

# **ECE 441**

# **Smart & Connected Embedded Systems**

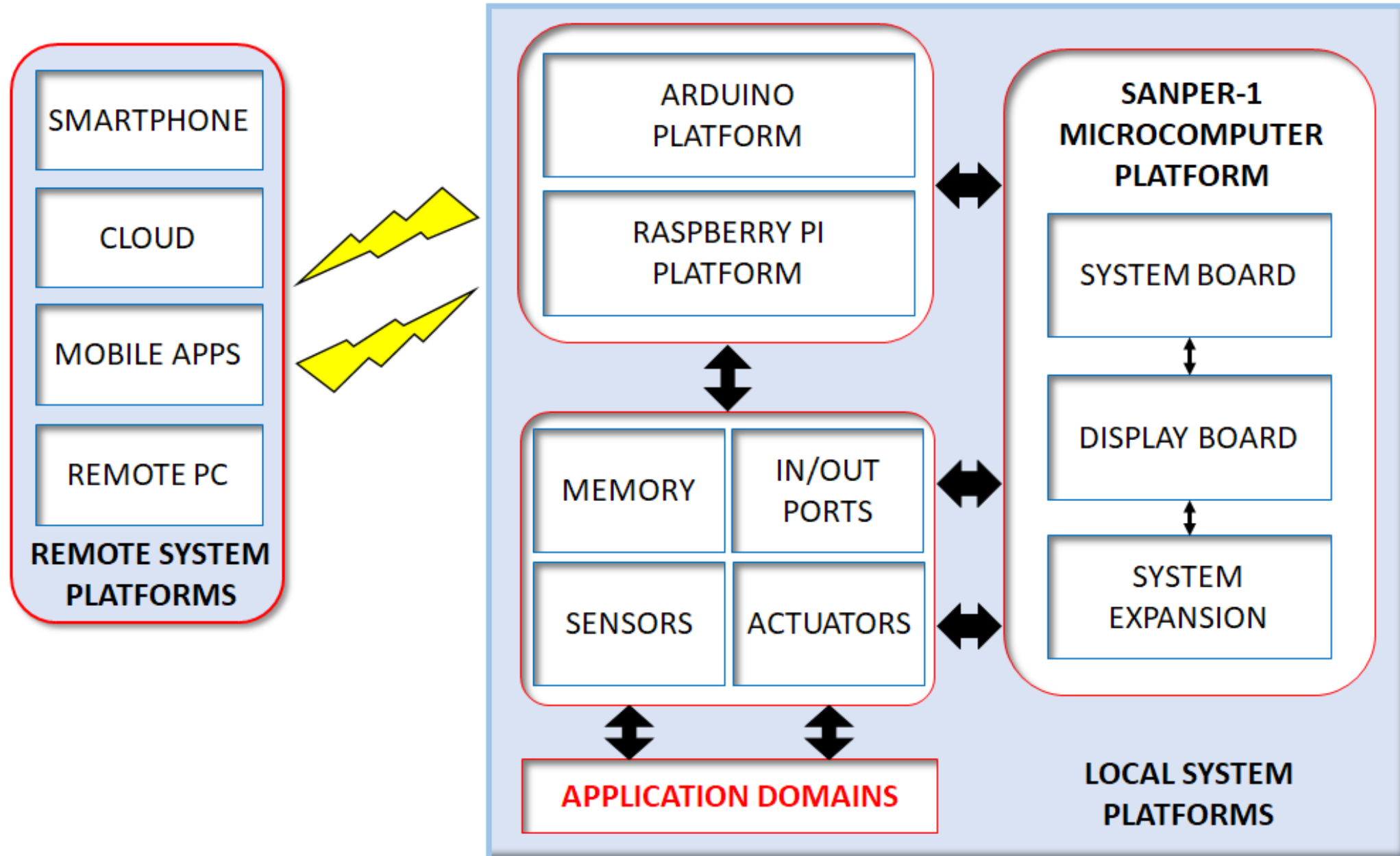
**Instructor:** Professor Jafar Saniie

**Teaching Assistants:** Xinrui Yu, Xin Huang, and Mikhail Gormov

# Wide Range of Projects

- Multiple computing platform architectures for smart and connected system applications can be used.
- The goal is to develop smart and connected systems.
- Examples for the design project is shown later in this presentation.

## ECE 441 – MAJOR DESIGN PROJECT: SMART AND CONNECTED SYSTEM ARCHITECTURE



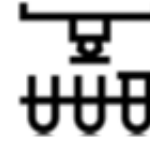
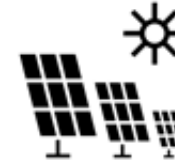
# APPLICATION DOMAINS



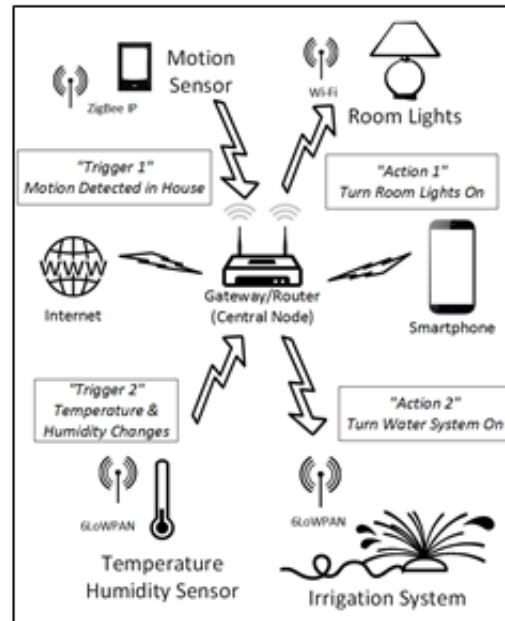
**Agriculture Automation**



**Energy Management**



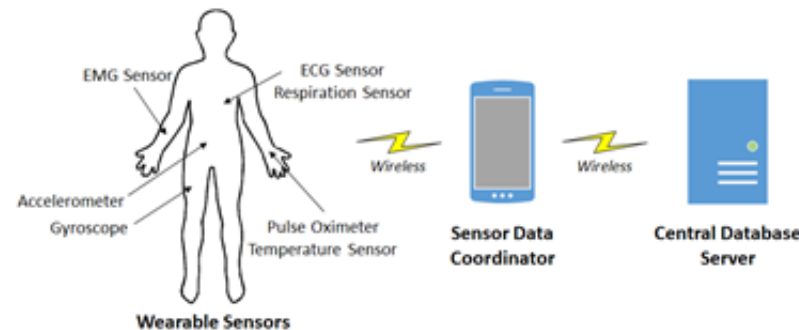
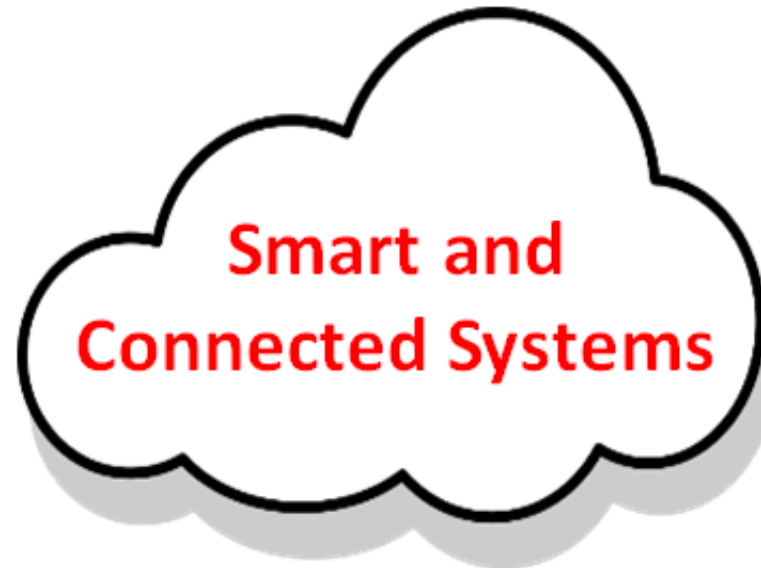
**Factory Automation**



**Home Automation**



**Smart Security**



**Remote Healthcare System**



**Building Management**



**Smart Transportation**



**Daily Activity Things**

# What is SANPER?

- The SANPER-1 Microcomputer Platform was designed and developed by Dr. Jafar Saniie and Mr. Stephen Perich.
- The platform includes a firmware package named “TUTOR” which is a MC68000 resident monitor program developed by Motorola, Inc.
- The platform could be used along with an external power supply and a video display terminal to construct an educational development system for the design project.





**SANPER-1 in the Lab**

# Basic Access to SANPER

- The SANPER is connected to the lab PC via a RS-232 DB25 to DB9 cable and a RS-232 DB9 to USB cable.
- The lab PC runs SecureCRT (a terminal emulator) to communicate with SANPER.



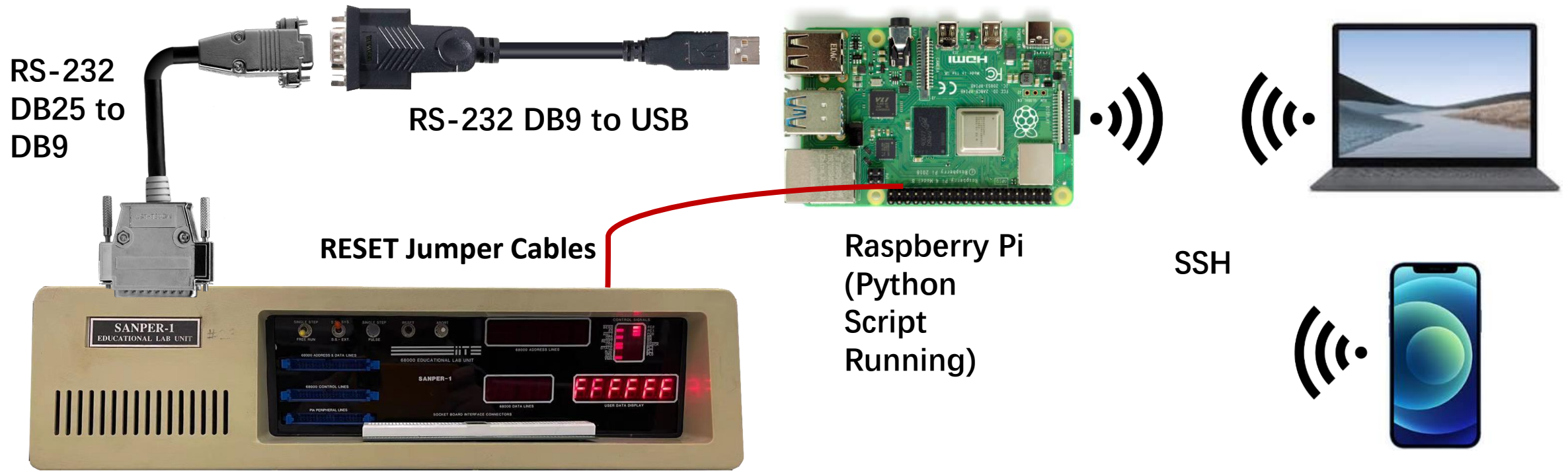
# Remote Access to SANPER

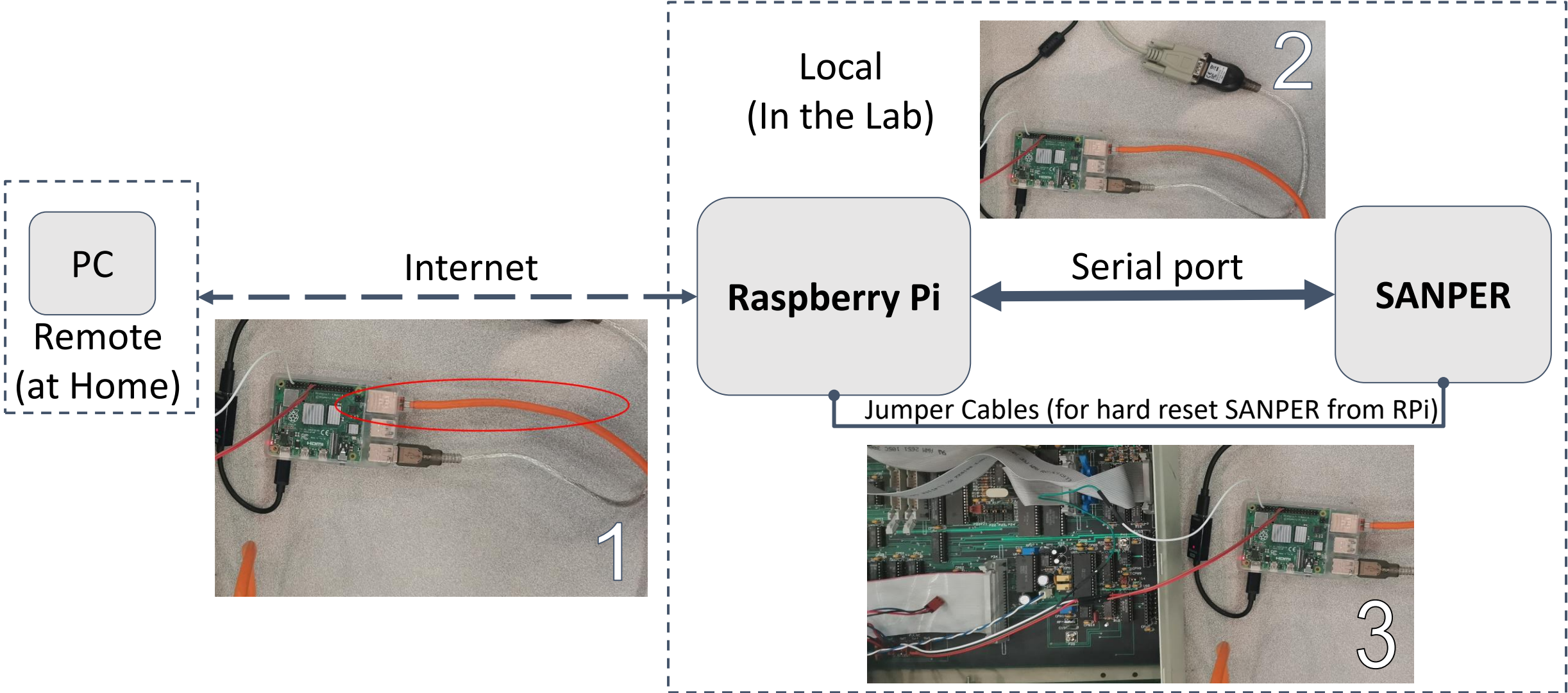
- Uses Raspberry Pi as a terminal to access SANPER remotely
- Access SANPER in a way like using SecureCRT on lab PCs
- Hardware RESET available without physically pressing the button
- Access SANPER remotely using PCs and smartphones
- **Hardware:**
  - Raspberry Pi
  - RS-232 DB25 to DB9 cable
  - RS-232 DB9 to USB cable
  - Jumper cables



# Access SANPER Remotely using Raspberry Pi

- The SANPER is connected to the Raspberry Pi with the same configuration.
- The Raspberry Pi runs a custom-built Python Script to communicate with SANPER.
- The Raspberry Pi can then communicate with other PCs and smartphones over the internet with SSH (Secure Shell, a cryptographic network protocol).



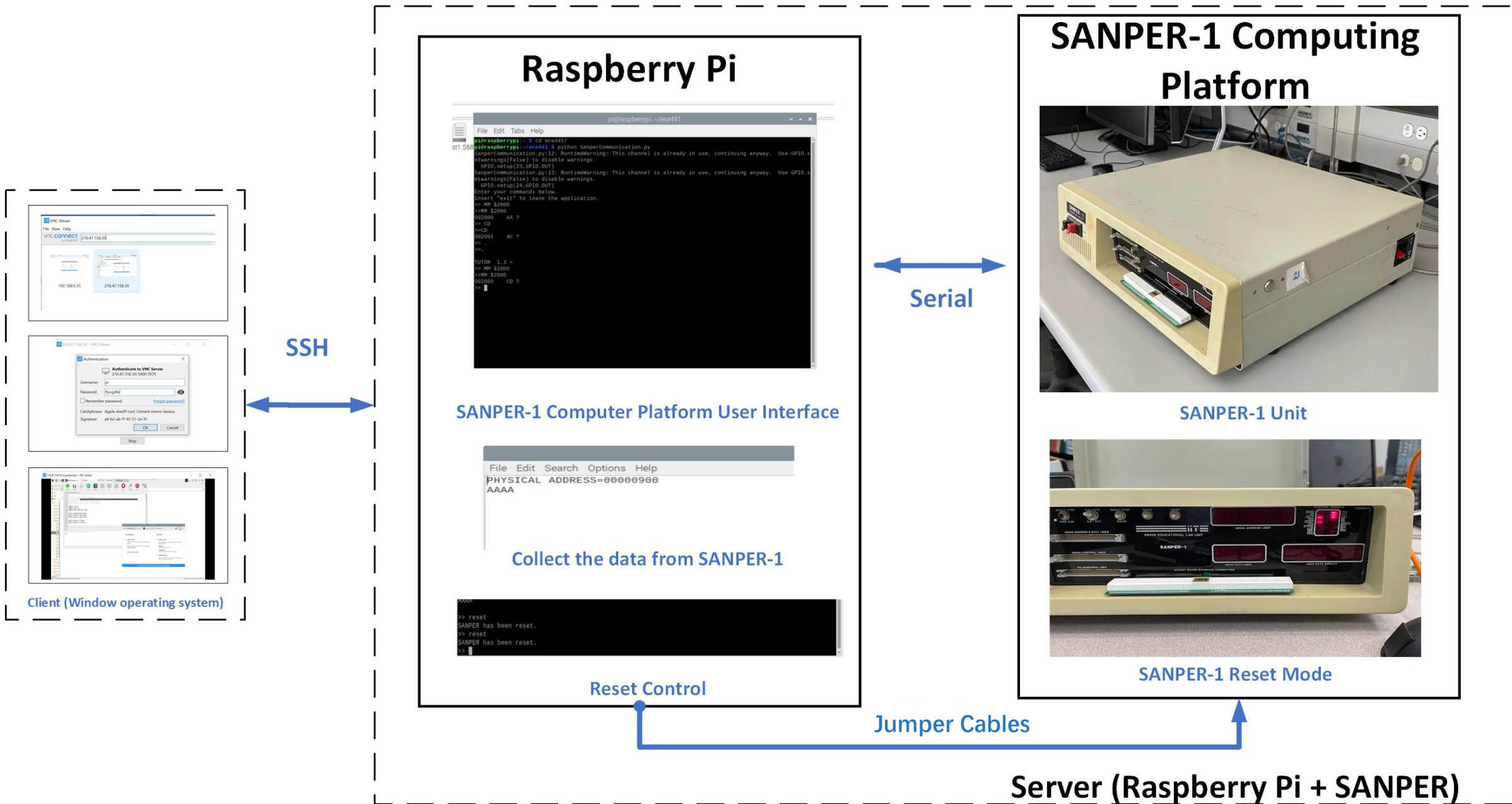


- The Raspberry Pi connects to the Internet through the orange ethernet cable
- The silver cable is the serial port connection between SANPER-1 and Raspberry Pi
- Three jumper cables connect the RESET input of the SANPER-1 and three GPIO ports on the Raspberry Pi for remote hard reset of the SANPER-1.

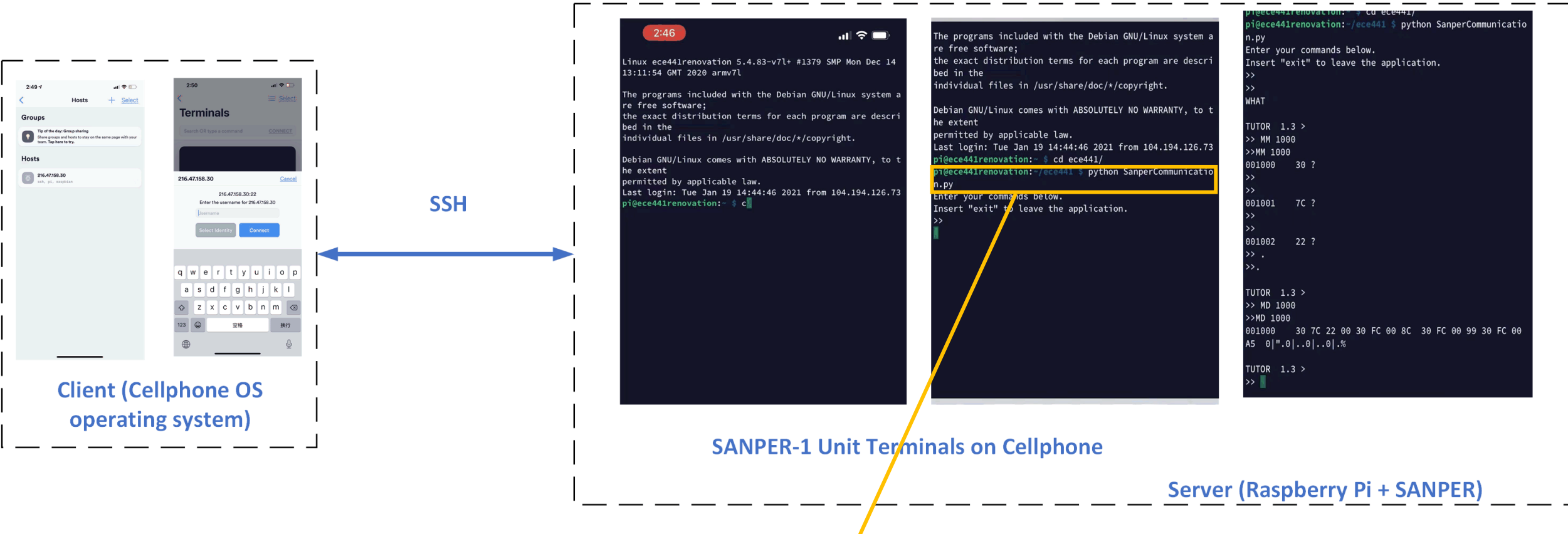




# Visualization Interface of Remote Access to SANPER



# Remote Access to SANPER using Smartphone



The Python script to communicate with SANPER is called SanperCommuniacion.py



2:46



bed in the  
individual files in /usr/share/doc/\*/copyright.

Debian GNU/Linux comes with ABSOLUTELY NO WARRANTY, to the extent  
permitted by applicable law.

Last login: Tue Jan 19 14:44:46 2021 from 104.194.126.73

pi@ece441renovation:~\$ cd ece441/

pi@ece441renovation:~/ece441\$ python SanperCommunication.py

Enter your commands below.

Insert "exit" to leave the application.

>>

>>

MMAT

TUTOR 1.3 >

>> MM 1000

>>MM 1000

001000 30 ?

>>

>>

001001 7C ?

>>

>>

001002 22 ?

>> .

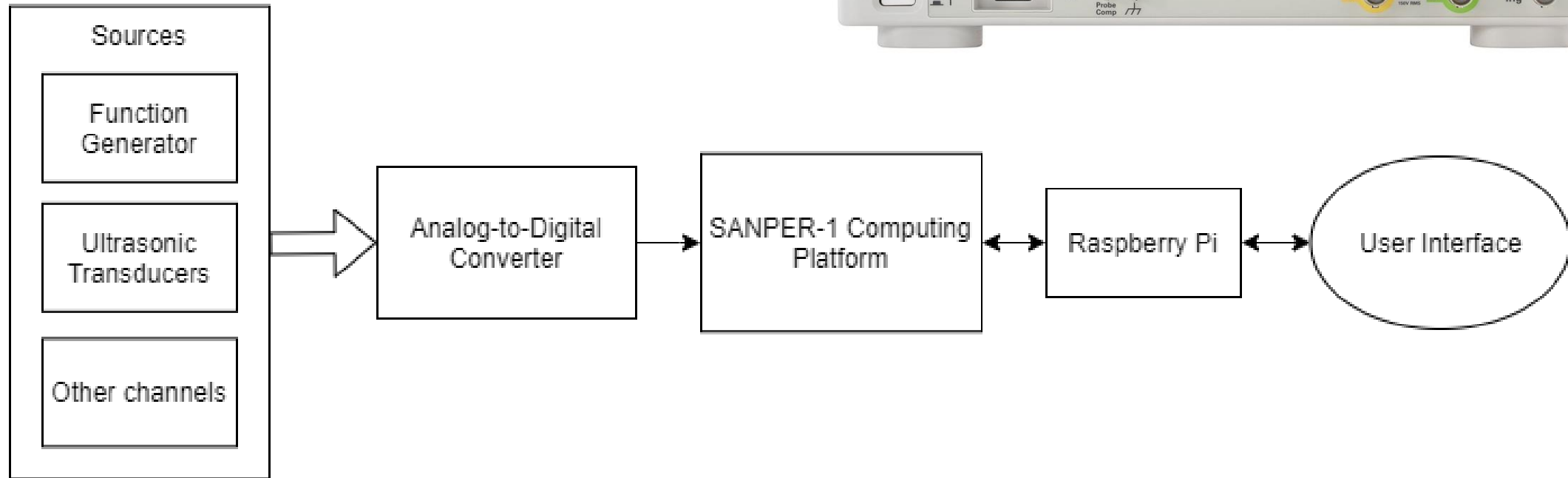
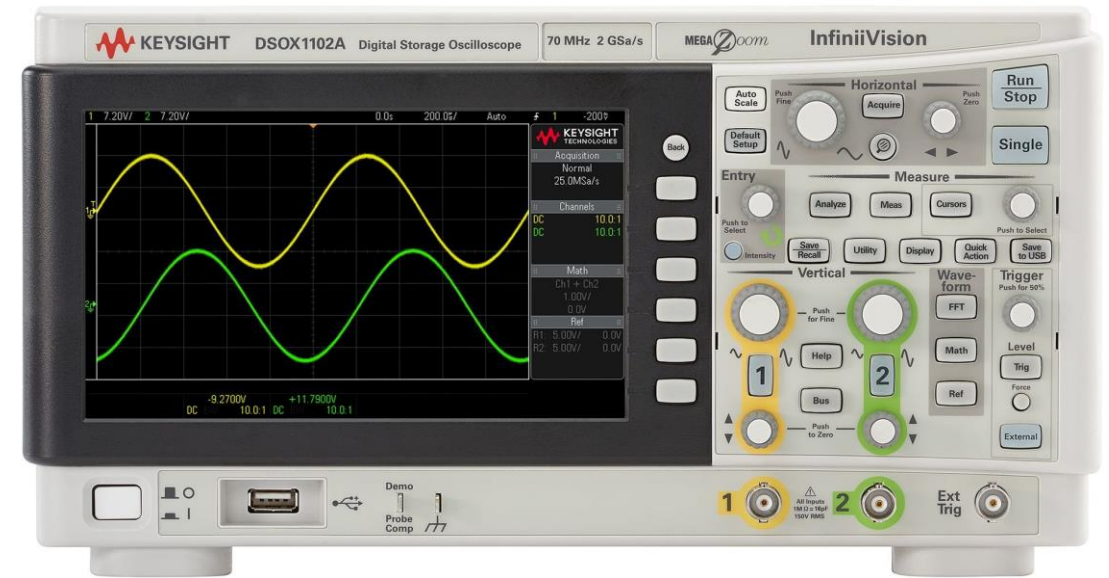
>>.

TUTOR 1.3 >

>> MD 1000



# Digital Oscilloscope



# Digital Oscilloscope

- This project is an oscilloscope that can pick up and display analog signals.
- A/D conversion is needed for interfacing with the signal inputs such as function generator or other analog signal sources.
- SANPER-1 Computing Platform transfer the sampled digital signals to the Raspberry Pi.
- **Hardware:**
  - **A/D Converter**
  - **Function Generator**

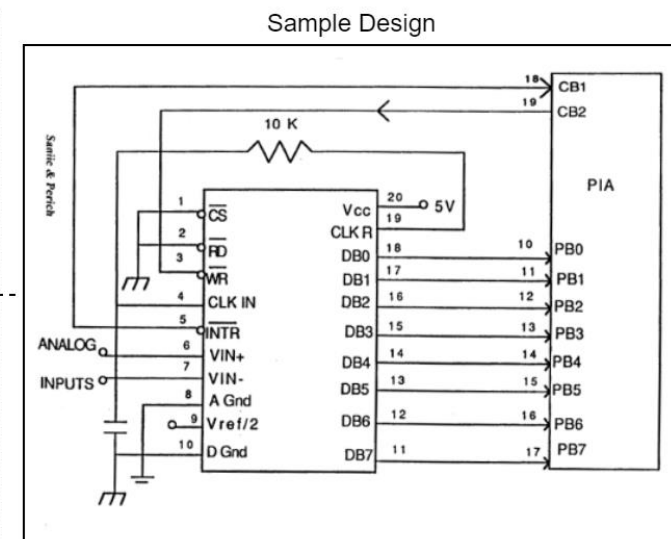
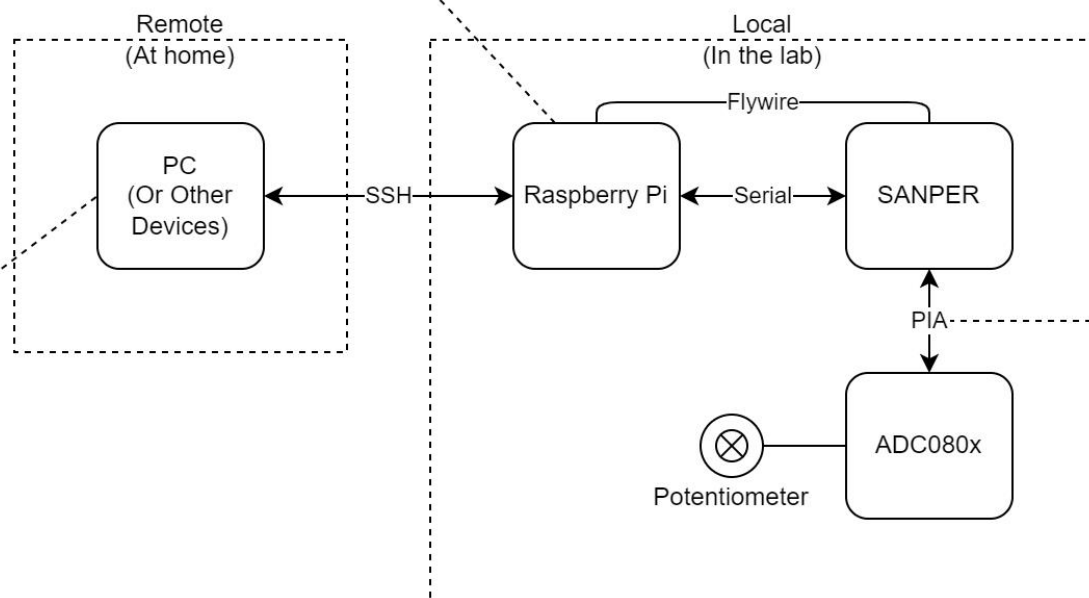
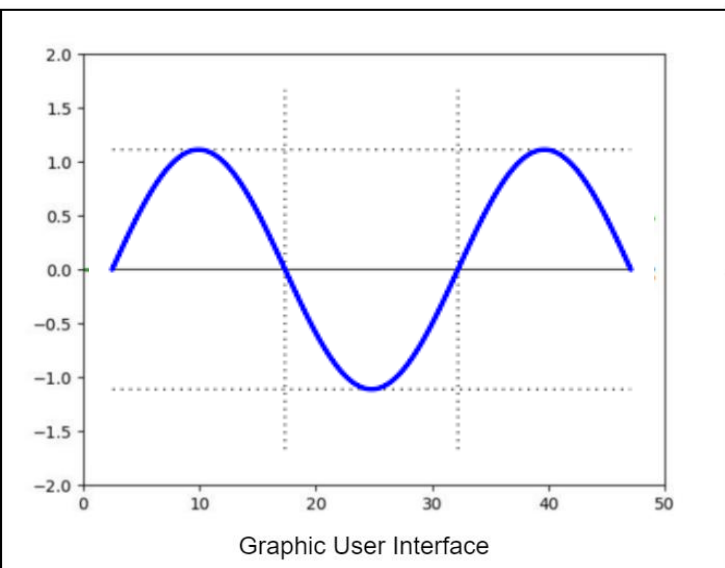
# Python Script for Serial Communication, data decoding and SSH connection

```

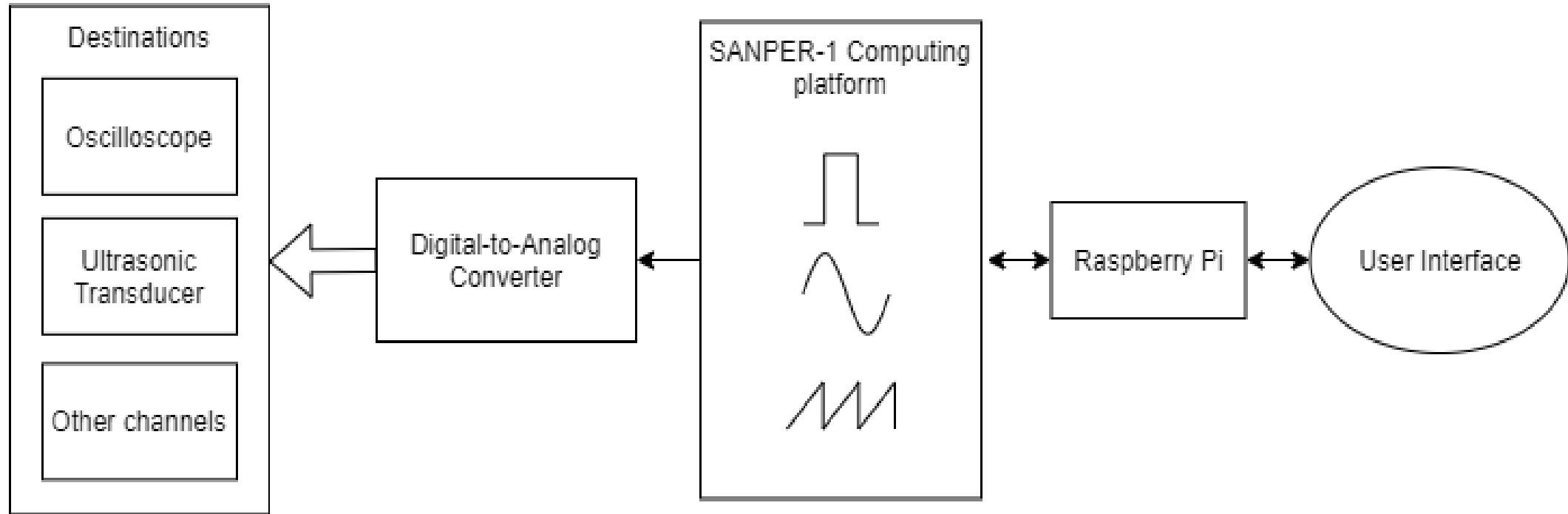
pi@raspberrypi: ~/ece441/
File Edit Tabs Help
pi@raspberrypi:~/ece441/ $ cd ece441/
pi@raspberrypi:~/ece441/ $ python SanperCommunication.py
SanperCommunication.py:12: RuntimeWarning: This channel is already in use, continuing anyway. Use GPIO.setwarnings(False) to disable warnings.
  GPIO.setup(23,GPIO.OUT)
SanperCommunication.py:13: RuntimeWarning: This channel is already in use, continuing anyway. Use GPIO.setwarnings(False) to disable warnings.
  GPIO.setup(24,GPIO.OUT)
Enter your commands below.
Insert "exit" to leave the application.
>> MM $2000
>>MM $2000
002000 AA ?
>> CD
>>CD
002001 4C ?
>> .
>>.
>>.
TUTOR 1.3 >
>> MM $2000
>>MM $2000
002000 CD ?
>>

```

2020-12-03 15:08:41:	Ax : -16	Ay : -19	Az 252
2020-12-03 15:08:42:	Ax : 61	Ay : 32	Az 255
2020-12-03 15:08:42:	Ax : 7	Ay : 185	Az 222
2020-12-03 15:08:43:	Ax : 14	Ay : 253	Az 133
2020-12-03 15:08:43:	Ax : 45	Ay : 121	Az 174
2020-12-03 15:08:44:	Ax : 24	Ay : -38	Az 274



# Function Generator



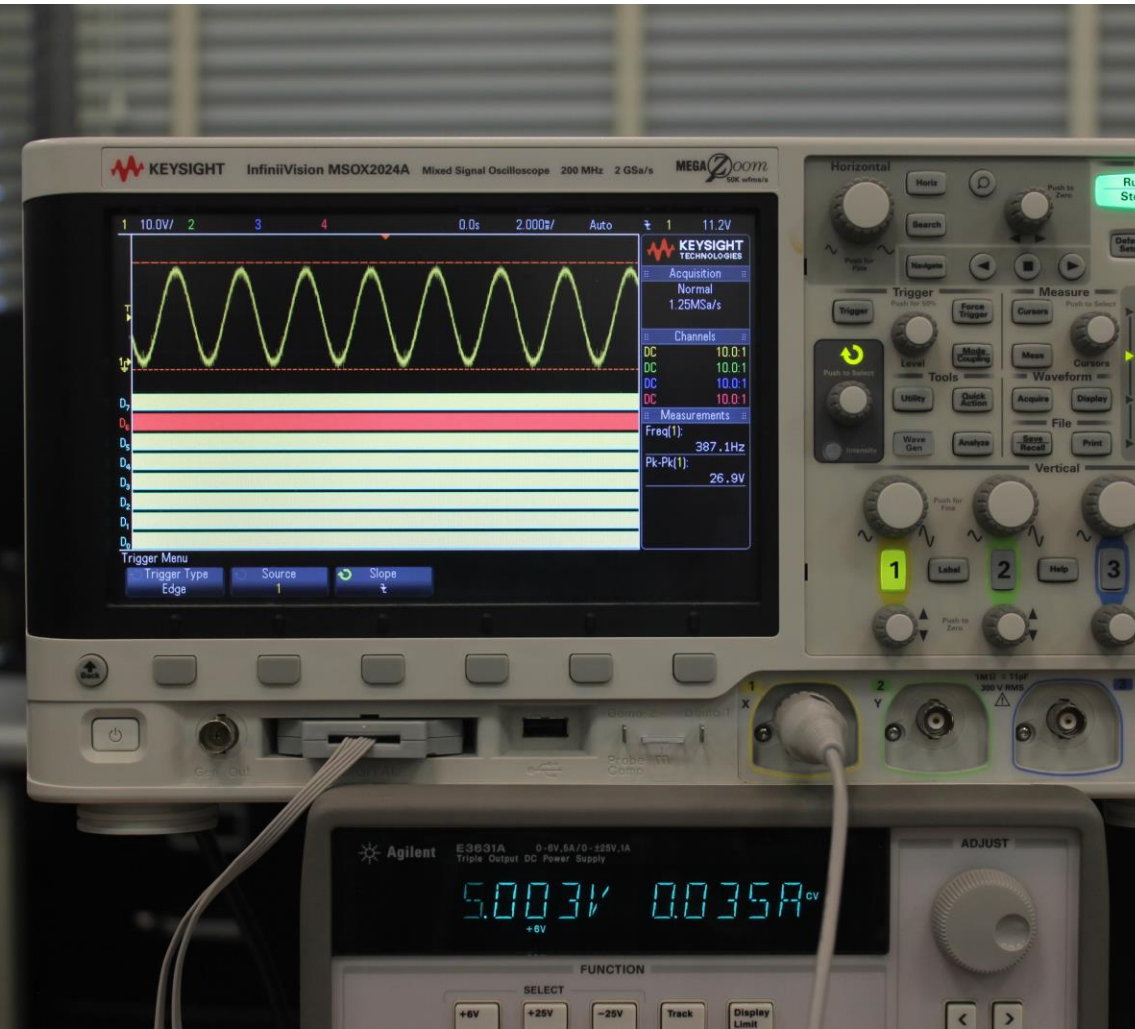
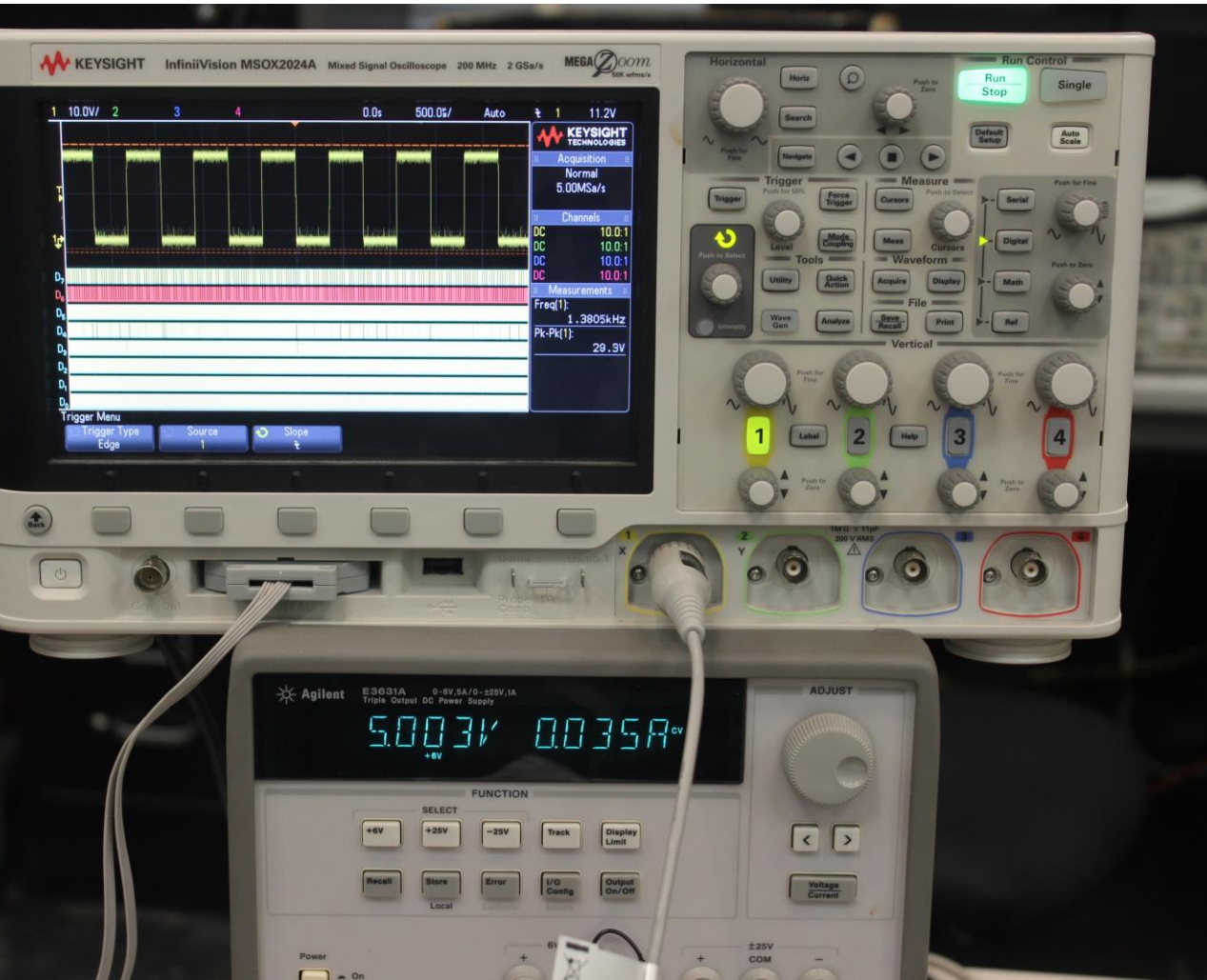


# Function Generator

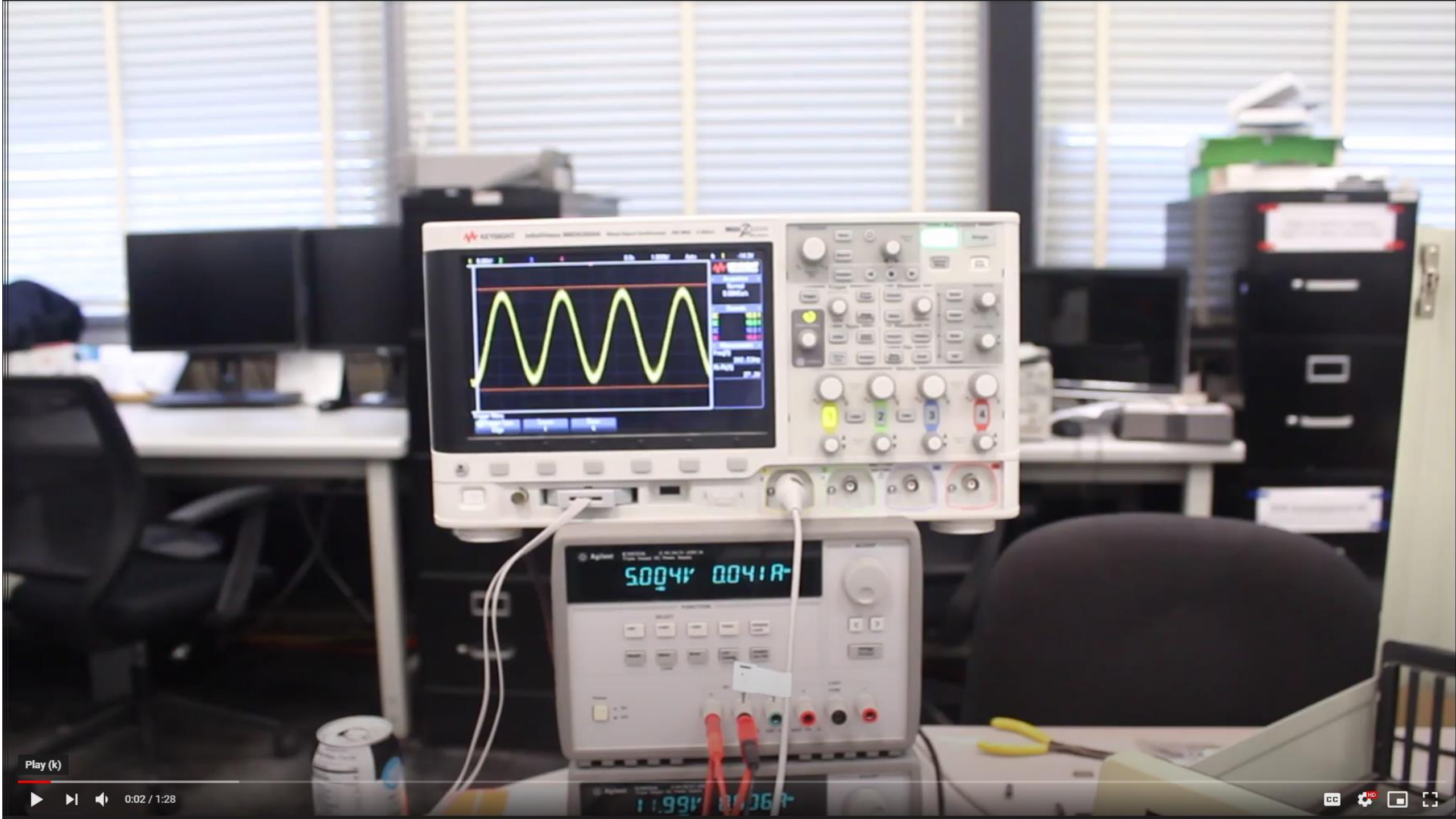


- This project is a function generator based on the SANPER-1 Computing Platform.
- User interfaces are available for the transmitter.
- SANPER-1 provides the essential modulation and demodulation processes.
- A/D conversion and D/A conversion are needed for interfacing with the channels through the transducers.
- **Hardware:**
  - A/D Converter
  - D/A Converter
  - Oscilloscope

# Function Generator Results







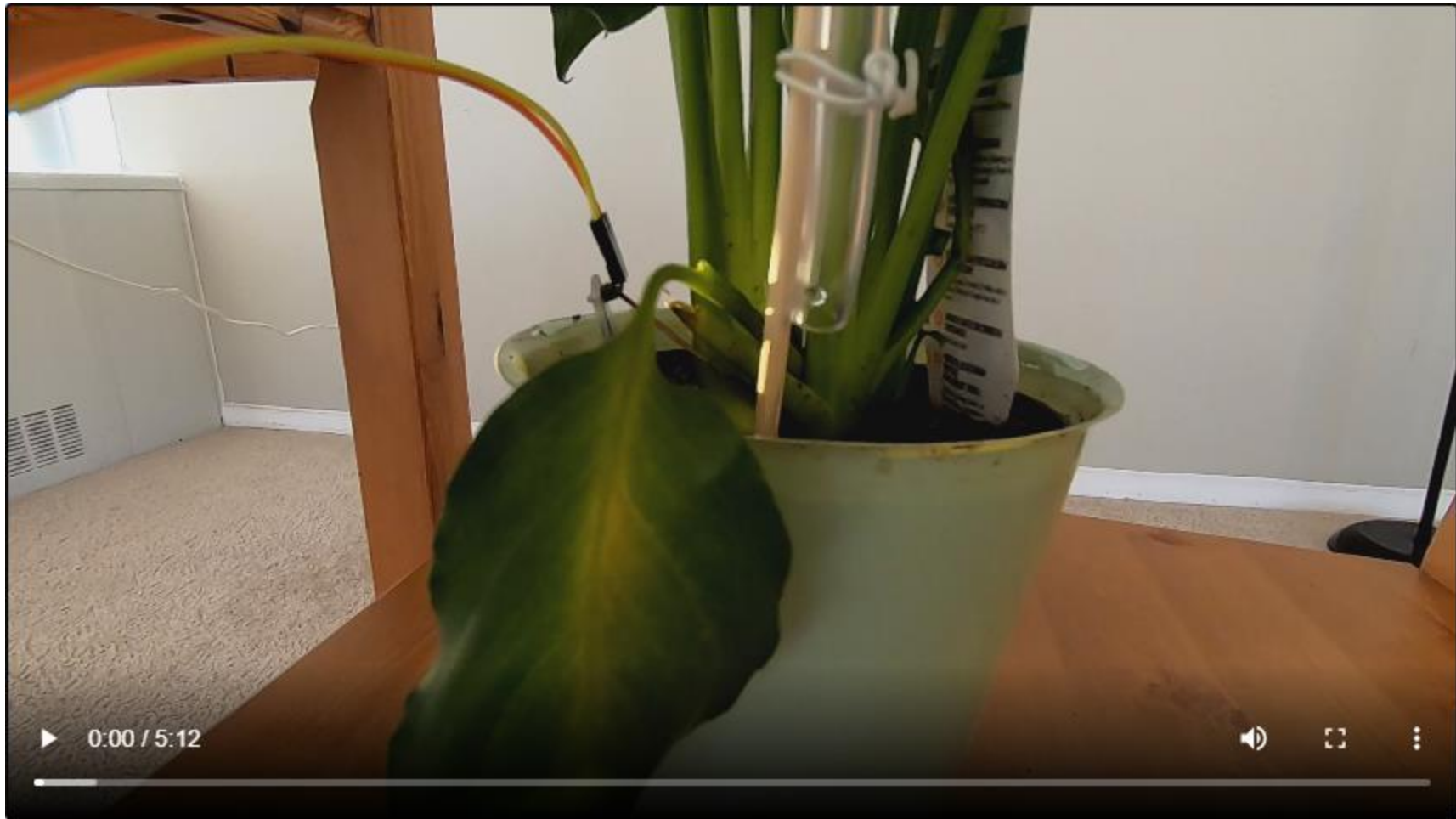
Play (k)

0:02 / 1:28

CC HD

# Smart Irrigation System

- A smart irrigation system should continuously monitor the amount of water, determine if watering is required for the plants, supply the exact or approximate amount of water required for the plants, and lastly discontinue the water supply when the required amount has been delivered to the plants.
- It can be said that plant monitoring system is a part of smart irrigation. This project focuses on monitoring soil moisture, as well as temperature, humidity, and light intensity.





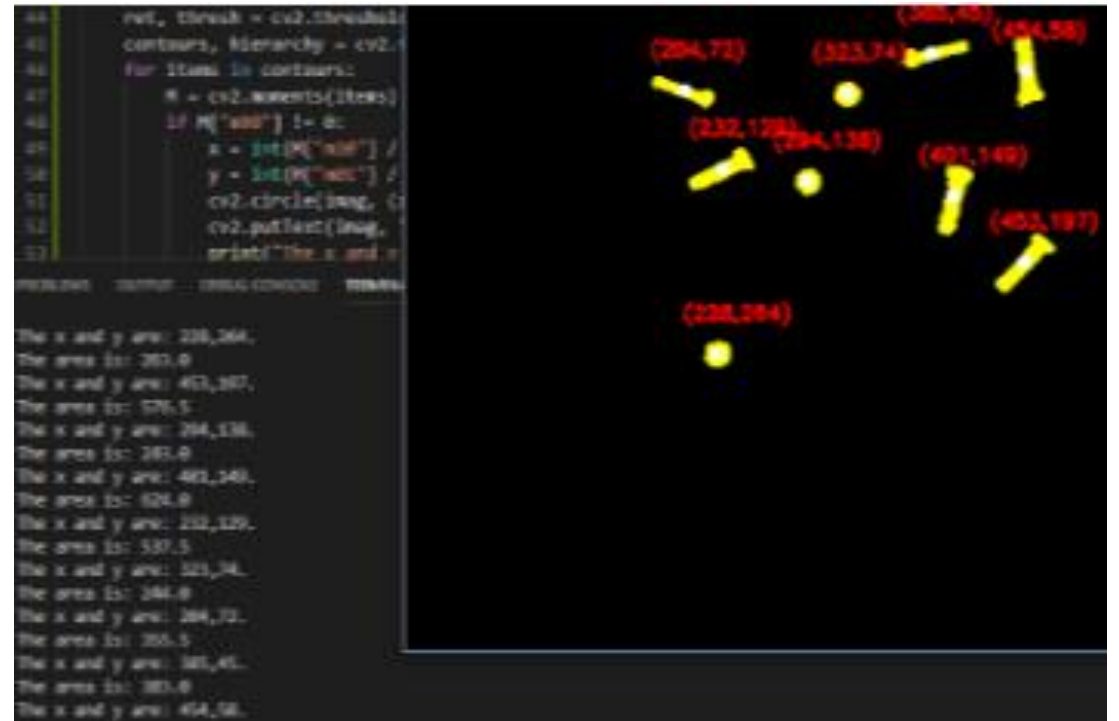
# Computer Vision Based Autonomous Robotic Arm

- The robotic arm will be used to identify, sort, and interact with objects within its reach.
- The objects that the robot will interact with will be different color nuts and bolts.
- A menu allows for the user to control the robot's speed, where it wants to go, what it should pick up, and even reverting an action.
- The red numbers on the picture marks the 8 motors that facilitate the move of the arm.



# Computer Vision Based Autonomous Robotic Arm

- The image is filtered, segmented and goes through an object recognition algorithm.



# Computer Vision Based Autonomous Robotic Arm Demo

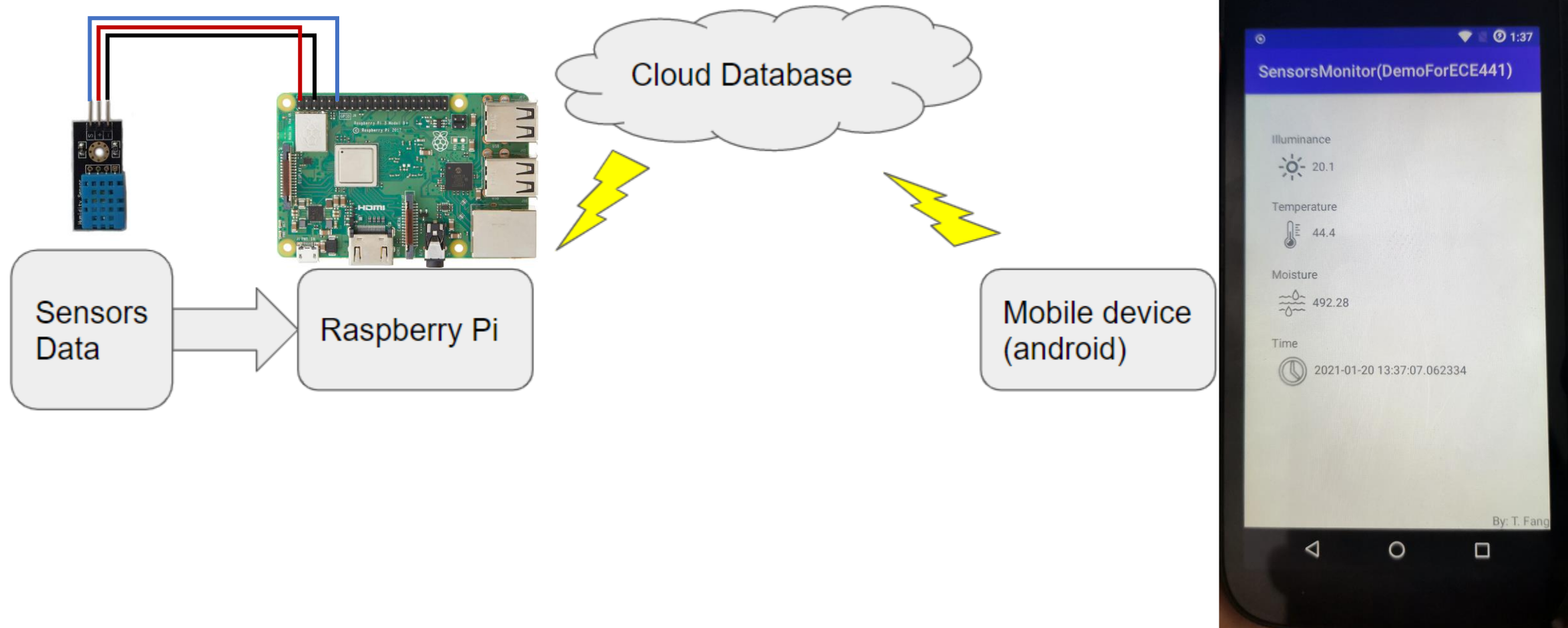


Embedded Computing and Signal Processing Research Laboratory  
Department of Electrical and Computer Engineering

# Smartphone Application for Sensor Monitoring

- Sensor's data is acquired either from SANPER-1 or directly from sensors connected to the Raspberry Pi
- A python script runs on the Raspberry Pi uploads the data to the cloud every two seconds
- The android cell phone will update the displayed sensors data once there are changes to the cloud database

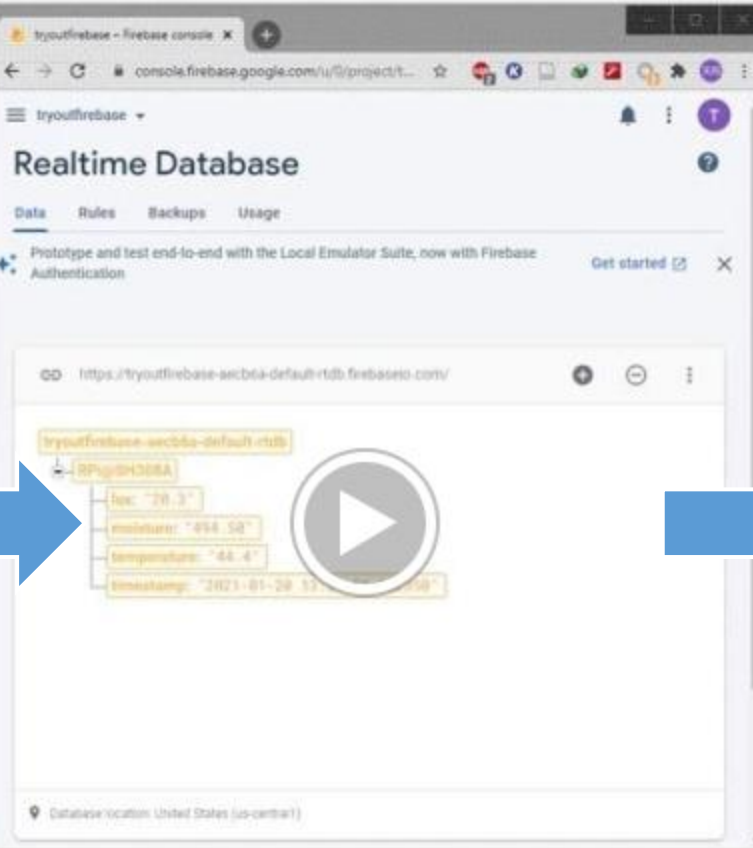
# Smartphone Application for Sensor Monitoring



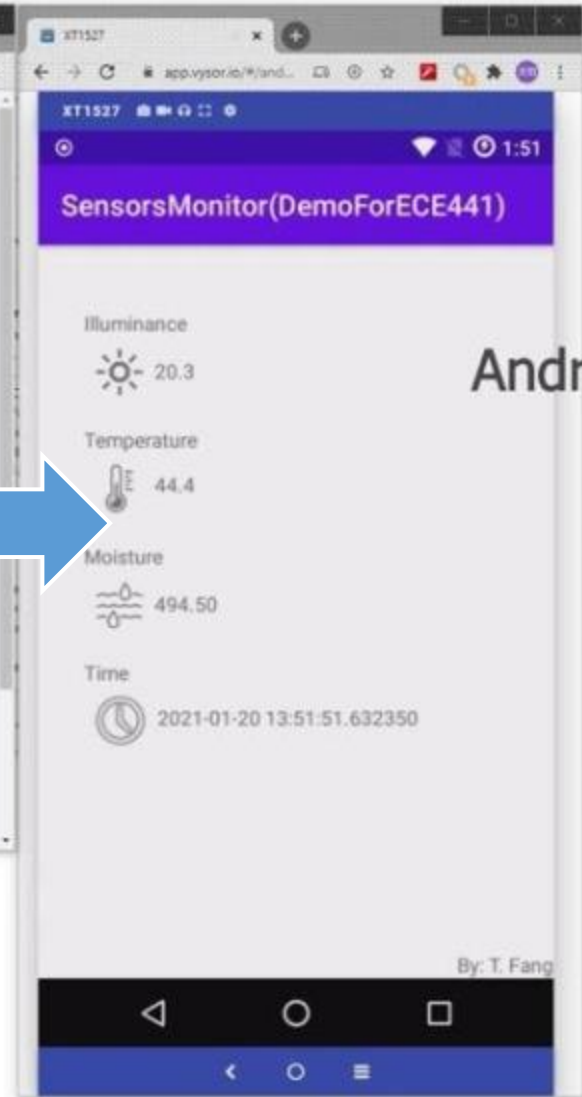


```
2021-01-20 13:50:20.240461 Lux:20.5 Moisture:484.38 Temperature45.4
2021-01-20 13:50:22.262129 Lux:20.3 Moisture:485.11 Temperature45.7
2021-01-20 13:50:24.282348 Lux:20.5 Moisture:488.04 Temperature46.9
2021-01-20 13:50:26.303568 Lux:20.1 Moisture:486.81 Temperature46.1
2021-01-20 13:50:28.327274 Lux:20.6 Moisture:487.57 Temperature45.8
2021-01-20 13:50:30.350022 Lux:20.5 Moisture:488.52 Temperature45.3
2021-01-20 13:50:32.373179 Lux:20.1 Moisture:489.34 Temperature44.4
2021-01-20 13:50:34.396377 Lux:20.3 Moisture:489.90 Temperature45.1
2021-01-20 13:50:36.417974 Lux:20.3 Moisture:491.34 Temperature44.3
2021-01-20 13:50:38.441353 Lux:20.4 Moisture:491.34 Temperature44.4
2021-01-20 13:50:40.469216 Lux:20.2 Moisture:492.28 Temperature45.1
2021-01-20 13:50:42.491208 Lux:20.5 Moisture:492.85 Temperature45.3
2021-01-20 13:50:44.514836 Lux:20.3 Moisture:493.02 Temperature45.4
2021-01-20 13:50:46.539185 Lux:20.5 Moisture:494.58 Temperature46.7
2021-01-20 13:50:48.566812 Lux:20.2 Moisture:495.58 Temperature46.9
2021-01-20 13:50:50.5951512 Lux:20.6 Moisture:491.63 Temperature46.1
2021-01-20 13:50:52.627333 Lux:20.5 Moisture:484.38 Temperature45.8
2021-01-20 13:50:54.659249 Lux:20.1 Moisture:485.11 Temperature45.3
2021-01-20 13:50:56.690321 Lux:20.3 Moisture:486.84 Temperature44.4
2021-01-20 13:50:58.721327 Lux:20.3 Moisture:486.81 Temperature45.1
2021-01-20 13:51:01.752347 Lux:20.4 Moisture:487.57 Temperature44.3
2021-01-20 13:51:03.784665 Lux:20.2 Moisture:488.52 Temperature44.4
2021-01-20 13:51:05.815398 Lux:20.5 Moisture:489.34 Temperature45.1
2021-01-20 13:51:07.846665 Lux:20.3 Moisture:489.90 Temperature45.3
2021-01-20 13:51:09.878223 Lux:20.3 Moisture:490.81 Temperature45.4
2021-01-20 13:51:11.904521 Lux:20.1 Moisture:491.34 Temperature46.7
2021-01-20 13:51:13.930815 Lux:20.6 Moisture:492.28 Temperature46.9
2021-01-20 13:51:15.9521968 Lux:20.5 Moisture:492.85 Temperature46.1
2021-01-20 13:51:17.9745848 Lux:20.2 Moisture:493.02 Temperature46.3
2021-01-20 13:51:19.9972359 Lux:20.3 Moisture:494.58 Temperature46.5
2021-01-20 13:51:21.995886 Lux:20.3 Moisture:495.58 Temperature46.7
2021-01-20 13:51:23.99947 Lux:20.4 Moisture:483.63 Temperature45.1
2021-01-20 13:51:25.99368 Lux:20.2 Moisture:484.38 Temperature44.3
2021-01-20 13:51:27.988118 Lux:20.5 Moisture:485.11 Temperature44.4
2021-01-20 13:51:29.982948 Lux:20.3 Moisture:486.84 Temperature45.1
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2021-01-20 13:51:41.962887 Lux:20.3 Moisture:490.81 Temperature45.8
2021-01-20 13:51:43.959777 Lux:20.3 Moisture:491.34 Temperature45.3
2021-01-20 13:51:45.956918 Lux:20.4 Moisture:492.28 Temperature44.4
2021-01-20 13:51:47.954911 Lux:20.2 Moisture:492.85 Temperature45.1
2021-01-20 13:51:49.952128 Lux:20.5 Moisture:493.02 Temperature44.3
2021-01-20 13:51:51.949358 Lux:20.3 Moisture:494.58 Temperature44.4
```

RaspberryPi  
(uploading sensors data)



Firebase Cloud  
(database on the Cloud)

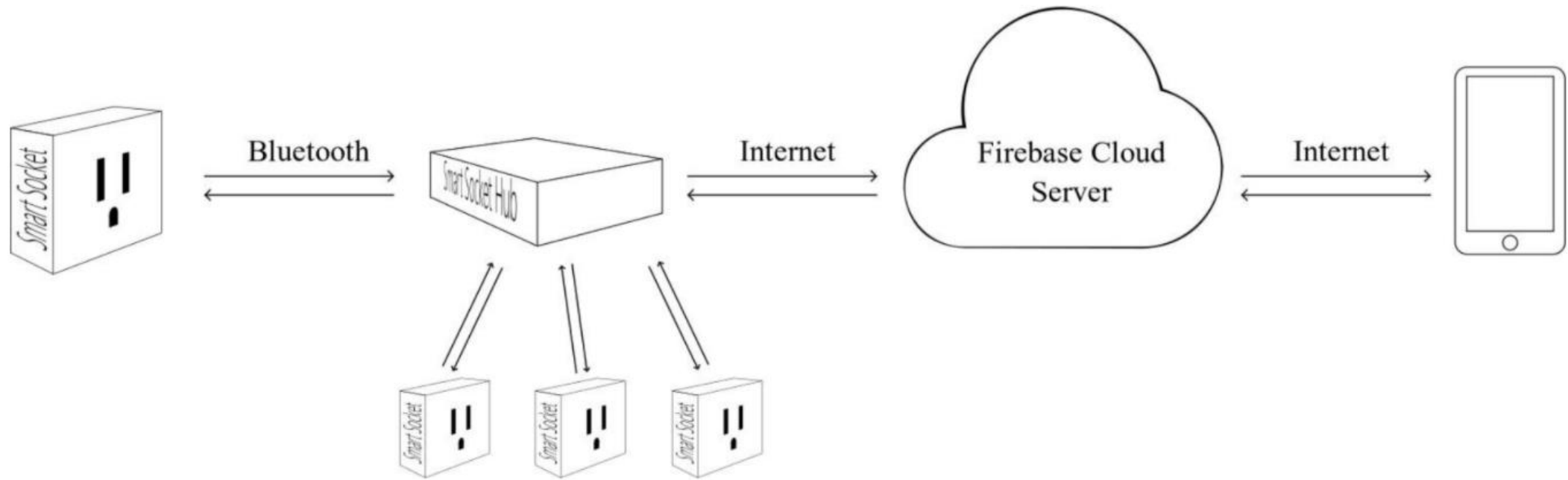


Android App

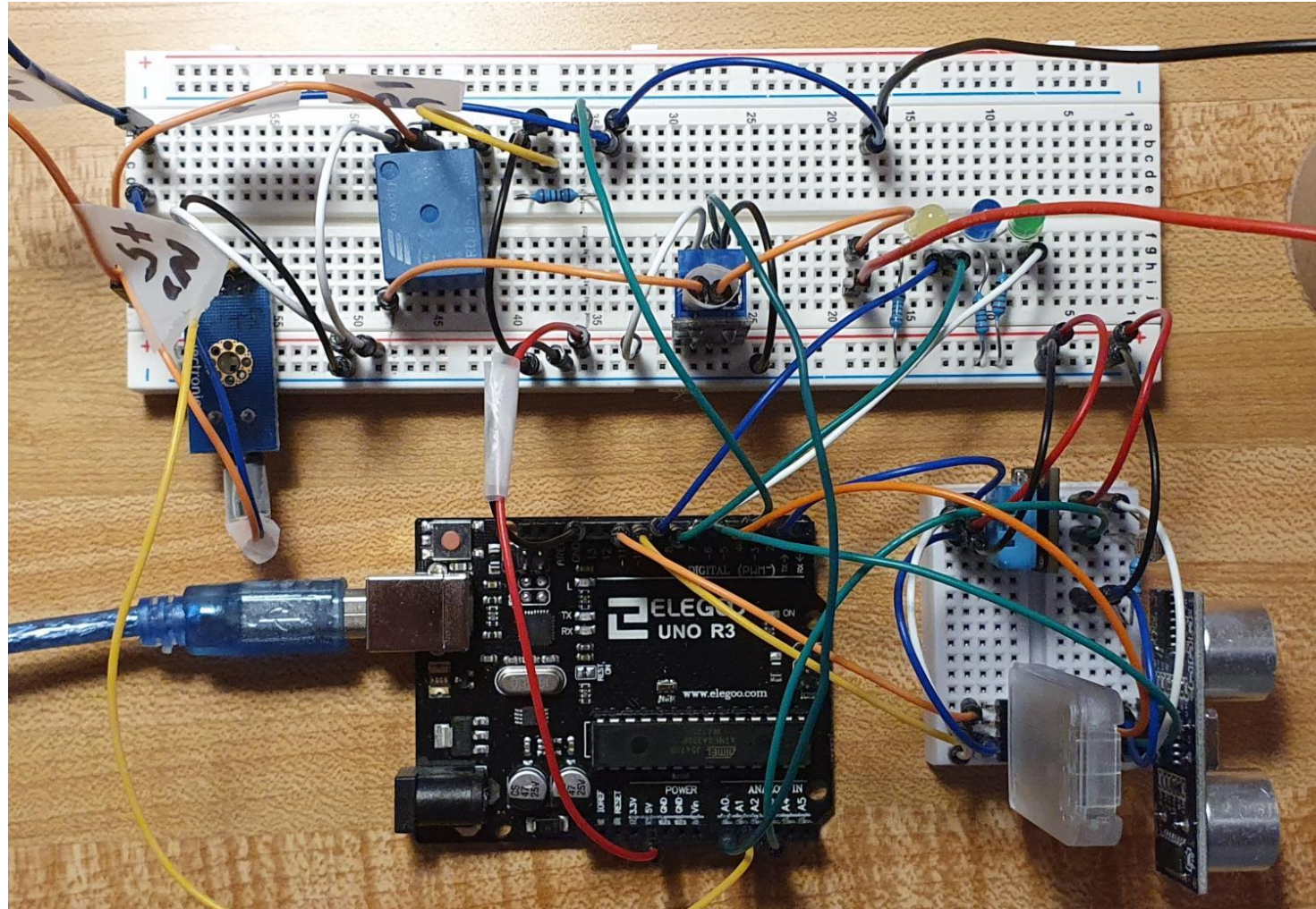
# Smart Socket

- The aim of this project is to build a custom 'Smart Socket' (SS) based on Arduino UNO and Raspberry Pi 3.
- Its main function is to provide services such as remote control and monitoring, reliable electrical protection and tasks automation.
- The remote control of the socket is based on a mobile application, which uses cloud services and allows the user to perform all tasks remotely.
- When combining the 'Smart Socket' with household appliances that are not connected or smart by design, they will instantly become active elements for the user, offering new and smart functionalities to optimize and improve its usage.

# Smart Socket General Architecture



# Smart Socket





# Smart Socket Demo: Remote Control Lights Across The Atlantic



**Thank You**