



## Subject card

Subject name and code	Numerical Methods in Automatic Control - laboratory, PG_00047694						
Field of study	Automatic Control, Cybernetics and Robotics						
Date of commencement of studies	October 2020		Academic year of realisation of subject		2022/2023		
Education level	first-cycle studies		Subject group		Optional subject group Subject group related to scientific research in the field of study		
Mode of study	Full-time studies		Mode of delivery		at the university		
Year of study	3		Language of instruction		Polish		
Semester of study	6		ECTS credits		2.0		
Learning profile	general academic profile		Assessment form		assessment		
Conducting unit	Department of Decision Systems and Robotics -> Faculty of Electronics, Telecommunications and Informatics						
Name and surname of lecturer (lecturers)	Subject supervisor		dr inż. Mariusz Domżałski				
	Teachers		dr inż. Mariusz Domżałski				
Lesson types and methods of instruction	Lesson type	Lecture	Tutorial	Laboratory	Project	Seminar	SUM
	Number of study hours	0.0	0.0	30.0	0.0	0.0	30
	E-learning hours included: 0.0						
Learning activity and number of study hours	Learning activity	Participation in didactic classes included in study plan		Participation in consultation hours		Self-study	SUM
	Number of study hours	30		2.0		18.0	50
Subject objectives	Learning and mastering the practice of modern numerical algorithms required to solve number of engineering problems.						
Learning outcomes	Course outcome		Subject outcome		Method of verification		
	[K6_U04] can apply knowledge of programming methods and techniques as well as select and apply appropriate programming methods and tools in computer software development or programming devices or controllers using microprocessors or programmable elements or systems specific to the field of study		Student is able to implement numerical methods algorithms. Student is able to assess the correctness of numerical algorithms.		[SU4] Assessment of ability to use methods and tools [SU1] Assessment of task fulfilment		
	[K6_U01] can apply mathematical knowledge to formulate and solve complex and non-typical problems related to the field of study and perform tasks, in an innovative way, in not entirely predictable conditions, by:n- appropriate selection of sources and information obtained from them, assessment, critical analysis and synthesis of this information,n-selection and application of appropriate methods and toolsn		Student is able to analyze mathematical problems and choose appropriate numerical methods to solve them. Student is able to use external sources when solving numerical problems.		[SU3] Assessment of ability to use knowledge gained from the subject [SU2] Assessment of ability to analyse information		

Subject contents	<ol style="list-style-type: none"><li>1. Numbers representation, errors, numerical stability.</li><li>2. Solution of linear algebraic equations: Gauss elimination.</li><li>3. LU factorization, the matrix inverse, vector and matrix norms, matrix condition number.</li><li>4. Solution of systems of nonlinear equations: Newton-Raphson method.</li><li>5. LQR optimal control.</li><li>6. Approximation. Nonlinear regression. Least squares method.</li><li>7. Kalman filtering.</li><li>8. Interpolation. Newton polynomials. Splines and piecewise interpolation.</li><li>9. Numerical integration of functions. Romberg method. Gauss quadrature.</li><li>10. Solution of ordinary differential equations: Euler's method, Heun's method, midpoint method.</li><li>11. Solution of systems of ordinary differential equations: Runge-Kutta method.</li><li>12. Equations and systems of differential equations: boundary-value problems. Finite-difference method.</li></ol>		
Prerequisites and co-requisites			
Assessment methods and criteria	Subject passing criteria	Passing threshold	Percentage of the final grade
	Programming excercises	50.0%	100.0%
Recommended reading	Basic literature	• Lecture notes in Numerical Methods in Automation and Robotics.	
	Supplementary literature	• Anthony Ralston, <i>A First Course in Numerical Analysis</i> , 2nd edition, Dover Publications, 2001. • <i>Numerical Recipes in C</i> , Second Edition (1992), <a href="http://http://www.nrbook.com/a/bookcpdf.php">http://http://www.nrbook.com/a/bookcpdf.php</a> . • Steven C. Chapra, <i>Applied Numerical Methods with MATLAB for Engineers and Scientists</i> , 2nd edition, McGraw-Hill, 2006.	
	eResources addresses	Adresy na platformie eNauczanie:	
Example issues/ example questions/ tasks being completed	The least squares method in identifying the transmittance of a dynamic linear object.  Implementation of the Kalman filter for a discrete system.  Solving ordinary differential equations using Runge-Kutta methods.  Solving partial differential equations using the finite difference method.		
Work placement	Not applicable		