Morphological Analysis

Major	Branch
Motor	DC Servo Stepper Brushless
Wheel Number	2 3 4 5
Base Material	Wood 3D Print Iron Aluminum
Wheels	Regular Spherical
Fixing types	(Nails) Wood Clips Tape
Base Shape	Triangle round Rectangle Square
Box	Above base In the base

by using Morphological Analysis, I design 3 different robot arm base and I choose the Blue one Because from we see in the table is the best choice.

