

Algorithms and Data Structures 2 CS 1501



Spring 2023

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Announcements

- Upcoming Deadlines
 - Homework 8: this Friday @ 11:59 pm
 - Assignment 2: this Friday @ 11:59 pm
 - Support video and slides on Canvas
 - Lab 7: Tuesday 3/21 @ 11:59 pm

Previous lecture

- LZW example and corner case
- Shannon's Entropy
- LZW vs. Huffman
- Burrows-Wheeler Compression Algorithm

This Lecture

- Burrows-Wheeler Compression Algorithm
- ADT Priority Queue (PQ)
 - Heap implementation
 - Heap Sort
 - Indexable PQ
- ADT Graph
 - definitions
 - representations

Burrows-Wheeler Data Compression Algorithm

- **Best** compression algorithm (in terms of compression ratio) **for text**
- The basis for UNIX's **bzip2** tool

Adapted from: https://www.cs.princeton.edu/courses/archive/spr03/cos226/assignments/burrows.html

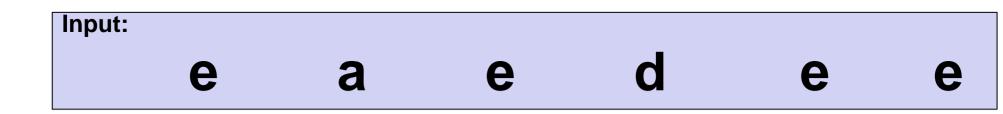
BWT: Compression Algorithm

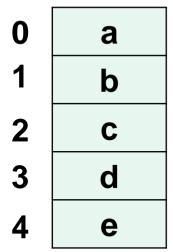
- Three steps
 - Burrows-Wheeler Transform
 - Cluster same letters as close to each other as possible
 - Move-To-Front Encoding
 - Convert output of previous step into an integer file with large frequency differences
 - Huffman Compression
 - Compress the file of integers using Huffman Compression

BWT: Expansion Algorithm

- Apply the inverse of compression steps in reverse order
 - Huffman decoding
 - Move-To-Front decoding
 - Inverse Burrows-Wheeler Transform

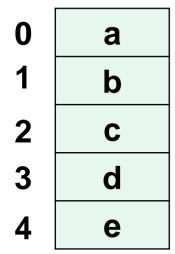
- Initialize an ordered list of the 256 ASCII characters
 - character *i* appears *i*th in the list
- For each character c from input
 - output the index in the list where c appears
 - move c to the front of the list (i.e., index 0)



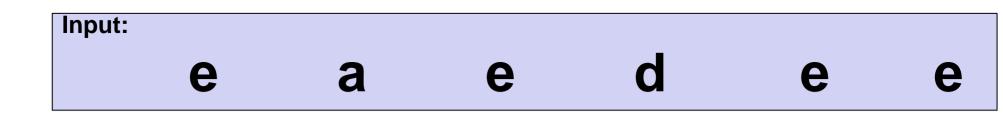


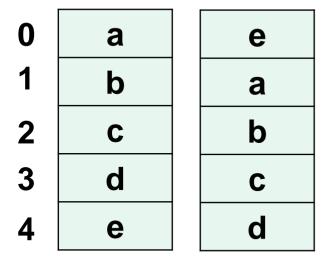






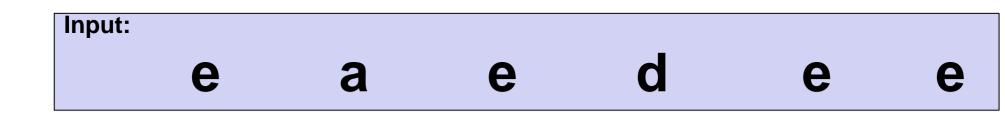


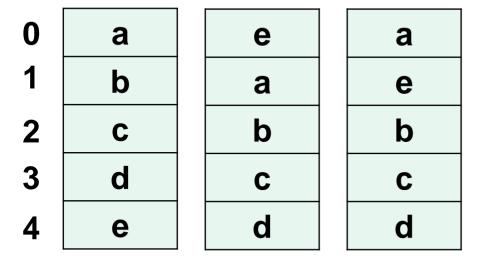




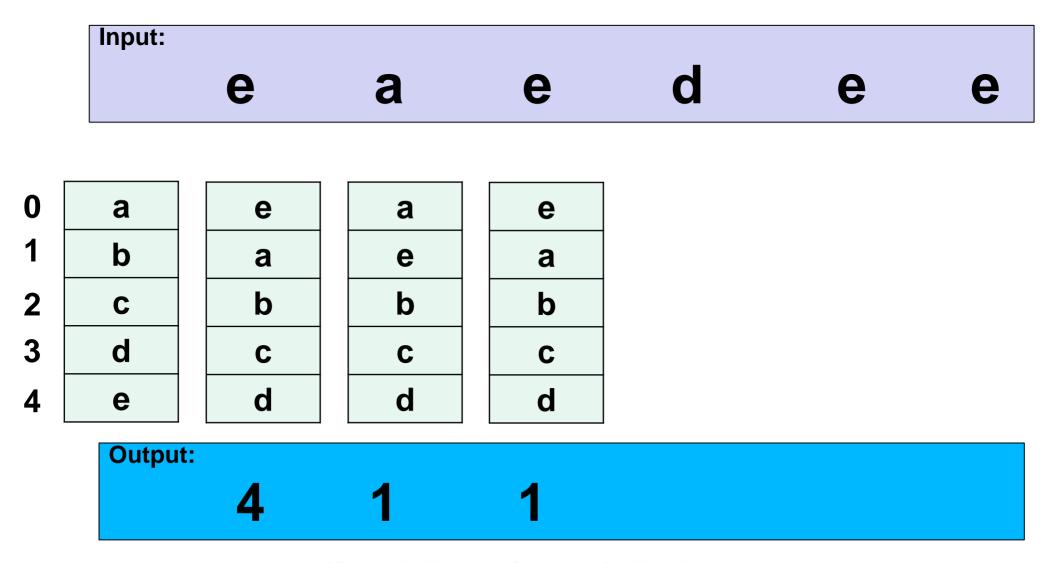
Output:

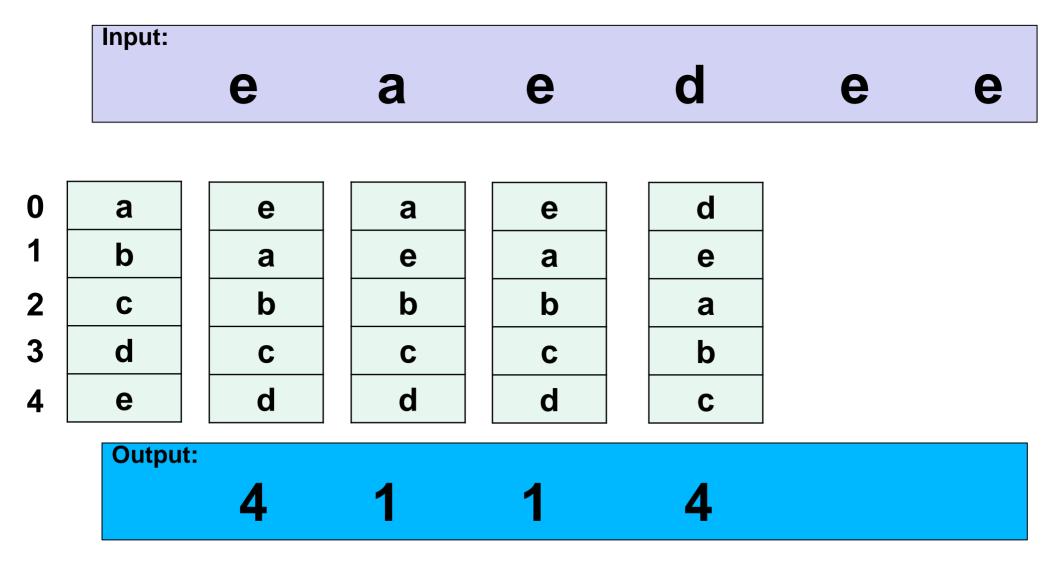
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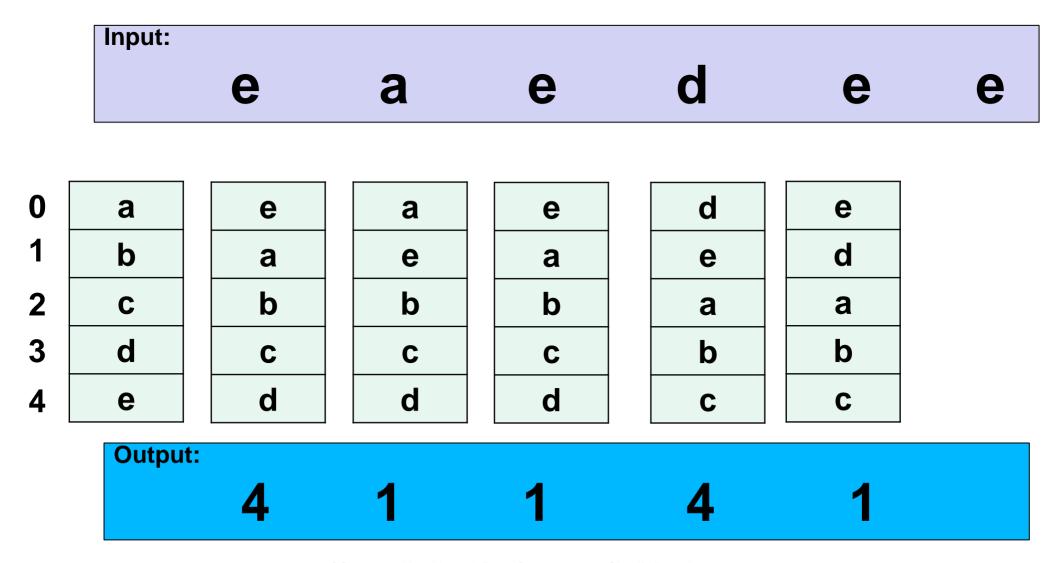


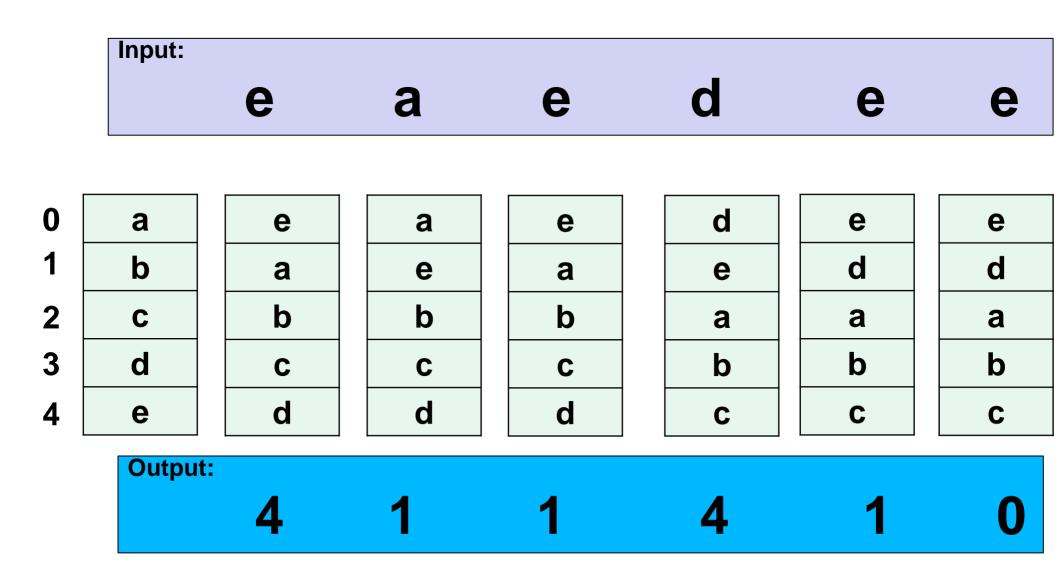


Output: 4 1





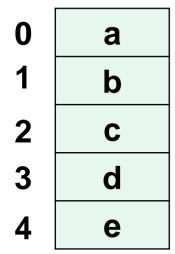




In the output of MTF Encoding, smaller integers have higher frequencies than larger integers

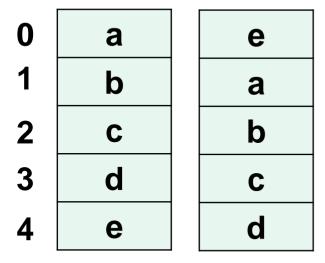
- Initialize an ordered list of 256 characters
 - o same as encoding
- For each integer *i* (*i* is between 0 and 255)
 - o print the *i*th character in the list
 - o move that character to the front of the list



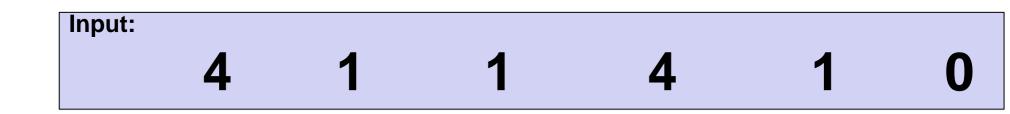


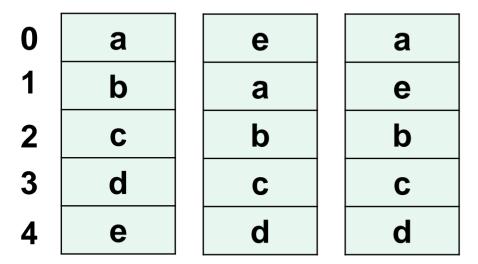




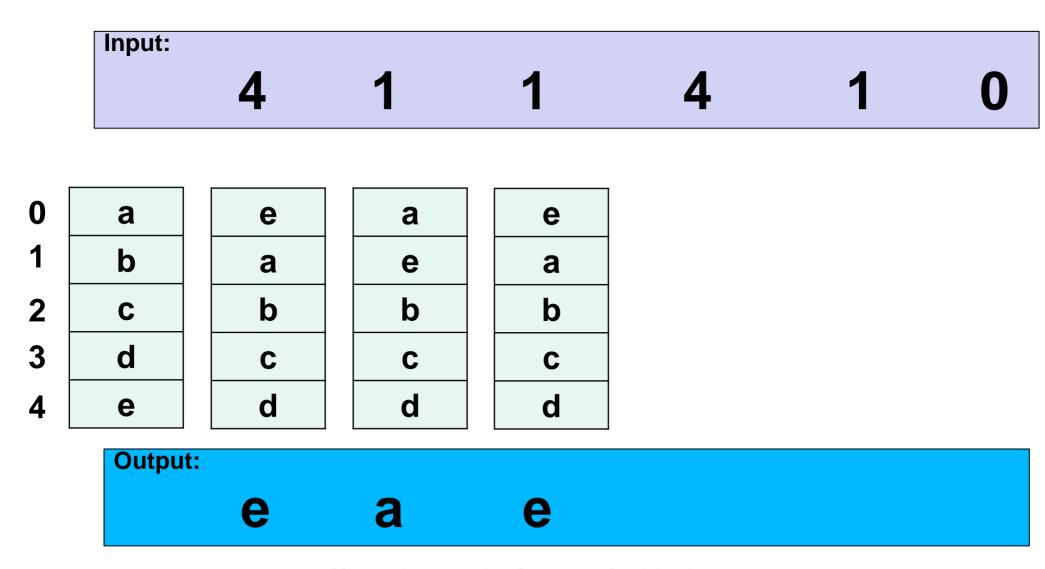


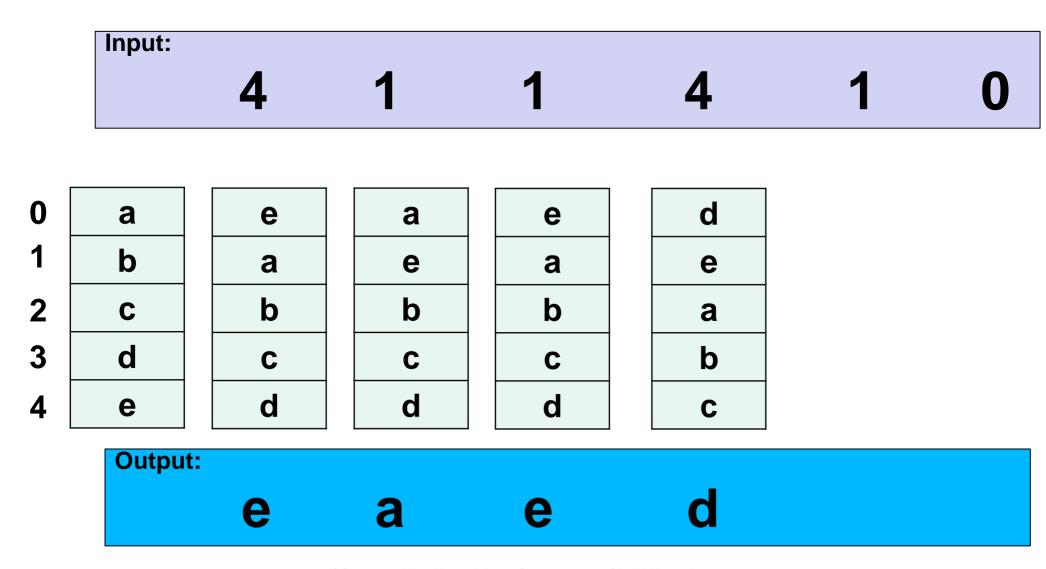


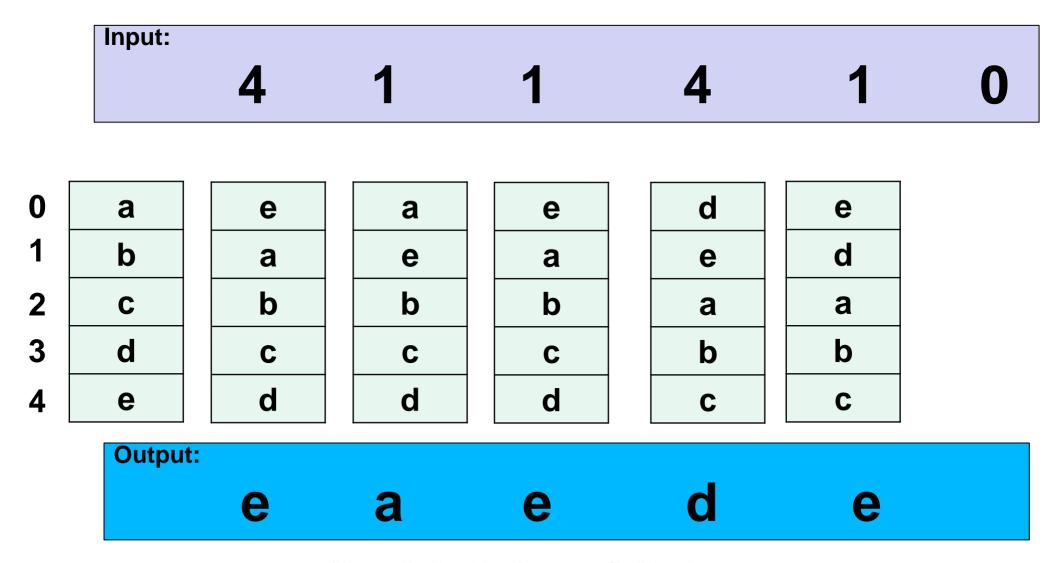


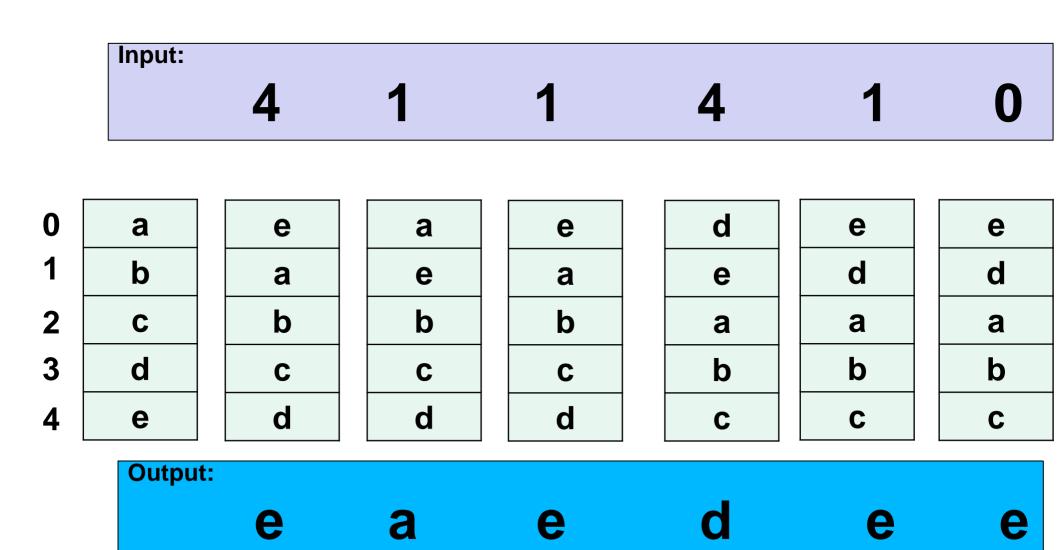












BWT: Compression Algorithm

Compression

- O Burrows-Wheeler Transform
- Move-To-Front Encoding ✓
- Huffman Compression

Expansion

- O Huffman decoding **V**
- Move-To-Front decoding
- Inverse Burrows-Wheeler Transform

Burrows-Wheeler Transform

- Rearranges the characters in the input
 - lots of clusters with repeated characters
 - still possible to recover the original input
- Intuition: Consider the string hen in English text
 - most of the time the letter preceding it is t or w
 - group all such preceding letters together (mostly t's and some w's)

Burrows-Wheeler Transform

- For each block of length N characters
 - generate N strings by cycling the characters of the block one step at a time
 - o sort the strings
 - O output is the **last column** in the sorted table and the **index** of the original block in the sorted array

Burrows-Wheeler Transform

- Example: Let's transform "ABRACADABRA"
- N = 11

AABRACADABR

Cyclic Versions of the string: After Sorting **ABRACADABRA** AABRACADABR BRACADABRAA ABRAABRACAD RACADABRAAB ABRACADABRA **ACADABRAABR** ACADABRAABR CADABRAABRA ADABRAABRAC ADABRAABRAC BRACADA **RDARCAAABB** DABRAABRACA ABRAABRACAD CADABRAABRA BRAABRACADA DABRAABRACA RAABRACADAB RAABRACADAB

RACADABRAAB

Burrows-Wheeler Transform Example 2

Input: ABABABA

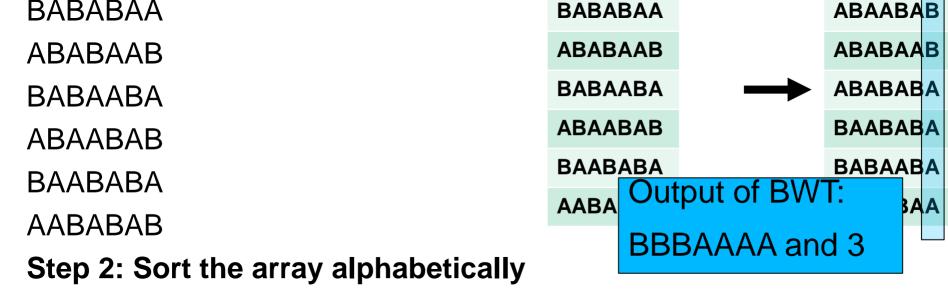
Step 1: Build an array of 7 strings, each a circular rotation of the original original array sorted array

ΔRΔRΔRΔ

by one character



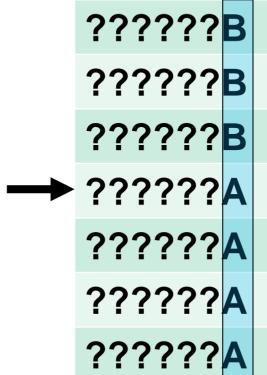
BABABAA



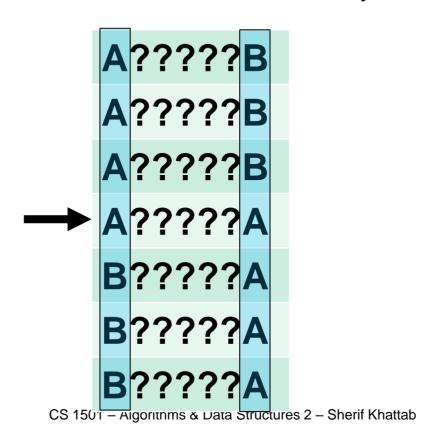
- **Notice that** the first column of the sorted array has the same characters as the last column
 - all columns have the same set of letters
- Step 3: Output the last column of the sorted array and the index of the input string in the sorted array

AARARAR

- Output of BWT:
 - BBBAAAA and 3
- How can we recover ABABABA?
- Step 1: Sort the encoded string
 - BBBAAAA → AAAABBB
 - The first column of the sorted array has the same characters as the last column
 - but in sorted order



- Output of BWT:
 - BBBAAAA and 3
- How can we recover ABABABA?
- Step 1: Sort the encoded string
 - BBBAAAA → AAAABBB
 - This gives us the first column of the sorted array



32

- Output of BWT:
 - BBBAAAA and 3
- How can we recover ABABABA?
- Step 2: Fill an array next[]
 - defined for each entry in the sorted array
 - holds the index in sorted array of the next string in the original array
 - Scan through the first column
 - for each row i holding character c
 - next[i] = first unassigned index of c in the last column original array

ABABABA

BABABAA

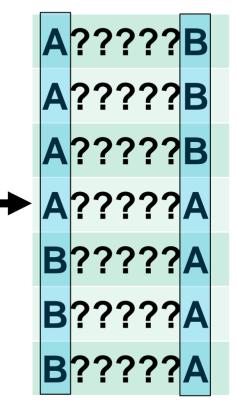
ABABAAB

BABAABA

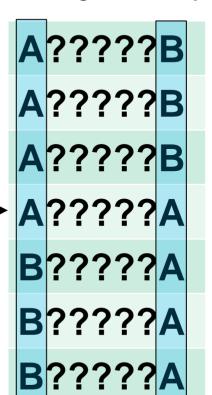
ABAABAB

BAABABA

AABABAB



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next

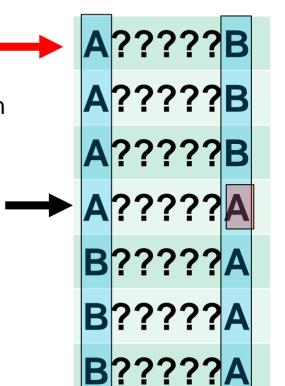
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next

3

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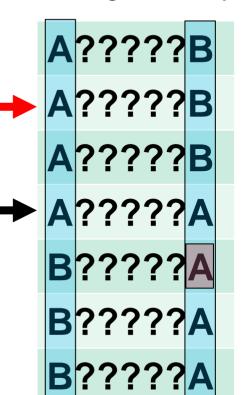
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next

3

4

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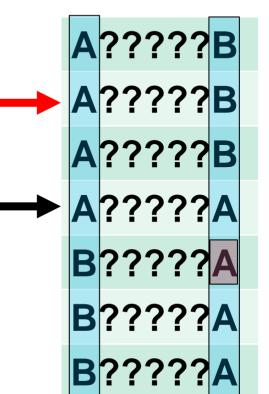
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next

3

4

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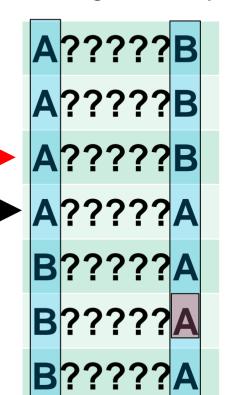
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next

3

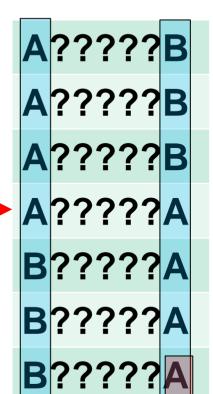
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next

3

4

5

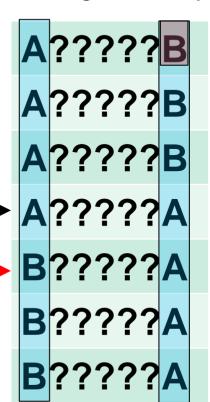
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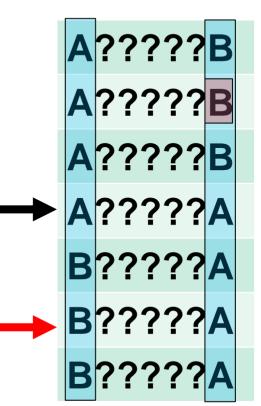
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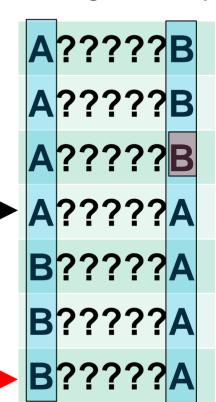
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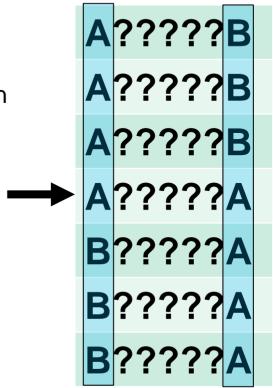
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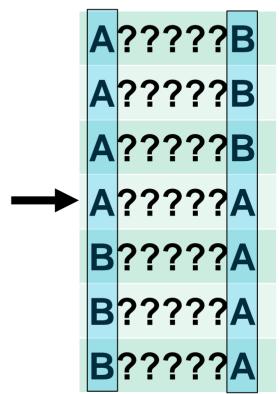


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 - for each row i holding character c
 - next[i] = first unassigned index of c in the last column
- Why does that work?
 - first character of a string becomes the last character in the next string in the original order



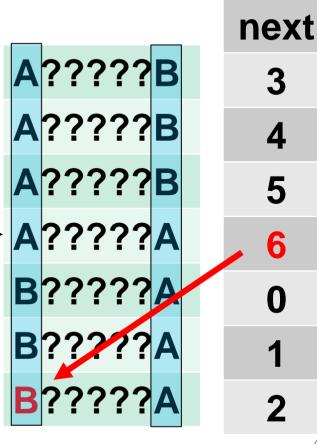
- Output of BWT:
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- How can we recover ABABABA?
- Step 3: Recover the input string using the next[] array
- We can conclude that A is the first character in the input string
 - why?

A??????



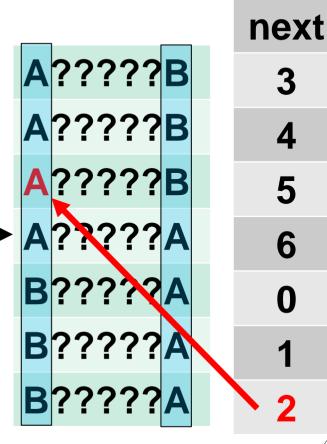
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 - why?
- The next character is the first character of the next string in the original order
 - first character in string at next[3]

AB?????



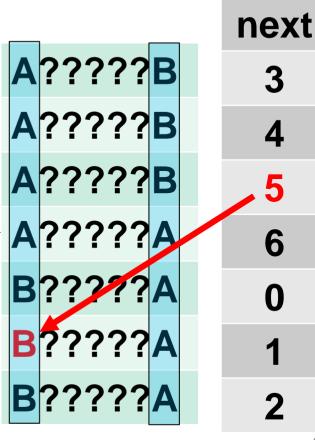
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 - first character in string at next[6]

ABA????



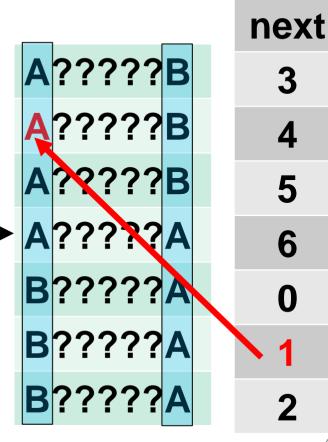
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- How can we recover ABABABA?
- Step 3: Recover the input string using the next[] array
- We can conclude that A is the first character in the input string
 - why?
- The next character is the first character of the next string in the original order
 - first character in string at next[2]

ABAB???



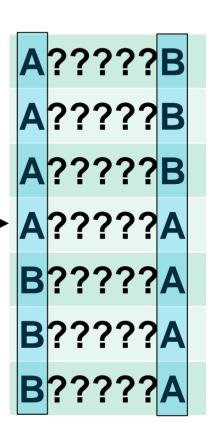
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- How can we recover ABABABA?
- Step 3: Recover the input string using the next[] array
- We can conclude that A is the first character in the input string
 - why?
- The next character is the first character of the next string in the original order
 - first character in string at next[5]

ABABA??



- Output of BWT:
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- How can we recover ABABABA?
- Step 3: Recover the input string using the next[] array
- We can conclude that A is the first character in the input string
 - why?
- The next character is the first character of the next string in the original order
 - first character in string at next[5]

ABABABA



Downsides of Burrows-Wheeler Algorithm

- process blocks of input file
 - O Compared to LZW, which processes the input one character at time
- The larger the block size, the better the compression
 - O But the **longer** the sorting time

Repetitive Minimum Problem

- Input:
 - a (large) dynamic set of data items
- Output:
 - repeatedly find a minimum item
- You are implementing an algorithm that repetitively solve this problem
 - examples of such an algorithm?
 - Selection sort and Huffman tree construction
- What we cover today applies to the repetitive maximum problem as well

Let's create an ADT!

The Priority Queue ADT

- Let's generalize min and max to highest priority
- Primary operations of the PQ:
 - O Insert
 - Find item with highest priority
 - e.g., findMin() or findMax()
 - Remove an item with highest priority
 - e.g., removeMin() or removeMax()
- We mentioned priority queues in building Huffman tries
 - How do we implement these operations?
 - Simplest approach: arrays

Unsorted array PQ

- Insert:
 - Add new item to the end of the array
 - \circ $\Theta(1)$
- Find:
 - Search for the highest priority item (e.g., min or max)
 - \circ $\Theta(n)$
- Remove:
 - Search for the highest priority item and delete
 - \circ $\Theta(n)$

Sorted array PQ

- Insert:
 - Add new item in appropriate sorted order
 - \circ $\Theta(n)$
- Find:
 - Return the item at the end of the array
 - \circ $\Theta(1)$
- Remove:
 - Return and delete the item at the end of the array
 - \circ $\Theta(1)$

So what other options do we have?

- What about a balanced binary search tree?
 - Insert
 - **■** Θ(lg n)
 - Find
 - **■** Θ(lg n)
 - Remove
 - Θ(lg n)
- OK, all operations are Θ(lg n)
 - No constant time operations

Which implementation should we choose?

- Depends on the application
- We can compare the *amortized runtime* of each implementation
- Given a set of operations performed by the application:

Amostized = Total runtime of asymme of operations runtime #operations

Example: Huffman Trie Construction

- K-1 iterations
 - O K is the # unique characters in the file to be compressed
- Fach iteration:
 - O 2 removeMin calls
 - O 1 insert call
- Unsorted Array: Total time Huffman Trie Construction =(K-1)*[2 * K + 1 * 1] = O(K²)
- Sorted Array: Total time Huffman Trie Construction =(K-1)*[2 * 1 + 1 * K] = O(K²)
- Balanced BST: Total time Huffman Trie Construction =(K-1)*[2 * log K + 1 * log K] =
 O(K log K)

Repetitive Highest Priority Problem

Input:

- a (large) dynamic set of data items
 - · each item has a priority
 - e.g., highest priority is minimum item
 - e.g., highest priority is maximum item
- a stream of zero or more of each of the following operations
 - Find a highest priority item in the set
 - Insert an item to the set
 - Remove a highest priority item from the set

Examples

- Selection sort
 - Repeatedly, remove a minimum item from the array and insert it in its correct position in the sorted array
- Huffman trie construction
 - Each iteration: remove a minimum tree from the forest (twice) and insert a new tree

Let's create an ADT!

- The ADT Priority Queue (PQ)
 - Primary operations of the PQ:
 - Insert
 - Find item with highest priority
 - e.g., findMin() or findMax()
 - Remove an item with highest priority
 - e.g., removeMin() or removeMax()

What are possible implementations of the PQ ADT?

	findMin	removeMin	insert
Unsorted Array	O(n)	O(n)	O(1)
Sorted Array	O(1)	O(1)	O(n)
Red-Black BST	O(log n)	O(log n)	O(log n)

Is a BST overkill to implement ADT PQ?

- Balanced BST (e.g., RB-BST) provides log n runntime time for all operations
- Our find and remove operations only need the highest priority item, not to find/remove any item
 - Can we take advantage of this to improve our runtime?
 - Yes!

The heap

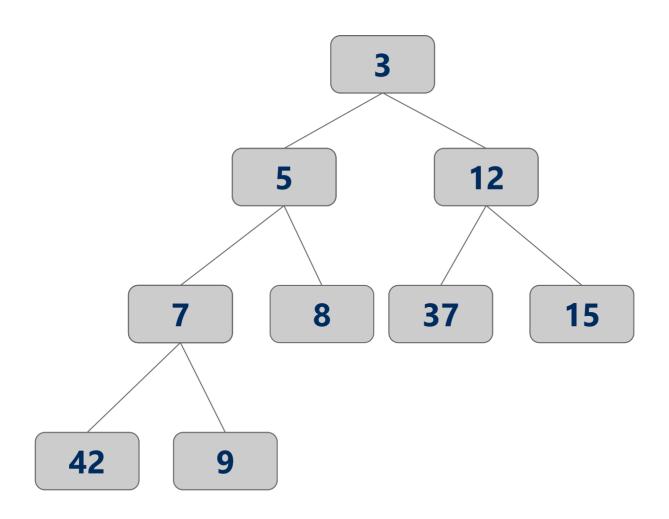
- A heap is complete binary tree such that for each node T in the tree:
 - T.item is of a higher priority than T.right_child.item
 - T.item is of a higher priority than T.left_child.item

- It does not matter how T.left_child.item relates to T.right_child.item
 - This is a relaxation of the approach needed by a BST

The *heap property*

Min Heap Example

• In a Min Heap, a highest priority item is a minimum item



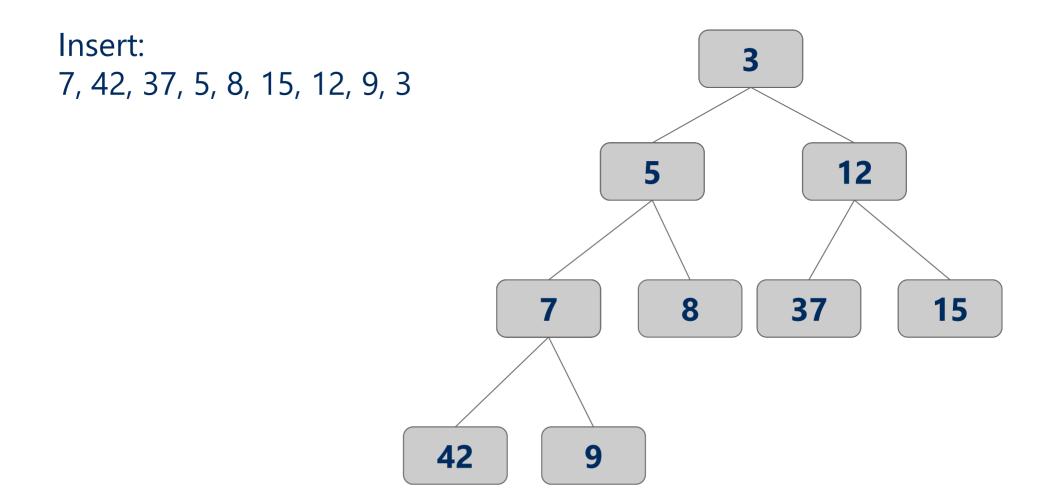
Heap PQ runtimes

- Find is easy
 - Simply the root of the tree
 - $\Theta(1)$
- Remove and insert are not quite so trivial
 - O The tree is modified and the heap property must be maintained

Heap insert

- Add a new node at the next available leaf
- Push the new node up the tree until it is supporting the heap property

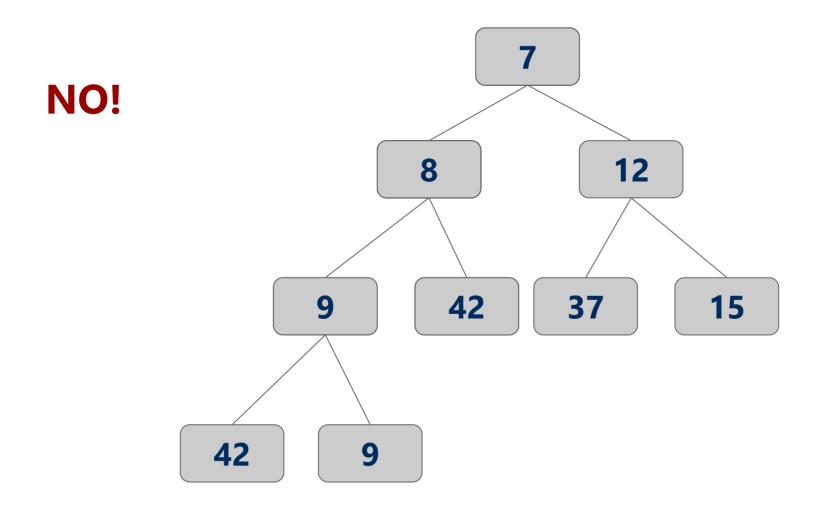
Min heap insert



Heap remove

- Tricky to delete root...
 - O So let's simply overwrite the root with the item from the last leaf and delete the last leaf
 - But then the root is violating the heap property...
 - So we push the root down the tree until it is supporting the heap property

Min heap removal



Heap runtimes

- Find
 - Ο Θ(1)
- Insert and remove
 - O Height of a complete binary tree is Ig n
 - At most, upheap and downheap operations traverse the height of the tree
 - \bigcirc Hence, insert and remove are $\Theta(\lg n)$

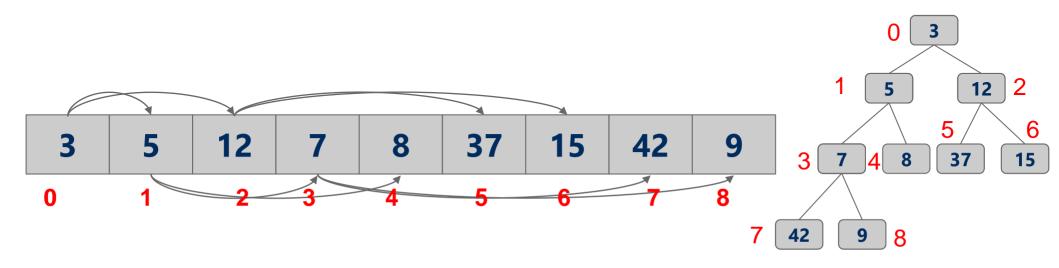
Heap implementation

- Simply implement tree nodes like for BST
 - This requires overhead for dynamic node allocation
 - O Also must follow chains of parent/child relations to traverse the tree
- Note that a heap will be a complete binary tree...
 - O We can easily represent a complete binary tree using an array

Storing a heap in an array

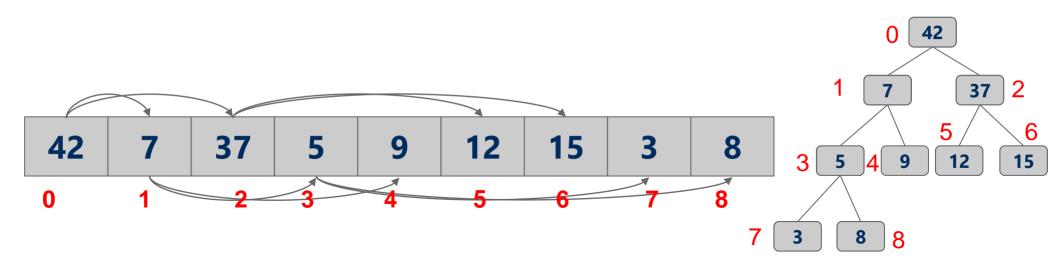
- Number nodes row-wise starting at 0
- Use these numbers as indices in the array
- Now, for node at index i
 - \bigcirc parent(i) = [(i 1) / 2]
 - left_child(i) = 2i + 1
 - O right_child(i) = 2i + 2

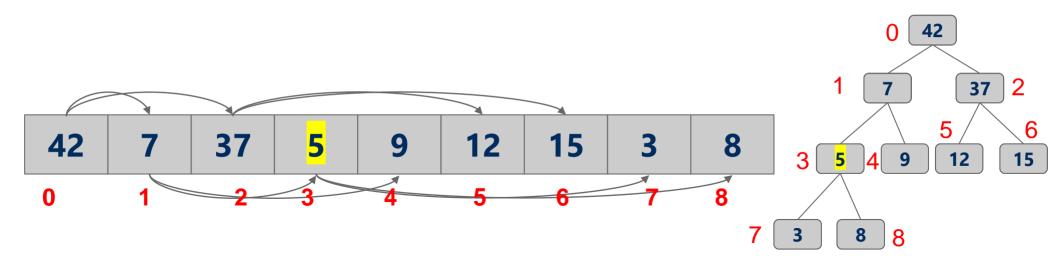
For arrays indexed from 0

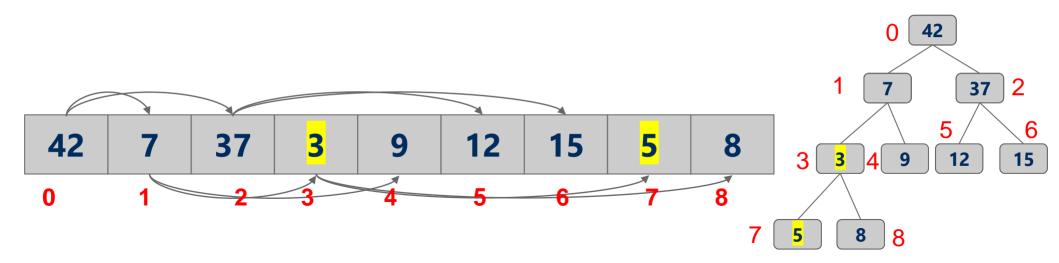


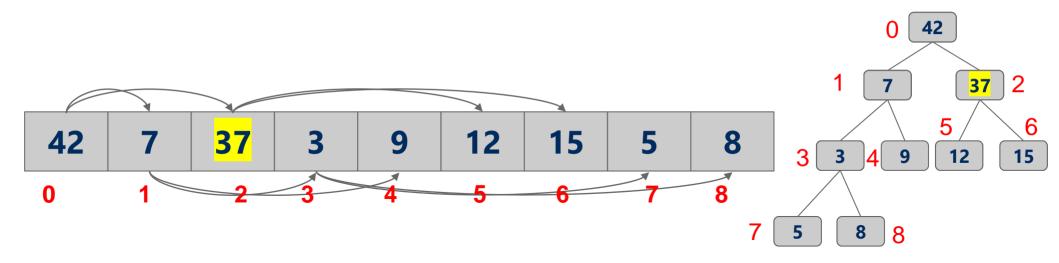
Can we turn any array into a heap?

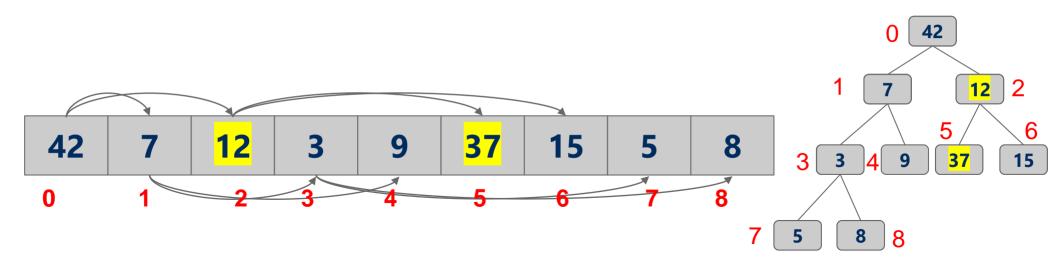
- Yes!
- Any array can be thought of as a complete tree!
- We can change it into a heap using the following algorithm
- Scan through the array right to left starting from the rightmost non-leaf
 - \bigcirc the largest index *i* such that left_child(i) is a valid index (i.e., < n)
 - \bigcirc 2i+1 < n \rightarrow i < (n-1)/2
 - O push the node down the tree until it is supporting the heap property
- This is called the **Heapify** operation

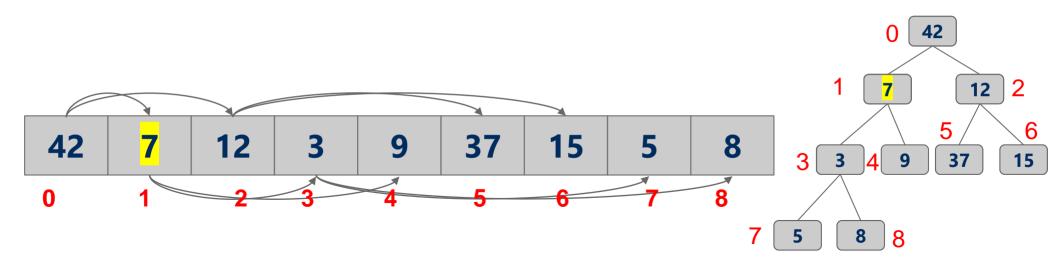


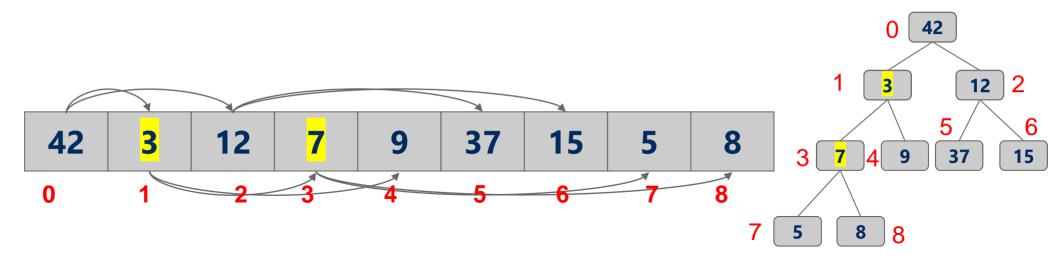


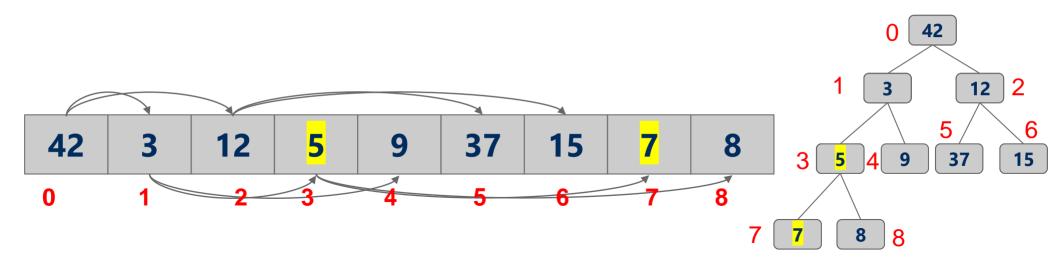


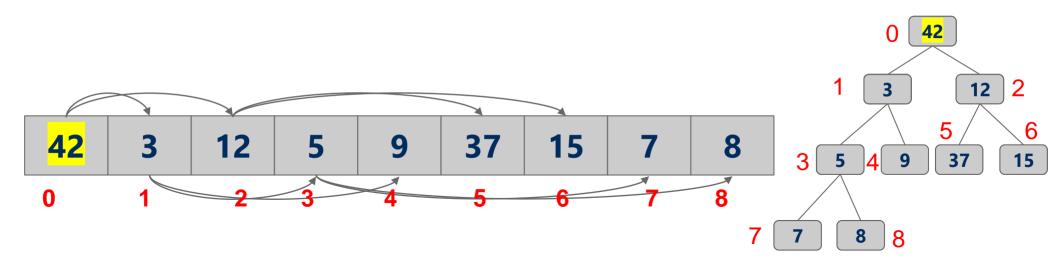


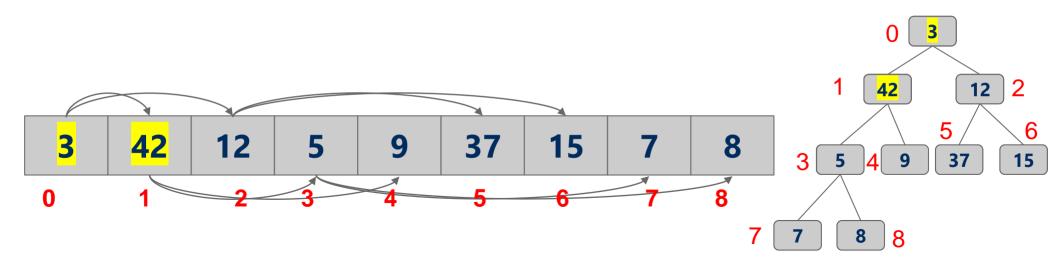


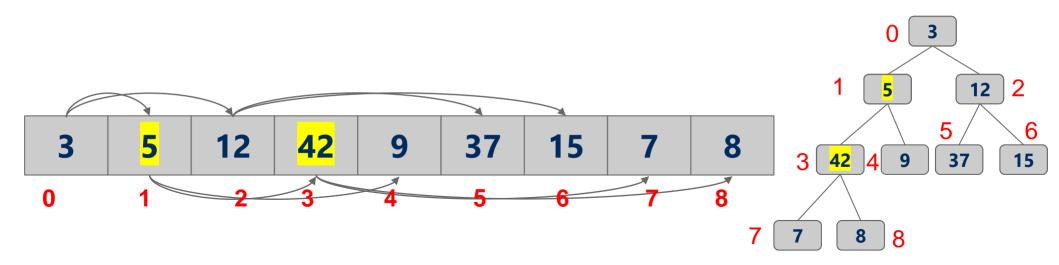


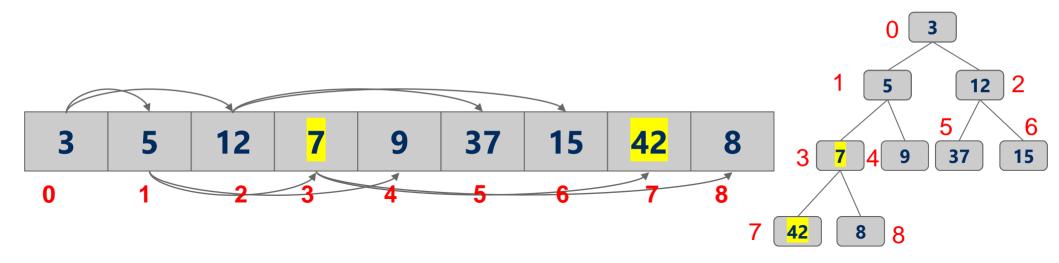


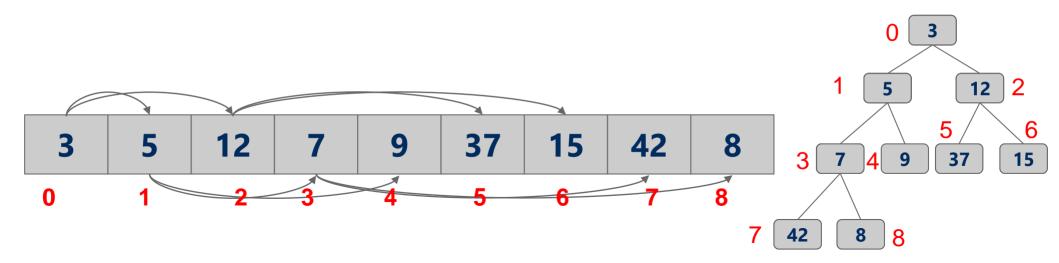










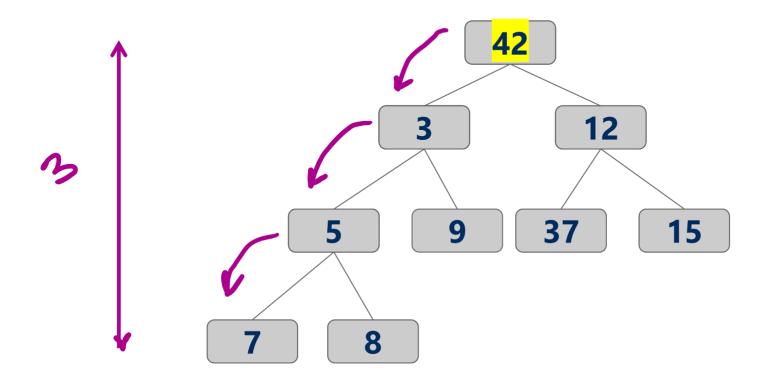


Heapify Running time

- Upper bound analysis:
 - O We make about n/2 downheap operations
 - log n each
 - O So, O(n log n)

Heapify Running time

- A tighter analysis
 - O for each node that we start from, we make at most *height[node]* swaps



Heapify Running time: A tighter analysis

- Runtime = $\sum_{i=1}^{n} height[n]$
- = $\sum_{i=0}^{\log n} number\ of\ nodes\ with\ height\ i$
- Assume a full tree
 - \bigcirc A node with height *i* has 2^i nodes in its subtree including itself
 - O Assume k nodes with height i:
 - O they will have $k2^i$ nodes in their subtrees
 - \bigcirc $k2^i <= n \rightarrow k <= n/2^i$
- So, at most n/2ⁱ nodes exist with height I
- = $\theta(largest term) = \theta(n)$

Heap Sort

- Heapify the numbers
 - MAX heap to sort ascending
 - MIN heap to sort descending
- "Remove" the root
 - O Don't actually delete the leaf node
- Consider the heap to be from 0 .. length 1
- Repeat

Heap sort analysis

- Runtime:
 - O Worst case:
 - n log n
- In-place?
 - O Yes
- Stable?
 - O No

Storing Objects in PQ

- What if we want to **update** an Object in the heap?
 - O What is the runtime to find an arbitrary item in a heap?
 - **■** Θ(n)
 - \blacksquare Hence, updating an item in the heap is Θ(n)
 - O Can we improve of this?
 - Back the PQ with something other than a heap?
 - Develop a clever workaround?

Indirection

- Maintain a second data structure that maps item IDs to each item's current position in the heap
- This creates an indexable PQ

Indirection example setup

- Let's say I'm shopping for a new video card and want to build a heap to help me keep track of the lowest price available from different stores.
- Keep objects of the following type in the heap:

```
class CardPrice implements Comparable<CardPrice>{
      public String store;
      public double price;
      public CardPrice(String s, double p) { ... }
      public int compareTo(CardPrice o) {
            if (price < o.price) { return -1; }</pre>
            else if (price > o.price) { return 1; }
            else { return 0; }
```

Indirection example

- n = new CardPrice("NE", 333.98);
- a = new CardPrice("AMZN", 339.99);
- x = new CardPrice("NCIX", 338.00);
- b = new CardPrice("BB", 349.99);
- Update price for NE: 340.00
- Update price for NCIX: 345.00
- Update price for BB: 200.00

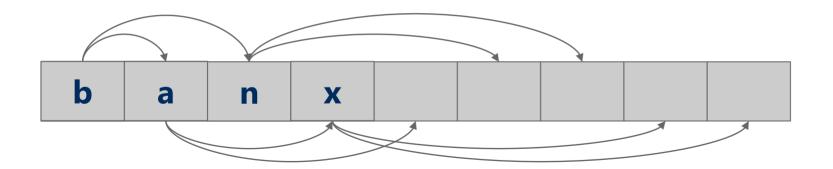
Indirection

"NE":2

"AMZN":1

"NCIX":3

"BB":0



Indexable PQ Discussion

- How are our runtimes affected?
- space utilization?
- how should we implement the indirection?
- what are the tradeoffs?

A new problem!!

- Input: A file containing LinkedIn (LI) accounts and their connections
 - Account1: Connection1, Connection2, ...
 - Account2: Connection1, Connection2, ...

•



CS 1501 – Algorithms & Data Structures 2 – Sherif Khattab

Problem of the Day

- Output: Answer the following questions:
 - Given two LI accounts, how "far" are they from each other?
 - e.g., 1st connection?, 2nd connection?, etc.
 - Are the accounts in the file all connected?
 - If not, how many connected components are there?
 - For each connected component, are there certain accounts that if removed, the remaining accounts become partitioned?

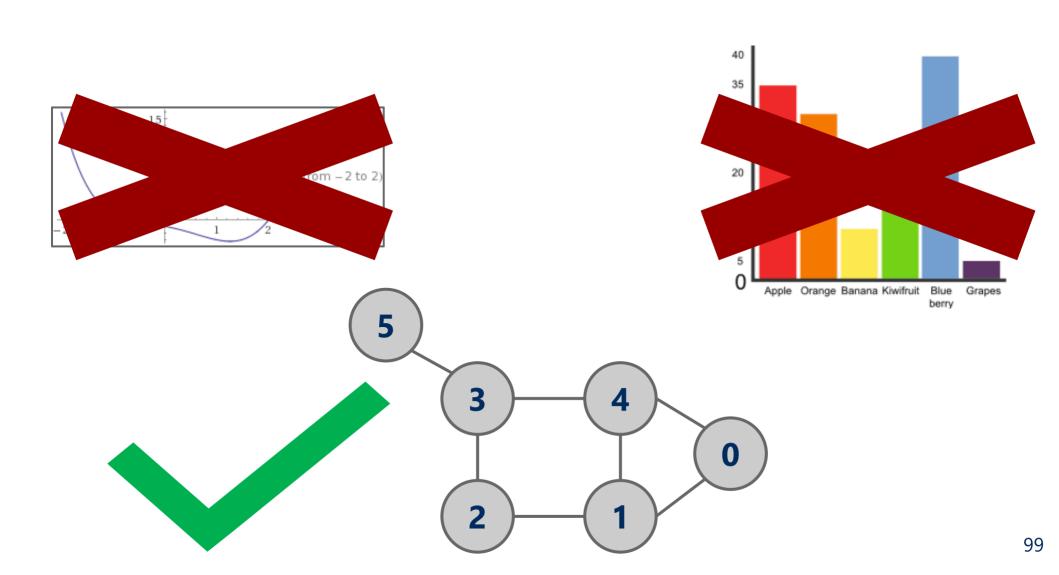


Which Data Type to use?

- Let's think first about how to organize the data that we have in memory
- Note that the operations are different from what we have been used to (search, sort, min, max, add, delete, ...)

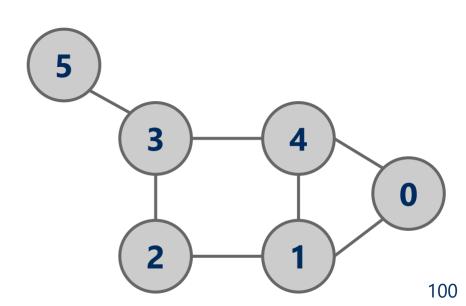
- Account1: Connection1, Connection2, ...
- Account2: Connection1, Connection2, ...
- ...

Graphs!



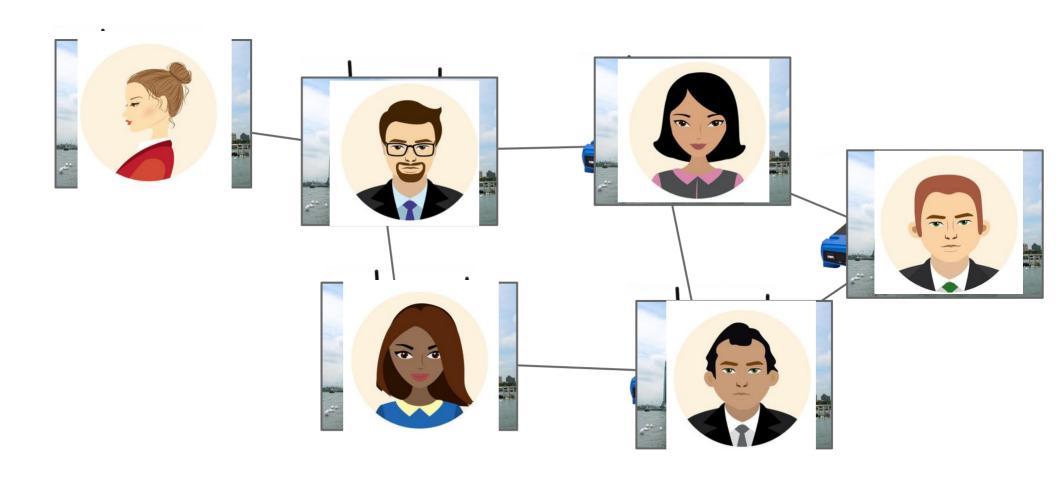
Graphs

- A graph G = (V, E)
 - O where V is a set of vertices
 - O E is a set of edges connecting vertex pairs
- Example:
 - \bigcirc V = {0, 1, 2, 3, 4, 5}
 - \bigcirc E = {(0, 1), (0, 4), (1, 2), (1, 4), (2, 3), (3, 4), (3, 5)}



Why?

• Can be used to model many different scenarios



Some definitions

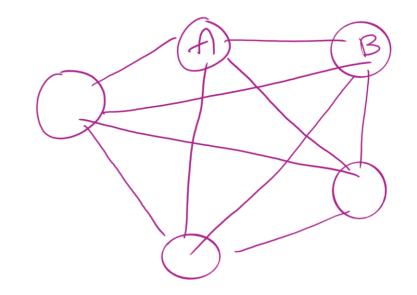
- Undirected graph
 - \bigcirc Edges are unordered pairs: (A, B) == (B, A)
- Directed graph
 - O Edges are ordered pairs: (A, B) != (B, A)
- Adjacent vertices, or neighbors
 - O Vertices connected by an edge

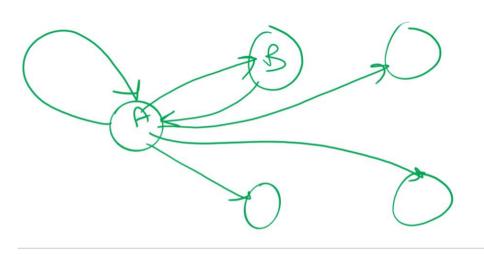
Graph sizes

- Let v = |V|, and e = |E|
- Given v, what are the minimum/maximum sizes of e?
 - O Minimum value of e?
 - Definition doesn't necessitate that there are any edges...
 - **So**, 0
 - O Maximum of e?
 - Depends...
 - Are self edges allowed?
 - Directed graph or undirected graph?
 - In this class, we'll assume directed graphs have self edges while undirected graphs do not

Maximum value of e (MAX)

- Undirected graph
 - O no self edges
 - \circ v*(v-1)?
 - O But, A->B is the same edge as B-> A
 - O Are we counting each twice?
 - \circ v*(v-1)/2
- Directed graph
 - O self edges allowed
 - O v*v?
 - A -> B is a different edge thanB -> A
 - Ov^2





More definitions

• A graph is considered *sparse* if:

$$\bigcirc$$
 e <= v lg v

• A graph is considered *dense* as it approaches $\mathcal{A}\mathcal{A}\mathcal{B}\mathcal{C}\mathcal{C}$ the maximum number of edges

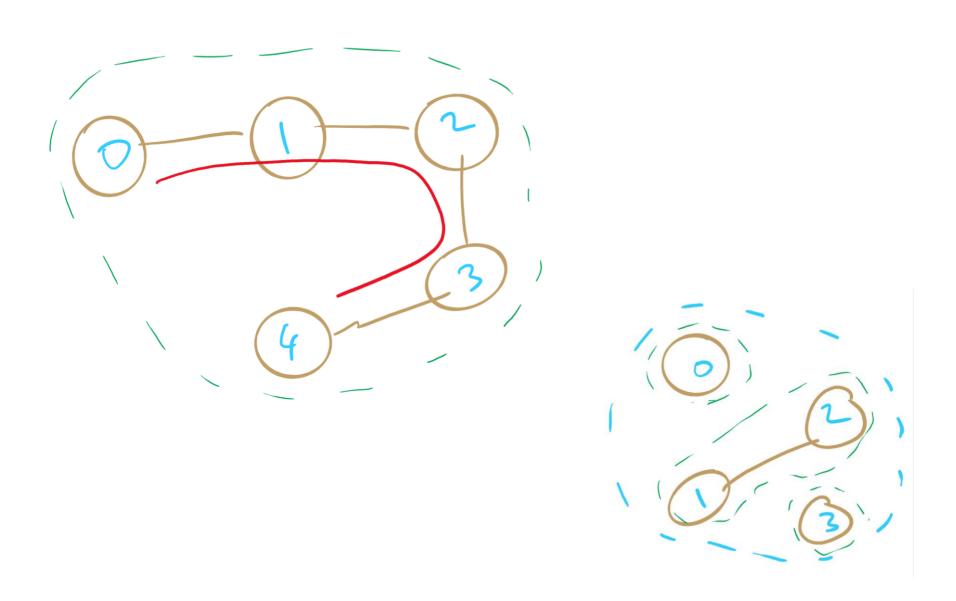
$$\bigcirc$$
 I.e., $e == MAX - \epsilon$

- A complete graph has the maximum number of edges
- Have we seen "sparse" and dense before?



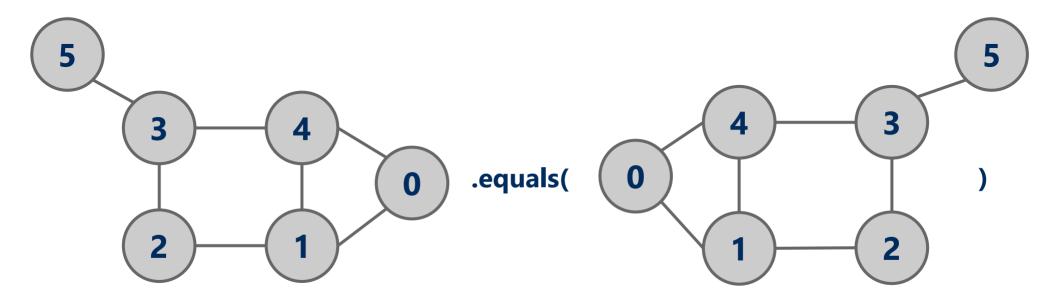


Sparse graphs



Question:

• Is



Representing graphs

- Trivially, graphs can be represented as:
 - List of vertices
 - List of edges
- Performance?
 - O Assume we're going to be analyzing static graphs
 - I.e., no insert and remove
 - O So what operations should we consider?

Graph operations

- Static graphs
 - O check if two vertices are neighbors
 - O find the list of neighbors of a given vertex
 - for directed graphs, in-neighbors and out-neighbors
- Dynamic graphs
 - O add/remove edges
 - Not our focus in this class

Representing graphs

- Trivially, graphs can be represented as:
 - List of vertices
 - List of edges
- Performance?
 - Check if two vertices are neighbors
 - **■** O(e)
 - O Find the list of neighbors of a given vertex
 - O(e)
- Space?
 - \bigcirc $\Theta(v + e)$ memory

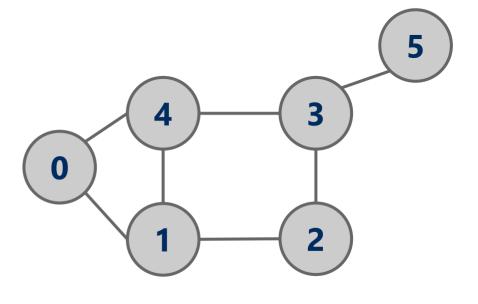
Using an adjacency matrix

Rows/columns are vertex labels

$$\bigcirc$$
 M[i][j] = 1 if (i, j) \in E

$$\bigcirc$$
 M[i][j] = 0 if (i, j) \notin E

	0	1	2	3	4	5
0	0	1	0	0	1	0
1	1	0	~	0	1	0
2	0	1	0	1	0	0
3	0	0	1	0	1	1
4	1	1	0	1	0	0
5	0	0	0	1	0	0



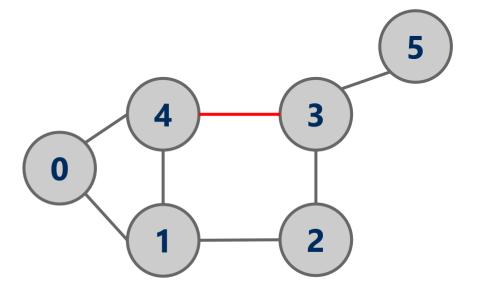
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	0	1	2	3	4	5
0	0	1	0	0	1	0
1	1	0	1	0	1	0
2	0	1	0	1	0	0
3	0	0	1	0	1	1
4	1	1	0	1	0	0
5	0	0	0	1	0	0



Adjacency matrix analysis

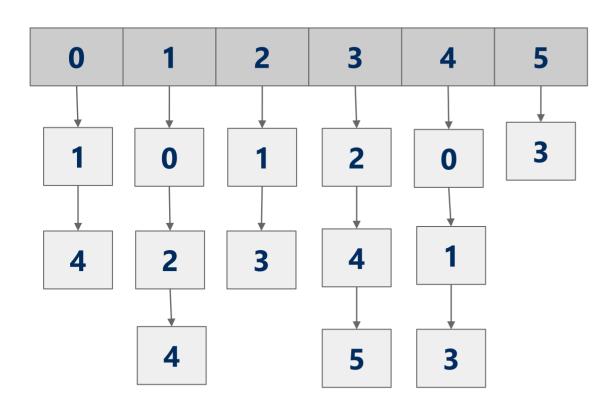
- Runtime?
 - O Check if two vertices are neighbors
 - **■** Θ(1)
 - O Find the list of neighbors of a vertex
 - **■** O(v)
 - \bigcirc O(v²) time to initialize
- Space?
 - $O(v^2)$

	0	1	2	3	4	5
0	0	1	0	0	1	0
1	1	0	1	0	1	0
2	0	1	0	1	0	0
3	0	0	1	0	1	1
4	1	1	0	1	0	0
5	0	0	0	1	0	0

Adjacency lists

Array of neighbor lists

O A[i] contains a list of the neighbors of vertex i



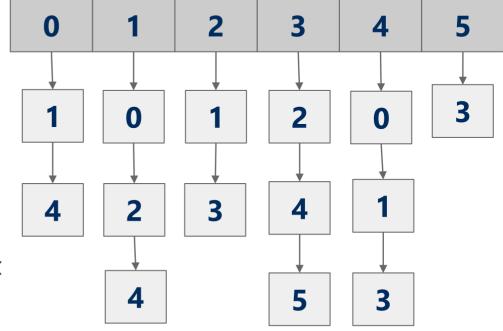
Adjacency list analysis



- Check if two vertices are neighbors
- O Find the list of neighbors of a vertex
 - **■** Θ(d)
 - d is the degree of a vertex (# of neighbors)
 - **■** O(v)

• Space?

- \bigcirc $\Theta(v + e)$ memory
- O overhead of node use
- \bigcirc Could be much less than v^2



Comparison

 Where would we want to use adjacency lists vs adjacency matrices?

- Dense graphs?
- Sparse graphs?
- What about the list of vertices/list of edges approach?