

**ECE 442/510**

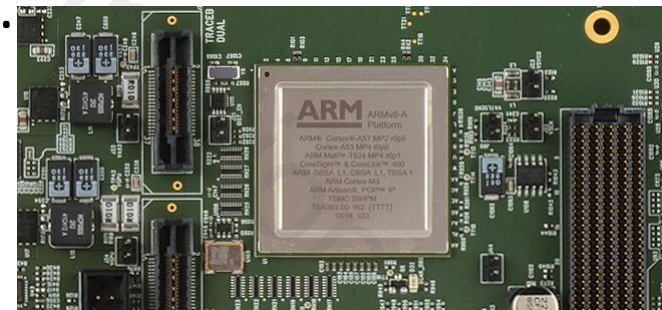
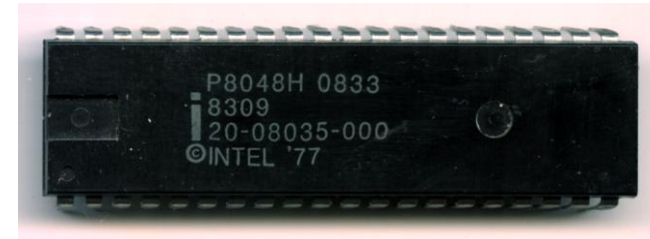
**Internet of Things and Cyber Physical Systems**

**Lecture 3: Design with Arduino & Lab 1**

**Summer 2022**

# What is a Microcontroller?

- Computer on a single integrated chip
  - CPU, Control Unit, Memory, Clock, I/O (see previous lecture notes)
- Common microcontrollers (to name a few...)
  - Atmel AT89, ATmega, AVR32, MARC4...
  - Freescale Semiconductor 68HCxx, 683xx...
  - Intel 8048, 8051, MCS-251, MCS-296...
  - Lattice Semiconductor Mico8, Mico32...
  - MSP430 - Microchip PIC10, PIC16, PIC24, PIC32...
  - ARM (from multiple manufacturers)
- Home appliances, Mobile devices, Automotive, Military, Gaming Consoles...



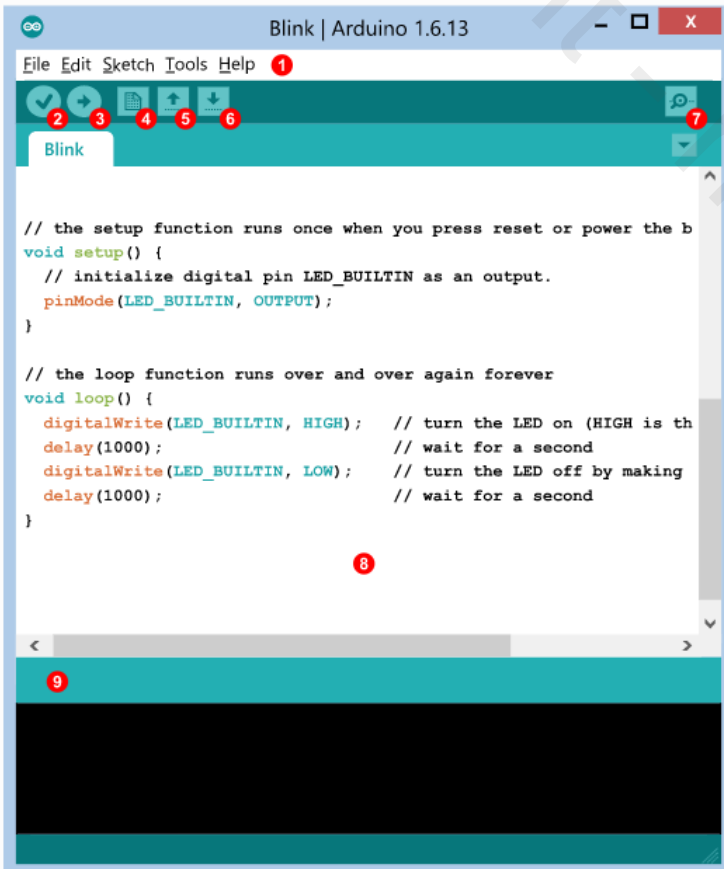
# What is an Arduino?

- A physical piece of hardware



# What is an Arduino?

- A programming environment



- 1 Menu: Selections of software features.
- 2 Verify: Compiles and verifies your sketch.
- 3 Upload: Send your sketch to STEMtera™ Breadboard.
- 4 New: Opens a new sketch window.
- 5 Open: Open and existing sketch.
- 6 Save: Save current active sketch.
- 7 Monitor: Opens a window to send and receive information.
- 8 Editor: Code editor area. Type your sketch in this area.
- 9 Message: IDE reports success or failure messages here.

# What is an Arduino?

- A community & philosophy



**Arduino Community Forums**

81 Arduino Forum

Using Arduino

| Category | Description  | Posts  | Topics |
|----------|--|--------|--------|
| +        | <b>Installation &amp; Troubleshooting</b><br>For problems with Arduino itself, NOT your project<br>Last post: Re: watch won't start u... by Criedhead on Today at 12:53:21 pm                    | 31921  | 6926   |
| +        | <b>Project Guidance</b><br>Advice on general approaches or feasibility<br>Last post: Re: Wake up arduino from RF... by eyco on Today at 01:22:31 pm  | 134095 | 18364  |
| +        | <b>Programming Questions</b><br>Understanding the language, error messages, etc.<br>Last post: Re: VC0006 PIC06 v1.0 Ca... by AWOL on Today at 01:41:37 pm                                       | 194840 | 22973  |
| +        | <b>General Electronics</b><br>Resistors, capacitors, breadboards, soldering, etc.<br>Last post: Re: Help with Arduino DA... by Criedhead on Today at 01:15:00 pm                                 | 70776  | 7611   |
| +        | <b>Microcontrollers</b><br>Standalone or alternative microcontrollers, in-system programming, bootloaders, etc.<br>Last post: Re: ATmega8 with xmega... by Tom Carpenter on Today at 01:44:43 pm | 33546  | 3688   |
| +        | <b>LEDs and Multiplexing</b><br>Controlling lots of inputs and outputs<br>Last post: Re: Control 8 x 7 Segmen... by daniel44 on Today at 11:43:40 am   | 25412  | 2979   |
| +        | <b>Displays</b><br>LCDs, OLEDs, PAL, NTSC, etc.<br>Last post: Need help with arduino L... by Criedhead on Today at 01:22:33 pm   | 21524  | 2779   |



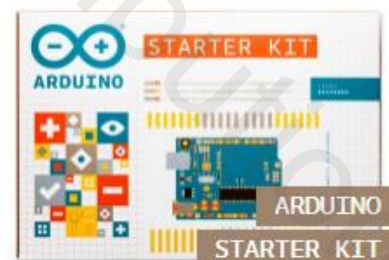
# Short History

- Initial team: Massimo Banzi, David Cuartielles, Tom Igoe, Gianluca Martino, David Mellis
- Influenced by *Processing* Development Environment and *Wiring* Programming Language
  - Simple, low cost tools for creating digital projects by non-engineers
- *Wiring* platform had ATmega168, an IDE based on *Processing* and library functions
- Arduino project forked from *Wiring* platform by adding support to ATmega8
- Adafruit Industries supplies Arduino boards and parts



# Various Types of Arduino

- Entry Level



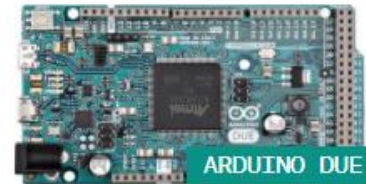
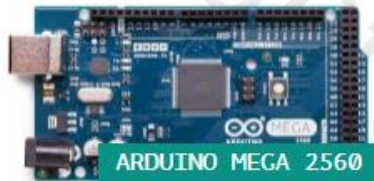
# Various Types of Arduino

- Arduino UNO
  - For general purpose development with electronics and coding
  - ATmega328, 5V, 14 Digital I/Os with 6 PWM channels
- Arduino Leonardo
  - Ideal for projects requiring the board to behave as a USB HID (human interface device)
  - ATmega32u4, 5V, 20 Digital I/Os with 7 PWM channels
- Arduino 101 (Intel Curie)
  - Intel x86 (Quark) & 32-bit ARC, 3.3V, 14 digital I/Os with 6 PWM channels
  - Bluetooth LE, 6-axis accelerometer/gyro
- Arduino Esplora
  - Arduino Leonardo based board with integrated sensors and actuators
  - ATmega32u4, 5V, analog joystick and 4 push buttons
- Arduino Micro, Nano, Mini
  - Smaller form factor, consumes reasonably less power



# Various Types of Arduino

- Enhanced Features



# Various Types of Arduino

- Arduino Mega 2560
  - Designed for more complex projects (3D printers and robotics)
  - ATmega2560, 54 digital I/Os with 15 PWM, 16 analog input pins
- Arduino Zero, M0/M0 Pro
  - Smart IoT devices, wearable technology, high-tech automation, etc.
  - 32-bit ARM Cortex M0, 20 digital I/Os, 6 12-bit ADC channels, 1 10-bit DAC channel
- Arduino Due
  - First Arduino board based on a 32-bit ARM core microcontroller
  - 32-bit ARM Cortex-M3, 54 digital I/Os, 12 analog inputs, 2 DAC
- Arduino MKR Zero
  - I<sup>2</sup>S (Inter-IC Sound) bus, SD for sound, music & digital audio data

# Various Types of Arduino

- Internet of Things



# Various Types of Arduino

- Arduino Yun/Ethernet
  - Specifically designed for IoT development
- Arduino Tian
  - Integrated TCP/IP Ethernet Controller
  - ATmega328, 14 digital I/Os, 6 analog inputs, microSD card reader
- Arduino Industrial 101
  - Small form-factor YUN designed for product integration
  - ATmega32u4, supports OpenWRT, built-in Wi-Fi,
- Arduino MKR 1000, FOX 1200, WAN 1300, GSM 1400
  - Ideal solutions for designing IoT devices with networking
  - 32-bit ARM Cortex-M0+
- Arduino Fio
  - Small and Li-Po battery ready for IoT devices
  - XBee-ready development board with ATmega328P

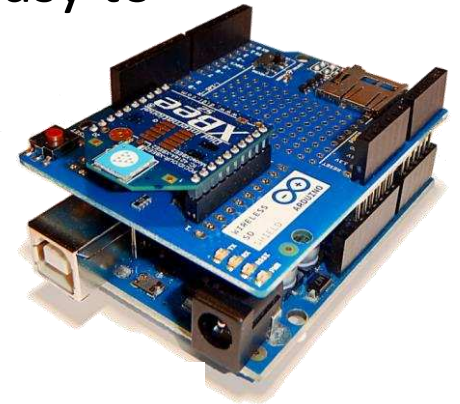
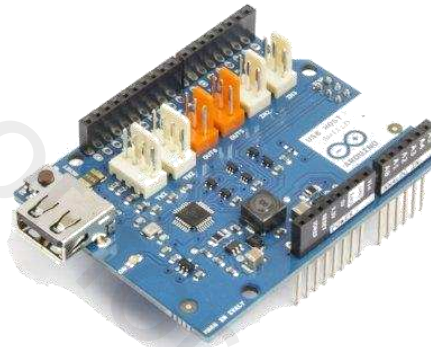
# Various Types of Arduino

|                    |  |
|--------------------|--|
| ENTRY LEVEL        | <div> <div>UNO</div> <div>LEONARDO</div> <div>101</div> <div>ESPLORA</div> <div>MICRO</div> <div>NANO</div> <div>MINI</div> <div>MKR2UNO ADAPTER</div> </div> <div> <div>STARTER KIT</div> <div>LCD SCREEN</div> </div>  |
| ENHANCED FEATURES  | <div> <div>MEGA</div> <div>ZERO</div> <div>DUE</div> <div>MEGA ADK</div> <div>MO</div> <div>MO PRO</div> <div>MKR ZERO</div> <div>MOTOR SHIELD</div> </div> <div> <div>USB HOST SHIELD</div> <div>PROTO SHIELD</div> <div>MKR PROTO SHIELD</div> <div>4 RELAYS SHIELD</div> </div> <div> <div>MEGA PROTO SHIELD</div> <div>MKR RELAY PROTO SHIELD</div> <div>ISP</div> <div>USB2SERIAL MICRO</div> </div> <div> <div>USB2SERIAL CONVERTER</div> </div> |
| INTERNET OF THINGS | <div> <div>YŪN</div> <div>ETHERNET</div> <div>TIAN</div> <div>INDUSTRIAL 101</div> <div>LEONARDO ETH</div> <div>MKR FOX 1200</div> </div> <div> <div>MKR WAN 1300</div> <div>MKR GSM 1400</div> <div>MKR1000</div> <div>YUN MINI</div> <div>YŪN SHIELD</div> <div>WIRELESS SD SHIELD</div> </div> <div> <div>WIRELESS PROTO SHIELD</div> <div>ETHERNET SHIELD V2</div> <div>GSM SHIELD V2</div> <div>MKR IoT BUNDLE</div> </div>                       |
| EDUCATION          | <div> <div>CTC 101</div> </div>  |
| WEARABLE           | <div> <div>GEMMA</div> <div>LILYPAD ARDUINO USB</div> <div>LILYPAD ARDUINO MAIN BOARD</div> <div>LILYPAD ARDUINO SIMPLE</div> </div> <div> <div>LILYPAD ARDUINO SIMPLE SNAP</div> </div>   |
| 3D PRINTING        | <div> <div>MATERIA 101</div> </div>  |



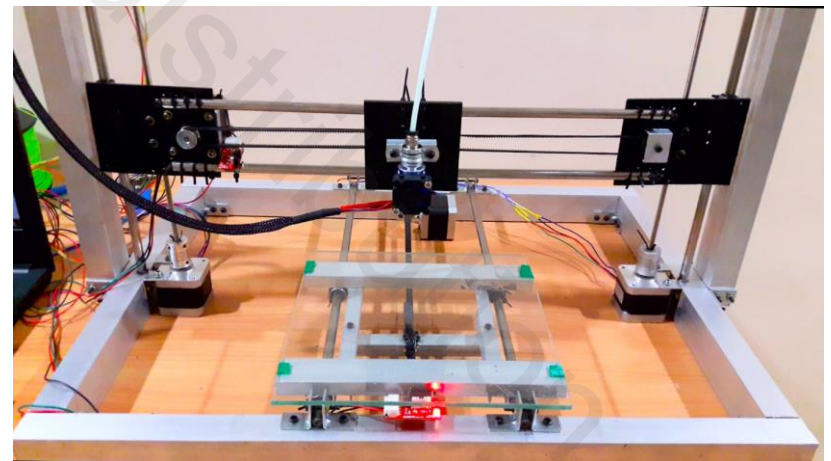
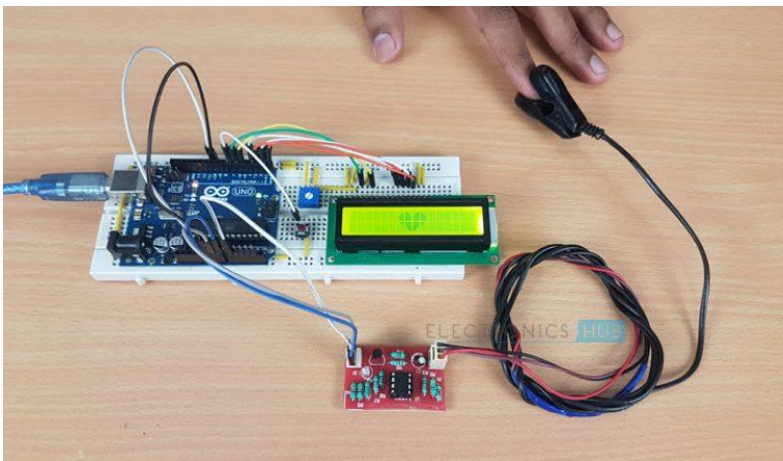
# Arduino Shields

- Boards that can be plugged on top of Arduino PCB extending its capabilities
- Different shields follow the same philosophy; easy to mount, cheap to produce
- TFT Touchscreen Shield
- Motor/Servo Shield
- Ethernet Shield
- Audio Wave Shield
- Cellular/GSM Shield
- Bluetooth/Wi-Fi Shield
- Proto-shield and many more...



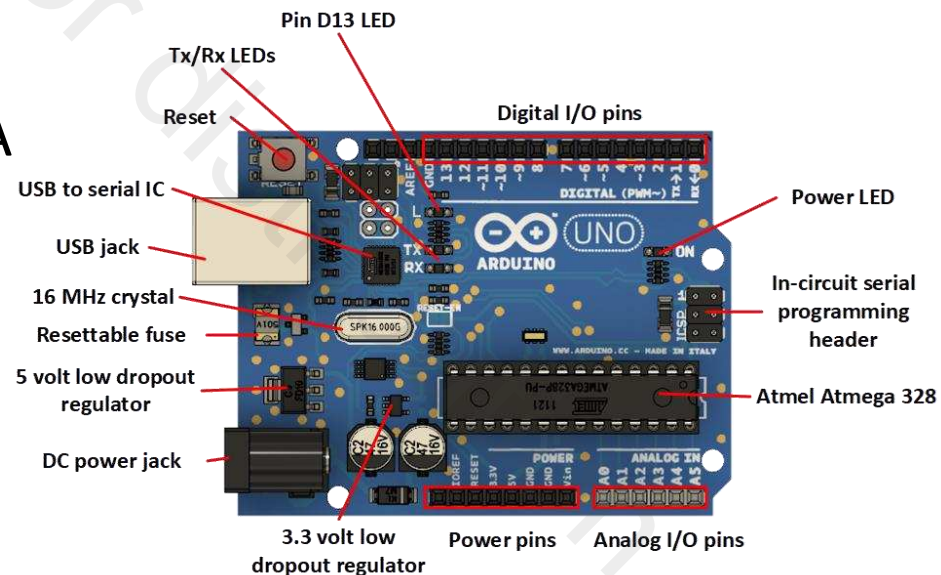
# Examples of Arduino Applications

- Home automation system (<https://tinyurl.com/ecasp-ha2018>)
- RC Car Remote-controlled via Bluetooth (<https://tinyurl.com/RCcarBT>)
- RGB Interior Car Lighting (<https://tinyurl.com/RGB-CarInterior-Arduino>)
- Robotic Arm Controller, Omni Wheel Robot (<https://tinyurl.com/ecasp-omni>)
- Irrigation Controller (<https://www.mysensors.org/build/irrigation>)
- Homemade 3D Printer (<https://all3dp.com/1/diy-arduino-3d-printer/>)
- Heartbeat monitoring system (<https://tinyurl.com/hbrsensor>)



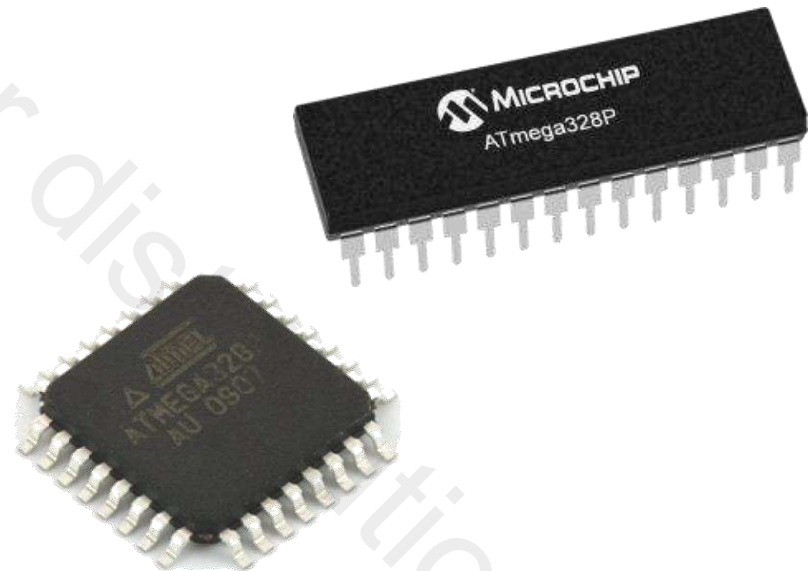
# Arduino UNO Hardware Specification

- Microcontroller: ATmega328P
- Operating Voltage: 5V
- Input Voltage(recommended): 7-12V
- Input Voltage(limits): 6-20V
- Digital I/O Pins: 14 (of which 6 provide PWM output)
- Analog Input Pins: 6
- DC Current per I/O Pin: 20mA
- DC Current for 3.3V Pin: 50mA
- Weight: 25g (0.88 oz)



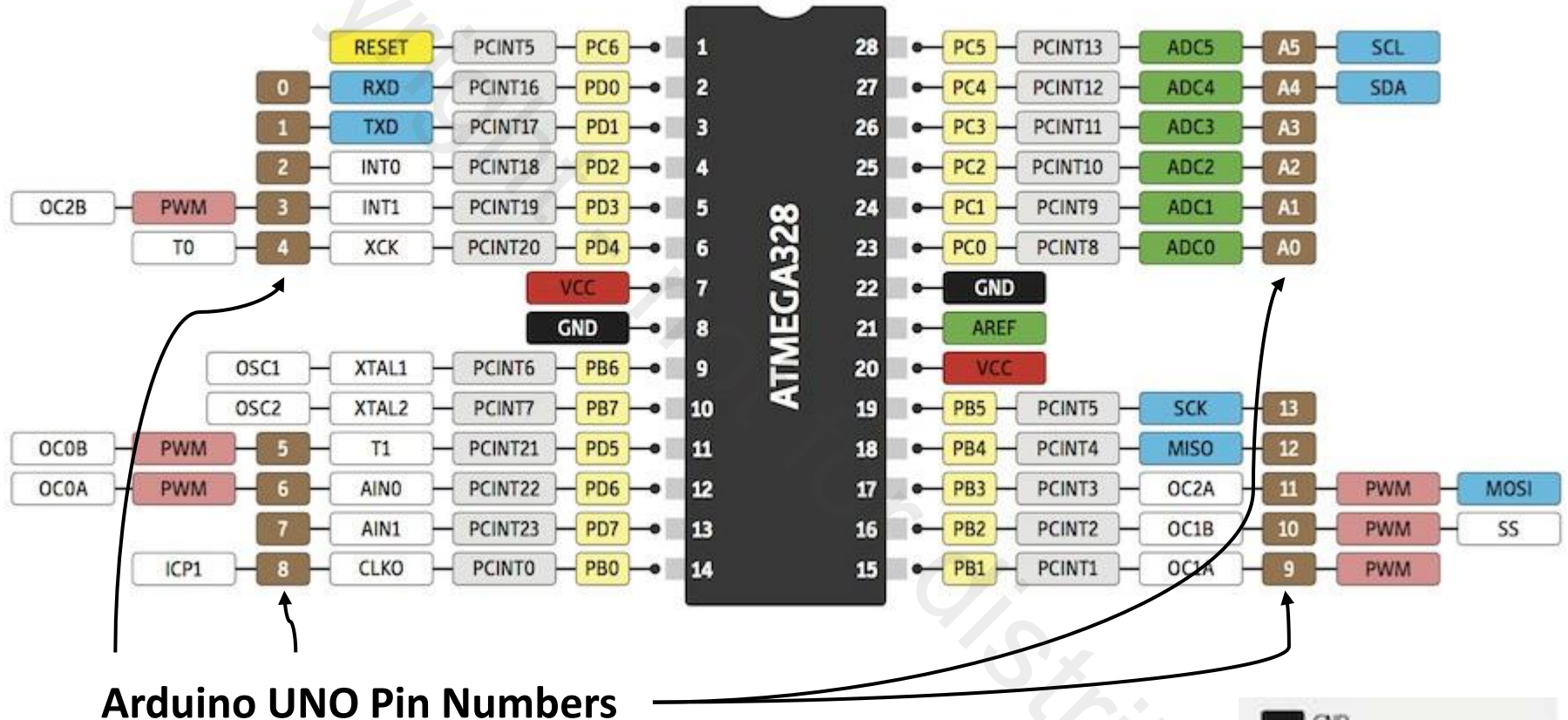
# ATmega328P Microcontroller

- AVR 8-bit RISC architecture
- 20 MIPS at 20 MHz
- 32 KB In-system programming (ISP) flash memory with read-while-write capabilities
  - ISP: a technique where a programmable device is programmed after the device is placed in a circuit board (no need to remove from circuit to re-program)
  - 0.5KB used by bootloader
- 1 KB EEPROM
  - Long-term data
- 2 KB SRAM
  - Temporary values, stack, etc.
- 23 programmable I/O channels
- 3 timers/counters
- 6 PWM outputs



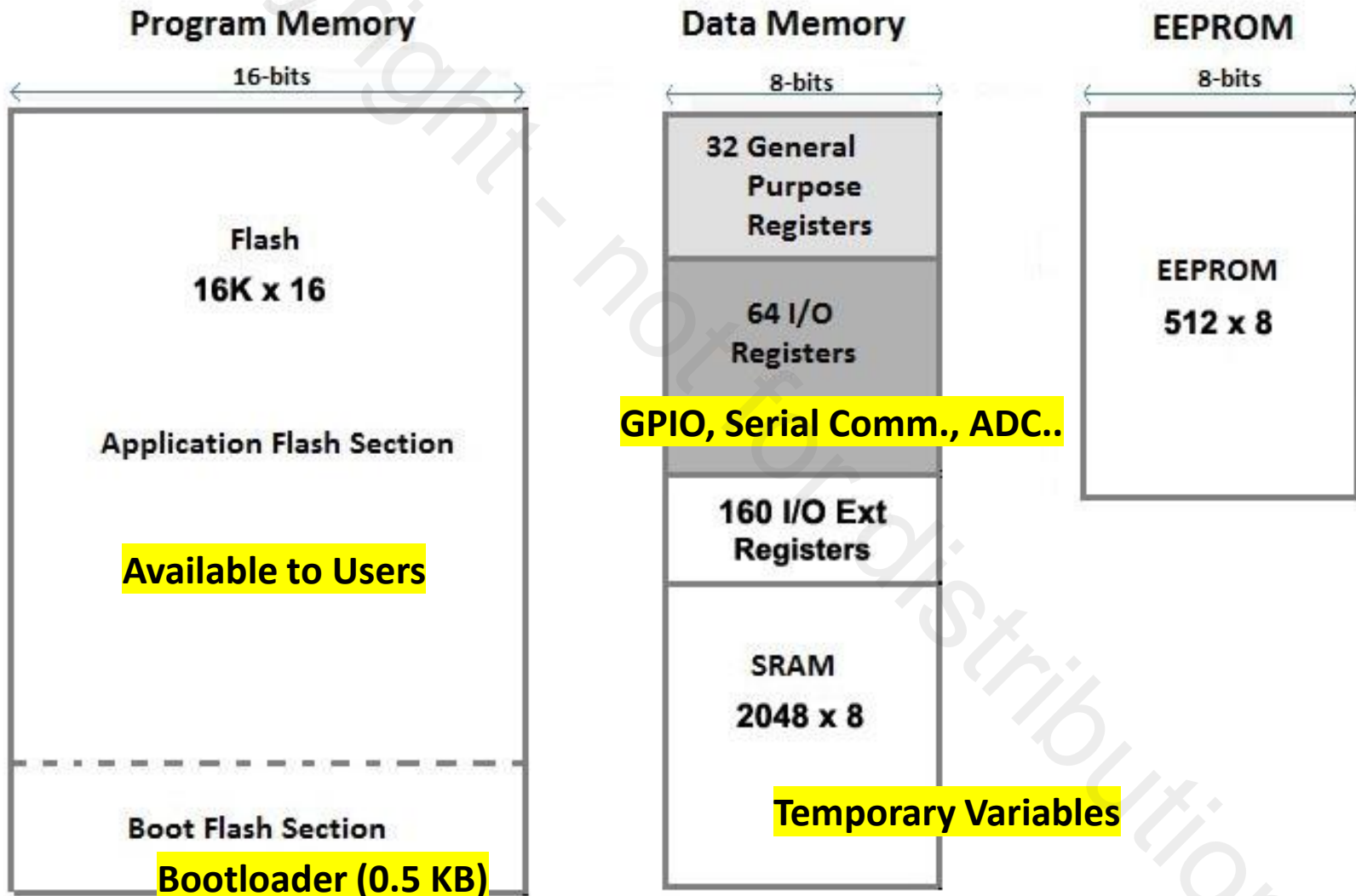


# ATmega328P Microcontroller

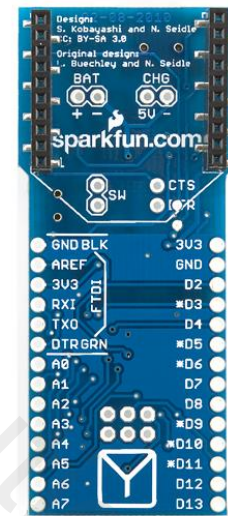
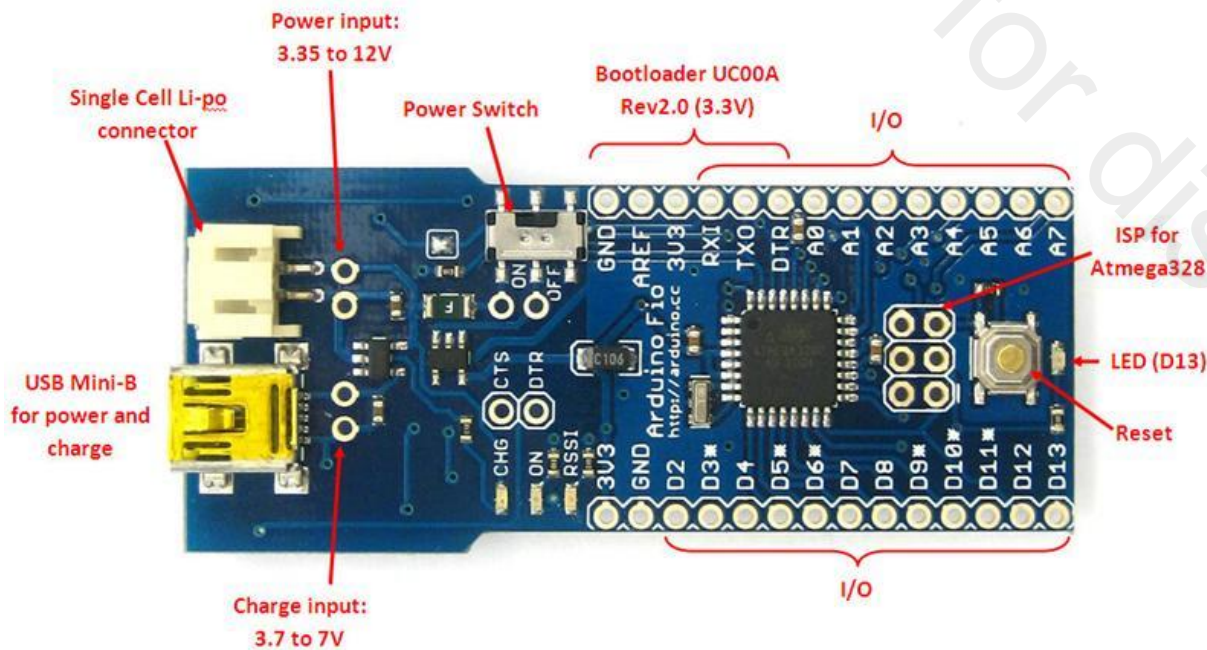
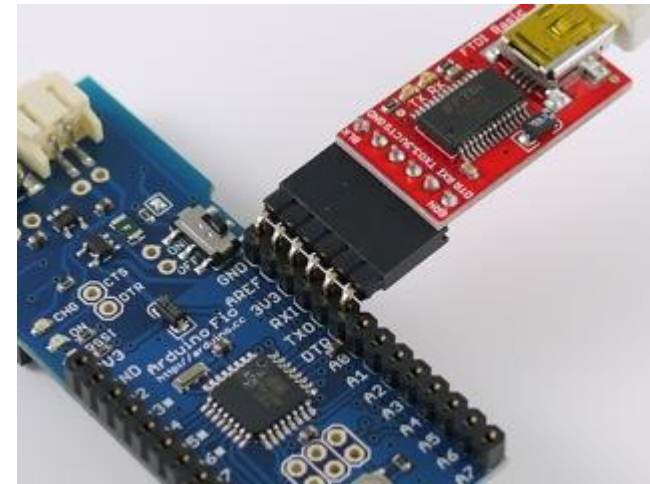
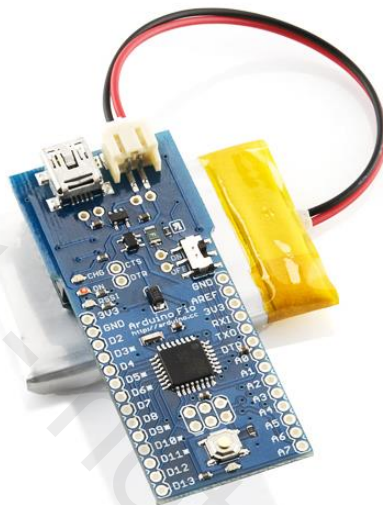




# ATmega328P Memory Map



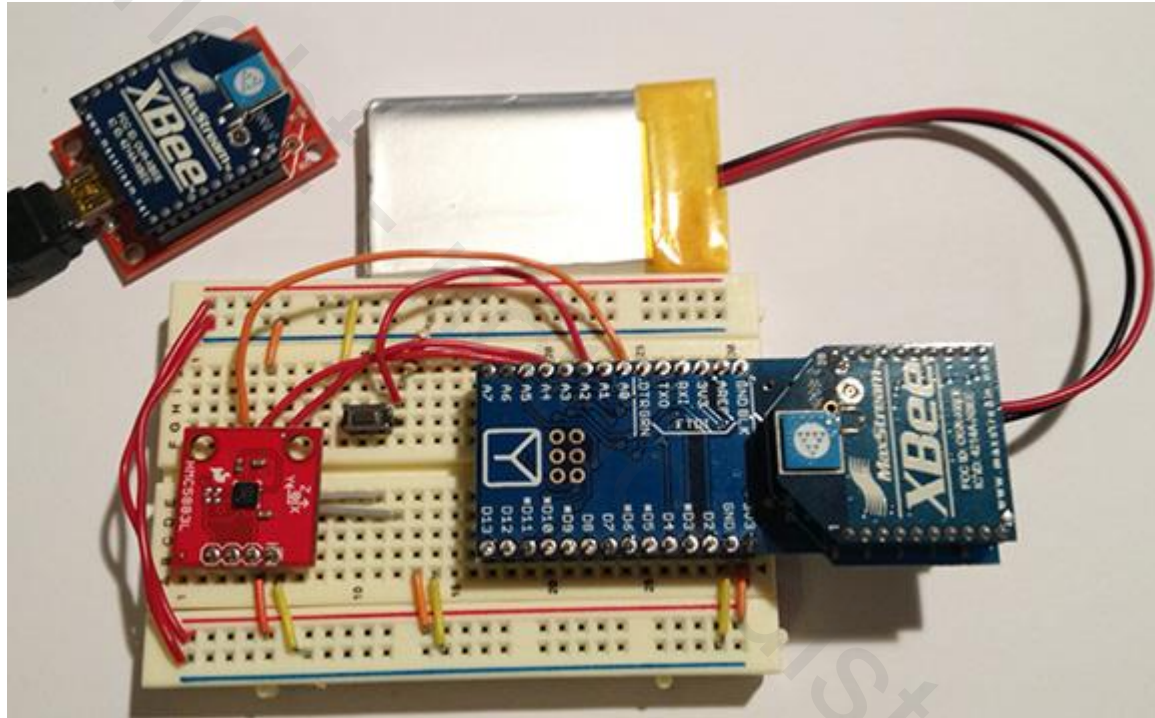
# Arduino Fio



# Arduino Fio Hardware Specification

- Microcontroller: ATmega328P at 8 MHz
- Operating Voltage: 3.3V
- Input Voltage: 3.35 – 12V
- Input Voltage for Charge: 3.7 – 7V
- Digital I/O Pins: 14 (of which 6 provide PWM output)
- Analog Input Pins: 8
- DC Current per I/O Pin: 40mA
- Flash Memory: 32KB (including 2KB for bootloader)
- Weight: 9g (0.32 oz)
- *Require a separate programmer attached to this board*

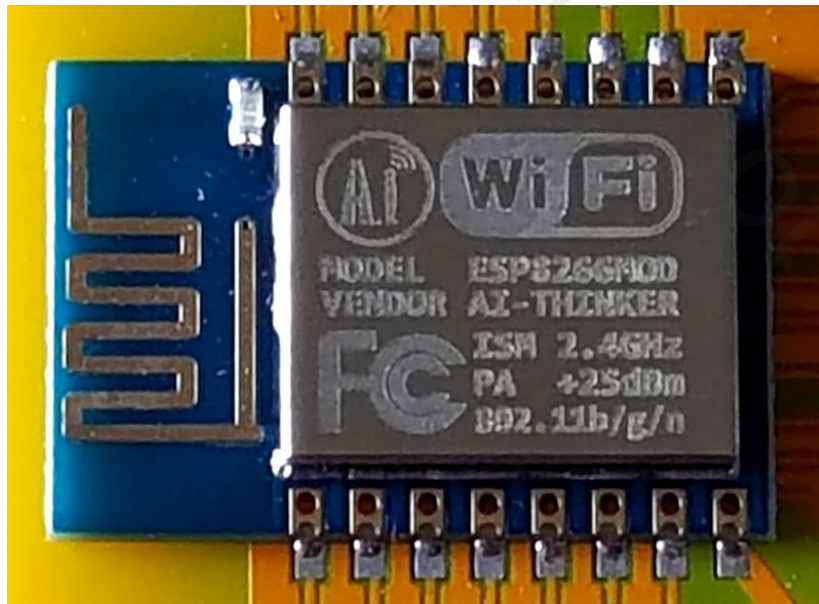
# Arduino Fio for XBee Communication



Simple Demo1: <https://www.youtube.com/watch?v=CdAWVDfQrB4>

Simple Demo2: <https://www.youtube.com/watch?v=w3RBKo6HO3w>

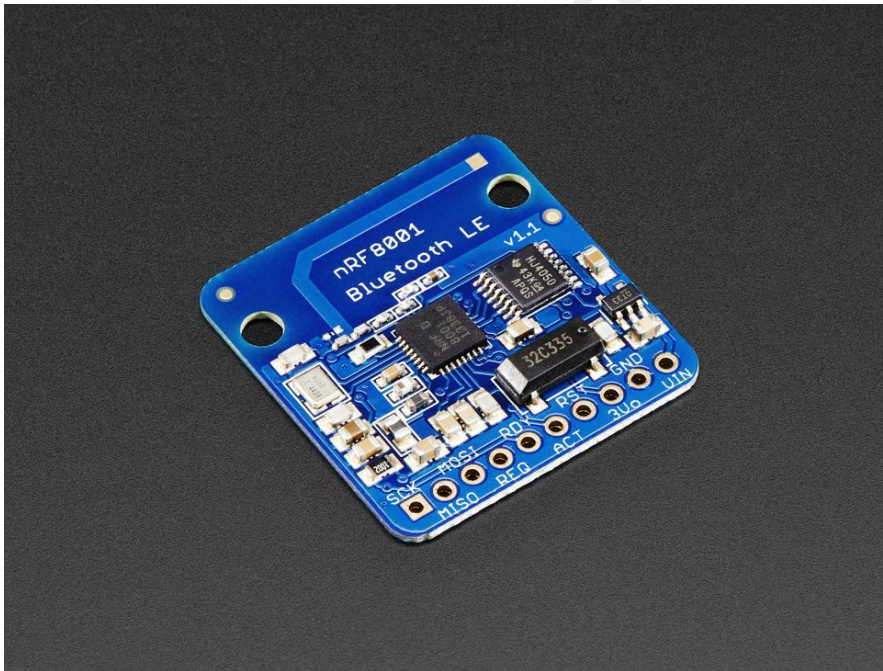
# Add Wi-Fi to Arduino



- Used in many IoT devices
- Cheap
- Easy to get (Amazon, Microcenter...)
- Easily can be added to any Arduino boards
- Shields are available as well

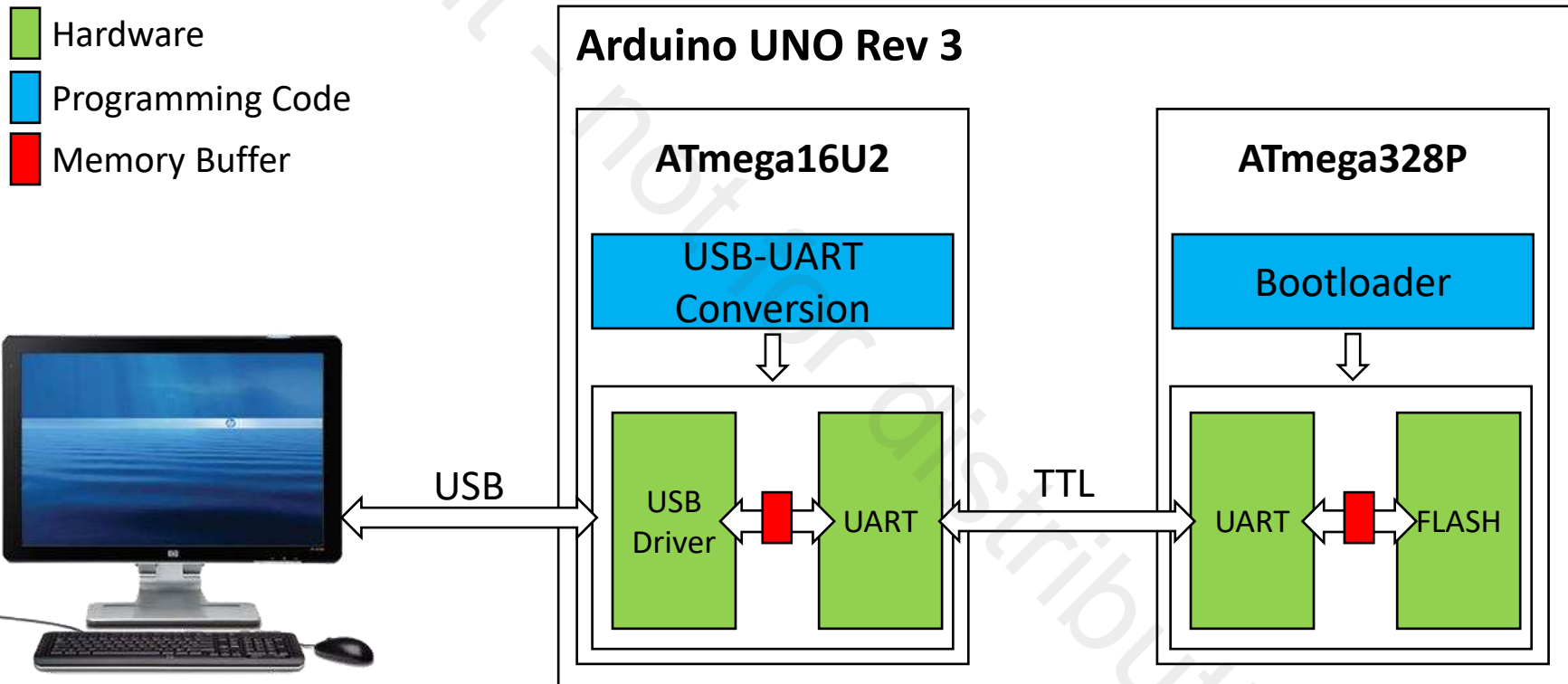


# Add Bluetooth LE to Arduino

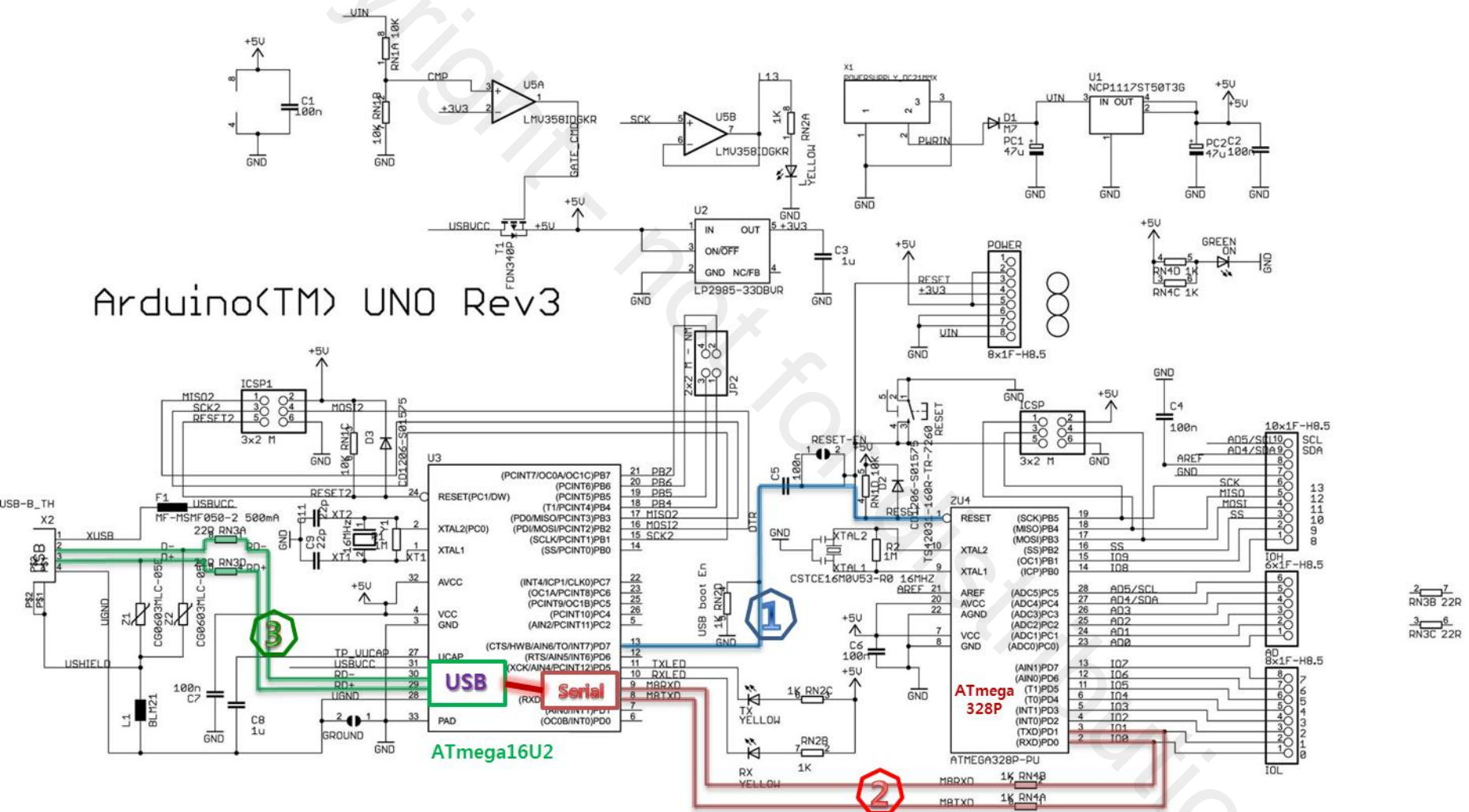


- nRF8001 Breakout
- Works between Arduino and any compatible iOS or Android (4.3+)
- Works by simulating a UART device, sending ASCII data
- Only \$20
- You could go for a shield

# Arduino UNO Upload Structure



Arduino(TM) UNO Rev3

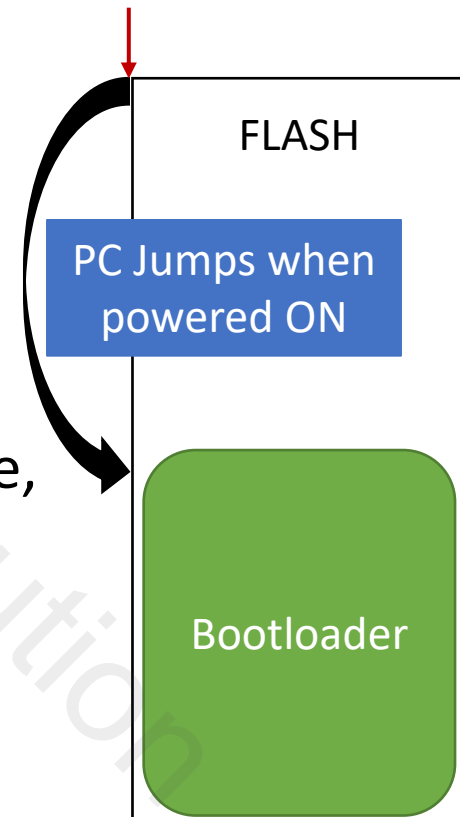


# Arduino UNO Upload Structure

- USB to UART Conversion on ATmega16U2 for assembly code from PC
  - Assembly code generated from compiling the *Arduino Sketch*
- Bootloader writes incoming assembly codes from serial communication onto the flash memory
- If a RESET signal is invoked, bootloader decides to write to flash or execute existing program
- When Arduino IDE uploads the sketch...
  - DTR signal is transmitted to the target microcontroller, and bootloader is executed (See (1) from previous slide)
  - Data including codes transmitted via UART(TTL) connection (See (2) from previous slide)
- When upload is complete...
  - Bootloader jumps to the uploaded program address after reset

# Bootloader

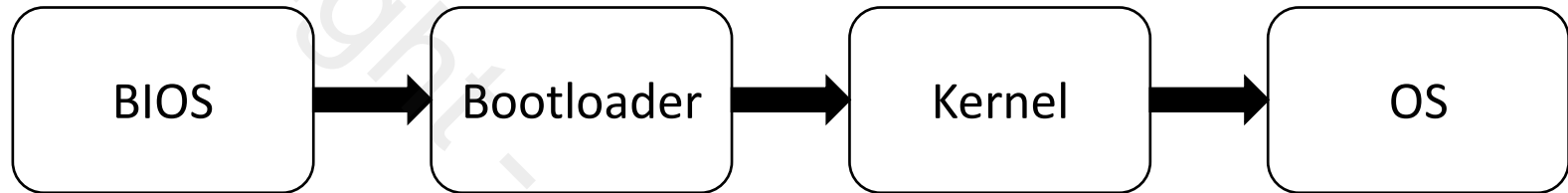
- A program that loads an operating system or the computer system when a computer is turned on
  - Bootloader is often called firmware mistakenly
  - Also called as boot manager or bootstrap loader
- Found in your laptop, desktop, smartphone, smartwatch, many embedded systems...
- A system software in the flash memory (ROM) that initializes all associated hardware, copies kernel to the memory (RAM), prepares the system for processing user commands
- Serial communication, interrupts, timer, console, memory, I/O peripherals, and others





# Bootloader

- Basic 'booting' sequence



- BIOS (Basic Input Output System) loaded from ROM
- BIOS calls bootloaders from all connected storage media sequentially
- **Bootloader prepares all hardware** before loading kernel
- After loading the kernel, framework is started, and UI is executed for the operating system
  - Kernel: where the commands are executed
  - Framework: delivers commands included in the program
  - UI: user interface, runs on top of kernel and framework
- Bootloader can be re-programmed by the user
  - For changing its original behavior due to changes on hardware/software, optimizations

# Bootloader - Examples

GNU GRUB version 2.02~beta2-9ubuntu1

\*Ubuntu

Advanced options for Ubuntu

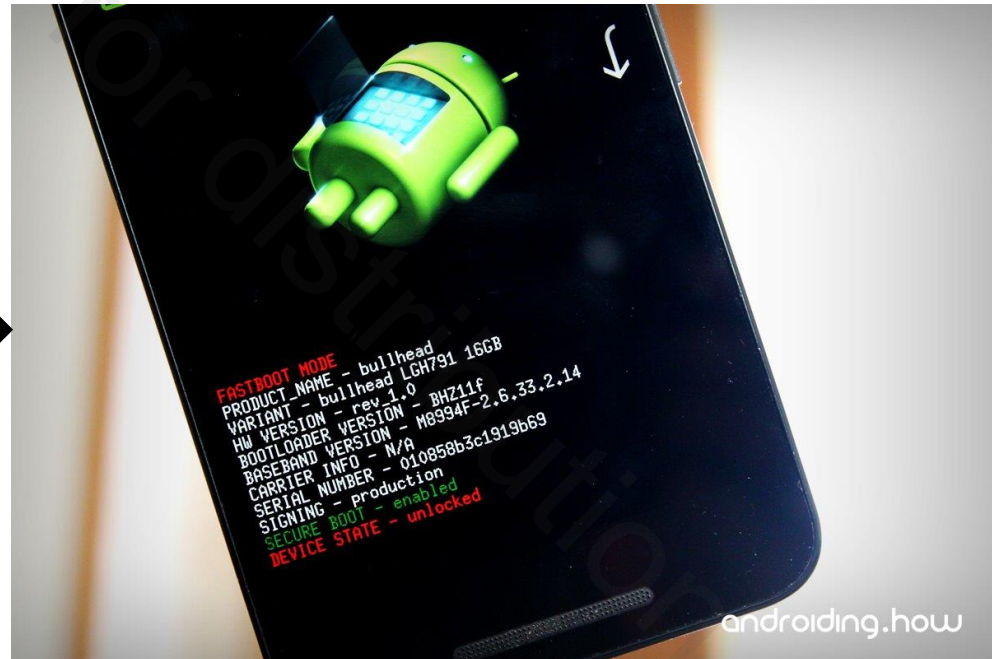
Memory test (memtest86+)

Memory test (memtest86+, serial console 115200)

Use the ↑ and ↓ keys to select which entry is highlighted.  
Press enter to boot the selected OS, 'e' to edit the commands  
before booting or 'c' for a command-line.

GNU GRUB Bootloader

Android Bootloader



# Bootloader - Examples

Windows 7 Boot Manager



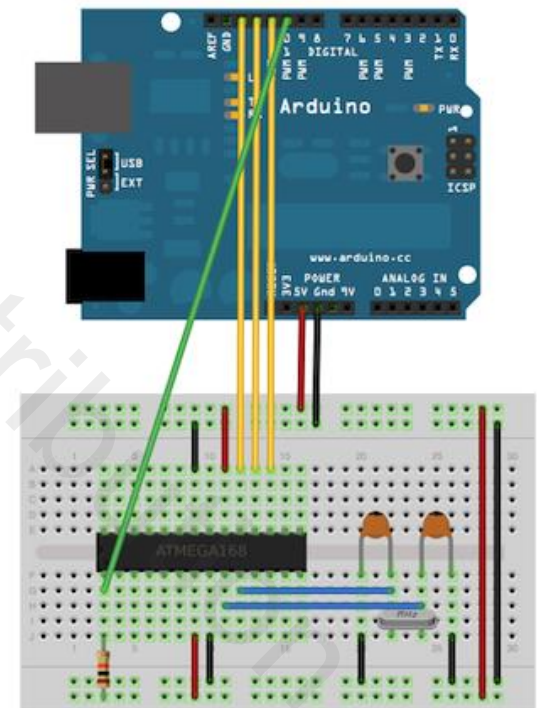
Choose an operating system



Windows 10 Boot Manager

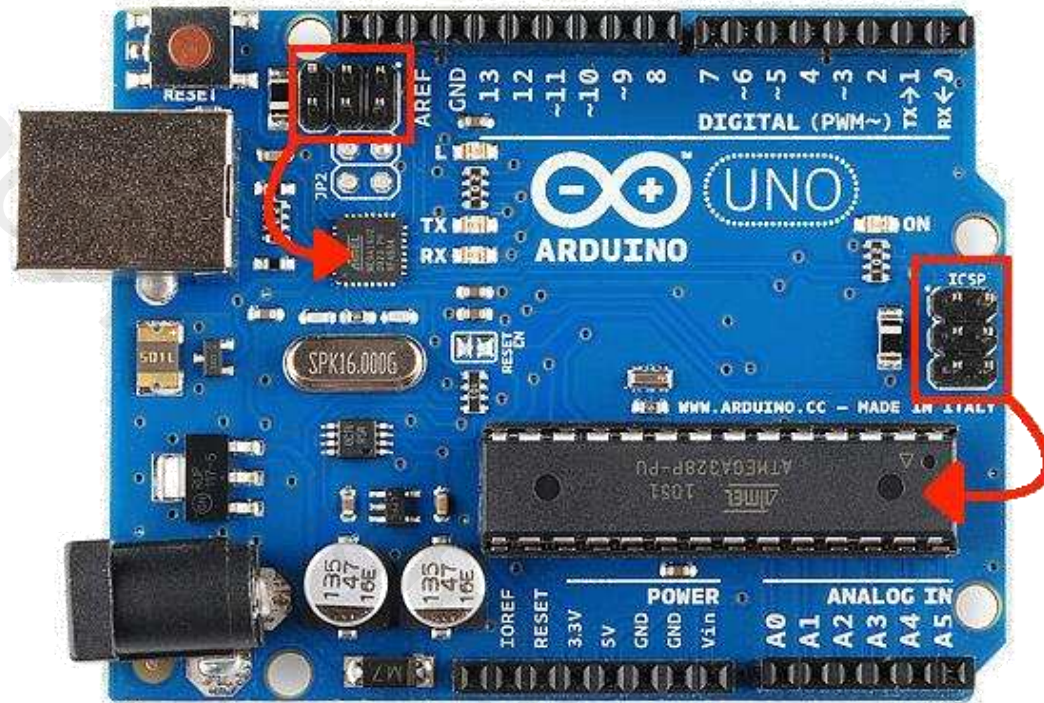
# Arduino Bootloader

- Allows installing new firmware without the need of an external programmer
- Initializes the microcontroller for running existing program or for flashing new program to the memory
- May be reprogrammed by...
  - AVR Studio, Arduino IDE
  - Arduino board as ISP
- When do you need to reprogram?
  - Corrupted or needed upgrade
  - New chip that doesn't contain bootloader



# Arduino Bootloader

- Two ICSP (in-circuit serial programming) headers
- Reflashing firmware of USB interface chip (ATmega16u2), use ATmega16u2 ICSP headers
- Reflashing bootloader, use ATmega328 ICSP headers
- Pins are SPI Pins (MISO, MOSI, SCK), Vcc, GND and Reset





# **Lab 1**

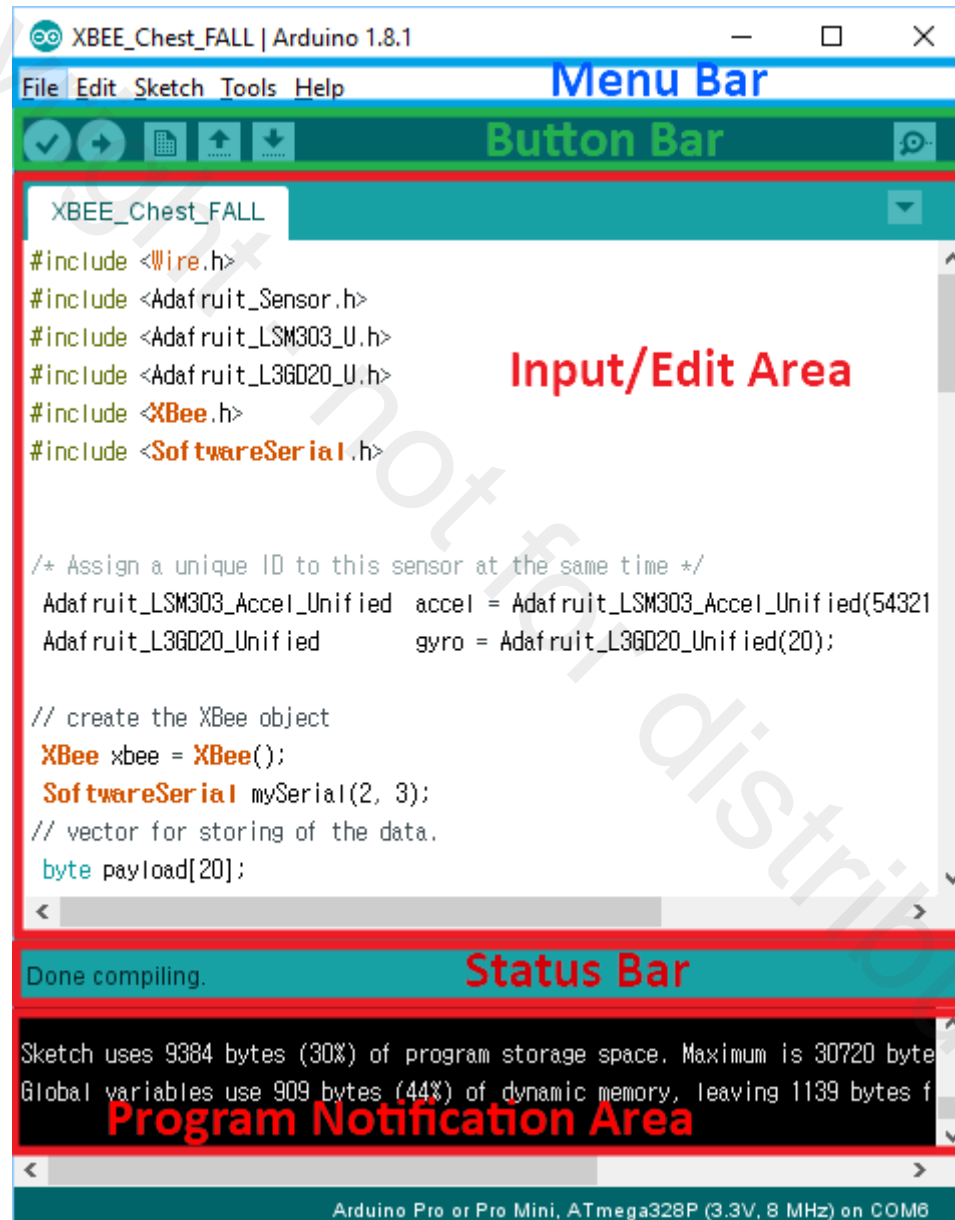
## **Traffic Light Controller**

### **Implementation using Arduino**

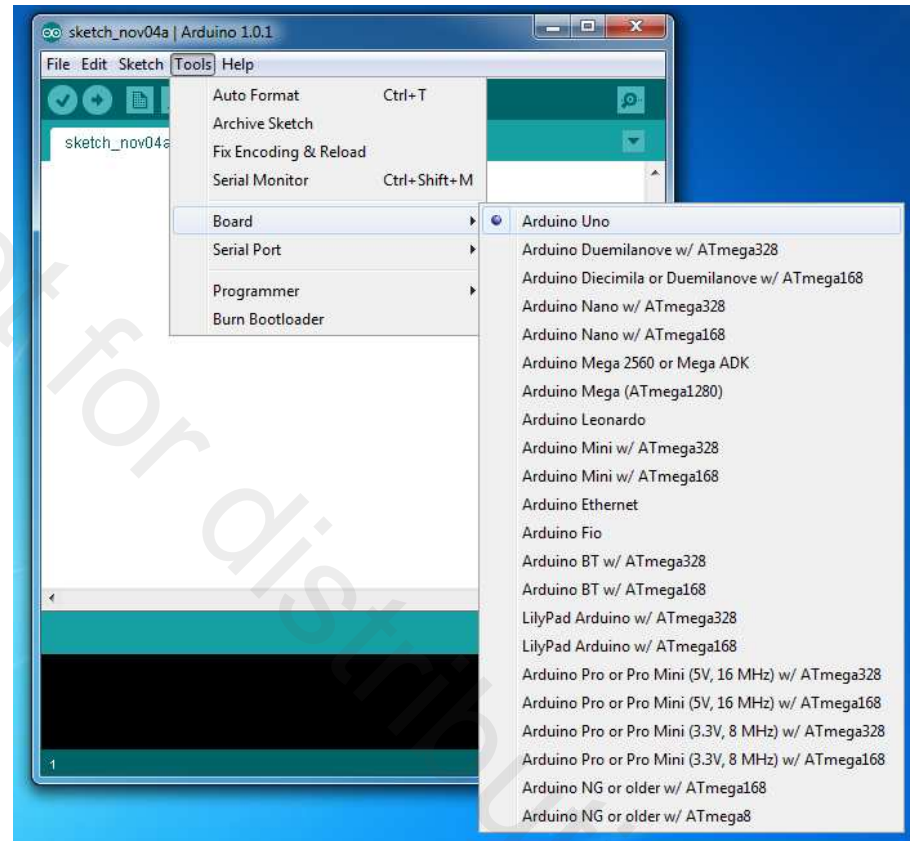
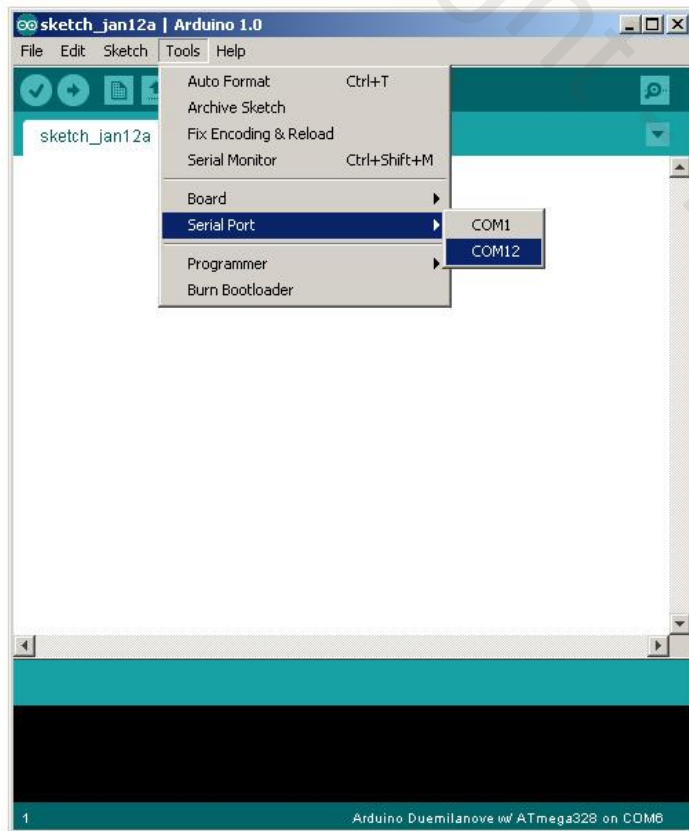
#### **UNO**

Lab explanation for Arduino  
<https://youtu.be/ZFMq9okTc3k>

# Arduino IDE



# Select Serial Port and Board



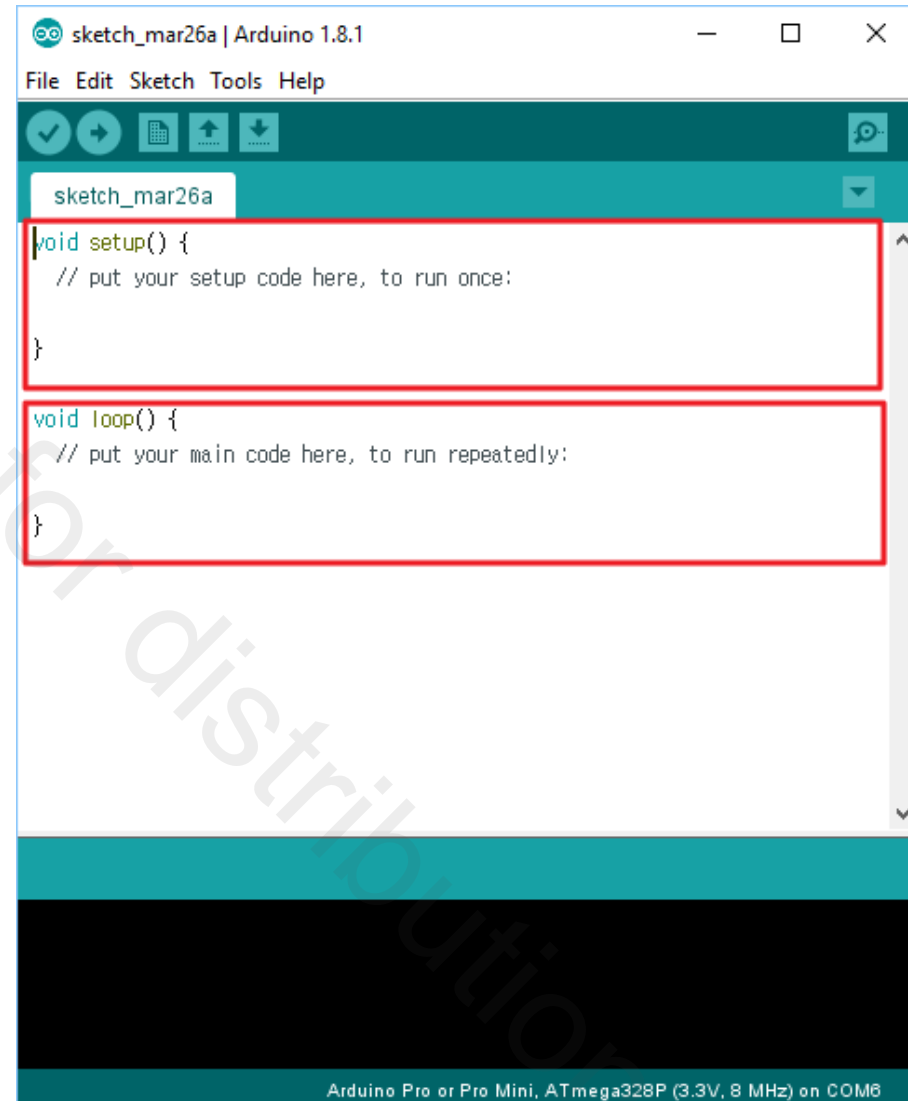
# Arduino Programming Sequence

- Write your sketch/program
- Compile your sketch (to check for errors)
- Upload your sketch to the Arduino board via USB cable
- Verify your result on Arduino or Serial Monitor



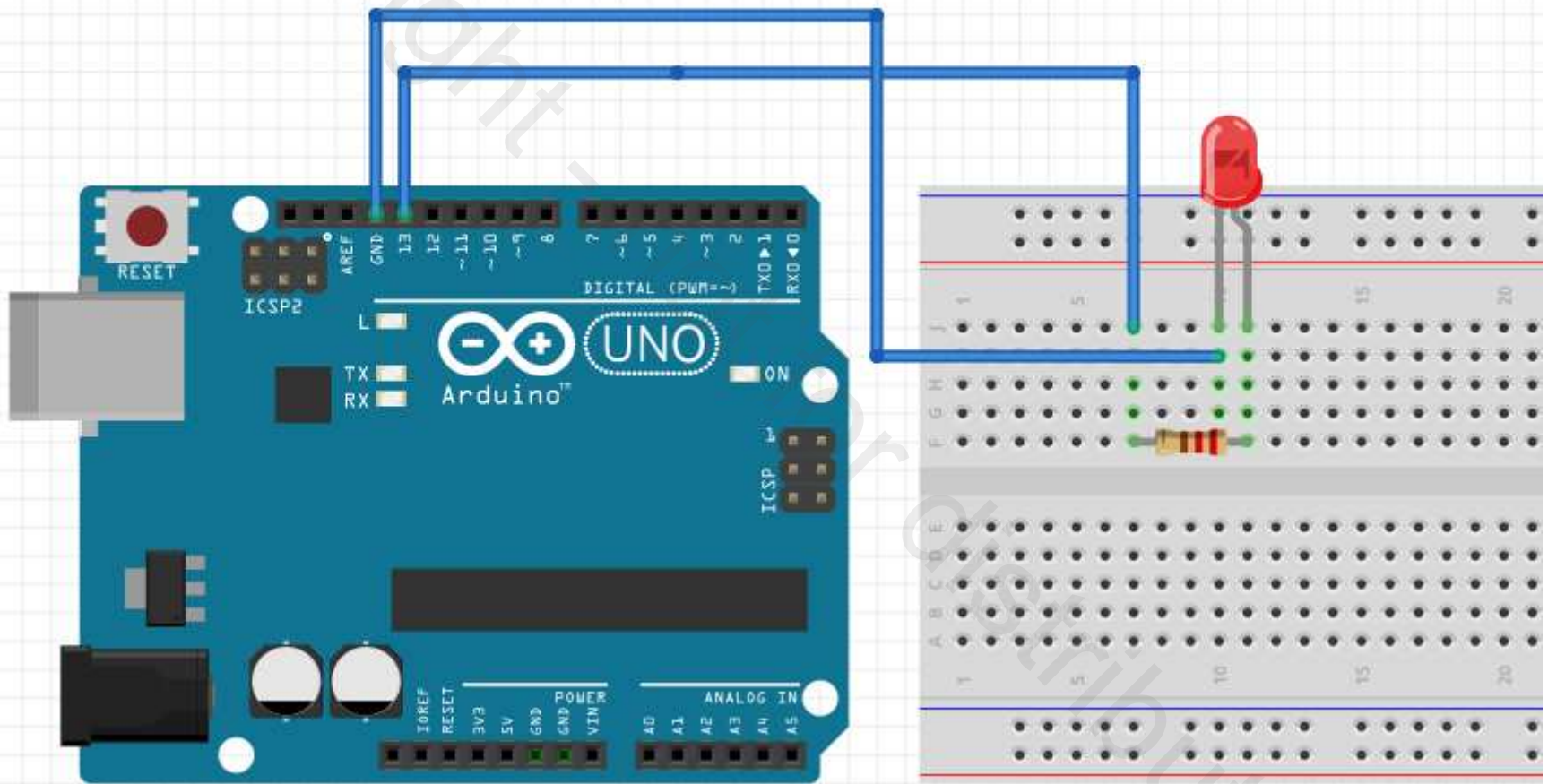
# Arduino Programming

- Case sensitive
- Statements are commands
- Must end with a semi-colon
- Comments follow a “//” or begin with /\* and end with \*/
  - Same as C programming
- void setup()
  - Will be executed only when the program begins (or reset button is pressed)
  - Initializations for communications, variables, I/Os...
- void loop()
  - Will be executed repeatedly
  - Program behavior





# Programming Example – LED Blink



# Programming Example – LED Blink

- `pinMode(pin, mode)`
  - pin: pin number on the board
  - mode: INPUT, OUTPUT, INPUT\_PULLUP
- `digitalWrite(pin, value)`
  - pin: pin number on the board
  - Value: HIGH or LOW
- `delay(value)`
  - value: milliseconds
- Initializes Pin #13 as OUTPUT
- Writes HIGH to Pin #13
- Waits for 1000ms (1s)
- Write LOW to Pin #13
- Waits for 1000ms (1s)
- LED will blink every 1 second

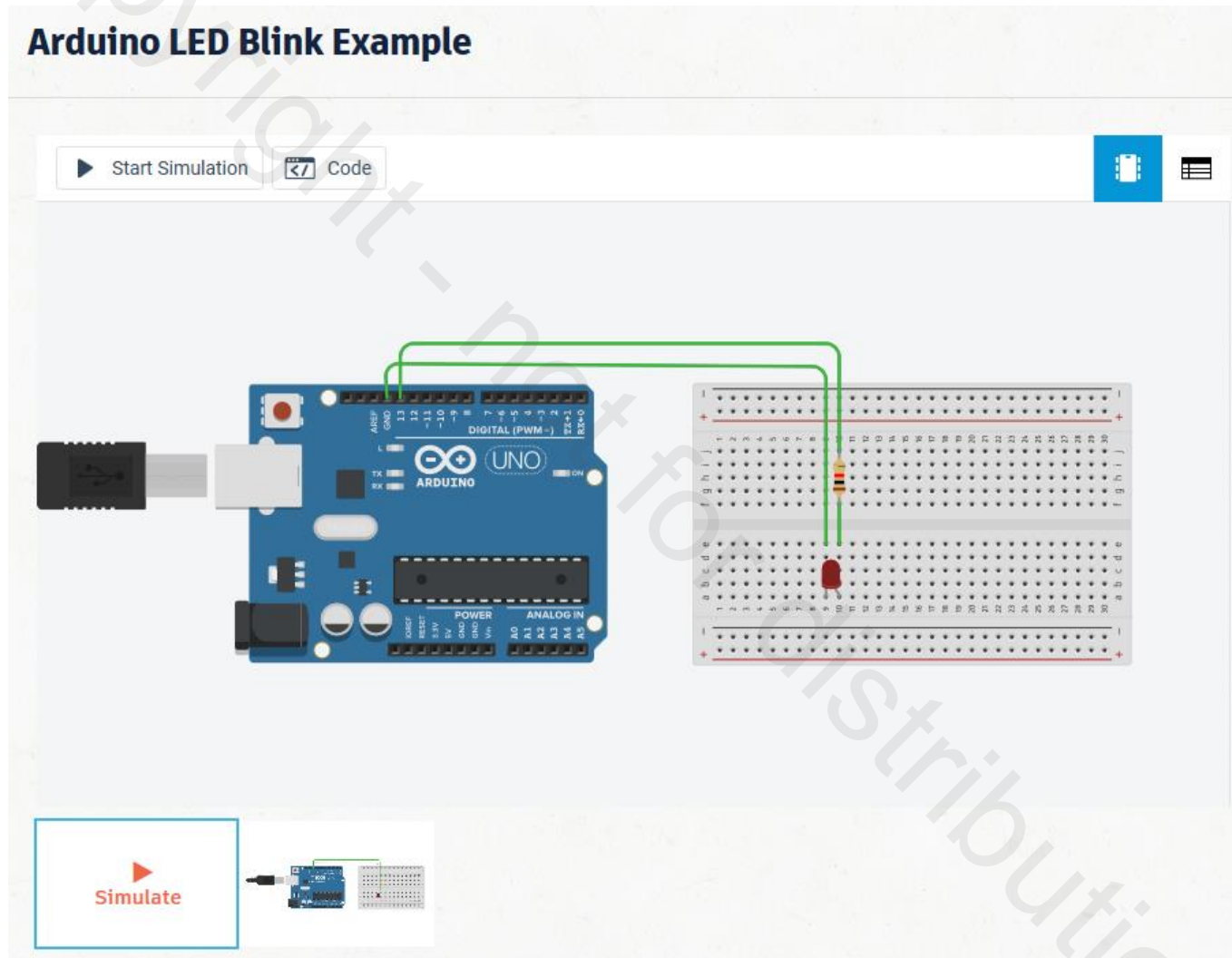
A screenshot of the Arduino IDE interface. The window title is "Blink | Arduino 1.8.1". The menu bar includes "File", "Edit", "Sketch", "Tools", and "Help". The toolbar shows icons for opening, saving, and running. The sketch name "Blink" is displayed in the top left of the editor. The code is as follows:

```
// the setup function runs once when you press reset or power the board
void setup() {
  // initialize digital pin LED_BUILTIN as an output.
  pinMode(13, OUTPUT);
}

// the loop function runs over and over again forever
void loop() {
  digitalWrite(13, HIGH);  // turn the LED on (HIGH is the voltage level)
  delay(1000);             // wait for a second
  digitalWrite(13, LOW);   // turn the LED off by making the voltage LOW
  delay(1000);             // wait for a second
}
```

The status bar at the bottom indicates "21" and "Arduino Pro or Pro Mini, ATmega328P (3.3V, 8 MHz) on COM6".

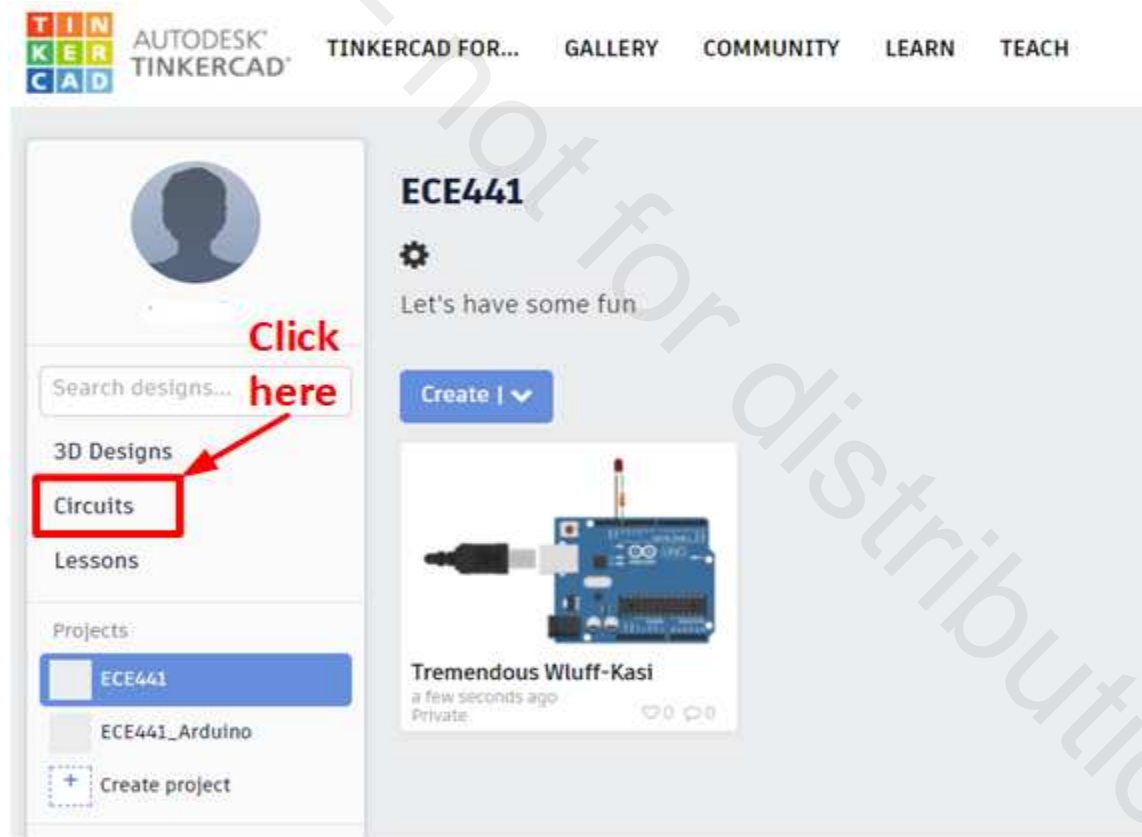
# Programming Example – LED Blink



<https://www.tinkercad.com/things/9bv1Y2v2Ea8>

# TinkerCAD

- Go to the website: <https://www.tinkercad.com>
- Register for Autodesk account using your Illinois Tech email address
- Click “Circuits” on the left panel



# TinkerCAD

- Click **Create** -> **Circuit** -> **+ Component** and add **Arduino Blink** from the **Starters** Tab.





# TinkerCAD

- Go to “**Code Editor**” and disable “**Block**” function since we don’t want to program it using the block diagram. Read the C code to gain a better understanding of the program flow.

The screenshot displays the TinkerCAD web interface with several key elements highlighted by red boxes and numbered circles:

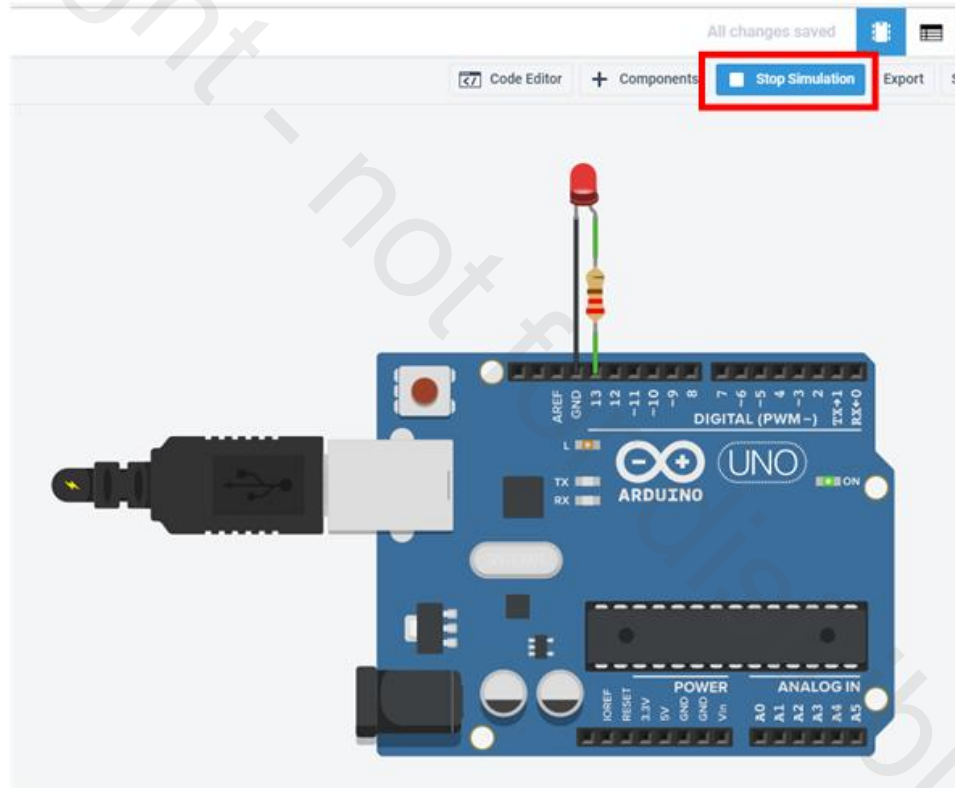
- 1**: The **Code Editor** tab in the top right corner.
- 2**: The **Block** button in the bottom left corner.
- 3**: A confirmation dialog box asking, "Are you sure that you want to close the blocks editor? Any blocks that you currently have will be lost. The code in the text editor will remain and become editable." with **OK** and **Cancel** buttons.
- 4**: The **Read and understand the C Code** text, pointing to the C code editor window.

The C code in the editor is as follows:

```
1  /*  
2  This program blinks pin 13 of the Arduino rthe  
3  built-in LED  
4  */  
5  
6  void setup() {  
7    pinMode(13, OUTPUT);  
8  }  
9  
10 void loop() {  
11  
12    // turn the LED on (HIGH is the voltage level)  
13    digitalWrite(13, HIGH);  
14    delay(1000); // Wait for 1000 milliseconds  
15    // turn the LED off by making the voltage LOW  
16    digitalWrite(13, LOW);  
17    delay(1000); // Wait for 1000 milliseconds  
18  }  
19
```

# TinkerCAD

- Click **“Start Simulation”** and observe the result.



# I/Os in Arduino UNO

- Analog I/O
  - Built-in ADC (Analog-to-Digital Converter) allows analog inputs into a digital value (Analog IN Pin #A0 to Pin #A5)
  - Absence of DAC (Digital-to-Analog Converter), PWM (Pulse-Width Modulator) can achieve some of the functions of an analog output
  - Libraries associated with each analog input and output
- Digital I/Os
  - GPIO. Input and output of HIGH and LOW values
  - Three (digital) serial communication protocols on Arduino UNO to interface with peripherals
  - Digital I/O Pin #0 to #13 on Arduino UNO
  - UART, SPI, I<sup>2</sup>C depending on the type of the peripherals
  - Libraries associated with each communication protocols
  - Initialize, data transmit, read/write from/to device

# Analog I/O

- `analogRead(pin)`
  - Converts value of the voltage on an analog input pin to digital
  - Returns a digital value from 0 to 1023 (Resolution: 10-bit ADC)
  - Reference is 5V on most Arduinos including Arduino UNO
  - 7V on Arduino Mini, Nano
  - 15V on Arduino Mega
- `analogWrite(pin, value)`
  - Output a PWM square wave signal to Pins #3, #5, #6, #9, #10, #11
  - Value from 0 to 255 (Resolution: 8-bit) compared against an 8-bit counter value
  - Output pin will be HIGH from counts 0 to *value*, LOW from counts *value*+1 to 255
  - Frequency of PWM signal on most pins approximately 490 Hz
  - Pins #5, #6 have 980 Hz on UNO, Pins #3, #11 on Leonardo

# Analog I/O - Example

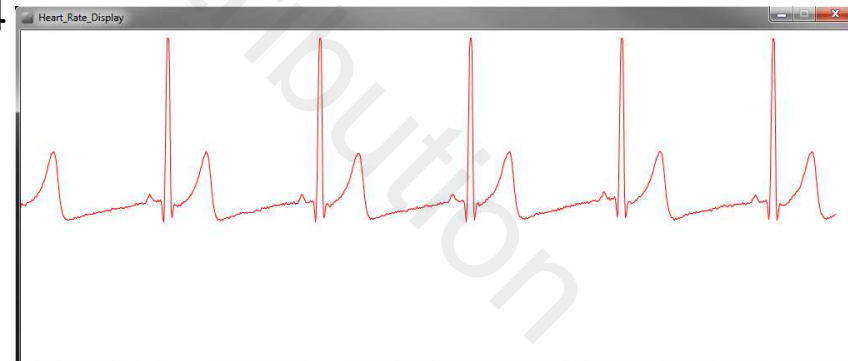
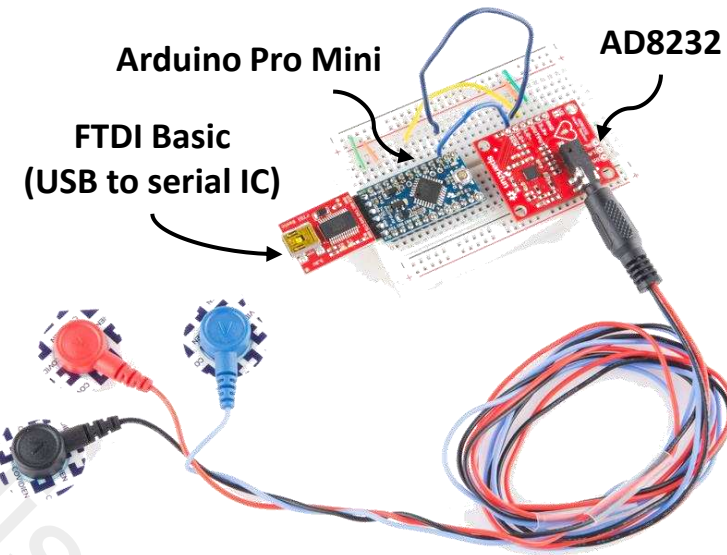
- AD8232 Heart Monitor (ECG Sensor)



AD8232

| Board Label | Pin Function       | Arduino Connection |
|-------------|--------------------|--------------------|
| GND         | Ground             | GND                |
| 3.3V        | 3.3V Power Supply  | 3.3V               |
| OUTPUT      | Output Signal      | A0                 |
| LO-         | Leads-off Detect - | 11                 |
| LO+         | Leads-off Detect + | 10                 |
| SDN         | Shutdown           | Not used           |

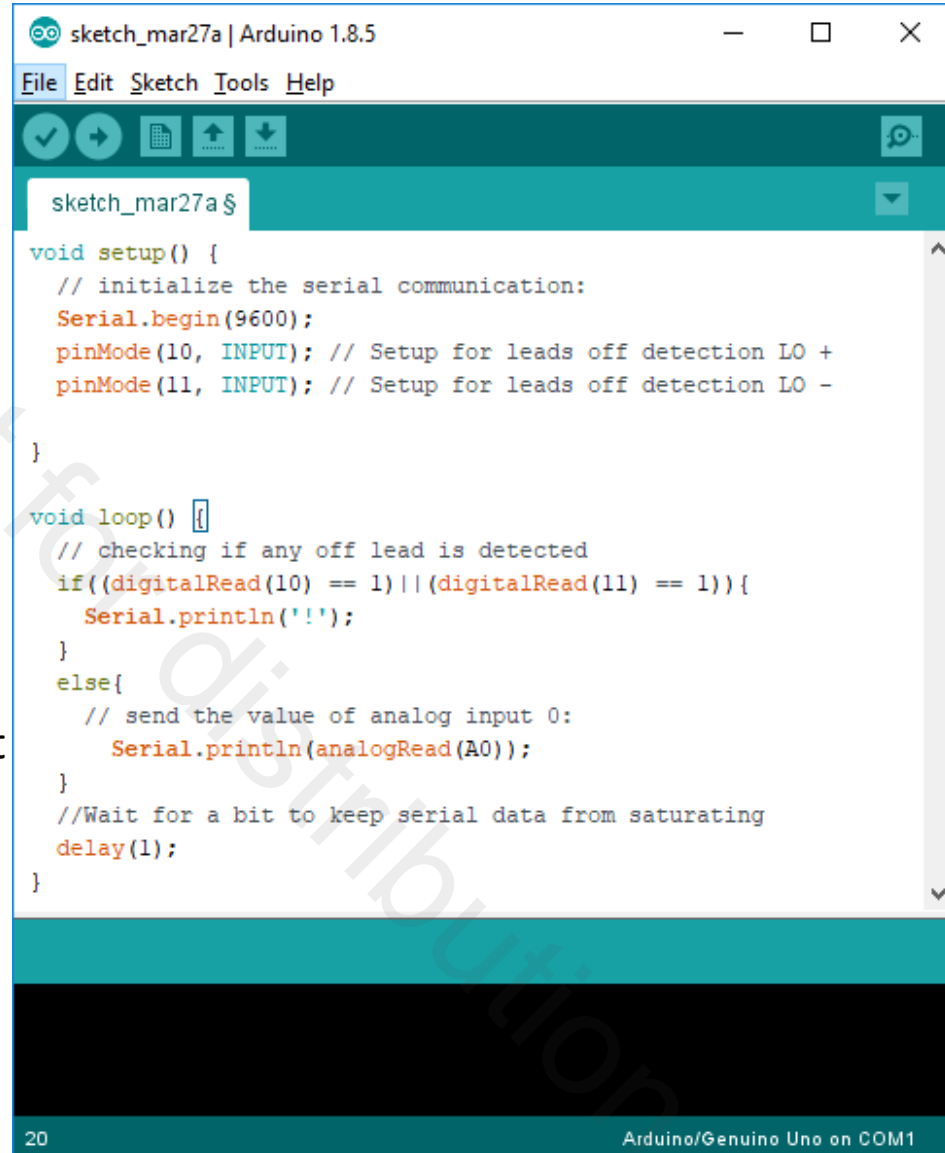
- Generates ECG (Electrocardiogram) signal from 3 lead electrode pads
- Output is an analog signal, Arduino board will convert to value between 0 to 1024





# Analog I/O - Example

- Class Serial in Arduino
  - Digital Pin #0 (Rx) #1 (Tx), USB connection
  - Use built-in serial monitor to communicate with the Arduino board (debugging...)
  - `begin(speed)`: sets data rate in bps (baud)
  - `println(value)`: prints data to the serial port
- `digitalRead(pin)`
  - pin: pin number on the board
  - Return value is either 0 (LOW) or 1 (HIGH)
- `analogRead(pin)`
  - pin: pin number on the board
  - Return value (0 – 1023)
- Initializes serial port communication at data rate of 9600bps
- Sets Pin #10, #11 as INPUT
- If any off lead is detected, print '!'
- Read in ECG signal data from A0, and print to the serial port



```
sketch_mar27a | Arduino 1.8.5
File Edit Sketch Tools Help

sketch_mar27a $

void setup() {
  // initialize the serial communication:
  Serial.begin(9600);
  pinMode(10, INPUT); // Setup for leads off detection LO +
  pinMode(11, INPUT); // Setup for leads off detection LO -
}

void loop() {
  // checking if any off lead is detected
  if((digitalRead(10) == 1) || (digitalRead(11) == 1)){
    Serial.println('!');
  }
  else{
    // send the value of analog input 0:
    Serial.println(analogRead(A0));
  }
  //Wait for a bit to keep serial data from saturating
  delay(1);
}
```

20 Arduino/Genuino Uno on COM1

# Digital I/O - UART

- Higher level software libraries provided for developers
  - No need to worry about start bit, stop bit, optional parity bit
  - Libraries
- *Serial*, *SoftwareSerial* libraries for UART implementation
  - *Serial*: Digital Pin #0 (Rx) #1 (Tx), USB connection, use built-in serial monitor to communicate with the Arduino board (debugging...)
  - *SoftwareSerial*: developed to allow serial communication on other digital pins, using software to replicate the functionality, similar to Serial but can choose Rx and Tx pins
- Designed for communication between two devices at a time
  - No method of differentiating multiple transmissions on the same line
- Half-duplex connection between two devices
  - Walkie-talkie-like communication

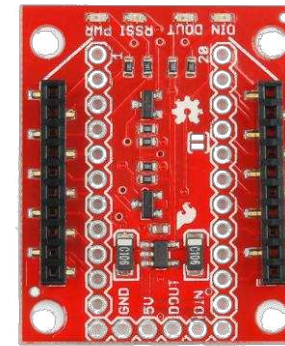
# Digital I/O – UART implementation

| Serial/Software Serial Method     | Purpose   | Code Example                      | Explanation   |
|-----------------------------------|---|-----------------------------------|---|
| Constructor (SoftwareSerial ONLY) | Define GPIO pins as UART Rx and Tx                                    | SoftwareSerial<br>mySerial(2, 3); | Defines a serial connection with Rx on Pin #2, Tx on Pin #3 |
| begin                             | Define data rate for serial connection                                | mySerial.begin(9600);             | Communication on “mySerial” port will occur at 9600 baud    |
| print/println                     | Write byte data into human-readable characters over serial connection | mySerial.println(“Hello World”);  | Writes bytes equivalent to <i>Hello World</i>               |
| write                             | Write raw byte data over the serial connection                        | mySerial.write(29);               | Writes byte with value 29                                   |
| read                              | Read data from the serial connection                                  | mySerial.read();                  | Reads from serial connection                                |

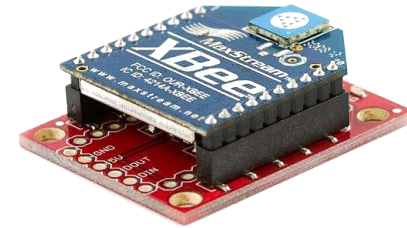
# Digital I/O – UART Example

- XBee + XBee Explorer Regulated

| Board Label | Pin Function     | Arduino Connection |
|-------------|------------------|--------------------|
| GND         | Ground           | GND                |
| 5V          | 5V Power Supply  | 5V                 |
| DOUT        | Data Output (Tx) | 2                  |
| DIN         | Data Input (Rx)  | 3                  |



XBee Explorer  
Regulated



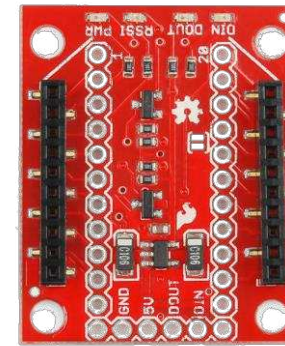
XBee Module

- XBee module is for ZigBee connection
- XBee Explorer Regulated translates 5V serial signals to 3.3V
- DOUT(Tx) and DIN(Rx) values are HIGH or LOW
- XBee's Tx is Arduino's Rx, XBee's Rx is Arduino's Tx
- Use *SoftwareSerial* library for data communication between Arduino board and XBee module
- Use *XBee* library for initializing, data packaging, setting receiver information...

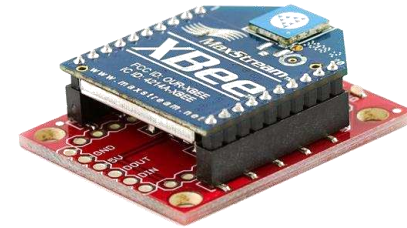
# Digital I/O – UART Example

- XBee + XBee Explorer Regulated

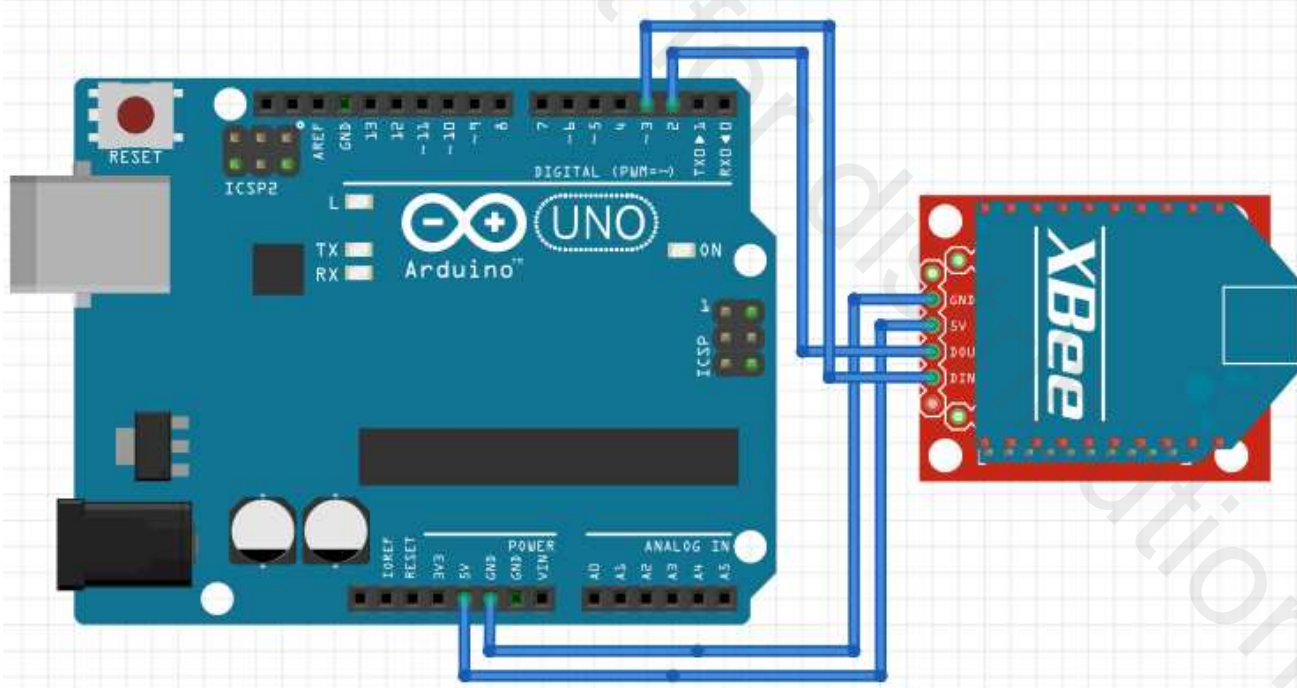
| Board Label | Pin Function     | Arduino Connection |
|-------------|------------------|--------------------|
| GND         | Ground           | GND                |
| 5V          | 5V Power Supply  | 5V                 |
| DOUT        | Data Output (Tx) | 2                  |
| DIN         | Data Input (Rx)  | 3                  |



XBee Explorer  
Regulated



XBee Module





# Digital I/O – UART Example

- Include required headers
  - XBee.h for XBee module behaviors
  - SoftwareSerial.h for SoftwareSerial
- Initialize pin #2, #3 to *mySerial*
- Necessary initialization for XBee
  - Set receiver's address
  - Prepare Tx data for ZigBee
- Set correct data rate between XBee and Arduino board
- Set mySerial as for sending and receiving packets over ZigBee
- payload[] contains data to be Tx
- send() function transmits packet to Tx including receiver's address, payload size, payload...



```
XBEE_Chest_FALL | Arduino 1.8.1
File Edit Sketch Tools Help

XBEE_Chest_FALL $
#include <XBee.h>
#include <SoftwareSerial.h>

XBee xbee = XBee(); // create the XBee object
SoftwareSerial mySerial(2, 3); // set Pin 2 as Rx, Pin 3 as Tx
byte payload[20]; // payload for zigbee data transfer

// XBee Initializations
XBeeAddress64 addr64 = XBeeAddress64(0x0013A200, 0x41241F14);
ZBTxRequest zbTx = ZBTxRequest(addr64, payload, sizeof(payload));
ZBTxStatusResponse txStatus = ZBTxStatusResponse();

void setup(void)
{
  mySerial.begin(57600); // set mySerial at 57600 baud
  xbee.setSerial(mySerial); // set mySerial for xbee
}

void loop(void)
{
  // pack payload[]
  // payload[2] = ...
  // payload[10] = ...

  // SENDS the information to the addressed XBEE module
  xbee.send(zbTx);
}
```

Done compiling.

Sketch uses 3720 bytes (12%) of program storage space. Maximum is 30720 byte  
Global variables use 482 bytes (23%) of dynamic memory, leaving 1566 bytes f

25 Arduino Pro or Pro Mini, ATmega328P (3.3V, 8 MHz) on COM6