# ECE 441
# Smart & Connected Embedded Systems

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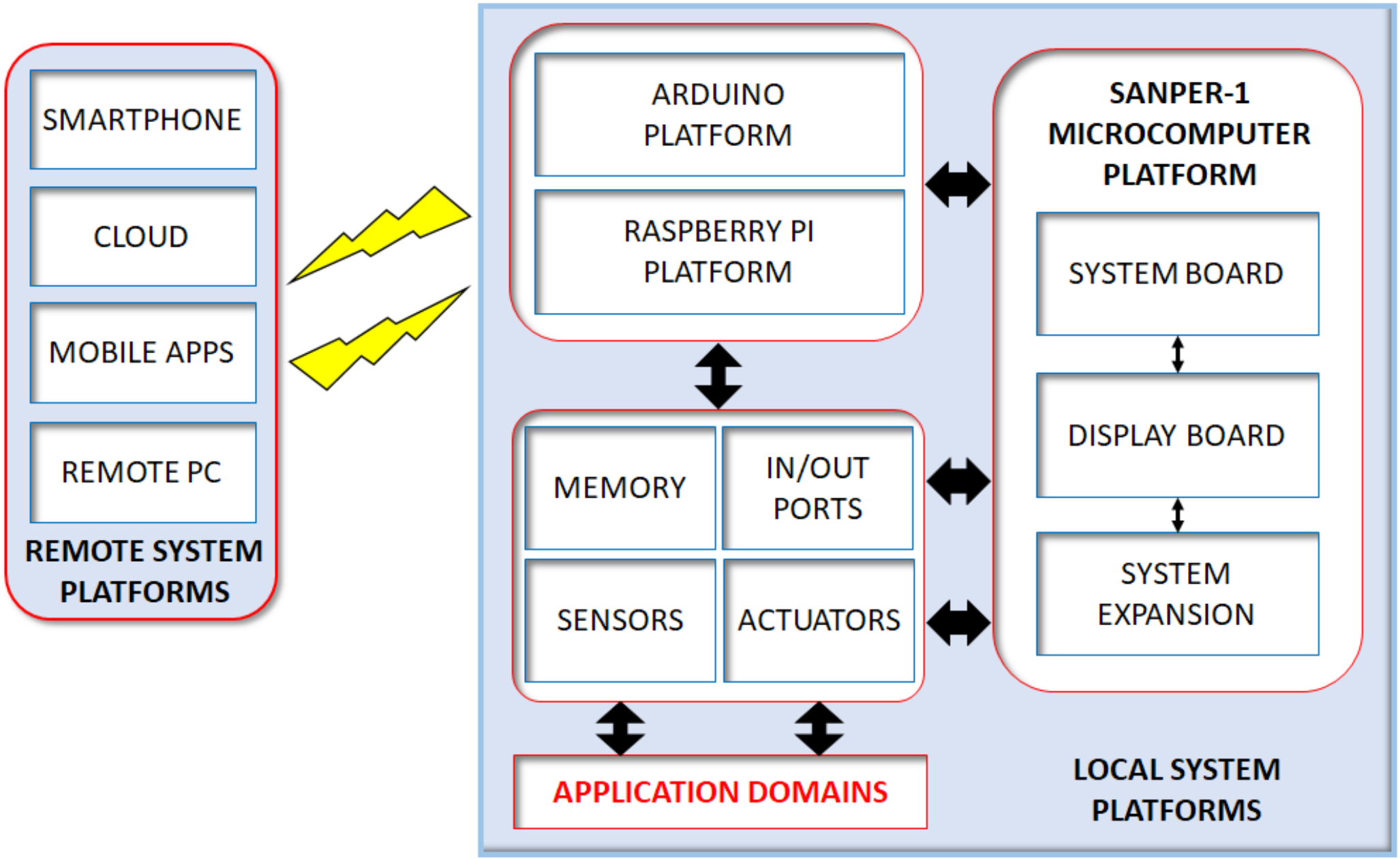
**Teaching Assistants:** Xinrui Yu, Xin Huang, and Mikhail Gormov

# Wide Range of Projects

- Multiple computing platform architectures for smart and connected system applications can be used.
- The goal is to develop smart and connected systems.
- Examples for the design project is shown later in this presentation.

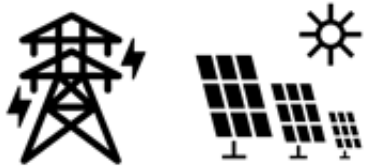
# ECE 441 – MAJOR DESIGN PROJECT:
# SMART AND CONNECTED SYSTEM ARCHITECTURE



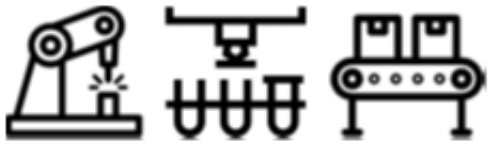
# APPLICATION DOMAINS

Vehicle, Asset, Person & Pet Monitoring and Controlling

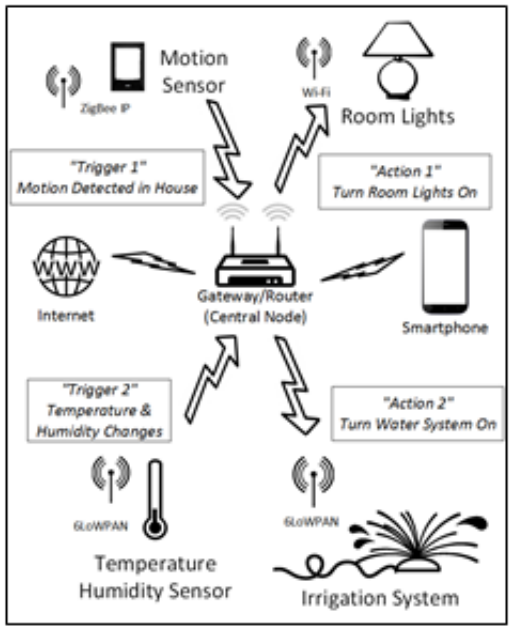
Agriculture Automation



Energy Management



Factory Automation




Home Automation

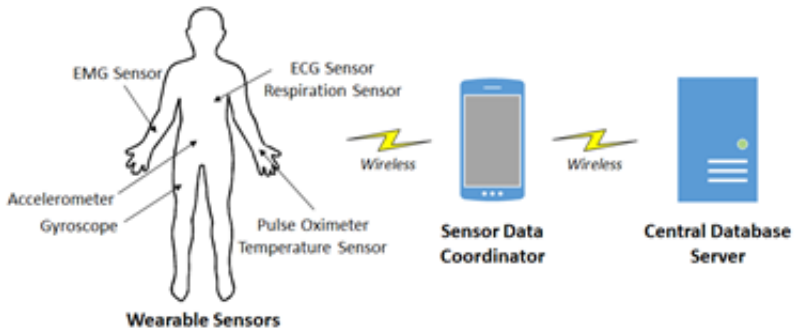
Smart and Connected Systems

Building Management

Smart Transportation

Daily Activity Things

Smart Security




Remote Healthcare System

# What is SANPER?

- The SANPER-1 Microcomputer Platform was designed and developed by Dr. Jafar Saniie and Mr. Stephen Perich.
- The platform includes a firmware package named “TUTOR” which is a MC68000 resident monitor program developed by Motorola, Inc.
- The platform could be used along with an external power supply and a video display terminal to construct an educational development system for the design project.


# SANPER-1 in the Lab

# Basic Access to SANPER

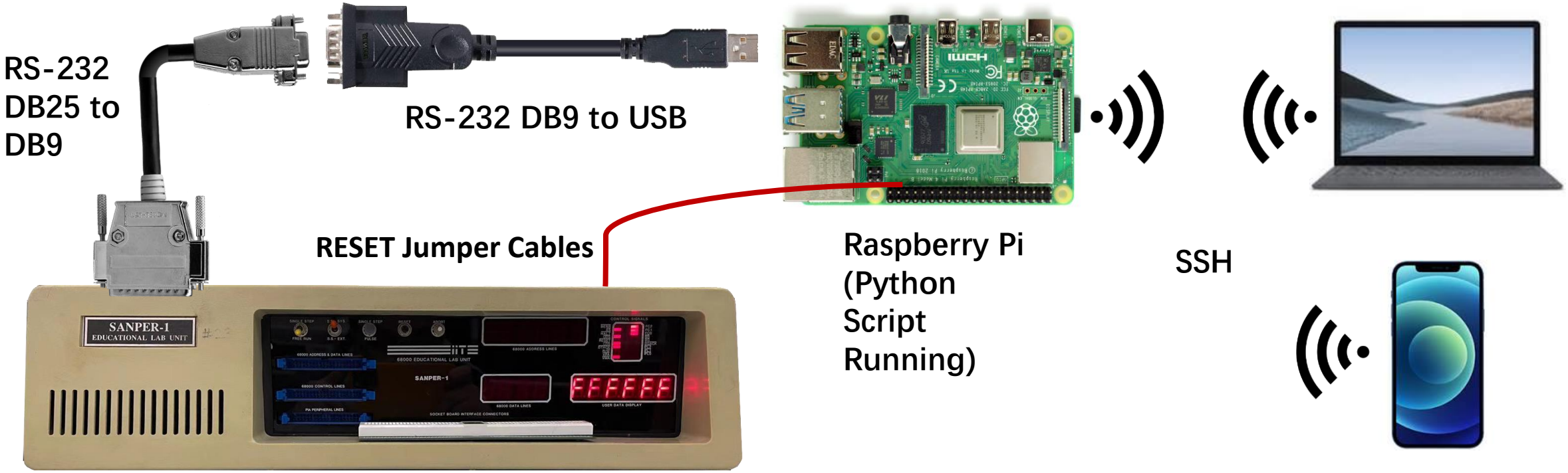
- The SANPER is connected to the lab PC via a RS-232 DB25 to DB9 cable and a RS-232 DB9 to USB cable.
- The lab PC runs SecureCRT (a terminal emulator) to communicate with SANPER.

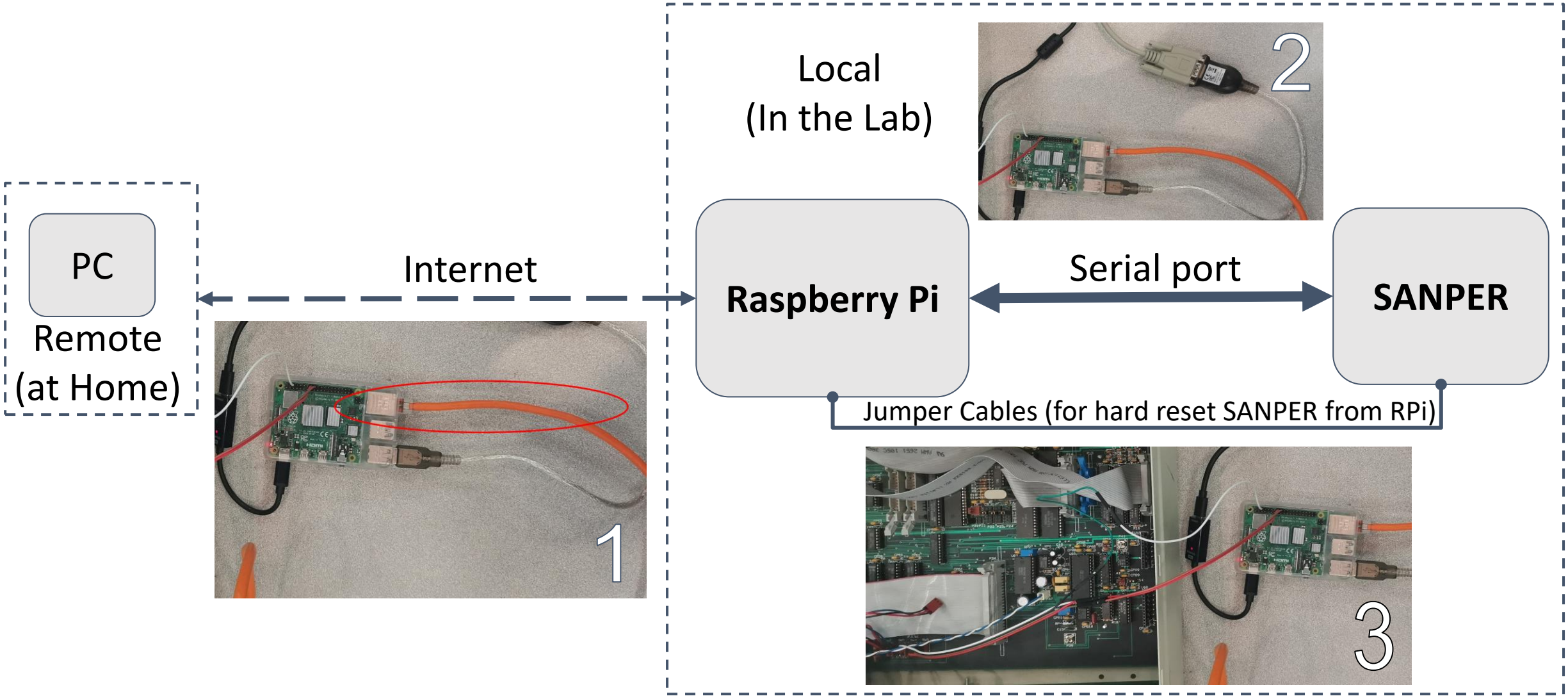
# Remote Access to SANPER

- Uses Raspberry Pi as a terminal to access SANPER remotely
- Access SANPER in a way like using SecureCRT on lab PCs
- Hardware RESET available without physically pressing the button
- Access SANPER remotely using PCs and smartphones
- **Hardware:**
  - **Raspberry Pi**
  - **RS-232 DB25 to DB9 cable**
  - **RS-232 DB9 to USB cable**
  - **Jumper cables**

# Access SANPER Remotely using Raspberry Pi

- The SANPER is connected to the Raspberry Pi with the same configuration.
- The Raspberry Pi runs a custom-built Python Script to communicate with SANPER.
- The Raspberry Pi can then communicate with other PCs and smartphones over the internet with SSH (Secure Shell, a cryptographic network protocol).





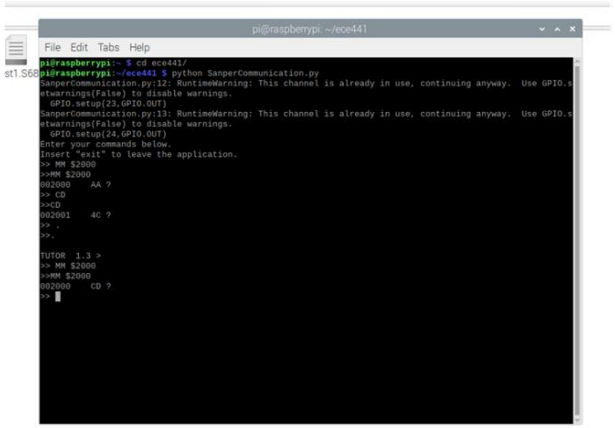

- The Raspberry Pi connects to the Internet through the orange ethernet cable
- The silver cable is the serial port connection between SANPER-1 and Raspberry Pi
- Three jumper cables connect the RESET input of the SANPER-1 and three GPIO ports on the Raspberry Pi for remote hard reset of the SANPER-1.

# Visualization Interface of Remote Access to SANPER

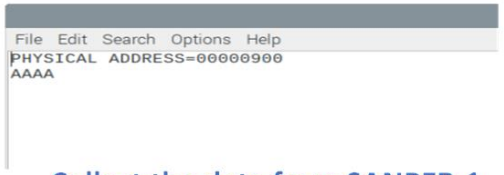
Client (Window operating system)

SSH

## Raspberry Pi



SANPER-1 Computer Platform User Interface



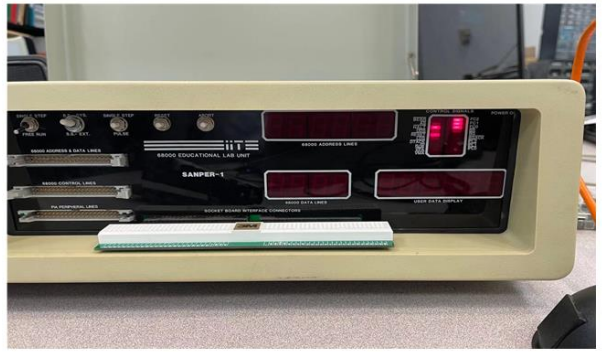

Collect the data from SANPER-1


Reset Control

Serial

## SANPER-1 Computing Platform

SANPER-1 Unit

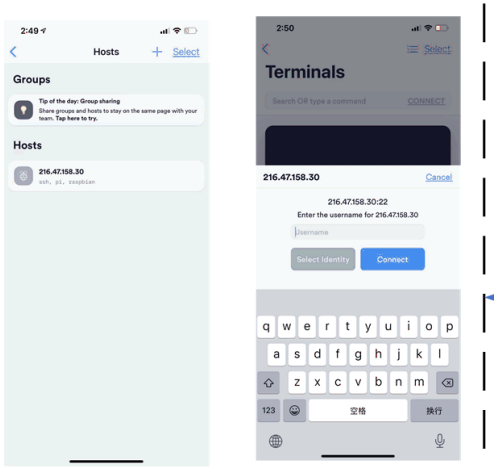


SANPER-1 Reset Mode

Jumper Cables

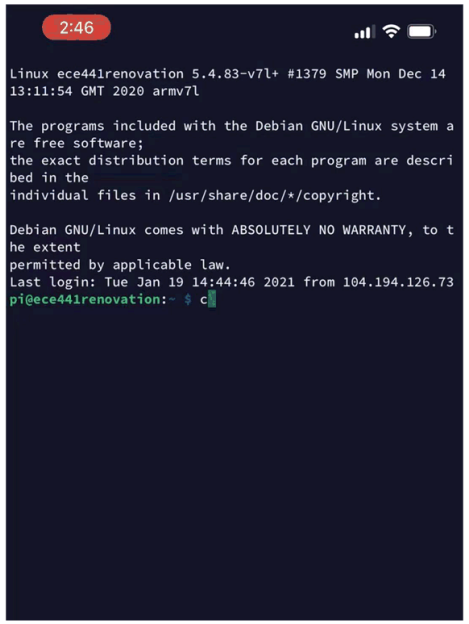
Server (Raspberry Pi + SANPER)

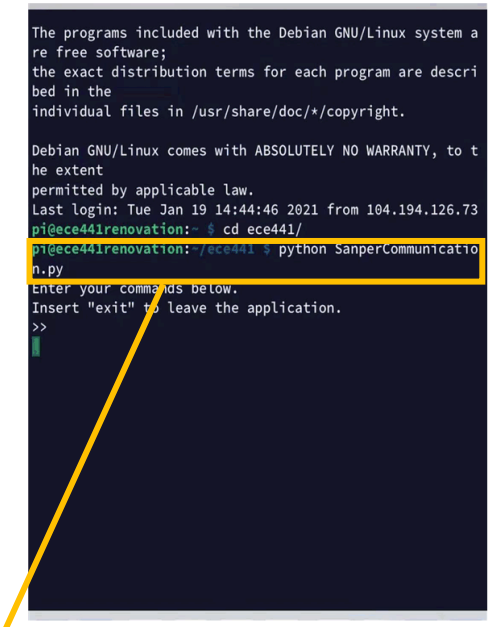
# Remote Access to SANPER using Smartphone

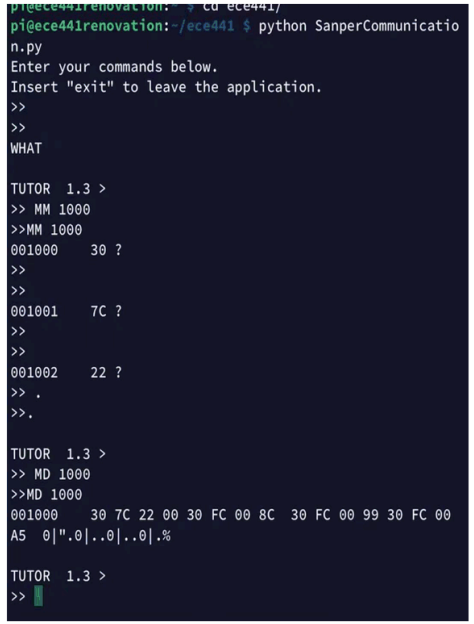



Client (Cellphone OS operating system)

SSH



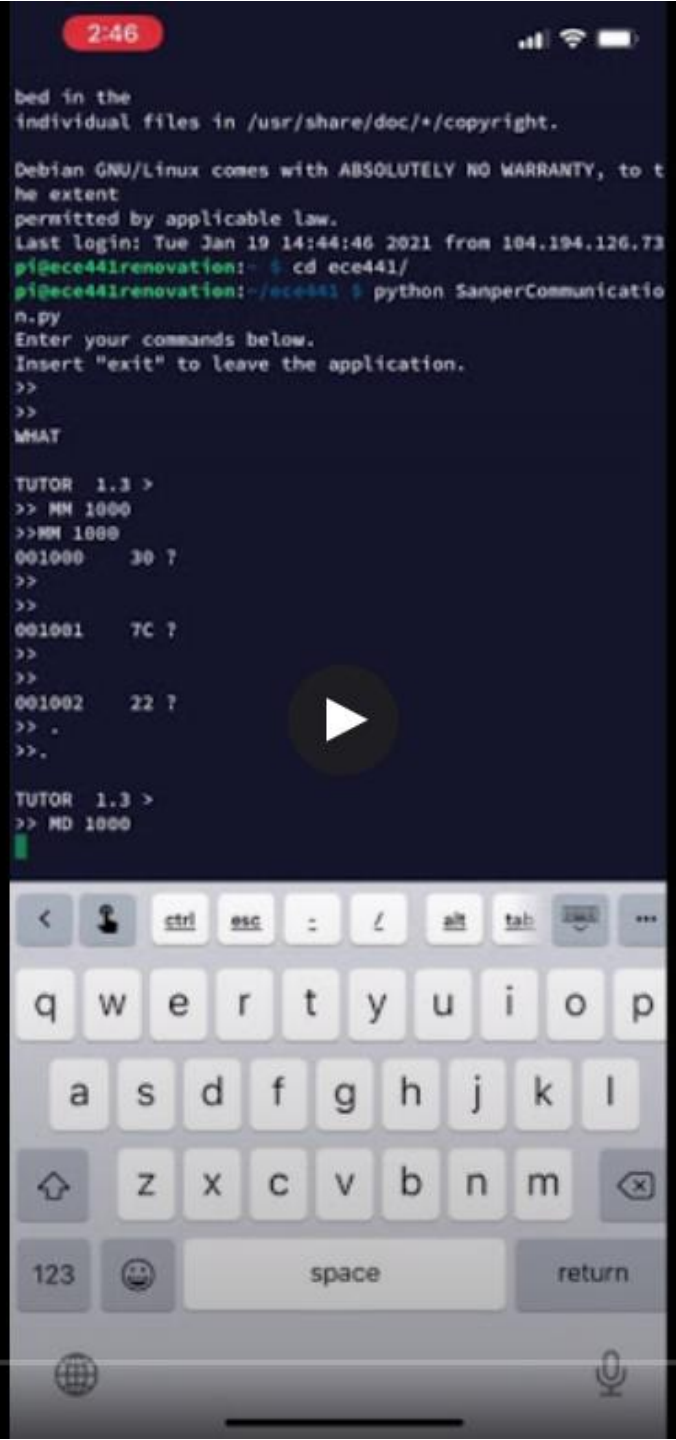




SANPER-1 Unit Terminals on Cellphone

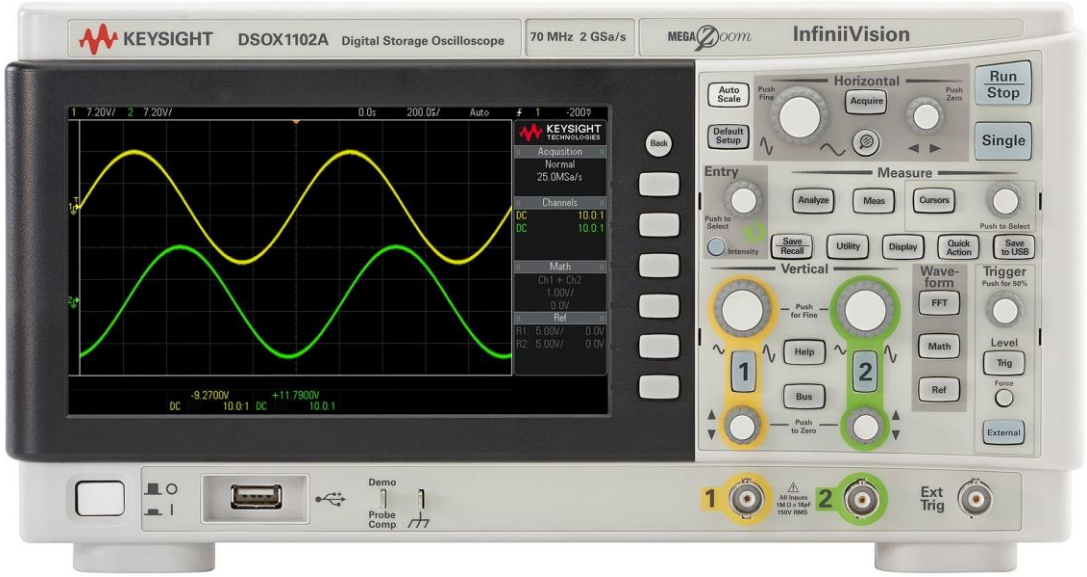
Server (Raspberry Pi + SANPER)

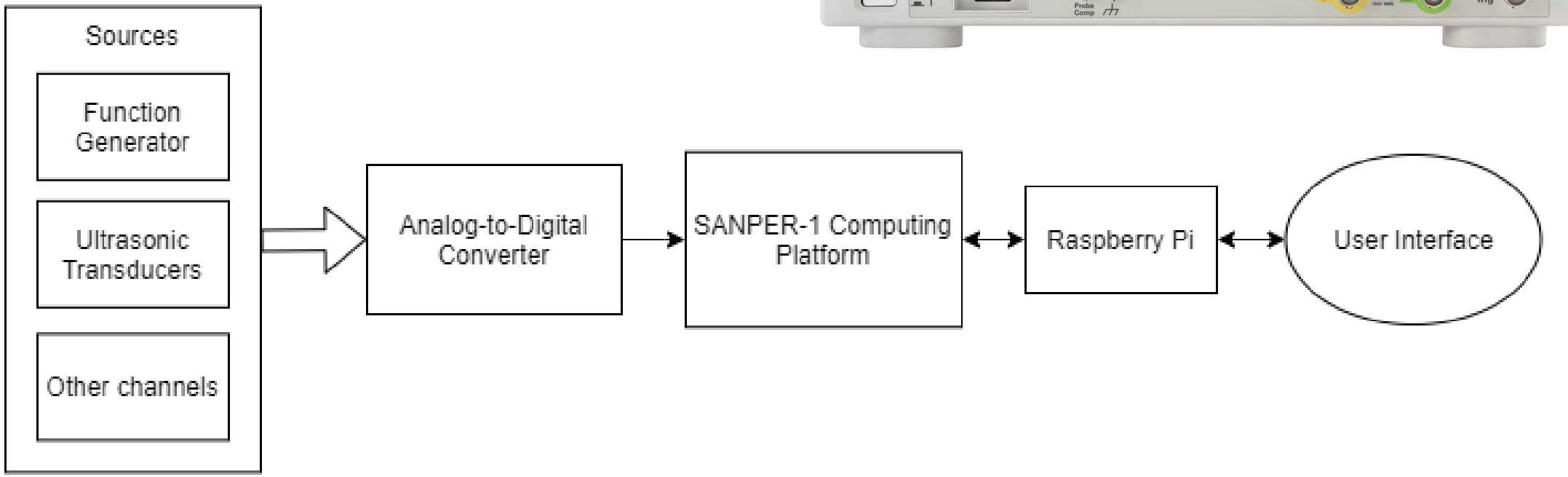
**The Python script to communicate with SANPER is called SanperCommuniation.py**


2:46
bed in the
individual files in /usr/share/doc/*/copyright.
Debian GNU/Linux comes with ABSOLUTELY NO WARRANTY, to t
he extent
permitted by applicable law.
Last login: Tue Jan 19 14:44:46 2021 from 104.194.126.73
pi@ece441renovation:~ $ cd ece441/
pi@ece441renovation:~/ece441 $ python SanperCommunicatio
n.py
Enter your commands below.
Insert "exit" to leave the application.
>>
>>
WHAT
TUTOR 1.3 >
>> MM 1000
>>MM 1000
001000 30 ?
>>
>>
001001 7C ?
>>
>>
001002 22 ?
>> .
>>.
TUTOR 1.3 >
>> MD 1000
ctrl
esc
alt
tab
q w e r t y u i o p
a s d f g h j k l
z x c v b n m
123
space
return

0:00 / 0:47

# Digital Oscilloscope

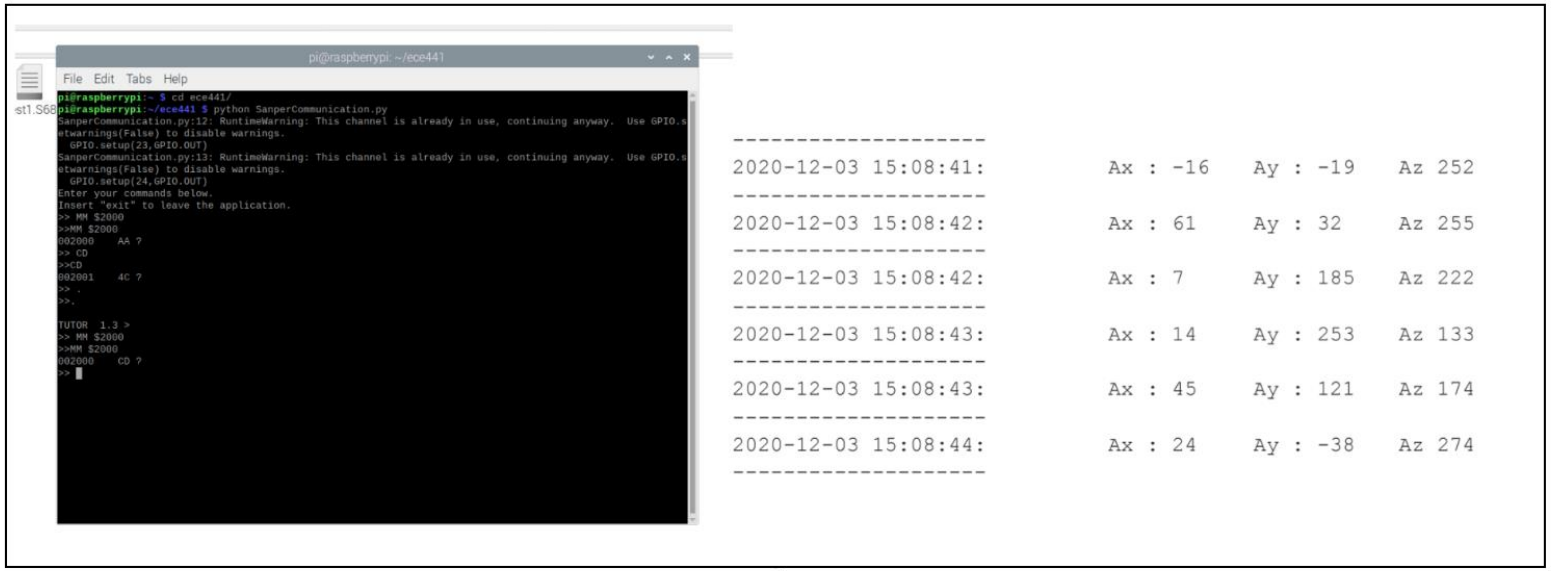


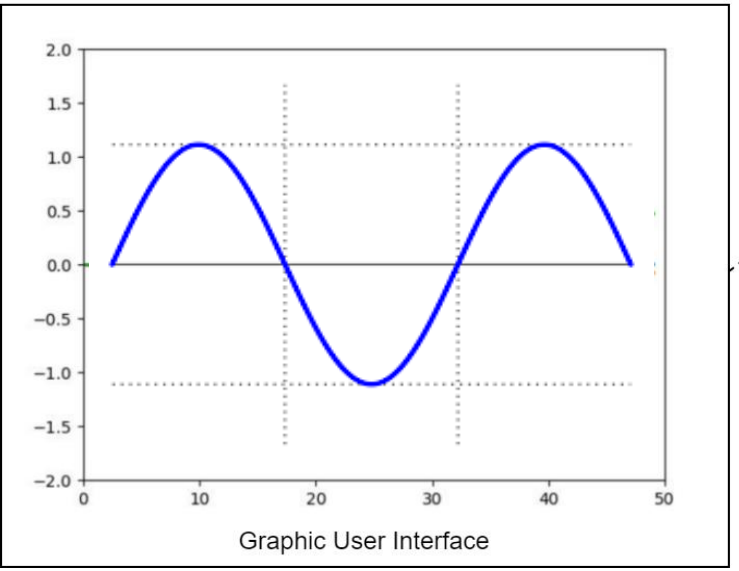



# Digital Oscilloscope

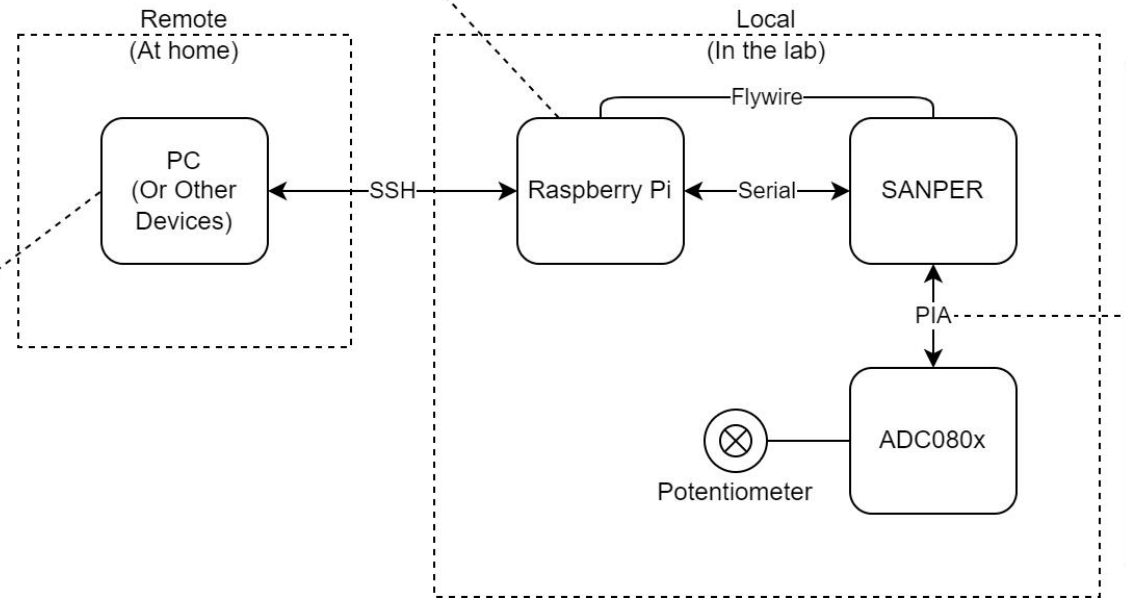
- This project is an oscilloscope that can pick up and display analog signals.
- A/D conversion is needed for interfacing with the signal inputs such as function generator or other analog signal sources.
- SANPER-1 Computing Platform transfer the sampled digital signals to the Raspberry Pi.
- **Hardware:**
  - **A/D Converter**
  - **Function Generator**

Python Script for Serial Communication, data decoding and SSH connection

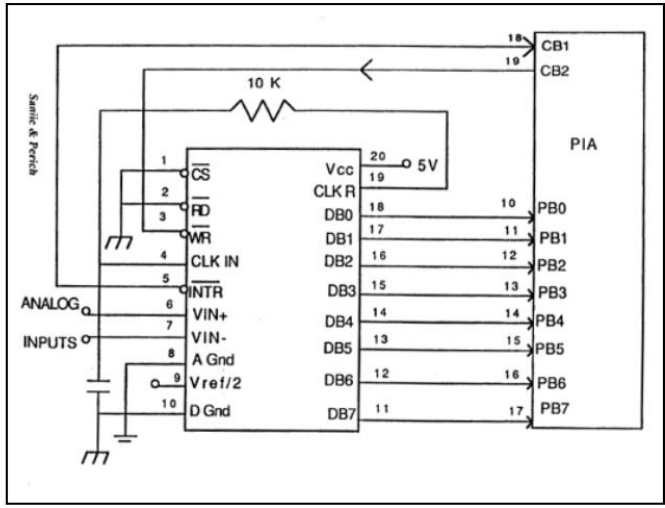


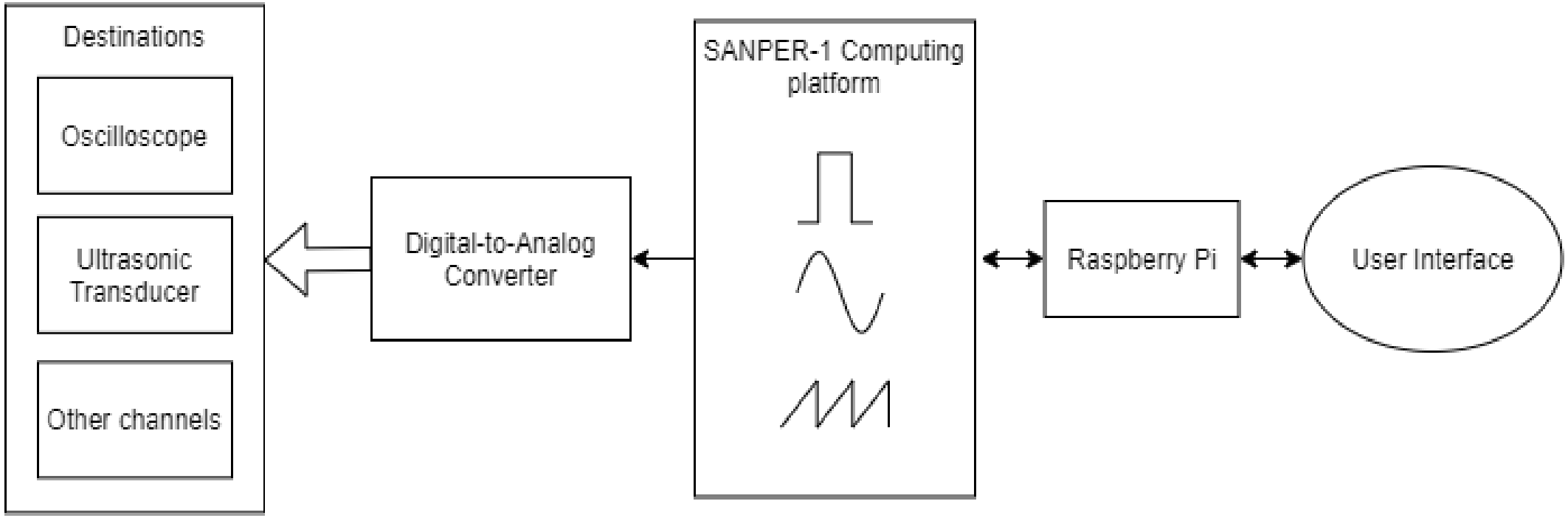
Graphic User Interface




Sample Design



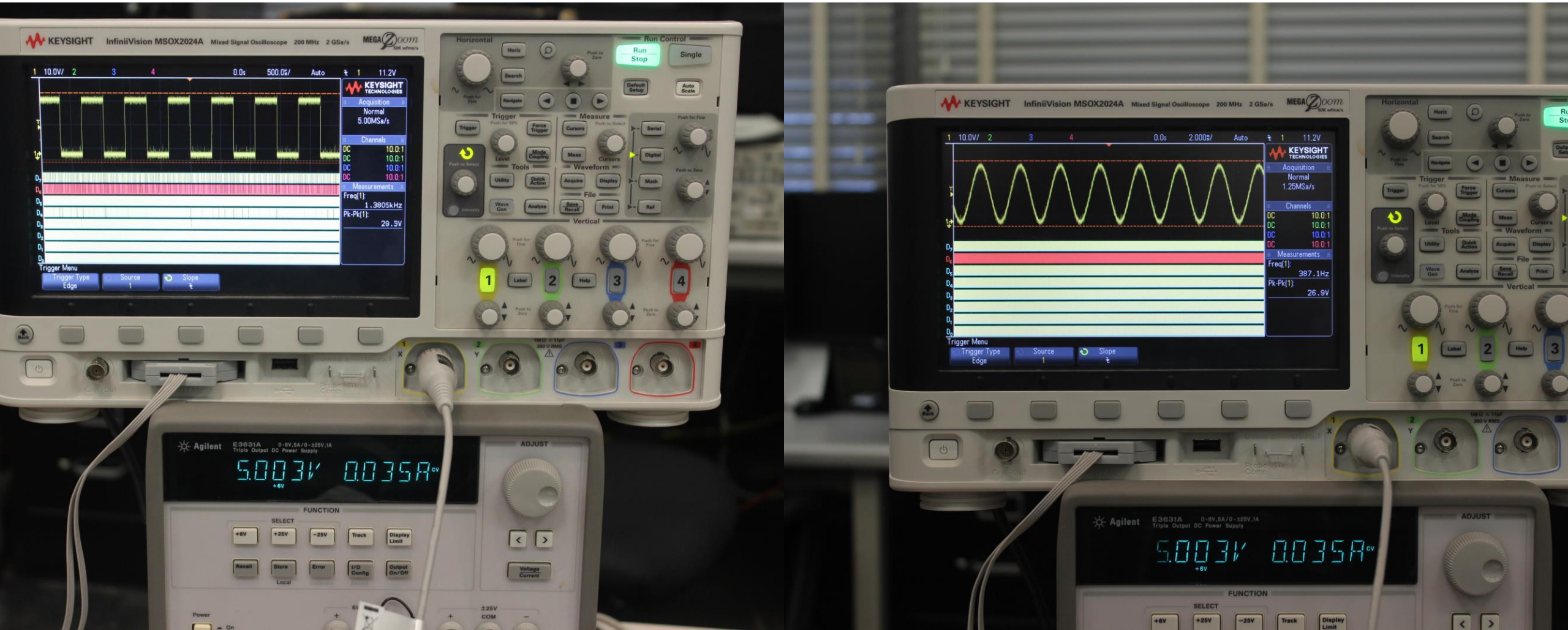
# Function Generator

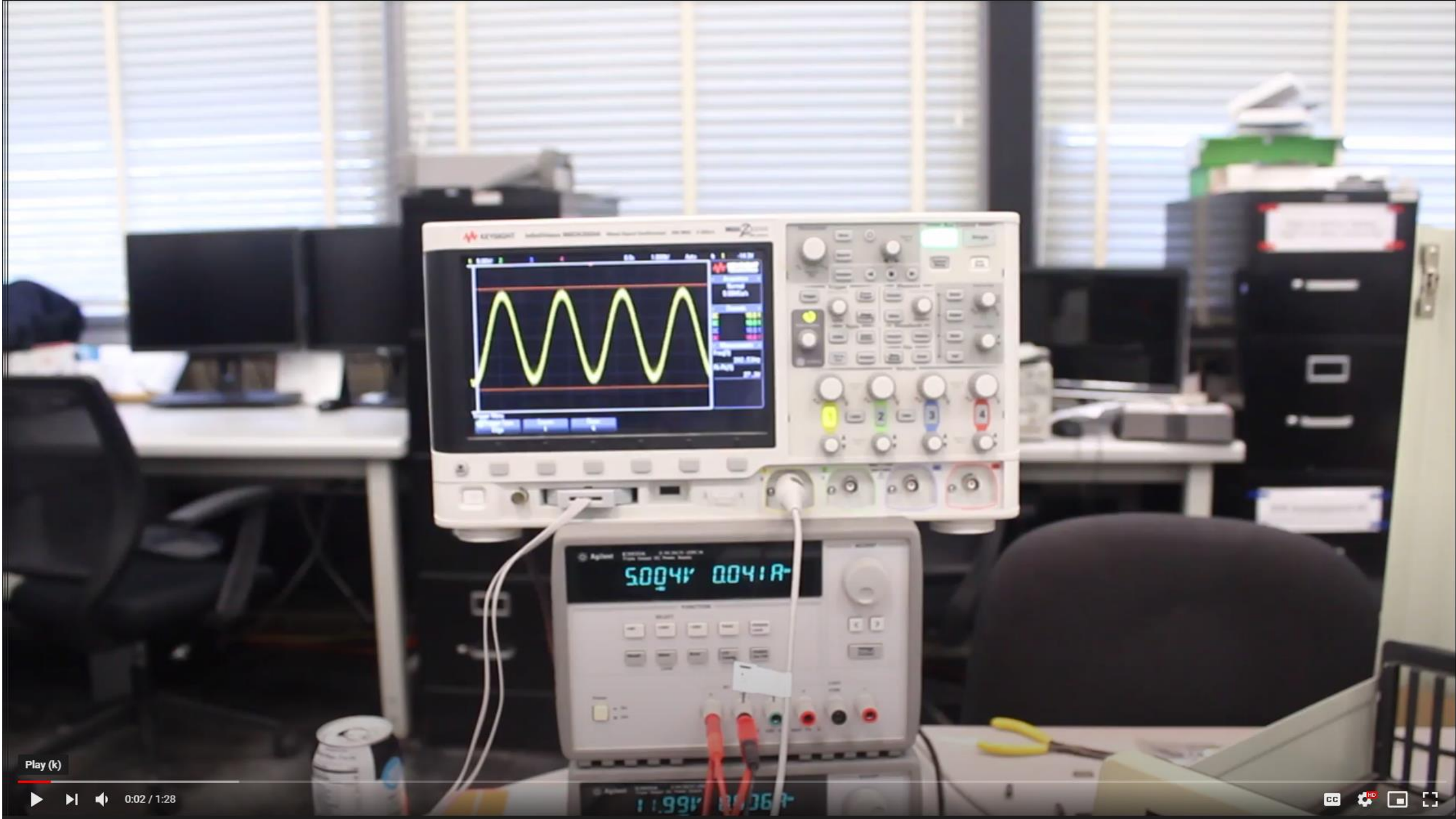


# Function Generator


- This project is a function generator based on the SANPER-1 Computing Platform.
- User interfaces are available for the transmitter.
- SANPER-1 provides the essential modulation and demodulation processes.
- A/D conversion and D/A conversion are needed for interfacing with the channels through the transducers.
- **Hardware:**
  - **A/D Converter**
  - **D/A Converter**
  - **Oscilloscope**

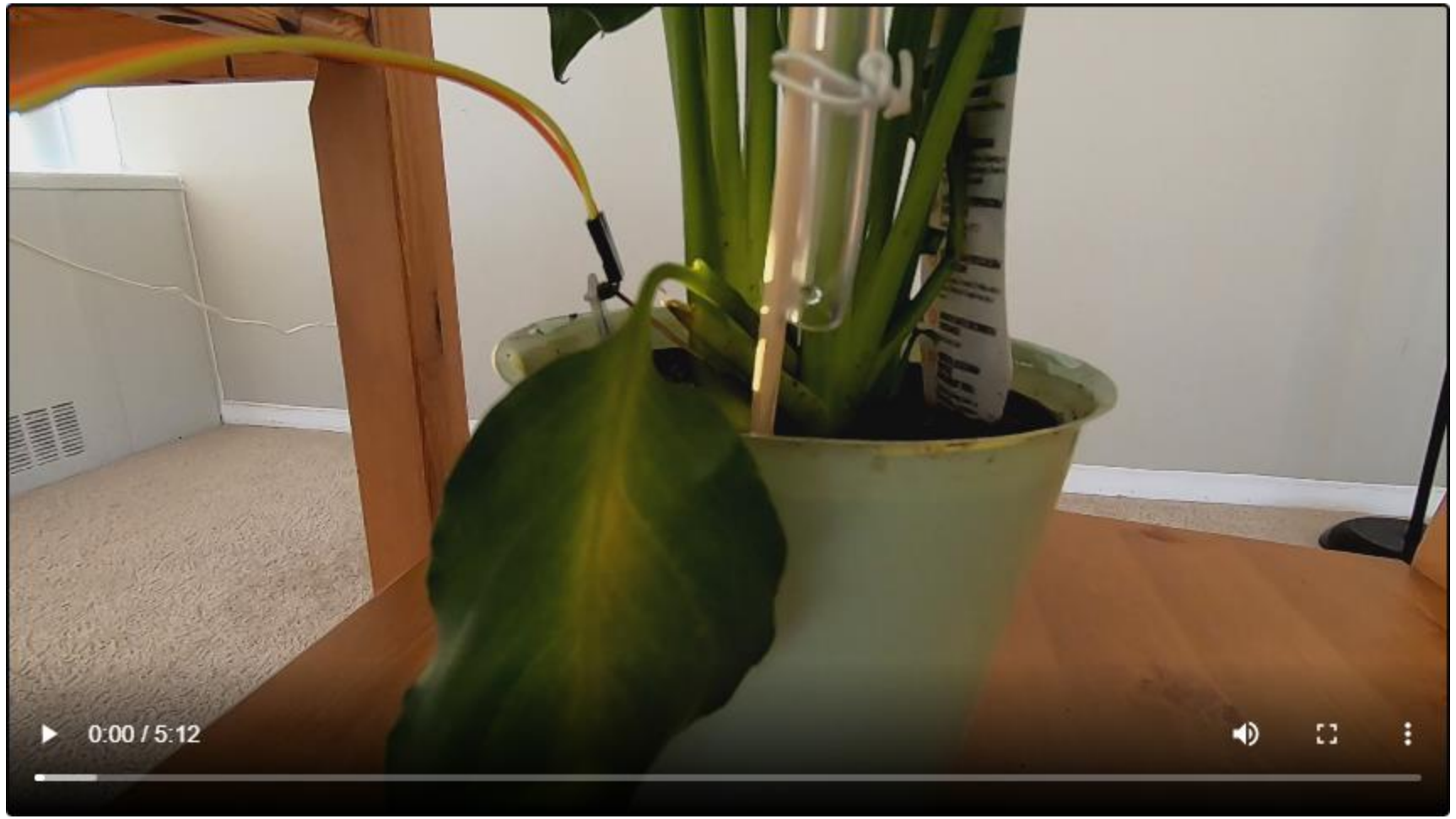
# Function Generator Results




Play (k)
0:02 / 1:28

# Smart Irrigation System

- A smart irrigation system should continuously monitor the amount of water, determine if watering is required for the plants, supply the exact or approximate amount of water required for the plants, and lastly discontinue the water supply when the required amount has been delivered to the plants.
- It can be said that plant monitoring system is a part of smart irrigation. This project focuses on monitoring soil moisture, as well as temperature, humidity, and light intensity.


0:00 / 5:12

# Computer Vision Based Autonomous Robotic Arm

- The robotic arm will be used to identify, sort, and interact with objects within its reach.
- The objects that the robot will interact with will be different color nuts and bolts.
- A menu allows for the user to control the robot's speed, where it wants to go, what it should pick up, and even reverting an action.
- The red numbers on the picture marks the 8 motors that facilitate the move of the arm.

# Computer Vision Based Autonomous Robotic Arm

- The image is filtered, segmented and goes through an object recognition algorithm.

# Computer Vision Based Autonomous Robotic Arm Demo

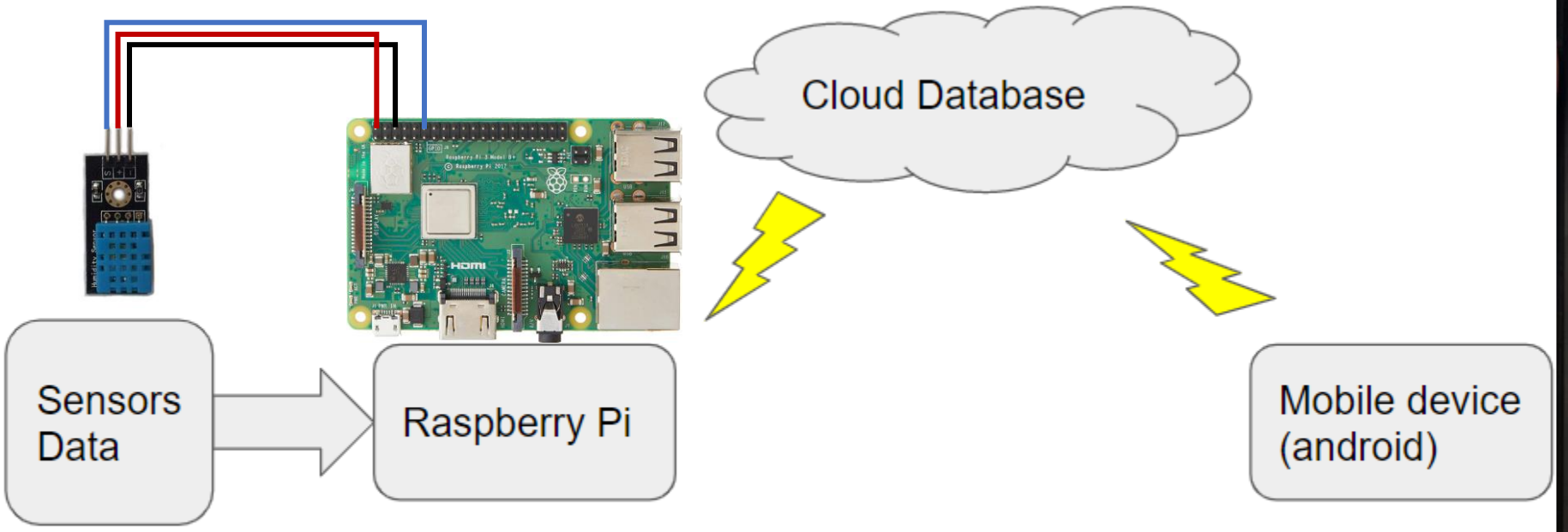

Embedded Computing and Signal Processing Research Laboratory

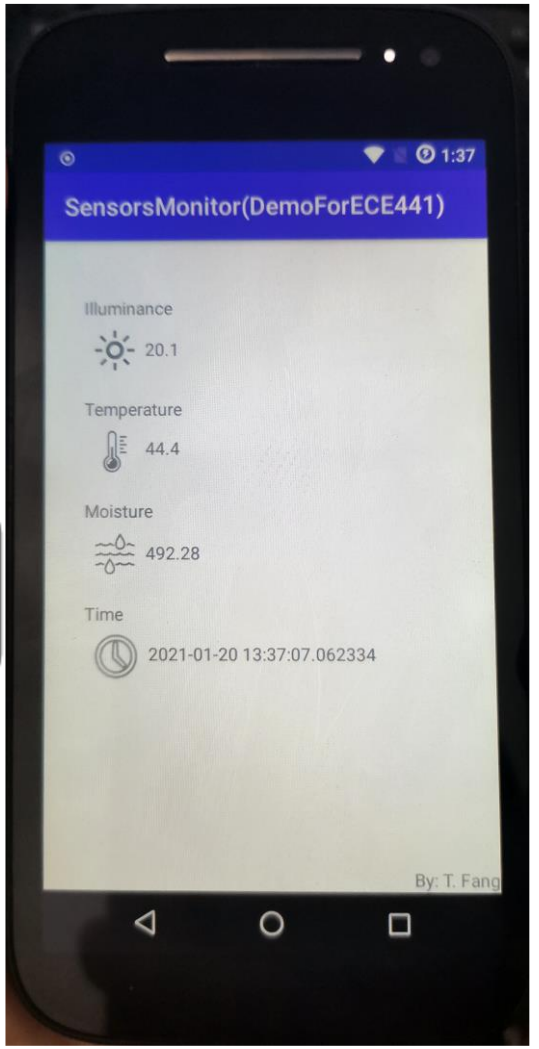
Department of Electrical and Computer Engineering

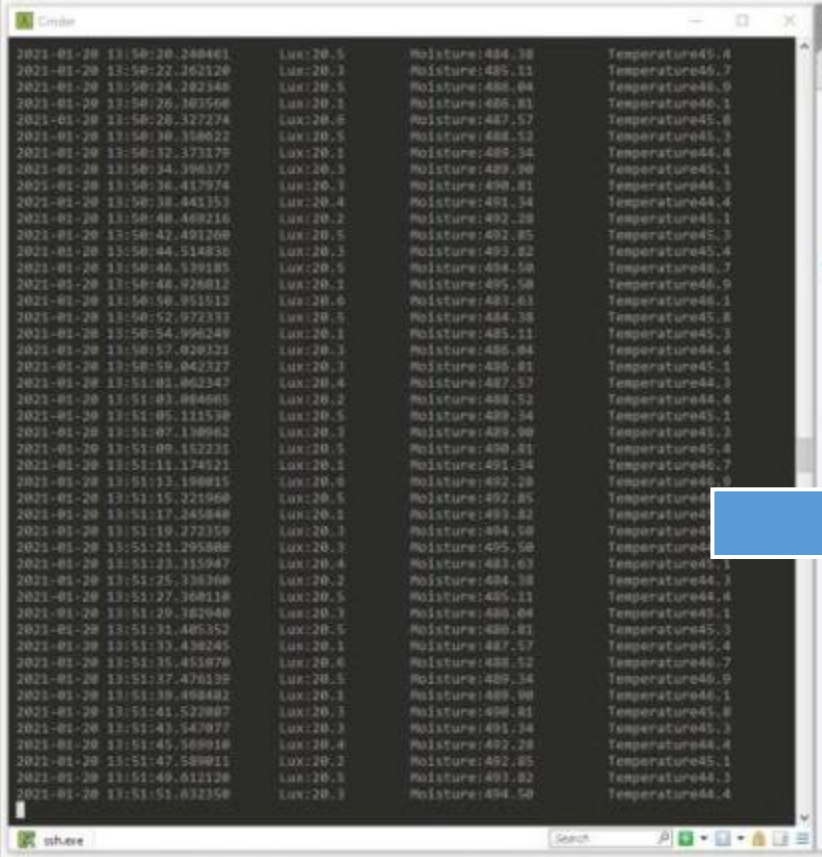
# Smartphone Application for Sensor Monitoring

- Sensor's data is acquired either from SANPER-1 or directly from sensors connected to the Raspberry Pi
- A python script runs on the Raspberry Pi uploads the data to the cloud every two seconds
- The android cell phone will update the displayed sensors data once there are changes to the cloud database

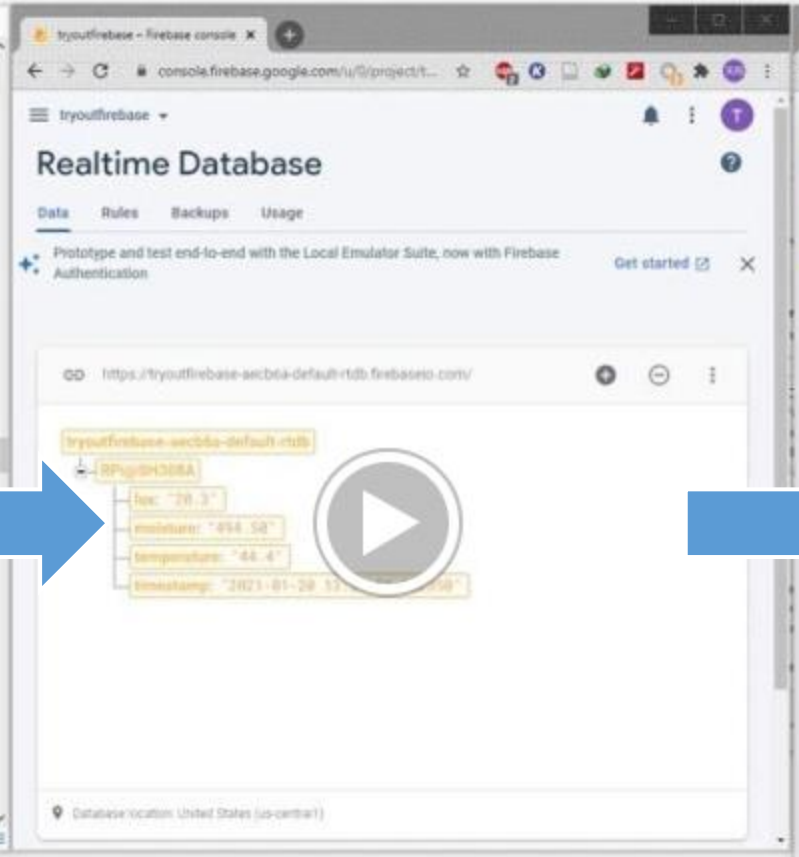
# Smartphone Application for Sensor Monitoring



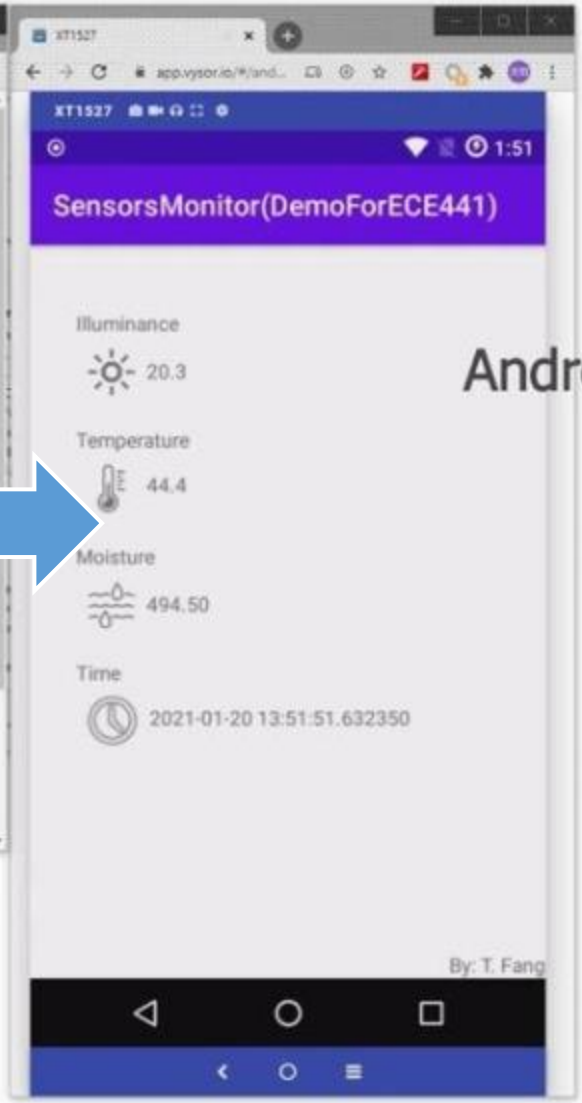





RaspberryPi
(uploading sensors data)




Firebase Cloud
(database on the Cloud)

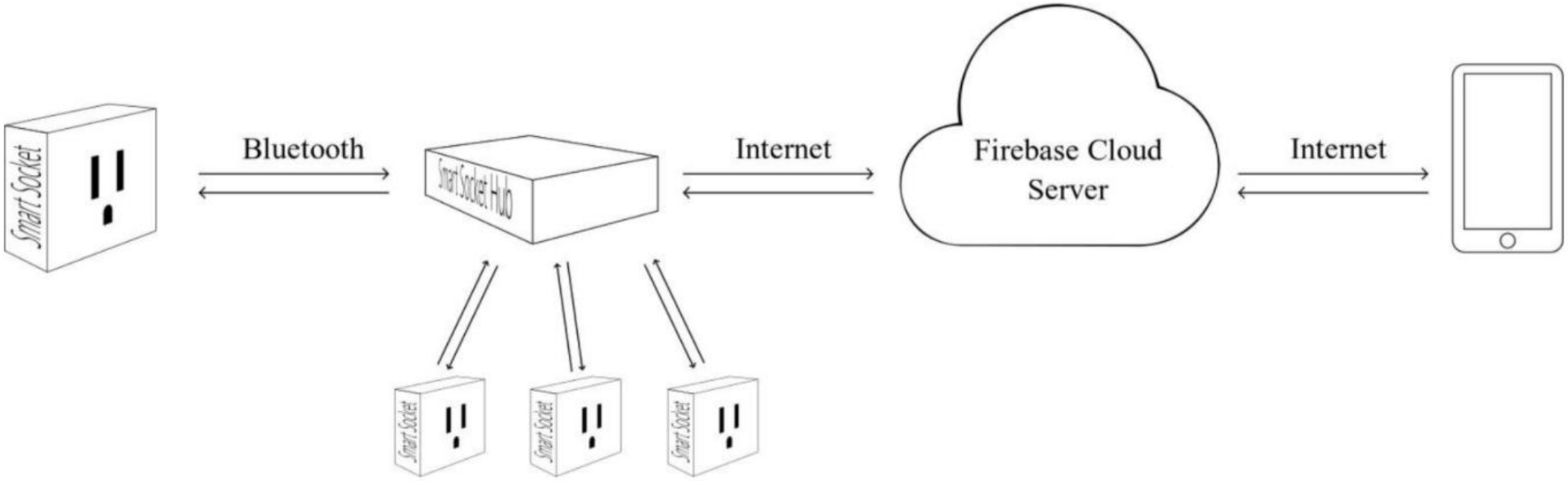



Android App

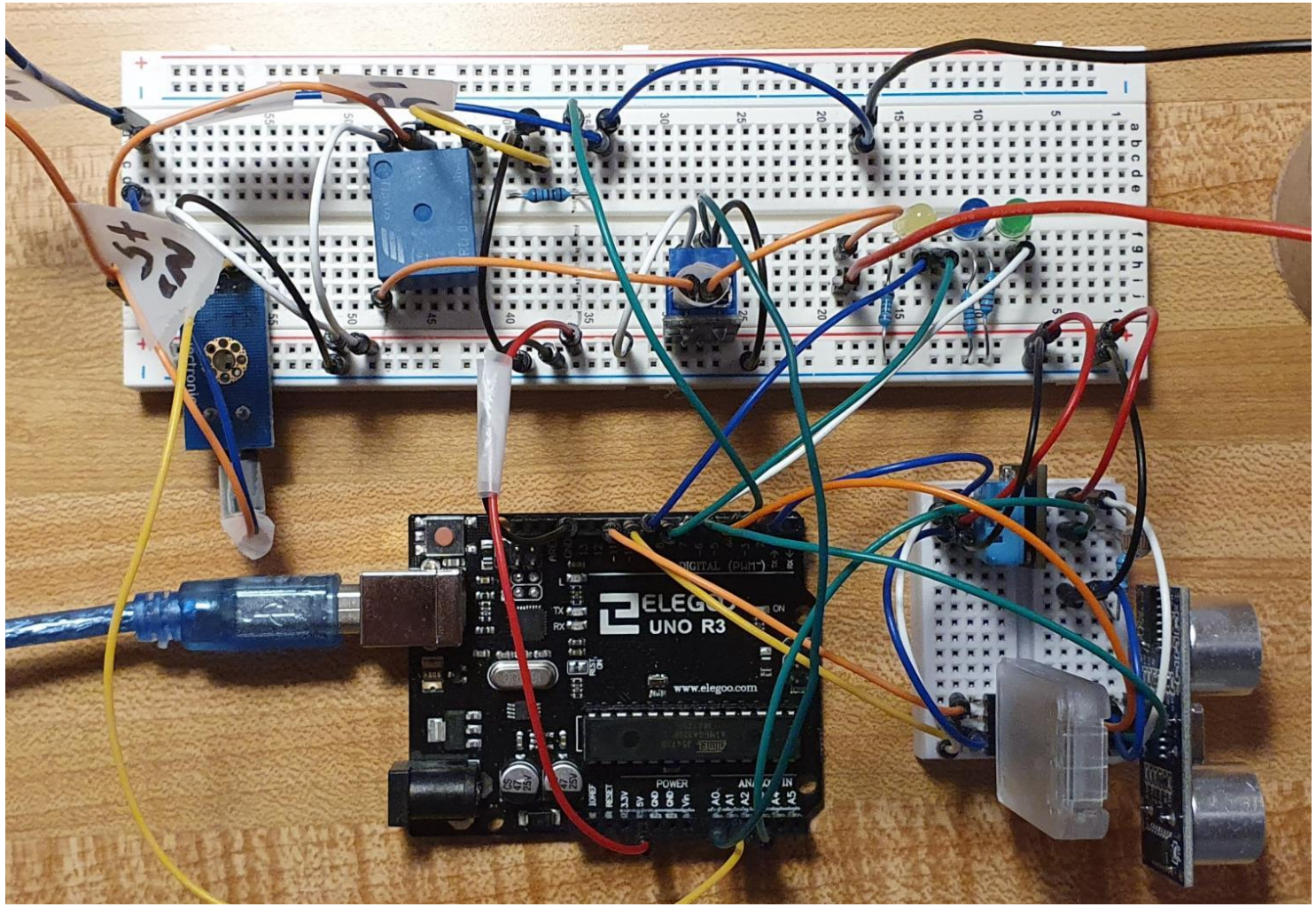
# Smart Socket

- The aim of this project is to build a custom ‘Smart Socket’ (SS) based on Arduino UNO and Raspberry Pi 3.
- Its main function is to provide services such as remote control and monitoring, reliable electrical protection and tasks automation.
- The remote control of the socket is based on a mobile application, which uses cloud services and allows the user to perform all tasks remotely.
- When combining the ‘Smart Socket’ with household appliances that are not connected or smart by design, they will instantly become active elements for the user, offering new and smart functionalities to optimize and improve its usage.

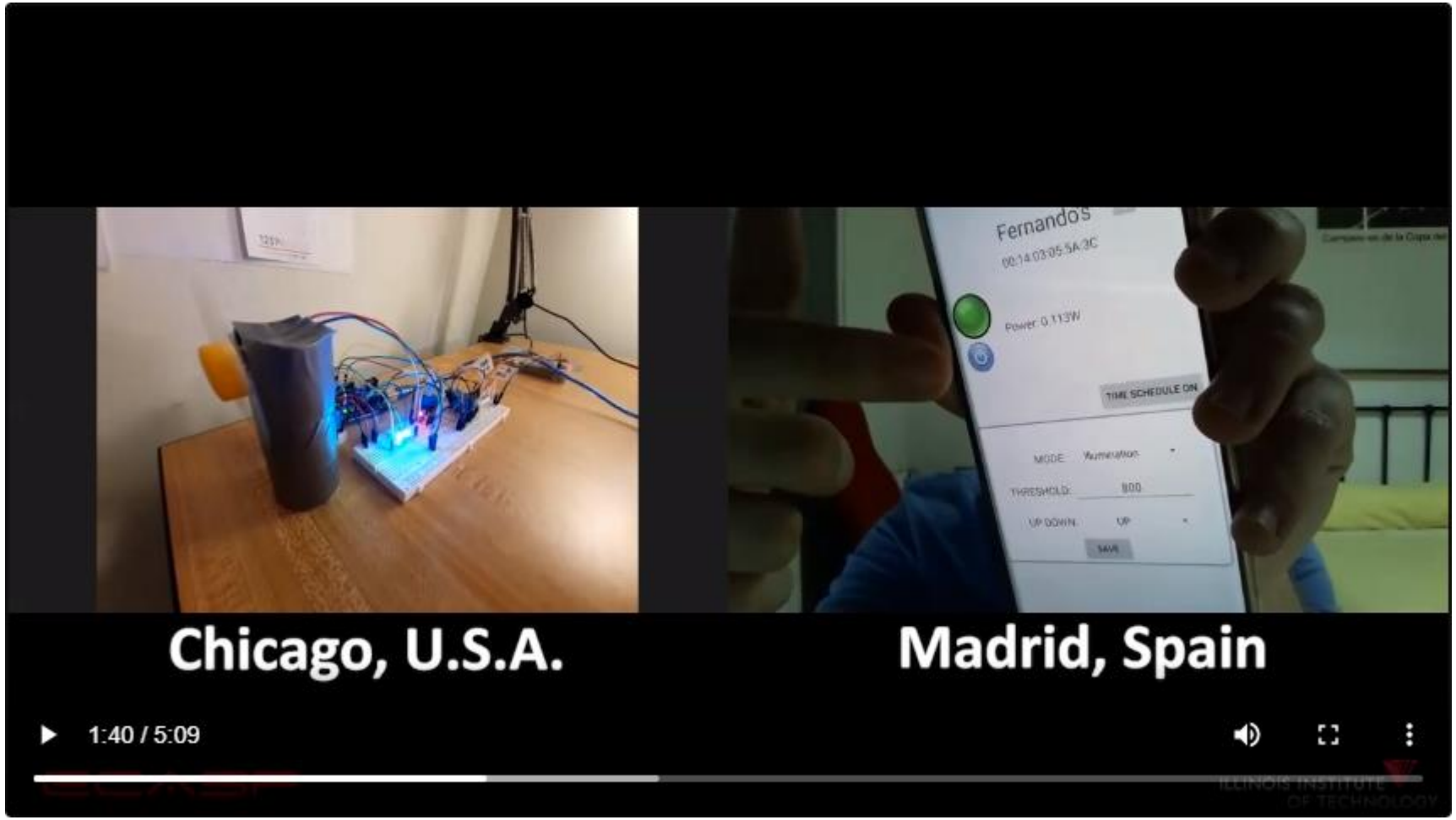
# Smart Socket General Architecture



# Smart Socket



# Smart Socket Demo:
# Remote Control Lights Across The Atlantic



# Thank You