



**Alan Rynne**

*2018 Portfolio*

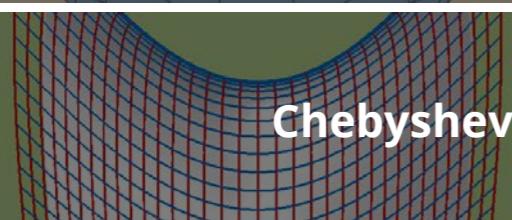


Hi! My name is Alan Rynne, I am a building engineer from Spain with a recently obtained Master's Degree in Parametric Design for Architecture. I am passionate about bringing together Architecture and technology to improve the way we work and design on a daily basis.

1. Geodesic Patterns for Freeform Architecture



2. Panneling with Planar Hexagons



3. Chebyshev Net Generation



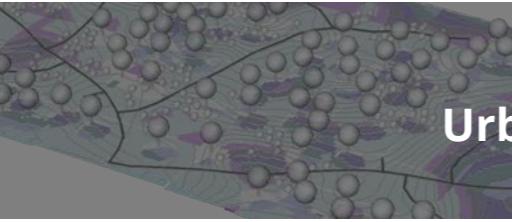
4. Triangular Gridshell



5. Cutty Sark Pavillion



6. Urban Landscaping



7. Urban Data Exploration



8. Reproducible Research



9. 3D Printing & CNC Machining



10. DIY Autonomous Drone



# Projects

# Geodesic Patterns for Freeform Architecture

Master Thesis - C# Implementation for Grasshopper

## Details

### Author

Alan Rynne

### Date

September 2018

### Website

<http://bit.ly/geoPatrn>

### Grade

10/10

### University

ETSAV - UPC

### Full Text PDF

[missing link!](#)

### Disclaimer

This research will be part of a larger book on the topic of *Surface Rationalization* that will be published during 2018/2019.

[Architectural Geometry](#)

[Fabrication-aware design](#)

[Freeform architecture](#)

Implementation and analysis of different existing techniques to obtain cladding solutions using exclusively straight planks, either wood or metal, in order to weight their benefits and weaknesses from an architectural standpoint. The research was mainly centred on the generation of geodesic curves, more specifically straightest geodesics, which minimize distance between two points on curved surface. For cost and manufacturing reasons, geodesic planks are favorable for cladding solutions, as they can be manufactured and assembled using inexpensive construction techniques. We will also explain some basic structural analysis concepts to check the admissibility of the generated solutions.

Fig. 1.1 - Computed pattern using the Evolution method

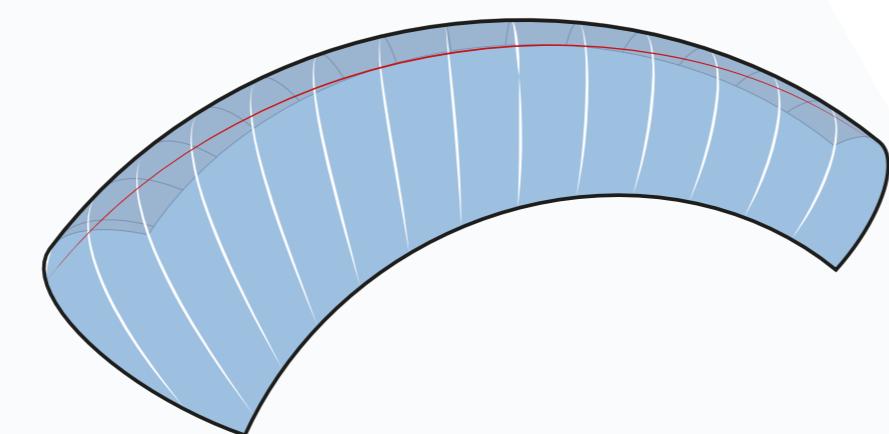
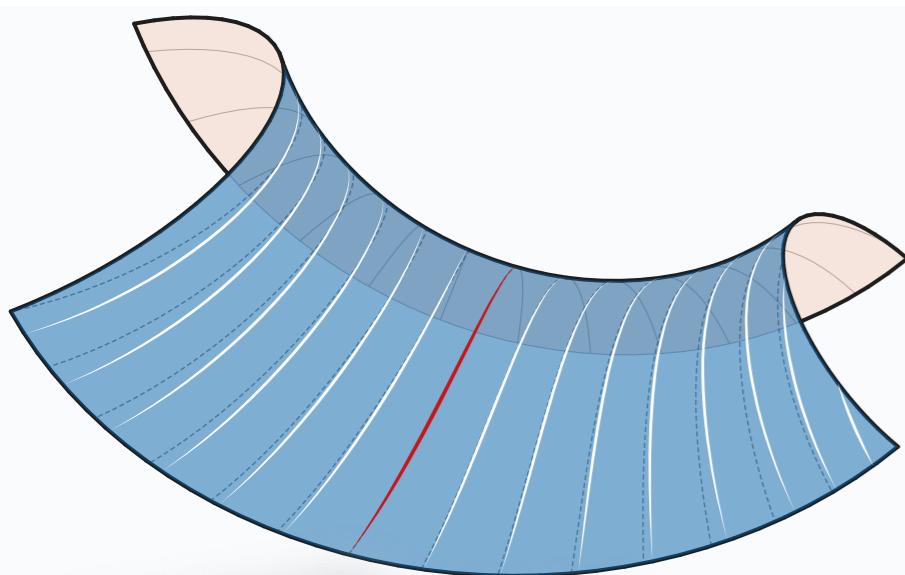


Fig. 1.2 - Geodesic pattern computed using the Piecewise Evolution method

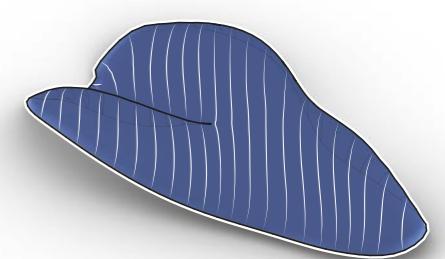
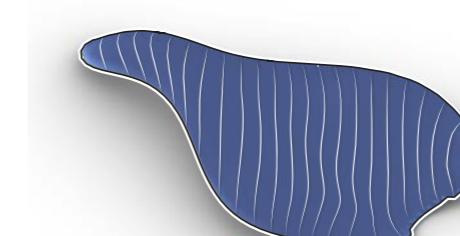
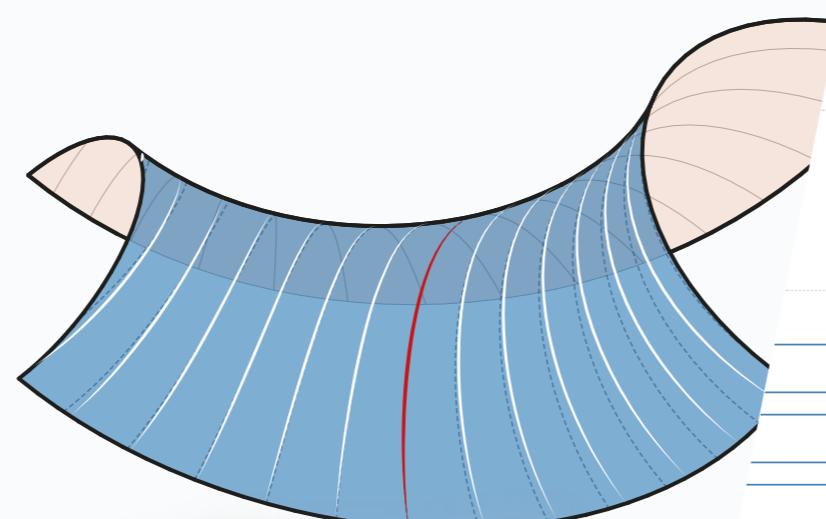
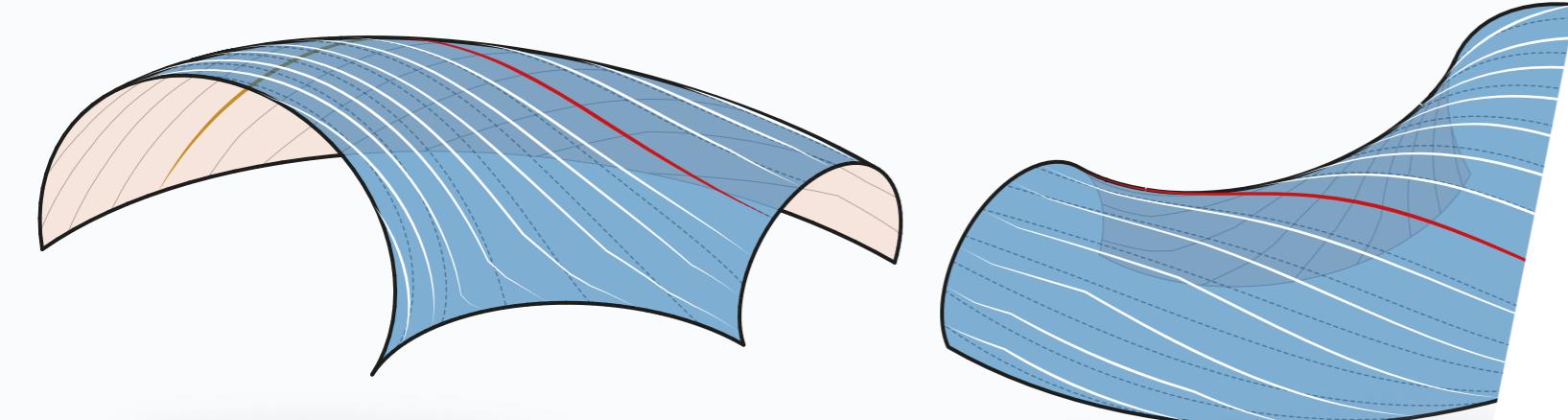


Fig. 1.4 - Level-set method starting configuration

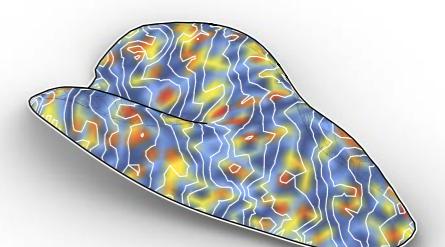
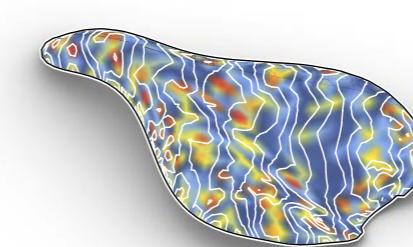
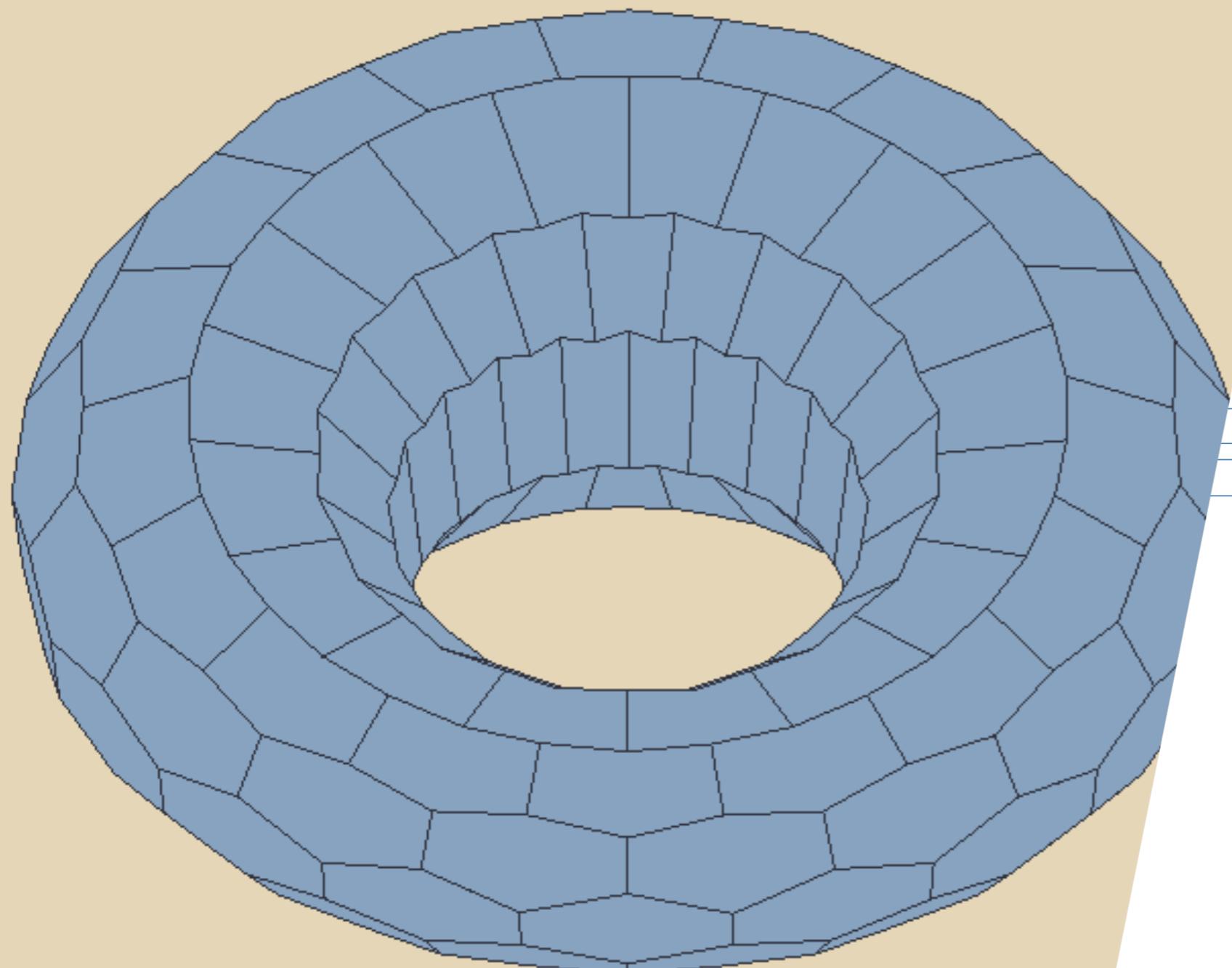


Fig. 1.5 - Computed geodesic pattern using the level-set method

Fig. 1.3 - Geodesic pattern computed using the Piecewise Evolution method

# Panneling with Planar Hexagons



## Details

### Author

Alan Rynne

Thiago Medeiros

David Granzewich

### Date

September 2017

### Website

[www.rynette.es](http://www.rynette.es)

### Location

Barcelona (Spain)

### Det.title

Some detail...

Complex panneling solutions

Architectural geometry

The goal of this research is to understand and expand upon the computational strategies behind planar hexagonal-dominant (PHex) surfaces. Initial exploration was based on several existing techniques: Edge Offset mesh, the Duality approach and the *singularity placement* method.

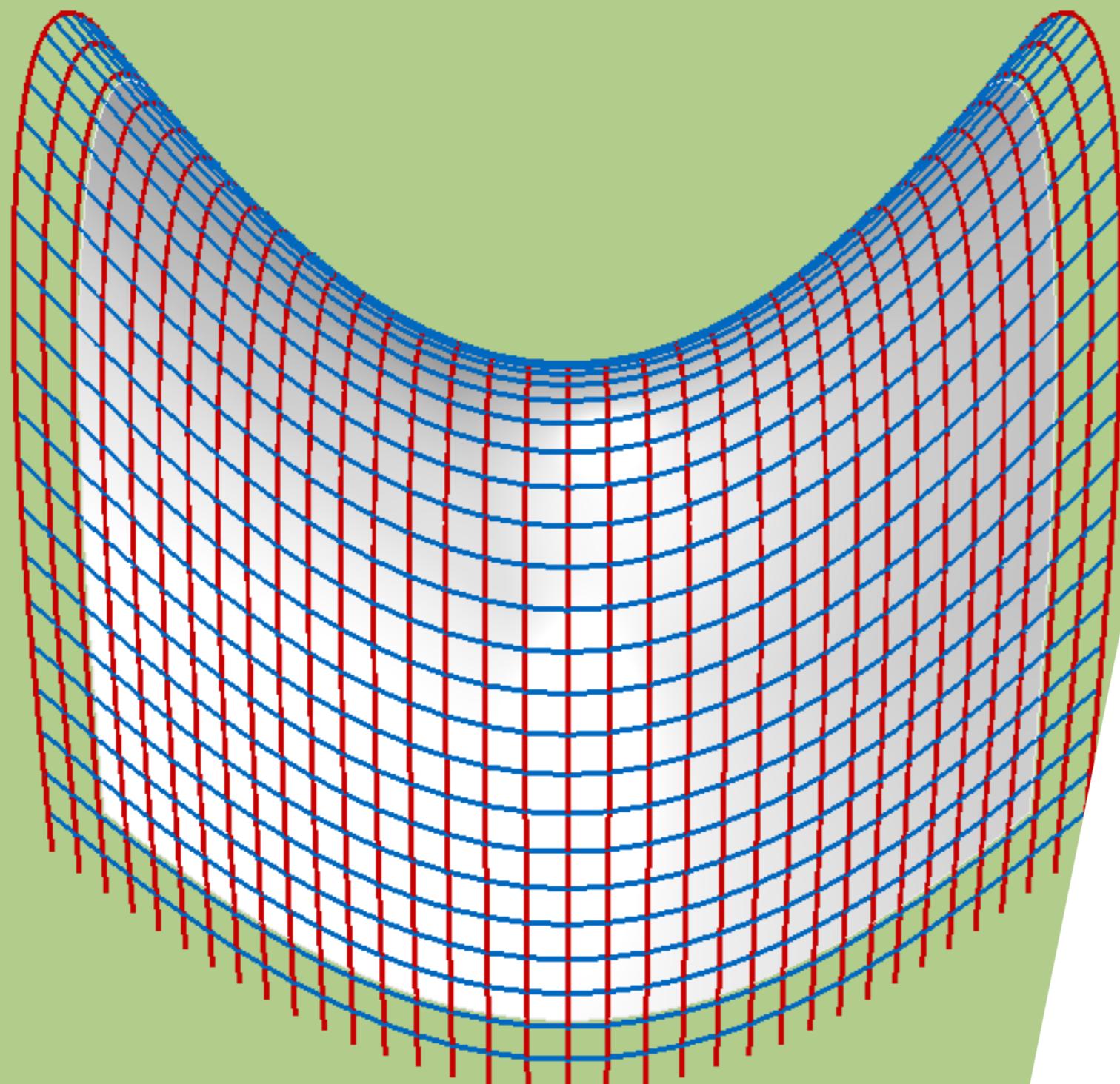
Out of the three explored methods, the Edge Offset method (which is based on the principle of plane intersections) proved to be the most reliable for generating planar panels, although for complex surfaces this technique needs to be coupled with complex shape optimization algorithms to successfully generate a watertight panelization.

Both the singularity placement method and the duality approach require the use of planarization algorithms or their conversion into as a *cyclidic* or *conical* meshes in order to achieve acceptable results. It would also be possible to panelize this solutions with non-planar panels via clustering techniques, which would also dramatically increase the cost of the solution. The obtained Edge Offset solution was then processed and fabricated at 1/100 scale using digital fabrication techniques.

This small research paper was elaborated during my attendance at the MPDA'18.

# Chebyshev Net Generation

Grasshopper component implemented in C#



## Details

Author  
Alan Rynne

Date  
January 2018

Website  
<http://bit.ly/chebNet>

Programming lang.  
C#

Developed as  
Grasshopper Component

Status  
Pending release

Gridshell design

Active-bending structures

Chebyshev nets are a special kind of 3D grid composed only of segments of equal length. They are of special interest when designing elastically-bent structures such as gridshells, since the equal length property of these nets guarantees that the grid could be assembled 'flat' on-site, and later bent to its final shape by either manual or mechanical means.

Developed as an Open Source project, the implementation was made as Rhino+Grasshopper Component since, at that time, there was no available open source tool for the platform.

The initial code is uploaded to my Github account, and the final release will be available at food4rhino.com in the near future.

More info on the link in details.

# Triangular Gridshell

Design & Construction of an actively-bent dome

## Details

### Author

Alan Rynne  
Martina Fabré  
Jatziri Rodriguez  
Noelia Rodriguez  
Christian Dimitri  
Martí Sais

### Date

June 2018

### Photo cred.

Andrés Flajszer

[Active-bending](#)

[Dome structure](#)

[Elastic membrane](#)

The aim of this study is to design and build a 6 m diameter dome structure covered by a stretchable membrane; using the previously published work in Chebychev Net gridshells, the introduction of singularity points in the grid design, analyzing the behavior of the structure on different configurations and the relation between each 'patch' to each other.

A special case exists when introducing a single valence 3 singularity on the center of a spherical dome: the bracing of each patch follows the same direction as the rods of its neighboring patches, leading to the assumption that structure and bracing could effectively be the same element. With this assumption, a number of new constructive problems arise when trying to erect the structure: Bracing joint should be left to slide freely in order to keep the structure flat during assembly, and would be fixed in place after the erection process.



Fig. 4.2 - Image by Andrés Flajszer



Fig. 4.1 - Image by Andrés Flajszer

# Cutty Sark Pavillion

Building adaptation study



## Details

### Author

Alan Rynne  
Uri Lewis

### Date

February 2018

Hybrid structures

Building adaptation

Lightweight construction

The purpose of this study was to analyze in depth an already existing building solution, in this case: The cutty sark pavilion. The building is an effimeral Lightweight structure that was designed for the purpose of the Cutty Sark boat refurbishment. The building solution is comprised of 3 kinds of elements, wood beams which are in pure compression, the membrane which is in pure tension, and the cast steel nodes which connect both elements together.

Once the key parts where identified, a parametric design was implemented using Rhino+Grasshopper® in order to adapt the solution to a completely different shape: A *Dupin cyclide*. You can find more info about this project on my website.

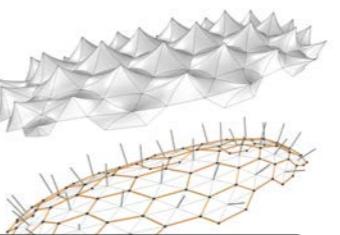


Fig. 5.2 - Surf: Initial U=18 V=6  
Dir=Across

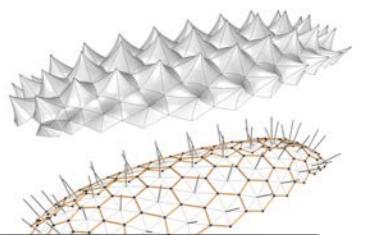


Fig. 5.3 - Surf: Initial U=18 V=6  
Dir=Over

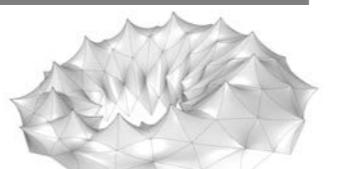


Fig. 5.4 - Surf: Dupin Cyclide U=18  
V=6 Dir=Across

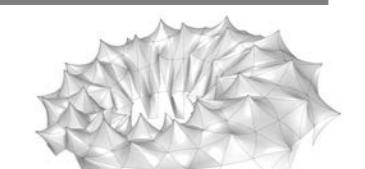


Fig. 5.5 - Surf: Initial U=18 V=6  
Dir=Over

# Urban Landscaping

Rooftop park generator

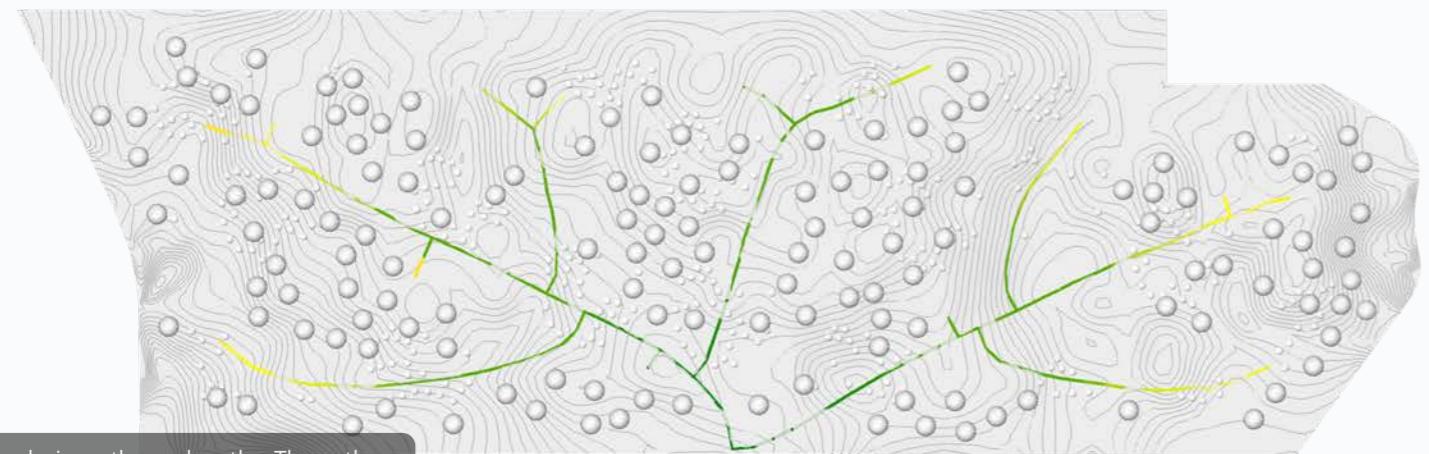


Fig. 6.1 - Slope analysis on the park paths. The paths were generated using a growth algorithm.

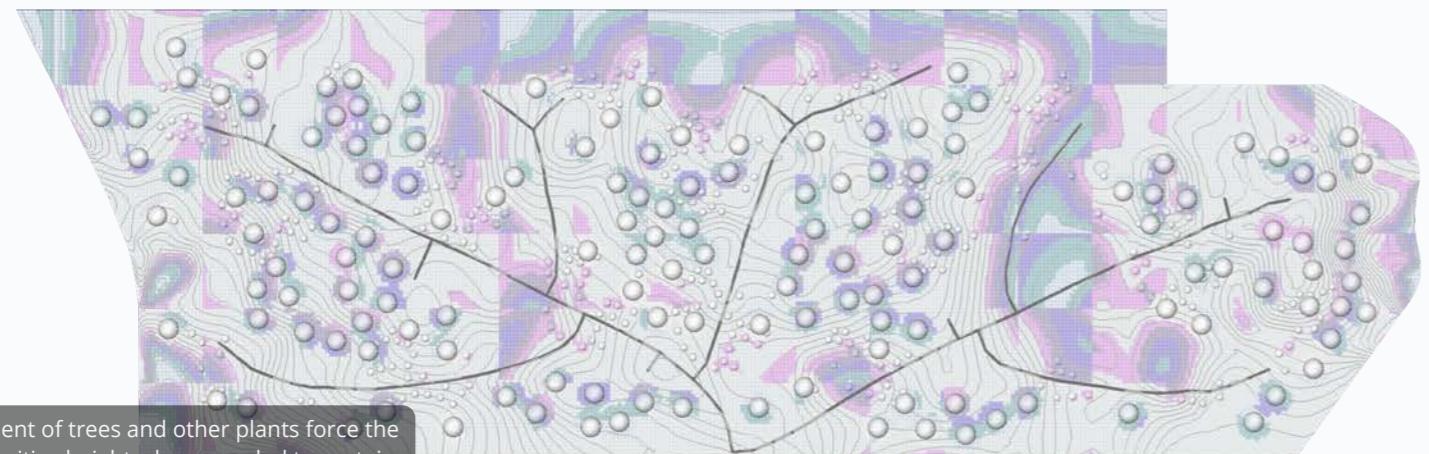


Fig. 6.2 - Placement of trees and other plants force the adjustment of cavities height where needed to sustain vegetation.

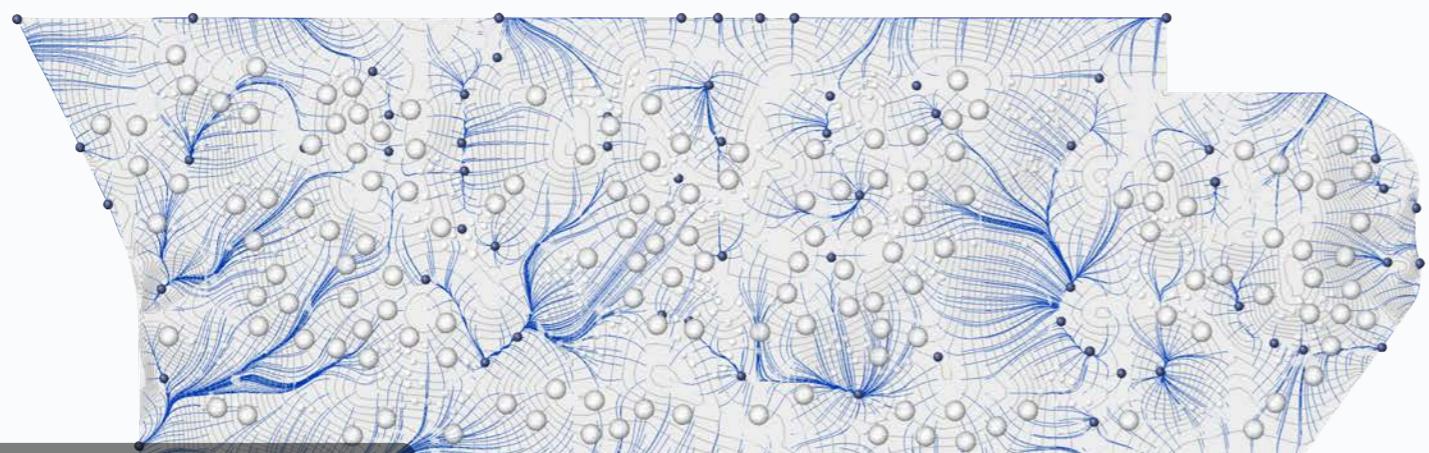


Fig. 6.3 - Water drainage analysis influences tree positioning, eliminating trees in unsustainable areas.

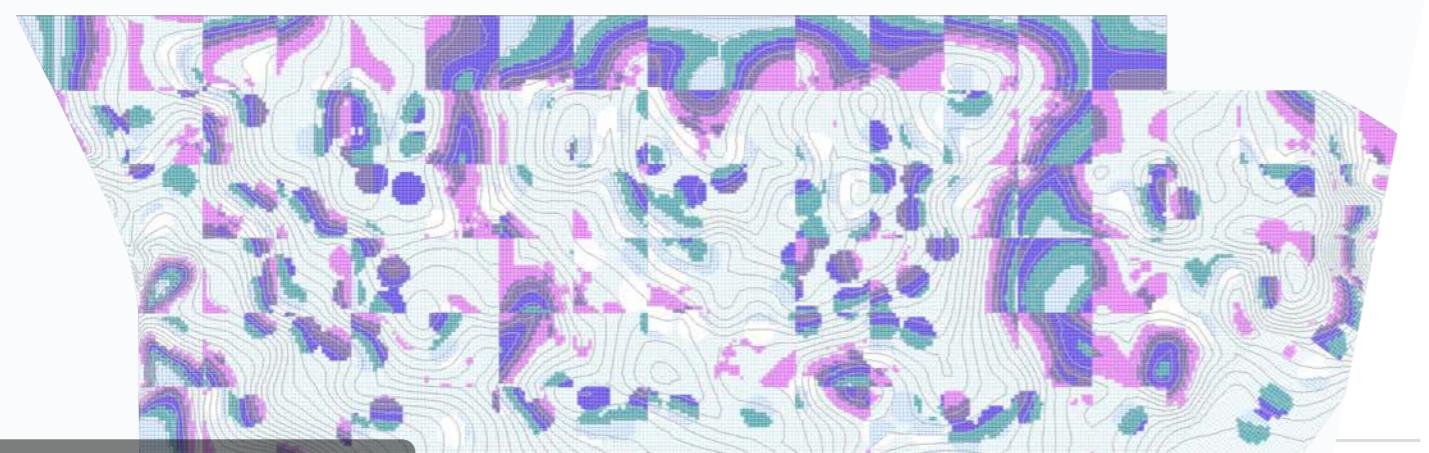


Fig. 6.4 - Top view of the computed rooftop cavities colored by height

## Details

Author  
Alan Rynne

Date  
May 2018

Rooftop garden

Optimization

Randomness

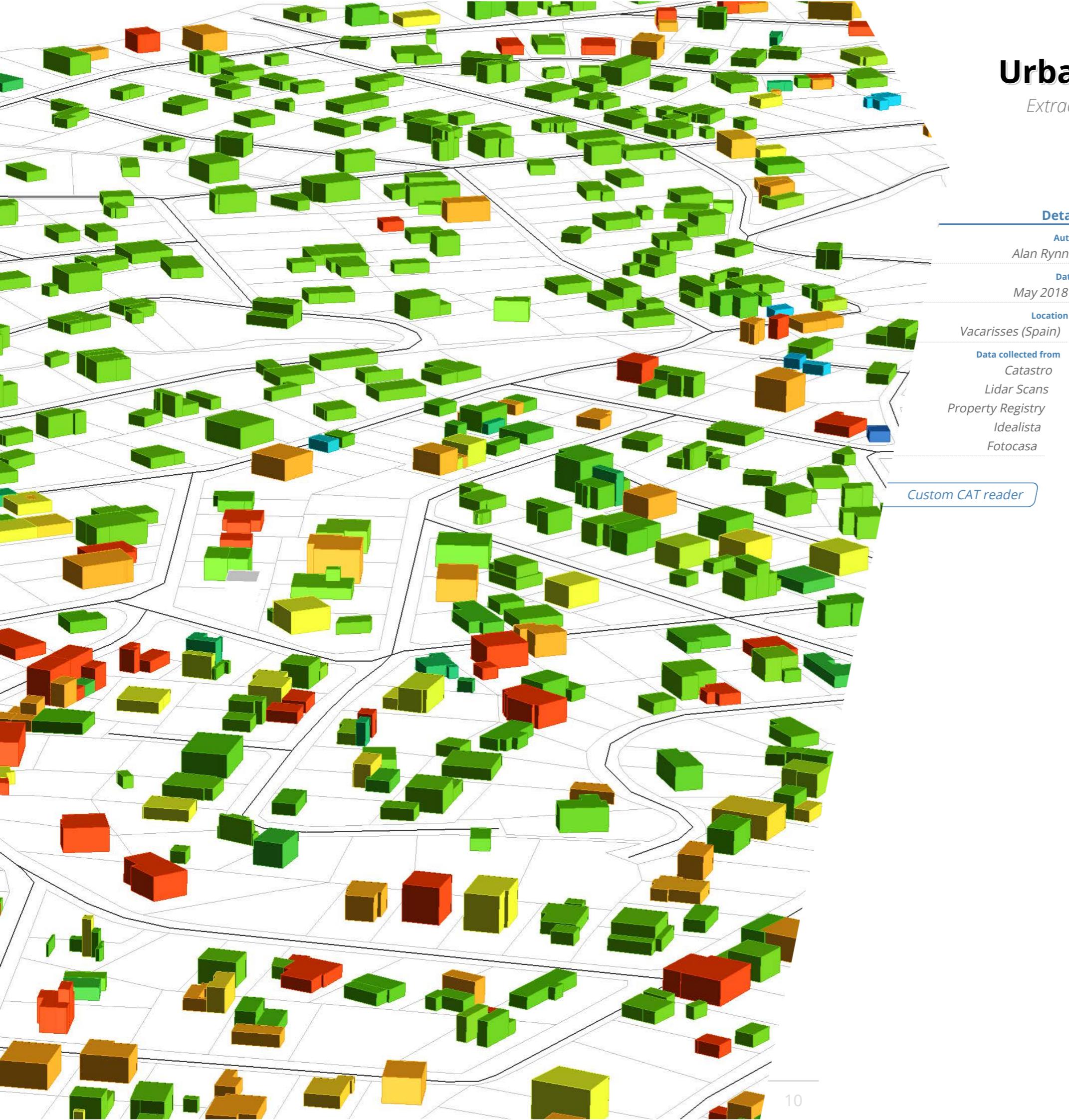
In this case, we looked into the problematic of building urban rooftop gardens: How to replicate a given topography on a rooftop, without overloading the structure nor adding unwanted filtrations to the underlying building floors? we opted for a 'hollow box' solution, that would allow us to raise the initial slab level in order to optimize for weight.

The height of these boxes was calculated taking into account the different vegetation that would exist in each area and their specific soil + watering needs in order to guarantee their survival. Water drainage was also taken into account (Fig 6.3) when placing the different species.

The result is an underlying topography between the desired one and the original slabs, creating more soil height around trees, while minimizing it on grass areas.

# Urban Data Exploration

Extraction and Analysis of urban public records in Vacarisses.



With the expansion of digital technologies and the growing access to public databases, it is more necessary than ever to be able to take advantage of every bit of information to empower our decision making. In this case, Vacarisses, a small town in the Barcelona area (Spain), was chosen as the object of the study in order to analyze the energy efficiency of the towns buildings and its possible repercussions.

Public and private databases were used in order to cross information that resulted in the graph below, although data was severely limited due to privacy regulations in Spain, it was possible to visualize the correlation of the different energy qualifications (A to G) to the existing legislation in Spain on that matter, and also quantify average emissions for each household per year.

# Reproducible Research

Working smarter (and faster) with Pandoc

During my year at the MPDA'18, there was a need to write our work as a set of scientific publications.

A scientific publication usually exhibits a very strict format, with very little space for the final appearance of the publication. I decided to adopt a new workflow based on GitHub (for version control and co-authoring), Pandoc (a conversion library for Markup formats), LaTeX templating and finally, some Markdown and YAML files to store the data.

I was extremely satisfied with the result, since it allowed me to concentrate fully on my research, leaving the more ‘tedious’ parts (bibliography, cross referencing, formating, etc) to an automated process controlled by a Makefile. The result was an easily updatable research paper that could also be published in different journals with little to no effort.

This portfolio was also generated using the same workflow, enabling the release concurrent HTML and PDF versions. I also wrote a quick tutorial on how to set this workflow up, which you can find at this project’s website link.

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9 <body>
10   <page size="A3" layout="landscape" class="paper title-page" id="particles-js">
11     <div class="image">
12       $if(title-image)$<div>$title-image$</div>$endif$
13       <div class="proj-image" style="background-image: url($title-image$);">
14         $if(title-image-caption)$<div class="caption">$title-image-caption$</div>$endif$</div>
15       $endfor$
16       $else$<div class="gradient-bg"></div>$endif$</div>
17       <div class="data">
18         <h1 class="title">$author.name$</h1>
19         <h3 class="subtitle">$title$</h3>
20       </div>
21       <script src="assets/js/particleTest.js" type="text/javascript"></script>
22     </page>
```

Fig. 8.1 - HTML5 Pandoc template

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75 small-image:
76   - link: https://archinect.imgix.net/uploads/iu/iuzqr872mhkafzpg.jpg?auto=compress%2Cformat
77   - link: https://assets.bwbx.io/images/users/iqjWHBFdfxIU/iNEv2lX15yAI/v1/-1x-1.jpg
78   - link: http://openjournal.com.au/wp-content/uploads/2017/03/71UTS23115.jpg
79   - link: https://archinect.imgix.net/uploads/iu/iuzqr872mhkafzpg.jpg?auto=compress%2Cformat
80
81 details:
82   - name: Grade
83   | data: 10/10
84   - name: University
85   | data: ETSAV – UPC
86 tabs:
87   - Rhino
88   - Grasshopper
89   - C#
90   - Optimization
91
92 keywords:
```

Fig. 8.2 - YAML data

```
80 You, 16 hours ago • Not working print
81 @media screen{
82   body{
83     background: ■rgb(204,204,204);
84   }
85   page {
86     background: ■white;
87     display: block;
88     margin: 0 auto;
89     margin-bottom: 0.5cm;
90     overflow: hidden;
91     z-index: -10;
92     box-shadow: 0 0 0.5cm □rgba(0,0,0,0.5);
93   }
94   page[size="A4"] {
95     width: 21cm;
96     height: 29.7cm;
```

Fig. 8.3 - CSS styles file

# 3D Printing & CNC Machining

DIY build for hobby purposes

## Details

Author  
Alan Rynne

Date  
2014-2016

CNC Machine  
Shapeoko

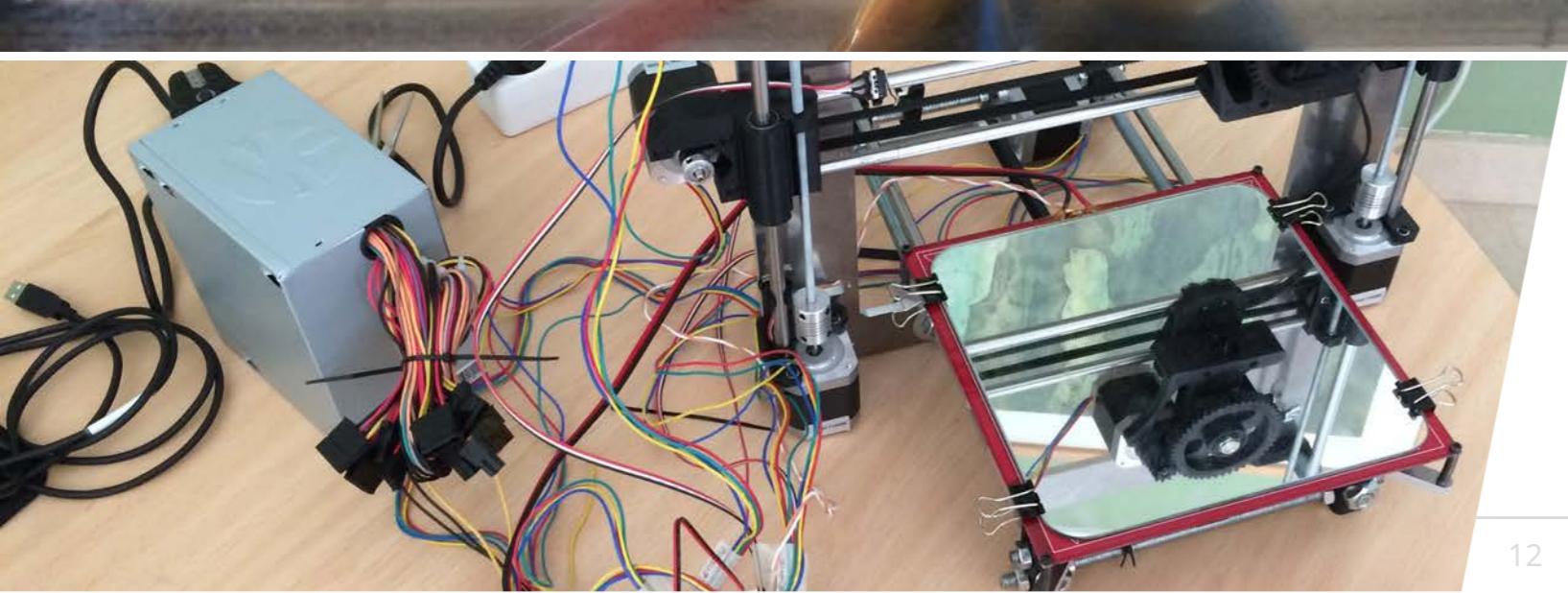
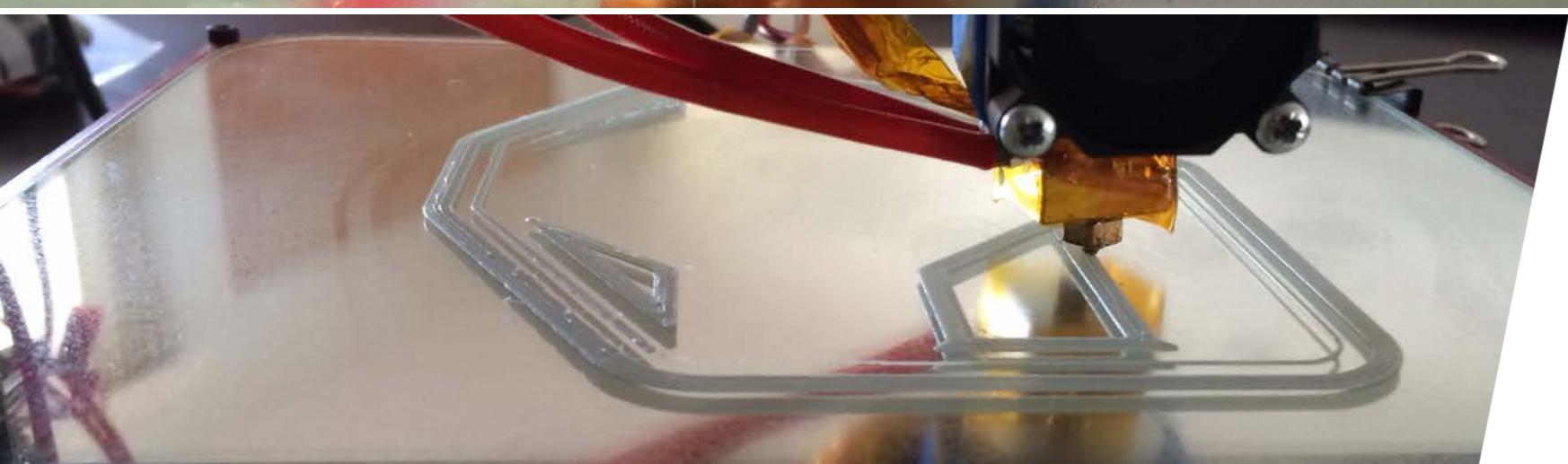
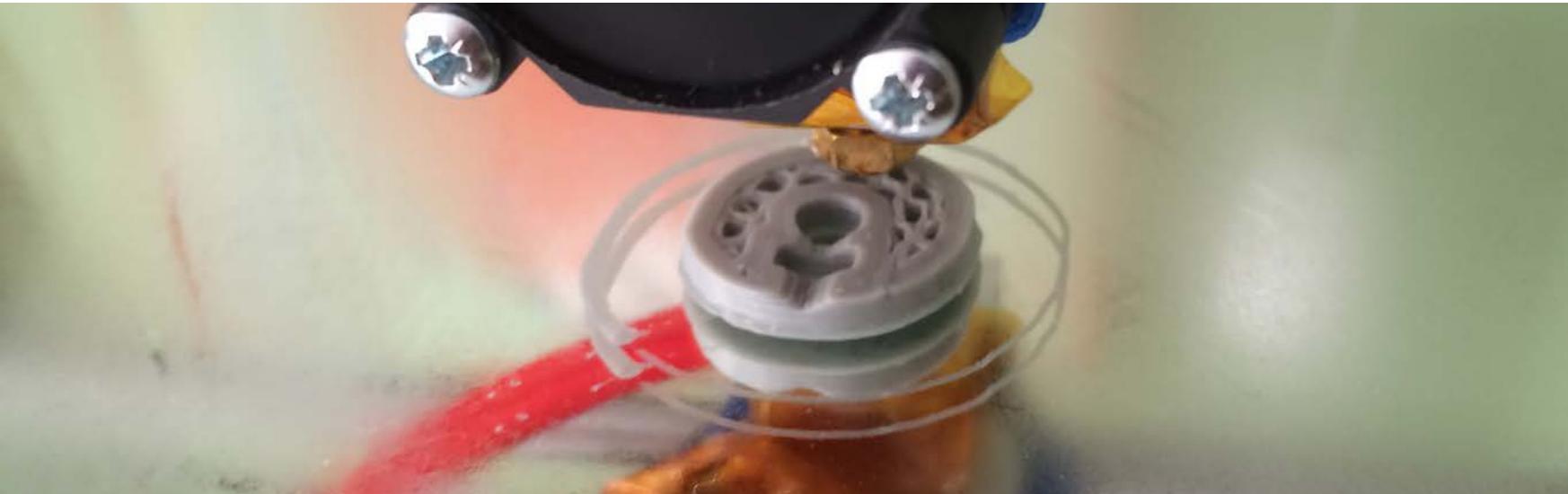
3D Printer  
Prusa i3

[Do It Yourself](#)

[Digital Fabrication](#)

[Electronics](#)

[Technology](#)



I have always been intrigued and driven by technology and during the years I have embarked in several hobby projects to investigate new (and not so new...) available technologies like 3D Printing and CNC machining.

I started building my first 3D printer in 2014, eventually abandoning that project in 2015 in favor of a DIY Prusa i3 model which was Open Source.

In 2016, I took on the challenge of building my own home CNC machine (50x50cm bedsize), which was also Open Source. Both 3D printer and CNC machine were used to build many of the parts of my other 2016 hobby project, a fully autonomous UAV (see project on the next page).

I also possess experience in handling industrial sized CNC machines and professional Laser and Knife 2D cutters.

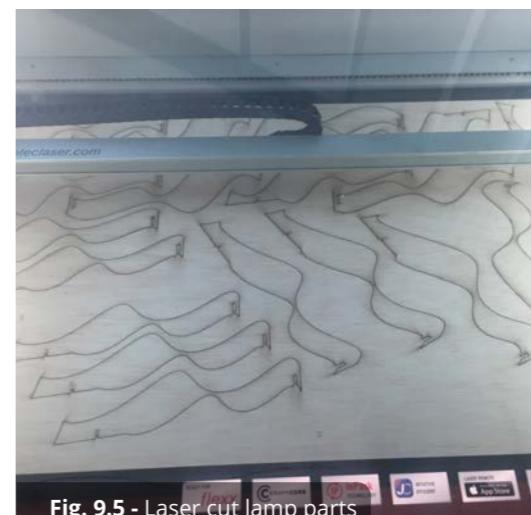


Fig. 9.5 - Laser cut lamp parts



Fig. 9.6 - Lamp prototype

# DIY Autonomous Drone

Construction of a UAV

## Details

### Author

Alan Rynne

### Date

2015-2016

### UAV Platform

Ardupilot

### configuration

Tricopter

[Do It Yourself](#)

[UAV](#)

[Electronics](#)

[Technology](#)

[Arduino](#)

Building my own drone has been one of the most challenging and fun experiences of my hobby projects so far. It is the perfect combination of electronics, design and engineering and IT FLIES! What else could I wish for?

Leaving the excitement behind, building it required an insane amount of time and effort, having to learn from flight mechanics to electronic soldering, chip programming, wireless communications and a very long list of other tangentially related topics, and tons of hours spent on trial and error.

The drone was fully designed in 3D using Rhino+Grasshopper inspired by previous designs uploaded to Thingiverse.com, and it was created as a Tricopter configuration, which added some extra complexity with the Yaw mechanism. While initially built with plywood, all the complex body parts in the final design were either 3D printed in ABS or CNC'd out of carbon fibre using the machines I built myself.



Fig. 10.3 - Drone in folded configuration





*You can always contact me at...*



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