

$$\text{name} ::= b^*:\text{list}(\text{byte}) \Rightarrow \text{name} \quad \text{if } \text{utf8}(\text{name}) = b^*$$

The auxiliary `utf8` function expressing this encoding is defined as follows:

$$\begin{aligned} \text{utf8}(ch^*) &= \text{concat}(\text{utf8}(ch)^*) \\ \text{utf8}(ch) &= b && \text{if } ch < \text{U}+80 \\ & && \wedge ch = b \\ \text{utf8}(ch) &= b_1 b_2 && \text{if } \text{U}+80 \leq ch < \text{U}+0800 \\ & && \wedge ch = 2^6 \cdot (b_1 - 0\text{x}C0) + \text{cont}(b_2) \\ \text{utf8}(ch) &= b_1 b_2 b_3 && \text{if } \text{U}+0800 \leq ch < \text{U}+\text{D}800 \vee \text{U}+\text{E}000 \leq ch < \text{U}+10000 \\ & && \wedge ch = 2^{12} \cdot (b_1 - 0\text{x}E0) + 2^6 \cdot \text{cont}(b_2) + \text{cont}(b_3) \\ \text{utf8}(ch) &= b_1 b_2 b_3 b_4 && \text{if } \text{U}+10000 \leq ch < \text{U}+11000 \\ & && \wedge ch = 2^{18} \cdot (b_1 - 0\text{x}F0) + 2^{12} \cdot \text{cont}(b_2) + 2^6 \cdot \text{cont}(b_3) + \text{cont}(b_4) \end{aligned}$$

where $\text{cont}(b) = b - 0\text{x}80$ if $(0\text{x}80 < b < 0\text{x}C0)$

Note: Unlike in some other formats, name strings are not 0-terminated.

5.3 Types

Note: In some places, possible types include both type constructors or types denoted by type indices. Thus, the binary format for type constructors corresponds to the encodings of small negative *sN* values, such that they can unambiguously occur in the same place as (positive) type indices.

5.3.1 Number Types

Number types are encoded by a single byte.

$$\begin{array}{lcl} \text{numtype} & ::= & 0\text{x}7C \Rightarrow \text{f}_{64} \\ & & | \quad 0\text{x}7D \Rightarrow \text{f}_{32} \\ & & | \quad 0\text{x}7E \Rightarrow \text{i}_{64} \\ & & | \quad 0\text{x}7F \Rightarrow \text{i}_{32} \end{array}$$

5.3.2 Vector Types

Vector types are also encoded by a single byte.

$$\text{vectype} ::= 0\text{x}7B \Rightarrow \text{v}_{128}$$

³⁴ <https://www.unicode.org/versions/latest/>

5.3.3 Heap Types

Heap types are encoded as either a single byte, or as a `type index` encoded as a positive signed integer.

<code>absheaptypes</code>	<code>::=</code>	<code>0x6A</code>	\Rightarrow	<code>array</code>
		<code>0x6B</code>	\Rightarrow	<code>struct</code>
		<code>0x6C</code>	\Rightarrow	<code>i31</code>
		<code>0x6D</code>	\Rightarrow	<code>eq</code>
		<code>0x6E</code>	\Rightarrow	<code>any</code>
		<code>0x6F</code>	\Rightarrow	<code>extern</code>
		<code>0x70</code>	\Rightarrow	<code>func</code>
		<code>0x71</code>	\Rightarrow	<code>none</code>
		<code>0x72</code>	\Rightarrow	<code>noextern</code>
		<code>0x73</code>	\Rightarrow	<code>nofunc</code>
<code>heaptypes</code>	<code>::=</code>	<code>ht:absheaptypes</code>	\Rightarrow	<code>ht</code>
		<code>x:s33</code>	\Rightarrow	<code>x</code> if $x \geq 0$

Note: The heap type `bot` cannot occur in a module.

5.3.4 Reference Types

Reference types are either encoded by a single byte followed by a `heap type`, or, as a short form, directly as an abstract heap type.

<code>reftypes</code>	<code>::=</code>	<code>0x63 ht:heaptypes</code>	\Rightarrow	<code>ref null ht</code>
		<code>0x64 ht:heaptypes</code>	\Rightarrow	<code>ref ht</code>
		<code>ht:absheaptypes</code>	\Rightarrow	<code>ref null ht</code>

5.3.5 Value Types

Value types are encoded with their respective encoding as a `number type`, `vector type`, or `reference type`.

<code>valtypes</code>	<code>::=</code>	<code>nt:numtypes</code>	\Rightarrow	<code>nt</code>
		<code>vt:vectypes</code>	\Rightarrow	<code>vt</code>
		<code>rt:reftypes</code>	\Rightarrow	<code>rt</code>

Note: The value type `bot` cannot occur in a module.

Value types can occur in contexts where `type indices` are also allowed, such as in the case of `block types`. Thus, the binary format for types corresponds to the `signed LEB128`³⁵ encoding of small negative `sN` values, so that they can coexist with (positive) type indices in the future.

5.3.6 Result Types

Result types are encoded by the respective lists of value types.

<code>resulttypes</code>	<code>::=</code>	<code>t*:list(valtypes)</code>	\Rightarrow	<code>t*</code>
--------------------------	------------------	--------------------------------	---------------	-----------------

³⁵ https://en.wikipedia.org/wiki/LEB128#Signed_LEB128

5.3.7 Composite Types

Composite types are encoded by a distinct byte followed by a type encoding of the respective form.

<code>mut</code>	<code>::= 0x00</code>	$\Rightarrow \epsilon$
	<code> 0x01</code>	$\Rightarrow \text{mut}$
<code>comptype</code>	<code>::= 0x5E yt:fieldtype</code>	$\Rightarrow \text{array } yt$
	<code> 0x5F yt*:list(fieldtype)</code>	$\Rightarrow \text{struct } yt^*$
	<code> 0x60 t1*:resultttype t2*:resultttype</code>	$\Rightarrow \text{func } (t_1^* \rightarrow t_2^*)$
<code>fieldtype</code>	<code>::= zt:storagetype mut?:mut</code>	$\Rightarrow \text{mut}^? zt$
<code>storagetype</code>	<code>::= t:valtype</code>	$\Rightarrow t$
	<code> pt:packtype</code>	$\Rightarrow pt$
<code>packtype</code>	<code>::= 0x77</code>	$\Rightarrow i16$
	<code> 0x78</code>	$\Rightarrow i8$

5.3.8 Recursive Types

Recursive types are encoded by the byte 0x4E followed by a list of sub types. Additional shorthands are recognized for unary recursions and sub types without super types.

<code>rectype</code>	<code>::= 0x4E st*:list(subtype)</code>	$\Rightarrow \text{rec } st^*$
	<code> st:subtype</code>	$\Rightarrow \text{rec } st$
<code>subtype</code>	<code>::= 0x4F x*:list(typeidx) ct:comptype</code>	$\Rightarrow \text{sub final } x^* ct$
	<code> 0x50 x*:list(typeidx) ct:comptype</code>	$\Rightarrow \text{sub } x^* ct$
	<code> ct:comptype</code>	$\Rightarrow \text{sub final } \epsilon ct$

5.3.9 Limits

Limits are encoded with a preceding flag indicating whether a maximum is present.

<code>limits</code>	<code>::= 0x00 n:u32</code>	$\Rightarrow [n .. 2^{32} - 1]$
	<code> 0x01 n:u32 m:u32</code>	$\Rightarrow [n .. m]$

5.3.10 Memory Types

Memory types are encoded with their limits.

<code>memtype</code>	<code>::= lim:limits</code>	$\Rightarrow \text{lim page}$
----------------------	-----------------------------	-------------------------------

5.3.11 Table Types

Table types are encoded with their limits and the encoding of their element reference type.

<code>tabletype</code>	<code>::= rt:reftype lim:limits</code>	$\Rightarrow \text{lim } rt$
------------------------	--	------------------------------

5.3.12 Global Types

Global types are encoded by their [value type](#) and a flag for their [mutability](#).

$$\text{globaltype} ::= t:\text{valtype } \text{mut}^?:\text{mut} \Rightarrow \text{mut}^? t$$

5.3.13 External Types

External types are encoded by a distinguishing byte followed by an encoding of the respective form of type.

<code>externtype</code>	<code>::=</code>	<code>0x00</code>	<code>x:typeidx</code>	\Rightarrow	<code>func</code> <code>x</code>
			<code> </code>	<code>0x01</code>	<code>tt:tabletype</code> \Rightarrow <code>table</code> <code>tt</code>
			<code> </code>	<code>0x02</code>	<code>mt:memtype</code> \Rightarrow <code>mem</code> <code>mt</code>
			<code> </code>	<code>0x03</code>	<code>gt:globaltype</code> \Rightarrow <code>global</code> <code>gt</code>

5.4 Instructions

[Instructions](#) are encoded by *opcodes*. Each opcode is represented by a single byte, and is followed by the instruction's immediate arguments, where present. The only exception are [structured control instructions](#), which consist of several opcodes bracketing their nested instruction sequences.

Note: Gaps in the byte code ranges for encoding instructions are reserved for future extensions.

5.4.1 Control Instructions

[Control instructions](#) have varying encodings. For structured instructions, the instruction sequences forming nested blocks are terminated with explicit opcodes for end and else.

[Block types](#) are encoded in special compressed form, by either the byte 0x40 indicating the empty type, as a single value type, or as a [type index](#) encoded as a positive [signed integer](#).

<code>blocktype</code>	<code>::=</code>	<code>0x40</code>	\Rightarrow	ϵ	
		<code> </code>	<code>t:valtype</code>	\Rightarrow	<code>t</code>
		<code> </code>	<code>i:s33</code>	\Rightarrow	<code>i</code> if $i \geq 0$
<code>instr</code>	<code>::=</code>	<code>0x00</code>	\Rightarrow	<code>unreachable</code>	
		<code> </code>	<code>0x01</code>	\Rightarrow	<code>nop</code>
		<code> </code>	<code>0x02</code> <code>bt:blocktype</code> <code>(in:instr)*</code> <code>0x0B</code>	\Rightarrow	<code>block</code> <code>bt</code> <code>in*</code>
		<code> </code>	<code>0x03</code> <code>bt:blocktype</code> <code>(in:instr)*</code> <code>0x0B</code>	\Rightarrow	<code>loop</code> <code>bt</code> <code>in*</code>
		<code> </code>	<code>0x04</code> <code>bt:blocktype</code> <code>(in:instr)*</code> <code>0x0B</code>	\Rightarrow	<code>if</code> <code>bt</code> <code>in*</code> <code>else</code> ϵ
		<code> </code>	<code>0x04</code> <code>bt:blocktype</code> <code>(in₁:instr)*</code>		
		<code> </code>	<code>0x05</code> <code>(in₂:instr)*</code> <code>0x0B</code>	\Rightarrow	<code>if</code> <code>bt</code> <code>in₁*</code> <code>else</code> <code>in₂*</code>
		<code> </code>	<code>0x0C</code> <code>l:labelidx</code>	\Rightarrow	<code>br</code> <code>l</code>
		<code> </code>	<code>0x0D</code> <code>l:labelidx</code>	\Rightarrow	<code>br_if</code> <code>l</code>
		<code> </code>	<code>0x0E</code> <code>l*:list(labelidx)</code> <code>l_n:labelidx</code>	\Rightarrow	<code>br_table</code> <code>l*</code> <code>l_n</code>
		<code> </code>	<code>0x0F</code>	\Rightarrow	<code>return</code>
		<code> </code>	<code>0x10</code> <code>x:funcidx</code>	\Rightarrow	<code>call</code> <code>x</code>
		<code> </code>	<code>0x11</code> <code>y:typeidx</code> <code>x:tableidx</code>	\Rightarrow	<code>call_indirect</code> <code>x</code> <code>y</code>
		<code> </code>	<code>0x12</code> <code>x:funcidx</code>	\Rightarrow	<code>return_call</code> <code>x</code>
		<code> </code>	<code>0x13</code> <code>y:typeidx</code> <code>x:tableidx</code>	\Rightarrow	<code>return_call_indirect</code> <code>x</code> <code>y</code>
		<code> </code>	<code>...</code>		

Note: The else opcode 0x05 in the encoding of an if instruction can be omitted if the following instruction sequence is empty.

Unlike any other occurrence, the type index in a block type is encoded as a positive signed integer, so that its signed LEB128 bit pattern cannot collide with the encoding of value types or the special code 0x40, which correspond to the LEB128 encoding of negative integers. To avoid any loss in the range of allowed indices, it is treated as a 33 bit signed integer.

5.4.2 Reference Instructions

Generic reference instructions are represented by single byte codes, others use prefixes and type operands.

<code>instr ::=</code>	<code>...</code>	
	<code>0xD0 <i>ht</i>:heaptypes</code>	\Rightarrow <code>ref.null <i>ht</i></code>
	<code>0xD1</code>	\Rightarrow <code>ref.is_null</code>
	<code>0xD2 <i>x</i>:funcidx</code>	\Rightarrow <code>ref.func <i>x</i></code>
	<code>0xD3</code>	\Rightarrow <code>ref.eq</code>
	<code>0xD4</code>	\Rightarrow <code>ref.as_non_null</code>
	<code>0xD5 <i>l</i>:labelidx</code>	\Rightarrow <code>br_on_null <i>l</i></code>
	<code>0xD6 <i>l</i>:labelidx</code>	\Rightarrow <code>br_on_non_null <i>l</i></code>
	<code>0xFB 0:u32 <i>x</i>:typeidx</code>	\Rightarrow <code>struct.new <i>x</i></code>
	<code>0xFB 1:u32 <i>x</i>:typeidx</code>	\Rightarrow <code>struct.new_default <i>x</i></code>
	<code>0xFB 2:u32 <i>x</i>:typeidx <i>i</i>:u32</code>	\Rightarrow <code>struct.get <i>x</i> <i>i</i></code>
	<code>0xFB 3:u32 <i>x</i>:typeidx <i>i</i>:u32</code>	\Rightarrow <code>struct.get_s <i>x</i> <i>i</i></code>
	<code>0xFB 4:u32 <i>x</i>:typeidx <i>i</i>:u32</code>	\Rightarrow <code>struct.get_u <i>x</i> <i>i</i></code>
	<code>0xFB 5:u32 <i>x</i>:typeidx <i>i</i>:u32</code>	\Rightarrow <code>struct.set <i>x</i> <i>i</i></code>
	<code>0xFB 6:u32 <i>x</i>:typeidx</code>	\Rightarrow <code>array.new <i>x</i></code>
	<code>0xFB 7:u32 <i>x</i>:typeidx</code>	\Rightarrow <code>array.new_default <i>x</i></code>
	<code>0xFB 8:u32 <i>x</i>:typeidx <i>n</i>:u32</code>	\Rightarrow <code>array.new_fixed <i>x</i> <i>n</i></code>
	<code>0xFB 9:u32 <i>x</i>:typeidx <i>y</i>:dataidx</code>	\Rightarrow <code>array.new_data <i>x</i> <i>y</i></code>
	<code>0xFB 10:u32 <i>x</i>:typeidx <i>y</i>:elemidx</code>	\Rightarrow <code>array.new_elem <i>x</i> <i>y</i></code>
	<code>0xFB 11:u32 <i>x</i>:typeidx</code>	\Rightarrow <code>array.get <i>x</i></code>
	<code>0xFB 12:u32 <i>x</i>:typeidx</code>	\Rightarrow <code>array.get_s <i>x</i></code>
	<code>0xFB 13:u32 <i>x</i>:typeidx</code>	\Rightarrow <code>array.get_u <i>x</i></code>
	<code>0xFB 14:u32 <i>x</i>:typeidx</code>	\Rightarrow <code>array.set <i>x</i></code>
	<code>0xFB 15:u32</code>	\Rightarrow <code>array.len</code>
	<code>0xFB 16:u32 <i>x</i>:typeidx</code>	\Rightarrow <code>array.fill <i>x</i></code>
	<code>0xFB 17:u32 <i>x</i>₁:typeidx <i>x</i>₂:typeidx</code>	\Rightarrow <code>array.copy <i>x</i>₁ <i>x</i>₂</code>
	<code>0xFB 18:u32 <i>x</i>:typeidx <i>y</i>:dataidx</code>	\Rightarrow <code>array.init_data <i>x</i> <i>y</i></code>
	<code>0xFB 19:u32 <i>x</i>:typeidx <i>y</i>:elemidx</code>	\Rightarrow <code>array.init_elem <i>x</i> <i>y</i></code>
	<code>0xFB 20:u32 <i>ht</i>:heaptypes</code>	\Rightarrow <code>ref.test (ref <i>ht</i>)</code>
	<code>0xFB 21:u32 <i>ht</i>:heaptypes</code>	\Rightarrow <code>ref.test (ref null <i>ht</i>)</code>
	<code>0xFB 22:u32 <i>ht</i>:heaptypes</code>	\Rightarrow <code>ref.cast (ref <i>ht</i>)</code>
	<code>0xFB 23:u32 <i>ht</i>:heaptypes</code>	\Rightarrow <code>ref.cast (ref null <i>ht</i>)</code>
	<code>0xFB 24:u32 (null₁[?], null₂[?]):castop</code>	
	<code><i>l</i>:labelidx <i>ht</i>₁:heaptypes <i>ht</i>₂:heaptypes</code>	\Rightarrow <code>br_on_cast <i>l</i> (ref null₁[?] <i>ht</i>₁) (ref null₂[?] <i>ht</i>₂)</code>
	<code>0xFB 25:u32 (null₁[?], null₂[?]):castop</code>	
	<code><i>l</i>:labelidx <i>ht</i>₁:heaptypes <i>ht</i>₂:heaptypes</code>	\Rightarrow <code>br_on_cast_fail <i>l</i> (ref null₁[?] <i>ht</i>₁) (ref null₂[?] <i>ht</i>₂)</code>
	<code>0xFB 26:u32</code>	\Rightarrow <code>any.convert_extern</code>
	<code>0xFB 27:u32</code>	\Rightarrow <code>extern.convert_any</code>
	<code>0xFB 28:u32</code>	\Rightarrow <code>ref.i31</code>
	<code>0xFB 29:u32</code>	\Rightarrow <code>i31.get_s</code>
	<code>0xFB 30:u32</code>	\Rightarrow <code>i31.get_u</code>
	<code>...</code>	
<code>castop ::=</code>	<code>0x00</code>	\Rightarrow (ϵ, ϵ)
	<code>0x01</code>	\Rightarrow (null, ϵ)
	<code>0x02</code>	\Rightarrow (ϵ, null)
	<code>0x03</code>	\Rightarrow $(\text{null}, \text{null})$

5.4.3 Parametric Instructions

Parametric instructions are represented by single byte codes, possibly followed by a type annotation.

```
instr ::= ...
      | 0x1A                               ⇒ drop
      | 0x1B                               ⇒ select
      | 0x1C ts:list(valtype)           ⇒ select ts
      | ...
```

5.4.4 Variable Instructions

Variable instructions are represented by byte codes followed by the encoding of the respective `index`.

```
instr ::= ...
      | 0x20 x:localidx ⇒ local.get x
      | 0x21 x:localidx ⇒ local.set x
      | 0x22 x:localidx ⇒ local.tee x
      | 0x23 x:globalidx ⇒ global.get x
      | 0x24 x:globalidx ⇒ global.set x
      | ...
```

5.4.5 Table Instructions

Table instructions are represented either by a single byte or a one byte prefix followed by a variable-length `unsigned integer`.

```
instr ::= ...
      | 0x25 x:tableidx ⇒ table.get x
      | 0x26 x:tableidx ⇒ table.set x
      | 0xFC 12:u32 y:elemidx x:tableidx ⇒ table.init x y
      | 0xFC 13:u32 x:elemidx ⇒ elem.drop x
      | 0xFC 14:u32 x1:tableidx x2:tableidx ⇒ table.copy x1 x2
      | 0xFC 15:u32 x:tableidx ⇒ table.grow x
      | 0xFC 16:u32 x:tableidx ⇒ table.size x
      | 0xFC 17:u32 x:tableidx ⇒ table.fill x
      | ...
```

5.4.6 Memory Instructions

Each variant of `memory instruction` is encoded with a different byte code. Loads and stores are followed by the encoding of their `memory` immediate, which includes the `memory index` if bit 6 of the flags field containing alignment is set; the memory index defaults to 0 otherwise.

<code>memarg ::=</code>	<code>n:u32 m:u32</code>	\Rightarrow	$(0, \{\text{align } n, \text{offset } m\})$	if $n < 2^6$
	<code> n:u32 x:memidx m:u32</code>	\Rightarrow	$(x, \{\text{align } (n - 2^6), \text{offset } m\})$	if $2^6 \leq n < 2^7$
<code>instr ::=</code>	<code>...</code>			
	<code> 0x28 (x, ao):memarg</code>	\Rightarrow	<code>i32.load x ao</code>	
	<code> 0x29 (x, ao):memarg</code>	\Rightarrow	<code>i64.load x ao</code>	
	<code> 0x2A (x, ao):memarg</code>	\Rightarrow	<code>f32.load x ao</code>	
	<code> 0x2B (x, ao):memarg</code>	\Rightarrow	<code>f64.load x ao</code>	
	<code> 0x2C (x, ao):memarg</code>	\Rightarrow	<code>i32.load8 s x ao</code>	
	<code> 0x2D (x, ao):memarg</code>	\Rightarrow	<code>i32.load8 u x ao</code>	
	<code> 0x2E (x, ao):memarg</code>	\Rightarrow	<code>i32.load16 s x ao</code>	
	<code> 0x2F (x, ao):memarg</code>	\Rightarrow	<code>i32.load16 u x ao</code>	
	<code> 0x30 (x, ao):memarg</code>	\Rightarrow	<code>i64.load8 s x ao</code>	
	<code> 0x31 (x, ao):memarg</code>	\Rightarrow	<code>i64.load8 u x ao</code>	
	<code> 0x32 (x, ao):memarg</code>	\Rightarrow	<code>i64.load16 s x ao</code>	
	<code> 0x33 (x, ao):memarg</code>	\Rightarrow	<code>i64.load16 u x ao</code>	
	<code> 0x34 (x, ao):memarg</code>	\Rightarrow	<code>i64.load32 s x ao</code>	
	<code> 0x35 (x, ao):memarg</code>	\Rightarrow	<code>i64.load32 u x ao</code>	
	<code> 0x36 (x, ao):memarg</code>	\Rightarrow	<code>i32.store x ao</code>	
	<code> 0x37 (x, ao):memarg</code>	\Rightarrow	<code>i64.store x ao</code>	
	<code> 0x38 (x, ao):memarg</code>	\Rightarrow	<code>f32.store x ao</code>	
	<code> 0x39 (x, ao):memarg</code>	\Rightarrow	<code>f64.store x ao</code>	
	<code> 0x3A (x, ao):memarg</code>	\Rightarrow	<code>i32.store8 x ao</code>	
	<code> 0x3B (x, ao):memarg</code>	\Rightarrow	<code>i32.store16 x ao</code>	
	<code> 0x3C (x, ao):memarg</code>	\Rightarrow	<code>i64.store8 x ao</code>	
	<code> 0x3D (x, ao):memarg</code>	\Rightarrow	<code>i64.store16 x ao</code>	
	<code> 0x3E (x, ao):memarg</code>	\Rightarrow	<code>i64.store32 x ao</code>	
	<code> 0x3F x:memidx</code>	\Rightarrow	<code>memory.size x</code>	
	<code> 0x40 x:memidx</code>	\Rightarrow	<code>memory.grow x</code>	
	<code> 0xFC 8:u32 y:dataidx x:memidx</code>	\Rightarrow	<code>memory.init x y</code>	
	<code> 0xFC 9:u32 x:dataidx</code>	\Rightarrow	<code>data.drop x</code>	
	<code> 0xFC 10:u32 x₁:memidx x₂:memidx</code>	\Rightarrow	<code>memory.copy x₁ x₂</code>	
	<code> 0xFC 11:u32 x:memidx</code>	\Rightarrow	<code>memory.fill x</code>	
	<code> ...</code>			

5.4.7 Numeric Instructions

All variants of [numeric instructions](#) are represented by separate byte codes.

The const instructions are followed by the respective literal.

<code>instr ::=</code>	<code>...</code>
	<code> 0x41 n:u32 \Rightarrow i32.const n</code>
	<code> 0x42 n:u64 \Rightarrow i64.const n</code>
	<code> 0x43 p:f32 \Rightarrow f32.const p</code>
	<code> 0x44 p:f64 \Rightarrow f64.const p</code>
	<code> ...</code>

All other numeric instructions are plain opcodes without any immediates.

```
instr ::= ...
      | 0x45 ⇒ i32.eqz
      | 0x46 ⇒ i32.eq
      | 0x47 ⇒ i32.ne
      | 0x48 ⇒ i32.lt_s
      | 0x49 ⇒ i32.lt_u
      | 0x4A ⇒ i32.gt_s
      | 0x4B ⇒ i32.gt_u
      | 0x4C ⇒ i32.le_s
      | 0x4D ⇒ i32.le_u
      | 0x4E ⇒ i32.ge_s
      | 0x4F ⇒ i32.ge_u
      | 0x50 ⇒ i64.eqz
      | 0x51 ⇒ i64.eq
      | 0x52 ⇒ i64.ne
      | 0x53 ⇒ i64.lt_s
      | 0x54 ⇒ i64.lt_u
      | 0x55 ⇒ i64.gt_s
      | 0x56 ⇒ i64.gt_u
      | 0x57 ⇒ i64.le_s
      | 0x58 ⇒ i64.le_u
      | 0x59 ⇒ i64.ge_s
      | 0x5A ⇒ i64.ge_u
      | ...

instr ::= ...
      | 0x5B ⇒ f32.eq
      | 0x5C ⇒ f32.ne
      | 0x5D ⇒ f32.lt
      | 0x5E ⇒ f32.gt
      | 0x5F ⇒ f32.le
      | 0x60 ⇒ f32.ge
      | 0x61 ⇒ f64.eq
      | 0x62 ⇒ f64.ne
      | 0x63 ⇒ f64.lt
      | 0x64 ⇒ f64.gt
      | 0x65 ⇒ f64.le
      | 0x66 ⇒ f64.ge
      | ...
```

```
instr ::= ...  
      | 0x67 ⇒ i32.clz  
      | 0x68 ⇒ i32.ctz  
      | 0x69 ⇒ i32.popcnt  
      | 0x6A ⇒ i32.add  
      | 0x6B ⇒ i32.sub  
      | 0x6C ⇒ i32.mul  
      | 0x6D ⇒ i32.div_s  
      | 0x6E ⇒ i32.div_u  
      | 0x6F ⇒ i32.rem_s  
      | 0x70 ⇒ i32.rem_u  
      | 0x71 ⇒ i32.and  
      | 0x72 ⇒ i32.or  
      | 0x73 ⇒ i32.xor  
      | 0x74 ⇒ i32.shl  
      | 0x75 ⇒ i32.shr_s  
      | 0x76 ⇒ i32.shr_u  
      | 0x77 ⇒ i32.rotl  
      | 0x78 ⇒ i32.rotr  
      | 0x79 ⇒ i64.clz  
      | 0x7A ⇒ i64.ctz  
      | 0x7B ⇒ i64.popcnt  
      | 0x7C ⇒ i64.add  
      | 0x7D ⇒ i64.sub  
      | 0x7E ⇒ i64.mul  
      | 0x7F ⇒ i64.div_s  
      | 0x80 ⇒ i64.div_u  
      | 0x81 ⇒ i64.rem_s  
      | 0x82 ⇒ i64.rem_u  
      | 0x83 ⇒ i64.and  
      | 0x84 ⇒ i64.or  
      | 0x85 ⇒ i64.xor  
      | 0x86 ⇒ i64.shl  
      | 0x87 ⇒ i64.shr_s  
      | 0x88 ⇒ i64.shr_u  
      | 0x89 ⇒ i64.rotl  
      | 0x8A ⇒ i64.rotr  
      | ...
```

```

instr ::= ...
    | 0x8B ⇒ f32.abs
    | 0x8C ⇒ f32.neg
    | 0x8D ⇒ f32.ceil
    | 0x8E ⇒ f32.floor
    | 0x8F ⇒ f32.trunc
    | 0x90 ⇒ f32.nearest
    | 0x91 ⇒ f32.sqrt
    | 0x92 ⇒ f32.add
    | 0x93 ⇒ f32.sub
    | 0x94 ⇒ f32.mul
    | 0x95 ⇒ f32.div
    | 0x96 ⇒ f32.min
    | 0x97 ⇒ f32.max
    | 0x98 ⇒ f32.copysign
    | 0x99 ⇒ f64.abs
    | 0x9A ⇒ f64.neg
    | 0x9B ⇒ f64.ceil
    | 0x9C ⇒ f64.floor
    | 0x9D ⇒ f64.trunc
    | 0x9E ⇒ f64.nearest
    | 0x9F ⇒ f64.sqrt
    | 0xA0 ⇒ f64.add
    | 0xA1 ⇒ f64.sub
    | 0xA2 ⇒ f64.mul
    | 0xA3 ⇒ f64.div
    | 0xA4 ⇒ f64.min
    | 0xA5 ⇒ f64.max
    | 0xA6 ⇒ f64.copysign
    | ...

instr ::= ...
    | 0xA7 ⇒ i32.convert_i64
    | 0xA8 ⇒ i32.convert_f32_s
    | 0xA9 ⇒ i32.convert_f32_u
    | 0xAA ⇒ i32.convert_f64_s
    | 0xAB ⇒ i32.convert_f64_u
    | 0xAC ⇒ i64.convert_i32_s
    | 0xAD ⇒ i64.convert_i32_u
    | 0xAE ⇒ i64.convert_f32_s
    | 0xAF ⇒ i64.convert_f32_u
    | 0xB0 ⇒ i64.convert_f64_s
    | 0xB1 ⇒ i64.convert_f64_u
    | 0xB2 ⇒ f32.convert_i32_s
    | 0xB3 ⇒ f32.convert_i32_u
    | 0xB4 ⇒ f32.convert_i64_s
    | 0xB5 ⇒ f32.convert_i64_u
    | 0xB6 ⇒ f32.convert_f64
    | 0xB7 ⇒ f64.convert_i32_s
    | 0xB8 ⇒ f64.convert_i32_u
    | 0xB9 ⇒ f64.convert_i64_s
    | 0xBA ⇒ f64.convert_i64_u
    | 0xBB ⇒ f64.convert_f32
    | 0xBC ⇒ i32.reinterpret_f32
    | 0xBD ⇒ i64.reinterpret_f64
    | 0xBE ⇒ f32.reinterpret_i32
    | 0xBF ⇒ f64.reinterpret_i64
    | ...

```

```

instr ::= ...
      | 0xC0 ⇒ i32.extend8_s
      | 0xC1 ⇒ i32.extend16_s
      | 0xC2 ⇒ i64.extend8_s
      | 0xC3 ⇒ i64.extend16_s
      | 0xC4 ⇒ i64.extend32_s
      | ...

```

The saturating truncation instructions all have a one byte prefix, whereas the actual opcode is encoded by a variable-length [unsigned integer](#).

```

instr ::= ...
      | 0xFC 0:u32 ⇒ i32.convert_sat_f32_s
      | 0xFC 1:u32 ⇒ i32.convert_sat_f32_u
      | 0xFC 2:u32 ⇒ i32.convert_sat_f64_s
      | 0xFC 3:u32 ⇒ i32.convert_sat_f64_u
      | 0xFC 4:u32 ⇒ i64.convert_sat_f32_s
      | 0xFC 5:u32 ⇒ i64.convert_sat_f32_u
      | 0xFC 6:u32 ⇒ i64.convert_sat_f64_s
      | 0xFC 7:u32 ⇒ i64.convert_sat_f64_u
      | ...

```

5.4.8 Vector Instructions

All variants of [vector instructions](#) are represented by separate byte codes. They all have a one byte prefix, whereas the actual opcode is encoded by a variable-length [unsigned integer](#).

Vector loads and stores are followed by the encoding of their *memarg* immediate.

```

laneidx ::= l:byte ⇒ l
instr ::= ...
      | 0xFD 0:u32 (x, ao):memarg ⇒ v128.load x ao
      | 0xFD 1:u32 (x, ao):memarg ⇒ v128.load8x8_s x ao
      | 0xFD 2:u32 (x, ao):memarg ⇒ v128.load8x8_u x ao
      | 0xFD 3:u32 (x, ao):memarg ⇒ v128.load16x4_s x ao
      | 0xFD 4:u32 (x, ao):memarg ⇒ v128.load16x4_u x ao
      | 0xFD 5:u32 (x, ao):memarg ⇒ v128.load32x2_s x ao
      | 0xFD 6:u32 (x, ao):memarg ⇒ v128.load32x2_u x ao
      | 0xFD 7:u32 (x, ao):memarg ⇒ v128.load8_splat x ao
      | 0xFD 8:u32 (x, ao):memarg ⇒ v128.load16_splat x ao
      | 0xFD 9:u32 (x, ao):memarg ⇒ v128.load32_splat x ao
      | 0xFD 10:u32 (x, ao):memarg ⇒ v128.load64_splat x ao
      | 0xFD 11:u32 (x, ao):memarg ⇒ v128.store x ao
      | 0xFD 84:u32 (x, ao):memarg l:laneidx ⇒ v128.load8_lane x ao l
      | 0xFD 85:u32 (x, ao):memarg l:laneidx ⇒ v128.load16_lane x ao l
      | 0xFD 86:u32 (x, ao):memarg l:laneidx ⇒ v128.load32_lane x ao l
      | 0xFD 87:u32 (x, ao):memarg l:laneidx ⇒ v128.load64_lane x ao l
      | 0xFD 88:u32 (x, ao):memarg l:laneidx ⇒ v128.store8_lane x ao l
      | 0xFD 89:u32 (x, ao):memarg l:laneidx ⇒ v128.store16_lane x ao l
      | 0xFD 90:u32 (x, ao):memarg l:laneidx ⇒ v128.store32_lane x ao l
      | 0xFD 91:u32 (x, ao):memarg l:laneidx ⇒ v128.store64_lane x ao l
      | 0xFD 92:u32 (x, ao):memarg ⇒ v128.load32_zero x ao
      | 0xFD 93:u32 (x, ao):memarg ⇒ v128.load64_zero x ao
      | ...

```

The const instruction for vectors is followed by 16 immediate bytes, which are converted into an *i128* in [littleendian](#)

byte order:

```
instr ::= ...
      | 0xFD 12:u32 (b:byte)16 ⇒ v128.const bytes128-1((b)16)
      | ...
```

The shuffle instruction is also followed by the encoding of 16 *laneidx* immediates.

```
instr ::= ...
      | 0xFD 13:u32 (l:laneidx)16 ⇒ i8x16.shuffle l
      | 0xFD 14:u32                ⇒ i8x16.swizzle
      | ...
```

Lane instructions are followed by the encoding of a *laneidx* immediate.

```
instr ::= ...
      | 0xFD 21:u32 l:laneidx ⇒ i8x16.extract_lane_s l
      | 0xFD 22:u32 l:laneidx ⇒ i8x16.extract_lane_u l
      | 0xFD 23:u32 l:laneidx ⇒ i8x16.replace_lane l
      | 0xFD 24:u32 l:laneidx ⇒ i16x8.extract_lane_s l
      | 0xFD 25:u32 l:laneidx ⇒ i16x8.extract_lane_u l
      | 0xFD 26:u32 l:laneidx ⇒ i16x8.replace_lane l
      | 0xFD 27:u32 l:laneidx ⇒ i32x4.extract_lane l
      | 0xFD 28:u32 l:laneidx ⇒ i32x4.replace_lane l
      | 0xFD 29:u32 l:laneidx ⇒ i64x2.extract_lane l
      | 0xFD 30:u32 l:laneidx ⇒ i64x2.replace_lane l
      | 0xFD 31:u32 l:laneidx ⇒ f32x4.extract_lane l
      | 0xFD 32:u32 l:laneidx ⇒ f32x4.replace_lane l
      | 0xFD 33:u32 l:laneidx ⇒ f64x2.extract_lane l
      | 0xFD 34:u32 l:laneidx ⇒ f64x2.replace_lane l
      | ...
```

All other vector instructions are plain opcodes without any immediates.

```
instr ::= ...
      | 0xFD 15:u32 ⇒ i8x16.splat
      | 0xFD 16:u32 ⇒ i16x8.splat
      | 0xFD 17:u32 ⇒ i32x4.splat
      | 0xFD 18:u32 ⇒ i64x2.splat
      | 0xFD 19:u32 ⇒ f32x4.splat
      | 0xFD 20:u32 ⇒ f64x2.splat
      | ...
```

```

instr ::= ...
| 0xFD 35:u32 ⇒ i8x16.eq
| 0xFD 36:u32 ⇒ i8x16.ne
| 0xFD 37:u32 ⇒ i8x16.lt_s
| 0xFD 38:u32 ⇒ i8x16.lt_u
| 0xFD 39:u32 ⇒ i8x16.gt_s
| 0xFD 40:u32 ⇒ i8x16.gt_u
| 0xFD 41:u32 ⇒ i8x16.le_s
| 0xFD 42:u32 ⇒ i8x16.le_u
| 0xFD 43:u32 ⇒ i8x16.ge_s
| 0xFD 44:u32 ⇒ i8x16.ge_u
| 0xFD 45:u32 ⇒ i16x8.eq
| 0xFD 46:u32 ⇒ i16x8.ne
| 0xFD 47:u32 ⇒ i16x8.lt_s
| 0xFD 48:u32 ⇒ i16x8.lt_u
| 0xFD 49:u32 ⇒ i16x8.gt_s
| 0xFD 50:u32 ⇒ i16x8.gt_u
| 0xFD 51:u32 ⇒ i16x8.le_s
| 0xFD 52:u32 ⇒ i16x8.le_u
| 0xFD 53:u32 ⇒ i16x8.ge_s
| 0xFD 54:u32 ⇒ i16x8.ge_u
| 0xFD 55:u32 ⇒ i32x4.eq
| 0xFD 56:u32 ⇒ i32x4.ne
| 0xFD 57:u32 ⇒ i32x4.lt_s
| 0xFD 58:u32 ⇒ i32x4.lt_u
| 0xFD 59:u32 ⇒ i32x4.gt_s
| 0xFD 60:u32 ⇒ i32x4.gt_u
| 0xFD 61:u32 ⇒ i32x4.le_s
| 0xFD 62:u32 ⇒ i32x4.le_u
| 0xFD 63:u32 ⇒ i32x4.ge_s
| 0xFD 64:u32 ⇒ i32x4.ge_u
| 0xFD 214:u32 ⇒ i64x2.eq
| 0xFD 215:u32 ⇒ i64x2.ne
| 0xFD 216:u32 ⇒ i64x2.lt_s
| 0xFD 217:u32 ⇒ i64x2.gt_s
| 0xFD 218:u32 ⇒ i64x2.le_s
| 0xFD 219:u32 ⇒ i64x2.ge_s
| ...

```

```

instr ::= ...
| 0xFD 65:u32 ⇒ f32x4.eq
| 0xFD 66:u32 ⇒ f32x4.ne
| 0xFD 67:u32 ⇒ f32x4.lt
| 0xFD 68:u32 ⇒ f32x4.gt
| 0xFD 69:u32 ⇒ f32x4.le
| 0xFD 70:u32 ⇒ f32x4.ge
| 0xFD 71:u32 ⇒ f64x2.eq
| 0xFD 72:u32 ⇒ f64x2.ne
| 0xFD 73:u32 ⇒ f64x2.lt
| 0xFD 74:u32 ⇒ f64x2.gt
| 0xFD 75:u32 ⇒ f64x2.le
| 0xFD 76:u32 ⇒ f64x2.ge
| ...

```

```
instr ::= ...  
      | 0xFD 77:u32 ⇒ v128.not  
      | 0xFD 78:u32 ⇒ v128.and  
      | 0xFD 79:u32 ⇒ v128.andnot  
      | 0xFD 80:u32 ⇒ v128.or  
      | 0xFD 81:u32 ⇒ v128.xor  
      | 0xFD 82:u32 ⇒ v128.bitselect  
      | 0xFD 83:u32 ⇒ v128.any_true  
      | ...
```

```
instr ::= ...  
      | 0xFD 96:u32 ⇒ i8x16.abs  
      | 0xFD 97:u32 ⇒ i8x16.neg  
      | 0xFD 98:u32 ⇒ i8x16.popcnt  
      | 0xFD 99:u32 ⇒ i8x16.all_true  
      | 0xFD 100:u32 ⇒ i8x16.bitmask  
      | 0xFD 101:u32 ⇒ i8x16.narrow_i16x8_s  
      | 0xFD 102:u32 ⇒ i8x16.narrow_i16x8_u  
      | 0xFD 107:u32 ⇒ i8x16.shl  
      | 0xFD 108:u32 ⇒ i8x16.shr_s  
      | 0xFD 109:u32 ⇒ i8x16.shr_u  
      | 0xFD 110:u32 ⇒ i8x16.add  
      | 0xFD 111:u32 ⇒ i8x16.add_sat_s  
      | 0xFD 112:u32 ⇒ i8x16.add_sat_u  
      | 0xFD 113:u32 ⇒ i8x16.sub  
      | 0xFD 114:u32 ⇒ i8x16.sub_sat_s  
      | 0xFD 115:u32 ⇒ i8x16.sub_sat_u  
      | 0xFD 118:u32 ⇒ i8x16.min_s  
      | 0xFD 119:u32 ⇒ i8x16.min_u  
      | 0xFD 120:u32 ⇒ i8x16.max_s  
      | 0xFD 121:u32 ⇒ i8x16.max_u  
      | 0xFD 123:u32 ⇒ i8x16.avgr_u  
      | ...
```



```

instr ::= ...
      | 0xFD 124:u32 ⇒ i16x8.extadd_pairwise_i8x16_s
      | 0xFD 125:u32 ⇒ i16x8.extadd_pairwise_i8x16_u
      | 0xFD 128:u32 ⇒ i16x8.abs
      | 0xFD 129:u32 ⇒ i16x8.neg
      | 0xFD 131:u32 ⇒ i16x8.all_true
      | 0xFD 132:u32 ⇒ i16x8.bitmask
      | 0xFD 133:u32 ⇒ i16x8.narrow_i32x4_s
      | 0xFD 134:u32 ⇒ i16x8.narrow_i32x4_u
      | 0xFD 135:u32 ⇒ i16x8.extend_s_i8x16_low
      | 0xFD 136:u32 ⇒ i16x8.extend_s_i8x16_high
      | 0xFD 137:u32 ⇒ i16x8.extend_u_i8x16_low
      | 0xFD 138:u32 ⇒ i16x8.extend_u_i8x16_high
      | 0xFD 139:u32 ⇒ i16x8.shl
      | 0xFD 140:u32 ⇒ i16x8.shr_s
      | 0xFD 141:u32 ⇒ i16x8.shr_u
      | 0xFD 130:u32 ⇒ i16x8.q15mulr_sat_s
      | 0xFD 142:u32 ⇒ i16x8.add
      | 0xFD 143:u32 ⇒ i16x8.add_sat_s
      | 0xFD 144:u32 ⇒ i16x8.add_sat_u
      | 0xFD 145:u32 ⇒ i16x8.sub
      | 0xFD 146:u32 ⇒ i16x8.sub_sat_s
      | 0xFD 147:u32 ⇒ i16x8.sub_sat_u
      | 0xFD 149:u32 ⇒ i16x8.mul
      | 0xFD 150:u32 ⇒ i16x8.min_s
      | 0xFD 151:u32 ⇒ i16x8.min_u
      | 0xFD 152:u32 ⇒ i16x8.max_s
      | 0xFD 153:u32 ⇒ i16x8.max_u
      | 0xFD 155:u32 ⇒ i16x8.avgr_u
      | 0xFD 156:u32 ⇒ i16x8.extmul_low_i8x16_s
      | 0xFD 157:u32 ⇒ i16x8.extmul_high_i8x16_s
      | 0xFD 158:u32 ⇒ i16x8.extmul_low_i8x16_u
      | 0xFD 159:u32 ⇒ i16x8.extmul_high_i8x16_u
      | ...

```

```

instr ::= ...
| 0xFD 126:u32 ⇒ i32x4.extadd_pairwise_i16x8_s
| 0xFD 127:u32 ⇒ i32x4.extadd_pairwise_i16x8_u
| 0xFD 160:u32 ⇒ i32x4.abs
| 0xFD 161:u32 ⇒ i32x4.neg
| 0xFD 163:u32 ⇒ i32x4.all_true
| 0xFD 164:u32 ⇒ i32x4.bitmask
| 0xFD 167:u32 ⇒ i32x4.extend_s_i16x8_low
| 0xFD 168:u32 ⇒ i32x4.extend_s_i16x8_high
| 0xFD 169:u32 ⇒ i32x4.extend_u_i16x8_low
| 0xFD 170:u32 ⇒ i32x4.extend_u_i16x8_high
| 0xFD 171:u32 ⇒ i32x4.shl
| 0xFD 172:u32 ⇒ i32x4.shr_s
| 0xFD 173:u32 ⇒ i32x4.shr_u
| 0xFD 174:u32 ⇒ i32x4.add
| 0xFD 177:u32 ⇒ i32x4.sub
| 0xFD 181:u32 ⇒ i32x4.mul
| 0xFD 182:u32 ⇒ i32x4.min_s
| 0xFD 183:u32 ⇒ i32x4.min_u
| 0xFD 184:u32 ⇒ i32x4.max_s
| 0xFD 185:u32 ⇒ i32x4.max_u
| 0xFD 186:u32 ⇒ i32x4.dot_i16x8_s
| 0xFD 188:u32 ⇒ i32x4.extmul_low_i16x8_s
| 0xFD 189:u32 ⇒ i32x4.extmul_high_i16x8_s
| 0xFD 190:u32 ⇒ i32x4.extmul_low_i16x8_u
| 0xFD 191:u32 ⇒ i32x4.extmul_high_i16x8_u
| ...

instr ::= ...
| 0xFD 192:u32 ⇒ i64x2.abs
| 0xFD 193:u32 ⇒ i64x2.neg
| 0xFD 195:u32 ⇒ i64x2.all_true
| 0xFD 196:u32 ⇒ i64x2.bitmask
| 0xFD 199:u32 ⇒ i64x2.extend_s_i32x4_low
| 0xFD 200:u32 ⇒ i64x2.extend_s_i32x4_high
| 0xFD 201:u32 ⇒ i64x2.extend_u_i32x4_low
| 0xFD 202:u32 ⇒ i64x2.extend_u_i32x4_high
| 0xFD 203:u32 ⇒ i64x2.shl
| 0xFD 204:u32 ⇒ i64x2.shr_s
| 0xFD 205:u32 ⇒ i64x2.shr_u
| 0xFD 206:u32 ⇒ i64x2.add
| 0xFD 209:u32 ⇒ i64x2.sub
| 0xFD 213:u32 ⇒ i64x2.mul
| 0xFD 220:u32 ⇒ i64x2.extmul_low_i32x4_s
| 0xFD 221:u32 ⇒ i64x2.extmul_high_i32x4_s
| 0xFD 222:u32 ⇒ i64x2.extmul_low_i32x4_u
| 0xFD 223:u32 ⇒ i64x2.extmul_high_i32x4_u
| ...

```

```

instr ::= ...
      | 0xFD 103:u32 ⇒ f32x4.ceil
      | 0xFD 104:u32 ⇒ f32x4.floor
      | 0xFD 105:u32 ⇒ f32x4.trunc
      | 0xFD 106:u32 ⇒ f32x4.nearest
      | 0xFD 224:u32 ⇒ f32x4.abs
      | 0xFD 225:u32 ⇒ f32x4.neg
      | 0xFD 227:u32 ⇒ f32x4.sqrt
      | 0xFD 228:u32 ⇒ f32x4.add
      | 0xFD 229:u32 ⇒ f32x4.sub
      | 0xFD 230:u32 ⇒ f32x4.mul
      | 0xFD 231:u32 ⇒ f32x4.div
      | 0xFD 232:u32 ⇒ f32x4.min
      | 0xFD 233:u32 ⇒ f32x4.max
      | 0xFD 234:u32 ⇒ f32x4.pmin
      | 0xFD 235:u32 ⇒ f32x4.pmax
      | ...

instr ::= ...
      | 0xFD 116:u32 ⇒ f64x2.ceil
      | 0xFD 117:u32 ⇒ f64x2.floor
      | 0xFD 122:u32 ⇒ f64x2.trunc
      | 0xFD 148:u32 ⇒ f64x2.nearest
      | 0xFD 236:u32 ⇒ f64x2.abs
      | 0xFD 237:u32 ⇒ f64x2.neg
      | 0xFD 239:u32 ⇒ f64x2.sqrt
      | 0xFD 240:u32 ⇒ f64x2.add
      | 0xFD 241:u32 ⇒ f64x2.sub
      | 0xFD 242:u32 ⇒ f64x2.mul
      | 0xFD 243:u32 ⇒ f64x2.div
      | 0xFD 244:u32 ⇒ f64x2.min
      | 0xFD 245:u32 ⇒ f64x2.max
      | 0xFD 246:u32 ⇒ f64x2.pmin
      | 0xFD 247:u32 ⇒ f64x2.pmax
      | ...

instr ::= ...
      | 0xFD 94:u32 ⇒ f32x4.demote_f64x2_zero
      | 0xFD 95:u32 ⇒ f64x2.promote_f32x4_low
      | 0xFD 248:u32 ⇒ i32x4.trunc_sat_f32x4_s
      | 0xFD 249:u32 ⇒ i32x4.trunc_sat_f32x4_u
      | 0xFD 250:u32 ⇒ f32x4.convert_i32x4_s
      | 0xFD 251:u32 ⇒ f32x4.convert_i32x4_u
      | 0xFD 252:u32 ⇒ i32x4.trunc_sat_zero_f64x2_s
      | 0xFD 253:u32 ⇒ i32x4.trunc_sat_zero_f64x2_u
      | 0xFD 254:u32 ⇒ f64x2.convert_s_i32x4_low
      | 0xFD 255:u32 ⇒ f64x2.convert_u_i32x4_low

```

5.4.9 Expressions

Expressions are encoded by their instruction sequence terminated with an explicit 0x0B opcode for end.

$$\text{expr} ::= (in:instr)^* 0x0B \Rightarrow in^*$$

5.5 Modules

The binary encoding of modules is organized into *sections*. Most sections correspond to one component of a `module` record, except that `function definitions` are split into two sections, separating their type declarations in the `function section` from their bodies in the `code section`.

Note: This separation enables *parallel* and *streaming* compilation of the functions in a module.

5.5.1 Indices

All basic **indices** are encoded with their respective value.

typeid _x	::=	<i>x</i> :u32	⇒	<i>x</i>
funcid _x	::=	<i>x</i> :u32	⇒	<i>x</i>
tableid _x	::=	<i>x</i> :u32	⇒	<i>x</i>
memid _x	::=	<i>x</i> :u32	⇒	<i>x</i>
globalid _x	::=	<i>x</i> :u32	⇒	<i>x</i>
elemid _x	::=	<i>x</i> :u32	⇒	<i>x</i>
dataid _x	::=	<i>x</i> :u32	⇒	<i>x</i>
localid _x	::=	<i>x</i> :u32	⇒	<i>x</i>
labelid _x	::=	<i>l</i> :u32	⇒	<i>l</i>

External indices are encoded by a distinguishing byte followed by an encoding of their respective value.

externidx	::=	0x00	x :funcidx	\Rightarrow	func x
		0x01	x :tableidx	\Rightarrow	table x
		0x02	x :memidx	\Rightarrow	memory x
		0x03	x :globalidx	\Rightarrow	global x

5.5.2 Sections

Each section consists of

- a one-byte section *id*,
- the *length* of the contents, in bytes,
- the actual *contents*, whose structure is dependent on the section *id*.

Every section is optional; an omitted section is equivalent to the section being present with empty contents.

The following parameterized grammar rule defines the generic structure of a section with id N and contents described by the grammar X .

$$\text{section}_N(\mathbf{X}) ::= N:\text{byte } len:\text{u32 } en^*: \mathbf{X} \Rightarrow en^* \quad \text{if } len = ||\mathbf{X}||$$

$$| \epsilon \Rightarrow \epsilon$$

For most sections, the contents X encodes a [list](#). In these cases, the empty result ϵ is interpreted as the empty list.

Note: Other than for unknown [custom sections](#), the *size* is not required for decoding, but can be used to skip sections when navigating through a binary. The module is malformed if the size does not match the length of the binary contents *X*.

The following section ids are used:

Id	Section
0	custom section
1	type section
2	import section
3	function section
4	table section
5	memory section
6	global section
7	export section
8	start section
9	element section
10	code section
11	data section
12	data count section

Note: Section ids do not always correspond to the [order of sections](#) in the encoding of a module.

5.5.3 Custom Section

Custom sections have the id 0. They are intended to be used for debugging information or third-party extensions, and are ignored by the WebAssembly semantics. Their contents consist of a [name](#) further identifying the custom section, followed by an uninterpreted sequence of bytes for custom use.

```
customsec ::= section0(custom)
custom   ::= name byte*
```

Note: If an implementation interprets the data of a custom section, then errors in that data, or the placement of the section, must not invalidate the module.

5.5.4 Type Section

The *type section* has the id 1. It decodes into the list of [recursive types](#) of a [module](#).

```
typesec ::= ty*:section1(list(type)) ⇒ ty*
type    ::= qt:rectype                ⇒ type qt
```

5.5.5 Import Section

The *import section* has the id 2. It decodes into the list of **imports** of a **module**.

$$\begin{aligned}
\text{importsec} &::= im^*:\text{section}_2(\text{list}(\text{import})) &\Rightarrow im^* \\
\text{import} &::= nm_1:\text{name } nm_2:\text{name } xt:\text{externtype} &\Rightarrow \text{import } nm_1 \text{ } nm_2 \text{ } xt
\end{aligned}$$

5.5.6 Function Section

The *function section* has the id 3. It decodes into a list of **type indices** that classify the **functions** of a **module**. The bodies of the respective functions are encoded separately in the **code section**.

$$\text{funcsec} ::= x^*:\text{section}_3(\text{list}(\text{typeid})) \Rightarrow x^*$$

5.5.7 Table Section

The *table section* has the id 4. It decodes into the list of **tables** of a **module**.

$$\begin{aligned}
\text{tablesec} &::= tab^*:\text{section}_4(\text{list}(\text{table})) &\Rightarrow tab^* \\
\text{table} &::= tt:\text{tabletype} &\Rightarrow \text{table } tt \text{ (ref.null ht)} &\quad \text{if } tt = \text{lim (ref null? ht)} \\
&| 0x40 \text{ } 0x00 \text{ } tt:\text{tabletype } e:\text{expr} &\Rightarrow \text{table } tt \text{ } e
\end{aligned}$$

Note: The encoding of a table type cannot start with byte 0x40, hence decoding is unambiguous. The zero byte following it is reserved for future extensions.

5.5.8 Memory Section

The *memory section* has the id 5. It decodes into the list of **memories** of a **module**.

$$\begin{aligned}
\text{memsec} &::= mem^*:\text{section}_5(\text{list}(\text{mem})) &\Rightarrow mem^* \\
\text{mem} &::= mt:\text{memtype} &\Rightarrow \text{memory } mt
\end{aligned}$$

5.5.9 Global Section

The *global section* has the id 6. It decodes into the list of **globals** of a **module**.

$$\begin{aligned}
\text{globalsec} &::= glob^*:\text{section}_6(\text{list}(\text{global})) &\Rightarrow glob^* \\
\text{global} &::= gt:\text{globaltype } e:\text{expr} &\Rightarrow \text{global } gt \text{ } e
\end{aligned}$$

5.5.10 Export Section

The *export section* has the id 7. It decodes into the list of **exports** of a **module**.

$$\begin{aligned}
\text{exportsec} &::= ex^*:\text{section}_7(\text{list}(\text{export})) &\Rightarrow ex^* \\
\text{export} &::= nm:\text{name } xx:\text{externidx} &\Rightarrow \text{export } nm \text{ } xx
\end{aligned}$$

5.5.11 Start Section

The *start section* has the id 8. It decodes into the optional *start function* of a *module*.

```
startsec ::= start*:section8(start) ⇒ start*
start    ::= x:funcidx                ⇒ (start x)
```

5.5.12 Element Section

The *element section* has the id 9. It decodes into the list of *element segments* of a *module*.

```
elemsec ::= elem*:section9(list(elem)) ⇒ elem*
elemkind ::= 0x00                      ⇒ ref null func
elem     ::= 0:u32 eo:expr y*:list(funcidx) ⇒
              elem (ref func) (ref.func y)* (active 0 eo)
              | 1:u32 rt:elemkind y*:list(funcidx) ⇒
              elem rt (ref.func y)* passive
              | 2:u32 x:tableidx e:expr rt:elemkind y*:list(funcidx) ⇒
              elem rt (ref.func y)* (active x e)
              | 3:u32 rt:elemkind y*:list(funcidx) ⇒
              elem rt (ref.func y)* declare
              | 4:u32 eo:expr e*:list(expr) ⇒
              elem (ref null func) e* (active 0 eo)
              | 5:u32 rt:reftype e*:list(expr) ⇒
              elem rt e* passive
              | 6:u32 x:tableidx eo:expr e*:list(expr) ⇒
              elem (ref null func) e* (active x eo)
              | 7:u32 rt:reftype e*:list(expr) ⇒
              elem rt e* declare
```

Note: The initial integer can be interpreted as a bitfield. Bit 0 indicates a passive or declarative segment, bit 1 indicates the presence of an explicit table index for an active segment and otherwise distinguishes passive from declarative segments, bit 2 indicates the use of element type and element *expressions* instead of element kind and element indices.

Additional element kinds may be added in future versions of WebAssembly.

5.5.13 Code Section

The *code section* has the id 10. It decodes into the list of *code entries* that are pairs of lists of *locals* and *expressions*. They represent the body of the *functions* of a *module*. The types of the respective functions are encoded separately in the *function section*.

The encoding of each code entry consists of

- the *u32 length* of the function code in bytes,
- the actual *function code*, which in turn consists of
 - the declaration of *locals*,
 - the function *body* as an *expression*.

Local declarations are compressed into a list whose entries consist of

- a *u32 count*,
- a *value type*,

denoting *count* locals of the same value type.

<code>codesec</code>	<code>::=</code>	<code>code*:section₁₀(list(code))</code>	\Rightarrow	<code>code*</code>	
<code>code</code>	<code>::=</code>	<code>len:u32 code:func</code>	\Rightarrow	<code>code</code>	if $len = func $
<code>func</code>	<code>::=</code>	<code>loc*:list(locals) e:expr</code>	\Rightarrow	<code>(concat(loc*), e)</code>	if $ concat(loc*) < 2^{32}$
<code>locals</code>	<code>::=</code>	<code>n:u32 t:valtype</code>	\Rightarrow	<code>(local t)ⁿ</code>	

Here, *code* ranges over pairs (*local**, *expr*). Any code for which the length of the resulting sequence is out of bounds of the maximum size of a `list` is malformed.

Note: Like with `sections`, the code *size* is not needed for decoding, but can be used to skip functions when navigating through a binary. The module is malformed if a size does not match the length of the respective function code.

5.5.14 Data Section

The *data section* has the id 11. It decodes into the list of `data segments` of a `module`.

<code>datasec</code>	<code>::=</code>	<code>data*:section₁₁(list(data))</code>	\Rightarrow	<code>data*</code>
<code>data</code>	<code>::=</code>	<code>0:u32 e:expr b*:list(byte)</code>	\Rightarrow	<code>data b* (active 0 e)</code>
		<code> 1:u32 b*:list(byte)</code>	\Rightarrow	<code>data b* passive</code>
		<code> 2:u32 x:memidx e:expr b*:list(byte)</code>	\Rightarrow	<code>data b* (active x e)</code>

Note: The initial integer can be interpreted as a bitfield. Bit 0 indicates a passive segment, bit 1 indicates the presence of an explicit memory index for an active segment.

5.5.15 Data Count Section

The *data count section* has the id 12. It decodes into an optional `u32` count that represents the number of `data segments` in the `data section`. If this count does not match the length of the data segment list, the module is malformed.

<code>datacntsec</code>	<code>::=</code>	<code>n*:section₁₂(datacnt)</code>	\Rightarrow	<code>n*</code>
<code>datacnt</code>	<code>::=</code>	<code>n:u32</code>	\Rightarrow	<code>n</code>

Note: The data count section is used to simplify single-pass validation. Since the data section occurs after the code section, the `memory.init` and `data.drop` instructions would not be able to check whether the data segment index is valid until the data section is read. The data count section occurs before the code section, so a single-pass validator can use this count instead of deferring validation.

5.5.16 Modules

The encoding of a `module` starts with a preamble containing a 4-byte magic number (the string ‘\0asm’) and a version field. The current version of the WebAssembly binary format is 1.

The preamble is followed by a sequence of `sections`. `Custom sections` may be inserted at any place in this sequence, while other sections must occur at most once and in the prescribed order. All sections can be empty.

The lengths of lists produced by the (possibly empty) `function` and `code` section must match up.

Similarly, the optional data count must match the length of the [data segment](#) list. Furthermore, it must be present if any [data index](#) occurs in the code section.

```

magic ::= 0x00 0x61 0x73 0x6D
version ::= 0x01 0x00 0x00 0x00
module ::= magic version
         customsec* type*:typesec
         customsec* import*:importsec
         customsec* typeidxn:funcsec
         customsec* table*:tablesec
         customsec* mem*:memsec
         customsec* global*:globalsec
         customsec* export*:exportsec
         customsec* start*:startsec
         customsec* elem*:elemsec
         customsec* m':datacntsec
         customsec* (local*, expr)n:codesec
         customsec* datam:datasec
         customsec*
           ⇒
           module type* import* funcn global* table* mem* elem* datam start* export*
             if m' ≠ ε ∨ dataidx(funcn) = ε
             ∧ m = ∑(m')
             ∧ (func = func typeidx local* expr)n

```

Note: The version of the WebAssembly binary format may increase in the future if backward-incompatible changes have to be made to the format. However, such changes are expected to occur very infrequently, if ever. The binary format is intended to be forward-compatible, such that future extensions can be made without incrementing its version.

6.1 Conventions

The textual format for WebAssembly **modules** is a rendering of their **abstract syntax** into **S-expressions**³⁶.

Like the **binary format**, the text format is defined by an *attribute grammar*. A text string is a well-formed description of a module if and only if it is generated by the grammar. Each production of this grammar has at most one synthesized attribute: the abstract syntax that the respective character sequence expresses. Thus, the attribute grammar implicitly defines a *parsing* function. Some productions also take a **context** as an inherited attribute that records bound **identifiers**.

Except for a few exceptions, the core of the text grammar closely mirrors the grammar of the abstract syntax. However, it also defines a number of *abbreviations* that are “syntactic sugar” over the core syntax.

The recommended extension for files containing WebAssembly modules in text format is “.wat”. Files with this extension are assumed to be encoded in UTF-8, as per **Unicode**³⁷ (Section 2.5).

6.1.1 Grammar

The following conventions are adopted in defining grammar rules of the text format. They mirror the conventions used for **abstract syntax** and for the **binary format**. In order to distinguish symbols of the textual syntax from symbols of the abstract syntax, *typewriter* font is adopted for the former.

- Terminal symbols are either literal strings of characters enclosed in quotes or expressed as **Unicode**³⁸ scalar values: ‘module’, U+0A. (All characters written literally are unambiguously drawn from the 7-bit **ASCII**³⁹ subset of Unicode.)
- Nonterminal symbols are written in typewriter font: `valtype`, `instr`.
- T^n is a sequence of $n \geq 0$ iterations of T .
- T^* is a possibly empty sequence of iterations of T . (This is a shorthand for T^n used where n is not relevant.)
- T^+ is a sequence of one or more iterations of T . (This is a shorthand for T^n where $n \geq 1$.)
- $T^?$ is an optional occurrence of T . (This is a shorthand for T^n where $n \leq 1$.)

³⁶ <https://en.wikipedia.org/wiki/S-expression>

³⁷ <https://www.unicode.org/versions/latest/>

³⁸ <https://www.unicode.org/versions/latest/>

³⁹ <https://webstore.ansi.org/RecordDetail.aspx?sku=INCITS+4-1986%5bR2012%5d>

- $x:T$ denotes the same language as the nonterminal T , but also binds the variable x to the attribute synthesized for T . A pattern may also be used instead of a variable, e.g., $(x, y):T$.
- Productions are written $\text{sym} ::= T_1 \Rightarrow A_1 \mid \dots \mid T_n \Rightarrow A_n$, where each A_i is the attribute that is synthesized for sym in the given case, usually from attribute variables bound in T_i .
- Some productions are augmented by side conditions in parentheses, which restrict the applicability of the production. They provide a shorthand for a combinatorial expansion of the production into many separate cases.
- If the same meta variable or non-terminal symbol appears multiple times in a production (in the syntax or in an attribute), then all those occurrences must have the same instantiation.
- A distinction is made between *lexical* and *syntactic* productions. For the latter, arbitrary **white space** is allowed in any place where the grammar contains spaces. The productions defining **lexical syntax** and the syntax of **values** are considered lexical, all others are syntactic.

Note: For example, the **textual grammar** for **number types** is given as follows:

$$\begin{array}{llll} \text{numtype} & ::= & \text{'i32'} & \Rightarrow & \text{i32} \\ & & \text{'i64'} & \Rightarrow & \text{i64} \\ & & \text{'f32'} & \Rightarrow & \text{f32} \\ & & \text{'f64'} & \Rightarrow & \text{f64} \end{array}$$

The **textual grammar** for **limits** is defined as follows:

$$\begin{array}{llll} \text{limits} & ::= & n:\text{u32} & \Rightarrow & \{\min n, \max \epsilon\} \\ & & | & & n:\text{u32} \ m:\text{u32} & \Rightarrow & \{\min n, \max m\} \end{array}$$

The variables n and m name the attributes of the respective **u32** nonterminals, which in this case are the actual **unsigned integers** those parse into. The attribute of the complete production then is the abstract syntax for the limit, expressed in terms of the former values.

6.1.2 Abbreviations

In addition to the core grammar, which corresponds directly to the **abstract syntax**, the textual syntax also defines a number of *abbreviations* that can be used for convenience and readability.

Abbreviations are defined by *rewrite rules* specifying their expansion into the core syntax:

$$\text{abbreviation syntax} \quad \equiv \quad \text{expanded syntax}$$

These expansions are assumed to be applied, recursively and in order of appearance, before applying the core grammar rules to construct the abstract syntax.

6.1.3 Contexts

The text format allows the use of symbolic **identifiers** in place of **indices**. To resolve these identifiers into concrete indices, some grammar productions are indexed by an *identifier context* I as a synthesized attribute that records the declared identifiers in each **index space**. In addition, the context records the types defined in the module, so that **parameter** indices can be computed for **functions**.

It is convenient to define identifier contexts as *records* I with abstract syntax as follows:

$$I ::= \{ \begin{array}{ll} \text{types} & (\text{id}^?)^*, \\ \text{funcs} & (\text{id}^?)^*, \\ \text{tables} & (\text{id}^?)^*, \\ \text{mems} & (\text{id}^?)^*, \\ \text{globals} & (\text{id}^?)^*, \\ \text{elem} & (\text{id}^?)^*, \\ \text{data} & (\text{id}^?)^*, \\ \text{locals} & (\text{id}^?)^*, \\ \text{labels} & (\text{id}^?)^*, \\ \text{fields} & ((\text{id}^?)^*)^* \} \\ \text{typedefs} & \text{subtype}^* \} \end{array}$$

For each index space, such a context contains the list of *identifiers* assigned to the defined indices. Unnamed indices are associated with empty (ϵ) entries in these lists. Fields have *dependent* name spaces, and hence a separate list of field identifiers per type.

An identifier context is *well-formed* if no index space contains duplicate identifiers. For fields, names need only be unique within a single type.

Conventions

To avoid unnecessary clutter, empty components are omitted when writing out identifier contexts. For example, the record $\{\}$ is shorthand for an *identifier context* whose components are all empty.

6.1.4 Lists

Lists are written as plain sequences, but with a restriction on the length of these sequence.

$$\text{list}(A) ::= (x:A)^n \Rightarrow x^n \quad (\text{if } n < 2^{32})$$

6.2 Lexical Format

6.2.1 Characters

The text format assigns meaning to *source text*, which consists of a sequence of *characters*. Characters are assumed to be represented as valid *Unicode*⁴⁰ (Section 2.4) *scalar values*.

$$\begin{array}{ll} \text{source} & ::= \text{char}^* \\ \text{char} & ::= \text{U+00} \mid \dots \mid \text{U+D7FF} \mid \text{U+E000} \mid \dots \mid \text{U+10FFFF} \end{array}$$

Note: While source text may contain any Unicode character in *comments* or *string* literals, the rest of the grammar is formed exclusively from the characters supported by the 7-bit *ASCII*⁴¹ subset of Unicode.

⁴⁰ <https://www.unicode.org/versions/latest/>

⁴¹ <https://webstore.ansi.org/RecordDetail.aspx?sku=INCITS+4-1986%5bR2012%5d>

6.2.2 Tokens

The character stream in the source text is divided, from left to right, into a sequence of *tokens*, as defined by the following grammar.

```
token      ::= keyword | uN | sN | fN | string | id | '(' | ')' | reserved
keyword    ::= ('a' | ... | 'z') idchar*      (if occurring as a literal terminal in the grammar)
reserved   ::= (idchar | string)+
```

Tokens are formed from the input character stream according to the *longest match* rule. That is, the next token always consists of the longest possible sequence of characters that is recognized by the above lexical grammar. Tokens can be separated by *white space*, but except for strings, they cannot themselves contain whitespace.

Keyword tokens are defined either implicitly by an occurrence of a *terminal symbol* in literal form, such as ‘keyword’, in a *syntactic* production of this chapter, or explicitly where they arise in this chapter.

Any token that does not fall into any of the other categories is considered *reserved*, and cannot occur in source text.

Note: The effect of defining the set of reserved tokens is that all tokens must be separated by either parentheses, *white space*, or *comments*. For example, ‘0\$x’ is a single reserved token, as is “a”b”. Consequently, they are not recognized as two separate tokens ‘0’ and ‘\$x’, or “a” and “b”, respectively, but instead disallowed. This property of tokenization is not affected by the fact that the definition of reserved tokens overlaps with other token classes.

6.2.3 White Space

White space is any sequence of literal space characters, formatting characters, or *comments*. The allowed formatting characters correspond to a subset of the [ASCII⁴² format effectors](#), namely, *horizontal tabulation* (U+09), *line feed* (U+0A), and *carriage return* (U+0D).

```
space      ::= (' ' | format | comment)*
format     ::= newline | U+09
newline    ::= U+0A | U+0D | U+0D U+0A
```

The only relevance of white space is to separate *tokens*. It is otherwise ignored.

6.2.4 Comments

A *comment* can either be a *line comment*, started with a double semicolon ‘;;’ and extending to the end of the line, or a *block comment*, enclosed in delimiters ‘(;’ ... ‘;’)’. Block comments can be nested.

```
comment     ::= linecomment | blockcomment
linecomment ::= ‘;;’ linechar* (newline | eof)
linechar    ::= c:char                               (if c ≠ U+0A ∧ c ≠ U+0D)
blockcomment ::= ‘(;’ blockchar* ‘;’)
blockchar   ::= c:char                               (if c ≠ ‘;’ ∧ c ≠ ‘(’)
               | ‘;’                               (if the next character is not ‘)’)
               | ‘(’                               (if the next character is not ‘;’)
               | blockcomment
```

Here, the pseudo token *eof* indicates the end of the input. The *look-ahead* restrictions on the productions for *blockchar* disambiguate the grammar such that only well-bracketed uses of block comment delimiters are allowed.

Note: Any formatting and control characters are allowed inside comments.

⁴² <https://webstore.ansi.org/RecordDetail.aspx?sku=INCITS+4-1986%5bR2012%5d>

6.3 Values

The grammar productions in this section define *lexical syntax*, hence no *white space* is allowed.

6.3.1 Integers

All *integers* can be written in either decimal or hexadecimal notation. In both cases, digits can optionally be separated by underscores.

<i>sign</i>	::=	$\epsilon \Rightarrow + \mid '+' \Rightarrow + \mid '-' \Rightarrow -$	
<i>digit</i>	::=	$'0' \Rightarrow 0 \mid \dots \mid '9' \Rightarrow 9$	
<i>hexdigit</i>	::=	$d:\text{digit} \Rightarrow d$	
		$\mid 'A' \Rightarrow 10 \mid \dots \mid 'F' \Rightarrow 15$	
		$\mid 'a' \Rightarrow 10 \mid \dots \mid 'f' \Rightarrow 15$	
<i>num</i>	::=	$d:\text{digit} \Rightarrow d$	
		$\mid n:\text{num} \text{ '}'? d:\text{digit} \Rightarrow 10 \cdot n + d$	
<i>hexnum</i>	::=	$h:\text{hexdigit} \Rightarrow h$	
		$\mid n:\text{hexnum} \text{ '}'? h:\text{hexdigit} \Rightarrow 16 \cdot n + h$	

The allowed syntax for integer literals depends on size and signedness. Moreover, their value must lie within the range of the respective type.

<i>uN</i>	::=	$n:\text{num} \Rightarrow n$	(if $n < 2^N$)
		$\mid '0x' n:\text{hexnum} \Rightarrow n$	(if $n < 2^N$)
<i>sN</i>	::=	$\pm:\text{sign} n:\text{num} \Rightarrow \pm n$	(if $-2^{N-1} \leq \pm n < 2^{N-1}$)
		$\mid \pm:\text{sign} '0x' n:\text{hexnum} \Rightarrow \pm n$	(if $-2^{N-1} \leq \pm n < 2^{N-1}$)

Uninterpreted integers can be written as either signed or unsigned, and are normalized to unsigned in the abstract syntax.

<i>iN</i>	::=	$n:\text{uN} \Rightarrow n$	
		$\mid i:\text{sN} \Rightarrow n$	(if $i = \text{signed}(n)$)

6.3.2 Floating-Point

Floating-point values can be represented in either decimal or hexadecimal notation.

<i>frac</i>	::=	$d:\text{digit} \Rightarrow d/10$
		$\mid d:\text{digit} \text{ '}'? p:\text{frac} \Rightarrow (d + p/10)/10$
<i>hexfrac</i>	::=	$h:\text{hexdigit} \Rightarrow h/16$
		$\mid h:\text{hexdigit} \text{ '}'? p:\text{hexfrac} \Rightarrow (h + p/16)/16$
<i>float</i>	::=	$p:\text{num} \text{ '}'? \Rightarrow p$
		$\mid p:\text{num} \text{ '}' q:\text{frac} \Rightarrow p + q$
		$\mid p:\text{num} \text{ '}'? ('E' \mid 'e') \pm:\text{sign} e:\text{num} \Rightarrow p \cdot 10^{\pm e}$
		$\mid p:\text{num} \text{ '}' q:\text{frac} ('E' \mid 'e') \pm:\text{sign} e:\text{num} \Rightarrow (p + q) \cdot 10^{\pm e}$
<i>hexfloat</i>	::=	$'0x' p:\text{hexnum} \text{ '}'? \Rightarrow p$
		$\mid '0x' p:\text{hexnum} \text{ '}' q:\text{hexfrac} \Rightarrow p + q$
		$\mid '0x' p:\text{hexnum} \text{ '}'? ('P' \mid 'p') \pm:\text{sign} e:\text{num} \Rightarrow p \cdot 2^{\pm e}$
		$\mid '0x' p:\text{hexnum} \text{ '}' q:\text{hexfrac} ('P' \mid 'p') \pm:\text{sign} e:\text{num} \Rightarrow (p + q) \cdot 2^{\pm e}$

The value of a literal must not lie outside the representable range of the corresponding [IEEE 754⁴³](https://ieeexplore.ieee.org/document/8766229) type (that is, a numeric value must not overflow to $\pm\text{infinity}$), but it may be *rounded* to the nearest representable value.

⁴³ <https://ieeexplore.ieee.org/document/8766229>

Note: Rounding can be prevented by using hexadecimal notation with no more significant bits than supported by the required type.

Floating-point values may also be written as constants for *infinity* or *canonical NaN* (*not a number*). Furthermore, arbitrary NaN values may be expressed by providing an explicit payload value.

<code>f_N</code>	<code>::=</code>	<code>±:sign z:f_Nmag</code>	\Rightarrow	$\pm z$	
<code>f_Nmag</code>	<code>::=</code>	<code>z:float</code>	\Rightarrow	$\text{float}_N(z)$	(if $\text{float}_N(z) \neq \pm\infty$)
		<code>z:hexfloat</code>	\Rightarrow	$\text{float}_N(z)$	(if $\text{float}_N(z) \neq \pm\infty$)
		<code>'inf'</code>	\Rightarrow	∞	
		<code>'nan'</code>	\Rightarrow	$\text{nan}(\text{canon}_N)$	
		<code>'nan:0x' n:hexnum</code>	\Rightarrow	$\text{nan}(n)$	(if $1 \leq n < 2^{\text{signif}(N)}$)

6.3.3 Strings

Strings denote sequences of bytes that can represent both textual and binary data. They are enclosed in quotation marks and may contain any character other than [ASCII](#)⁴⁴ control characters, quotation marks (`"`), or backslash (`\`), except when expressed with an *escape sequence*.

<code>string</code>	<code>::=</code>	<code>"" (b*:stringelem)* ""</code>	\Rightarrow	$\text{concat}((b^*)^*)$	(if $ \text{concat}((b^*)^*) < 2^{32}$)
<code>stringelem</code>	<code>::=</code>	<code>c:stringchar</code>	\Rightarrow	$\text{utf8}(c)$	
		<code>'\ ' n:hexdigit m:hexdigit</code>	\Rightarrow	$16 \cdot n + m$	

Each character in a string literal represents the byte sequence corresponding to its UTF-8 [Unicode](#)⁴⁵ (Section 2.5) encoding, except for hexadecimal escape sequences `\hh`, which represent raw bytes of the respective value.

<code>stringchar</code>	<code>::=</code>	<code>c:char</code>	\Rightarrow	c	(if $c \geq \text{U}+20 \wedge c \neq \text{U}+7\text{F} \wedge c \neq \text{'"} \wedge c \neq \backslash$)
		<code>'\t'</code>	\Rightarrow	$\text{U}+09$	
		<code>'\n'</code>	\Rightarrow	$\text{U}+0\text{A}$	
		<code>'\r'</code>	\Rightarrow	$\text{U}+0\text{D}$	
		<code>'\"'</code>	\Rightarrow	$\text{U}+22$	
		<code>'\''</code>	\Rightarrow	$\text{U}+27$	
		<code>'\\'</code>	\Rightarrow	$\text{U}+5\text{C}$	
		<code>'\u{' n:hexnum '}'</code>	\Rightarrow	$\text{U}+(n)$	(if $n < 0\text{x}\text{D}800 \vee 0\text{x}\text{E}000 \leq n < 0\text{x}\text{110000}$)

6.3.4 Names

Names are strings denoting a literal character sequence. A name string must form a valid UTF-8 encoding as defined by [Unicode](#)⁴⁶ (Section 2.5) and is interpreted as a string of Unicode scalar values.

<code>name</code>	<code>::=</code>	<code>b*:string</code>	\Rightarrow	c^*	(if $b^* = \text{utf8}(c^*)$)
-------------------	------------------	------------------------	---------------	-------	--------------------------------

Note: Presuming the source text is itself encoded correctly, strings that do not contain any uses of hexadecimal byte escapes are always valid names.

⁴⁴ <https://webstore.ansi.org/RecordDetail.aspx?sku=INCITS+4-1986%5bR2012%5d>

⁴⁵ <https://www.unicode.org/versions/latest/>

⁴⁶ <https://www.unicode.org/versions/latest/>

6.3.5 Identifiers

Indices can be given in both numeric and symbolic form. Symbolic *identifiers* that stand in lieu of indices start with ‘\$’, followed by any sequence of printable [ASCII](#)⁴⁷ characters that does not contain a space, quotation mark, comma, semicolon, or bracket.

```

id      ::= '$' idchar+
idchar  ::= '0' | ... | '9'
          | 'A' | ... | 'Z'
          | 'a' | ... | 'z'
          | '!' | '#' | '$' | '%' | '&' | "'" | '*' | '+' | '-' | '.' | '/'
          | ':' | '<' | '=' | '>' | '?' | '@' | '\' | '~' | '_' | '^' | '|' | '~'

```

Conventions

The expansion rules of some abbreviations require insertion of a *fresh* identifier. That may be any syntactically valid identifier that does not already occur in the given source text.

6.4 Types

6.4.1 Number Types

```

numtypeI ::= 'i32' ⇒ i32
          | 'i64' ⇒ i64
          | 'f32' ⇒ f32
          | 'f64' ⇒ f64

```

6.4.2 Vector Types

```

vectypeI ::= 'v128' ⇒ v128

```

6.4.3 Heap Types

```

absheaptypes ::= 'any'      ⇒ any
                | 'eq'      ⇒ eq
                | 'i31'     ⇒ i31
                | 'struct'  ⇒ struct
                | 'array'   ⇒ array
                | 'none'    ⇒ none
                | 'func'    ⇒ func
                | 'nofunc'  ⇒ nofunc
                | 'extern'  ⇒ extern
                | 'noextern' ⇒ noextern
heaptypesI  ::= t:absheaptypes ⇒ y
                | x:typeidxI   ⇒ x

```

⁴⁷ <https://webstore.ansi.org/RecordDetail.aspx?sku=INCITS+4-1986%5bR2012%5d>

6.4.4 Reference Types

$$\begin{aligned} \text{reftype}_I &::= (' \text{'ref'} \text{ ht:heaptypes } ') &\Rightarrow & \text{ref ht} \\ &| (' \text{'ref'} \text{'null'} \text{ ht:heaptypes } ') &\Rightarrow & \text{ref null ht} \end{aligned}$$

Abbreviations

There are shorthands for references to abstract heap types.

	<code>'anyref'</code>	\equiv	<code>(' 'ref' 'null' 'any' ')</code>
<code>'eqref'</code>	\equiv	<code>(' 'ref' 'null' 'eq' ')</code>	
<code>'i31ref'</code>	\equiv	<code>(' 'ref' 'null' 'i31' ')</code>	
<code>'structref'</code>	\equiv	<code>(' 'ref' 'null' 'struct' ')</code>	
<code>'arrayref'</code>	\equiv	<code>(' 'ref' 'null' 'array' ')</code>	
<code>'nullref'</code>	\equiv	<code>(' 'ref' 'null' 'none' ')</code>	
<code>'funcref'</code>	\equiv	<code>(' 'ref' 'null' 'func' ')</code>	
<code>'nullfuncref'</code>	\equiv	<code>(' 'ref' 'null' 'nofunc' ')</code>	
<code>'externref'</code>	\equiv	<code>(' 'ref' 'null' 'extern' ')</code>	
<code>'nullexternref'</code>	\equiv	<code>(' 'ref' 'null' 'noextern' ')</code>	

6.4.5 Value Types

$$\begin{aligned} \text{valtype}_I &::= t:\text{numtype}_I &\Rightarrow & t \\ &| t:\text{vectype}_I &\Rightarrow & t \\ &| t:\text{reftype}_I &\Rightarrow & t \end{aligned}$$

6.4.6 Function Types

$$\begin{aligned} \text{functype}_I &::= (' \text{'func'} \text{ t}_1^*:\text{list}(\text{param}_I) \text{ t}_2^*:\text{list}(\text{result}_I) ') &\Rightarrow & [t_1^*] \rightarrow [t_2^*] \\ \text{param}_I &::= (' \text{'param'} \text{ id? } t:\text{valtype}_I ') &\Rightarrow & t \\ \text{result}_I &::= (' \text{'result'} t:\text{valtype}_I ') &\Rightarrow & t \end{aligned}$$

Note: The optional identifier names for parameters in a function type only have documentation purpose. They cannot be referenced from anywhere.

Abbreviations

Multiple anonymous parameters or results may be combined into a single declaration:

$$\begin{aligned} (' \text{'param'} \text{ valtype}^* ') &\equiv ((' \text{'param'} \text{ valtype } '))^* \\ (' \text{'result'} \text{ valtype}^* ') &\equiv ((' \text{'result'} \text{ valtype } '))^* \end{aligned}$$

6.4.7 Aggregate Types

<code>arraytype_I</code>	<code>::=</code>	<code>(' 'array' ft:fieldtype_I ')</code>	\Rightarrow	<code>ft</code>
<code>structtype_I</code>	<code>::=</code>	<code>(' 'struct' ft*:list(field_I) ')</code>	\Rightarrow	<code>ft*</code>
<code>field_I</code>	<code>::=</code>	<code>(' 'field' id? ft:fieldtype_I ')</code>	\Rightarrow	<code>ft</code>
<code>fieldtype_I</code>	<code>::=</code>	<code>st:storage_I</code>	\Rightarrow	<code>const st</code>
		<code> </code> <code>(' 'mut' st:storage_I ')</code>	\Rightarrow	<code>var st</code>
<code>storage_I</code>	<code>::=</code>	<code>t:valtype_I</code>	\Rightarrow	<code>t</code>
		<code> </code> <code>t:packtype</code>	\Rightarrow	<code>t</code>
<code>packtype</code>	<code>::=</code>	<code>'i8'</code>	\Rightarrow	<code>i8</code>
		<code> </code> <code>'i16'</code>	\Rightarrow	<code>i16</code>

Abbreviations

Multiple anonymous structure fields may be combined into a single declaration:

`(' 'field' fieldtype* ')` \equiv `(((' 'field' fieldtype '))*`

6.4.8 Composite Types

<code>comptype_I</code>	<code>::=</code>	<code>at:arraytype_I</code>	\Rightarrow	<code>array at</code>
		<code> </code> <code>st:structtype_I</code>	\Rightarrow	<code>struct at</code>
		<code> </code> <code>ft:functype_I</code>	\Rightarrow	<code>func ft</code>

6.4.9 Recursive Types

<code>rectype_I</code>	<code>::=</code>	<code>(' 'rec' st*:list(typedef_I) ')</code>	\Rightarrow	<code>rec st*</code>
<code>typedef_I</code>	<code>::=</code>	<code>(' 'type' id? st:subtype_I ')</code>	\Rightarrow	<code>st</code>
<code>subtype_I</code>	<code>::=</code>	<code>(' 'sub' 'final'? x*:list(typeidx_I) ct:comptype_I ')</code>	\Rightarrow	<code>sub final? x* ct</code>

Abbreviations

Singular recursive types can omit the `'rec'` keyword:

`typedef` \equiv `(' 'rec' typedef ')`

Similarly, final sub types with no super-types can omit the `sub` keyword and arguments:

`comptype` \equiv `(' 'sub' 'final' ϵ comptype ')`

6.4.10 Limits

<code>limits</code>	<code>::=</code>	<code>n:u32</code>	\Rightarrow	<code>{min n, max ϵ}</code>
		<code> </code> <code>n:u32 m:u32</code>	\Rightarrow	<code>{min n, max m}</code>

6.4.11 Memory Types

$$\text{memtype}_I ::= \text{lim:limits} \Rightarrow \text{lim}$$

6.4.12 Table Types

$$\text{tabletype}_I ::= \text{lim:limits } \text{et:reftype}_I \Rightarrow \text{lim } \text{et}$$

6.4.13 Global Types

$$\begin{aligned} \text{globaltype}_I &::= t:\text{valtype} && \Rightarrow \text{const } t \\ &| \text{'(' 'mut' } t:\text{valtype}_I \text{' ')} && \Rightarrow \text{var } t \end{aligned}$$

6.5 Instructions

Instructions are syntactically distinguished into *plain* and *structured* instructions.

$$\begin{aligned} \text{instr}_I &::= \text{in:plaininstr}_I \Rightarrow \text{in} \\ &| \text{in:blockinstr}_I \Rightarrow \text{in} \end{aligned}$$

In addition, as a syntactic abbreviation, instructions can be written as S-expressions in *folded* form, to group them visually.

6.5.1 Labels

Structured control instructions can be annotated with a symbolic *label identifier*. They are the only *symbolic identifiers* that can be bound locally in an instruction sequence. The following grammar handles the corresponding update to the *identifier context* by *composing* the context with an additional label entry.

$$\begin{aligned} \text{label}_I &::= v:\text{id} \Rightarrow \{\text{labels } v\} \oplus I && (\text{if } v \notin I.\text{labels}) \\ &| v:\text{id} \Rightarrow \{\text{labels } v\} \oplus (I \text{ with labels}[i] = \epsilon) && (\text{if } I.\text{labels}[i] = v) \\ &| \epsilon \Rightarrow \{\text{labels } (\epsilon)\} \oplus I \end{aligned}$$

Note: The new label entry is inserted at the *beginning* of the label list in the identifier context. This effectively shifts all existing labels up by one, mirroring the fact that control instructions are indexed relatively not absolutely.

If a label with the same name already exists, then it is shadowed and the earlier label becomes inaccessible.

6.5.2 Control Instructions

Structured control instructions can bind an optional symbolic *label identifier*. The same label identifier may optionally be repeated after the corresponding *end* and *else* pseudo instructions, to indicate the matching delimiters.

Their *block type* is given as a *type use*, analogous to the type of *functions*. However, the special case of a type use that is syntactically empty or consists of only a single *result* is not regarded as an *abbreviation* for an inline *function*.

type, but is parsed directly into an optional `value` type.

$$\begin{aligned}
 \text{blocktype}_I &::= (t:\text{result}_I)^? \Rightarrow t^? \\
 &| x, I':\text{typeuse}_I \Rightarrow x \quad (\text{if } I' = \{\text{locals } (\epsilon)^*\}) \\
 \text{blockinstr}_I &::= \text{'block' } I':\text{label}_I \text{ bt:blocktype}_I (in:\text{instr}_{I'})^* \text{'end' } id^? \\
 &\Rightarrow \text{block } bt \text{ in}^* \text{ end} \quad (\text{if } id^? = \epsilon \vee id^? = \text{label}) \\
 &| \text{'loop' } I':\text{label}_I \text{ bt:blocktype}_I (in:\text{instr}_{I'})^* \text{'end' } id^? \\
 &\Rightarrow \text{loop } bt \text{ in}^* \text{ end} \quad (\text{if } id^? = \epsilon \vee id^? = \text{label}) \\
 &| \text{'if' } I':\text{label}_I \text{ bt:blocktype}_I (in_1:\text{instr}_{I'})^* \text{'else' } id_1^? (in_2:\text{instr}_{I'})^* \text{'end' } id_2^? \\
 &\Rightarrow \text{if } bt \text{ in}_1^* \text{ else } in_2^* \text{ end} \quad (\text{if } id_1^? = \epsilon \vee id_1^? = \text{label}, id_2^? = \epsilon \vee id_2^? = \text{label})
 \end{aligned}$$

Note: The side condition stating that the `identifier context` I' must only contain unnamed entries in the rule for `typeuse` block types enforces that no identifier can be bound in any `param` declaration for a block type.

All other control instruction are represented verbatim.

$$\begin{aligned}
 \text{plaininstr}_I &::= \text{'unreachable'} && \Rightarrow \text{unreachable} \\
 &| \text{'nop'} && \Rightarrow \text{nop} \\
 &| \text{'br' } l:\text{labelidx}_I && \Rightarrow \text{br } l \\
 &| \text{'br_if' } l:\text{labelidx}_I && \Rightarrow \text{br_if } l \\
 &| \text{'br_table' } l*:\text{list}(\text{labelidx}_I) \text{ } l_N:\text{labelidx}_I && \Rightarrow \text{br_table } l^* \text{ } l_N \\
 &| \text{'br_on_null' } l:\text{labelidx}_I && \Rightarrow \text{br_on_null } l \\
 &| \text{'br_on_non_null' } l:\text{labelidx}_I && \Rightarrow \text{br_on_non_null } l \\
 &| \text{'br_on_cast' } l:\text{labelidx}_I \text{ } t_1:\text{reftype } t_2:\text{reftype} && \Rightarrow \text{br_on_cast } l \text{ } t_1 \text{ } t_2 \\
 &| \text{'br_on_cast_fail' } l:\text{labelidx}_I \text{ } t_1:\text{reftype } t_2:\text{reftype} && \Rightarrow \text{br_on_cast_fail } l \text{ } t_1 \text{ } t_2 \\
 &| \text{'return'} && \Rightarrow \text{return} \\
 &| \text{'call' } x:\text{funcidx}_I && \Rightarrow \text{call } x \\
 &| \text{'call_ref' } x:\text{typeidx} && \Rightarrow \text{call_ref } x \\
 &| \text{'call_indirect' } x:\text{tableidx } y, I':\text{typeuse}_I && \Rightarrow \text{call_indirect } x \text{ } y \quad (\text{if } I' = \{\}) \\
 &| \text{'return_call' } x:\text{funcidx}_I && \Rightarrow \text{return_call } x \\
 &| \text{'return_call_ref' } x:\text{typeidx} && \Rightarrow \text{return_call_ref } x \\
 &| \text{'return_call_indirect' } x:\text{tableidx } y, I':\text{typeuse}_I && \Rightarrow \text{return_call_indirect } x \text{ } y \quad (\text{if } I' = \{\})
 \end{aligned}$$

Note: The side condition stating that the `identifier context` I' must only contain unnamed entries in the rule for `call_indirect` enforces that no identifier can be bound in any `param` declaration appearing in the type annotation.

Abbreviations

The `'else'` keyword of an `'if'` instruction can be omitted if the following instruction sequence is empty.

$$\text{'if' label blocktype}_I \text{ instr}^* \text{'end'} \equiv \text{'if' label blocktype}_I \text{ instr}^* \text{'else' 'end'}$$

Also, for backwards compatibility, the table index to `'call_indirect'` and `'return_call_indirect'` can be omitted, defaulting to 0.

$$\begin{aligned}
 &\text{'call_indirect' typeuse} && \equiv && \text{'call_indirect' 0 typeuse} \\
 \text{'return_call_indirect' typeuse} && \equiv && \text{'return_call_indirect' 0 typeuse}
 \end{aligned}$$

6.5.3 Reference Instructions

<code>plaininstr_I</code>	<code>::=</code>	<code>...</code>	
		<code>'ref.null' t:heaptype</code>	\Rightarrow <code>ref.null t</code>
		<code>'ref.func' x:funcidx</code>	\Rightarrow <code>ref.func x</code>
		<code>'ref.is_null'</code>	\Rightarrow <code>ref.is_null</code>
		<code>'ref.as_non_null'</code>	\Rightarrow <code>ref.as_non_null</code>
		<code>'ref.eq'</code>	\Rightarrow <code>ref.eq</code>
		<code>'ref.test' t:reftype</code>	\Rightarrow <code>ref.test t</code>
		<code>'ref.cast' t:reftype</code>	\Rightarrow <code>ref.cast t</code>
		<code>'struct.new' x:typeidx_I</code>	\Rightarrow <code>struct.new x</code>
		<code>'struct.new_default' x:typeidx_I</code>	\Rightarrow <code>struct.new_default x</code>
		<code>'struct.get' x:typeidx_I y:fieldidx_{I,x}</code>	\Rightarrow <code>struct.get x y</code>
		<code>'struct.get_u' x:typeidx_I y:fieldidx_{I,x}</code>	\Rightarrow <code>struct.get_u x y</code>
		<code>'struct.get_s' x:typeidx_I y:fieldidx_{I,x}</code>	\Rightarrow <code>struct.get_s x y</code>
		<code>'struct.set' x:typeidx_I y:fieldidx_{I,x}</code>	\Rightarrow <code>struct.set x y</code>
		<code>'array.new' x:typeidx_I</code>	\Rightarrow <code>array.new x</code>
		<code>'array.new_default' x:typeidx_I</code>	\Rightarrow <code>array.new_default x</code>
		<code>'array.new_fixed' x:typeidx_I n:u32</code>	\Rightarrow <code>array.new_fixed x n</code>
		<code>'array.new_data' x:typeidx_I y:dataidx_I</code>	\Rightarrow <code>array.new_data x y</code>
		<code>'array.new_elem' x:typeidx_I y:elemidx_I</code>	\Rightarrow <code>array.new_elem x y</code>
		<code>'array.get' x:typeidx_I</code>	\Rightarrow <code>array.get x</code>
		<code>'array.get_u' x:typeidx_I</code>	\Rightarrow <code>array.get_u x</code>
		<code>'array.get_s' x:typeidx_I</code>	\Rightarrow <code>array.get_s x</code>
		<code>'array.set' x:typeidx_I</code>	\Rightarrow <code>array.set x</code>
		<code>'array.len'</code>	\Rightarrow <code>array.len</code>
		<code>'array.fill' x:typeidx_I</code>	\Rightarrow <code>array.fill x</code>
		<code>'array.copy' x:typeidx_I y:typeidx_I</code>	\Rightarrow <code>array.copy x y</code>
		<code>'array.init_data' x:typeidx_I y:dataidx_I</code>	\Rightarrow <code>array.init_data x y</code>
		<code>'array.init_elem' x:typeidx_I y:elemidx_I</code>	\Rightarrow <code>array.init_elem x y</code>
		<code>'ref.i31'</code>	\Rightarrow <code>ref.i31</code>
		<code>'i31.get_u'</code>	\Rightarrow <code>i31.get_u</code>
		<code>'i31.get_s'</code>	\Rightarrow <code>i31.get_s</code>
		<code>'any.convert_extern'</code>	\Rightarrow <code>any.convert_extern</code>
		<code>'extern.convert_any'</code>	\Rightarrow <code>extern.convert_any</code>

6.5.4 Parametric Instructions

<code>plaininstr_I</code>	<code>::=</code>	<code>...</code>	
		<code>'drop'</code>	\Rightarrow <code>drop</code>
		<code>'select' ((t:result_I)*)?</code>	\Rightarrow <code>select (t*)?</code>

6.5.5 Variable Instructions

<code>plaininstr_I</code>	<code>::=</code>	<code>...</code>	
		<code>'local.get' x:localidx_I</code>	\Rightarrow <code>local.get x</code>
		<code>'local.set' x:localidx_I</code>	\Rightarrow <code>local.set x</code>
		<code>'local.tee' x:localidx_I</code>	\Rightarrow <code>local.tee x</code>
		<code>'global.get' x:globalidx_I</code>	\Rightarrow <code>global.get x</code>
		<code>'global.set' x:globalidx_I</code>	\Rightarrow <code>global.set x</code>

6.5.6 Table Instructions

<code>plaininstr_I</code>	::=	...	
		<code>'table.get' x:tableidx_I</code>	⇒ <code>table.get x</code>
		<code>'table.set' x:tableidx_I</code>	⇒ <code>table.set x</code>
		<code>'table.size' x:tableidx_I</code>	⇒ <code>table.size x</code>
		<code>'table.grow' x:tableidx_I</code>	⇒ <code>table.grow x</code>
		<code>'table.fill' x:tableidx_I</code>	⇒ <code>table.fill x</code>
		<code>'table.copy' x:tableidx_I y:tableidx_I</code>	⇒ <code>table.copy x y</code>
		<code>'table.init' x:tableidx_I y:elemidx_I</code>	⇒ <code>table.init x y</code>
		<code>'elem.drop' x:elemidx_I</code>	⇒ <code>elem.drop x</code>

Abbreviations

For backwards compatibility, all [table indices](#) may be omitted from table instructions, defaulting to 0.

<code>'table.get'</code>	≡	<code>'table.get' '0'</code>
<code>'table.set'</code>	≡	<code>'table.set' '0'</code>
<code>'table.size'</code>	≡	<code>'table.size' '0'</code>
<code>'table.grow'</code>	≡	<code>'table.grow' '0'</code>
<code>'table.fill'</code>	≡	<code>'table.fill' '0'</code>
<code>'table.copy'</code>	≡	<code>'table.copy' '0' '0'</code>
<code>'table.init' x:elemidx_I</code>	≡	<code>'table.init' '0' x:elemidx_I</code>

6.5.7 Memory Instructions

The offset and alignment immediates to memory instructions are optional. The offset defaults to 0, the alignment to the storage size of the respective memory access, which is its *natural alignment*. Lexically, an [offset](#) or [align](#)

phrase is considered a single **keyword token**, so no **white space** is allowed around the '='.

<code>memarg_N</code>	::=	<code>o:offset a:align_N</code>	⇒	{align
<code>offset</code>	::=	<code>'offset='o:u32</code>	⇒	<code>o</code>
		<code>ε</code>	⇒	<code>0</code>
<code>align_N</code>	::=	<code>'align='a:u32</code>	⇒	<code>a</code>
		<code>ε</code>	⇒	<code>N</code>
<code>plaininstr_I</code>	::=	...		
		<code>'i32.load' x:memidx m:memarg₄</code>	⇒	<code>i32.load</code>
		<code>'i64.load' x:memidx m:memarg₈</code>	⇒	<code>i64.load</code>
		<code>'f32.load' x:memidx m:memarg₄</code>	⇒	<code>f32.load</code>
		<code>'f64.load' x:memidx m:memarg₈</code>	⇒	<code>f64.load</code>
		<code>'v128.load' x:memidx m:memarg₁₆</code>	⇒	<code>v128.load</code>
		<code>'i32.load8_s' x:memidx m:memarg₁</code>	⇒	<code>i32.load8_s</code>
		<code>'i32.load8_u' x:memidx m:memarg₁</code>	⇒	<code>i32.load8_u</code>
		<code>'i32.load16_s' x:memidx m:memarg₂</code>	⇒	<code>i32.load16_s</code>
		<code>'i32.load16_u' x:memidx m:memarg₂</code>	⇒	<code>i32.load16_u</code>
		<code>'i64.load8_s' x:memidx m:memarg₁</code>	⇒	<code>i64.load8_s</code>
		<code>'i64.load8_u' x:memidx m:memarg₁</code>	⇒	<code>i64.load8_u</code>
		<code>'i64.load16_s' x:memidx m:memarg₂</code>	⇒	<code>i64.load16_s</code>
		<code>'i64.load16_u' x:memidx m:memarg₂</code>	⇒	<code>i64.load16_u</code>
		<code>'i64.load32_s' x:memidx m:memarg₄</code>	⇒	<code>i64.load32_s</code>
		<code>'i64.load32_u' x:memidx m:memarg₄</code>	⇒	<code>i64.load32_u</code>
		<code>'v128.load8x8_s' x:memidx m:memarg₈</code>	⇒	<code>v128.load8x8_s</code>
		<code>'v128.load8x8_u' x:memidx m:memarg₈</code>	⇒	<code>v128.load8x8_u</code>
		<code>'v128.load16x4_s' x:memidx m:memarg₈</code>	⇒	<code>v128.load16x4_s</code>
		<code>'v128.load16x4_u' x:memidx m:memarg₈</code>	⇒	<code>v128.load16x4_u</code>
		<code>'v128.load32x2_s' x:memidx m:memarg₈</code>	⇒	<code>v128.load32x2_s</code>
		<code>'v128.load32x2_u' x:memidx m:memarg₈</code>	⇒	<code>v128.load32x2_u</code>
		<code>'v128.load8_splat' x:memidx m:memarg₁</code>	⇒	<code>v128.load8_splat</code>
		<code>'v128.load16_splat' x:memidx m:memarg₂</code>	⇒	<code>v128.load16_splat</code>
		<code>'v128.load32_splat' x:memidx m:memarg₄</code>	⇒	<code>v128.load32_splat</code>
		<code>'v128.load64_splat' x:memidx m:memarg₈</code>	⇒	<code>v128.load64_splat</code>
		<code>'v128.load32_zero' x:memidx m:memarg₄</code>	⇒	<code>v128.load32_zero</code>
		<code>'v128.load64_zero' x:memidx m:memarg₈</code>	⇒	<code>v128.load64_zero</code>
		<code>'v128.load8_lane' x:memidx m:memarg₁ y:u8</code>	⇒	<code>v128.load8_lane</code>
		<code>'v128.load16_lane' x:memidx m:memarg₂ y:u8</code>	⇒	<code>v128.load16_lane</code>
		<code>'v128.load32_lane' x:memidx m:memarg₄ y:u8</code>	⇒	<code>v128.load32_lane</code>
		<code>'v128.load64_lane' x:memidx m:memarg₈ y:u8</code>	⇒	<code>v128.load64_lane</code>
		<code>'i32.store' x:memidx m:memarg₄</code>	⇒	<code>i32.store</code>
		<code>'i64.store' x:memidx m:memarg₈</code>	⇒	<code>i64.store</code>
		<code>'f32.store' x:memidx m:memarg₄</code>	⇒	<code>f32.store</code>
		<code>'f64.store' x:memidx m:memarg₈</code>	⇒	<code>f64.store</code>
		<code>'v128.store' x:memidx m:memarg₁₆</code>	⇒	<code>v128.store</code>
		<code>'i32.store8' x:memidx m:memarg₁</code>	⇒	<code>i32.store8</code>
		<code>'i32.store16' x:memidx m:memarg₂</code>	⇒	<code>i32.store16</code>
		<code>'i64.store8' x:memidx m:memarg₁</code>	⇒	<code>i64.store8</code>
		<code>'i64.store16' x:memidx m:memarg₂</code>	⇒	<code>i64.store16</code>
		<code>'i64.store32' x:memidx m:memarg₄</code>	⇒	<code>i64.store32</code>
		<code>'v128.store8_lane' x:memidx m:memarg₁ y:u8</code>	⇒	<code>v128.store8_lane</code>
		<code>'v128.store16_lane' x:memidx m:memarg₂ y:u8</code>	⇒	<code>v128.store16_lane</code>
		<code>'v128.store32_lane' x:memidx m:memarg₄ y:u8</code>	⇒	<code>v128.store32_lane</code>
		<code>'v128.store64_lane' x:memidx m:memarg₈ y:u8</code>	⇒	<code>v128.store64_lane</code>
<code>'memory.size' x:memidx</code>	⇒	<code>memory.size x</code>		
		<code>'memory.grow' x:memidx</code>	⇒	<code>memory.grow</code>
		<code>'memory.fill' x:memidx</code>	⇒	<code>memory.fill</code>
		<code>'memory.copy' x:memidx y:memidx</code>	⇒	<code>memory.copy</code>
		<code>'memory.init' x:memidx y:dataidx_I</code>	⇒	<code>memory.init</code>
		<code>'data.drop' x:dataidx_I</code>	⇒	<code>data.drop</code>

Abbreviations

As an abbreviation, the memory index can be omitted in all memory instructions, defaulting to 0.

<code>numtype.load memarg</code>	<code>≡ numtype.load '0' memarg</code>
<code>vectype.load memarg</code>	<code>≡ vectype.load '0' memarg</code>
<code>numtype.load N'_sx memarg</code>	<code>≡ numtype.load N'_sx '0' memarg</code>
<code>vectype.load NxM'_sx memarg</code>	<code>≡ vectype.load NxM'_sx '0' memarg</code>
<code>vectype.load N'_splat memarg</code>	<code>≡ vectype.load N'_splat '0' memarg</code>
<code>vectype.load N'_zero memarg</code>	<code>≡ vectype.load N'_zero '0' memarg</code>
<code>vectype.load N'_lane memarg u8</code>	<code>≡ vectype.load N'_lane '0' memarg u8</code>
<code>numtype.store memarg</code>	<code>≡ numtype.store '0' memarg</code>
<code>vectype.store memarg</code>	<code>≡ vectype.store '0' memarg</code>
<code>numtype.store N memarg</code>	<code>≡ numtype.store N '0' memarg</code>
<code>vectype.store N'_lane memarg u8</code>	<code>≡ vectype.store N'_lane '0' memarg u8</code>
<code>'memory.size'</code>	<code>≡ 'memory.size' '0'</code>
<code>'memory.grow'</code>	<code>≡ 'memory.grow' '0'</code>
<code>'memory.fill'</code>	<code>≡ 'memory.fill' '0'</code>
<code>'memory.copy'</code>	<code>≡ 'memory.copy' '0' '0'</code>
<code>'memory.init' x:elemidx_I</code>	<code>≡ 'memory.init' '0' x:elemidx_I</code>

6.5.8 Numeric Instructions

<code>plaininstr_I</code>	<code>::=</code>	<code>...</code>
		<code>'i32.const' n:i32 ⇒ i32.const n</code>
		<code>'i64.const' n:i64 ⇒ i64.const n</code>
		<code>'f32.const' z:f32 ⇒ f32.const z</code>
		<code>'f64.const' z:f64 ⇒ f64.const z</code>
		<code>'i32.clz' ⇒ i32.clz</code>
		<code>'i32.ctz' ⇒ i32.ctz</code>
		<code>'i32.popcnt' ⇒ i32.popcnt</code>
		<code>'i32.add' ⇒ i32.add</code>
		<code>'i32.sub' ⇒ i32.sub</code>
		<code>'i32.mul' ⇒ i32.mul</code>
		<code>'i32.div_s' ⇒ i32.div_s</code>
		<code>'i32.div_u' ⇒ i32.div_u</code>
		<code>'i32.rem_s' ⇒ i32.rem_s</code>
		<code>'i32.rem_u' ⇒ i32.rem_u</code>
		<code>'i32.and' ⇒ i32.and</code>
		<code>'i32.or' ⇒ i32.or</code>
		<code>'i32.xor' ⇒ i32.xor</code>
		<code>'i32.shl' ⇒ i32.shl</code>
		<code>'i32.shr_s' ⇒ i32.shr_s</code>
		<code>'i32.shr_u' ⇒ i32.shr_u</code>
		<code>'i32.rotl' ⇒ i32.rotl</code>
		<code>'i32.rotr' ⇒ i32.rotr</code>

'i64.clz'	⇒	i64.clz
'i64.ctz'	⇒	i64.ctz
'i64.popcnt'	⇒	i64.popcnt
'i64.add'	⇒	i64.add
'i64.sub'	⇒	i64.sub
'i64.mul'	⇒	i64.mul
'i64.div_s'	⇒	i64.div_s
'i64.div_u'	⇒	i64.div_u
'i64.rem_s'	⇒	i64.rem_s
'i64.rem_u'	⇒	i64.rem_u
'i64.and'	⇒	i64.and
'i64.or'	⇒	i64.or
'i64.xor'	⇒	i64.xor
'i64.shl'	⇒	i64.shl
'i64.shr_s'	⇒	i64.shr_s
'i64.shr_u'	⇒	i64.shr_u
'i64.rotl'	⇒	i64.rotl
'i64.rotr'	⇒	i64.rotr

'f32.abs'	⇒	f32.abs
'f32.neg'	⇒	f32.neg
'f32.ceil'	⇒	f32.ceil
'f32.floor'	⇒	f32.floor
'f32.trunc'	⇒	f32.trunc
'f32.nearest'	⇒	f32.nearest
'f32.sqrt'	⇒	f32.sqrt
'f32.add'	⇒	f32.add
'f32.sub'	⇒	f32.sub
'f32.mul'	⇒	f32.mul
'f32.div'	⇒	f32.div
'f32.min'	⇒	f32.min
'f32.max'	⇒	f32.max
'f32.copysign'	⇒	f32.copysign

'f64.abs'	⇒	f64.abs
'f64.neg'	⇒	f64.neg
'f64.ceil'	⇒	f64.ceil
'f64.floor'	⇒	f64.floor
'f64.trunc'	⇒	f64.trunc
'f64.nearest'	⇒	f64.nearest
'f64.sqrt'	⇒	f64.sqrt
'f64.add'	⇒	f64.add
'f64.sub'	⇒	f64.sub
'f64.mul'	⇒	f64.mul
'f64.div'	⇒	f64.div
'f64.min'	⇒	f64.min
'f64.max'	⇒	f64.max
'f64.copysign'	⇒	f64.copysign

'i32.eqz'	⇒	i32.eqz
'i32.eq'	⇒	i32.eq
'i32.ne'	⇒	i32.ne
'i32.lt_s'	⇒	i32.lt_s
'i32.lt_u'	⇒	i32.lt_u
'i32.gt_s'	⇒	i32.gt_s
'i32.gt_u'	⇒	i32.gt_u
'i32.le_s'	⇒	i32.le_s
'i32.le_u'	⇒	i32.le_u
'i32.ge_s'	⇒	i32.ge_s
'i32.ge_u'	⇒	i32.ge_u
'i64.eqz'	⇒	i64.eqz
'i64.eq'	⇒	i64.eq
'i64.ne'	⇒	i64.ne
'i64.lt_s'	⇒	i64.lt_s
'i64.lt_u'	⇒	i64.lt_u
'i64.gt_s'	⇒	i64.gt_s
'i64.gt_u'	⇒	i64.gt_u
'i64.le_s'	⇒	i64.le_s
'i64.le_u'	⇒	i64.le_u
'i64.ge_s'	⇒	i64.ge_s
'i64.ge_u'	⇒	i64.ge_u
'f32.eq'	⇒	f32.eq
'f32.ne'	⇒	f32.ne
'f32.lt'	⇒	f32.lt
'f32.gt'	⇒	f32.gt
'f32.le'	⇒	f32.le
'f32.ge'	⇒	f32.ge
'f64.eq'	⇒	f64.eq
'f64.ne'	⇒	f64.ne
'f64.lt'	⇒	f64.lt
'f64.gt'	⇒	f64.gt
'f64.le'	⇒	f64.le
'f64.ge'	⇒	f64.ge

'i32.wrap_i64'	⇒	i32.wrap_i64
'i32.trunc_f32_s'	⇒	i32.trunc_f32_s
'i32.trunc_f32_u'	⇒	i32.trunc_f32_u
'i32.trunc_f64_s'	⇒	i32.trunc_f64_s
'i32.trunc_f64_u'	⇒	i32.trunc_f64_u
'i32.trunc_sat_f32_s'	⇒	i32.trunc_sat_f32_s
'i32.trunc_sat_f32_u'	⇒	i32.trunc_sat_f32_u
'i32.trunc_sat_f64_s'	⇒	i32.trunc_sat_f64_s
'i32.trunc_sat_f64_u'	⇒	i32.trunc_sat_f64_u
'i64.extend_i32_s'	⇒	i64.extend_i32_s
'i64.extend_i32_u'	⇒	i64.extend_i32_u
'i64.trunc_f32_s'	⇒	i64.trunc_f32_s
'i64.trunc_f32_u'	⇒	i64.trunc_f32_u
'i64.trunc_f64_s'	⇒	i64.trunc_f64_s
'i64.trunc_f64_u'	⇒	i64.trunc_f64_u
'i64.trunc_sat_f32_s'	⇒	i64.trunc_sat_f32_s
'i64.trunc_sat_f32_u'	⇒	i64.trunc_sat_f32_u
'i64.trunc_sat_f64_s'	⇒	i64.trunc_sat_f64_s
'i64.trunc_sat_f64_u'	⇒	i64.trunc_sat_f64_u
'f32.convert_i32_s'	⇒	f32.convert_i32_s
'f32.convert_i32_u'	⇒	f32.convert_i32_u
'f32.convert_i64_s'	⇒	f32.convert_i64_s
'f32.convert_i64_u'	⇒	f32.convert_i64_u
'f32.demote_f64'	⇒	f32.demote_f64
'f64.convert_i32_s'	⇒	f64.convert_i32_s
'f64.convert_i32_u'	⇒	f64.convert_i32_u
'f64.convert_i64_s'	⇒	f64.convert_i64_s
'f64.convert_i64_u'	⇒	f64.convert_i64_u
'f64.promote_f32'	⇒	f64.promote_f32
'i32.reinterpret_f32'	⇒	i32.reinterpret_f32
'i64.reinterpret_f64'	⇒	i64.reinterpret_f64
'f32.reinterpret_i32'	⇒	f32.reinterpret_i32
'f64.reinterpret_i64'	⇒	f64.reinterpret_i64
'i32.extend8_s'	⇒	i32.extend8_s
'i32.extend16_s'	⇒	i32.extend16_s
'i64.extend8_s'	⇒	i64.extend8_s
'i64.extend16_s'	⇒	i64.extend16_s
'i64.extend32_s'	⇒	i64.extend32_s

6.5.9 Vector Instructions

Vector constant instructions have a mandatory [shape](#) descriptor, which determines how the following values are parsed.

'v128.const' 'i8x16' (n:i8) ¹⁶	⇒	v128.const bytes _{i128} ⁻¹ (bytes _{i8} (n) ¹⁶)
'v128.const' 'i16x8' (n:i16) ⁸	⇒	v128.const bytes _{i128} ⁻¹ (bytes _{i16} (n) ⁸)
'v128.const' 'i32x4' (n:i32) ⁴	⇒	v128.const bytes _{i128} ⁻¹ (bytes _{i32} (n) ⁴)
'v128.const' 'i64x2' (n:i64) ²	⇒	v128.const bytes _{i128} ⁻¹ (bytes _{i64} (n) ²)
'v128.const' 'f32x4' (z:f32) ⁴	⇒	v128.const bytes _{i128} ⁻¹ (bytes _{f32} (z) ⁴)
'v128.const' 'f64x2' (z:f64) ²	⇒	v128.const bytes _{i128} ⁻¹ (bytes _{f64} (z) ²)
'i8x16.shuffle' (laneidx:u8) ¹⁶	⇒	i8x16.shuffle laneidx ¹⁶
'i8x16.swizzle'	⇒	i8x16.swizzle

'i8x16.splat'	⇒	i8x16.splat
'i16x8.splat'	⇒	i16x8.splat
'i32x4.splat'	⇒	i32x4.splat
'i64x2.splat'	⇒	i64x2.splat
'f32x4.splat'	⇒	f32x4.splat
'f64x2.splat'	⇒	f64x2.splat
'i8x16.extract_lane_s' laneidx:u8	⇒	i8x16.extract_lane_s laneidx
'i8x16.extract_lane_u' laneidx:u8	⇒	i8x16.extract_lane_u laneidx
'i8x16.replace_lane' laneidx:u8	⇒	i8x16.replace_lane laneidx
'i16x8.extract_lane_s' laneidx:u8	⇒	i16x8.extract_lane_s laneidx
'i16x8.extract_lane_u' laneidx:u8	⇒	i16x8.extract_lane_u laneidx
'i16x8.replace_lane' laneidx:u8	⇒	i16x8.replace_lane laneidx
'i32x4.extract_lane' laneidx:u8	⇒	i32x4.extract_lane laneidx
'i32x4.replace_lane' laneidx:u8	⇒	i32x4.replace_lane laneidx
'i64x2.extract_lane' laneidx:u8	⇒	i64x2.extract_lane laneidx
'i64x2.replace_lane' laneidx:u8	⇒	i64x2.replace_lane laneidx
'f32x4.extract_lane' laneidx:u8	⇒	f32x4.extract_lane laneidx
'f32x4.replace_lane' laneidx:u8	⇒	f32x4.replace_lane laneidx
'f64x2.extract_lane' laneidx:u8	⇒	f64x2.extract_lane laneidx
'f64x2.replace_lane' laneidx:u8	⇒	f64x2.replace_lane laneidx
'i8x16.eq'	⇒	i8x16.eq
'i8x16.ne'	⇒	i8x16.ne
'i8x16.lt_s'	⇒	i8x16.lt_s
'i8x16.lt_u'	⇒	i8x16.lt_u
'i8x16.gt_s'	⇒	i8x16.gt_s
'i8x16.gt_u'	⇒	i8x16.gt_u
'i8x16.le_s'	⇒	i8x16.le_s
'i8x16.le_u'	⇒	i8x16.le_u
'i8x16.ge_s'	⇒	i8x16.ge_s
'i8x16.ge_u'	⇒	i8x16.ge_u
'i16x8.eq'	⇒	i16x8.eq
'i16x8.ne'	⇒	i16x8.ne
'i16x8.lt_s'	⇒	i16x8.lt_s
'i16x8.lt_u'	⇒	i16x8.lt_u
'i16x8.gt_s'	⇒	i16x8.gt_s
'i16x8.gt_u'	⇒	i16x8.gt_u
'i16x8.le_s'	⇒	i16x8.le_s
'i16x8.le_u'	⇒	i16x8.le_u
'i16x8.ge_s'	⇒	i16x8.ge_s
'i16x8.ge_u'	⇒	i16x8.ge_u
'i32x4.eq'	⇒	i32x4.eq
'i32x4.ne'	⇒	i32x4.ne
'i32x4.lt_s'	⇒	i32x4.lt_s
'i32x4.lt_u'	⇒	i32x4.lt_u
'i32x4.gt_s'	⇒	i32x4.gt_s
'i32x4.gt_u'	⇒	i32x4.gt_u
'i32x4.le_s'	⇒	i32x4.le_s
'i32x4.le_u'	⇒	i32x4.le_u
'i32x4.ge_s'	⇒	i32x4.ge_s
'i32x4.ge_u'	⇒	i32x4.ge_u

'i64x2.eq'	⇒	i64x2.eq
'i64x2.ne'	⇒	i64x2.ne
'i64x2.lt_s'	⇒	i64x2.lt_s
'i64x2.gt_s'	⇒	i64x2.gt_s
'i64x2.le_s'	⇒	i64x2.le_s
'i64x2.ge_s'	⇒	i64x2.ge_s
'f32x4.eq'	⇒	f32x4.eq
'f32x4.ne'	⇒	f32x4.ne
'f32x4.lt'	⇒	f32x4.lt
'f32x4.gt'	⇒	f32x4.gt
'f32x4.le'	⇒	f32x4.le
'f32x4.ge'	⇒	f32x4.ge
'f64x2.eq'	⇒	f64x2.eq
'f64x2.ne'	⇒	f64x2.ne
'f64x2.lt'	⇒	f64x2.lt
'f64x2.gt'	⇒	f64x2.gt
'f64x2.le'	⇒	f64x2.le
'f64x2.ge'	⇒	f64x2.ge
'v128.not'	⇒	v128.not
'v128.and'	⇒	v128.and
'v128.andnot'	⇒	v128.andnot
'v128.or'	⇒	v128.or
'v128.xor'	⇒	v128.xor
'v128.bitselect'	⇒	v128.bitselect
'v128.any_true'	⇒	v128.any_true
'i8x16.abs'	⇒	i8x16.abs
'i8x16.neg'	⇒	i8x16.neg
'i8x16.all_true'	⇒	i8x16.all_true
'i8x16.bitmask'	⇒	i8x16.bitmask
'i8x16.narrow_i16x8_s'	⇒	i8x16.narrow_i16x8_s
'i8x16.narrow_i16x8_u'	⇒	i8x16.narrow_i16x8_u
'i8x16.shl'	⇒	i8x16.shl
'i8x16.shr_s'	⇒	i8x16.shr_s
'i8x16.shr_u'	⇒	i8x16.shr_u
'i8x16.add'	⇒	i8x16.add
'i8x16.add_sat_s'	⇒	i8x16.add_sat_s
'i8x16.add_sat_u'	⇒	i8x16.add_sat_u
'i8x16.sub'	⇒	i8x16.sub
'i8x16.sub_sat_s'	⇒	i8x16.sub_sat_s
'i8x16.sub_sat_u'	⇒	i8x16.sub_sat_u
'i8x16.min_s'	⇒	i8x16.min_s
'i8x16.min_u'	⇒	i8x16.min_u
'i8x16.max_s'	⇒	i8x16.max_s
'i8x16.max_u'	⇒	i8x16.max_u
'i8x16.avgr_u'	⇒	i8x16.avgr_u
'i8x16.popcnt'	⇒	i8x16.popcnt

'i16x8.abs'	⇒	i16x8.abs
'i16x8.neg'	⇒	i16x8.neg
'i16x8.all_true'	⇒	i16x8.all_true
'i16x8.bitmask'	⇒	i16x8.bitmask
'i16x8.narrow_i32x4_s'	⇒	i16x8.narrow_i32x4_s
'i16x8.narrow_i32x4_u'	⇒	i16x8.narrow_i32x4_u
'i16x8.extend_low_i8x16_s'	⇒	i16x8.extend_low_i8x16_s
'i16x8.extend_high_i8x16_s'	⇒	i16x8.extend_high_i8x16_s
'i16x8.extend_low_i8x16_u'	⇒	i16x8.extend_low_i8x16_u
'i16x8.extend_high_i8x16_u'	⇒	i16x8.extend_high_i8x16_u
'i16x8.shl'	⇒	i16x8.shl
'i16x8.shr_s'	⇒	i16x8.shr_s
'i16x8.shr_u'	⇒	i16x8.shr_u
'i16x8.add'	⇒	i16x8.add
'i16x8.add_sat_s'	⇒	i16x8.add_sat_s
'i16x8.add_sat_u'	⇒	i16x8.add_sat_u
'i16x8.sub'	⇒	i16x8.sub
'i16x8.sub_sat_s'	⇒	i16x8.sub_sat_s
'i16x8.sub_sat_u'	⇒	i16x8.sub_sat_u
'i16x8.mul'	⇒	i16x8.mul
'i16x8.min_s'	⇒	i16x8.min_s
'i16x8.min_u'	⇒	i16x8.min_u
'i16x8.max_s'	⇒	i16x8.max_s
'i16x8.max_u'	⇒	i16x8.max_u
'i16x8.avgr_u'	⇒	i16x8.avgr_u
'i16x8.q15mulr_sat_s'	⇒	i16x8.q15mulr_sat_s
'i16x8.extmul_low_i8x16_s'	⇒	i16x8.extmul_low_i8x16_s
'i16x8.extmul_high_i8x16_s'	⇒	i16x8.extmul_high_i8x16_s
'i16x8.extmul_low_i8x16_u'	⇒	i16x8.extmul_low_i8x16_u
'i16x8.extmul_high_i8x16_u'	⇒	i16x8.extmul_high_i8x16_u
'i16x8.extadd_pairwise_i8x16_s'	⇒	i16x8.extadd_pairwise_i8x16_s
'i16x8.extadd_pairwise_i8x16_u'	⇒	i16x8.extadd_pairwise_i8x16_u
'i32x4.abs'	⇒	i32x4.abs
'i32x4.neg'	⇒	i32x4.neg
'i32x4.all_true'	⇒	i32x4.all_true
'i32x4.bitmask'	⇒	i32x4.bitmask
'i32x4.extadd_pairwise_i16x8_s'	⇒	i32x4.extadd_pairwise_i16x8_s
'i32x4.extend_low_i16x8_s'	⇒	i32x4.extend_low_i16x8_s
'i32x4.extend_high_i16x8_s'	⇒	i32x4.extend_high_i16x8_s
'i32x4.extend_low_i16x8_u'	⇒	i32x4.extend_low_i16x8_u
'i32x4.extend_high_i16x8_u'	⇒	i32x4.extend_high_i16x8_u
'i32x4.shl'	⇒	i32x4.shl
'i32x4.shr_s'	⇒	i32x4.shr_s
'i32x4.shr_u'	⇒	i32x4.shr_u
'i32x4.add'	⇒	i32x4.add
'i32x4.sub'	⇒	i32x4.sub
'i32x4.mul'	⇒	i32x4.mul
'i32x4.min_s'	⇒	i32x4.min_s
'i32x4.min_u'	⇒	i32x4.min_u
'i32x4.max_s'	⇒	i32x4.max_s
'i32x4.max_u'	⇒	i32x4.max_u
'i32x4.dot_i16x8_s'	⇒	i32x4.dot_i16x8_s
'i32x4.extmul_low_i16x8_s'	⇒	i32x4.extmul_low_i16x8_s
'i32x4.extmul_high_i16x8_s'	⇒	i32x4.extmul_high_i16x8_s
'i32x4.extmul_low_i16x8_u'	⇒	i32x4.extmul_low_i16x8_u
'i32x4.extmul_high_i16x8_u'	⇒	i32x4.extmul_high_i16x8_u

'i64x2.abs'	⇒	i64x2.abs
'i64x2.neg'	⇒	i64x2.neg
'i64x2.all_true'	⇒	i64x2.all_true
'i64x2.bitmask'	⇒	i64x2.bitmask
'i64x2.extend_low_i32x4_s'	⇒	i64x2.extend_low_i32x4_s
'i64x2.extend_high_i32x4_s'	⇒	i64x2.extend_high_i32x4_s
'i64x2.extend_low_i32x4_u'	⇒	i64x2.extend_low_i32x4_u
'i64x2.extend_high_i32x4_u'	⇒	i64x2.extend_high_i32x4_u
'i64x2.shl'	⇒	i64x2.shl
'i64x2.shr_s'	⇒	i64x2.shr_s
'i64x2.shr_u'	⇒	i64x2.shr_u
'i64x2.add'	⇒	i64x2.add
'i64x2.sub'	⇒	i64x2.sub
'i64x2.mul'	⇒	i64x2.mul
'i64x2.extmul_low_i32x4_s'	⇒	i64x2.extmul_low_i32x4_s
'i64x2.extmul_high_i32x4_s'	⇒	i64x2.extmul_high_i32x4_s
'i64x2.extmul_low_i32x4_u'	⇒	i64x2.extmul_low_i32x4_u
'i64x2.extmul_high_i32x4_u'	⇒	i64x2.extmul_high_i32x4_u

'f32x4.abs'	⇒	f32x4.abs
'f32x4.neg'	⇒	f32x4.neg
'f32x4.sqrt'	⇒	f32x4.sqrt
'f32x4.ceil'	⇒	f32x4.ceil
'f32x4.floor'	⇒	f32x4.floor
'f32x4.trunc'	⇒	f32x4.trunc
'f32x4.nearest'	⇒	f32x4.nearest
'f32x4.add'	⇒	f32x4.add
'f32x4.sub'	⇒	f32x4.sub
'f32x4.mul'	⇒	f32x4.mul
'f32x4.div'	⇒	f32x4.div
'f32x4.min'	⇒	f32x4.min
'f32x4.max'	⇒	f32x4.max
'f32x4.pmin'	⇒	f32x4.pmin
'f32x4.pmax'	⇒	f32x4.pmax

'f64x2.abs'	⇒	f64x2.abs
'f64x2.neg'	⇒	f64x2.neg
'f64x2.sqrt'	⇒	f64x2.sqrt
'f64x2.ceil'	⇒	f64x2.ceil
'f64x2.floor'	⇒	f64x2.floor
'f64x2.trunc'	⇒	f64x2.trunc
'f64x2.nearest'	⇒	f64x2.nearest
'f64x2.add'	⇒	f64x2.add
'f64x2.sub'	⇒	f64x2.sub
'f64x2.mul'	⇒	f64x2.mul
'f64x2.div'	⇒	f64x2.div
'f64x2.min'	⇒	f64x2.min
'f64x2.max'	⇒	f64x2.max
'f64x2.pmin'	⇒	f64x2.pmin
'f64x2.pmax'	⇒	f64x2.pmax

'i32x4.trunc_sat_f32x4_s'	⇒	i32x4.trunc_sat_f32x4_s
'i32x4.trunc_sat_f32x4_u'	⇒	i32x4.trunc_sat_f32x4_u
'i32x4.trunc_sat_f64x2_s_zero'	⇒	i32x4.trunc_sat_f64x2_s_zero
'i32x4.trunc_sat_f64x2_u_zero'	⇒	i32x4.trunc_sat_f64x2_u_zero
'f32x4.convert_i32x4_s'	⇒	f32x4.convert_i32x4_s
'f32x4.convert_i32x4_u'	⇒	f32x4.convert_i32x4_u
'f64x2.convert_low_i32x4_s'	⇒	f64x2.convert_low_i32x4_s
'f64x2.convert_low_i32x4_u'	⇒	f64x2.convert_low_i32x4_u
'f32x4.demote_f64x2_zero'	⇒	f32x4.demote_f64x2_zero
'f64x2.promote_low_f32x4'	⇒	f64x2.promote_low_f32x4

6.5.10 Folded Instructions

Instructions can be written as S-expressions by grouping them into *folded* form. In that notation, an instruction is wrapped in parentheses and optionally includes nested folded instructions to indicate its operands.

In the case of [block instructions](#), the folded form omits the 'end' delimiter. For *if* instructions, both branches have to be wrapped into nested S-expressions, headed by the keywords 'then' and 'else'.

The set of all phrases defined by the following abbreviations recursively forms the auxiliary syntactic class *foldedinstr*. Such a folded instruction can appear anywhere a regular instruction can.

```

('plaininstr foldedinstr*')           ≡ foldedinstr* plaininstr
('block' label blocktype instr*')     ≡ 'block' label blocktype instr* 'end'
('loop' label blocktype instr*')      ≡ 'loop' label blocktype instr* 'end'
('if' label blocktype foldedinstr* ('then' instr*') ('else' instr*')? ') ≡
    foldedinstr* 'if' label blocktype instr* 'else' (instr*)? 'end'

```

Note: For example, the instruction sequence

```
(local.get $x) (i32.const 2) i32.add (i32.const 3) i32.mul
```

can be folded into

```
(i32.mul (i32.add (local.get $x) (i32.const 2)) (i32.const 3))
```

Folded instructions are solely syntactic sugar, no additional syntactic or type-based checking is implied.

6.5.11 Expressions

Expressions are written as instruction sequences. No explicit 'end' keyword is included, since they only occur in bracketed positions.

$$\text{expr}_I ::= (\text{in}:\text{instr}_I)^* \Rightarrow \text{in}^* \text{end}$$

6.6 Modules

6.6.1 Indices

Indices can be given either in raw numeric form or as symbolic **identifiers** when bound by a respective construct. Such identifiers are looked up in the suitable space of the **identifier context** I .

typeid_I	$::=$	$x::u32$	\Rightarrow	x
	$ $	$v:\text{id}$	\Rightarrow	x (if $I.\text{types}[x] = v$)
funcid_I	$::=$	$x::u32$	\Rightarrow	x
	$ $	$v:\text{id}$	\Rightarrow	x (if $I.\text{funcs}[x] = v$)
tableid_I	$::=$	$x::u32$	\Rightarrow	x
	$ $	$v:\text{id}$	\Rightarrow	x (if $I.\text{tables}[x] = v$)
memid_I	$::=$	$x::u32$	\Rightarrow	x
	$ $	$v:\text{id}$	\Rightarrow	x (if $I.\text{mems}[x] = v$)
globalid_I	$::=$	$x::u32$	\Rightarrow	x
	$ $	$v:\text{id}$	\Rightarrow	x (if $I.\text{globals}[x] = v$)
elemid_I	$::=$	$x::u32$	\Rightarrow	x
	$ $	$v:\text{id}$	\Rightarrow	x (if $I.\text{elem}[x] = v$)
dataid_I	$::=$	$x::u32$	\Rightarrow	x
	$ $	$v:\text{id}$	\Rightarrow	x (if $I.\text{data}[x] = v$)
localid_I	$::=$	$x::u32$	\Rightarrow	x
	$ $	$v:\text{id}$	\Rightarrow	x (if $I.\text{locals}[x] = v$)
labelid_I	$::=$	$l::u32$	\Rightarrow	l
	$ $	$v:\text{id}$	\Rightarrow	l (if $I.\text{labels}[l] = v$)
$\text{fieldid}_{I,x}$	$::=$	$i::u32$	\Rightarrow	i
	$ $	$v:\text{id}$	\Rightarrow	i (if $I.\text{fields}[x][i] = v$)

6.6.2 Type Uses

A **type use** is a reference to a function **type definition**. It may optionally be augmented by explicit inlined **parameter** and **result** declarations. That allows binding symbolic **identifiers** to name the **local indices** of parameters. If inline declarations are given, then their types must match the referenced **function type**.

typeuse_I	$::=$	$(\text{'type' } x:\text{typeid}_I \text{'}) \Rightarrow x, I'$ (if $I.\text{typedefs}[x] = \text{sub final (func } [t_1^n] \rightarrow [t_2^*]) \wedge I' = \{\text{locals } (\epsilon)^n\}$)
	$ $	$(\text{'type' } x:\text{typeid}_I \text{'}) (t_1:\text{param})^* (t_2:\text{result})^* \Rightarrow x, I'$ (if $I.\text{typedefs}[x] = \text{sub final (func } [t_1^*] \rightarrow [t_2^*]) \wedge I' = \{\text{locals id(param)}^*\}$ well-formed)

Note: If inline declarations are given, their types must be *syntactically* equal to the types from the indexed definition; possible type **substitutions** from other definitions that might make them equal are not taken into account. This is to simplify syntactic pre-processing.

The synthesized attribute of a **typeuse** is a pair consisting of both the used **type index** and the local **identifier context** containing possible parameter identifiers. The following auxiliary function extracts optional identifiers from parameters:

$$\text{id}(\text{'(' 'param' id? ... ')'}) = \text{id?}$$

Note: Both productions overlap for the case that the function type is $[] \rightarrow []$. However, in that case, they also produce the same results, so that the choice is immaterial.

The **well-formedness** condition on I' ensures that the parameters do not contain duplicate identifiers.

Abbreviations

A **typeuse** may also be replaced entirely by inline **parameter** and **result** declarations. In that case, a **type index** is automatically inserted:

$$(t_1:\text{param})^* (t_2:\text{result})^* \equiv (' \text{'type'} x ') \text{ param}^* \text{ result}^*$$

where x is the smallest existing **type index** whose **recursive type** definition in the current module is of the form

$$(' \text{'rec'} (' \text{'type'} (' \text{'sub'} \text{'final'} (' \text{'func'} \text{ param}^* \text{ result}^* ') ') ')')$$

If no such index exists, then a new **recursive type** of the same form is inserted at the end of the module.

Abbreviations are expanded in the order they appear, such that previously inserted type definitions are reused by consecutive expansions.

6.6.3 Imports

The descriptors in imports can bind a symbolic function, table, memory, or global **identifier**.

$$\begin{aligned} \text{import}_I &::= (' \text{'import'} \text{ mod:name } nm:\text{name } d:\text{importdesc}_I ') \\ &\Rightarrow \{ \text{module } mod, \text{name } nm, \text{desc } d \} \\ \text{importdesc}_I &::= \begin{array}{l} (' \text{'func'} \text{ id}^? x, I':\text{typeuse}_I ') \\ | (' \text{'table'} \text{ id}^? tt:\text{tabletype}_I ') \\ | (' \text{'memory'} \text{ id}^? mt:\text{memtype}_I ') \\ | (' \text{'global'} \text{ id}^? gt:\text{globaltype}_I ') \end{array} \Rightarrow \begin{array}{l} \text{func } x \\ \text{table } tt \\ \text{mem } mt \\ \text{global } gt \end{array} \end{aligned}$$

Abbreviations

As an abbreviation, imports may also be specified inline with **function**, **table**, **memory**, or **global** definitions; see the respective sections.

6.6.4 Functions

Function definitions can bind a symbolic **function identifier**, and **local identifiers** for its **parameters** and **locals**.

$$\begin{aligned} \text{func}_I &::= (' \text{'func'} \text{ id}^? x, I':\text{typeuse}_I (\text{loc}:\text{local}_I)^* (\text{in}:\text{instr}_{I''})^* ') \\ &\Rightarrow \{ \text{type } x, \text{locals } \text{loc}^*, \text{body } \text{in}^* \text{ end} \} \\ &\quad (\text{if } I'' = I \oplus I' \oplus \{ \text{locals id}(\text{local})^* \} \text{ well-formed}) \\ \text{local}_I &::= (' \text{'local'} \text{ id}^? t:\text{valtype}_I ') \Rightarrow \{ \text{type } t \} \end{aligned}$$

The definition of the local **identifier context** I'' uses the following auxiliary function to extract optional identifiers from locals:

$$\text{id}(' \text{'local'} \text{ id}^? \dots ') = \text{id}^?$$

Note: The **well-formedness** condition on I'' ensures that parameters and locals do not contain duplicate identifiers.

Abbreviations

Multiple anonymous locals may be combined into a single declaration:

$$(\text{'local' valtype}^* \text{'}) \equiv ((\text{'local' valtype} \text{'}))^*$$

Functions can be defined as [imports](#) or [exports](#) inline:

$$\begin{aligned} (\text{'func' id}^? (\text{'import' name}_1 \text{ name}_2 \text{'}) \text{ typeuse} \text{'}) &\equiv \\ &(\text{'import' name}_1 \text{ name}_2 (\text{'func' id}^? \text{ typeuse} \text{'}) \text{'}) \\ (\text{'func' id}^? (\text{'export' name} \text{'}) \dots \text{'}) &\equiv \\ &(\text{'export' name} (\text{'func' id} \text{'}) \text{'}) (\text{'func' id}' \dots \text{'}) \\ &(\text{if id}^? \neq \epsilon \wedge \text{id}' = \text{id}^? \vee \text{id}^? = \epsilon \wedge \text{id}' \text{ fresh}) \end{aligned}$$

Note: The latter abbreviation can be applied repeatedly, if “...” contains additional export clauses. Consequently, a function declaration can contain any number of exports, possibly followed by an import.

6.6.5 Tables

Table definitions can bind a symbolic [table identifier](#).

$$\text{table}_I ::= (\text{'table' id}^? \text{ tt:tabletype}_I \text{ e:expr}_I \text{'}) \Rightarrow \{\text{type tt, init e}\}$$

Abbreviations

A table’s initialization [expression](#) can be omitted, in which case it defaults to [ref.null](#):

$$\begin{aligned} (\text{'table' id}^? \text{ tabletype} \text{'}) &\equiv (\text{'table' id}^? \text{ tabletype} (\text{'ref.null ht' \text{'})} \text{'}) \\ &(\text{if tabletype} = \text{limits} (\text{'ref' 'null'}^? \text{ ht} \text{'})) \end{aligned}$$

An [element segment](#) can be given inline with a table definition, in which case its offset is 0 and the [limits](#) of the [table type](#) are inferred from the length of the given segment:

$$\begin{aligned} &(\text{'table' id}^? \text{ reftype} (\text{'elem' expr}^n \text{:list(elemexpr) \text{'}} \text{'}) \text{'}) \equiv \\ &(\text{'table' id}' \text{ n n reftype} \text{'}) \\ &(\text{'elem' (\text{'table' id}' \text{'}) (\text{'i32.const' '0' \text{'}}) \text{ reftype list(elemexpr) \text{'}} \text{'}) \\ &(\text{if id}^? \neq \epsilon \wedge \text{id}' = \text{id}^? \vee \text{id}^? = \epsilon \wedge \text{id}' \text{ fresh}) \\ &(\text{'table' id}^? \text{ reftype} (\text{'elem' x}^n \text{:list(funcidx) \text{'}} \text{'}) \text{'}) \equiv \\ &(\text{'table' id}' \text{ n n reftype} \text{'}) \\ &(\text{'elem' (\text{'table' id}' \text{'}) (\text{'i32.const' '0' \text{'}}) \text{ reftype list((\text{'ref.func' funcidx} \text{'}) \text{'}) \text{'}} \text{'}) \\ &(\text{if id}^? \neq \epsilon \wedge \text{id}' = \text{id}^? \vee \text{id}^? = \epsilon \wedge \text{id}' \text{ fresh}) \end{aligned}$$

Tables can be defined as [imports](#) or [exports](#) inline:

$$\begin{aligned} &(\text{'table' id}^? (\text{'import' name}_1 \text{ name}_2 \text{'}) \text{ tabletype} \text{'}) \equiv \\ &(\text{'import' name}_1 \text{ name}_2 (\text{'table' id}^? \text{ tabletype} \text{'}) \text{'}) \\ &(\text{'table' id}^? (\text{'export' name} \text{'}) \dots \text{'}) \equiv \\ &(\text{'export' name} (\text{'table' id}' \text{'}) \text{'}) (\text{'table' id}' \dots \text{'}) \\ &(\text{if id}^? \neq \epsilon \wedge \text{id}' = \text{id}^? \vee \text{id}^? = \epsilon \wedge \text{id}' \text{ fresh}) \end{aligned}$$

Note: The latter abbreviation can be applied repeatedly, if “...” contains additional export clauses. Consequently, a table declaration can contain any number of exports, possibly followed by an import.

6.6.6 Memories

Memory definitions can bind a symbolic [memory identifier](#).

$$\text{mem}_I ::= \text{'(' 'memory' id? mt:memtype}_I \text{'')} \Rightarrow \{\text{type } mt\}$$

Abbreviations

A [data segment](#) can be given inline with a memory definition, in which case its offset is 0 and the [limits](#) of the [memory type](#) are inferred from the length of the data, rounded up to [page size](#):

$$\begin{aligned} \text{'(' 'memory' id? (' 'data' b":datastring '') '')} &\equiv \\ \text{'(' 'memory' id' m m ')} & \\ \text{'(' 'data' (' 'memory' id' ')) (' 'i32.const' '0' ')} &\text{datastring ')} \\ \text{(if id? } \neq \epsilon \wedge \text{id' = id? } \vee \text{id? = } \epsilon \wedge \text{id' fresh, } m = \text{ceil}(n/64 \text{ Ki}) &\end{aligned}$$

Memories can be defined as [imports](#) or [exports](#) inline:

$$\begin{aligned} \text{'(' 'memory' id? (' 'import' name}_1 \text{ name}_2 \text{'')} \text{ memtype ')} &\equiv \\ \text{'(' 'import' name}_1 \text{ name}_2 \text{'(' 'memory' id? memtype ')} \text{'')} & \\ \text{'(' 'memory' id? (' 'export' name ')} \dots \text{'')} &\equiv \\ \text{'(' 'export' name (' 'memory' id' ')} \text{'')} \text{'(' 'memory' id' } \dots \text{'')} & \\ \text{(if id? } \neq \epsilon \wedge \text{id' = id? } \vee \text{id? = } \epsilon \wedge \text{id' fresh)} &\end{aligned}$$

Note: The latter abbreviation can be applied repeatedly, if “...” contains additional export clauses. Consequently, a memory declaration can contain any number of exports, possibly followed by an import.

6.6.7 Globals

Global definitions can bind a symbolic [global identifier](#).

$$\text{global}_I ::= \text{'(' 'global' id? gt:globaltype}_I \text{ e:expr}_I \text{'')} \Rightarrow \{\text{type } gt, \text{init } e\}$$

Abbreviations

Globals can be defined as [imports](#) or [exports](#) inline:

$$\begin{aligned} \text{'(' 'global' id? (' 'import' name}_1 \text{ name}_2 \text{'')} \text{ globaltype ')} &\equiv \\ \text{'(' 'import' name}_1 \text{ name}_2 \text{'(' 'global' id? globaltype ')} \text{'')} & \\ \text{'(' 'global' id? (' 'export' name ')} \dots \text{'')} &\equiv \\ \text{'(' 'export' name (' 'global' id' ')} \text{'')} \text{'(' 'global' id' } \dots \text{'')} & \\ \text{(if id? } \neq \epsilon \wedge \text{id' = id? } \vee \text{id? = } \epsilon \wedge \text{id' fresh)} &\end{aligned}$$

Note: The latter abbreviation can be applied repeatedly, if “...” contains additional export clauses. Consequently, a global declaration can contain any number of exports, possibly followed by an import.

6.6.8 Exports

The syntax for exports mirrors their [abstract syntax](#) directly.

$$\begin{array}{llll}
 \text{export}_I & ::= & \text{'(' 'export' nm:name d:exportdesc}_I \text{')'} & \Rightarrow \{ \text{name nm, desc d} \} \\
 \text{exportdesc}_I & ::= & \text{'(' 'func' x:funcidx}_I \text{')'} & \Rightarrow \text{func } x \\
 & | & \text{'(' 'table' x:tableidx}_I \text{')'} & \Rightarrow \text{table } x \\
 & | & \text{'(' 'memory' x:memidx}_I \text{')'} & \Rightarrow \text{mem } x \\
 & | & \text{'(' 'global' x:globalidx}_I \text{')'} & \Rightarrow \text{global } x
 \end{array}$$

Abbreviations

As an abbreviation, exports may also be specified inline with [function](#), [table](#), [memory](#), or [global](#) definitions; see the respective sections.

6.6.9 Start Function

A [start function](#) is defined in terms of its index.

$$\text{start}_I ::= \text{'(' 'start' x:funcidx}_I \text{')'} \Rightarrow \{ \text{func } x \}$$

Note: At most one start function may occur in a module, which is ensured by a suitable side condition on the [module grammar](#).

6.6.10 Element Segments

Element segments allow for an optional [table index](#) to identify the table to initialize.

$$\begin{array}{llll}
 \text{elem}_I & ::= & \text{'(' 'elem' id? (et,y*):elemlist}_I \text{')'} & \Rightarrow \{ \text{type et, init y*, mode passive} \} \\
 & | & \text{'(' 'elem' id? x:tableuse}_I \text{' (' 'offset' e:expr}_I \text{')' (et,y*):elemlist}_I \text{')'} & \Rightarrow \{ \text{type et, init y*, mode active \{table x, offset e\}} \} \\
 & | & \text{'(' 'elem' id? 'declare' (et,y*):elemlist}_I \text{')'} & \Rightarrow \{ \text{type et, init y*, mode declare} \} \\
 \text{elemlist}_I & ::= & t:\text{reftype}_I \text{ y*}: \text{list}(\text{elemexpr}_I) & \Rightarrow (\text{type t, init y*}) \\
 \text{elemexpr}_I & ::= & \text{'(' 'item' e:expr}_I \text{')'} & \Rightarrow e \\
 \text{tableuse}_I & ::= & \text{'(' 'table' x:tableidx}_I \text{')'} & \Rightarrow x
 \end{array}$$

Abbreviations

As an abbreviation, a single instruction may occur in place of the offset of an active element segment or as an element expression:

$$\begin{array}{ll}
 \text{'(' instr ')} & \equiv \text{'(' 'offset' instr ')} \\
 \text{'(' instr ')} & \equiv \text{'(' 'item' instr ')}
 \end{array}$$

Also, the element list may be written as just a sequence of [function indices](#):

$$\text{'func' list(funcidx}_I) \equiv \text{'(ref' 'func' list('(' 'ref.func' funcidx}_I \text{')')}$$

A table use can be omitted, defaulting to 0. Furthermore, for backwards compatibility with earlier versions of WebAssembly, if the table use is omitted, the 'func' keyword can be omitted as well.

$$\begin{array}{ll}
 \epsilon & \equiv \text{'(' 'table' '0' ')} \\
 \text{'(' 'elem' id? (' 'offset' expr}_I \text{') list(funcidx}_I \text{')'} & \equiv \text{'(' 'elem' id? (' 'table' '0' ')} \text{'(' 'offset' expr}_I \text{')'}
 \end{array}$$

As another abbreviation, element segments may also be specified inline with [table](#) definitions; see the respective section.

6.6.11 Data Segments

Data segments allow for an optional [memory index](#) to identify the memory to initialize. The data is written as a [string](#), which may be split up into a possibly empty sequence of individual string literals.

```

dataI      ::= '(' 'data' id? b*:datastring ')'
              ⇒ {init b*, mode passive}
              | '(' 'data' id? x:memuseI '(' 'offset' e:exprI ')' b*:datastring ')'
              ⇒ {init b*, mode active {memory x', offset e}}
datastring ::= (b*:string)* ⇒ concat((b*)*)
memuseI   ::= '(' 'memory' x:memidxI ')' ⇒ x

```

Note: In the current version of WebAssembly, the only valid memory index is 0 or a symbolic [memory identifier](#) resolving to the same value.

Abbreviations

As an abbreviation, a single instruction may occur in place of the offset of an active data segment:

$$(' \text{instr} ') \equiv (' \text{'offset' instr} ')$$

Also, a memory use can be omitted, defaulting to 0.

$$\epsilon \equiv (' \text{'memory' '0'} ')$$

As another abbreviation, data segments may also be specified inline with [memory](#) definitions; see the respective section.

6.6.12 Modules

A module consists of a sequence of fields that can occur in any order. All definitions and their respective bound [identifiers](#) scope over the entire module, including the text preceding them.

A module may optionally bind an [identifier](#) that names the module. The name serves a documentary role only.

Note: Tools may include the module name in the [name section](#) of the [binary format](#).

```

module      ::= '(' 'module' id? (m:modulefieldI)* ')' ⇒ ⊕ m*
              (if I = ⊕ idc(modulefield)* well-formed)
modulefieldI ::= ty*:rectypeI ⇒ {types ty*}
              | im:importI   ⇒ {imports im}
              | fn:funcI     ⇒ {funcs fn}
              | ta:tableI    ⇒ {tables ta}
              | me:memI      ⇒ {mems me}
              | gl:globalI   ⇒ {globals gl}
              | ex:exportI   ⇒ {exports ex}
              | st:startI    ⇒ {start st}
              | el:elemI     ⇒ {elems el}
              | da:dataI     ⇒ {datas da}

```

The following restrictions are imposed on the composition of [modules](#): $m_1 \oplus m_2$ is defined if and only if

- $m_1.\text{start} = \epsilon \vee m_2.\text{start} = \epsilon$
- $m_1.\text{funcs} = m_1.\text{tables} = m_1.\text{mems} = m_1.\text{globals} = \epsilon \vee m_2.\text{imports} = \epsilon$

Note: The first condition ensures that there is at most one start function. The second condition enforces that all **imports** must occur before any regular definition of a **function**, **table**, **memory**, or **global**, thereby maintaining the ordering of the respective **index spaces**.

The **well-formedness** condition on I in the grammar for **module** ensures that no namespace contains duplicate identifiers.

The definition of the initial **identifier context** I uses the following auxiliary definition which maps each relevant definition to a singular context with one (possibly empty) identifier:

<code>idc('(' 'rec' typedef* ')')</code>	$= \bigoplus \text{idc}(\text{typedef})^*$
<code>idc('(' 'type' id? subtype ')')</code>	$= \{\text{types } (id?), \text{fields idf}(\text{subtype}), \text{typedefs } st\}$
<code>idc('(' 'func' id? ... ')')</code>	$= \{\text{funcs } (id?)\}$
<code>idc('(' 'table' id? ... ')')</code>	$= \{\text{tables } (id?)\}$
<code>idc('(' 'memory' id? ... ')')</code>	$= \{\text{mems } (id?)\}$
<code>idc('(' 'global' id? ... ')')</code>	$= \{\text{globals } (id?)\}$
<code>idc('(' 'elem' id? ... ')')</code>	$= \{\text{elem } (id?)\}$
<code>idc('(' 'data' id? ... ')')</code>	$= \{\text{data } (id?)\}$
<code>idc('(' 'import' ... '(' 'func' id? ... ')')')</code>	$= \{\text{funcs } (id?)\}$
<code>idc('(' 'import' ... '(' 'table' id? ... ')')')</code>	$= \{\text{tables } (id?)\}$
<code>idc('(' 'import' ... '(' 'memory' id? ... ')')')</code>	$= \{\text{mems } (id?)\}$
<code>idc('(' 'import' ... '(' 'global' id? ... ')')')</code>	$= \{\text{globals } (id?)\}$
<code>idc('(' ... ')')</code>	$= \{\}$
<code>idf('(' 'sub' ... comptype ')')</code>	$= \text{idf}(\text{comptype})$
<code>idf('(' 'struct' Tfield* ')')</code>	$= \bigoplus \text{idf}(\text{field})^*$
<code>idf('(' 'array' ... ')')</code>	$= \epsilon$
<code>idf('(' 'func' ... ')')</code>	$= \epsilon$
<code>idf('(' 'field' id? ... ')')</code>	$= id?$

Abbreviations

In a source file, the **module** `(module ...)` surrounding the module body may be omitted.

$$\text{modulefield}^* \equiv '(' \text{'module' modulefield}^* ')'$$

7.1 Embedding

A WebAssembly implementation will typically be *embedded* into a *host* environment. An *embedder* implements the connection between such a host environment and the WebAssembly semantics as defined in the main body of this specification. An embedder is expected to interact with the semantics in well-defined ways.

This section defines a suitable interface to the WebAssembly semantics in the form of entry points through which an embedder can access it. The interface is intended to be complete, in the sense that an embedder does not need to reference other functional parts of the WebAssembly specification directly.

Note: On the other hand, an embedder does not need to provide the host environment with access to all functionality defined in this interface. For example, an implementation may not support [parsing](#) of the [text format](#).

7.1.1 Types

In the description of the embedder interface, syntactic classes from the [abstract syntax](#) and the [runtime's abstract machine](#) are used as names for variables that range over the possible objects from that class. Hence, these syntactic classes can also be interpreted as types.

For numeric parameters, notation like $n : u32$ is used to specify a symbolic name in addition to the respective value range.

7.1.2 Booleans

Interface operation that are predicates return Boolean values:

$$bool ::= false \mid true$$

7.1.3 Errors

Failure of an interface operation is indicated by an auxiliary syntactic class:

$$error ::= error$$

In addition to the error conditions specified explicitly in this section, implementations may also return errors when specific [implementation limitations](#) are reached.

Note: Errors are abstract and unspecific with this definition. Implementations can refine it to carry suitable classifications and diagnostic messages.

7.1.4 Pre- and Post-Conditions

Some operations state *pre-conditions* about their arguments or *post-conditions* about their results. It is the embedder's responsibility to meet the pre-conditions. If it does, the post conditions are guaranteed by the semantics.

In addition to pre- and post-conditions explicitly stated with each operation, the specification adopts the following conventions for [runtime objects](#) (*store*, *moduleinst*, *externval*, *addresses*):

- Every runtime object passed as a parameter must be [valid](#) per an implicit pre-condition.
- Every runtime object returned as a result is [valid](#) per an implicit post-condition.

Note: As long as an embedder treats runtime objects as abstract and only creates and manipulates them through the interface defined here, all implicit pre-conditions are automatically met.

7.1.5 Store

`store_init() : store`

1. Return the empty [store](#).

$$\text{store_init}() = \{\text{funcs } \epsilon, \text{ mems } \epsilon, \text{ tables } \epsilon, \text{ globals } \epsilon\}$$

7.1.6 Modules

`module_decode(byte*) : module | error`

1. If there exists a derivation for the [byte](#) sequence *byte** as a [module](#) according to the [binary grammar](#) for [modules](#), yielding a [module](#) *m*, then return *m*.
2. Else, return [error](#).

$$\begin{aligned} \text{module_decode}(b^*) &= m && (\text{if } \text{module} \xRightarrow{*} m:b^*) \\ \text{module_decode}(b^*) &= \text{error} && (\text{otherwise}) \end{aligned}$$

$\text{module_parse}(\text{char}^*) : \text{module} \mid \text{error}$

1. If there exists a derivation for the source char^* as a **module** according to the text grammar for modules, yielding a **module** m , then return m .
2. Else, return **error**.

$$\begin{aligned} \text{module_parse}(c^*) &= m && (\text{if } \text{module} \xRightarrow{*} m:c^*) \\ \text{module_parse}(c^*) &= \text{error} && (\text{otherwise}) \end{aligned}$$

$\text{module_validate}(\text{module}) : \text{error}^?$

1. If **module** is **valid**, then return nothing.
2. Else, return **error**.

$$\begin{aligned} \text{module_validate}(m) &= \epsilon && (\text{if } \vdash m : \text{externtype}^* \rightarrow \text{externtype}'^*) \\ \text{module_validate}(m) &= \text{error} && (\text{otherwise}) \end{aligned}$$

$\text{module_instantiate}(\text{store}, \text{module}, \text{externval}^*) : (\text{store}, \text{moduleinst} \mid \text{error})$

1. Try **instantiating** **module** in **store** with external values externval^* as imports:
 - a. If it succeeds with a **module** instance moduleinst , then let **result** be moduleinst .
 - b. Else, let **result** be **error**.
2. Return the new store paired with **result**.

$$\begin{aligned} \text{module_instantiate}(S, m, ev^*) &= (S', F.\text{module}) && (\text{if } \text{instantiate}(S, m, ev^*) \hookrightarrow^* S'; F; \epsilon) \\ \text{module_instantiate}(S, m, ev^*) &= (S', \text{error}) && (\text{if } \text{instantiate}(S, m, ev^*) \hookrightarrow^* S'; F; \text{trap}) \end{aligned}$$

Note: The store may be modified even in case of an error.

$\text{module_imports}(\text{module}) : (\text{name}, \text{name}, \text{externtype})^*$

1. Pre-condition: **module** is **valid** with the external import types externtype^* and external export types $\text{externtype}'^*$.
2. Let import^* be the **imports** $\text{module}.\text{imports}$.
3. Assert: the length of import^* equals the length of externtype^* .
4. For each import_i in import^* and corresponding externtype_i in externtype^* , do:
 - a. Let result_i be the triple $(\text{import}_i.\text{module}, \text{import}_i.\text{name}, \text{externtype}_i)$.
5. Return the concatenation of all result_i , in index order.
6. Post-condition: each externtype_i is **valid** under the empty context.

$$\begin{aligned} \text{module_imports}(m) &= (im.\text{module}, im.\text{name}, \text{externtype})^* \\ &\quad (\text{if } im^* = m.\text{imports} \wedge \vdash m : \text{externtype}^* \rightarrow \text{externtype}'^*) \end{aligned}$$

$\text{module_exports}(\text{module}) : (\text{name}, \text{externtype})^*$

1. Pre-condition: module is valid with the external import types externtype^* and external export types $\text{externtype}'^*$.
2. Let export^* be the exports module.exports .
3. Assert: the length of export^* equals the length of $\text{externtype}'^*$.
4. For each export_i in export^* and corresponding $\text{externtype}'_i$ in $\text{externtype}'^*$, do:
 - a. Let result_i be the pair $(\text{export}_i.\text{name}, \text{externtype}'_i)$.
5. Return the concatenation of all result_i , in index order.
6. Post-condition: each $\text{externtype}'_i$ is valid under the empty context.

$$\begin{aligned} \text{module_exports}(m) &= (\text{ex}.\text{name}, \text{externtype}')^* \\ &\quad (\text{if } \text{ex}^* = m.\text{exports} \wedge \vdash m : \text{externtype}^* \rightarrow \text{externtype}'^*) \end{aligned}$$

7.1.7 Module Instances

$\text{instance_export}(\text{moduleinst}, \text{name}) : \text{externval} \mid \text{error}$

1. Assert: due to validity of the module instance moduleinst , all its export names are different.
2. If there exists an exportinst_i in $\text{moduleinst.exports}$ such that $\text{name } \text{exportinst}_i.\text{name}$ equals name , then:
 - a. Return the external value $\text{exportinst}_i.\text{value}$.
3. Else, return `error`.

$$\begin{aligned} \text{instance_export}(m, \text{name}) &= m.\text{exports}[i].\text{value} && (\text{if } m.\text{exports}[i].\text{name} = \text{name}) \\ \text{instance_export}(m, \text{name}) &= \text{error} && (\text{otherwise}) \end{aligned}$$

7.1.8 Functions

$\text{func_alloc}(\text{store}, \text{functype}, \text{hostfunc}) : (\text{store}, \text{funcaddr})$

1. Pre-condition: the functype is valid under the empty context.
2. Let funcaddr be the result of allocating a host function in store with function type functype and host function code hostfunc .
3. Return the new store paired with funcaddr .

$$\text{func_alloc}(S, \text{ta}, \text{code}) = (S', a) \quad (\text{if } \text{allocfunc}(S, \{\}, \text{ta}, \text{code}) = S', a)$$

Note: This operation assumes that hostfunc satisfies the pre- and post-conditions required for a function instance with type functype .

Regular (non-host) function instances can only be created indirectly through module instantiation.

$\text{func_type}(\text{store}, \text{funcaddr}) : \text{functype}$

1. Let functype be the function type $S.\text{funcs}[a].\text{type}$.
2. Return functype .
3. Post-condition: the returned function type is valid.

$$\text{func_type}(S, a) = S.\text{funcs}[a].\text{type}$$

$\text{func_invoke}(\text{store}, \text{funcaddr}, \text{val}^*) : (\text{store}, \text{val}^* \mid \text{error})$

1. Try **invoking** the function funcaddr in store with values val^* as arguments:
 - a. If it succeeds with values val^* as results, then let result be val^* .
 - b. Else it has trapped, hence let result be **error**.
2. Return the new store paired with result .

$$\begin{aligned} \text{func_invoke}(S, a, v^*) &= (S', v'^*) && (\text{if } \text{invoke}(S, a, v^*) \hookrightarrow^* S'; F; v'^*) \\ \text{func_invoke}(S, a, v^*) &= (S', \text{error}) && (\text{if } \text{invoke}(S, a, v^*) \hookrightarrow^* S'; F; \text{trap}) \end{aligned}$$

Note: The store may be modified even in case of an error.

7.1.9 Tables

$\text{table_alloc}(\text{store}, \text{tabletype}, \text{ref}) : (\text{store}, \text{tableaddr})$

1. Pre-condition: the tabletype is valid under the empty context.
2. Let tableaddr be the result of allocating a table in store with table type tabletype and initialization value ref .
3. Return the new store paired with tableaddr .

$$\text{table_alloc}(S, tt, r) = (S', a) \quad (\text{if } \text{alloctable}(S, tt, r) = S', a)$$

$\text{table_type}(\text{store}, \text{tableaddr}) : \text{tabletype}$

1. Return $S.\text{tables}[a].\text{type}$.
2. Post-condition: the returned table type is valid under the empty context.

$$\text{table_type}(S, a) = S.\text{tables}[a].\text{type}$$

$\text{table_read}(\text{store}, \text{tableaddr}, i : u32) : \text{ref} \mid \text{error}$

1. Let ti be the table instance $\text{store.tables}[\text{tableaddr}]$.
2. If i is larger than or equal to the length of $ti.\text{elem}$, then return **error**.
3. Else, return the reference value $ti.\text{elem}[i]$.

$$\begin{aligned} \text{table_read}(S, a, i) &= r && (\text{if } S.\text{tables}[a].\text{elem}[i] = r) \\ \text{table_read}(S, a, i) &= \text{error} && (\text{otherwise}) \end{aligned}$$

$\text{table_write}(\text{store}, \text{tableaddr}, i : u32, \text{ref}) : \text{store} \mid \text{error}$

1. Let ti be the table instance $\text{store.tables}[\text{tableaddr}]$.
2. If i is larger than or equal to the length of $ti.\text{elem}$, then return **error**.
3. Replace $ti.\text{elem}[i]$ with the reference value ref .
4. Return the updated store.

$$\begin{aligned} \text{table_write}(S, a, i, r) &= S' && (\text{if } S' = S \text{ with } \text{tables}[a].\text{elem}[i] = r) \\ \text{table_write}(S, a, i, r) &= \text{error} && (\text{otherwise}) \end{aligned}$$

$\text{table_size}(\text{store}, \text{tableaddr}) : u32$

1. Return the length of $\text{store.tables}[\text{tableaddr}].\text{elem}$.

$$\text{table_size}(S, a) = n \quad (\text{if } |S.\text{tables}[a].\text{elem}| = n)$$

$\text{table_grow}(\text{store}, \text{tableaddr}, n : u32, \text{ref}) : \text{store} \mid \text{error}$

1. Try growing the table instance $\text{store.tables}[\text{tableaddr}]$ by n elements with initialization value ref :
 - a. If it succeeds, return the updated store.
 - b. Else, return **error**.

$$\begin{aligned} \text{table_grow}(S, a, n, r) &= S' && (\text{if } S' = S \text{ with } \text{tables}[a] = \text{growtable}(S.\text{tables}[a], n, r)) \\ \text{table_grow}(S, a, n, r) &= \text{error} && (\text{otherwise}) \end{aligned}$$

7.1.10 Memories

$\text{mem_alloc}(\text{store}, \text{memtype}) : (\text{store}, \text{memaddr})$

1. Pre-condition: the memtype is valid under the empty context.
2. Let memaddr be the result of allocating a memory in store with memory type memtype .
3. Return the new store paired with memaddr .

$$\text{mem_alloc}(S, mt) = (S', a) \quad (\text{if } \text{allocmem}(S, mt) = S', a)$$

$\text{mem_type}(\text{store}, \text{memaddr}) : \text{memtype}$

1. Return $S.\text{mems}[a].\text{type}$.
2. Post-condition: the returned **memory type** is **valid** under the empty context.

$$\text{mem_type}(S, a) = S.\text{mems}[a].\text{type}$$

$\text{mem_read}(\text{store}, \text{memaddr}, i : u32) : \text{byte} \mid \text{error}$

1. Let mi be the **memory instance** $\text{store.mems}[\text{memaddr}]$.
2. If i is larger than or equal to the length of $mi.\text{bytes}$, then return **error**.
3. Else, return the **byte** $mi.\text{bytes}[i]$.

$$\begin{aligned} \text{mem_read}(S, a, i) &= b && (\text{if } S.\text{mems}[a].\text{bytes}[i] = b) \\ \text{mem_read}(S, a, i) &= \text{error} && (\text{otherwise}) \end{aligned}$$

$\text{mem_write}(\text{store}, \text{memaddr}, i : u32, \text{byte}) : \text{store} \mid \text{error}$

1. Let mi be the **memory instance** $\text{store.mems}[\text{memaddr}]$.
2. If $u32$ is larger than or equal to the length of $mi.\text{bytes}$, then return **error**.
3. Replace $mi.\text{bytes}[i]$ with byte .
4. Return the updated store.

$$\begin{aligned} \text{mem_write}(S, a, i, b) &= S' && (\text{if } S' = S \text{ with } \text{mems}[a].\text{bytes}[i] = b) \\ \text{mem_write}(S, a, i, b) &= \text{error} && (\text{otherwise}) \end{aligned}$$

$\text{mem_size}(\text{store}, \text{memaddr}) : u32$

1. Return the length of $\text{store.mems}[\text{memaddr}].\text{bytes}$ divided by the **page size**.

$$\text{mem_size}(S, a) = n \quad (\text{if } |S.\text{mems}[a].\text{bytes}| = n \cdot 64 \text{ Ki})$$

$\text{mem_grow}(\text{store}, \text{memaddr}, n : u32) : \text{store} \mid \text{error}$

1. Try **growing** the **memory instance** $\text{store.mems}[\text{memaddr}]$ by n pages:
 - a. If it succeeds, return the updated store.
 - b. Else, return **error**.

$$\begin{aligned} \text{mem_grow}(S, a, n) &= S' && (\text{if } S' = S \text{ with } \text{mems}[a] = \text{growmem}(S.\text{mems}[a], n)) \\ \text{mem_grow}(S, a, n) &= \text{error} && (\text{otherwise}) \end{aligned}$$

7.1.11 Globals

$\text{global_alloc}(\text{store}, \text{globaltype}, \text{val}) : (\text{store}, \text{globaladdr})$

1. Pre-condition: the *globaltype* is valid under the empty context.
2. Let *globaladdr* be the result of allocating a global in *store* with global type *globaltype* and initialization value *val*.
3. Return the new store paired with *globaladdr*.

$$\text{global_alloc}(S, gt, v) = (S', a) \quad (\text{if } \text{allocglobal}(S, gt, v) = S', a)$$

$\text{global_type}(\text{store}, \text{globaladdr}) : \text{globaltype}$

1. Return $S.\text{globals}[a].\text{type}$.
2. Post-condition: the returned global type is valid under the empty context.

$$\text{global_type}(S, a) = S.\text{globals}[a].\text{type}$$

$\text{global_read}(\text{store}, \text{globaladdr}) : \text{val}$

1. Let *gi* be the global instance $\text{store.globals}[\text{globaladdr}]$.
2. Return the value *gi.value*.

$$\text{global_read}(S, a) = v \quad (\text{if } S.\text{globals}[a].\text{value} = v)$$

$\text{global_write}(\text{store}, \text{globaladdr}, \text{val}) : \text{store} \mid \text{error}$

1. Let *gi* be the global instance $\text{store.globals}[\text{globaladdr}]$.
2. Let *mut t* be the structure of the global type *gi.type*.
3. If *mut* is not *var*, then return *error*.
4. Replace *gi.value* with the value *val*.
5. Return the updated store.

$$\begin{aligned} \text{global_write}(S, a, v) &= S' && (\text{if } S.\text{globals}[a].\text{type} = \text{var } t \wedge S' = S \text{ with } \text{globals}[a].\text{value} = v) \\ \text{global_write}(S, a, v) &= \text{error} && (\text{otherwise}) \end{aligned}$$

7.1.12 Values

$\text{ref_type}(\text{store}, \text{ref}) : \text{reftype}$

1. Pre-condition: the reference *ref* is valid under store *S*.
2. Return the reference type *t* with which *ref* is valid.
3. Post-condition: the returned reference type is valid under the empty context.

$$\text{ref_type}(S, r) = t \quad (\text{if } S \vdash r : t)$$

Note: In future versions of WebAssembly, not all references may carry precise type information at run time. In such cases, this function may return a less precise supertype.

$\text{val_default}(\text{valtype}) : \text{val}$

1. If $\text{default}_{\text{valtype}}$ is not defined, then return *error*.
1. Else, return the value $\text{default}_{\text{valtype}}$.

$$\begin{aligned} \text{val_default}(t) &= v && (\text{if } \text{default}_t = v) \\ \text{val_default}(t) &= \text{error} && (\text{if } \text{default}_t = \epsilon) \end{aligned}$$

7.1.13 Matching

$\text{match_valtype}(\text{valtype}_1, \text{valtype}_2) : \text{bool}$

1. Pre-condition: the value types valtype_1 and valtype_2 are valid under the empty context.
2. If valtype_1 matches valtype_2 , then return *true*.
3. Else, return *false*.

$$\begin{aligned} \text{match_reftype}(t_1, t_2) &= \text{true} && (\text{if } \vdash t_1 \leq t_2) \\ \text{match_reftype}(t_1, t_2) &= \text{false} && (\text{otherwise}) \end{aligned}$$

$\text{match_externtype}(\text{externtype}_1, \text{externtype}_2) : \text{bool}$

1. Pre-condition: the extern types externtype_1 and externtype_2 are valid under the empty context.
2. If externtype_1 matches externtype_2 , then return *true*.
3. Else, return *false*.

$$\begin{aligned} \text{match_externtype}(et_1, et_2) &= \text{true} && (\text{if } \vdash et_1 \leq et_2) \\ \text{match_externtype}(et_1, et_2) &= \text{false} && (\text{otherwise}) \end{aligned}$$

7.2 Implementation Limitations

Implementations typically impose additional restrictions on a number of aspects of a WebAssembly module or execution. These may stem from:

- physical resource limits,
- constraints imposed by the embedder or its environment,
- limitations of selected implementation strategies.

This section lists allowed limitations. Where restrictions take the form of numeric limits, no minimum requirements are given, nor are the limits assumed to be concrete, fixed numbers. However, it is expected that all implementations have “reasonably” large limits to enable common applications.

Note: A conforming implementation is not allowed to leave out individual *features*. However, designated subsets of WebAssembly may be specified in the future.

7.2.1 Syntactic Limits

Structure

An implementation may impose restrictions on the following dimensions of a module:

- the number of [types](#) in a [module](#)
- the number of [functions](#) in a [module](#), including imports
- the number of [tables](#) in a [module](#), including imports
- the number of [memories](#) in a [module](#), including imports
- the number of [globals](#) in a [module](#), including imports
- the number of [element segments](#) in a [module](#)
- the number of [data segments](#) in a [module](#)
- the number of [imports](#) to a [module](#)
- the number of [exports](#) from a [module](#)
- the number of [sub types](#) in a [recursive type](#)
- the subtyping depth of a [sub type](#)
- the number of fields in a [structure type](#)
- the number of parameters in a [function type](#)
- the number of results in a [function type](#)
- the number of parameters in a [block type](#)
- the number of results in a [block type](#)
- the number of [locals](#) in a [function](#)
- the number of [instructions](#) in a [function body](#)
- the number of [instructions](#) in a [structured control instruction](#)
- the number of [structured control instructions](#) in a [function](#)
- the nesting depth of [structured control instructions](#)
- the number of [label indices](#) in a [br_table](#) instruction
- the number of instructions in a [constant expression](#)
- the length of the array in a [array.new_fixed](#) instruction
- the length of an [element segment](#)
- the length of a [data segment](#)
- the length of a [name](#)
- the range of [characters](#) in a [name](#)

If the limits of an implementation are exceeded for a given module, then the implementation may reject the [validation](#), compilation, or [instantiation](#) of that module with an embedder-specific error.

Note: The last item allows [embedders](#) that operate in limited environments without support for [Unicode](#)⁴⁸ to limit the names of [imports](#) and [exports](#) to common subsets like [ASCII](#)⁴⁹.

⁴⁸ <https://www.unicode.org/versions/latest/>

⁴⁹ <https://webstore.ansi.org/RecordDetail.aspx?sku=INCITS+4-1986%5bR2012%5d>

Binary Format

For a module given in [binary format](#), additional limitations may be imposed on the following dimensions:

- the size of a [module](#)
- the size of any [section](#)
- the size of an individual [function's code](#)
- the size of a [structured control instruction](#)
- the size of an individual [constant expression's](#) instruction sequence
- the number of [sections](#)

Text Format

For a module given in [text format](#), additional limitations may be imposed on the following dimensions:

- the size of the [source text](#)
- the size of any syntactic element
- the size of an individual [token](#)
- the nesting depth of [folded instructions](#)
- the length of symbolic [identifiers](#)
- the range of literal [characters](#) allowed in the [source text](#)

7.2.2 Validation

An implementation may defer [validation](#) of individual [functions](#) until they are first [invoked](#).

If a function turns out to be invalid, then the invocation, and every consecutive call to the same function, results in a [trap](#).

Note: This is to allow implementations to use interpretation or just-in-time compilation for functions. The function must still be fully validated before execution of its body begins.

7.2.3 Execution

Restrictions on the following dimensions may be imposed during [execution](#) of a WebAssembly program:

- the number of allocated [module instances](#)
- the number of allocated [function instances](#)
- the number of allocated [table instances](#)
- the number of allocated [memory instances](#)
- the number of allocated [global instances](#)
- the number of allocated [structure instances](#)
- the number of allocated [array instances](#)
- the size of a [table instance](#)
- the size of a [memory instance](#)
- the size of an [array instance](#)

- the number of [frames](#) on the [stack](#)
- the number of [labels](#) on the [stack](#)
- the number of [values](#) on the [stack](#)

If the runtime limits of an implementation are exceeded during execution of a computation, then it may terminate that computation and report an embedder-specific error to the invoking code.

Some of the above limits may already be verified during instantiation, in which case an implementation may report exceedance in the same manner as for [syntactic limits](#).

Note: Concrete limits are usually not fixed but may be dependent on specifics, interdependent, vary over time, or depend on other implementation- or embedder-specific situations or events.

7.3 Type Soundness

The [type system](#) of WebAssembly is *sound*, implying both *type safety* and *memory safety* with respect to the WebAssembly semantics. For example:

- All types declared and derived during validation are respected at run time; e.g., every [local](#) or [global](#) variable will only contain type-correct values, every [instruction](#) will only be applied to operands of the expected type, and every [function invocation](#) always evaluates to a result of the right type (if it does not [trap](#) or [diverge](#)).
- No memory location will be read or written except those explicitly defined by the program, i.e., as a [local](#), a [global](#), an element in a [table](#), or a location within a linear [memory](#).
- There is no undefined behavior, i.e., the [execution rules](#) cover all possible cases that can occur in a [valid](#) program, and the rules are mutually consistent.

Soundness also is instrumental in ensuring additional properties, most notably, *encapsulation* of function and module scopes: no [locals](#) can be accessed outside their own function and no [module](#) components can be accessed outside their own module unless they are explicitly [exported](#) or [imported](#).

The typing rules defining WebAssembly [validation](#) only cover the *static* components of a WebAssembly program. In order to state and prove soundness precisely, the typing rules must be extended to the *dynamic* components of the abstract [runtime](#), that is, the [store](#), [configurations](#), and [administrative instructions](#).⁵⁰

7.3.1 Contexts

In order to check [rolled up](#) recursive types, the [context](#) is locally extended with an additional component that records the [sub type](#) corresponding to each [recursive type index](#) within the current [recursive type](#):

$$C ::= \{ \dots, \text{recs } subtype^* \}$$

⁵⁰ The formalization and theorems are derived from the following article: Andreas Haas, Andreas Rossberg, Derek Schuff, Ben Titzer, Dan Gohman, Luke Wagner, Alon Zakai, JF Bastien, Michael Holman. [Bringing the Web up to Speed with WebAssembly](#)^{Page 256, 51}. Proceedings of the 38th ACM SIGPLAN Conference on Programming Language Design and Implementation (PLDI 2017). ACM 2017.

⁵¹ <https://dl.acm.org/citation.cfm?doid=3062341.3062363>

7.3.2 Types

Well-formedness for [extended type forms](#) is defined as follows.

Heap Type *bot*

- The heap type is valid.

$$\overline{C \vdash \text{bot} : \text{ok}}$$

Heap Type *rec i*

- The recursive type index *i* must exist in *C.recs*.
- Then the heap type is valid.

$$\frac{C.\text{recs}[i] = \text{subtype}}{C \vdash \text{rec } i : \text{ok}}$$

Value Type *bot*

- The value type is valid.

$$\overline{C \vdash \text{bot} : \text{ok}}$$

Recursive Types *rec subtype**

- Let *C'* be the current context *C*, but where *recs* is *subtype**.
- There must be a [type index](#) *x*, such that for each sub type *subtype_i* in *subtype**:
 - Under the context *C'*, the sub type *subtype_i* must be valid for type index *x + i* and recursive type index *i*.
- Then the recursive type is valid for the type index *x*.

$$\frac{C, \text{recs } \text{subtype}^* \vdash \text{rec } \text{subtype}^* : \text{ok}(x, 0)}{C \vdash \text{rec } \text{subtype}^* : \text{ok}(x)}$$

$$\frac{C \vdash \text{subtype} : \text{ok}(x, i) \quad C \vdash \text{rec } \text{subtype}'^* : \text{ok}(x + 1, i + 1)}{C \vdash \text{rec } \text{subtype } \text{subtype}'^* : \text{ok}(x, i)}$$

Note: These rules are a generalisation of the ones [previously given](#).

Sub types *sub final? ht* comptype*

- The composite type *comptype* must be valid.
- The sequence *ht** may be no longer than 1.
- For every heap type *ht_k* in *ht**:
 - The heap type *ht_k* must be ordered before a type index *x* and recursive type index *i*, meaning:
 - * Either *ht_k* is a [defined type](#).
 - * Or *ht_k* is a [type index](#) *y_k* that is smaller than *x*.
 - * Or *ht_k* is a [recursive type index](#) *rec j_k* where *j_k* is smaller than *i*.

- Let sub type $subtype_k$ be the unrolling of the heap type ht_k , meaning:
 - * Either ht_k is a defined type $deftype_k$, then $subtype_k$ must be the unrolling of $deftype_k$.
 - * Or ht_k is a type index y_k , then $subtype_k$ must be the unrolling of the defined type $C.types[y_k]$.
 - * Or ht_k is a recursive type index $rec\ j_k$, then $subtype_k$ must be $C.recs[j_k]$.
- The sub type $subtype_k$ must not contain `final`.
- Let $comptype'_k$ be the composite type in $subtype_k$.
- The composite type $comptype$ must match $comptype'_k$.
- Then the sub type is valid for the type index x and recursive type index i .

$$\frac{\begin{array}{l} |ht^*| \leq 1 \quad (ht \prec x, i)^* \quad (\text{unroll}_C(ht) = \text{sub } ht'^* \text{ } comptype')^* \\ C \vdash comptype : \text{ok} \quad (C \vdash comptype \leq comptype')^* \end{array}}{C \vdash \text{sub final? } ht^* \text{ } comptype : \text{ok}(x, i)}$$

where:

$$\begin{aligned} (deftype \prec x, i) &= \text{true} \\ (y \prec x, i) &= y < x \\ (rec\ j \prec x, i) &= j < i \\ \text{unroll}_C(deftype) &= \text{unroll}(deftype) \\ \text{unroll}_C(y) &= \text{unroll}(C.types[y]) \\ \text{unroll}_C(rec\ j) &= C.recs[j] \end{aligned}$$

Note: This rule is a generalisation of the ones previously given, which only allowed type indices as supertypes.

7.3.3 Subtyping

In a rolled-up recursive type, a recursive type indices $rec\ i$ matches another heap type ht if:

- Let $\text{sub final? } ht'^* \text{ } comptype$ be the sub type $C.recs[i]$.
- The heap type ht is contained in ht'^* .

$$\frac{C.recs[i] = \text{sub final? } (ht_1^* \text{ } ht \text{ } ht_2^*) \text{ } comptype}{C \vdash \text{rec } i \leq ht}$$

Note: This rule is only invoked when checking validity of rolled-up recursive types.

7.3.4 Results

Results can be classified by result types as follows.

Results val^*

- For each value val_i in val^* :
 - The value val_i is valid with some value type t_i .
- Let t^* be the concatenation of all t_i .
- Then the result is valid with result type $[t^*]$.

$$\frac{(S \vdash val : t)^*}{S \vdash val^* : [t^*]}$$

Results trap

- The result is valid with result type $[t^*]$, for any valid closed result types.

$$\frac{\vdash [t^*] : \text{ok}}{S \vdash \text{trap} : [t^*]}$$

7.3.5 Store Validity

The following typing rules specify when a runtime store S is *valid*. A valid store must consist of **function**, **table**, **memory**, **global**, and **module** instances that are themselves valid, relative to S .

To that end, each kind of instance is classified by a respective **function**, **table**, **memory**, or **global** type. Module instances are classified by *module contexts*, which are regular **contexts** repurposed as module types describing the **index spaces** defined by a module.

Store S

- Each function instance funcinst_i in $S.\text{funcs}$ must be valid with some function type functype_i .
- Each table instance tableinst_i in $S.\text{tables}$ must be valid with some table type tabletype_i .
- Each memory instance meminst_i in $S.\text{mems}$ must be valid with some memory type memtype_i .
- Each global instance globalinst_i in $S.\text{globals}$ must be valid with some global type globaltype_i .
- Each element instance eleminst_i in $S.\text{elems}$ must be valid with some reference type reftype_i .
- Each data instance datainst_i in $S.\text{datas}$ must be valid.
- Each structure instance structinst_i in $S.\text{structs}$ must be valid.
- Each array instance arrayinst_i in $S.\text{arrays}$ must be valid.
- No **reference** to a bound **structure address** must be reachable from itself through a path consisting only of indirections through immutable structure or array **fields**.
- No **reference** to a bound **array address** must be reachable from itself through a path consisting only of indirections through immutable structure or array **fields**.
- Then the store is valid.

$$\frac{\begin{array}{l} (S \vdash \text{funcinst} : \text{deftype})^* \quad (S \vdash \text{tableinst} : \text{tabletype})^* \\ (S \vdash \text{meminst} : \text{memtype})^* \quad (S \vdash \text{globalinst} : \text{globaltype})^* \\ (S \vdash \text{eleminst} : \text{reftype})^* \quad (S \vdash \text{datainst} : \text{ok})^* \\ (S \vdash \text{structinst} : \text{ok})^* \quad (S \vdash \text{arrayinst} : \text{ok})^* \\ S = \{\text{funcs } \text{funcinst}^*, \text{globals } \text{globalinst}^*, \text{tables } \text{tableinst}^*, \text{mems } \text{meminst}^*, \\ \text{elems } \text{eleminst}^*, \text{datas } \text{datainst}^*, \text{structs } \text{structinst}^*, \text{arrays } \text{arrayinst}^*\} \\ (S.\text{structs}[a_s] = \text{structinst})^* \quad ((\text{ref.struct } a_s) \gg_S^+ (\text{ref.struct } a_s))^* \\ (S.\text{arrays}[a_a] = \text{arrayinst})^* \quad ((\text{ref.array } a_a) \gg_S^+ (\text{ref.array } a_a))^* \end{array}}{\vdash S : \text{ok}}$$

where $\text{val}_1 \gg_S^+ \text{val}_2$ denotes the transitive closure of the following *reachability* relation on values:

$$\begin{array}{lll} (\text{ref.struct } a) & \gg_S & S.\text{structs}[a].\text{fields}[i] \quad \text{if } \text{expand}(S.\text{structs}[a].\text{type}) = \text{struct } ft_1^i (\text{const } st) ft_2^* \\ (\text{ref.array } a) & \gg_S & S.\text{arrays}[a].\text{fields}[i] \quad \text{if } \text{expand}(S.\text{arrays}[a].\text{type}) = \text{array } (\text{const } st) \\ (\text{ref.extern } ref) & \gg_S & ref \end{array}$$

Note: The constraint on reachability through immutable fields prevents the presence of cyclic data structures that can not be constructed in the language. Cycles can only be formed using mutation.

Function Instances $\{\text{type } \text{functype}, \text{module } \text{moduleinst}, \text{code } \text{func}\}$

- The function type functype must be valid under an empty context.
- The module instance moduleinst must be valid with some context C .
- Under context C :
 - The function func must be valid with some function type $\text{functype}'$.
 - The function type $\text{functype}'$ must match functype .
- Then the function instance is valid with function type functype .

$$\frac{\begin{array}{c} \vdash \text{functype} : \text{ok} \quad S \vdash \text{moduleinst} : C \\ C \vdash \text{func} : \text{functype}' \quad C \vdash \text{functype}' \leq \text{functype} \end{array}}{S \vdash \{\text{type } \text{functype}, \text{module } \text{moduleinst}, \text{code } \text{func}\} : \text{functype}}$$

Host Function Instances $\{\text{type } \text{functype}, \text{hostfunc } hf\}$

- The function type functype must be valid under an empty context.
- Let $[t_1^*] \rightarrow [t_2^*]$ be the function type functype .
- For every valid store S_1 extending S and every sequence val^* of values whose types coincide with t_1^* :
 - Executing hf in store S_1 with arguments val^* has a non-empty set of possible outcomes.
 - For every element R of this set:
 - * Either R must be \perp (i.e., divergence).
 - * Or R consists of a valid store S_2 extending S_1 and a result result whose type coincides with t_2^* .
- Then the function instance is valid with function type functype .

$$\frac{\begin{array}{c} \forall S_1, \text{val}^*, \vdash S_1 : \text{ok} \wedge \vdash S \preceq S_1 \wedge S_1 \vdash \text{val}^* : [t_1^*] \implies \\ hf(S_1; \text{val}^*) \supset \emptyset \wedge \\ \forall R \in hf(S_1; \text{val}^*), R = \perp \vee \\ \exists S_2, \text{result}, \vdash S_2 : \text{ok} \wedge \vdash S_1 \preceq S_2 \wedge S_2 \vdash \text{result} : [t_2^*] \wedge R = (S_2; \text{result}) \end{array}}{\vdash [t_1^*] \rightarrow [t_2^*] : \text{ok} \quad S \vdash \{\text{type } [t_1^*] \rightarrow [t_2^*], \text{hostfunc } hf\} : [t_1^*] \rightarrow [t_2^*]}$$

Note: This rule states that, if appropriate pre-conditions about store and arguments are satisfied, then executing the host function must satisfy appropriate post-conditions about store and results. The post-conditions match the ones in the [execution rule](#) for invoking host functions.

Any store under which the function is invoked is assumed to be an extension of the current store. That way, the function itself is able to make sufficient assumptions about future stores.

Table Instances $\{\text{type } (\text{limits } t), \text{elem } \text{ref}^*\}$

- The table type $\text{limits } t$ must be valid under the empty context.
- The length of ref^* must equal limits.min .
- For each reference ref_i in the table's elements ref^n :
 - The reference ref_i must be valid with some reference type t'_i .
 - The reference type t'_i must match the reference type t .
- Then the table instance is valid with table type $\text{limits } t$.

$$\frac{\vdash \text{limits } t : \text{ok} \quad n = \text{limits.min} \quad (S \vdash \text{ref} : t')^n \quad (\vdash t' \leq t)^n}{S \vdash \{\text{type } (\text{limits } t), \text{elem } \text{ref}^n\} : \text{limits } t}$$

Memory Instances $\{\text{type } \text{limits}, \text{bytes } b^*\}$

- The memory type *limits* must be valid under the empty context.
- The length of b^* must equal *limits.min* multiplied by the page size 64 Ki.
- Then the memory instance is valid with memory type *limits*.

$$\frac{\vdash \text{limits} : \text{ok} \quad n = \text{limits.min} \cdot 64 \text{ Ki}}{S \vdash \{\text{type } \text{limits}, \text{bytes } b^n\} : \text{limits}}$$

Global Instances $\{\text{type } (\text{mut } t), \text{value } \text{val}\}$

- The global type *mut t* must be valid under the empty context.
- The value *val* must be valid with some value type t' .
- The value type t' must match the value type *t*.
- Then the global instance is valid with global type *mut t*.

$$\frac{\vdash \text{mut } t : \text{ok} \quad S \vdash \text{val} : t' \quad \vdash t' \leq t}{S \vdash \{\text{type } (\text{mut } t), \text{value } \text{val}\} : \text{mut } t}$$

Element Instances $\{\text{type } t, \text{elem } \text{ref}^*\}$

- The reference type *t* must be valid under the empty context.
- For each reference ref_i in the elements ref^n :
 - The reference ref_i must be valid with some reference type t'_i .
 - The reference type t'_i must match the reference type *t*.
- Then the element instance is valid with reference type *t*.

$$\frac{\vdash t : \text{ok} \quad (S \vdash \text{ref} : t')^* \quad (\vdash t' \leq t)^*}{S \vdash \{\text{type } t, \text{elem } \text{ref}^*\} : t}$$

Data Instances $\{\text{bytes } b^*\}$

- The data instance is valid.

$$\overline{S \vdash \{\text{bytes } b^*\} : \text{ok}}$$

Structure Instances $\{\text{type } \textit{deftype}, \text{fields } \textit{fieldval}^*\}$

- The defined type $\textit{deftype}$ must be valid.
- The expansion of $\textit{deftype}$ must be a structure type $\text{struct } \textit{fieldtype}^*$.
- The length of the sequence of field values $\textit{fieldval}^*$ must be the same as the length of the sequence of field types $\textit{fieldtype}^*$.
- For each field value $\textit{fieldval}_i$ in $\textit{fieldval}^*$ and corresponding field type $\textit{fieldtype}_i$ in $\textit{fieldtype}^*$:
 - Let $\textit{fieldtype}_i$ be $\text{mut } \textit{storagetype}_i$.
 - The field value $\textit{fieldval}_i$ must be valid with storage type $\textit{storagetype}_i$.
- Then the structure instance is valid.

$$\frac{\vdash dt : \text{ok} \quad \text{expand}(dt) = \text{struct } (\text{mut } st)^* \quad (S \vdash fv : st)^*}{S \vdash \{\text{type } dt, \text{fields } fv^*\} : \text{ok}}$$

Array Instances $\{\text{type } \textit{deftype}, \text{fields } \textit{fieldval}^*\}$

- The defined type $\textit{deftype}$ must be valid.
- The expansion of $\textit{deftype}$ must be an array type $\text{array } \textit{fieldtype}$.
- Let $\textit{fieldtype}$ be $\text{mut } \textit{storagetype}$.
- For each field value $\textit{fieldval}_i$ in $\textit{fieldval}^*$:
 - The field value $\textit{fieldval}_i$ must be valid with storage type $\textit{storagetype}$.
- Then the array instance is valid.

$$\frac{\vdash dt : \text{ok} \quad \text{expand}(dt) = \text{array } (\text{mut } st) \quad (S \vdash fv : st)^*}{S \vdash \{\text{type } dt, \text{fields } fv^*\} : \text{ok}}$$

Field Values $\textit{fieldval}$

- If $\textit{fieldval}$ is a value val , then:
 - The value val must be valid with value type t .
 - Then the field value is valid with value type t .
- Else, $\textit{fieldval}$ is a packed value $\textit{packval}$:
 - Let $\textit{packtype}.\text{pack } i$ be the field value $\textit{fieldval}$.
 - Then the field value is valid with packed type $\textit{packtype}$.

$$\overline{S \vdash \textit{pt}.\text{pack } i : \textit{pt}}$$

Export Instances {name *name*, value *externval*}

- The external value *externval* must be valid with some external type *externtype*.
- Then the export instance is valid.

$$\frac{S \vdash \text{externval} : \text{externtype}}{S \vdash \{\text{name } \text{name}, \text{value } \text{externval}\} : \text{ok}}$$

Module Instances *moduleinst*

- Each defined type *deftype_i* in *moduleinst.types* must be valid under the empty context.
- For each function address *funcaddr_i* in *moduleinst.funcs*, the external value func *funcaddr_i* must be valid with some external type *functype_i*.
- For each table address *tableaddr_i* in *moduleinst.tables*, the external value table *tableaddr_i* must be valid with some external type *tabletype_i*.
- For each memory address *memaddr_i* in *moduleinst.mems*, the external value mem *memaddr_i* must be valid with some external type *memtype_i*.
- For each global address *globaladdr_i* in *moduleinst.globals*, the external value global *globaladdr_i* must be valid with some external type *globaltype_i*.
- For each element address *elemaddr_i* in *moduleinst.elems*, the element instance *S.elems[elemaddr_i]* must be valid with some reference type *reftype_i*.
- For each data address *dataaddr_i* in *moduleinst.datas*, the data instance *S.datas[dataaddr_i]* must be valid with *ok_i*.
- Each export instance *exportinst_i* in *moduleinst.exports* must be valid.
- For each export instance *exportinst_i* in *moduleinst.exports*, the name *exportinst_i.name* must be different from any other name occurring in *moduleinst.exports*.
- Let *deftype** be the concatenation of all *deftype_i* in order.
- Let *functype** be the concatenation of all *functype_i* in order.
- Let *tabletype** be the concatenation of all *tabletype_i* in order.
- Let *memtype** be the concatenation of all *memtype_i* in order.
- Let *globaltype** be the concatenation of all *globaltype_i* in order.
- Let *reftype** be the concatenation of all *reftype_i* in order.
- Let *ok** be the concatenation of all *ok_i* in order.
- Let *m* be the length of *moduleinst.funcs*.
- Let *x** be the sequence of function indices from 0 to *m* − 1.
- Then the module instance is valid with context {types *deftype**, funcs *functype**, tables *tabletype**, mems *memtype**, globals *globaltype**, elems *reftype**, datas *ok**, refs *x**}.

$$\frac{
\begin{array}{l}
(\vdash \text{deftype} : \text{ok})^* \\
(S \vdash \text{func } \text{funcaddr} : \text{func } \text{functype})^* \quad (S \vdash \text{table } \text{tableaddr} : \text{table } \text{tabletype})^* \\
(S \vdash \text{mem } \text{memaddr} : \text{mem } \text{memtype})^* \quad (S \vdash \text{global } \text{globaladdr} : \text{global } \text{globaltype})^* \\
(S \vdash S.\text{elems}[\text{elemaddr}] : \text{reftype})^* \quad (S \vdash S.\text{datas}[\text{dataaddr}] : \text{ok})^* \\
(S \vdash \text{exportinst} : \text{ok})^* \quad (\text{exportinst.name})^* \text{ disjoint}
\end{array}
}{
\begin{array}{l}
S \vdash \{ \text{types } \text{deftype}^*, \\
\text{funcs } \text{funcaddr}^*, \\
\text{tables } \text{tableaddr}^*, \\
\text{mems } \text{memaddr}^*, \\
\text{globals } \text{globaladdr}^*, \\
\text{elems } \text{elemaddr}^*, \\
\text{datas } \text{dataaddr}^*, \\
\text{exports } \text{exportinst}^* \} : \{ \text{types } \text{deftype}^*, \\
\text{funcs } \text{functype}^*, \\
\text{tables } \text{tabletype}^*, \\
\text{mems } \text{memtype}^*, \\
\text{globals } \text{globaltype}^*, \\
\text{elems } \text{reftype}^*, \\
\text{datas } \text{ok}^*, \\
\text{refs } 0 \dots (|\text{funcaddr}^*| - 1) \}
\end{array}$$

7.3.6 Configuration Validity

To relate the WebAssembly [type system](#) to its [execution semantics](#), the [typing rules for instructions](#) must be extended to [configurations](#) $S; T$, which relates the [store](#) to [execution threads](#).

Configurations and threads are classified by their [result type](#). In addition to the store S , threads are typed under a [return type](#) $\text{resulttype}^?$, which controls whether and with which type a [return](#) instruction is allowed. This type is absent (ϵ) except for instruction sequences inside an administrative [frame](#) instruction.

Finally, [frames](#) are classified with [frame contexts](#), which extend the [module contexts](#) of a frame's associated [module instance](#) with the [locals](#) that the frame contains.

Configurations $S; T$

- The [store](#) S must be [valid](#).
- Under no allowed return type, the [thread](#) T must be [valid](#) with some [result type](#) $[t^*]$.
- Then the configuration is valid with the [result type](#) $[t^*]$.

$$\frac{\vdash S : \text{ok} \quad S; \epsilon \vdash T : [t^*]}{\vdash S; T : [t^*]}$$

Threads $F; \text{instr}^*$

- Let $\text{resulttype}^?$ be the current allowed return type.
- The [frame](#) F must be [valid](#) with a [context](#) C .
- Let C' be the same [context](#) as C , but with [return](#) set to $\text{resulttype}^?$.
- Under context C' , the instruction sequence instr^* must be [valid](#) with some type $\square \rightarrow [t^*]$.
- Then the thread is valid with the [result type](#) $[t^*]$.

$$\frac{S \vdash F : C \quad S; C, \text{return } \text{resulttype}^? \vdash \text{instr}^* : \square \rightarrow [t^*]}{S; \text{resulttype}^? \vdash F; \text{instr}^* : [t^*]}$$

Frames $\{\text{locals } val^*, \text{module } moduleinst\}$

- The **module instance** $moduleinst$ must be **valid** with some **module context** C .
- Each **value** val_i in val^* must be **valid** with some **value type** t_i .
- Let t^* be the concatenation of all t_i in order.
- Let C' be the same **context** as C , but with the **value types** t^* prepended to the **locals** list.
- Then the frame is **valid** with **frame context** C' .

$$\frac{S \vdash moduleinst : C \quad (S \vdash val : t)^*}{S \vdash \{\text{locals } val^*, \text{module } moduleinst\} : (C, \text{locals } t^*)}$$

7.3.7 Administrative Instructions

Typing rules for **administrative instructions** are specified as follows. In addition to the **context** C , typing of these instructions is defined under a given **store** S .

To that end, all previous typing judgements $C \vdash prop$ are generalized to include the store, as in $S; C \vdash prop$, by implicitly adding S to all rules – S is never modified by the pre-existing rules, but it is accessed in the extra rules for **administrative instructions** given below.

trap

- The instruction is **valid** with any **valid instruction type** of the form $[t_1^*] \rightarrow [t_2^*]$.

$$\frac{C \vdash [t_1^*] \rightarrow [t_2^*] : \text{ok}}{S; C \vdash \text{trap} : [t_1^*] \rightarrow [t_2^*]}$$

val

- The **value** val must be **valid** with **value type** t .
- Then it is **valid** as an instruction with type $[] \rightarrow [t]$.

$$\frac{S \vdash val : t}{S; C \vdash val : [] \rightarrow [t]}$$

invoke funcaddr

- The **external function value** $func \text{ funcaddr}$ must be **valid** with **external function type** $funcfunc\text{type}'$.
- Let $[t_1^*] \rightarrow [t_2^*]$ be the **function type** $func\text{type}$.
- Then the instruction is **valid** with type $[t_1^*] \rightarrow [t_2^*]$.

$$\frac{S \vdash func \text{ funcaddr} : func \ [t_1^*] \rightarrow [t_2^*]}{S; C \vdash \text{invoke } funcaddr : [t_1^*] \rightarrow [t_2^*]}$$

$\text{label}_n\{instr_0^*\} \text{ instr}^* \text{ end}$

- The instruction sequence $instr_0^*$ must be **valid** with some type $[t_1^n] \rightarrow_{x^*} [t_2^*]$.
- Let C' be the same **context** as C , but with the **result type** $[t_1^n]$ prepended to the **labels** list.
- Under context C' , the instruction sequence $instr^*$ must be **valid** with type $[] \rightarrow_{x'^*} [t_2^*]$.
- Then the compound instruction is valid with type $[] \rightarrow [t_2^*]$.

$$\frac{S; C \vdash instr_0^* : [t_1^n] \rightarrow_{x^*} [t_2^*] \quad S; C, \text{labels } [t_1^n] \vdash instr^* : [] \rightarrow_{x'^*} [t_2^*]}{S; C \vdash \text{label}_n\{instr_0^*\} \text{ instr}^* \text{ end} : [] \rightarrow [t_2^*]}$$

$\text{frame}_n\{F\} \text{ instr}^* \text{ end}$

- Under the **valid** return type $[t^n]$, the **thread** $F; instr^*$ must be **valid** with **result type** $[t^n]$.
- Then the compound instruction is valid with type $[] \rightarrow [t^n]$.

$$\frac{C \vdash [t^n] : \text{ok} \quad S; [t^n] \vdash F; instr^* : [t^n]}{S; C \vdash \text{frame}_n\{F\} \text{ instr}^* \text{ end} : [] \rightarrow [t^n]}$$

7.3.8 Store Extension

Programs can mutate the **store** and its contained instances. Any such modification must respect certain invariants, such as not removing allocated instances or changing immutable definitions. While these invariants are inherent to the execution semantics of WebAssembly **instructions** and **modules**, **host functions** do not automatically adhere to them. Consequently, the required invariants must be stated as explicit constraints on the **invocation** of host functions. Soundness only holds when the **embedder** ensures these constraints.

The necessary constraints are codified by the notion of store *extension*: a store state S' extends state S , written $S \preceq S'$, when the following rules hold.

Note: Extension does not imply that the new store is valid, which is defined separately [above](#).

Store S

- The length of $S.\text{funcs}$ must not shrink.
- The length of $S.\text{tables}$ must not shrink.
- The length of $S.\text{mems}$ must not shrink.
- The length of $S.\text{globals}$ must not shrink.
- The length of $S.\text{elems}$ must not shrink.
- The length of $S.\text{datas}$ must not shrink.
- The length of $S.\text{structs}$ must not shrink.
- The length of $S.\text{arrays}$ must not shrink.
- For each **function instance** $funcinst_i$ in the original $S.\text{funcs}$, the new function instance must be an **extension** of the old.
- For each **table instance** $tableinst_i$ in the original $S.\text{tables}$, the new table instance must be an **extension** of the old.
- For each **memory instance** $meminst_i$ in the original $S.\text{mems}$, the new memory instance must be an **extension** of the old.

- For each **global instance** $globalinst_i$ in the original $S.globals$, the new global instance must be an **extension** of the old.
- For each **element instance** $eleminst_i$ in the original $S.elems$, the new element instance must be an **extension** of the old.
- For each **data instance** $datainst_i$ in the original $S.datas$, the new data instance must be an **extension** of the old.
- For each **structure instance** $structinst_i$ in the original $S.structs$, the new structure instance must be an **extension** of the old.
- For each **array instance** $arrayinst_i$ in the original $S.arrays$, the new array instance must be an **extension** of the old.

$$\begin{array}{lll}
 S_1.funcs = funcinst_1^* & S_2.funcs = funcinst_1'^* funcinst_2^* & (\vdash funcinst_1 \preceq funcinst_1')^* \\
 S_1.tables = tableinst_1^* & S_2.tables = tableinst_1'^* tableinst_2^* & (\vdash tableinst_1 \preceq tableinst_1')^* \\
 S_1.mems = meminst_1^* & S_2.mems = meminst_1'^* meminst_2^* & (\vdash meminst_1 \preceq meminst_1')^* \\
 S_1.globals = globalinst_1^* & S_2.globals = globalinst_1'^* globalinst_2^* & (\vdash globalinst_1 \preceq globalinst_1')^* \\
 S_1.elems = eleminst_1^* & S_2.elems = eleminst_1'^* eleminst_2^* & (\vdash eleminst_1 \preceq eleminst_1')^* \\
 S_1.datas = datainst_1^* & S_2.datas = datainst_1'^* datainst_2^* & (\vdash datainst_1 \preceq datainst_1')^* \\
 S_1.structs = structinst_1^* & S_2.structs = structinst_1'^* structinst_2^* & (\vdash structinst_1 \preceq structinst_1')^* \\
 S_1.arrays = arrayinst_1^* & S_2.arrays = arrayinst_1'^* arrayinst_2^* & (\vdash arrayinst_1 \preceq arrayinst_1')^* \\
 \hline
 & \vdash S_1 \preceq S_2
 \end{array}$$

Function Instance $funcinst$

- A function instance must remain unchanged.

$$\vdash funcinst \preceq funcinst$$

Table Instance $tableinst$

- The table type $tableinst.type$ must remain unchanged.
- The length of $tableinst.elem$ must not shrink.

$$\frac{n_1 \leq n_2}{\vdash \{\text{type } tt, \text{elem } (fa_1^?)^{n_1}\} \preceq \{\text{type } tt, \text{elem } (fa_2^?)^{n_2}\}}$$

Memory Instance $meminst$

- The memory type $meminst.type$ must remain unchanged.
- The length of $meminst.bytes$ must not shrink.

$$\frac{n_1 \leq n_2}{\vdash \{\text{type } mt, \text{bytes } b_1^{n_1}\} \preceq \{\text{type } mt, \text{bytes } b_2^{n_2}\}}$$

Global Instance *globalinst*

- The global type *globalinst.type* must remain unchanged.
- Let *mut t* be the structure of *globalinst.type*.
- If *mut* is *const*, then the value *globalinst.value* must remain unchanged.

$$\frac{mut = \text{var} \vee val_1 = val_2}{\vdash \{\text{type } (mut\ t), \text{value } val_1\} \preceq \{\text{type } (mut\ t), \text{value } val_2\}}$$

Element Instance *eleminst*

- The reference type *eleminst.type* must remain unchanged.
- The list *eleminst.elem* must:
 - either remain unchanged,
 - or shrink to length 0.

$$\vdash \{\text{type } t, \text{elem } a^*\} \preceq \{\text{type } t, \text{elem } a^*\}$$

$$\vdash \{\text{type } t, \text{elem } a^*\} \preceq \{\text{type } t, \text{elem } \epsilon\}$$

Data Instance *datainst*

- The list *datainst.bytes* must:
 - either remain unchanged,
 - or shrink to length 0.

$$\vdash \{\text{bytes } b^*\} \preceq \{\text{bytes } b^*\}$$

$$\vdash \{\text{bytes } b^*\} \preceq \{\text{bytes } \epsilon\}$$

Structure Instance *structinst*

- The defined type *structinst.type* must remain unchanged.
- Assert: due to store well-formedness, the expansion of *structinst.type* is a structure type.
- Let *struct fieldtype** be the expansion of *structinst.type*.
- The length of the list *structinst.fields* must remain unchanged.
- Assert: due to store well-formedness, the length of *structinst.fields* is the same as the length of *fieldtype**.
- For each field value *fieldval_i* in *structinst.fields* and corresponding field type *fieldtype_i* in *fieldtype**:
 - Let *mut_i st_i* be the structure of *fieldtype_i*.
 - If *mut_i* is *const*, then the field value *fieldval_i* must remain unchanged.

$$\frac{(mut = \text{var} \vee fieldval_1 = fieldval_2)^*}{\vdash \{\text{type } (mut\ st)^*, \text{fields } fieldval_1^*\} \preceq \{\text{type } (mut\ st)^*, \text{fields } fieldval_2^*\}}$$

Array Instance *arrayinst*

- The defined type *arrayinst.type* must remain unchanged.
- Assert: due to store well-formedness, the expansion of *arrayinst.type* is an array type.
- Let *array fieldtype* be the expansion of *arrayinst.type*.
- The length of the list *arrayinst.fields* must remain unchanged.
- Let *mut st* be the structure of *fieldtype*.
- If *mut* is *const*, then the sequence of field values *arrayinst.fields* must remain unchanged.

$$\frac{\text{mut} = \text{var} \vee \text{fieldval}_1^* = \text{fieldval}_2^*}{\vdash \{\text{type}(\text{mut st}), \text{fields fieldval}_1^*\} \preceq \{\text{type}(\text{mut st}), \text{fields fieldval}_2^*\}}$$

7.3.9 Theorems

Given the definition of *valid configurations*, the standard soundness theorems hold.⁵²⁵⁴

Theorem (Preservation). If a configuration $S;T$ is *valid* with *result type* $[t^*]$ (i.e., $\vdash S;T : [t^*]$), and steps to $S';T'$ (i.e., $S;T \hookrightarrow S';T'$), then $S';T'$ is a *valid configuration* with the same *result type* (i.e., $\vdash S';T' : [t^*]$). Furthermore, S' is an *extension* of S (i.e., $\vdash S \preceq S'$).

A *terminal thread* is one whose sequence of *instructions* is a *result*. A *terminal configuration* is a configuration whose thread is terminal.

Theorem (Progress). If a configuration $S;T$ is *valid* (i.e., $\vdash S;T : [t^*]$ for some *result type* $[t^*]$), then either it is terminal, or it can step to some configuration $S';T'$ (i.e., $S;T \hookrightarrow S';T'$).

From Preservation and Progress the soundness of the WebAssembly type system follows directly.

Corollary (Soundness). If a configuration $S;T$ is *valid* (i.e., $\vdash S;T : [t^*]$ for some *result type* $[t^*]$), then it either diverges or takes a finite number of steps to reach a terminal configuration $S';T'$ (i.e., $S;T \hookrightarrow^* S';T'$) that is *valid* with the same *result type* (i.e., $\vdash S';T' : [t^*]$) and where S' is an *extension* of S (i.e., $\vdash S \preceq S'$).

In other words, every thread in a *valid configuration* either runs forever, traps, or terminates with a result that has the expected type. Consequently, given a *valid store*, no computation defined by *instantiation* or *invocation* of a *valid module* can “crash” or otherwise (mis)behave in ways not covered by the *execution* semantics given in this specification.

7.4 Type System Properties

7.4.1 Principal Types

The *type system* of WebAssembly features both *subtyping* and simple forms of *polymorphism* for *instruction types*. That has the effect that every instruction or instruction sequence can be classified with multiple different instruction types.

However, the typing rules still allow deriving *principal types* for instruction sequences. That is, every *valid instruction sequence* has one particular type scheme, possibly containing some unconstrained place holder *type variables*, that is a subtype of all its *valid instruction types*, after substituting its type variables with suitable specific types.

⁵² A machine-verified version of the formalization and soundness proof of the PLDI 2017 paper is described in the following article: Conrad Watt. *Mechanising and Verifying the WebAssembly Specification*^{Page 269, 53}. Proceedings of the 7th ACM SIGPLAN Conference on Certified Programs and Proofs (CPP 2018). ACM 2018.

⁵³ <https://dl.acm.org/citation.cfm?id=3167082>

⁵⁴ Machine-verified formalizations and soundness proofs of the semantics from the official specification are described in the following article: Conrad Watt, Xiaojia Rao, Jean Pichon-Pharabod, Martin Bodin, Philippa Gardner. *Two Mechanisations of WebAssembly 1.0*⁵⁵. Proceedings of the 24th International Symposium on Formal Methods (FM 2021). Springer 2021.

⁵⁵ https://link.springer.com/chapter/10.1007/978-3-030-90870-6_4

Moreover, when deriving an instruction type in a “forward” manner, i.e., the *input* of the instruction sequence is already fixed to specific types, then it has a principal *output* type expressible without type variables, up to a possibly [polymorphic stack](#) bottom representable with one single variable. In other words, “forward” principal types are effectively *closed*.

Note: For example, in isolation, the instruction `ref.as_non_null` has the type $[(\text{ref } \text{null } ht)] \rightarrow [(\text{ref } ht)]$ for any choice of valid [heap type](#) ht . Moreover, if the input type $[(\text{ref } \text{null } ht)]$ is already determined, i.e., a specific ht is given, then the output type $[(\text{ref } ht)]$ is fully determined as well.

The implication of the latter property is that a validator for *complete* instruction sequences (as they occur in valid modules) can be implemented with a simple left-to-right [algorithm](#) that does not require the introduction of type variables.

A typing algorithm capable of handling *partial* instruction sequences (as might be considered for program analysis or program manipulation) needs to introduce type variables and perform substitutions, but it does not need to perform backtracking or record any non-syntactic constraints on these type variables.

Technically, the [syntax](#) of [heap](#), [value](#), and [result](#) types can be enriched with type variables as follows:

$$\begin{aligned} \text{null} &::= \text{null}^? \mid \alpha_{\text{null}} \\ \text{heapttype} &::= \dots \mid \alpha_{\text{heapttype}} \\ \text{reftype} &::= \text{ref } \text{null } \text{heapttype} \\ \text{valtype} &::= \dots \mid \alpha_{\text{valtype}} \mid \alpha_{\text{numvectype}} \\ \text{resulttype} &::= [\alpha_{\text{valtype}^*}^? \text{valtype}^*] \end{aligned}$$

where each α_{xyz} ranges over a set of type variables for syntactic class xyz , respectively. The special class *numvectype* is defined as $\text{numtype} \mid \text{vectype} \mid \text{bot}$, and is only needed to handle unannotated [select](#) instructions.

A type is *closed* when it does not contain any type variables, and *open* otherwise. A *type substitution* σ is a finite mapping from type variables to closed types of the respective syntactic class. When applied to an open type, it replaces the type variables α from its domain with the respective $\sigma(\alpha)$.

Theorem (Principal Types). If an instruction sequence instr^* is [valid](#) with some closed [instruction type](#) instrtype (i.e., $C \vdash \text{instr}^* : \text{instrtype}$), then it is also valid with a possibly open instruction type instrtype_{\min} (i.e., $C \vdash \text{instr}^* : \text{instrtype}_{\min}$), such that for *every* closed type $\text{instrtype}'$ with which instr^* is valid (i.e., for all $C \vdash \text{instr}^* : \text{instrtype}'$), there exists a substitution σ , such that $\sigma(\text{instrtype}_{\min})$ is a subtype of $\text{instrtype}'$ (i.e., $C \vdash \sigma(\text{instrtype}_{\min}) \leq \text{instrtype}'$). Furthermore, instrtype_{\min} is unique up to the choice of type variables.

Theorem (Closed Principal Forward Types). If closed input type $[t_1^*]$ is given and the instruction sequence instr^* is [valid](#) with [instruction type](#) $[t_1^*] \rightarrow_{x^*} [t_2^*]$ (i.e., $C \vdash \text{instr}^* : [t_1^*] \rightarrow_{x^*} [t_2^*]$), then it is also valid with instruction type $[t_1^*] \rightarrow_{x^*} [\alpha_{\text{valtype}^*}^? t^*]$ (i.e., $C \vdash \text{instr}^* : [t_1^*] \rightarrow_{x^*} [\alpha_{\text{valtype}^*}^? t^*]$), where all t^* are closed, such that for *every* closed result type $[t_2'^*]$ with which instr^* is valid (i.e., for all $C \vdash \text{instr}^* : [t_1^*] \rightarrow_{x^*} [t_2'^*]$), there exists a substitution σ , such that $[t_2'^*] = [\sigma(\alpha_{\text{valtype}^*}^?) t^*]$.

7.4.2 Type Lattice

The [Principal Types](#) property depends on the existence of a *greatest lower bound* for any pair of types.

Theorem (Greatest Lower Bounds for Value Types). For any two value types t_1 and t_2 that are [valid](#) (i.e., $C \vdash t_1 : \text{ok}$ and $C \vdash t_2 : \text{ok}$), there exists a valid value type t that is a subtype of both t_1 and t_2 (i.e., $C \vdash t : \text{ok}$ and $C \vdash t \leq t_1$ and $C \vdash t \leq t_2$), such that *every* valid value type t' that also is a subtype of both t_1 and t_2 (i.e., for all $C \vdash t' : \text{ok}$ and $C \vdash t' \leq t_1$ and $C \vdash t' \leq t_2$), is a subtype of t (i.e., $C \vdash t' \leq t$).

Note: The greatest lower bound of two types may be [bot](#).

Theorem (Conditional Least Upper Bounds for Value Types). Any two value types t_1 and t_2 that are [valid](#) (i.e., $C \vdash t_1 : \text{ok}$ and $C \vdash t_2 : \text{ok}$) either have no common supertype, or there exists a valid value type t that is a supertype of both t_1 and t_2 (i.e., $C \vdash t : \text{ok}$ and $C \vdash t_1 \leq t$ and $C \vdash t_2 \leq t$), such that *every* valid value type t'

that also is a supertype of both t_1 and t_2 (i.e., for all $C \vdash t' : \text{ok}$ and $C \vdash t_1 \leq t'$ and $C \vdash t_2 \leq t'$), is a supertype of t (i.e., $C \vdash t \leq t'$).

Note: If a top type was added to the type system, a least upper bound would exist for any two types.

Corollary (Type Lattice). Assuming the addition of a provisional top type, **value types** form a lattice with respect to their **subtype** relation.

Finally, value types can be partitioned into multiple disjoint hierarchies that are not related by subtyping, except through **bot**.

Theorem (Disjoint Subtype Hierarchies). The greatest lower bound of two **value types** is **bot** or **ref bot** if and only if they do not have a least upper bound.

In other words, types that do not have common supertypes, do not have common subtypes either (other than **bot** or **ref bot**), and vice versa.

Note: Types from disjoint hierarchies can safely be represented in mutually incompatible ways in an implementation, because their values can never flow to the same place.

7.4.3 Compositionality

Valid instruction sequences can be freely *composed*, as long as their types match up.

Theorem (Composition). If two instruction sequences instr_1^* and instr_2^* are valid with types $[t_1^*] \rightarrow_{x_1^*} [t^*]$ and $[t^*] \rightarrow_{x_2^*} [t_2^*]$, respectively (i.e., $C \vdash \text{instr}_1^* : [t_1^*] \rightarrow_{x_1^*} [t^*]$ and $C \vdash \text{instr}_2^* : [t^*] \rightarrow_{x_2^*} [t_2^*]$), then the concatenated instruction sequence $(\text{instr}_1^* \text{ instr}_2^*)$ is valid with type $[t_1^*] \rightarrow_{x_1^* x_2^*} [t_2^*]$ (i.e., $C \vdash \text{instr}_1^* \text{ instr}_2^* : [t_1^*] \rightarrow_{x_1^* x_2^*} [t_2^*]$).

Note: More generally, instead of a shared type $[t^*]$, it suffices if the output type of instr_1^* is a **subtype** of the input type of instr_2^* , since the subtype can always be weakened to its supertype by subsumption.

Inversely, valid instruction sequences can also freely be *decomposed*, that is, splitting them anywhere produces two instruction sequences that are both **valid**.

Theorem (Decomposition). If an instruction sequence instr^* that is valid with type $[t_1^*] \rightarrow_{x^*} [t_2^*]$ (i.e., $C \vdash \text{instr}^* : [t_1^*] \rightarrow_{x^*} [t_2^*]$) is split into two instruction sequences instr_1^* and instr_2^* at any point (i.e., $\text{instr}^* = \text{instr}_1^* \text{ instr}_2^*$), then these are separately valid with some types $[t_1^*] \rightarrow_{x_1^*} [t^*]$ and $[t^*] \rightarrow_{x_2^*} [t_2^*]$, respectively (i.e., $C \vdash \text{instr}_1^* : [t_1^*] \rightarrow_{x_1^*} [t^*]$ and $C \vdash \text{instr}_2^* : [t^*] \rightarrow_{x_2^*} [t_2^*]$), where $x^* = x_1^* x_2^*$.

Note: This property holds because validation is required even for unreachable code. Without that, instr_2^* might not be valid in isolation.

7.5 Validation Algorithm

The specification of WebAssembly **validation** is purely *declarative*. It describes the constraints that must be met by a **module** or **instruction** sequence to be valid.

This section sketches the skeleton of a sound and complete *algorithm* for effectively validating code, i.e., sequences of **instructions**. (Other aspects of validation are straightforward to implement.)

In fact, the algorithm is expressed over the flat sequence of opcodes as occurring in the **binary format**, and performs only a single pass over it. Consequently, it can be integrated directly into a decoder.

The algorithm is expressed in typed pseudo code whose semantics is intended to be self-explanatory.

7.5.1 Data Structures

Types

Value types are representable as sets of enumerations:

```
type num_type = I32 | I64 | F32 | F64
type vec_type = V128
type heap_type =
  Any | Eq | I31 | Struct | Array | None |
  Func | Nofunc | Extern | Noextern | Bot |
  Def(def : def_type)
type ref_type = Ref(heap : heap_type, null : bool)
type val_type = num_type | vec_type | ref_type | Bot

func is_num(t : val_type) : bool =
  return t = I32 || t = I64 || t = F32 || t = F64 || t = Bot

func is_vec(t : val_type) : bool =
  return t = V128 || t = Bot

func is_ref(t : val_type) : bool =
  return not (is_num t || is_vec t) || t = Bot
```

Similarly, `defined types` `def_type` can be represented:

```
type pack_type = I8 | I16
type field_type = Field(val : val_type | pack_type, mut : bool)

type struct_type = Struct(fields : list(field_type))
type array_type = Array(fields : field_type)
type func_type = Func(params : list(val_type), results : list(val_type))
type comp_type = struct_type | array_type | func_type

type sub_type = Sub(super : list(def_type), body : comp_type, final : bool)
type rec_type = Rec(types : list(sub_type))

type def_type = Def(rec : rec_type, proj : int32)

func unpack_field(t : field_type) : val_type =
  if (it = I8 || t = I16) return I32
  return t

func expand_def(t : def_type) : comp_type =
  return t.rec.types[t.proj].body
```

These representations assume that all types have been `closed` by substituting all `type indices` (in `concrete heap types` and in `sub types`) with their respective `defined types`. This includes *recursive* references to enclosing `defined types`, such that type representations form graphs and may be *cyclic* for *recursive types*.

We assume that all types have been *canonicalized*, such that equality on two type representations holds if and only if their *closures* are syntactically equivalent, making it a constant-time check.

Note: For the purpose of type canonicalization, recursive references from a `heap type` to an enclosing `recursive type` (i.e., forward edges in the graph that form a cycle) need to be distinguished from references to previously defined types. However, this distinction does not otherwise affect validation, so is ignored here. In the graph representation, all recursive types are effectively infinitely *unrolled*.

We further assume that [validation](#) and [subtyping](#) checks are defined on value types, as well as a few auxiliary functions on composite types:

```
func validate_val_type(t : val_type)
func validate_ref_type(t : ref_type)

func matches_val(t1 : val_type, t2 : val_type) : bool
func matches_ref(t1 : val_type, t2 : val_type) : bool

func is_func(t : comp_type) : bool
func is_struct(t : comp_type) : bool
func is_array(t : comp_type) : bool
```

Finally, the following function computes the least precise supertype of a given [heap type](#) (its corresponding top type):

```
func top_heap_type(t : heap_type) : heap_type =
  switch (t)
  case (Any | Eq | I31 | Struct | Array | None)
    return Any
  case (Func | Nofunc)
    return Func
  case (Extern | Noextern)
    return Extern
  case (Def(dt))
    switch (dt.rec.types[dt.proj].body)
    case (Struct(_) | Array(_))
      return Any
    case (Func(_))
      return Func
  case (Bot)
    raise CannotOccurInSource
```

Context

Validation requires a [context](#) for checking uses of [indices](#). For the purpose of presenting the algorithm, it is maintained in a set of global variables:

```
var return_type : list(val_type)
var types : array(def_type)
var locals : array(val_type)
var locals_init : array(bool)
var globals : array(global_type)
var funcs : array(func_type)
var tables : array(table_type)
var mems : array(mem_type)
```

This assumes suitable representations for the various [types](#) besides `val_type`, which are omitted here.

For locals, there is an additional array recording the initialization status of each local.

Stacks

The algorithm uses three separate stacks: the *value stack*, the *control stack*, and the *initialization stack*. The value stack tracks the [types](#) of operand values on the [stack](#). The control stack tracks surrounding [structured control instructions](#) and their associated [blocks](#). The initialization stack records all [locals](#) that have been initialized since the beginning of the function.

```
type val_stack = stack(val_type)
type init_stack = stack(u32)

type ctrl_stack = stack(ctrl_frame)
type ctrl_frame = {
  opcode : opcode
  start_types : list(val_type)
  end_types : list(val_type)
  val_height : nat
  init_height : nat
  unreachable : bool
}
```

For each entered block, the control stack records a *control frame* with the originating opcode, the types on the top of the operand stack at the start and end of the block (used to check its result as well as branches), the height of the operand stack at the start of the block (used to check that operands do not underflow the current block), the height of the initialization stack at the start of the block (used to reset initialization status at the end of the block), and a flag recording whether the remainder of the block is unreachable (used to handle [stack-polymorphic](#) typing after branches).

For the purpose of presenting the algorithm, these stacks are simply maintained as global variables:

```
var vals : val_stack
var inits : init_stack
var ctrls : ctrl_stack
```

However, these variables are not manipulated directly by the main checking function, but through a set of auxiliary functions:

```
func push_val(type : val_type) =
  vals.push(type)

func pop_val() : val_type =
  if (vals.size() = ctrls[0].height && ctrls[0].unreachable) return Bot
  error_if(vals.size() = ctrls[0].height)
  return vals.pop()

func pop_val(expect : val_type) : val_type =
  let actual = pop_val()
  error_if(not matches_val(actual, expect))
  return actual

func pop_num() : num_type | Bot =
  let actual = pop_val()
  error_if(not is_num(actual))
  return actual

func pop_ref() : ref_type =
  let actual = pop_val()
  error_if(not is_ref(actual))
  if (actual = Bot) return Ref(Bot, false)
```

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```

return actual

func push_vals(types : list(val_type)) = foreach (t in types) push_val(t)
func pop_vals(types : list(val_type)) : list(val_type) =
  var popped := []
  foreach (t in reverse(types)) popped.prepend(pop_val(t))
  return popped

```

Pushing an operand value simply pushes the respective type to the value stack.

Popping an operand value checks that the value stack does not underflow the current block and then removes one type. But first, a special case is handled where the block contains no known values, but has been marked as unreachable. That can occur after an unconditional branch, when the stack is typed *polymorphically*. In that case, the Bot type is returned, because that is a *principal* choice trivially satisfying all use constraints.

A second function for popping an operand value takes an expected type, which the actual operand type is checked against. The types may differ by subtyping, including the case where the actual type is Bot, and thereby matches unconditionally. The function returns the actual type popped from the stack.

Finally, there are accumulative functions for pushing or popping multiple operand types.

Note: The notation `stack[i]` is meant to index the stack from the top, so that, e.g., `ctrls[0]` accesses the element pushed last.

The initialization stack and the initialization status of locals is manipulated through the following functions:

```

func get_local(idx : u32) =
  error_if(not locals_init[idx])

func set_local(idx : u32) =
  if (not locals_init[idx])
    inits.push(idx)
    locals_init[idx] := true

func reset_locals(height : nat) =
  while (inits.size() > height)
    locals_init[inits.pop()] := false

```

Getting a local verifies that it is known to be initialized. When a local is set that was not set already, then its initialization status is updated and the change is recorded in the initialization stack. Thus, the initialization status of all locals can be reset to a previous state by denoting a specific height in the initialization stack.

The size of the initialization stack is bounded by the number of (non-defaultable) locals in a function, so can be preallocated by an algorithm.

The control stack is likewise manipulated through auxiliary functions:

```

func push_ctrl(opcode : opcode, in : list(val_type), out : list(val_type)) =
  let frame = ctrl_frame(opcode, in, out, vals.size(), inits.size(), false)
  ctrls.push(frame)
  push_vals(in)

func pop_ctrl() : ctrl_frame =
  error_if(ctrls.is_empty())
  let frame = ctrls[0]
  pop_vals(frame.end_types)
  error_if(vals.size() != frame.val_height)
  reset_locals(frame.init_height)

```

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```

ctrls.pop()
return frame

func label_types(frame : ctrl_frame) : list(val_types) =
  return (if (frame.opcode = loop) frame.start_types else frame.end_types)

func unreachable() =
  vals.resize(ctrls[0].height)
  ctrls[0].unreachable := true

```

Pushing a control frame takes the types of the label and result values. It allocates a new frame record recording them along with the current height of the operand stack and marks the block as reachable.

Popping a frame first checks that the control stack is not empty. It then verifies that the operand stack contains the right types of values expected at the end of the exited block and pops them off the operand stack. Afterwards, it checks that the stack has shrunk back to its initial height. Finally, it undoes all changes to the initialization status of locals that happen inside the block.

The type of the `label` associated with a control frame is either that of the stack at the start or the end of the frame, determined by the opcode that it originates from.

Finally, the current frame can be marked as unreachable. In that case, all existing operand types are purged from the value stack, in order to allow for the `stack-polymorphism` logic in `pop_val` to take effect. Because every function has an implicit outermost label that corresponds to an implicit block frame, it is an invariant of the validation algorithm that there always is at least one frame on the control stack when validating an instruction, and hence, `ctrls[0]` is always defined.

Note: Even with the unreachable flag set, consecutive operands are still pushed to and popped from the operand stack. That is necessary to detect invalid `examples` like `(unreachable (i32.const) i64.add)`. However, a polymorphic stack cannot underflow, but instead generates Bot types as needed.

7.5.2 Validation of Opcode Sequences

The following function shows the validation of a number of representative instructions that manipulate the stack. Other instructions are checked in a similar manner.

```

func validate(opcode) =
  switch (opcode)
  case (i32.add)
    pop_val(I32)
    pop_val(I32)
    push_val(I32)

  case (drop)
    pop_val()

  case (select)
    pop_val(I32)
    let t1 = pop_val()
    let t2 = pop_val()
    error_if(not (is_num(t1) && is_num(t2) || is_vec(t1) && is_vec(t2)))
    error_if(t1 != t2 && t1 != Bot && t2 != Bot)
    push_val(if (t1 = Bot) t2 else t1)

  case (select t)

```

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```

    pop_val(I32)
    pop_val(t)
    pop_val(t)
    push_val(t)

    case (ref.is_null)
        pop_ref()
        push_val(I32)

    case (ref.as_non_null)
        let rt = pop_ref()
        push_val(Ref(rt.heap, false))

    case (ref.test rt)
        validate_ref_type(rt)
        pop_val(Ref(top_heap_type(rt), true))
        push_val(I32)

    case (local.get x)
        get_local(x)
        push_val(locals[x])

    case (local.set x)
        pop_val(locals[x])
        set_local(x)

    case (unreachable)
        unreachable()

    case (block t1*->t2*)
        pop_vals([t1*])
        push_ctrl(block, [t1*], [t2*])

    case (loop t1*->t2*)
        pop_vals([t1*])
        push_ctrl(loop, [t1*], [t2*])

    case (if t1*->t2*)
        pop_val(I32)
        pop_vals([t1*])
        push_ctrl(if, [t1*], [t2*])

    case (end)
        let frame = pop_ctrl()
        push_vals(frame.end_types)

    case (else)
        let frame = pop_ctrl()
        error_if(frame.opcode != if)
        push_ctrl(else, frame.start_types, frame.end_types)

    case (br n)
        error_if(ctrls.size() < n)
        pop_vals(label_types(ctrls[n]))
        unreachable()

```

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```

case (br_if n)
  error_if(ctrls.size() < n)
  pop_val(I32)
  pop_vals(label_types(ctrls[n]))
  push_vals(label_types(ctrls[n]))

case (br_table n* m)
  pop_val(I32)
  error_if(ctrls.size() < m)
  let arity = label_types(ctrls[m]).size()
  foreach (n in n*)
    error_if(ctrls.size() < n)
    error_if(label_types(ctrls[n]).size() != arity)
    push_vals(pop_vals(label_types(ctrls[n])))
  pop_vals(label_types(ctrls[m]))
  unreachable()

case (br_on_null n)
  error_if(ctrls.size() < n)
  let rt = pop_ref()
  pop_vals(label_types(ctrls[n]))
  push_vals(label_types(ctrls[n]))
  push_val(Ref(rt.heap, false))

case (br_on_cast n rt1 rt2)
  validate_ref_type(rt1)
  validate_ref_type(rt2)
  pop_val(rt1)
  push_val(rt2)
  pop_vals(label_types(ctrls[n]))
  push_vals(label_types(ctrls[n]))
  pop_val(rt2)
  push_val(diff_ref_type(rt2, rt1))

case (return)
  pop_vals(return_types)
  unreachable()

case (call_ref x)
  let t = expand_def(types[x])
  error_if(not is_func(t))
  pop_vals(t.params)
  pop_val(Ref(Def(types[x])))
  push_vals(t.results)

case (return_call_ref x)
  let t = expand_def(types[x])
  error_if(not is_func(t))
  pop_vals(t.params)
  pop_val(Ref(Def(types[x])))
  error_if(t.results.len() != return_types.len())
  push_vals(t.results)
  pop_vals(return_types)
  unreachable()

case (struct.new x)

```

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```

let t = expand_def(types[x])
error_if(not is_struct(t))
for (ti in reverse(t.fields))
  pop_val(unpack_field(ti))
push_val(Ref(Def(types[x])))

case (struct.set x n)
let t = expand_def(types[x])
error_if(not is_struct(t) || n >= t.fields.len())
pop_val(Ref(Def(types[x])))
pop_val(unpack_field(st.fields[n]))

```

Note: It is an invariant under the current WebAssembly instruction set that an operand of Bot type is never duplicated on the stack. This would change if the language were extended with stack instructions like `dup`. Under such an extension, the above algorithm would need to be refined by replacing the Bot type with proper *type variables* to ensure that all uses are consistent.

7.6 Custom Sections

This appendix defines dedicated [custom sections](#) for WebAssembly's [binary format](#). Such sections do not contribute to, or otherwise affect, the WebAssembly semantics, and like any custom section they may be ignored by an implementation. However, they provide useful meta data that implementations can make use of to improve user experience or take compilation hints.

Currently, only one dedicated custom section is defined, the [name section](#).

7.6.1 Name Section

The *name section* is a [custom section](#) whose name string is itself 'name'. The name section should appear only once in a module, and only after the [data section](#).

The purpose of this section is to attach printable names to definitions in a module, which e.g. can be used by a debugger or when parts of the module are to be rendered in [text form](#).

Note: All [names](#) are represented in [Unicode](#)⁵⁶ encoded in UTF-8. Names need not be unique.

Subsections

The [data](#) of a name section consists of a sequence of *subsections*. Each subsection consists of a

- a one-byte subsection *id*,
- the *u32 size* of the contents, in bytes,
- the actual *contents*, whose structure is dependent on the subsection id.

```

namesec          ::= section0(namedata)
namedata         ::= n:name (if n = 'name')
                  modulenamessubsec?
                  funcnamesubsec?
                  localnamesubsec?
namesubsectionN(B) ::= N:byte size:u32 B (if size = ||B||)

```

⁵⁶ <https://www.unicode.org/versions/latest/>

The following subsection ids are used:

Id	Subsection
0	module name
1	function names
2	local names
4	type names
10	field names

Each subsection may occur at most once, and in order of increasing id.

Name Maps

A *name map* assigns [names](#) to [indices](#) in a given [index space](#). It consists of a [list](#) of index/name pairs in order of increasing index value. Each index must be unique, but the assigned names need not be.

```
namemap      ::= list(nameassoc)
nameassoc    ::= idx name
```

An *indirect name map* assigns [names](#) to a two-dimensional [index space](#), where secondary indices are *grouped* by primary indices. It consists of a list of primary index/name map pairs in order of increasing index value, where each name map in turn maps secondary indices to names. Each primary index must be unique, and likewise each secondary index per individual name map.

```
indirectnamemap ::= list(indirectnameassoc)
indirectnameassoc ::= idx namemap
```

Module Names

The *module name subsection* has the id 0. It simply consists of a single [name](#) that is assigned to the module itself.

```
modulenamesubsec ::= namesubsection0(name)
```

Function Names

The *function name subsection* has the id 1. It consists of a [name map](#) assigning function names to [function indices](#).

```
funcnamesubsec ::= namesubsection1(namemap)
```

Local Names

The *local name subsection* has the id 2. It consists of an [indirect name map](#) assigning local names to [local indices](#) grouped by [function indices](#).

```
localnamesubsec ::= namesubsection2(indirectnamemap)
```

Type Names

The *type name subsection* has the id 4. It consists of a *name map* assigning type names to *type indices*.

```
typenamesubsec ::= namesubsection1(namemap)
```

Field Names

The *field name subsection* has the id 10. It consists of an *indirect name map* assigning field names to *field indices* grouped by *type indices*.

```
fieldnamesubsec ::= namesubsection2(indirectnamemap)
```

7.7 Change History

Since the original release 1.0 of the WebAssembly specification, a number of proposals for extensions have been integrated. The following sections provide an overview of what has changed.

7.7.1 Release 2.0

Sign extension instructions

Added new numeric instructions for performing sign extension within integer representations.⁵⁷

- New numeric instructions: *inn.extendN_s*

Non-trapping float-to-int conversions

Added new conversion instructions that avoid trapping when converting a floating-point number to an integer.⁵⁸

- New numeric instructions: *inn.trunc_sat_fmm_sx*

Multiple values

Generalized the result type of blocks and functions to allow for multiple values; in addition, introduced the ability to have block parameters.⁵⁹

- *Function types* allow more than one result
- *Block types* can be arbitrary function types

⁵⁷ <https://github.com/WebAssembly/spec/tree/main/proposals/sign-extension-ops/>

⁵⁸ <https://github.com/WebAssembly/spec/tree/main/proposals/nontrapping-float-to-int-conversion/>

⁵⁹ <https://github.com/WebAssembly/spec/tree/main/proposals/multi-value/>

Reference types

Added `funcref` and `externref` as new value types and respective instructions.⁶⁰

- New value types: reference types `funcref` and `externref`
- New reference instructions: `ref.null`, `ref.func`, `ref.is_null`
- Extended parametric instruction: `select` with optional type immediate
- New declarative form of element segment

Table instructions

Added instructions to directly access and modify tables.^{Page 282, 60}

- Table types allow any reference type as element type
- New table instructions: `table.get`, `table.set`, `table.size`, `table.grow`

Multiple tables

Added the ability to use multiple tables per module.⁶⁰

- Modules may `define`, `import`, and `export` multiple tables
- Table instructions take a table index immediate: `table.get`, `table.set`, `table.size`, `table.grow`, `call_indirect`
- Element segments take a table index

Bulk memory and table instructions

Added instructions that modify ranges of memory or table entries.⁶⁰⁶¹

- New memory instructions: `memory.fill`, `memory.init`, `memory.copy`, `data.drop`
- New table instructions: `table.fill`, `table.init`, `table.copy`, `elem.drop`
- New passive form of data segment
- New passive form of element segment
- New data count section in binary format
- Active data and element segments boundaries are no longer checked at compile time but may trap instead

Vector instructions

Added vector type and instructions that manipulate multiple numeric values in parallel (also known as *SIMD*, single instruction multiple data)⁶²

- New value type: `v128`
- New memory instructions: `v128.load`, `v128.loadN_xM_sx`, `v128.loadN_zero`, `v128.loadN_splat`, `v128.loadN_lane`, `v128.store`, `v128.storeN_lane`
- New constant vector instruction: `v128.const`
- New unary vector instructions: `v128.not`, `iN_xM.abs`, `iN_xM.neg`, `i8x16.popcnt`, `fN_xM.abs`, `fN_xM.neg`, `fN_xM.sqrt`, `fN_xM.ceil`, `fN_xM.floor`, `fN_xM.trunc`, `fN_xM.nearest`

⁶⁰ <https://github.com/WebAssembly/spec/tree/main/proposals/reference-types/>

⁶¹ <https://github.com/WebAssembly/spec/tree/main/proposals/bulk-memory-operations/>

⁶² <https://github.com/WebAssembly/spec/tree/main/proposals/simd/>

- New binary **vector instructions**: `v128.and`, `v128.andnot`, `v128.or`, `v128.xor`, `iNxM.add`, `iNxM.sub`, `iNxM.mul`, `iNxM.add_sat_sx`, `iNxM.sub_sat_sx`, `iNxM.min_sx`, `iNxM.max_sx`, `iNxM.shl`, `iNxM.shr_sx`, `fNxM.add`, `iNxM.extmul_half_iNxM'_sx`, `i16x8.q15mulr_sat_s`, `i32x4.dot_i16x8_s`, `i16x8.extadd_pairwise_i8x16_sx`, `i32x4.extadd_pairwise_i16x8_sx`, `i8x16.avgr_u`, `i16x8.avgr_u`, `fNxM.sub`, `fNxM.mul`, `fNxM.div`, `fNxM.min`, `fNxM.max`, `fNxM.pmin`, `fNxM.pmax`
- New ternary **vector instruction**: `v128.bitselect`
- New test **vector instructions**: `v128.any_true`, `iNxM.all_true`
- New relational **vector instructions**: `iNxM.eq`, `iNxM.ne`, `iNxM.lt_sx`, `iNxM.gt_sx`, `iNxM.le_sx`, `iNxM.ge_sx`, `fNxM.eq`, `fNxM.ne`, `fNxM.lt`, `fNxM.gt`, `fNxM.le`, `fNxM.ge`
- New conversion **vector instructions**: `i32x4.trunc_sat_f32x4_sx`, `i32x4.trunc_sat_f64x2_sx_zero`, `f32x4.convert_i32x4_sx`, `f32x4.demote_f64x2_zero`, `f64x2.convert_low_i32x4_sx`, `f64x2.promote_low_f32x4`
- New lane access **vector instructions**: `iNxM.extract_lane_sx?`, `iNxM.replace_lane`, `fNxM.extract_lane`, `fNxM.replace_lane`
- New lane splitting/combining **vector instructions**: `iNxM.extend_half_iNxM'_sx`, `i8x16.narrow_i16x8_sx`, `i16x8.narrow_i32x4_sx`
- New byte reordering **vector instructions**: `i8x16.shuffle`, `i8x16.swizzle`
- New injection/projection **vector instructions**: `iNxM.splat`, `fNxM.splat`, `iNxM.bitmask`

7.7.2 Release 3.0

Extended constant expressions

Allowed basic numeric computations in constant expressions.⁶³

- Extended set of **constant instructions** with `inn.add`, `inn.sub`, and `inn.mul`, and `global.get` for any previously declared immutable `global`

Note: The **garbage collection** added further constant instructions.

Tail calls

Added instructions to perform tail calls.⁶⁴

- New **control instructions**: `return_call` and `return_call_indirect`

Multiple memories

Added the ability to use multiple memories per module.⁶⁵

- Modules may define, import, and export multiple memories
- Memory instructions take a **memory index** immediate: `memory.size`, `memory.grow`, `memory.fill`, `memory.copy`, `memory.init`, `t.load`, `t.store`, `t.loadN_sx`, `t.storeN`, `v128.loadNxM_sx`, `v128.loadN_zero`, `v128.loadN_splat`, `v128.loadN_lane`, `v128.storeN_lane`
- Data segments take a **memory index**

⁶³ <https://github.com/WebAssembly/extended-const/blob/main/proposals/extended-const/>

⁶⁴ <https://github.com/WebAssembly/spec/tree/main/proposals/tail-call/>

⁶⁵ <https://github.com/WebAssembly/multi-memory/blob/main/proposals/multi-memory/>

Typeful references

Added more precise types for references.⁶⁶

- New generalised form of reference types: (ref null[?] *heaptypes*)
- New class of heap types: *func*, *extern*, *typeid*x**
- Basic subtyping on reference and value types
- New reference instructions: *ref.as_non_null*, *br_on_null*, *br_on_non_null*
- New control instruction: *call_ref*
- Refined typing of reference instruction *ref.func* with more precise result type
- Refined typing of local instructions and instruction sequences to track the initialization status of locals with non-defaultable type
- Extended table definitions with optional initializer expression

Garbage collection

Added managed reference types.⁶⁷

- New forms of heap types: *any*, *eq*, *i31*, *struct*, *array*, *none*, *nofunc*, *noextern*
- New reference type short-hands: *anyref*, *eqref*, *i31ref*, *structref*, *arrayref*, *nullref*, *nullfuncref*, *nullexternref*
- New forms of type definitions: structure and array types, sub types, and recursive types
- Enriched subtyping based on explicitly declared sub types and the new heap types
- New generic reference instructions: *ref.eq*, *ref.test*, *ref.cast*, *br_on_cast*, *br_on_cast_fail*
- New reference instructions for unboxed scalars: *ref.i31*, *i31.get_s*x**
- New reference instructions for structure types: *struct.new*, *struct.new_default*, *struct.get_s*x**[?], *struct.set*
- New reference instructions for array types: *array.new*, *array.new_default*, *array.new_fixed*, *array.new_data*, *array.new_elem*, *array.get_s*x**[?], *array.set*, *array.len*, *array.fill*, *array.copy*, *array.init_data*, *array.init_elem*
- New reference instructions for converting host types: *any.convert_extern*, *extern.convert_any*
- Extended set of constant instructions with *ref.i31*, *struct.new*, *struct.new_default*, *array.new*, *array.new_default*, *array.new_fixed*, *any.convert_extern*, *extern.convert_any*

7.8 Index of Types

Category	Constructor	Binary Opcode
Type index	<i>x</i>	(positive number as <i>s32</i> or <i>u32</i>)
Number type	<i>i32</i>	0x7F (-1 as <i>s7</i>)
Number type	<i>i64</i>	0x7E (-2 as <i>s7</i>)
Number type	<i>f32</i>	0x7D (-3 as <i>s7</i>)
Number type	<i>f64</i>	0x7C (-4 as <i>s7</i>)
Vector type	<i>v128</i>	0x7B (-5 as <i>s7</i>)
(reserved)		0x7A .. 0x79
Packed type	<i>i8</i>	0x78 (-8 as <i>s7</i>)
Packed type	<i>i16</i>	0x77 (-9 as <i>s7</i>)
(reserved)		0x78 .. 0x74

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⁶⁶ <https://github.com/WebAssembly/spec/tree/main/proposals/function-references/>

⁶⁷ <https://github.com/WebAssembly/spec/tree/main/proposals/gc/>

Table 1 – continued from previous page

Category	Constructor	Binary Opcode
Heap type	nofunc	0x73 (-13 as <i>s7</i>)
Heap type	noextern	0x72 (-14 as <i>s7</i>)
Heap type	none	0x71 (-15 as <i>s7</i>)
Heap type	func	0x70 (-16 as <i>s7</i>)
Heap type	extern	0x6F (-17 as <i>s7</i>)
Heap type	any	0x6E (-18 as <i>s7</i>)
Heap type	eq	0x6D (-19 as <i>s7</i>)
Heap type	i31	0x6C (-20 as <i>s7</i>)
Heap type	struct	0x6B (-21 as <i>s7</i>)
Heap type	array	0x6A (-22 as <i>s7</i>)
(reserved)		0x69 .. 0x65
Reference type	ref	0x64 (-28 as <i>s7</i>)
Reference type	ref null	0x63 (-29 as <i>s7</i>)
(reserved)		0x62 .. 0x61
Composite type	func <i>[valtype*] → [valtype*]</i>	0x60 (-32 as <i>s7</i>)
Composite type	struct <i>fieldtype*</i>	0x5F (-33 as <i>s7</i>)
Composite type	array <i>fieldtype</i>	0x5E (-34 as <i>s7</i>)
(reserved)		0x5D .. 0x51
Sub type	sub <i>typeid*</i> <i>comptype</i>	0x50 (-48 as <i>s7</i>)
Sub type	sub final <i>typeid*</i> <i>comptype</i>	0x4F (-49 as <i>s7</i>)
Recursive type	rec <i>subtype*</i>	0x4E (-50 as <i>s7</i>)
(reserved)		0x4D .. 0x41
Result type	<i>[e]</i>	0x40 (-64 as <i>s7</i>)
Table type	<i>limits reftype</i>	(none)
Memory type	<i>limits</i>	(none)
Global type	<i>mut valtype</i>	(none)

7.9 Index of Instructions

Instruction	Binary Opcode	Type	Validation	Execution
unreachable	0x00	$[t_1^*] \rightarrow [t_2^*]$	validation	execution
nop	0x01	$[] \rightarrow []$	validation	execution
block <i>bt</i>	0x02	$[t_1^*] \rightarrow [t_2^*]$	validation	execution
loop <i>bt</i>	0x03	$[t_1^*] \rightarrow [t_2^*]$	validation	execution
if <i>bt</i>	0x04	$[t_1^* \text{ i32}] \rightarrow [t_2^*]$	validation	execution
else	0x05			
(reserved)	0x06			
(reserved)	0x07			
(reserved)	0x08			
(reserved)	0x09			
(reserved)	0x0A			
end	0x0B			
br <i>l</i>	0x0C	$[t_1^* t^*] \rightarrow [t_2^*]$	validation	execution
br_if <i>l</i>	0x0D	$[t^* \text{ i32}] \rightarrow [t^*]$	validation	execution
br_table <i>l* l</i>	0x0E	$[t_1^* t^* \text{ i32}] \rightarrow [t_2^*]$	validation	execution
return	0x0F	$[t_1^* t^*] \rightarrow [t_2^*]$	validation	execution
call <i>x</i>	0x10	$[t_1^*] \rightarrow [t_2^*]$	validation	execution
call_indirect <i>x y</i>	0x11	$[t_1^* \text{ i32}] \rightarrow [t_2^*]$	validation	execution
return_call <i>x</i>	0x12	$[t_1^*] \rightarrow [t_2^*]$	validation	execution
return_call_indirect <i>x y</i>	0x13	$[t_1^* \text{ i32}] \rightarrow [t_2^*]$	validation	execution

continues on next page

Table 2 – continued from previous page

Instruction	Binary Opcode	Type	Validation	Execution
<code>call_ref x</code>	0x14	$[t_1^* (\text{ref null } x)] \rightarrow [t_2^*]$	validation	execution
<code>return_call_ref x</code>	0x15	$[t_1^* (\text{ref null } x)] \rightarrow [t_2^*]$	validation	execution
(reserved)	0x16			
(reserved)	0x17			
(reserved)	0x18			
(reserved)	0x19			
<code>drop</code>	0x1A	$[t] \rightarrow []$	validation	execution
<code>select</code>	0x1B	$[t \ t \ i_{32}] \rightarrow [t]$	validation	execution
<code>select t</code>	0x1C	$[t \ t \ i_{32}] \rightarrow [t]$	validation	execution
(reserved)	0x1D			
(reserved)	0x1E			
(reserved)	0x1F			
<code>local.get x</code>	0x20	$[] \rightarrow [t]$	validation	execution
<code>local.set x</code>	0x21	$[t] \rightarrow []$	validation	execution
<code>local.tee x</code>	0x22	$[t] \rightarrow [t]$	validation	execution
<code>global.get x</code>	0x23	$[] \rightarrow [t]$	validation	execution
<code>global.set x</code>	0x24	$[t] \rightarrow []$	validation	execution
<code>table.get x</code>	0x25	$[i_{32}] \rightarrow [t]$	validation	execution
<code>table.set x</code>	0x26	$[i_{32} \ t] \rightarrow []$	validation	execution
(reserved)	0x27			
<code>i32.load x memarg</code>	0x28	$[i_{32}] \rightarrow [i_{32}]$	validation	execution
<code>i64.load x memarg</code>	0x29	$[i_{32}] \rightarrow [i_{64}]$	validation	execution
<code>f32.load x memarg</code>	0x2A	$[i_{32}] \rightarrow [f_{32}]$	validation	execution
<code>f64.load x memarg</code>	0x2B	$[i_{32}] \rightarrow [f_{64}]$	validation	execution
<code>i32.load8_s x memarg</code>	0x2C	$[i_{32}] \rightarrow [i_{32}]$	validation	execution
<code>i32.load8_u x memarg</code>	0x2D	$[i_{32}] \rightarrow [i_{32}]$	validation	execution
<code>i32.load16_s x memarg</code>	0x2E	$[i_{32}] \rightarrow [i_{32}]$	validation	execution
<code>i32.load16_u x memarg</code>	0x2F	$[i_{32}] \rightarrow [i_{32}]$	validation	execution
<code>i64.load8_s x memarg</code>	0x30	$[i_{32}] \rightarrow [i_{64}]$	validation	execution
<code>i64.load8_u x memarg</code>	0x31	$[i_{32}] \rightarrow [i_{64}]$	validation	execution
<code>i64.load16_s x memarg</code>	0x32	$[i_{32}] \rightarrow [i_{64}]$	validation	execution
<code>i64.load16_u x memarg</code>	0x33	$[i_{32}] \rightarrow [i_{64}]$	validation	execution
<code>i64.load32_s x memarg</code>	0x34	$[i_{32}] \rightarrow [i_{64}]$	validation	execution
<code>i64.load32_u x memarg</code>	0x35	$[i_{32}] \rightarrow [i_{64}]$	validation	execution
<code>i32.store x memarg</code>	0x36	$[i_{32} \ i_{32}] \rightarrow []$	validation	execution
<code>i64.store x memarg</code>	0x37	$[i_{32} \ i_{64}] \rightarrow []$	validation	execution
<code>f32.store x memarg</code>	0x38	$[i_{32} \ f_{32}] \rightarrow []$	validation	execution
<code>f64.store x memarg</code>	0x39	$[i_{32} \ f_{64}] \rightarrow []$	validation	execution
<code>i32.store8 x memarg</code>	0x3A	$[i_{32} \ i_{32}] \rightarrow []$	validation	execution
<code>i32.store16 x memarg</code>	0x3B	$[i_{32} \ i_{32}] \rightarrow []$	validation	execution
<code>i64.store8 x memarg</code>	0x3C	$[i_{32} \ i_{64}] \rightarrow []$	validation	execution
<code>i64.store16 x memarg</code>	0x3D	$[i_{32} \ i_{64}] \rightarrow []$	validation	execution
<code>i64.store32 x memarg</code>	0x3E	$[i_{32} \ i_{64}] \rightarrow []$	validation	execution
<code>memory.size x</code>	0x3F	$[] \rightarrow [i_{32}]$	validation	execution
<code>memory.grow x</code>	0x40	$[i_{32}] \rightarrow [i_{32}]$	validation	execution
<code>i32.const i32</code>	0x41	$[] \rightarrow [i_{32}]$	validation	execution
<code>i64.const i64</code>	0x42	$[] \rightarrow [i_{64}]$	validation	execution
<code>f32.const f32</code>	0x43	$[] \rightarrow [f_{32}]$	validation	execution
<code>f64.const f64</code>	0x44	$[] \rightarrow [f_{64}]$	validation	execution
<code>i32.eqz</code>	0x45	$[i_{32}] \rightarrow [i_{32}]$	validation	execution (C)
<code>i32.eq</code>	0x46	$[i_{32} \ i_{32}] \rightarrow [i_{32}]$	validation	execution (C)
<code>i32.ne</code>	0x47	$[i_{32} \ i_{32}] \rightarrow [i_{32}]$	validation	execution (C)
<code>i32.lt_s</code>	0x48	$[i_{32} \ i_{32}] \rightarrow [i_{32}]$	validation	execution (C)

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Instruction	Binary Opcode	Type	Validation	Execution
i32.lt_u	0x49	$[i32\ i32] \rightarrow [i32]$	validation	execution (0)
i32.gt_s	0x4A	$[i32\ i32] \rightarrow [i32]$	validation	execution (0)
i32.gt_u	0x4B	$[i32\ i32] \rightarrow [i32]$	validation	execution (0)
i32.le_s	0x4C	$[i32\ i32] \rightarrow [i32]$	validation	execution (0)
i32.le_u	0x4D	$[i32\ i32] \rightarrow [i32]$	validation	execution (0)
i32.ge_s	0x4E	$[i32\ i32] \rightarrow [i32]$	validation	execution (0)
i32.ge_u	0x4F	$[i32\ i32] \rightarrow [i32]$	validation	execution (0)
i64.eqz	0x50	$[i64] \rightarrow [i32]$	validation	execution (0)
i64.eq	0x51	$[i64\ i64] \rightarrow [i32]$	validation	execution (0)
i64.ne	0x52	$[i64\ i64] \rightarrow [i32]$	validation	execution (0)
i64.lt_s	0x53	$[i64\ i64] \rightarrow [i32]$	validation	execution (0)
i64.lt_u	0x54	$[i64\ i64] \rightarrow [i32]$	validation	execution (0)
i64.gt_s	0x55	$[i64\ i64] \rightarrow [i32]$	validation	execution (0)
i64.gt_u	0x56	$[i64\ i64] \rightarrow [i32]$	validation	execution (0)
i64.le_s	0x57	$[i64\ i64] \rightarrow [i32]$	validation	execution (0)
i64.le_u	0x58	$[i64\ i64] \rightarrow [i32]$	validation	execution (0)
i64.ge_s	0x59	$[i64\ i64] \rightarrow [i32]$	validation	execution (0)
i64.ge_u	0x5A	$[i64\ i64] \rightarrow [i32]$	validation	execution (0)
f32.eq	0x5B	$[f32\ f32] \rightarrow [i32]$	validation	execution (0)
f32.ne	0x5C	$[f32\ f32] \rightarrow [i32]$	validation	execution (0)
f32.lt	0x5D	$[f32\ f32] \rightarrow [i32]$	validation	execution (0)
f32.gt	0x5E	$[f32\ f32] \rightarrow [i32]$	validation	execution (0)
f32.le	0x5F	$[f32\ f32] \rightarrow [i32]$	validation	execution (0)
f32.ge	0x60	$[f32\ f32] \rightarrow [i32]$	validation	execution (0)
f64.eq	0x61	$[f64\ f64] \rightarrow [i32]$	validation	execution (0)
f64.ne	0x62	$[f64\ f64] \rightarrow [i32]$	validation	execution (0)
f64.lt	0x63	$[f64\ f64] \rightarrow [i32]$	validation	execution (0)
f64.gt	0x64	$[f64\ f64] \rightarrow [i32]$	validation	execution (0)
f64.le	0x65	$[f64\ f64] \rightarrow [i32]$	validation	execution (0)
f64.ge	0x66	$[f64\ f64] \rightarrow [i32]$	validation	execution (0)
i32.clz	0x67	$[i32] \rightarrow [i32]$	validation	execution (0)
i32.ctz	0x68	$[i32] \rightarrow [i32]$	validation	execution (0)
i32.popcnt	0x69	$[i32] \rightarrow [i32]$	validation	execution (0)
i32.add	0x6A	$[i32\ i32] \rightarrow [i32]$	validation	execution (0)
i32.sub	0x6B	$[i32\ i32] \rightarrow [i32]$	validation	execution (0)
i32.mul	0x6C	$[i32\ i32] \rightarrow [i32]$	validation	execution (0)
i32.div_s	0x6D	$[i32\ i32] \rightarrow [i32]$	validation	execution (0)
i32.div_u	0x6E	$[i32\ i32] \rightarrow [i32]$	validation	execution (0)
i32.rem_s	0x6F	$[i32\ i32] \rightarrow [i32]$	validation	execution (0)
i32.rem_u	0x70	$[i32\ i32] \rightarrow [i32]$	validation	execution (0)
i32.and	0x71	$[i32\ i32] \rightarrow [i32]$	validation	execution (0)
i32.or	0x72	$[i32\ i32] \rightarrow [i32]$	validation	execution (0)
i32.xor	0x73	$[i32\ i32] \rightarrow [i32]$	validation	execution (0)
i32.shl	0x74	$[i32\ i32] \rightarrow [i32]$	validation	execution (0)
i32.shr_s	0x75	$[i32\ i32] \rightarrow [i32]$	validation	execution (0)
i32.shr_u	0x76	$[i32\ i32] \rightarrow [i32]$	validation	execution (0)
i32.rotl	0x77	$[i32\ i32] \rightarrow [i32]$	validation	execution (0)
i32.rotr	0x78	$[i32\ i32] \rightarrow [i32]$	validation	execution (0)
i64.clz	0x79	$[i64] \rightarrow [i64]$	validation	execution (0)
i64.ctz	0x7A	$[i64] \rightarrow [i64]$	validation	execution (0)
i64.popcnt	0x7B	$[i64] \rightarrow [i64]$	validation	execution (0)
i64.add	0x7C	$[i64\ i64] \rightarrow [i64]$	validation	execution (0)
i64.sub	0x7D	$[i64\ i64] \rightarrow [i64]$	validation	execution (0)

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Table 2 – continued from previous page

Instruction	Binary Opcode	Type	Validation	Execution
i64.mul	0x7E	$[i64\ i64] \rightarrow [i64]$	validation	execution (0)
i64.div_s	0x7F	$[i64\ i64] \rightarrow [i64]$	validation	execution (0)
i64.div_u	0x80	$[i64\ i64] \rightarrow [i64]$	validation	execution (0)
i64.rem_s	0x81	$[i64\ i64] \rightarrow [i64]$	validation	execution (0)
i64.rem_u	0x82	$[i64\ i64] \rightarrow [i64]$	validation	execution (0)
i64.and	0x83	$[i64\ i64] \rightarrow [i64]$	validation	execution (0)
i64.or	0x84	$[i64\ i64] \rightarrow [i64]$	validation	execution (0)
i64.xor	0x85	$[i64\ i64] \rightarrow [i64]$	validation	execution (0)
i64.shl	0x86	$[i64\ i64] \rightarrow [i64]$	validation	execution (0)
i64.shr_s	0x87	$[i64\ i64] \rightarrow [i64]$	validation	execution (0)
i64.shr_u	0x88	$[i64\ i64] \rightarrow [i64]$	validation	execution (0)
i64.rotl	0x89	$[i64\ i64] \rightarrow [i64]$	validation	execution (0)
i64.rotr	0x8A	$[i64\ i64] \rightarrow [i64]$	validation	execution (0)
f32.abs	0x8B	$[f32] \rightarrow [f32]$	validation	execution (0)
f32.neg	0x8C	$[f32] \rightarrow [f32]$	validation	execution (0)
f32.ceil	0x8D	$[f32] \rightarrow [f32]$	validation	execution (0)
f32.floor	0x8E	$[f32] \rightarrow [f32]$	validation	execution (0)
f32.trunc	0x8F	$[f32] \rightarrow [f32]$	validation	execution (0)
f32.nearest	0x90	$[f32] \rightarrow [f32]$	validation	execution (0)
f32.sqrt	0x91	$[f32] \rightarrow [f32]$	validation	execution (0)
f32.add	0x92	$[f32\ f32] \rightarrow [f32]$	validation	execution (0)
f32.sub	0x93	$[f32\ f32] \rightarrow [f32]$	validation	execution (0)
f32.mul	0x94	$[f32\ f32] \rightarrow [f32]$	validation	execution (0)
f32.div	0x95	$[f32\ f32] \rightarrow [f32]$	validation	execution (0)
f32.min	0x96	$[f32\ f32] \rightarrow [f32]$	validation	execution (0)
f32.max	0x97	$[f32\ f32] \rightarrow [f32]$	validation	execution (0)
f32.copysign	0x98	$[f32\ f32] \rightarrow [f32]$	validation	execution (0)
f64.abs	0x99	$[f64] \rightarrow [f64]$	validation	execution (0)
f64.neg	0x9A	$[f64] \rightarrow [f64]$	validation	execution (0)
f64.ceil	0x9B	$[f64] \rightarrow [f64]$	validation	execution (0)
f64.floor	0x9C	$[f64] \rightarrow [f64]$	validation	execution (0)
f64.trunc	0x9D	$[f64] \rightarrow [f64]$	validation	execution (0)
f64.nearest	0x9E	$[f64] \rightarrow [f64]$	validation	execution (0)
f64.sqrt	0x9F	$[f64] \rightarrow [f64]$	validation	execution (0)
f64.add	0xA0	$[f64\ f64] \rightarrow [f64]$	validation	execution (0)
f64.sub	0xA1	$[f64\ f64] \rightarrow [f64]$	validation	execution (0)
f64.mul	0xA2	$[f64\ f64] \rightarrow [f64]$	validation	execution (0)
f64.div	0xA3	$[f64\ f64] \rightarrow [f64]$	validation	execution (0)
f64.min	0xA4	$[f64\ f64] \rightarrow [f64]$	validation	execution (0)
f64.max	0xA5	$[f64\ f64] \rightarrow [f64]$	validation	execution (0)
f64.copysign	0xA6	$[f64\ f64] \rightarrow [f64]$	validation	execution (0)
i32.wrap_i64	0xA7	$[i64] \rightarrow [i32]$	validation	execution (0)
i32.trunc_f32_s	0xA8	$[f32] \rightarrow [i32]$	validation	execution (0)
i32.trunc_f32_u	0xA9	$[f32] \rightarrow [i32]$	validation	execution (0)
i32.trunc_f64_s	0xAA	$[f64] \rightarrow [i32]$	validation	execution (0)
i32.trunc_f64_u	0xAB	$[f64] \rightarrow [i32]$	validation	execution (0)
i64.extend_i32_s	0xAC	$[i32] \rightarrow [i64]$	validation	execution (0)
i64.extend_i32_u	0xAD	$[i32] \rightarrow [i64]$	validation	execution (0)
i64.trunc_f32_s	0xAE	$[f32] \rightarrow [i64]$	validation	execution (0)
i64.trunc_f32_u	0xAF	$[f32] \rightarrow [i64]$	validation	execution (0)
i64.trunc_f64_s	0xB0	$[f64] \rightarrow [i64]$	validation	execution (0)
i64.trunc_f64_u	0xB1	$[f64] \rightarrow [i64]$	validation	execution (0)
f32.convert_i32_s	0xB2	$[i32] \rightarrow [f32]$	validation	execution (0)

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Instruction	Binary Opcode	Type	Validation	Execution
<code>f32.convert_i32_u</code>	0xB3	$[i32] \rightarrow [f32]$	validation	execution (0)
<code>f32.convert_i64_s</code>	0xB4	$[i64] \rightarrow [f32]$	validation	execution (0)
<code>f32.convert_i64_u</code>	0xB5	$[i64] \rightarrow [f32]$	validation	execution (0)
<code>f32.demote_f64</code>	0xB6	$[f64] \rightarrow [f32]$	validation	execution (0)
<code>f64.convert_i32_s</code>	0xB7	$[i32] \rightarrow [f64]$	validation	execution (0)
<code>f64.convert_i32_u</code>	0xB8	$[i32] \rightarrow [f64]$	validation	execution (0)
<code>f64.convert_i64_s</code>	0xB9	$[i64] \rightarrow [f64]$	validation	execution (0)
<code>f64.convert_i64_u</code>	0xBA	$[i64] \rightarrow [f64]$	validation	execution (0)
<code>f64.promote_f32</code>	0xBB	$[f32] \rightarrow [f64]$	validation	execution (0)
<code>i32.reinterpret_f32</code>	0xBC	$[f32] \rightarrow [i32]$	validation	execution (0)
<code>i64.reinterpret_f64</code>	0xBD	$[f64] \rightarrow [i64]$	validation	execution (0)
<code>f32.reinterpret_i32</code>	0xBE	$[i32] \rightarrow [f32]$	validation	execution (0)
<code>f64.reinterpret_i64</code>	0xBF	$[i64] \rightarrow [f64]$	validation	execution (0)
<code>i32.extend8_s</code>	0xC0	$[i32] \rightarrow [i32]$	validation	execution (0)
<code>i32.extend16_s</code>	0xC1	$[i32] \rightarrow [i32]$	validation	execution (0)
<code>i64.extend8_s</code>	0xC2	$[i64] \rightarrow [i64]$	validation	execution (0)
<code>i64.extend16_s</code>	0xC3	$[i64] \rightarrow [i64]$	validation	execution (0)
<code>i64.extend32_s</code>	0xC4	$[i64] \rightarrow [i64]$	validation	execution (0)
(reserved)	0xC5			
(reserved)	0xC6			
(reserved)	0xC7			
(reserved)	0xC8			
(reserved)	0xC9			
(reserved)	0xCA			
(reserved)	0xCB			
(reserved)	0xCC			
(reserved)	0xCD			
(reserved)	0xCE			
(reserved)	0xCF			
<code>ref.null ht</code>	0xD0	$[] \rightarrow [(ref\ null\ ht)]$	validation	execution
<code>ref.is_null</code>	0xD1	$[(ref\ null\ ht)] \rightarrow [i32]$	validation	execution
<code>ref.func x</code>	0xD2	$[] \rightarrow [ref\ ht]$	validation	execution
<code>ref.eq</code>	0xD3	$[eqref\ eqref] \rightarrow [i32]$	validation	execution
<code>ref.as_non_null</code>	0xD4	$[(ref\ null\ ht)] \rightarrow [(ref\ ht)]$	validation	execution
<code>br_on_null l</code>	0xD5	$[t^* (ref\ null\ ht)] \rightarrow [t^* (ref\ ht)]$	validation	execution
<code>br_on_non_null l</code>	0xD6	$[t^* (ref\ null\ ht)] \rightarrow [t^*]$	validation	execution
(reserved)	0xD7			
(reserved)	0xD8			
(reserved)	0xD9			
(reserved)	0xDA			
(reserved)	0xDB			
(reserved)	0xDC			
(reserved)	0xDD			
(reserved)	0xDE			
(reserved)	0xDF			
(reserved)	0xE0			
(reserved)	0xE1			
(reserved)	0xE2			
(reserved)	0xE3			
(reserved)	0xE4			
(reserved)	0xE5			
(reserved)	0xE6			
(reserved)	0xE7			

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Instruction	Binary Opcode	Type	Validation	Execution
(reserved)	0xE8			
(reserved)	0xE9			
(reserved)	0xEA			
(reserved)	0xEB			
(reserved)	0xEC			
(reserved)	0xED			
(reserved)	0xEE			
(reserved)	0xEF			
(reserved)	0xF0			
(reserved)	0xF1			
(reserved)	0xF2			
(reserved)	0xF3			
(reserved)	0xF4			
(reserved)	0xF5			
(reserved)	0xF6			
(reserved)	0xF7			
(reserved)	0xF8			
(reserved)	0xF9			
(reserved)	0xFA			
struct.new x	0xFB 0x00	$[t^*] \rightarrow [(ref\ x)]$	validation	execution
struct.new_default x	0xFB 0x01	$[] \rightarrow [(ref\ x)]$	validation	execution
struct.get $x\ y$	0xFB 0x02	$[(ref\ null\ x)] \rightarrow [t]$	validation	execution
struct.get_s $x\ y$	0xFB 0x03	$[(ref\ null\ x)] \rightarrow [i32]$	validation	execution
struct.get_u $x\ y$	0xFB 0x04	$[(ref\ null\ x)] \rightarrow [i32]$	validation	execution
struct.set $x\ y$	0xFB 0x05	$[(ref\ null\ x)\ t] \rightarrow []$	validation	execution
array.new x	0xFB 0x06	$[t] \rightarrow [(ref\ x)]$	validation	execution
array.new_default x	0xFB 0x07	$[i32] \rightarrow [(ref\ x)]$	validation	execution
array.new_fixed $x\ n$	0xFB 0x08	$[t^n] \rightarrow [(ref\ x)]$	validation	execution
array.new_data $x\ y$	0xFB 0x09	$[i32\ i32] \rightarrow [(ref\ x)]$	validation	execution
array.new_elem $x\ y$	0xFB 0x0A	$[i32\ i32] \rightarrow [(ref\ x)]$	validation	execution
array.get x	0xFB 0x0B	$[(ref\ null\ x)\ i32] \rightarrow [t]$	validation	execution
array.get_s x	0xFB 0x0C	$[(ref\ null\ x)\ i32] \rightarrow [i32]$	validation	execution
array.get_u x	0xFB 0x0D	$[(ref\ null\ x)\ i32] \rightarrow [i32]$	validation	execution
array.set x	0xFB 0x0E	$[(ref\ null\ x)\ i32\ t] \rightarrow []$	validation	execution
array.len	0xFB 0x0F	$[(ref\ null\ array)] \rightarrow [i32]$	validation	execution
array.fill x	0xFB 0x10	$[(ref\ null\ x)\ i32\ t\ i32] \rightarrow []$	validation	execution
array.copy $x\ y$	0xFB 0x11	$[(ref\ null\ x)\ i32\ (ref\ null\ y)\ i32\ i32] \rightarrow []$	validation	execution
array.init_data $x\ y$	0xFB 0x12	$[(ref\ null\ x)\ i32\ i32\ i32] \rightarrow []$	validation	execution
array.init_elem $x\ y$	0xFB 0x13	$[(ref\ null\ x)\ i32\ i32\ i32] \rightarrow []$	validation	execution
ref.test (ref t)	0xFB 0x14	$[(ref\ t')] \rightarrow [i32]$	validation	execution
ref.test (ref null t)	0xFB 0x15	$[(REF\ null\ t')] \rightarrow [i32]$	validation	execution
ref.cast (ref t)	0xFB 0x16	$[(ref\ t')] \rightarrow [(ref\ t)]$	validation	execution
ref.cast (ref null t)	0xFB 0x17	$[(ref\ null\ t')] \rightarrow [(ref\ null\ t)]$	validation	execution
br_on_cast $t_1\ t_2$	0xFB 0x18	$[t_1] \rightarrow [t_1 \setminus t_2]$	validation	execution
br_on_cast_fail $t_1\ t_2$	0xFB 0x19	$[t_1] \rightarrow [t_2]$	validation	execution
any.convert_extern	0xFB 0x1A	$[(ref\ null\ extern)] \rightarrow [(ref\ null\ any)]$	validation	execution
extern.convert_any	0xFB 0x1B	$[(ref\ null\ any)] \rightarrow [(ref\ null\ extern)]$	validation	execution
ref.i31	0xFB 0x1C	$[i32] \rightarrow [(ref\ i31)]$	validation	execution
i31.get_s	0xFB 0x1D	$[i31ref] \rightarrow [i32]$	validation	execution
i31.get_u	0xFB 0x1E	$[i31ref] \rightarrow [i32]$	validation	execution
(reserved)	0xFB 0x1E...			
i32.trunc_sat_f32_s	0xFC 0x00	$[f32] \rightarrow [i32]$	validation	execution (C)
i32.trunc_sat_f32_u	0xFC 0x01	$[f32] \rightarrow [i32]$	validation	execution (C)

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Table 2 – continued from previous page

Instruction	Binary Opcode	Type	Validation	Execution
<code>i32.trunc_sat_f64_s</code>	0xFC 0x02	$[f64] \rightarrow [i32]$	validation	execution (C)
<code>i32.trunc_sat_f64_u</code>	0xFC 0x03	$[f64] \rightarrow [i32]$	validation	execution (C)
<code>i64.trunc_sat_f32_s</code>	0xFC 0x04	$[f32] \rightarrow [i64]$	validation	execution (C)
<code>i64.trunc_sat_f32_u</code>	0xFC 0x05	$[f32] \rightarrow [i64]$	validation	execution (C)
<code>i64.trunc_sat_f64_s</code>	0xFC 0x06	$[f64] \rightarrow [i64]$	validation	execution (C)
<code>i64.trunc_sat_f64_u</code>	0xFC 0x07	$[f64] \rightarrow [i64]$	validation	execution (C)
<code>memory.init x y</code>	0xFC 0x08	$[i32\ i32\ i32] \rightarrow []$	validation	execution
<code>data.drop x</code>	0xFC 0x09	$[] \rightarrow []$	validation	execution
<code>memory.copy x y</code>	0xFC 0x0A	$[i32\ i32\ i32] \rightarrow []$	validation	execution
<code>memory.fill y</code>	0xFC 0x0B	$[i32\ i32\ i32] \rightarrow []$	validation	execution
<code>table.init x y</code>	0xFC 0x0C	$[i32\ i32\ i32] \rightarrow []$	validation	execution
<code>elem.drop x</code>	0xFC 0x0D	$[] \rightarrow []$	validation	execution
<code>table.copy x y</code>	0xFC 0x0E	$[i32\ i32\ i32] \rightarrow []$	validation	execution
<code>table.grow x</code>	0xFC 0x0F	$[t\ i32] \rightarrow [i32]$	validation	execution
<code>table.size x</code>	0xFC 0x10	$[] \rightarrow [i32]$	validation	execution
<code>table.fill x</code>	0xFC 0x11	$[i32\ t\ i32] \rightarrow []$	validation	execution
(reserved)	0xFC 0x1E . . .			
<code>v128.load x memarg</code>	0xFD 0x00	$[i32] \rightarrow [v128]$	validation	execution
<code>v128.load8x8_s x memarg</code>	0xFD 0x01	$[i32] \rightarrow [v128]$	validation	execution
<code>v128.load8x8_u x memarg</code>	0xFD 0x02	$[i32] \rightarrow [v128]$	validation	execution
<code>v128.load16x4_s x memarg</code>	0xFD 0x03	$[i32] \rightarrow [v128]$	validation	execution
<code>v128.load16x4_u x memarg</code>	0xFD 0x04	$[i32] \rightarrow [v128]$	validation	execution
<code>v128.load32x2_s x memarg</code>	0xFD 0x05	$[i32] \rightarrow [v128]$	validation	execution
<code>v128.load32x2_u x memarg</code>	0xFD 0x06	$[i32] \rightarrow [v128]$	validation	execution
<code>v128.load8_splat x memarg</code>	0xFD 0x07	$[i32] \rightarrow [v128]$	validation	execution
<code>v128.load16_splat x memarg</code>	0xFD 0x08	$[i32] \rightarrow [v128]$	validation	execution
<code>v128.load32_splat x memarg</code>	0xFD 0x09	$[i32] \rightarrow [v128]$	validation	execution
<code>v128.load64_splat x memarg</code>	0xFD 0x0A	$[i32] \rightarrow [v128]$	validation	execution
<code>v128.store x memarg</code>	0xFD 0x0B	$[i32\ v128] \rightarrow []$	validation	execution
<code>v128.const i128</code>	0xFD 0x0C	$[] \rightarrow [v128]$	validation	execution
<code>i8x16.shuffle laneidx¹⁶</code>	0xFD 0x0D	$[v128\ v128] \rightarrow [v128]$	validation	execution
<code>i8x16.swizzle</code>	0xFD 0x0E	$[v128\ v128] \rightarrow [v128]$	validation	execution
<code>i8x16.splat</code>	0xFD 0x0F	$[i32] \rightarrow [v128]$	validation	execution
<code>i16x8.splat</code>	0xFD 0x10	$[i32] \rightarrow [v128]$	validation	execution
<code>i32x4.splat</code>	0xFD 0x11	$[i32] \rightarrow [v128]$	validation	execution
<code>i64x2.splat</code>	0xFD 0x12	$[i64] \rightarrow [v128]$	validation	execution
<code>f32x4.splat</code>	0xFD 0x13	$[f32] \rightarrow [v128]$	validation	execution
<code>f64x2.splat</code>	0xFD 0x14	$[f64] \rightarrow [v128]$	validation	execution
<code>i8x16.extract_lane_s laneidx</code>	0xFD 0x15	$[v128] \rightarrow [i32]$	validation	execution
<code>i8x16.extract_lane_u laneidx</code>	0xFD 0x16	$[v128] \rightarrow [i32]$	validation	execution
<code>i8x16.replace_lane laneidx</code>	0xFD 0x17	$[v128\ i32] \rightarrow [v128]$	validation	execution
<code>i16x8.extract_lane_s laneidx</code>	0xFD 0x18	$[v128] \rightarrow [i32]$	validation	execution
<code>i16x8.extract_lane_u laneidx</code>	0xFD 0x19	$[v128] \rightarrow [i32]$	validation	execution
<code>i16x8.replace_lane laneidx</code>	0xFD 0x1A	$[v128\ i32] \rightarrow [v128]$	validation	execution
<code>i32x4.extract_lane laneidx</code>	0xFD 0x1B	$[v128] \rightarrow [i32]$	validation	execution
<code>i32x4.replace_lane laneidx</code>	0xFD 0x1C	$[v128\ i32] \rightarrow [v128]$	validation	execution
<code>i64x2.extract_lane laneidx</code>	0xFD 0x1D	$[v128] \rightarrow [i64]$	validation	execution
<code>i64x2.replace_lane laneidx</code>	0xFD 0x1E	$[v128\ i64] \rightarrow [v128]$	validation	execution
<code>f32x4.extract_lane laneidx</code>	0xFD 0x1F	$[v128] \rightarrow [f32]$	validation	execution
<code>f32x4.replace_lane laneidx</code>	0xFD 0x20	$[v128\ f32] \rightarrow [v128]$	validation	execution
<code>f64x2.extract_lane laneidx</code>	0xFD 0x21	$[v128] \rightarrow [f64]$	validation	execution
<code>f64x2.replace_lane laneidx</code>	0xFD 0x22	$[v128\ f64] \rightarrow [v128]$	validation	execution
<code>i8x16.eq</code>	0xFD 0x23	$[v128\ v128] \rightarrow [v128]$	validation	execution (C)

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Instruction	Binary Opcode	Type	Validation	Execution
i8x16.ne	0xFD 0x24	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
i8x16.lt_s	0xFD 0x25	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
i8x16.lt_u	0xFD 0x26	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
i8x16.gt_s	0xFD 0x27	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
i8x16.gt_u	0xFD 0x28	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
i8x16.le_s	0xFD 0x29	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
i8x16.le_u	0xFD 0x2A	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
i8x16.ge_s	0xFD 0x2B	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
i8x16.ge_u	0xFD 0x2C	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
i16x8.eq	0xFD 0x2D	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
i16x8.ne	0xFD 0x2E	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
i16x8.lt_s	0xFD 0x2F	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
i16x8.lt_u	0xFD 0x30	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
i16x8.gt_s	0xFD 0x31	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
i16x8.gt_u	0xFD 0x32	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
i16x8.le_s	0xFD 0x33	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
i16x8.le_u	0xFD 0x34	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
i16x8.ge_s	0xFD 0x35	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
i16x8.ge_u	0xFD 0x36	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
i32x4.eq	0xFD 0x37	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
i32x4.ne	0xFD 0x38	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
i32x4.lt_s	0xFD 0x39	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
i32x4.lt_u	0xFD 0x3A	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
i32x4.gt_s	0xFD 0x3B	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
i32x4.gt_u	0xFD 0x3C	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
i32x4.le_s	0xFD 0x3D	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
i32x4.le_u	0xFD 0x3E	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
i32x4.ge_s	0xFD 0x3F	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
i32x4.ge_u	0xFD 0x40	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
f32x4.eq	0xFD 0x41	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
f32x4.ne	0xFD 0x42	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
f32x4.lt	0xFD 0x43	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
f32x4.gt	0xFD 0x44	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
f32x4.le	0xFD 0x45	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
f32x4.ge	0xFD 0x46	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
f64x2.eq	0xFD 0x47	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
f64x2.ne	0xFD 0x48	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
f64x2.lt	0xFD 0x49	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
f64x2.gt	0xFD 0x4A	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
f64x2.le	0xFD 0x4B	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
f64x2.ge	0xFD 0x4C	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
v128.not	0xFD 0x4D	$[v128] \rightarrow [v128]$	validation	execution (0)
v128.and	0xFD 0x4E	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
v128.andnot	0xFD 0x4F	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
v128.or	0xFD 0x50	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
v128.xor	0xFD 0x51	$[v128\ v128] \rightarrow [v128]$	validation	execution (0)
v128.bitselect	0xFD 0x52	$[v128\ v128\ v128] \rightarrow [v128]$	validation	execution (0)
v128.any_true	0xFD 0x53	$[v128] \rightarrow [i32]$	validation	execution
v128.load8_lane <i>memarg laneidx</i>	0xFD 0x54	$[i32\ v128] \rightarrow [v128]$	validation	execution
v128.load16_lane <i>memarg laneidx</i>	0xFD 0x55	$[i32\ v128] \rightarrow [v128]$	validation	execution
v128.load32_lane <i>memarg laneidx</i>	0xFD 0x56	$[i32\ v128] \rightarrow [v128]$	validation	execution
v128.load64_lane <i>memarg laneidx</i>	0xFD 0x57	$[i32\ v128] \rightarrow [v128]$	validation	execution
v128.store8_lane <i>memarg laneidx</i>	0xFD 0x58	$[i32\ v128] \rightarrow []$	validation	execution

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Instruction	Binary Opcode	Type	Validation	Execution
<code>v128.store16_lane memarg laneidx</code>	0xFD 0x59	$[i32\ v128] \rightarrow []$	validation	execution
<code>v128.store32_lane memarg laneidx</code>	0xFD 0x5A	$[i32\ v128] \rightarrow []$	validation	execution
<code>v128.store64_lane memarg laneidx</code>	0xFD 0x5B	$[i32\ v128] \rightarrow []$	validation	execution
<code>v128.load32_zero memarg</code>	0xFD 0x5C	$[i32] \rightarrow [v128]$	validation	execution
<code>v128.load64_zero memarg</code>	0xFD 0x5D	$[i32] \rightarrow [v128]$	validation	execution
<code>f32x4.demote_f64x2_zero</code>	0xFD 0x5E	$[v128] \rightarrow [v128]$	validation	execution (C)
<code>f64x2.promote_low_f32x4</code>	0xFD 0x5F	$[v128] \rightarrow [v128]$	validation	execution (C)
<code>i8x16.abs</code>	0xFD 0x60	$[v128] \rightarrow [v128]$	validation	execution (C)
<code>i8x16.neg</code>	0xFD 0x61	$[v128] \rightarrow [v128]$	validation	execution (C)
<code>i8x16.popcnt</code>	0xFD 0x62	$[v128] \rightarrow [v128]$	validation	execution (C)
<code>i8x16.all_true</code>	0xFD 0x63	$[v128] \rightarrow [i32]$	validation	execution
<code>i8x16.bitmask</code>	0xFD 0x64	$[v128] \rightarrow [i32]$	validation	execution
<code>i8x16.narrow_i16x8_s</code>	0xFD 0x65	$[v128\ v128] \rightarrow [v128]$	validation	execution
<code>i8x16.narrow_i16x8_u</code>	0xFD 0x66	$[v128\ v128] \rightarrow [v128]$	validation	execution
<code>f32x4.ceil</code>	0xFD 0x67	$[v128] \rightarrow [v128]$	validation	execution (C)
<code>f32x4.floor</code>	0xFD 0x68	$[v128] \rightarrow [v128]$	validation	execution (C)
<code>f32x4.trunc</code>	0xFD 0x69	$[v128] \rightarrow [v128]$	validation	execution (C)
<code>f32x4.nearest</code>	0xFD 0x6A	$[v128] \rightarrow [v128]$	validation	execution (C)
<code>i8x16.shl</code>	0xFD 0x6B	$[v128\ i32] \rightarrow [v128]$	validation	execution (C)
<code>i8x16.shr_s</code>	0xFD 0x6C	$[v128\ i32] \rightarrow [v128]$	validation	execution (C)
<code>i8x16.shr_u</code>	0xFD 0x6D	$[v128\ i32] \rightarrow [v128]$	validation	execution (C)
<code>i8x16.add</code>	0xFD 0x6E	$[v128\ v128] \rightarrow [v128]$	validation	execution (C)
<code>i8x16.add_sat_s</code>	0xFD 0x6F	$[v128\ v128] \rightarrow [v128]$	validation	execution (C)
<code>i8x16.add_sat_u</code>	0xFD 0x70	$[v128\ v128] \rightarrow [v128]$	validation	execution (C)
<code>i8x16.sub</code>	0xFD 0x71	$[v128\ v128] \rightarrow [v128]$	validation	execution (C)
<code>i8x16.sub_sat_s</code>	0xFD 0x72	$[v128\ v128] \rightarrow [v128]$	validation	execution (C)
<code>i8x16.sub_sat_u</code>	0xFD 0x73	$[v128\ v128] \rightarrow [v128]$	validation	execution (C)
<code>f64x2.ceil</code>	0xFD 0x74	$[v128] \rightarrow [v128]$	validation	execution (C)
<code>f64x2.floor</code>	0xFD 0x75	$[v128] \rightarrow [v128]$	validation	execution (C)
<code>i8x16.min_s</code>	0xFD 0x76	$[v128\ v128] \rightarrow [v128]$	validation	execution (C)
<code>i8x16.min_u</code>	0xFD 0x77	$[v128\ v128] \rightarrow [v128]$	validation	execution (C)
<code>i8x16.max_s</code>	0xFD 0x78	$[v128\ v128] \rightarrow [v128]$	validation	execution (C)
<code>i8x16.max_u</code>	0xFD 0x79	$[v128\ v128] \rightarrow [v128]$	validation	execution (C)
<code>f64x2.trunc</code>	0xFD 0x7A	$[v128] \rightarrow [v128]$	validation	execution (C)
<code>i8x16.avgr_u</code>	0xFD 0x7B	$[v128\ v128] \rightarrow [v128]$	validation	execution (C)
<code>i16x8.extadd_pairwise_i8x16_s</code>	0xFD 0x7C	$[v128] \rightarrow [v128]$	validation	execution
<code>i16x8.extadd_pairwise_i8x16_u</code>	0xFD 0x7D	$[v128] \rightarrow [v128]$	validation	execution
<code>i32x4.extadd_pairwise_i16x8_s</code>	0xFD 0x7E	$[v128] \rightarrow [v128]$	validation	execution
<code>i32x4.extadd_pairwise_i16x8_u</code>	0xFD 0x7F	$[v128] \rightarrow [v128]$	validation	execution
<code>i16x8.abs</code>	0xFD 0x80 0x01	$[v128] \rightarrow [v128]$	validation	execution (C)
<code>i16x8.neg</code>	0xFD 0x81 0x01	$[v128] \rightarrow [v128]$	validation	execution (C)
<code>i16x8.q15mulr_sat_s</code>	0xFD 0x82 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (C)
<code>i16x8.all_true</code>	0xFD 0x83 0x01	$[v128] \rightarrow [i32]$	validation	execution
<code>i16x8.bitmask</code>	0xFD 0x84 0x01	$[v128] \rightarrow [i32]$	validation	execution
<code>i16x8.narrow_i32x4_s</code>	0xFD 0x85 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution
<code>i16x8.narrow_i32x4_u</code>	0xFD 0x86 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution
<code>i16x8.extend_low_i8x16_s</code>	0xFD 0x87 0x01	$[v128] \rightarrow [v128]$	validation	execution
<code>i16x8.extend_high_i8x16_s</code>	0xFD 0x88 0x01	$[v128] \rightarrow [v128]$	validation	execution
<code>i16x8.extend_low_i8x16_u</code>	0xFD 0x89 0x01	$[v128] \rightarrow [v128]$	validation	execution
<code>i16x8.extend_high_i8x16_u</code>	0xFD 0x8A 0x01	$[v128] \rightarrow [v128]$	validation	execution
<code>i16x8.shl</code>	0xFD 0x8B 0x01	$[v128\ i32] \rightarrow [v128]$	validation	execution (C)
<code>i16x8.shr_s</code>	0xFD 0x8C 0x01	$[v128\ i32] \rightarrow [v128]$	validation	execution (C)
<code>i16x8.shr_u</code>	0xFD 0x8D 0x01	$[v128\ i32] \rightarrow [v128]$	validation	execution (C)

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Instruction	Binary Opcode	Type	Validation	Execution
i16x8.add	0xFD 0x8E 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
i16x8.add_sat_s	0xFD 0x8F 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
i16x8.add_sat_u	0xFD 0x90 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
i16x8.sub	0xFD 0x91 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
i16x8.sub_sat_s	0xFD 0x92 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
i16x8.sub_sat_u	0xFD 0x93 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
f64x2.nearest	0xFD 0x94 0x01	$[v128] \rightarrow [v128]$	validation	execution (o
i16x8.mul	0xFD 0x95 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
i16x8.min_s	0xFD 0x96 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
i16x8.min_u	0xFD 0x97 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
i16x8.max_s	0xFD 0x98 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
i16x8.max_u	0xFD 0x99 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
(reserved)	0xFD 0x9A 0x01			
i16x8.avgr_u	0xFD 0x9B 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
i16x8.extmul_low_i8x16_s	0xFD 0x9C 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution
i16x8.extmul_high_i8x16_s	0xFD 0x9D 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution
i16x8.extmul_low_i8x16_u	0xFD 0x9E 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution
i16x8.extmul_high_i8x16_u	0xFD 0x9F 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution
i32x4.abs	0xFD 0xA0 0x01	$[v128] \rightarrow [v128]$	validation	execution (o
i32x4.neg	0xFD 0xA1 0x01	$[v128] \rightarrow [v128]$	validation	execution (o
(reserved)	0xFD 0xA2 0x01			
i32x4.all_true	0xFD 0xA3 0x01	$[v128] \rightarrow [i32]$	validation	execution
i32x4.bitmask	0xFD 0xA4 0x01	$[v128] \rightarrow [i32]$	validation	execution
(reserved)	0xFD 0xA5 0x01			
(reserved)	0xFD 0xA6 0x01			
i32x4.extend_low_i16x8_s	0xFD 0xA7 0x01	$[v128] \rightarrow [v128]$	validation	execution
i32x4.extend_high_i16x8_s	0xFD 0xA8 0x01	$[v128] \rightarrow [v128]$	validation	execution
i32x4.extend_low_i16x8_u	0xFD 0xA9 0x01	$[v128] \rightarrow [v128]$	validation	execution
i32x4.extend_high_i16x8_u	0xFD 0xAA 0x01	$[v128] \rightarrow [v128]$	validation	execution
i32x4.shl	0xFD 0xAB 0x01	$[v128\ i32] \rightarrow [v128]$	validation	execution (o
i32x4.shr_s	0xFD 0xAC 0x01	$[v128\ i32] \rightarrow [v128]$	validation	execution (o
i32x4.shr_u	0xFD 0xAD 0x01	$[v128\ i32] \rightarrow [v128]$	validation	execution (o
i32x4.add	0xFD 0xAE 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
(reserved)	0xFD 0xAF 0x01			
(reserved)	0xFD 0xB0 0x01			
i32x4.sub	0xFD 0xB1 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
(reserved)	0xFD 0xB2 0x01			
(reserved)	0xFD 0xB3 0x01			
(reserved)	0xFD 0xB4 0x01			
i32x4.mul	0xFD 0xB5 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
i32x4.min_s	0xFD 0xB6 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
i32x4.min_u	0xFD 0xB7 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
i32x4.max_s	0xFD 0xB8 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
i32x4.max_u	0xFD 0xB9 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
i32x4.dot_i16x8_s	0xFD 0xBA 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution
i32x4.extmul_low_i16x8_s	0xFD 0xBC 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution
i32x4.extmul_high_i16x8_s	0xFD 0xBD 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution
i32x4.extmul_low_i16x8_u	0xFD 0xBE 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution
i32x4.extmul_high_i16x8_u	0xFD 0xBF 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution
i64x2.abs	0xFD 0xC0 0x01	$[v128] \rightarrow [v128]$	validation	execution (o
i64x2.neg	0xFD 0xC1 0x01	$[v128] \rightarrow [v128]$	validation	execution (o
(reserved)	0xFD 0xC2 0x01			
i64x2.all_true	0xFD 0xC3 0x01	$[v128] \rightarrow [i32]$	validation	execution

continues on ne

Table 2 – continued from previous page

Instruction	Binary Opcode	Type	Validation	Execution
i64x2.bitmask	0xFD 0xC4 0x01	$[v128] \rightarrow [i32]$	validation	execution
(reserved)	0xFD 0xC5 0x01			
(reserved)	0xFD 0xC6 0x01			
i64x2.extend_low_i32x4_s	0xFD 0xC7 0x01	$[v128] \rightarrow [v128]$	validation	execution
i64x2.extend_high_i32x4_s	0xFD 0xC8 0x01	$[v128] \rightarrow [v128]$	validation	execution
i64x2.extend_low_i32x4_u	0xFD 0xC9 0x01	$[v128] \rightarrow [v128]$	validation	execution
i64x2.extend_high_i32x4_u	0xFD 0xCA 0x01	$[v128] \rightarrow [v128]$	validation	execution
i64x2.shl	0xFD 0xCB 0x01	$[v128\ i32] \rightarrow [v128]$	validation	execution (o
i64x2.shr_s	0xFD 0xCC 0x01	$[v128\ i32] \rightarrow [v128]$	validation	execution (o
i64x2.shr_u	0xFD 0xCD 0x01	$[v128\ i32] \rightarrow [v128]$	validation	execution (o
i64x2.add	0xFD 0xCE 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
(reserved)	0xFD 0xCF 0x01			
(reserved)	0xFD 0xD0 0x01			
i64x2.sub	0xFD 0xD1 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
(reserved)	0xFD 0xD2 0x01			
(reserved)	0xFD 0xD3 0x01			
(reserved)	0xFD 0xD4 0x01			
i64x2.mul	0xFD 0xD5 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
i64x2.eq	0xFD 0xD6 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
i64x2.ne	0xFD 0xD7 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
i64x2.lt_s	0xFD 0xD8 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
i64x2.gt_s	0xFD 0xD9 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
i64x2.le_s	0xFD 0xDA 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
i64x2.ge_s	0xFD 0xDB 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
i64x2.extmul_low_i32x4_s	0xFD 0xDC 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution
i64x2.extmul_high_i32x4_s	0xFD 0xDD 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution
i64x2.extmul_low_i32x4_u	0xFD 0xDE 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution
i64x2.extmul_high_i32x4_u	0xFD 0xDF 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution
f32x4.abs	0xFD 0xE0 0x01	$[v128] \rightarrow [v128]$	validation	execution (o
f32x4.neg	0xFD 0xE1 0x01	$[v128] \rightarrow [v128]$	validation	execution (o
(reserved)	0xFD 0xE2 0x01			
f32x4.sqrt	0xFD 0xE3 0x01	$[v128] \rightarrow [v128]$	validation	execution (o
f32x4.add	0xFD 0xE4 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
f32x4.sub	0xFD 0xE5 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
f32x4.mul	0xFD 0xE6 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
f32x4.div	0xFD 0xE7 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
f32x4.min	0xFD 0xE8 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
f32x4.max	0xFD 0xE9 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
f32x4.pmin	0xFD 0xEA 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
f32x4.pmax	0xFD 0xEB 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
f64x2.abs	0xFD 0xEC 0x01	$[v128] \rightarrow [v128]$	validation	execution (o
f64x2.neg	0xFD 0xED 0x01	$[v128] \rightarrow [v128]$	validation	execution (o
f64x2.sqrt	0xFD 0xEF 0x01	$[v128] \rightarrow [v128]$	validation	execution (o
f64x2.add	0xFD 0xF0 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
f64x2.sub	0xFD 0xF1 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
f64x2.mul	0xFD 0xF2 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
f64x2.div	0xFD 0xF3 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
f64x2.min	0xFD 0xF4 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
f64x2.max	0xFD 0xF5 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
f64x2.pmin	0xFD 0xF6 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
f64x2.pmax	0xFD 0xF7 0x01	$[v128\ v128] \rightarrow [v128]$	validation	execution (o
i32x4.trunc_sat_f32x4_s	0xFD 0xF8 0x01	$[v128] \rightarrow [v128]$	validation	execution (o
i32x4.trunc_sat_f32x4_u	0xFD 0xF9 0x01	$[v128] \rightarrow [v128]$	validation	execution (o

continues on ne

Table 2 – continued from previous page

Instruction	Binary Opcode	Type	Validation	Execution
<code>f32x4.convert_i32x4_s</code>	0xFD 0xFA 0x01	$[v_{128}] \rightarrow [v_{128}]$	validation	execution (0)
<code>f32x4.convert_i32x4_u</code>	0xFD 0xFB 0x01	$[v_{128}] \rightarrow [v_{128}]$	validation	execution (0)
<code>i32x4.trunc_sat_f64x2_s_zero</code>	0xFD 0xFC 0x01	$[v_{128}] \rightarrow [v_{128}]$	validation	execution (0)
<code>i32x4.trunc_sat_f64x2_u_zero</code>	0xFD 0xFD 0x01	$[v_{128}] \rightarrow [v_{128}]$	validation	execution (0)
<code>f64x2.convert_low_i32x4_s</code>	0xFD 0xFE 0x01	$[v_{128}] \rightarrow [v_{128}]$	validation	execution (0)
<code>f64x2.convert_low_i32x4_u</code>	0xFD 0xFF 0x01	$[v_{128}] \rightarrow [v_{128}]$	validation	execution (0)
(reserved)	0xFD 0x00 0x02 . . .			
(reserved)	0xFE			
(reserved)	0xFF			

Note: Multi-byte opcodes are given with the shortest possible encoding in the table. However, what is following the first byte is actually a `u32` with variable-length encoding and consequently has multiple possible representations.

7.10 Index of Semantic Rules

7.10.1 Well-formedness of Types

Construct	Judgement
Numeric type	$C \vdash \text{numtype} : \text{ok}$
Vector type	$C \vdash \text{vectype} : \text{ok}$
Heap type	$C \vdash \text{heapttype} : \text{ok}$
Reference type	$C \vdash \text{reftype} : \text{ok}$
Value type	$C \vdash \text{valtype} : \text{ok}$
Packed type	$C \vdash \text{packtype} : \text{ok}$
Storage type	$C \vdash \text{storagetype} : \text{ok}$
Field type	$C \vdash \text{fieldtype} : \text{ok}$
Result type	$C \vdash \text{resulttype} : \text{ok}$
Instruction type	$C \vdash \text{instrtype} : \text{ok}$
Function type	$C \vdash \text{functype} : \text{ok}$
Structure type	$C \vdash \text{structtype} : \text{ok}$
Array type	$C \vdash \text{arraytype} : \text{ok}$
Composite type	$C \vdash \text{comptype} : \text{ok}$
Sub type	$C \vdash \text{subtype} : \text{ok}$
Recursive type	$C \vdash \text{rectype} : \text{ok}$
Defined type	$C \vdash \text{deftype} : \text{ok}$
Block type	$C \vdash \text{blocktype} : \text{instrtype}$
Table type	$C \vdash \text{tabletype} : \text{ok}$
Memory type	$C \vdash \text{memtype} : \text{ok}$
Global type	$C \vdash \text{globaltype} : \text{ok}$
External type	$C \vdash \text{externtype} : \text{ok}$
Type definitions	$C \vdash \text{type}^* : \text{ok}$

7.10.2 Typing of Static Constructs

Construct	Judgement
Instruction	$S; C \vdash instr : functype$
Instruction sequence	$S; C \vdash instr^* : functype$
Expression	$C \vdash expr : resulttype$
Function	$C \vdash func : functype$
Local	$C \vdash local : localtype$
Table	$C \vdash table : tabletype$
Memory	$C \vdash mem : memtype$
Limits	$C \vdash limits : k$
Global	$C \vdash global : globaltype$
Element segment	$C \vdash elem : reftype$
Element mode	$C \vdash elemmode : reftype$
Data segment	$C \vdash data : ok$
Data mode	$C \vdash datamode : ok$
Start function	$C \vdash start : ok$
Export	$C \vdash export : externtype$
Export description	$C \vdash exportdesc : externtype$
Import	$C \vdash import : externtype$
Import description	$C \vdash importdesc : externtype$
Module	$\vdash module : externtype^* \rightarrow externtype^*$

7.10.3 Typing of Runtime Constructs

Construct	Judgement
Value	$S \vdash val : valtype$
Result	$S \vdash result : resulttype$
Packed value	$S \vdash packval : packtype$
Field value	$S \vdash fieldval : storagetype$
External value	$S \vdash externval : externtype$
Function instance	$S \vdash funcinst : functype$
Table instance	$S \vdash tableinst : tabletype$
Memory instance	$S \vdash meminst : memtype$
Global instance	$S \vdash globalinst : globaltype$
Element instance	$S \vdash eleminst : t$
Data instance	$S \vdash datainst : ok$
Structure instance	$S \vdash structinst : ok$
Array instance	$S \vdash arrayinst : ok$
Export instance	$S \vdash exportinst : ok$
Module instance	$S \vdash moduleinst : C$
Store	$\vdash store : ok$
Configuration	$\vdash config : [t^*]$
Thread	$S; resulttype^? \vdash thread : resulttype$
Frame	$S \vdash frame : C$

7.10.4 Constantness

Construct	Judgement
Constant expression	$C \vdash \text{exprconst}$
Constant instruction	$C \vdash \text{instrconst}$

7.10.5 Matching

Construct	Judgement
Number type	$C \vdash \text{numtype}_1 \leq \text{numtype}_2$
Vector type	$C \vdash \text{vectype}_1 \leq \text{vectype}_2$
Heap type	$C \vdash \text{heaptypes}_1 \leq \text{heaptypes}_2$
Reference type	$C \vdash \text{reftype}_1 \leq \text{reftype}_2$
Value type	$C \vdash \text{valtype}_1 \leq \text{valtype}_2$
Packed type	$C \vdash \text{packtype}_1 \leq \text{packtype}_2$
Storage type	$C \vdash \text{storagetype}_1 \leq \text{storagetype}_2$
Field type	$C \vdash \text{fieldtype}_1 \leq \text{fieldtype}_2$
Result type	$C \vdash \text{resulttype}_1 \leq \text{resulttype}_2$
Instruction type	$C \vdash \text{instrtype}_1 \leq \text{instrtype}_2$
Function type	$C \vdash \text{functype}_1 \leq \text{functype}_2$
Structure type	$C \vdash \text{structtype}_1 \leq \text{structtype}_2$
Array type	$C \vdash \text{arraytype}_1 \leq \text{arraytype}_2$
Composite type	$C \vdash \text{comptype}_1 \leq \text{comptype}_2$
Defined type	$C \vdash \text{deftype}_1 \leq \text{deftype}_2$
Table type	$C \vdash \text{tabletype}_1 \leq \text{tabletype}_2$
Memory type	$C \vdash \text{memtype}_1 \leq \text{memtype}_2$
Global type	$C \vdash \text{globaltype}_1 \leq \text{globaltype}_2$
External type	$C \vdash \text{externtype}_1 \leq \text{externtype}_2$
Limits	$C \vdash \text{limits}_1 \leq \text{limits}_2$

7.10.6 Store Extension

Construct	Judgement
Function instance	$\vdash \text{funcinst}_1 \preceq \text{funcinst}_2$
Table instance	$\vdash \text{tableinst}_1 \preceq \text{tableinst}_2$
Memory instance	$\vdash \text{meminst}_1 \preceq \text{meminst}_2$
Global instance	$\vdash \text{globalinst}_1 \preceq \text{globalinst}_2$
Element instance	$\vdash \text{eleminst}_1 \preceq \text{eleminst}_2$
Data instance	$\vdash \text{datainst}_1 \preceq \text{datainst}_2$
Structure instance	$\vdash \text{structinst}_1 \preceq \text{structinst}_2$
Array instance	$\vdash \text{arrayinst}_1 \preceq \text{arrayinst}_2$
Store	$\vdash \text{store}_1 \preceq \text{store}_2$

7.10.7 Execution

Construct	Judgement
Instruction	$S; F; instr^* \hookrightarrow S'; F'; instr'^*$
Expression	$S; F; expr \hookrightarrow S'; F'; expr'$

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