

Algorithms and Data Structures 2 CS 1501

Spring 2022
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(Slides are adapted from Dr. Ramirez's and Dr. Farnan's CS1501 slides.)

Announcements

- Upcoming deadlines:
 - Homework 8 due on 3/21
 - Lab 8 due on 3/25
 - Homework 9 due on 3/28
 - Assignment 2 due on 3/28

Previous lecture ...

Minimum Spanning Tree Problem

CourseMIRROR Reflections (most confusing)

- how to assign the value for each edge
- The process for finding an articulation point algorithmically was most confusing
- Why low is the minimum of num(v), num(w), lowest low(w)
- The method of visiting every node of a weighted graph using the path with the lightest weight was most confusing.

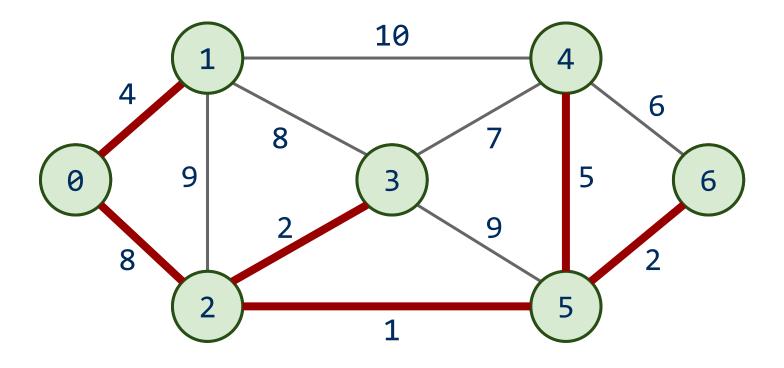
CourseMIRROR Reflections (most interesting)

- Tracing through Depth First and Breadth First Searches
- Low value tracking
- Algorithm for finding articulation points
- The idea of a weighted graph was most interesting.
- I found it interesting how back edges helped with finding articulation nodes
- The simplicity and correctness of Prim's algorithm
- The articulation point algorithm and minimizing costs with connections

Problem of the Day

- Neighborhood connectivity project
 - We want to keep a set of neighborhoods connected with the minimum cost possible
- Input: A set of neighborhoods and a file with the following format:
 - neighborhood i, neighborhood j, cost of connecting the two neighborhoods
 - •
- Output: A set of neighborhood pairs to be connected and a total cost
 - We can go from any neighborhood to any other (connected)
 - The total cost should be minimum (i.e., as small as it can be)
 (minimal cost)

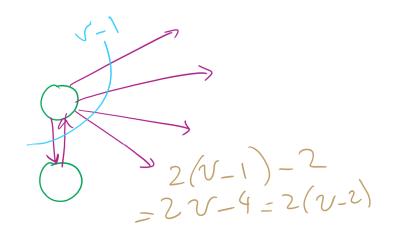
Prim's algorithm



Runtime of Prim's

- At each step, check all possible edges
- For a complete graph:
 - O First iteration:
 - v 1 possible edges
 - O Next iteration:
 - \blacksquare 2(v 2) possibilities
 - Each vertex in T shared v-1 edges with other vertices, but the edges they shared with each other already in T
 - O Next:
 - \blacksquare 3(v 3) possibilities
 - O ...
- Runtime:
 - $\bigcirc \quad \Sigma_{i=1 \text{ to } v} (i * (v i))$
 - **E**valuates to $Θ(v^3)$

Analysis of Naïve implementation of Prim's MST Algorithm



$$(v-1) + 2(v-2) + 3(v-3) + \cdots$$

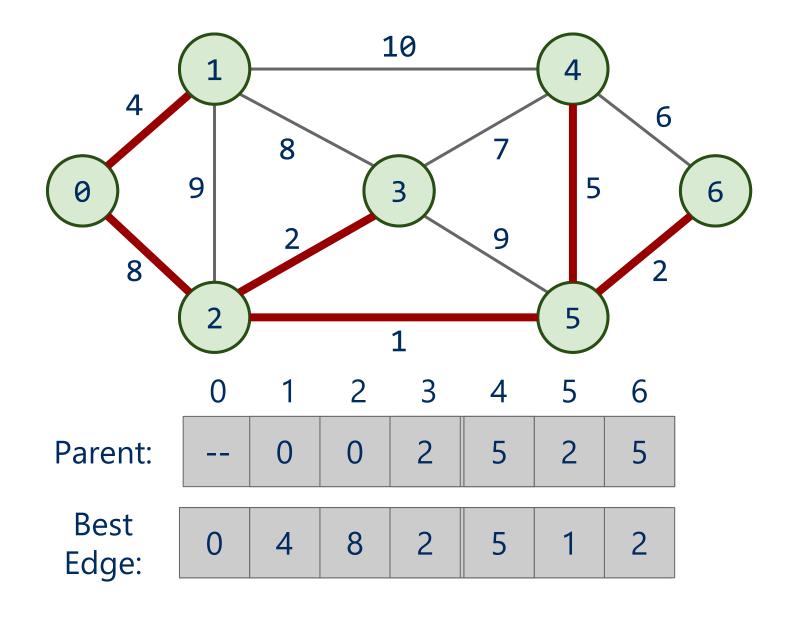
$$= \sum_{i=1}^{v} i(v-i)$$

$$= \sum_{i=1}^{v} (v-i)$$

Do we need to look through all remaining edges?

 No! We only need to consider the best edge possible for each vertex!

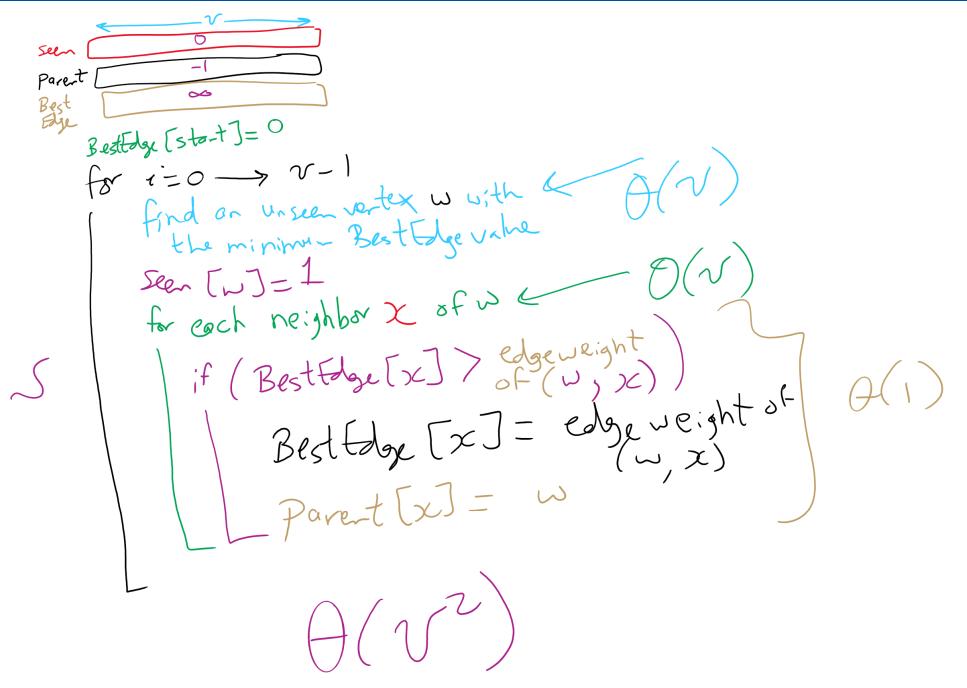
Prim's algorithm



OK, so what's our runtime?

- For every vertex we add to T, we'll need to check all of its neighbors to check for edges to add to T next
 - O Let's assume we use an adjacency matrix:
 - Takes $\Theta(v)$ to check the neighbors of a given vertex
 - Time to update parent/best edge arrays?
 - Time to pick next vertex?
 - O What about with an adjacency list?

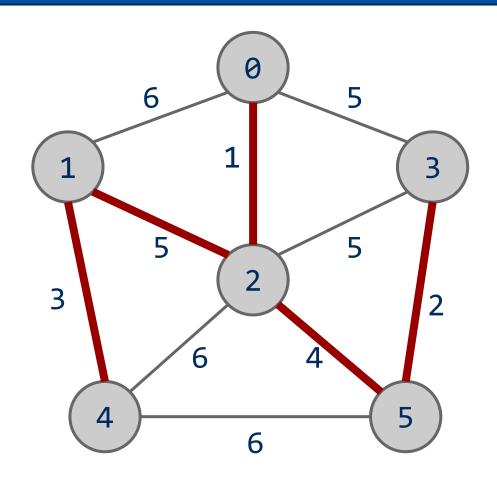
Prim's MST Algorithm



Another MST algorithm

- Kruskal's MST:
 - Insert all edges into a PQ
 - O Grab the min edge from the PQ that does not create a cycle in the MST
 - O Remove it from the PQ and add it to the MST

Kruskal's example



PQ:

- 1: (0, 2)
- 2: (3, 5)
- 3: (1, 4)
- 4: (2, 5)
- 5: (2, 3)
- 5: (0, 3)
- 5: (1, 2)
- 6: (0, 1)
- 6: (2, 4)
- 6: (4, 5)

Kruskal's runtime

- Instead of building up the MST starting from a single vertex, we build it up using edges all over the graph
- How do we efficiently implement cycle detection?

Kruskal's Runtime: Take 1

o terations Cycle O(N+e) detection DF5/BFS p(v+e)-()(e2)

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