Recorded at time: 687.41 world Broadcaster: /j2n6s300 robot state publisher Average rate:  $100\overline{0}0.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 root Broadcaster: /j2n6s300\_robot\_state\_publisher Average rate:  $100\overline{0}0.0$ Buffer length: 0.0 Most recent transform: 0.0 Oldest transform: 0.0 j2n6s300\_link\_base Broadcaster: /j2n6s300 robot state publisher Average rate:  $50.\overline{2}01$ Buffer length: 4.98 Most recent transform: 687.381 Oldest transform: 682.401 j2n6s300\_link\_1 Broadcaster: /j2n6s300\_robot\_state\_publisher Average rate:  $50.\overline{2}01$ Buffer length: 4.98 Most recent transform: 687.381 Oldest transform: 682.401 j2n6s300\_link\_2 Broadcaster: /j2n6s300 robot state publisher Average rate:  $50.\overline{2}01$ Buffer length: 4.98 Most recent transform: 687.381 Oldest transform: 682.401 j2n6s300\_link\_3 Broadcaster: /j2n6s300\_robot\_state\_publisher Average rate: 50.201 Buffer length: 4.98 Most recent transform: 687.381 Oldest transform: 682.401  $j2n6s300\_link\_4$ Broadcaster: /j2n6s300\_robot\_state\_publisher Average rate:  $50.\overline{2}01$ Buffer length: 4.98 Most recent transform: 687.381 Oldest transform: 682.401 j2n6s300\_link\_5 Broadcaster: /j2n6s300\_robot\_state\_publisher Average rate: 50.201 Buffer length: 4.98 Most recent transform: 687.381 Oldest transform: 682.401 j2n6s300 link 6 Broadcaster: /j2n6s300\_robot\_state\_publisher Average rate: 50.201 Broadcaster: /j2n6s300\_robot\_state\_publisher Broadcaster: /j2n6s300\_robot\_state\_publisher Broadcaster: /j2n6s300\_robot\_state\_publisher Average rate: 50.201 Buffer length: 4.98 Average rate:  $100\overline{0}0.0$ Average rate:  $50.\overline{2}01$ Buffer length: 4.98 Buffer length: 0.0 Buffer length: 4.98 Most recent transform: 0.0 Most recent transform: 687.381 Most recent transform: 687.381 Most recent transform: 687.381 Oldest transform: 0.0 Oldest transform: 682.401 Oldest transform: 682.401 Oldest transform: 682.401  $j2n6s300\_link\_finger\_1$ j2n6s300\_link\_finger\_2  $j2n6s300\_link\_finger\_3$ j2n6s300 end effector Broadcaster: /j2n6s300\_robot\_state\_publisher Broadcaster: /j2n6s300\_robot\_state\_publisher Average rate: 50.201 Broadcaster: /j2n6s300\_robot\_state\_publisher Average rate:  $50.\overline{2}01$ Average rate: 50.201 Buffer length: 4.98 Buffer length: 4.98 Buffer length: 4.98 Most recent transform: 687.381 Most recent transform: 687.381 Most recent transform: 687.381 Oldest transform: 682.401 Oldest transform: 682.401 Oldest transform: 682.401 j2n6s300\_link\_finger\_tip\_1 j2n6s300 link finger tip 2 j2n6s300 link finger tip 3

view frames Result