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OS LAB-8

- 1. Write your own C handlers to handle the following signals:
- a. Send a stop signal using Ctrl-Z
- b. Segmentation fault
- c. Divide by zero error

Code:

stop_signal.c:

```
1 #include<stdio.h>
 2 #include<signal.h>
 3 #include<unistd.h>
 4 #include<stdlib.h>
 6 void myhandler(int mysignal)
 8 printf("Exiting\n");
 9 exit(0);
10 }
11
12 int main(int argc, char * argv[])
13 {
14 signal(SIGTSTP, myhandler);
15
16 while(1)
17 {
18 printf("pid = %d\n", getpid());
19 sleep(1);
20 }
21 return 0;
22 }
```

```
alaric@alaric-virtual-machine:~/Desktop$ gcc stop_signal.c

alaric@alaric-virtual-machine:~/Desktop$ ./a.out

pid = 3227

pid = 3227
```

segmentation.c:

```
1 #include <stdio.h>
 2 #include <stdlib.h>
 3 #include <signal.h>
 4 #include <unistd.h>
 6 void myhandle(int signum)
 8 printf("There is a segmentation fault!\nPlease check!");
9 exit(2);
10 }
11
12 int main()
13 {
14 int *p = NULL;
15 signal(SIGSEGV, myhandle);
16 *p = 1;
17
18 return 0;
19 }
20
```

```
alaric@alaric-virtual-machine:~/Desktop$ ./a.out
There is a segmentation fault!
Please check!alaric@alaric-virtual-machine:~/Desktop$
```

divide_by_zero.c:

```
1 #include <stdio.h>
2 #include <stdlib.h>
 3 #include <signal.h>
4 #include <unistd.h>
 6 void myhandle(int signum)
7 {
8 printf("There is a divide by zero error\n");
9 exit(2);
10 }
11
12 int main()
13 {
14 int result;
15 int v1, v2;
16 \text{ v1} = 100;
17 \text{ v2} = 0;
18 printf("dividing: %d/%d\n", v1, v2);
19 signal(SIGFPE, myhandle);
20 result = v1 / v2;
21
22 return 0;
23 }
24
alaric@alaric-virtual-machine:~/Desktop$ gcc divide_by_zero.c
alaric@alaric-virtual-machine:~/Desktop$ ./a.out
dividing: 100/0
There is a divide by zero error
```

2. Child process that kills Parent process.

Code:

child_kills_parent.c:

```
1 #include <stdio.h>
2 #include <signal.h>
3 #include <unistd.h>
 4 #include <stdlib.h>
 6 void myhandle(int signo)
 8 if (signo == SIGINT)
9 printf("Signal received by parent and got terminated...\n");
10 return;
11 }
12
13 int main()
14 {
15 pid t pid, ppid;
16 ppid = getpid();
17 int x = 7;
18 printf("ppid = %d\n", ppid);
20 if ((pid = fork()) == 0)
21 {
22 x++;
23 printf("x:%d\n", x);
24 sleep(1);
25 printf("Signal sent to parent..\n");
26 kill(ppid, SIGINT);
27 }
28 else
29 {
30 x = x + 5;
31 printf("x:%d\n", x);
32 signal(SIGINT, myhandle);
33 sleep(5);
34 }
35
36 return 0;
37 }
 laric@alaric-virtual-machine:~/Desktop$ gcc child_kills_parent.c
alaric@alaric-virtual-machine:~/Desktop$ ./a.out
ppid = 2820
x:12
x:8
Signal sent to parent..
Signal received by parent and got terminated...
```

3. Write two c programs: One displaying the PID infinitely and the other program sending a signal to terminate the first program.

Code:

victim.c:

```
1 #include <stdio.h>
2 #include <signal.h>
3 #include <unistd.h>
4 #include <stdlib.h>
5
6 int main(int argc, char* argv[])
7 {
8 while(1)
9 {
10 printf("pid = %d\n", getpid());
11 sleep(1);
12 }
13
14 return(0);
15 }
```

killer.c:

```
1 #include <stdio.h>
2 #include <signal.h>
3 #include <unistd.h>
4 #include <stdlib.h>
5
6 int main(int argc, char* argv[])
7 {
8 signal(SIGKILL, SIG_DFL);
9 int pid;
10 printf("Enter process ID: ");
11 scanf("%d",&pid);
12 kill(pid, SIGKILL);
13
14 return(0);
15 }
```

```
alaric@alaric-virtual-machine:~/Desktop$ gcc victim.c
alaric@alaric-virtual-machine:~/Desktop$ ./a.out
pid = 4958
```

```
alaric@alaric-virtual-machine:~/Desktop$ gcc killer.c
alaric@alaric-virtual-machine:~/Desktop$ ./a.out
Enter process ID: 4958
```