## Alasdair

Youtube video: <a href="https://youtu.be/6ym87lrX8uE">https://youtu.be/6ym87lrX8uE</a>

Youtube video netcoded: obs only recorded a single window- will try to work this on reupload if able

Features: Walk around a nav mesh world, in this 'Pikmin' inspired course work. Create your cat swarm by gathering kittens and throw them at dangerous geese wandering around the world.

Menu controls: P: pause, C: start as client, V: start as server, B: start offline- (note unless fixed start offline does not currently spawn player- use as client to see offline mode without server instance running)

Movement: wasd

Kitten select: hover mouse over location and click with 'left click' mouse button

Kitten throw: 'right click' mouse button when a kitten is near

## **Features as Tick Sheet**

Bonus	Featu	ıres-
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$\checkmark$	Kittens move in swarm: A simple implementation of boids has been implemented
	so kittens follow the player as a flock
$\checkmark$	Tags, Layers and Trigger Colliders: The player can select kittens by hovering their
	mouse over the kittens. This can be done since collisions can ignore impulse
	calculations for gameObjects on certain layers. Similarly the cats know when they
	have collided with the relevant gameObject as a tag system informs them of what
	they have collided with.

## Play

	have collided with the relevant gameObject as a tag system informs them of what they have collided with.
Player	Movement-
$\checkmark$	Player can move: Use wasd to move the player character
$\checkmark$	Player can rotate: The player rotates to move direction
	<b>Player uses forces/impulses</b> : The player moves using addForce methods- as do kittens & all other navMesh agents
	Player uses torque/Impulses for rotation:
AABB a	and sphere collision-
$\checkmark$	Sphere/Sphere: Included- same as tutorial
$\checkmark$	Sphere/AABB: Included- same as tutorial
$\checkmark$	AABB/AABB: Included- same as tutorial
Racio E	extra collision:

## Basic Extra collision:

	Something vs Plane:
$\checkmark$	OBB vs Sphere: Navmesh world uses OBB- demonstrated with ramps in world
$ \checkmark $	Raycast vs world: Used in multiple places.

1. Projecting sphere trigger object to world position from mouse to select kittens

- 2. Raycast start point from object into navmesh dimensions (used so navmesh paths can be layered on top of each other)
- 3. Enemy vision- if there are no collisions between enemy and player then player is considered 'seen'

Collision	on Resolution:
$\checkmark$	Projection method used: same as seen in tutorial coursework
$\checkmark$	Impulse method used: same as seen in tutorial coursework
$\checkmark$	Multiple coefficients of restitution: set and get methods for restitution are included
	on objects. In this scene spheres have a higher restitution to demonstrate the effect
	Penalty method used: not included
	ul Behaviour:
$\leq$	Simple menu implemented: Pushdown Automata in Main menu system
	Multiple different obstacle types: not included
Gamei	olay Effects:
•	Player can collect bonuses: Player collects points when kittens are collected-
	Kittens then follow the player once selected
	Player can win Game: The game is won when all (50) cats are collected and
ت	brought back to the green square
$\overline{A}$	Player can lose Game: The game is lost when the player touches an enemy
	Player shown final score: The score is displayed on the UI and a menu screen
_	pops up on death with final score
Advan	ced AI:
$\checkmark$	Al Opponent present: An Al opponent navigates the world and searches for the
	player- if a player is spotted it will race towards them
$\checkmark$	State based Opponent AI: Enemy uses behaviour tree with multiple states
$\checkmark$	Behaviour Tree Opponent AI: Enemies & Kittens use behaviour tree
$\checkmark$	Al using raycasts: Mentioned in raycasts section- enemy vision uses raycasts
	Al can collect bonuses: not included
$\checkmark$	Al can avoid Obstacles: Enemy follows navmesh including ramps without falling off
	the edge (enemies can also go under existing navmesh paths for tunnel like areas-
	e.g under the sloped block)
	Al can respawn/ teleport if needed: not included
Pathfir	anding:
ااااااااا 	Grid based Pathfinding present: AI Kittens, Swarm and Enemies use navmesh
	pathfinding, but grid based pathfinding still exists in code base from tutorial
	Al uses pathfinding: Enemies path find to waypoints and player
	navmesh pathfinding
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Constr	aints:
$\checkmark$	Position constraint demonstrated: Bridge from tutorial within project
$\checkmark$	An obstacle uses constraints: Bridge from tutorial within project
	Orientation/ other constraints demonstrated:
Advan	ced collision resolution:
	Penalty method used: Not included
	Friction applied during resolution: Not included
Advan	ced collision detection:
	Capsule vs Sphere: Not included
	Capsule vs OBB/AABB: Not included
	Capsule vs Capsule: Not included
	OBB vs OBB: Not included
	Spatial Acceleration structures used: not included
Advan	ced menu:
	User can select different game types: Start as client, start as server and start
V	offline can each be selected from start which will start the game in a different
	gamemode
abla	Appropriate handling of menu state: States are changed using pushdown
	automata, pause activates when p is pressed and game starts on starting state.
Netwo	rking:
$\checkmark$	Client can connect to server: included as specified
$\checkmark$	Client can send packets: included as specified- client sends acknowledgement
	packages when receiving a package (these are not used in any way, but they are
_	sent)
$\checkmark$	Client can receive packets: included as specified
$\checkmark$	Server can send packets: included as specified
$\checkmark$	Server can receive packets: included as specified
	Client sends/receives high scores: included as specified
	Server sends/receives high scores: included as specified
$\checkmark$	Player Position is sent across network: Server player is synced across both
	clients where the client is in a 'spectate mode'
	Game state is sent via network: not included
	Goose (enemy AI) state is sent via network: not included