



University of
Pittsburgh

Algorithms and Data Structures 2

CS 1501



Spring 2023

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(Slides are adapted from Dr. Ramirez's and Dr. Farnan's CS1501 slides.)

Announcements

- Upcoming Deadlines
 - Homework 9: this Friday @ 11:59 pm
 - Lab 8: Tuesday 3/28 @ 11:59 pm
 - Assignment 3: Friday 3/31 @ 11:59 pm
 - Support video and slides on Canvas

Previous lecture

- ADT Graph
 - definitions
 - representations
 - traversals
 - BFS

This Lecture

- ADT Graph
 - traversals
 - BFS
 - shortest paths based on number of edges
 - connected components
 - DFS
 - finding articulation points of a graph
 - Minimum Spanning Tree (MST) problem
 - Prim's MST algorithm

BFS Pseudo-code

Q = new Queue

BFS(vertex v){

 add v to Q

 while(Q is not empty){

 w = remove head of Q

 visited[w] = true //mark w as visited

 for each unseen neighbor x

 seen[x] = true //mark x as seen

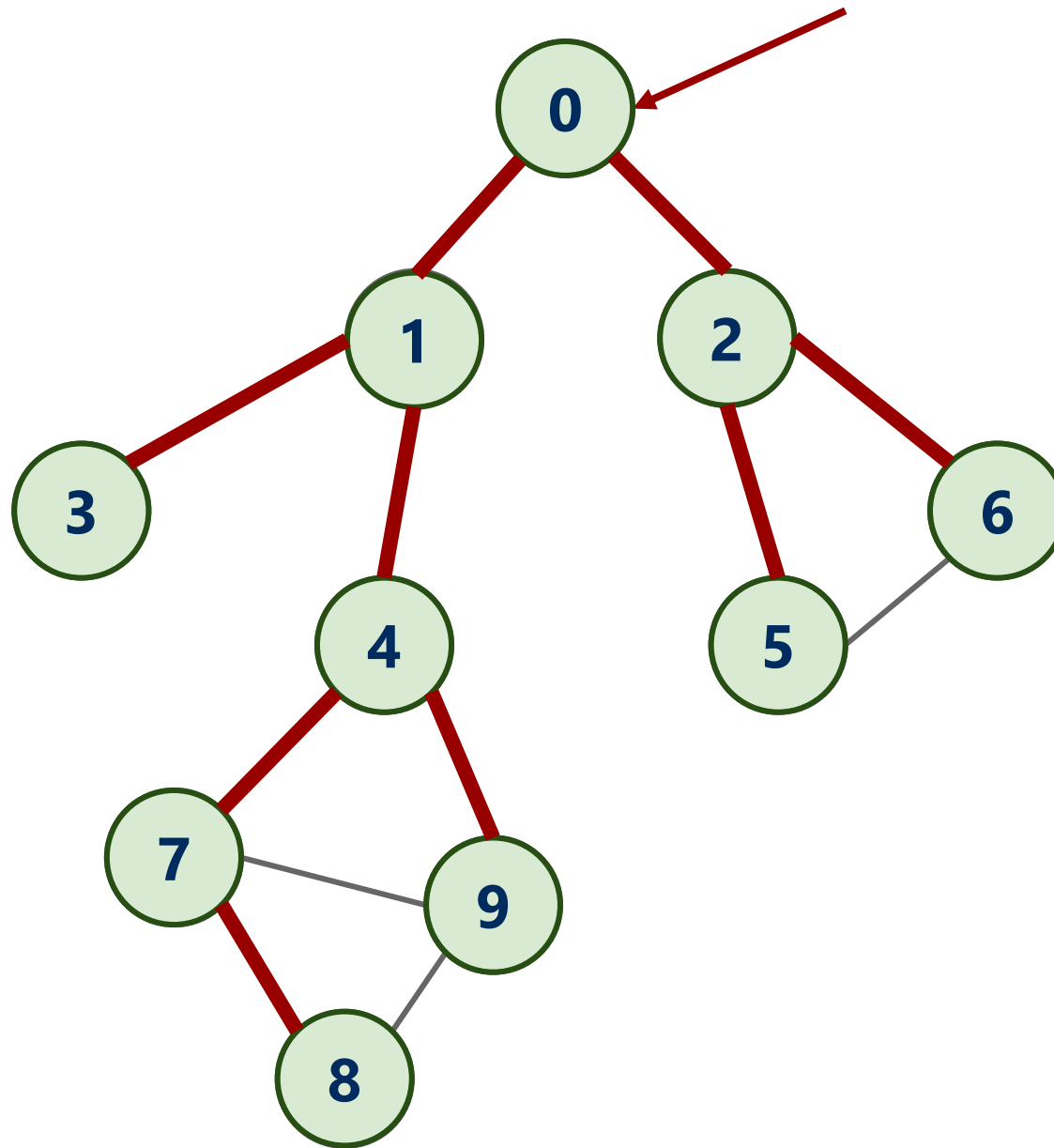
 parent[x] = w

 add x to Q

 }

}

BFS example



Shortest paths

- BFS traversals can further be used to determine the *shortest path* between two vertices

BFS Pseudo-code to compute shortest paths

Q = new Queue

BFS(vertex v){

 add v to Q

 while(Q is not empty){

 w = remove head of Q

 visited[w] = true //mark w as visited

 for each unseen neighbor x

 seen[x] = true //mark x as seen

 parent[x] = w

 distance[x] = distance[w] + 1

 add x to Q

 }

}

Problem of the Day

- **Input:** A file containing LinkedIn Connection information formatted like the following:
 - Account1: Connection1, Connection2, ...
 - Account2: Connection1, Connection2, ...
 - ...
- **Output:** Answer the following questions:
 - Given two LI accounts, how “far” are they from each other?
 - E.g., 1st connection, 2nd connection, etc. ✓
 - Are the accounts in the file all *connected*?
 - If not, how many *connected components* are there?
 - Are there certain accounts that if removed, the remaining accounts become *partitioned*?
 - These account are called *articulation points*



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Finding connected components

- A connected component is a connected subgraph G'
 - (V', E')
 - $V' \subseteq V$
 - $E' = \{(u, v) \in E \text{ and both } u \text{ and } v \in V'\}$
- To find all connected components:
 - wrapper function around BFS
 - A loop in the wrapper function will have to continually call `bfs()` while **there are still unseen vertices**
 - Each call will yield a spanning tree for a **connected component** of the graph

BFS Pseudo-code to compute connected components

```
int components = 0
for each vertex v in V
    if visited[v] = false
        components++
        Q = new Queue
        BFS(v)
```

```
BFS(vertex v){
    add v to Q
    component
    while(Q is not empty){
        w = remove head of Q
        visited[w] = true
        component[w] = components
        for each unseen neighbor x
            seen[x] = true
            add x to Q
    }
}
```

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Runtime Analysis of BFS

- Total time: **vertex processing time + edge processing time**
- Each vertex is added to the queue exactly once and removed exactly once
 - v add/remove operations
 - $O(v)$ time for vertex processing
- Edges are processed when adding the list of neighbors to the queue

Runtime Analysis of BFS: Adjacency Lists

- Each edge is processed at most twice, one per edge endpoint
 - $O(e)$ time for edge processing
- Total time: **vertex processing time + edge processing time**
 - $O(v + e)$

Runtime Analysis for BFS: Adjacency Matrix

- With Adjacency Matrix, BFS checks each *possible* edge!
 - $O(v^2)$ time for edge processing
- Total time: **vertex processing time + edge processing time**
 - $O(v^2 + v) = O(v^2)$
- ***Running time depends on data structure selection!***

Problem of the Day

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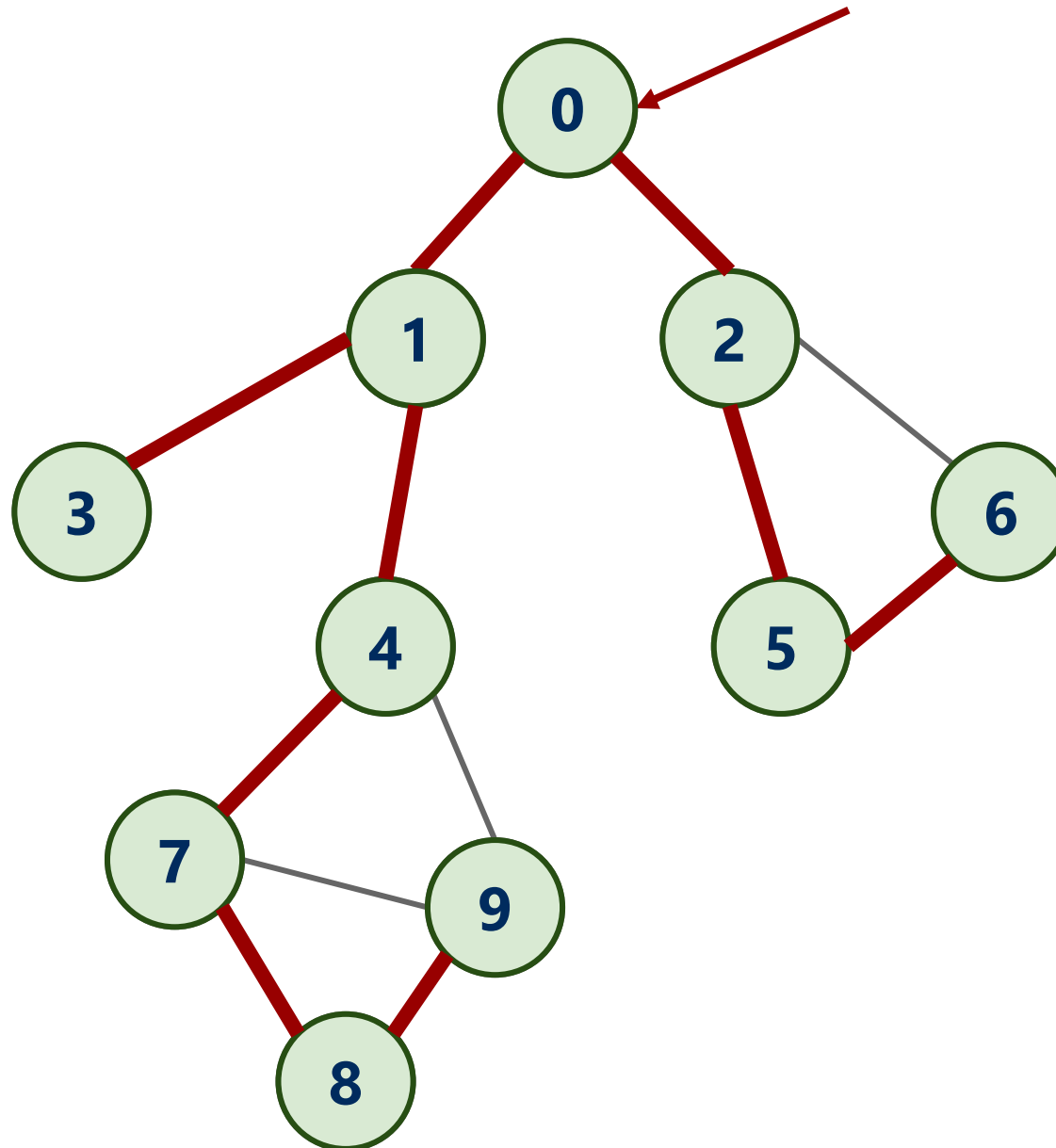
DFS – Depth First Search

- Already seen and used this throughout the term
 - For Huffman encoding...
 - as we build the codebook from the Huffman Trie
- Can be easily implemented recursively
 - For each vertex, visit *first* unseen neighbor
 - Backtrack at deadends (i.e., vertices with no unseen neighbors)
 - Try *next* unseen neighbor after backtracking
 - An arbitrary order of neighbors is assumed

DFS Pseudo-code

```
DFS(vertex v) {  
    seen[v] = true //mark v as seen  
  
    for each unseen neighbor w  
        parent[w] = v  
  
        DFS(w)  
  
}
```

DFS example



9
8
6
5
2
0

Runtime Stack

When to visit a vertex

```
DFS(vertex v) {  
    seen[v] = true //mark v as seen  
  
    visit v //pre-order DFS  
  
    for each unseen neighbor w  
        parent[w] = v  
  
        DFS(w)  
}
```

When to visit a vertex

```
DFS(vertex v) {  
    seen[v] = true //mark v as seen  
  
    for each unseen neighbor w  
        parent[w] = v  
  
        DFS(w)  
  
    visit v //post-order DFS  
}
```

When to visit a vertex

```
DFS(vertex v) {  
    seen[v] = true //mark v as seen  
  
    for each unseen neighbor w  
        parent[w] = v  
  
        DFS(w)  
  
    (re)visit v //in-order DFS  
}
```

Runtime Analysis of DFS: Adjacency Lists

- Total time: **vertex processing time + edge processing time**
- Each vertex is seen then visited exactly once
 - $O(v)$ time for vertex processing
 - except for in-order DFS
 - vertex processing is included in edge processing in that case
- Edges are processed when finding the list of neighbors
- Each edge is checked at most twice, one per edge endpoint
 - $O(e)$ time for edge processing
- Total time: $O(v + e)$

Runtime Analysis of BFS and DFS

- At a high level, DFS and BFS have the same runtime
 - Each vertex must be seen and then visited, but the order will differ between these two approaches
- The representation of the graph affect the runtimes of of these traversal algorithms?
 - $O(v + e)$ with Adjacency Lists
 - $O(v^2)$ with Adjacency Matrix
 - Note that for a dense graph, $v + e = O(v^2)$

Problem of the Day

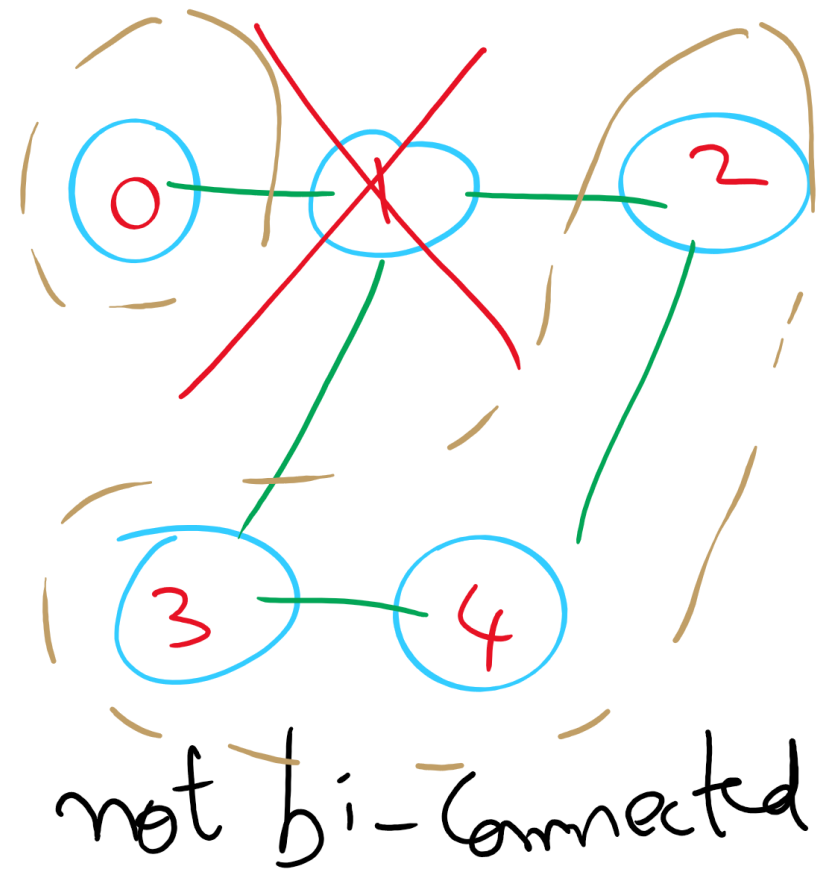
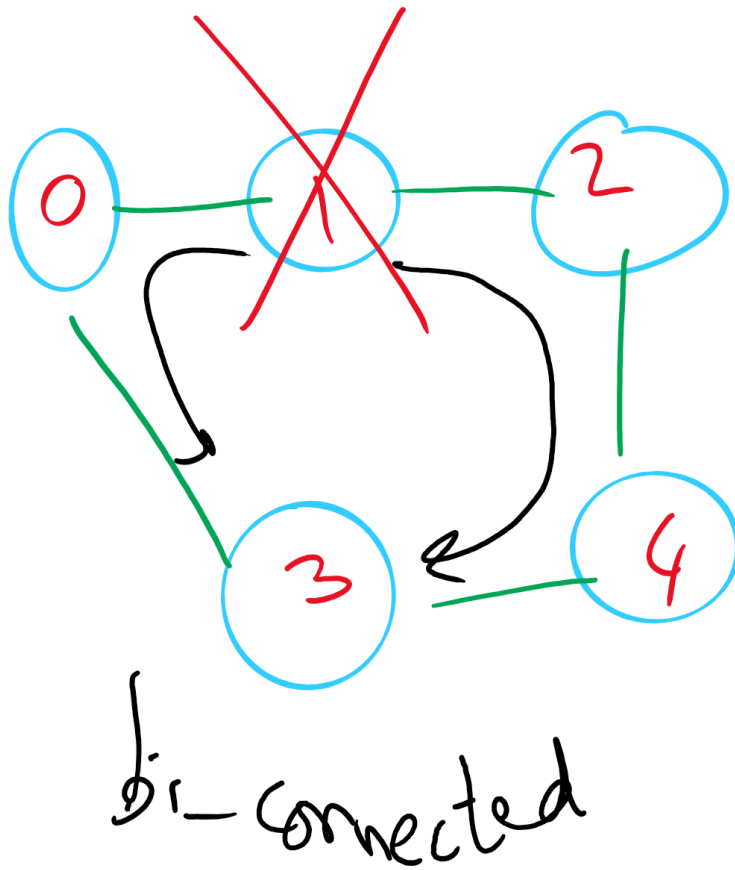
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Biconnected graphs

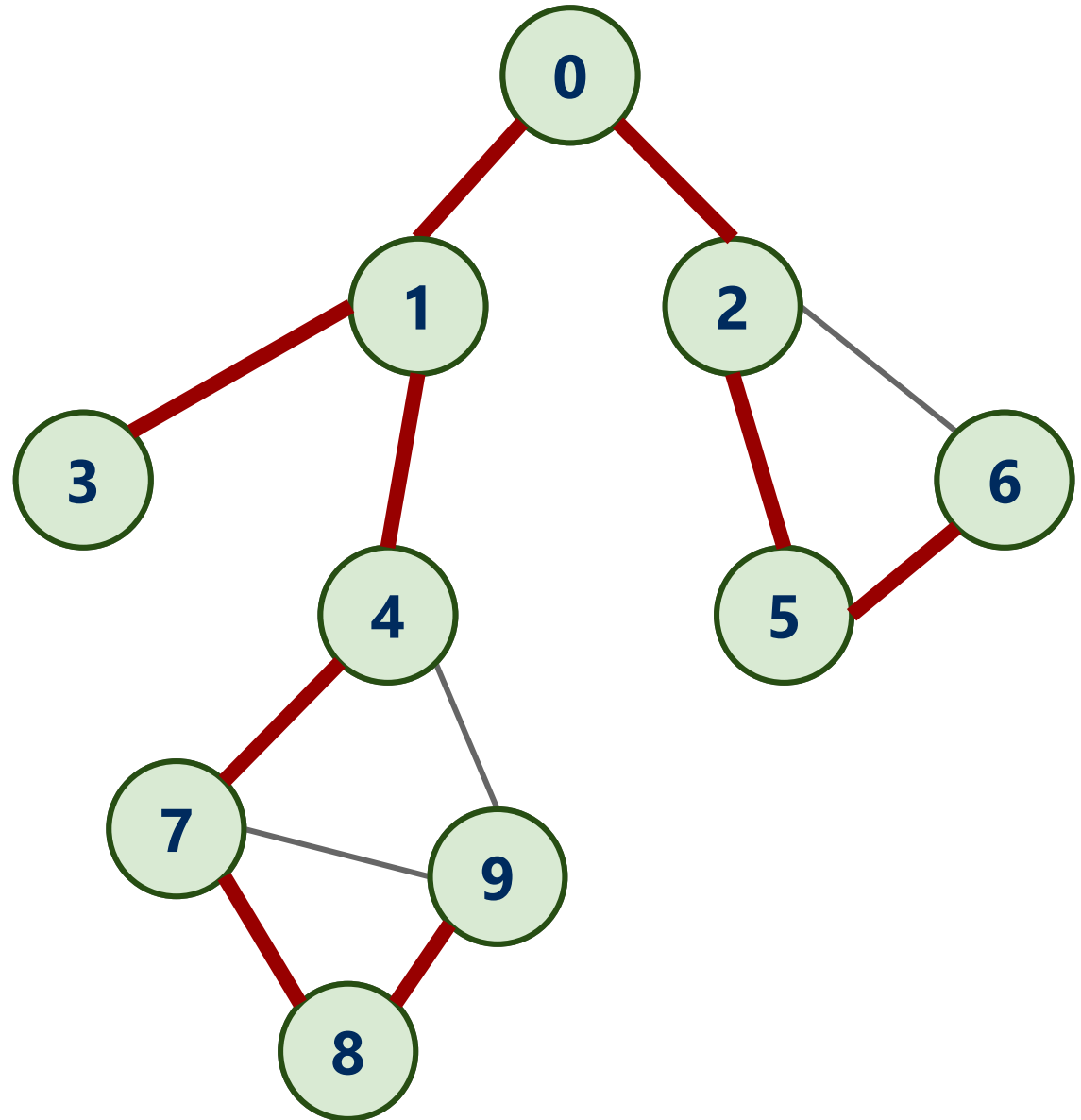
- A *biconnected graph* has at least 2 distinct paths between all vertex pairs
 - a distinct path shares no common edges or vertices with another path except for the start and end vertices
- A graph is biconnected graph iff it has zero *articulation points*
 - Vertices, that, if removed, will separate the graph

Biconnected Graph



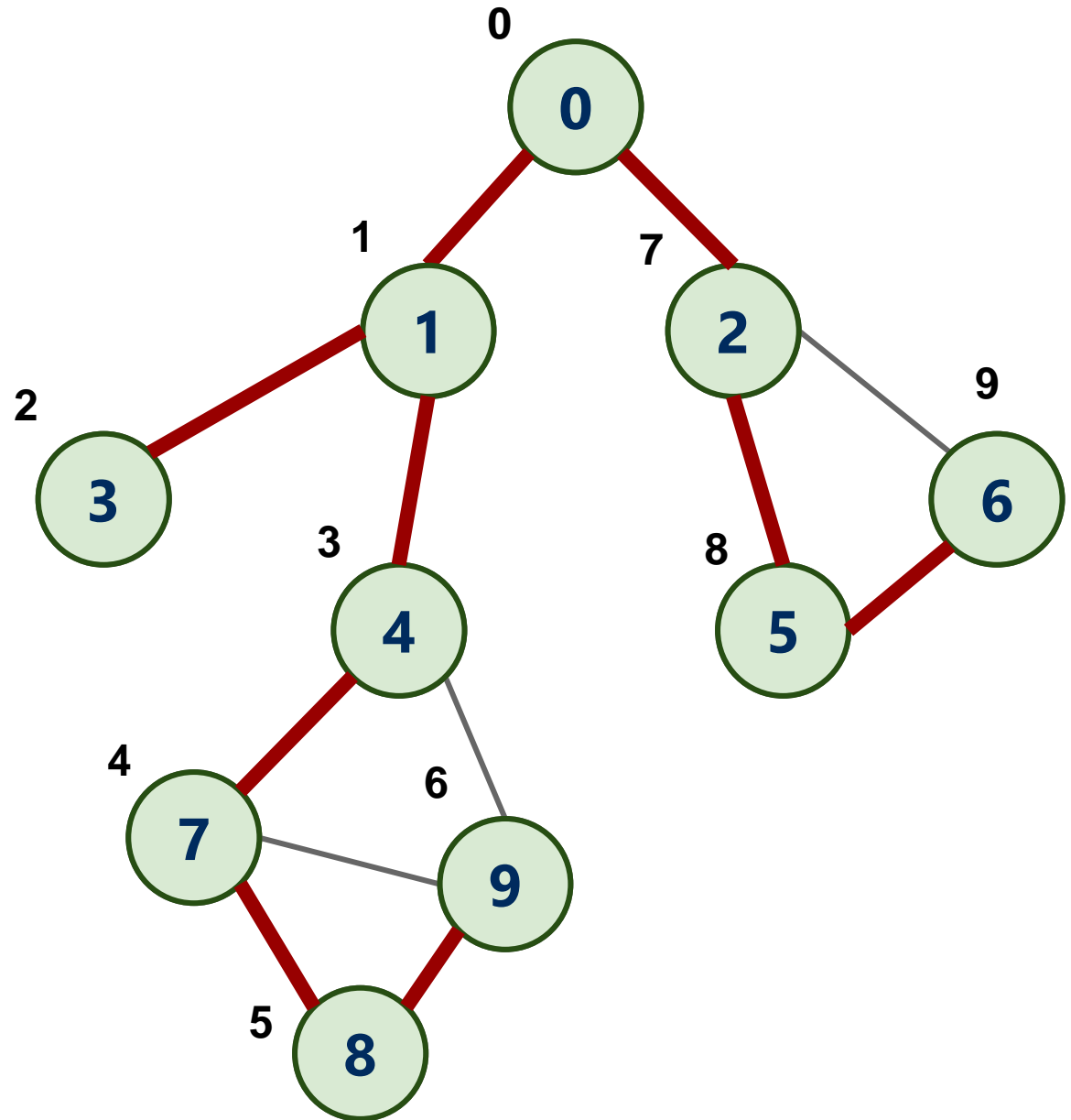
Finding articulation points of a graph

- A DFS traversal builds a spanning tree
 - red edges in the picture
- Edges not included in the spanning tree are called **back edges**
 - e.g., (4, 9) and (2, 6)



num(v)

- A pre-order DFS traversal visits the vertices in some order
 - let's number the vertices with their traversal order
 - num(v)



Finding articulation points of a graph

- For each non-root vertex v , find the lowest numbered vertex reachable from v
 - **not through v 's parent**
 - **using 0 or more tree edges then at most one back edge**
- move down the tree looking for a back edge that goes backwards the furthest

