



## Absolute Maximum Ratings

(All voltages referenced to GND.)

V <sub>DD</sub> .....	-0.3V to +40V	Multilayer Board (derate at 24.4mW/°C above +70°C).....	1951mW
M1, M2 .....	-0.3V to (V <sub>DD</sub> + 0.3V)	Operating Temperature Range .....	-40°C to +85°C
PWM, DIR, FWD, REV, FAULT, EN, SNS .....	-0.3V to +6.0V	Junction Temperature .....	+150°C
COM .....	-0.3V to +0.3V	Storage Temperature Range .....	-65°C to +150°C
Continuous Current Into M1, M2 .....	±3A	Lead Temperature (soldering, 10s) .....	+300°C
Continuous Power Dissipation (T <sub>A</sub> = +70°C)		Solder Temperature (reflow) .....	+260°C
Single-Layer Board (derate at 15.9mW/°C above +70°C).....			
			1270mW

Stresses beyond those listed under "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only, and functional operation of the device at these or any other conditions beyond those indicated in the operational sections of the specifications is not implied. Exposure to absolute maximum rating conditions for extended periods may affect device reliability.

## Package Thermal Characteristics (Note 1)

Junction-to-Case Thermal Resistance (θ <sub>JC</sub> )	Junction-to-Ambient Thermal Resistance (θ <sub>JA</sub> )
TDFN-EP (Single-Layer Board).....	TDFN-EP (Single-Layer Board).....
8.5°C/W	63°C/W
TDFN-EP (Multilayer Board).....	TDFN-EP (Multilayer Board).....
8.5°C/W	41°C/W

**Note 1:** Package thermal resistances were obtained using the method described in JEDEC specification JESD51-7, using a four-layer board. For detailed information on package thermal considerations, refer to [www.maximintegrated.com/thermal-tutorial](http://www.maximintegrated.com/thermal-tutorial).

## Electrical Characteristics

(V<sub>DD</sub> = 4.5V to 36V, T<sub>A</sub> = T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted. Typical values are at V<sub>DD</sub> = 12V, T<sub>A</sub> = +25°C) (Note 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
<b>POWER SUPPLY</b>						
Supply Voltage	V <sub>DD</sub>		4.5		36	V
Supply Current	I <sub>DD</sub>	EN = low, M1/M2 not connected	f <sub>PWM/FWD</sub> = 50kHz	1		mA
			No switching	0.5	1.2	
Shutdown Supply Current	I <sub>SHDN</sub>	EN = high, driver is in shutdown	V <sub>DD</sub> = 12V	3.7	10	μA
			V <sub>DD</sub> = 36V	10	20	
Undervoltage Lockout Threshold	V <sub>UVLO</sub>	V <sub>DD</sub> rising	3.3	3.8	4.3	V
Undervoltage Lockout Threshold Hysteresis	V <sub>UVLO_HYST</sub>			400		mV

**Electrical Characteristics (continued)**(V<sub>DD</sub> = 4.5V to 36V, T<sub>A</sub> = T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted. Typical values are at V<sub>DD</sub> = 12V, T<sub>A</sub> = +25°C) (Note 2)

PARAMETER	SYMBOL	CONDITIONS		MIN	TYP	MAX	UNITS
DRIVER (M1, M2)							
Driver Output Resistance (High Side + Low Side)	R <sub>ON</sub>	I <sub>M_</sub> = 2.5A	T <sub>J</sub> = +25°C	280	395	mΩ	
			T <sub>J</sub> = +125°C	410	580		
Driver Overload Current Limit	I <sub>M_OL</sub>			3		A	
M1, M2 Leakage Current	I <sub>M_LKG</sub>	EN̄ = High, V <sub>M1</sub> = V <sub>M2</sub> = 0V or V <sub>DD</sub>		-1	+1	μA	
M1, M2 Body Diode Forward-Voltage	V <sub>BF</sub>	Low-side diode, EN̄ = high, I <sub>F</sub> = 2.5A			1.5	V	
		High-side diode, EN̄ = high, I <sub>F</sub> = 2.5A			1.5		
CURRENT REGULATION (SNS, COM)							
SNS Current Sense Threshold	V <sub>SNS_TH</sub>	V <sub>SNS</sub> rising (Note 3)		94	100	110	mV
SNS Input Leakage Current	I <sub>SNS_LKG</sub>	V <sub>SNS</sub> = ±250mV		-1		+1	μA
COM Leakage Current	I <sub>COM_LKG</sub>	EN̄ = high, V <sub>COM</sub> = ±250mV		-1		+1	μA
LOGIC SIGNALS (PWM, DIR, FWD, REV, EN̄, FAULT̄)							
Input Logic-High Voltage	V <sub>IH</sub>	FWD, REV, PWM, DIR		2			V
Input Logic-Low Voltage	V <sub>IL</sub>	FWD, REV, PWM, DIR				0.8	V
EN̄ Input Logic-High Voltage	V <sub>EN_IH</sub>			1.6			
EN̄ Input Logic-Low Voltage	V <sub>EN_IL</sub>					0.4	
Input Leakage Current	I <sub>IL</sub>	PWM, DIR, FWD, REV, EN̄, V <sub>INPUT</sub> = 5.5V or 0V		-1		+1	μA
FAULT̄ Output Low Voltage	V <sub>OL</sub>	FAULT̄ asserted, I <sub>SINK</sub> = 5mA				0.5	V
FAULT̄ Off Leakage Current	I <sub>F_LKG</sub>	FAULT̄ deasserted, V <sub>FAULT̄</sub> = 5.5V		-1		+1	μA
PROTECTION							
Thermal-Shutdown Threshold	T <sub>SHDN</sub>	Temperature rising, FAULT̄ asserted			+160		°C
Thermal-Shutdown Hysteresis	T <sub>SHDN_HYST</sub>				10		°C

**AC Electrical Characteristics**(V<sub>DD</sub> = 4.5V to 36V, T<sub>A</sub> = T<sub>MIN</sub> to T<sub>MAX</sub>, unless otherwise noted. Typical values are at V<sub>DD</sub> = 12V, T<sub>A</sub> = +25°C) (Note 2)

PARAMETER	SYMBOL	CONDITIONS	MIN	TYP	MAX	UNITS
PWM Frequency	f <sub>SW</sub>	MAX14870, switching signal applied at PWM			50	kHz
		MAX14872, switching signal applied at FWD or REV			50	
Dead Time	t <sub>DEAD</sub>			140		ns
M1, M2 Slew Rate	SR			200		V/μs
M1, M2 High-Side Propagation Delay	t <sub>PR</sub>	R <sub>L</sub> = 1kΩ, C <sub>L</sub> = 50pF, PWM/FWD/DIR/REV rising, Figure 1		620		ns
M1, M2 Low-Side Propagation Delay	t <sub>PF</sub>	R <sub>L</sub> = 1kΩ, C <sub>L</sub> = 50pF, PWM/FWD/DIR/REV falling, Figure 1		583		ns
Current Regulation Fixed Off-Time	t <sub>OFF</sub>	PWM/FWD = high, $\overline{\text{EN}}$ = low, V <sub>SNS</sub> > V <sub>SNS_TH</sub>	7.8	15	22	μs
Current Regulation Minimum On-Time	t <sub>CR_BL</sub>	PWM/FWD = high, $\overline{\text{EN}}$ = low, V <sub>SNS</sub> > V <sub>SNS_TH</sub>		2.5		μs
Overcurrent Blanking Time	t <sub>OC_BL</sub>	M1/M2 is shorted to V <sub>DD</sub> or GND, Figure 2		1		μs
Overcurrent Autoretry Timeout	t <sub>OC_TO</sub>	PWM/FWD = high, $\overline{\text{EN}}$ = low, I <sub>M</sub> or I <sub>M2</sub> > I <sub>M_OL</sub> , Figure 2		2		ms
Enable Turn-On Delay	t <sub>EN_ON</sub>	PWM/FWD = high, R <sub>L</sub> = 1kΩ, C <sub>L</sub> = 50pF, $\overline{\text{EN}}$ falling, M1/M2 rising to 10%, Figure 3		23		μs
Enable Turn-Off Delay	t <sub>EN_OFF</sub>	PWM/FWD = high, R <sub>L</sub> = 1kΩ, C <sub>L</sub> = 50pF, $\overline{\text{EN}}$ rising, M1/M2 falling to 90%, Figure 3		50		μs

**Note 2:** All units are production tested at T<sub>A</sub> = +25°C. Specifications over temperature are guaranteed by design.**Note 3:** V<sub>SNS\_TH</sub> is the threshold voltage to turn on current regulation.

## Test Circuits/Timing Diagrams

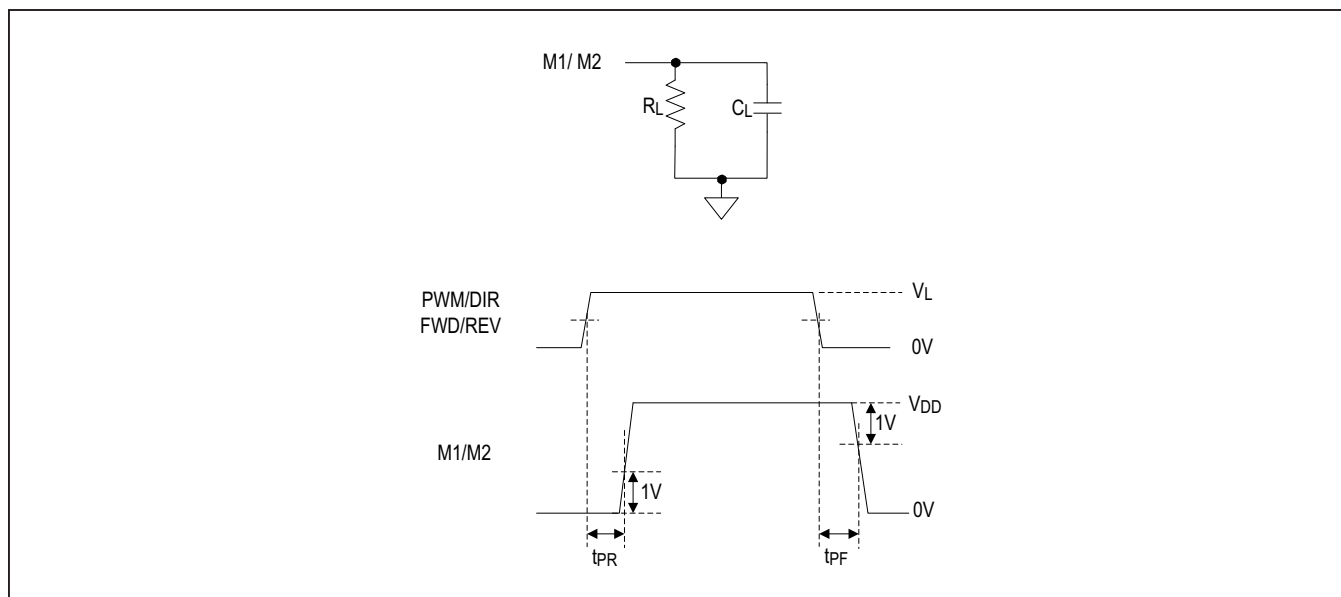


Figure 1. M1/M2 Propagation Delay

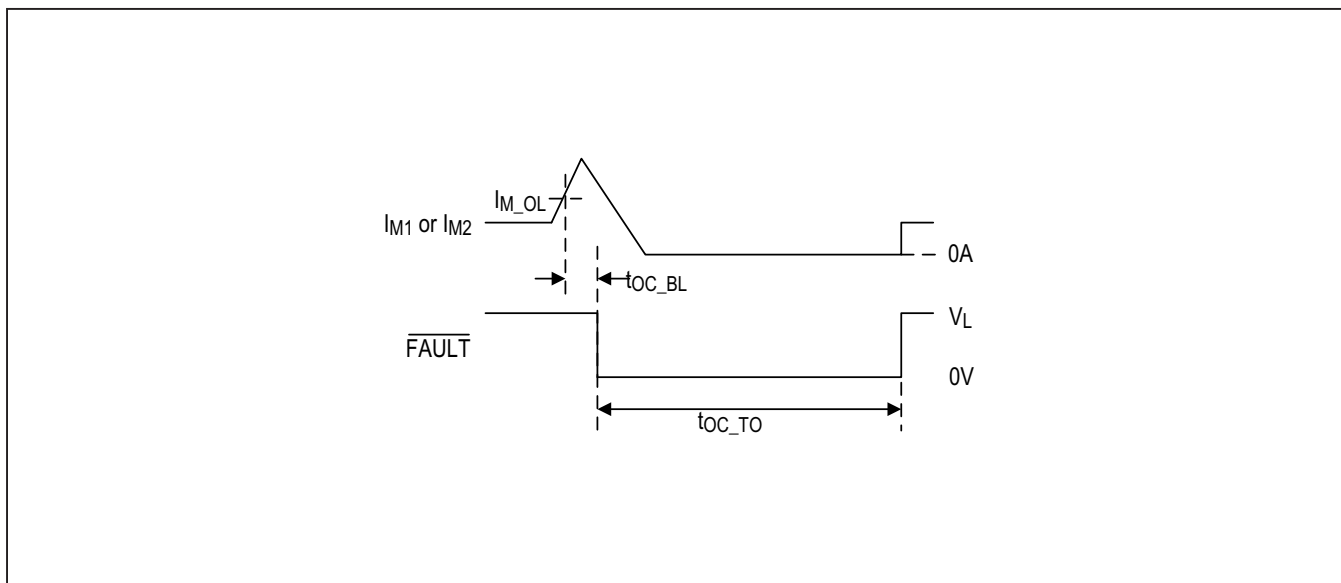


Figure 2. Overcurrent Autoretry Timeout

## Test Circuits/Timing Diagrams (continued)

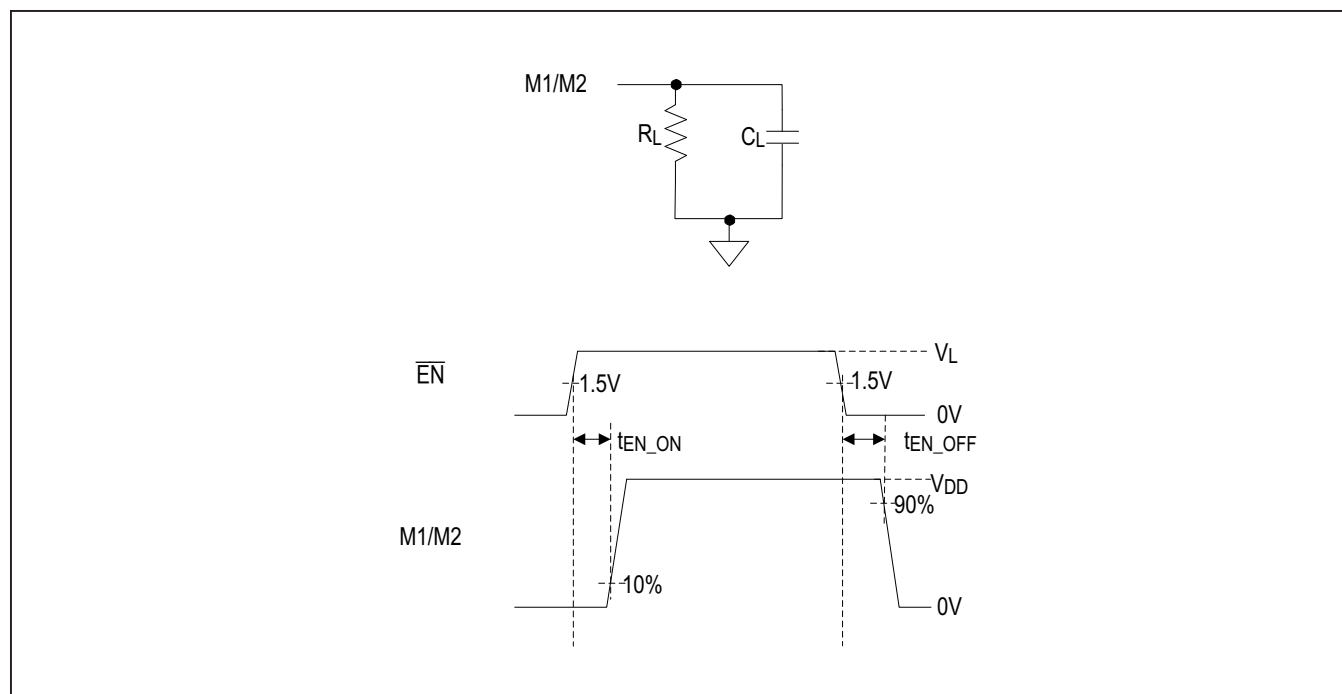
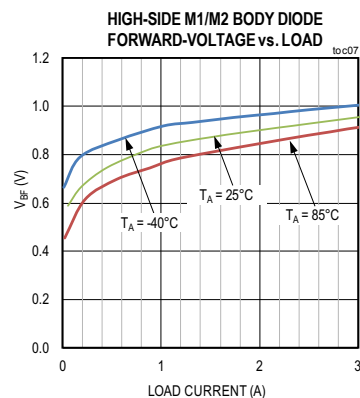
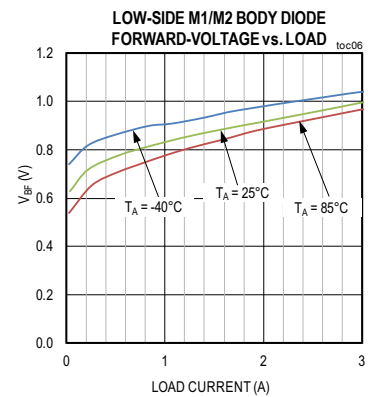
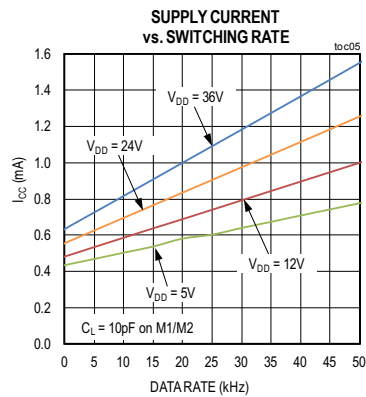
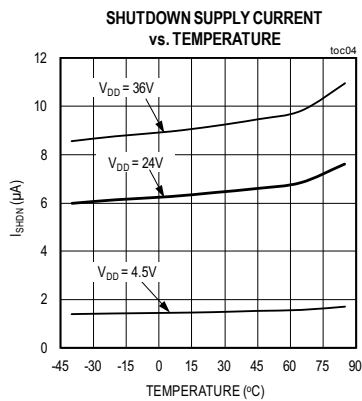
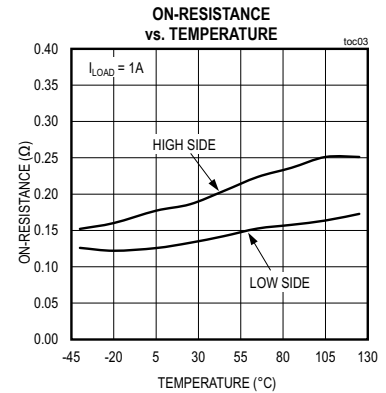
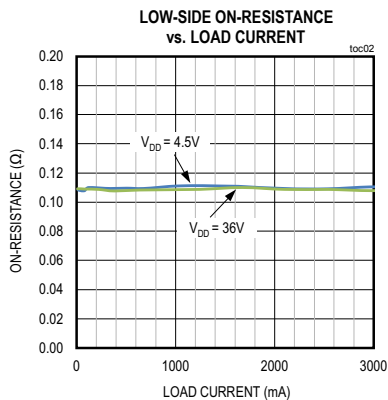
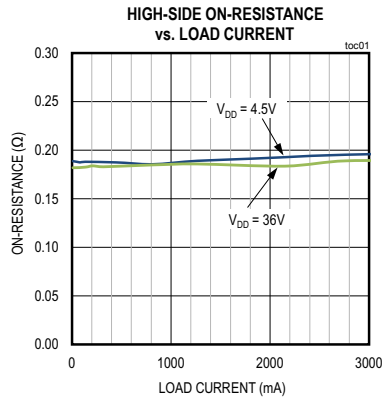


Figure 3. Enable/Disable Delays

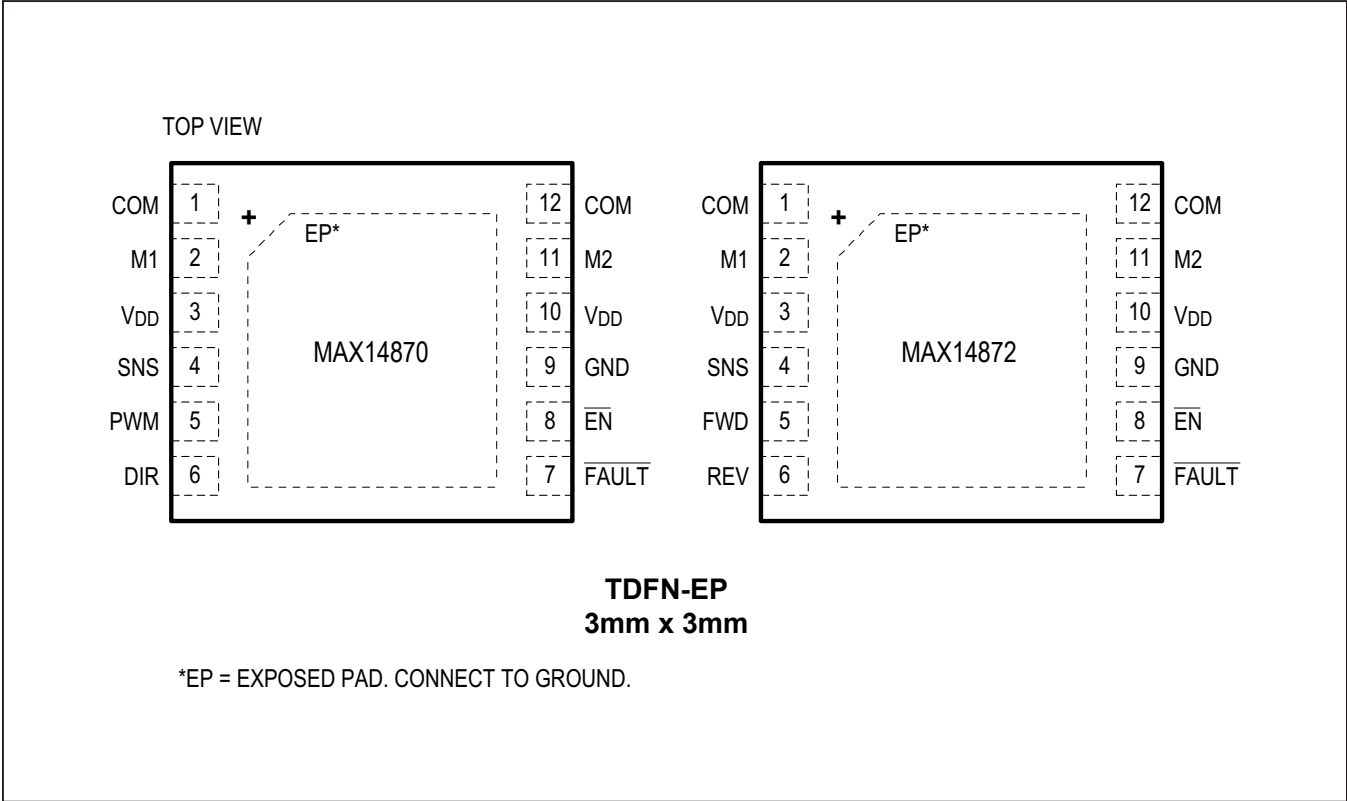
## Typical Operating Characteristics

(V<sub>DD</sub> = 12V, T<sub>A</sub> = +25°C, unless otherwise noted.)

MAX14870/MAX14872

Compact 4.5V to 36V  
Full-Bridge DC Motor Drivers

Pin Configuration



Pin Description

PIN		NAME	FUNCTION
MAX14870	MAX14872		
1, 12	1, 12	COM	COM Current Output. Connect a sense resistor ( $R_{SENSE}$ ) from COM to GND to use internal current regulation and/or external current control. Connect both COM pins together.
2	2	M1	Motor Driver Output 1. See the <a href="#">MAX14870 Function Table</a> and <a href="#">MAX14872 Function Table</a> for more information.
3, 10	3, 10	V <sub>DD</sub>	Power Supply Input. Bypass V <sub>DD</sub> to GND with a 1μF ceramic capacitor as close to the device as possible. Connect both V <sub>DD</sub> pins together.
4	4	SNS	Current Sense Input. Connect SNS to COM to enable current regulation. To bypass current regulation, connect SNS to GND.
5	—	PWM	PWM Control Logic Input. PWM and DIR control M1 and M2 on the MAX14870. See the <a href="#">MAX14870 Function Table</a> and <a href="#">MAX14872 Function Table</a> for more information.
6	—	DIR	Direction Control Logic Input. PWM and DIR control M1 and M2 on the MAX14870. See the <a href="#">MAX14870 Function Table</a> and <a href="#">MAX14872 Function Table</a> for more information.
—	5	FWD	Forward Control Logic Input. FWD and REV control M1 and M2 on the MAX14872. See the <a href="#">MAX14870 Function Table</a> and <a href="#">MAX14872 Function Table</a> for more information.
—	6	REV	Reverse Control Logic Input. FWD and REV control M1 and M2 on the MAX14872. See the <a href="#">MAX14870 Function Table</a> and <a href="#">MAX14872 Function Table</a> for more information.



## Pin Description (continued)

PIN		NAME	FUNCTION
MAX14870	MAX14872		
7	7	$\overline{\text{FAULT}}$	Open-Drain Active-Low Fault Output. $\overline{\text{FAULT}}$ goes low during an overcurrent condition and thermal shutdown.
8	8	$\overline{\text{EN}}$	Active-Low Enable Input. Drive $\overline{\text{EN}}$ low to enable the driver outputs. Drive $\overline{\text{EN}}$ high to three-state the driver outputs. The device is in shutdown when $\overline{\text{EN}}$ is high.
9	9	GND	Ground
11	11	M2	Motor Driver Output 2. See the <a href="#">MAX14870 Function Table</a> and <a href="#">MAX14872 Function Table</a> for more information.
—	—	EP	Exposed Pad. Connect to ground.

## MAX14870 Function Table

INPUTS				OUTPUTS		OPERATING MODE
$\overline{\text{EN}}$	$V_{\text{SNS}}$	PWM	DIR	M1	M2	
1	X	X	X	High impedance	High impedance	Shutdown
0	$< V_{\text{SNS\_TH}}$	0	X	GND	GND	Brake
0	$< V_{\text{SNS\_TH}}$	1	0	GND	$V_{\text{DD}}$	Counterclockwise/reverse
0	$< V_{\text{SNS\_TH}}$	1	1	$V_{\text{DD}}$	GND	Clockwise/forward
0	$> V_{\text{SNS\_TH}}$	1	0	Switching	Switching	Current regulation
0	$> V_{\text{SNS\_TH}}$	1	1	Switching	Switching	Current regulation

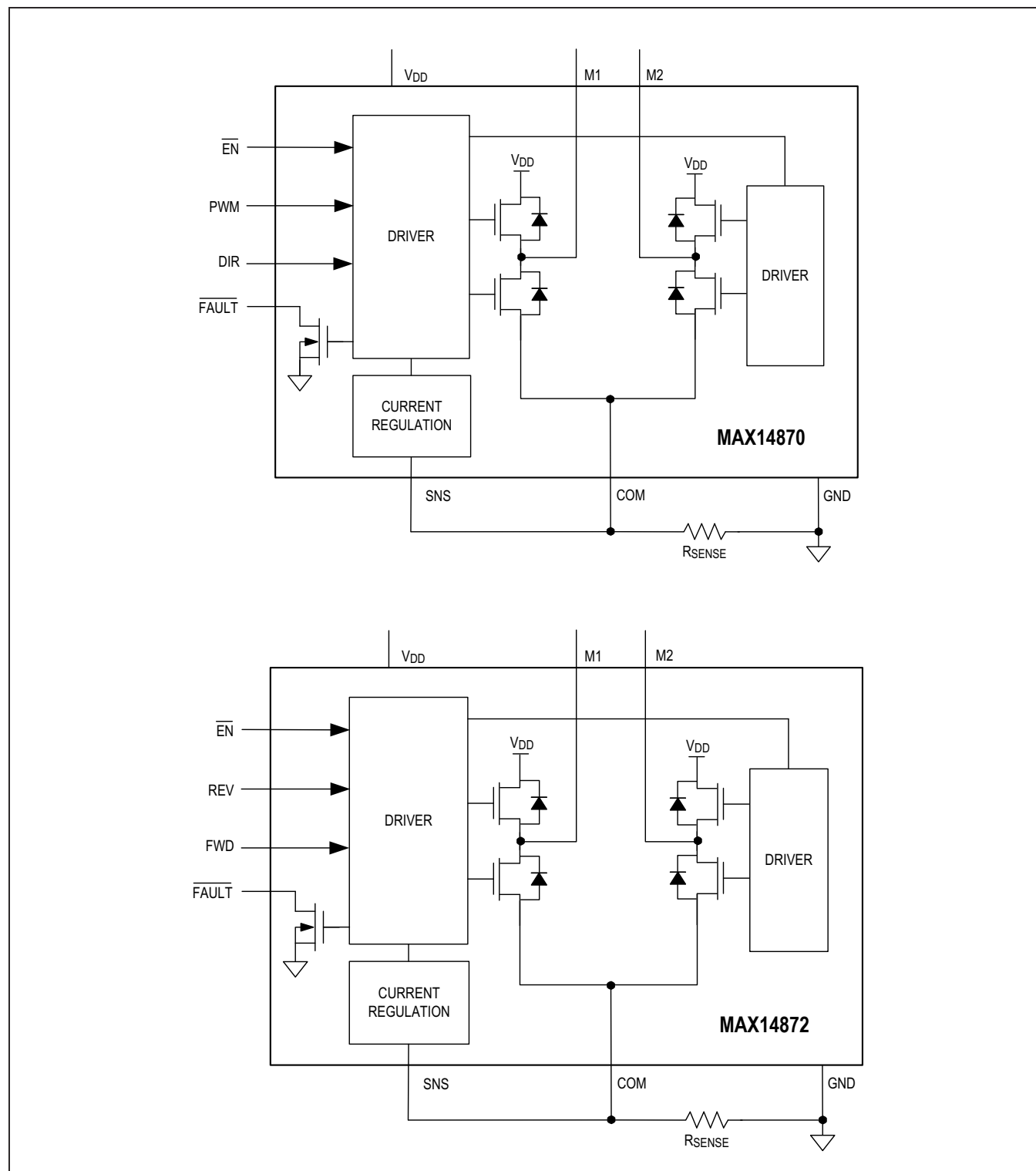
X = Don't care.

## MAX14872 Function Table

INPUTS				OUTPUTS		OPERATING MODE
$\overline{\text{EN}}$	$V_{\text{SNS}}$	FWD	REV	M1	M2	
1	X	X	X	High impedance	High impedance	Shutdown
0	$< V_{\text{SNS\_TH}}$	0	0	GND	GND	Brake
0	$< V_{\text{SNS\_TH}}$	1	0	$V_{\text{DD}}$	GND	Forward
0	$< V_{\text{SNS\_TH}}$	0	1	GND	$V_{\text{DD}}$	Reverse
0	$< V_{\text{SNS\_TH}}$	1	1	High impedance	High impedance	Three-state
0	$> V_{\text{SNS\_TH}}$	1	0	Switching	Switching	Current regulation
0	$> V_{\text{SNS\_TH}}$	0	1	Switching	Switching	Current regulation

X = Don't care.

## Functional Diagrams



## Detailed Description

The MAX14870/MAX14872 DC brushed motor drivers provide a low-power and flexible solution for driving and controlling brushed motors with voltages between 4.5V and 36V. Peak motor currents of up to 2.5A ensure large motor torque that is controllable by an external PWM signal and/or by autonomous internal current regulation.

The MAX14870 has PWM and direction-control inputs, while the MAX14872 has forward and reverse inputs for direction control. See the [MAX14870 Function Table](#) and [MAX14872 Function Table](#).

Charge-pump-less design requires minimal external components and low supply current.

Integrated current regulation allows limiting peak start-up motor currents. Shoot-through protection with a 140ns (typ) dead time ensures low operating current. Internal free-wheeling diodes absorb inductive motor currents. The  $\overline{\text{FAULT}}$  output signals thermal overload and overcurrents.

## Overcurrent Protection

The MAX14870/MAX14872 are protected against shorts on M1/M2 to any voltage between  $V_{DD}$  and GND, including shorts to GND,  $V_{DD}$ , and between M1 and M2 via overcurrent limiting. When a current above 6A (typ) flows through M1 or M2 for longer than 1 $\mu$ s, an overcurrent condition is detected and the H-bridge drivers are automatically disabled and the  $\overline{\text{FAULT}}$  output asserts.

If the overcurrent condition continues for longer than the overcurrent autoretry timeout (2ms (typ)) the MAX14870/MAX14872 enters autoretry mode. In autoretry mode, the M1 and M2 outputs are re-enabled for 1 $\mu$ s (typ) and  $\overline{\text{FAULT}}$  goes high-impedance. The drivers are disabled again and  $\overline{\text{FAULT}}$  is re-asserted if the overcurrent condition persists.

## PWM Control (MAX14870 Only)

The PWM input is used for motor speed/torque control. Increasing or decreasing the duty cycle at PWM sets the effective (average) voltage across the motor terminals and allows first-order speed control.

When PWM is logic-high, the motor is driven in the direction defined by DIR. When PWM is logic-low, the bridge is in brake mode. In brake mode, the motor current

continues flowing and recirculates through the low-side transistors of the H-bridge driver, due to its inductive impedance and back EMF.

## FWD/REV Control (MAX14872 only)

The FWD input is used to drive the motor forward/turn a relay on. The REV input reverses the M1 and M2 polarity, to drive the motor in reverse/turn a relay off.

FWD/REV control can be optionally used to implement either bipolar motor control (with both M1 and M2 switching) or unipolar control, where only M1 or M2 switches.

## Slope Control

The MAX14871 drivers turn-on and turn-off with active slope-control during the M1/M2 transition times. The integrated slew rate-limiting reduces EMC (like conducted and radiated EMI) associated with high di/dt rates.

## Thermal Shutdown

The MAX14870/MAX14872 include integrated protection against thermal overload. When the junction temperature exceeds 160°C (typ), the H-bridge is three-stated, M1 and M2 are disabled, and  $\overline{\text{FAULT}}$  is asserted.

If the motor was spinning before thermal shutdown occurred, the motor's inductance will push current through the internal M1 and M2 diodes, forcing the motor into fast decay, with a voltage across its terminals of  $V_{DD}$ .

M1 and M2 are automatically reenabled when the junction temperature falls to 150°C (typ).

## Current Sensing

Connect a sense resistor ( $R_{\text{SENSE}}$ ) between COM and GND to monitor the motor current during operation. Select  $R_{\text{SENSE}}$  such that the voltage at COM created by motor current flowing through the sense resistor is limited to within 250mV relative to GND ( $-250\text{mV} \leq V_{\text{COM}} \leq +250\text{mV}$ ).

Minimize series trace resistance from  $R_{\text{SENSE}}$  to GND to minimize voltage sense errors due to parasitic trace interconnect resistance. Use a star ground connection between the MAX14870/MAX14872 GND pins and the GND-side of  $R_{\text{SENSE}}$ . Connect the voltage sense close to the  $R_{\text{SENSE}}$  resistor and/or use differential voltage sensing. See [Figure 4](#).

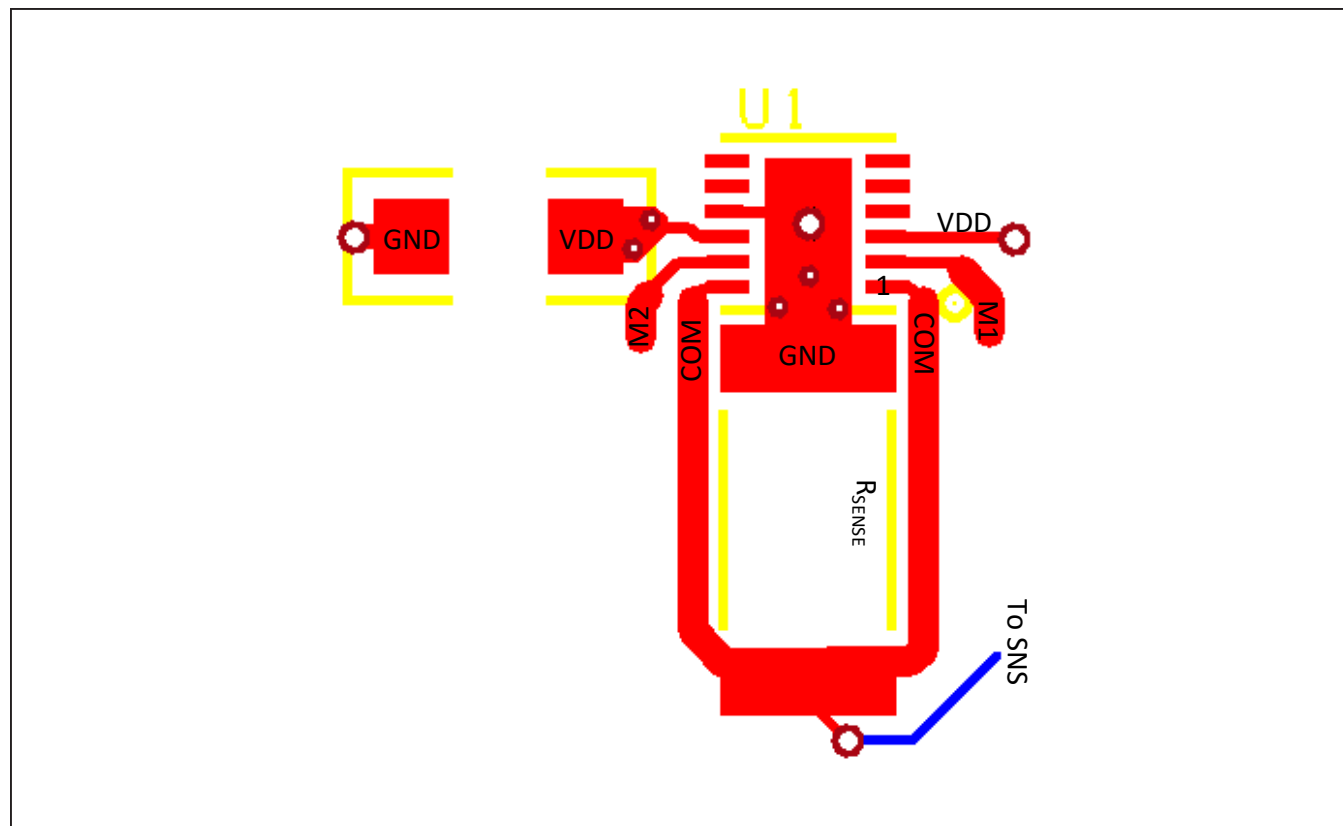


Figure 4. Layout Example for Accurate Current Sensing

## Current Regulation

The MAX14870/MAX14872 features internal current regulation to limit the startup current. Regulation is set when the motor current ( $I_M$ ) exceeds the current limit defined by the sense resistor ( $R_{SENSE}$ ):

$$I_{M \text{ MAX}} = 0.1V/R_{\text{SENSE}}$$

When the motor current exceeds the maximum threshold, the H-bridge drive is reversed for fast decay for a fixed time ( $t_{OFF} = 15\mu s$ ). The H-bridge is turned back to normal operation after  $t_{OFF}$ .

## Fast Decay Mode

When the motor current exceeds the set threshold, the H-bridge polarity is reversed during the 15 $\mu$ s (typ) t<sub>OFF</sub> period. This results in faster motor current decay since -V<sub>DD</sub> is applied across the motor's terminals. The motor current decrease is first order with an L/R time constant and proportional to (V<sub>DD</sub> + V<sub>EMF</sub>).

Note that if  $t_{OFF}$  is larger than the motor's L/R electrical time constant, the motor current can reverse direction, causing the motor to not start.

During fast decay, the motor's inductive current recirculates through the external  $V_{DD}$  supply, which charges up the  $V_{DD}$  bypass capacitor. Therefore, the voltage seen across  $R_{SENSE}$  is negative during the  $t_{OFF}$  delay.

## Applications Information

## Layout Considerations

Connect duplicate pins (COM pins and V<sub>DD</sub> pins) together with low-resistance traces. See the [Current Sensing](#) section for further layout recommendations.

## Power Considerations

The MAX14870/MAX14872 driver can generate more power than the package for the device can safely dissipate. Total power dissipation for the device is calculated using the following equation:

$$P_{TOTAL} = P_{DRIVER} + P_{SW} + P_D$$

The power dissipated inside of the driver is calculated as:

$$P_{\text{DRIVER}} = I_M^2 \times R_{\text{ON}}$$

where  $I_M$  is the motor current and  $R_{ON}$  is the on-resistance of the high and low-side FETs.

$P_{SW}$  is the power generated by the driver during the rise/fall times in switching and includes both arms of the bridge. Calculate  $P_{SW}$  using the following equation:

$$P_{SW} = I_M \times 2 \times V_{DS} \\ = I_M \times 2 \times (1/2 \times V_{DD} \times f_{SW} \times t_R)$$

where  $I_M$  is the motor current,  $t_R$  is the 200ns (typ) rise or fall time of the driver output, and  $f_{SW}$  is the switching frequency.

The internal diodes dissipate power during switching, as well. Calculate the power dissipated in the diodes as:

$$P_D = I_M \times 2 \times V_{BF} \times t_{DEAD} \times f_{SW}$$

### Operation Without Current Regulation

To operate the MAX14870/MAX14872 without internal or external current regulation, connect SNS directly to GND. No sense resistor is required for this configuration.

### Operation with External Current Regulation

The motor current can be controlled by external PWM regulation using sense resistor feedback in a control loop. To disable the internal current regulation circuitry of the MAX14870/MAX14872 and use external regulation, connect SNS directly to ground.

Note that, if fast decay control is used, the COM voltage pulses negatively when the H-bridge direction is inverted.

### Use of External Capacitors

Maxim does not recommend using external capacitors across the motor terminals. Added capacitance between H-bridge outputs increases the power dissipated in the H-bridge by:

$$P_D = V_{DD}^2 \times C \times f_{SW}$$

where  $C$  is the capacitance across M1/M2 and  $f_{SW}$  is the M1/M2 switching frequency. This power is dissipated without good reason.

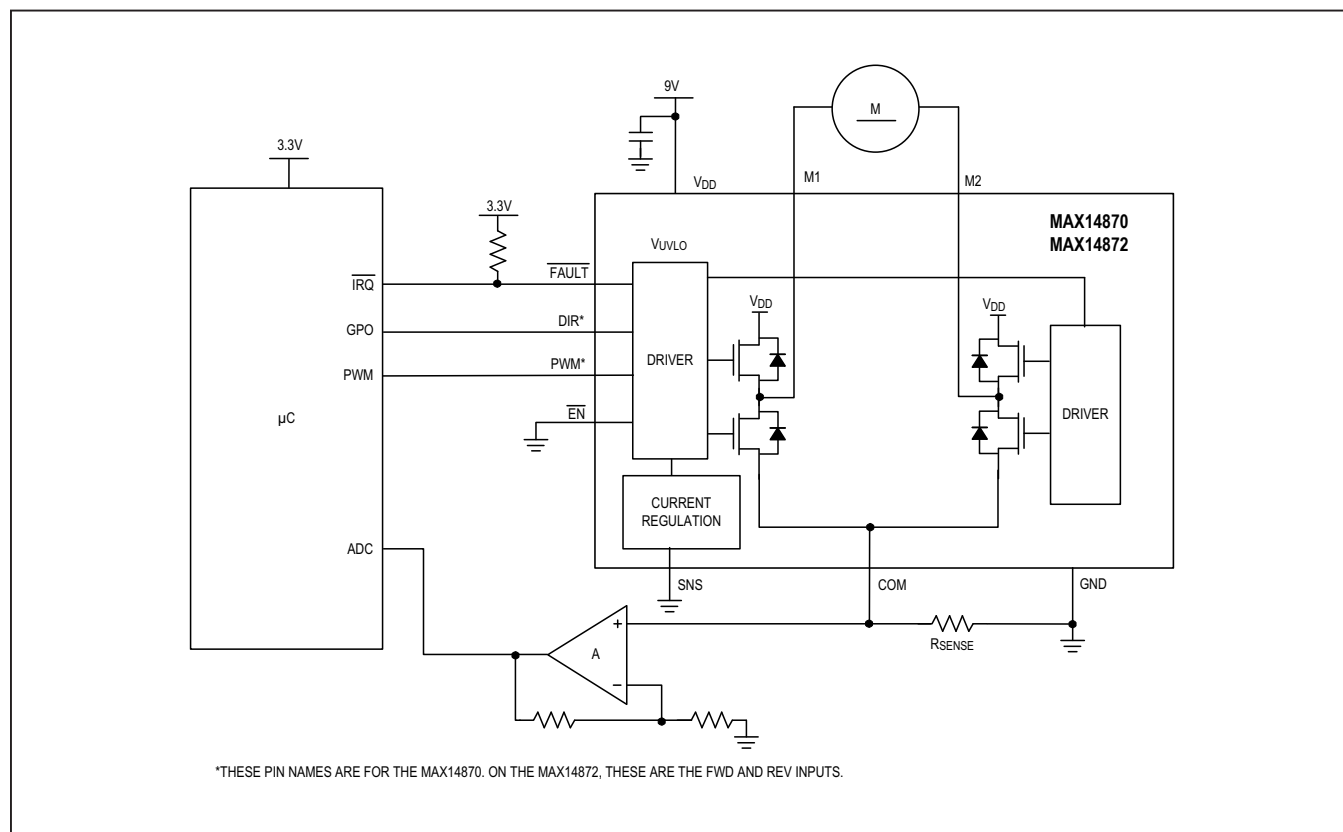


Figure 5. Operation with External Current Regulation

## Ordering Information

PART	TEMP RANGE	PIN-PACKAGE
MAX14870ETC+	-40°C to +85°C	12 TDFN-EP
MAX14872ETC+	-40°C to +85°C	12 TDFN-EP

+Denotes a lead(Pb)-free/RoHS-compliant package.

\*EP = Exposed pad.

## Package Information

For the latest package outline information and land patterns (footprints), go to [www.maximintegrated.com/packages](http://www.maximintegrated.com/packages). Note that a "+", "#", or "-" in the package code indicates RoHS status only. Package drawings may show a different suffix character, but the drawing pertains to the package regardless of RoHS status.

PACKAGE TYPE	PACKAGE CODE	OUTLINE NO.	LAND PATTERN NO.
12 TDFN-EP	TD1233+1	<a href="#">21-0664</a>	<a href="#">90-0397</a>

## Chip Information

PROCESS: BiCMOS

## Revision History

REVISION NUMBER	REVISION DATE	DESCRIPTION	PAGES CHANGED
0	9/14	Initial release	—
1	6/17	Modified Figure 4, deleted TOC 10, and edited Pin Description table	7, 9, 12

For pricing, delivery, and ordering information, please contact Maxim Direct at 1-888-629-4642, or visit Maxim Integrated's website at [www.maximintegrated.com](http://www.maximintegrated.com).

*Maxim Integrated cannot assume responsibility for use of any circuitry other than circuitry entirely embodied in a Maxim Integrated product. No circuit patent licenses are implied. Maxim Integrated reserves the right to change the circuitry and specifications without notice at any time. The parametric values (min and max limits) shown in the Electrical Characteristics table are guaranteed. Other parametric values quoted in this data sheet are provided for guidance.*