

Bayesian inference for spatial GP models:

Part 2

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Review of last lecture

- Gibbs sampler: Generate samples from $p(X_1, X_2)$ by iteratively generating samples from $p(X_1^{(t)} | X_2^{(t-1)})$ and $p(X_2^{(t)} | X_1^{(t)})$
- Implementing our own Gibbs sampler for the **unmarginalized model**: $y \sim N(X\beta + w, \tau^2 I)$, $w \sim N(0, \sigma^2 R(\phi))$
 - Assume ϕ is known
 - **Priors**: $\sigma^2 \sim IG(a_\sigma, b_\sigma)$, $\tau^2 \sim IG(a_\tau, b_\tau)$ and $\beta \sim N(\mu, V)$
 - Full conditionals:

$$\beta \mid \sigma^2, \tau^2, w, y \sim N(\mu^*, V^*)$$

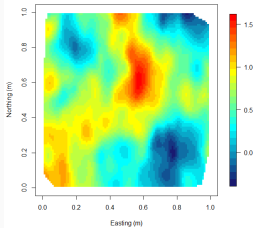
$$w \mid \sigma^2, \tau^2, \beta, y \sim N(m, C^*)$$

$$\sigma^2 \mid \beta, \tau^2, w, y \sim IG(a_\sigma^*, b_\sigma^*)$$

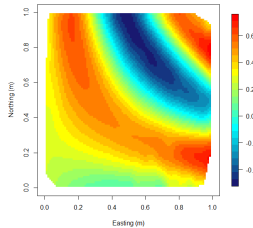
$$\tau^2 \mid \beta, \sigma^2, w, y \sim IG(a_\tau^*, b_\tau^*)$$

Data analysis

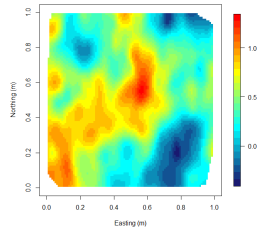
- Dataset 3 from Lecture 1
- True model: $y(s) \sim N(0.2 - 0.3x(s) + w(s), 0.01)$,
 $w(s) \sim GP, Cov(w(s_i), w(s_j)) = 0.25 * exp(-2||s_i - s_j||)$



$y(s)$



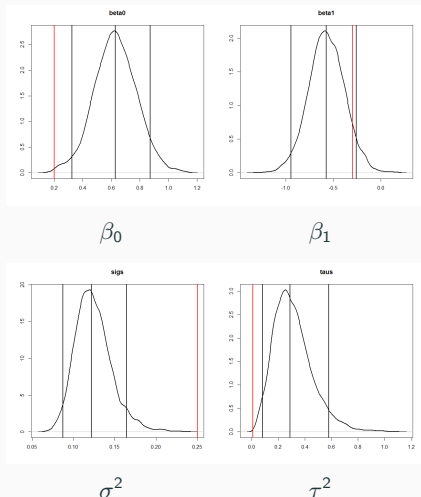
$x(s)$



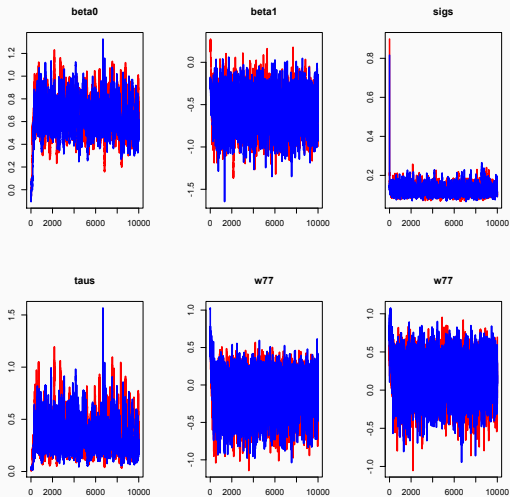
$w(s)$

Parameter posteriors

- ϕ is kept fixed at 4.23 (estimated value from variogram fitting)
- Gibbs sampler for w , β , σ^2 and τ^2



Convergence diagnostics: Trace plots



Convergence diagnostics: Gelman-Rubin shrink factor

- Run chains of length N with overdispersed initial values
- Discard the first N_b draws of each chain as burn-in
- For each variable θ , calculate the **within-chain** variance
$$W = \frac{1}{m} \sum_{j=1}^m \frac{1}{N-N_b-1} \sum_{i=N_b+1}^N (\theta^{(ij)} - \bar{\theta}_j)^2$$
- For each variable θ , calculate the **between-chain** variance
$$B = \frac{N-N_b}{m-1} \sum_{j=1}^m (\bar{\theta}_j - \bar{\theta})^2 \text{ where } \bar{\theta} = \frac{1}{m} \sum_{j=1}^m \bar{\theta}_j$$
- Calculate the **Gelman-Rubin shrink factor** as
$$R = \sqrt{\frac{(1 - \frac{1}{N-N_b})W + \frac{1}{N-N_b}B}{W}}$$
- $R > 1.1$ or 1.2 indicates lack of convergence
- **coda** package in R gives the GR-shrink factors for each variable

Convergence diagnostics: Gelman-Rubin shrink factor

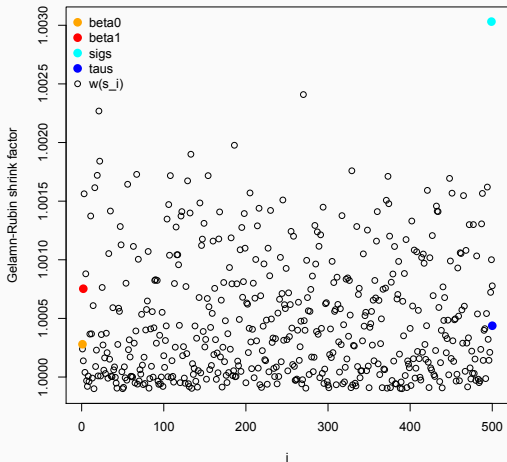


Figure: GR shrink factor for dataset 3

Convergence diagnostics: Plots of Gelman-Rubin shrink factor

- Plots of GR shrink factor against MCMC iteration number can help determine the burn-in

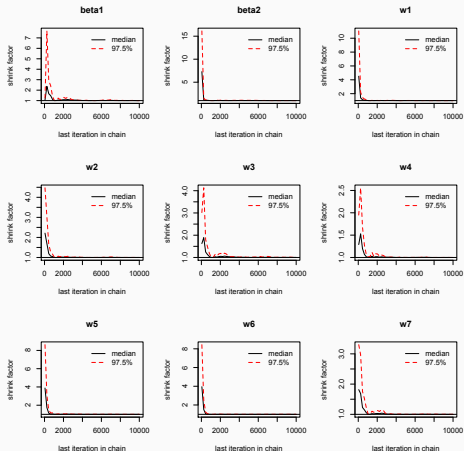


Figure: GR shrink factor as a function of MCMC iteration for dataset 3

Convergence diagnostics: Plots of Gelman-Rubin shrink factor

- Plots of GR shrink factor against MCMC iteration number can help determine the burn-in

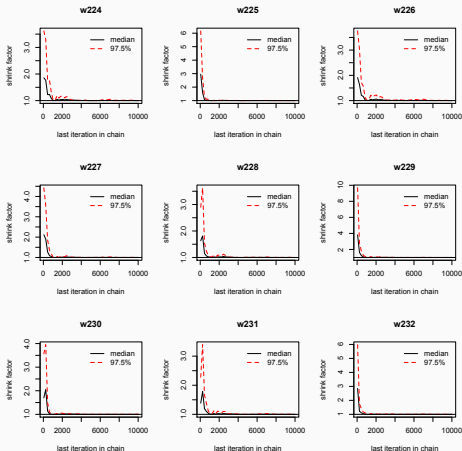
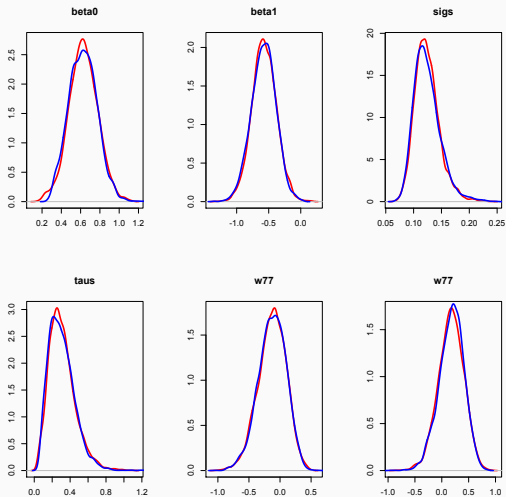


Figure: GR shrink factor as a function of MCMC iteration for dataset 3

Convergence diagnostics: Density plots



Model comparison using Bayesian output

- With holdout data we can use RMSPE (using posterior means or medians), out-of-sample CP (coverage probability) and CIW (confidence interval width) based on posterior quantiles

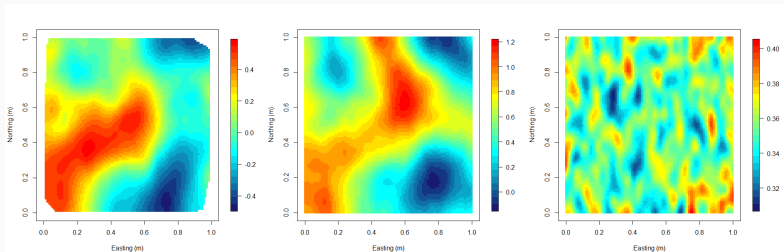
Model comparison using Bayesian output

- **Deviance Information Criterion (DIC)** (Spiegelhalter, 2002) uses the posterior samples for model comparison
- DIC for the model $l(y|\theta)$ is based on the **deviance**
 $D(y, \theta) = -2 \log l(y|\theta)$
- $\bar{D}(y) = E(D(y, \theta)|\theta) \approx \frac{1}{N} \sum_{i=1}^N D(y, \theta^{(i)})$
- $p_D = \bar{D}(y) - D(y, \bar{\theta})$ where $\bar{\theta} = E(\theta|y) \approx \frac{1}{N} \sum_{i=1}^N \theta^{(i)}$
- $DIC = \bar{D}(y) + p_D$
- The p_D term can be interpreted as **effective number of parameters** in the model and hence **penalizes more complex models** (similarity to AIC and BIC)

Posterior predictive distributions

- For the unmarginalized model, posterior samples for $w(s)$ are already generated for all s in the training data locations S
- Posterior predictive distributions $\tilde{y}(s)$ can be obtained using composition sampling:
 - If $s_0 \notin S$, generate samples from $w(s_0) | y$ using $w(s_0)^{(j)} | \cdot \sim N(c(s_0)'C^{-1}w^{(j)}, \sigma^{2(j)}(1 - r(s_0)'R^{-1}r(s_0)))$
 - $r(s_0) = \text{cor}(w(s_0), w)$ and $R = \text{cor}(w)$
 - If ϕ was also sampled, replace r and R by $c^{(j)}$ and $C^{(j)}$
 - For any s , generate $\tilde{y}(s)^{(j)} = N(x(s)'\beta^{(j)}, \tau^{2(j)})$

Posterior surfaces



$w(s) | y$

$\tilde{y}(s) | y$

$\text{var}(\tilde{y}(s) | y)$

Marginalized model

- Unmarginalized model has n additional parameters (w)
- May lead to slow MCMC convergence
- Marginalized model: $y \sim N(X\beta, \sigma^2 R(\phi) + \tau^2 I)$
- **Pros:** Only $p + 3$ parameters
- **Cons:** Even the full conditionals are not useful (except for β)
- How to do MCMC?

Metropolis algorithm

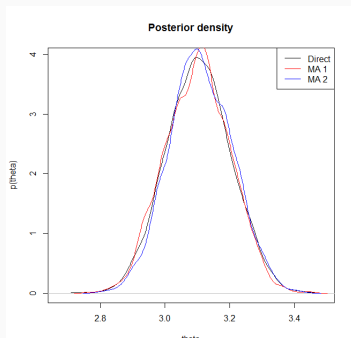
- We want to draw sample from a density $p(\theta) = f(\theta)/K$
- Begin with an initial θ^0
- Choose a function $q(x | y)$ such that
 - $q(x | y)$ is a valid density function in x for every value of y
 - $q(x | y) = q(y | x)$
 - e.g. $q(x | y) \sim N(x | y, \lambda) = \frac{1}{\sqrt{2\pi\lambda}} \exp(-\frac{1}{2\lambda}(x - y)^2)$
 - If θ is multivariate one can choose $q(x | y) \sim N(x | y, \Sigma)$
- q is called the **proposal density**
- If θ is multivariate, choose q to be a multivariate proposal density

Metropolis algorithm

- At the i^{th} iteration, generate θ^* from $q(\cdot | \theta_{i-1})$
- Calculate the ratio $r = f(\theta^*)/f(\theta_{i-1})$
- If $r \geq 1$, accept the new value i.e $\theta_i = \theta^*$
- If $r < 1$:
 - Accept the new value i.e $\theta_i = \theta^*$ with probability r
 - Keep the old value i.e $\theta_i = \theta_{i-1}$ with probability $1 - r$
- The sample $(\theta_i)_{i=N_b}^N$ is a sample from $p(\theta)$ where N_b is a burn-in period used
- An overall rate of acceptance around 30% – 50% is desirable (controlled by the **tuning** parameter λ)

Example

- $Y_i \stackrel{\text{iid}}{\sim} N(\theta, \sigma^2)$ for $i = 1, \dots, n$ where $\theta = 3$ (unknown), $\sigma^2 = 1$ (known) and $n = 100$
- Prior: $\theta \sim N(\mu, \tau^2)$ where $\mu = 0$ and $\tau^2 = 10$
- Metropolis algorithm:
$$p(\theta | Y) \propto \exp\left(-\frac{n}{2\sigma^2} (\bar{y} - \theta)^2 - \frac{1}{2\tau^2} (\theta - \mu)^2\right)$$
- Direct approach: $\theta | Y \sim N\left(\frac{\frac{n\bar{y}}{\sigma^2} + \frac{\mu}{\tau^2}}{\frac{n}{\sigma^2} + \frac{1}{\tau^2}}, \frac{1}{\frac{n}{\sigma^2} + \frac{1}{\tau^2}}\right)$



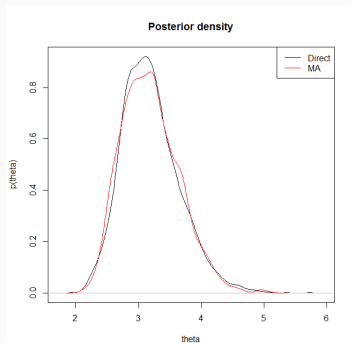
Jacobian adjustment

- Often the parameter of interest θ is not supported on the entire real line but on a part of it e.g. $[0, 1]$, $(0, \infty)$ etc.
- The normal proposal density is easy to use but has the entire real line as support
- One can choose a transformation g such that $\eta = g(\theta)$ is supported on the real line
- Generate new η^* using the normal proposal density
- Use the inverse transformation to obtain $\theta^* = g^{-1}(\eta^*)$
- The likelihood for η will be given by $p(\eta) = p(\theta)/|g'(\theta)|$
- Calculate

$$r = p(\eta^*)/p(\eta_{i-1}) = p(\theta^*)/p(\theta_{i-1}) \times |g'(\theta_{i-1})|/|g'(\theta^*)|$$

Example

- $Y_i \stackrel{\text{iid}}{\sim} N(0, \sigma^2)$ for $i = 1, \dots, n$ where $\sigma^2 = 4$ (unknown)
- σ^2 is supported on $(0, \infty)$. So, we use log transformation
- Prior: $\sigma^2 \sim \text{IG}(\alpha, \beta)$ where $\alpha = 2$ and $\beta = 1$
- Metropolis algorithm:
$$p(\sigma^2 | Y) \propto (\sigma^2)^{-1-\alpha-n/2} \exp(-(\beta + \sum_{i=1}^n y_i^2/2)/\sigma^2)$$
- Direct approach:
$$\sigma^2 | Y \sim \text{Inverse Gamma}(\alpha + n/2, \beta + \sum_{i=1}^n y_i^2/2)$$



Metropolis-Hastings Algorithm

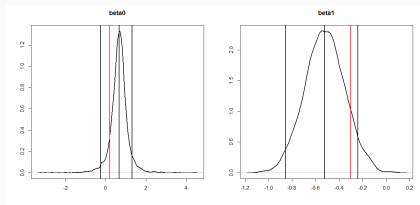
- Allows for asymmetric proposal densities
- We want to draw sample from a density $p(\theta) = f(\theta)/K$
- Let $q(x | y)$ denote the proposal density
- Calculate the ratio $r = \frac{f(\theta^*)q(\theta_{i-1} | \theta^*)}{f(\theta_{i-1})q(\theta^* | \theta_{i-1})}$
- Useful if f is asymmetric
- Reduces to Metropolis algorithm if q is symmetric

Metropolis within Gibbs

- For the marginalized model, doing MH for the entire vector $(\beta', \sigma^2, \tau^2, \phi)'$ may be slow if p is large
- Also, β has nice normal full conditionals
- One can use a **Metropolis Random Walk (RW) step** for the univariate full conditional target densities inside the Gibbs sampler
- Example: MCMC steps for the marginalized model:
 - (a) Gibbs for β : $\beta^{(j)} \sim N((X'X)^{-1}X'y, \tau^{2(j-1)}(X'X)^{-1})$
 - (b) RW for ϕ from target density
 $N(y | X\beta^{(j)}, \sigma^{2(j-1)}R(\phi) + \tau^{2(j-1)}I) \times p(\phi)$
 - (c) RW for σ^2 from $N(y | X\beta^{(j)}, \sigma^2R(\phi^{(j)} + \tau^{2(j-1)}I) \times p(\sigma^2)$
 - (d) RW for τ^2 from target density
 $N(y | X\beta^{(j)}, \sigma^{2(j)}R(\phi^{(j)} + \tau^2I) \times p(\phi)$

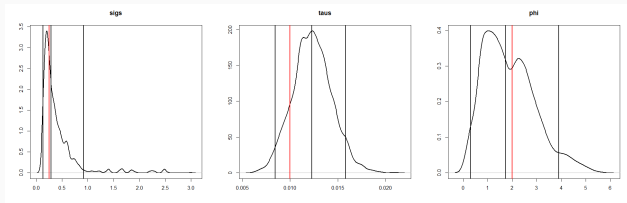
- <https://r-nimble.org/>
- Implements the MCMC for you
- You only need to specify the model and initialize the MCMC !
- We run the MCMC for the marginalized model for dataset 3 in Nimble

Parameter posteriors



β_0

β_1



σ^2

τ^2

ϕ

Recovering w

- The marginalized model integrates out the w 's
- We can recover them after the MCMC
- $w | y, \beta, \sigma^2, \tau^2, \phi \sim N(V_w(y - X\beta)/\tau^2, V_w)$ where $V_w = (I/\tau^2 + R(\phi)^{-1}/\sigma^2)^{-1}$
- Use composition sampling

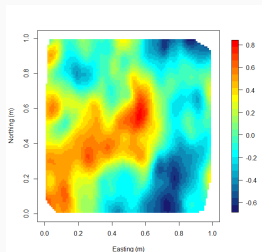


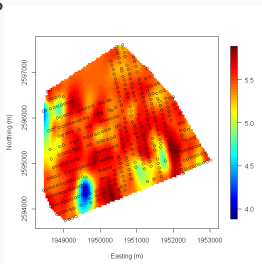
Figure: $w(s) | y$

Predictions for the marginalized model

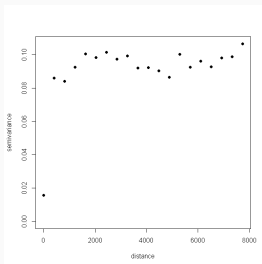
- Two ways to do predict $\tilde{y}(s) | y$ using composition sampling
- If you have already recovered w
 - Similar to the unmarginalized model
 - Generate $w(s_0) | w, params$ and then $\tilde{y}(s_0) | w(s_0), params$
- Direct approach (not requiring samples of w):
 - $c(s_0) = cov(w(s_0), w)$ and $\Sigma = \sigma^2 R(\phi) + \tau^2 I$
 - Generate samples of $\tilde{y}(s_0) | y, params \sim N(x(s_0)' \beta + c(s_0)' \Sigma^{-1} (y - X \beta), \sigma^2 + \tau^2 - c(s_0)' \Sigma^{-1} c(s_0))$

BEF data analysis in spBayes

- Dataset available in spBayes on long-term research studies on the Bartlett Experimental Forest, Bartlett, NH
- Forest inventory data for 437 locations
- Variables include species specific basal area and biomass; inventory plot coordinates; slope; elevation; and tasseled cap brightness (TC1), greenness (TC2), and wetness (TC3) components from spring, summer, and fall 2002 Landsat images



log biomass



Variogram

MCMC free Bayesian inference

- The marginalized model can be reparametrized as:
 $N(y, X\beta, \sigma^2(R(\phi) + \alpha I))$ where $\alpha = \tau^2/\sigma^2$
- If ϕ and α is fixed, we can do **exact conjugate sampling**
- *bayesGeostatExact* does that
- Fixed values of ϕ and α can be chosen from the variogram

	2.5%	25%	50%	75%	97.5%
(Intercept)	-0.624	0.267	0.728	1.182	2.079
Elevation	0.000	0.001	0.001	0.001	0.001
Slope	-0.017	-0.013	-0.011	-0.008	-0.004
Brightness	-0.001	0.006	0.010	0.013	0.021
Greenness	0.000	0.004	0.007	0.009	0.014
Wetness	0.015	0.021	0.024	0.028	0.034
σ^2	0.072	0.079	0.083	0.087	0.094
τ^2	0.014	0.016	0.016	0.017	0.019

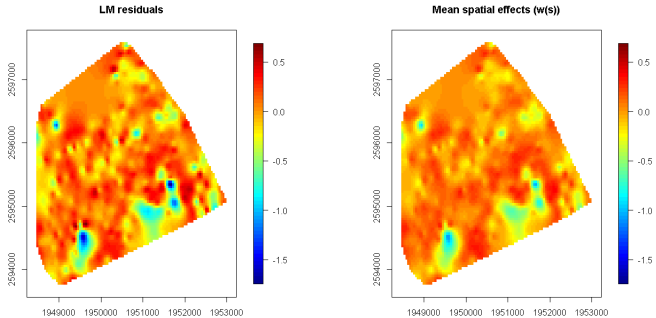
Full Bayesian inference

- *spLM* function
- Even **marginalizes out β** to make the chain only 3 dimensional

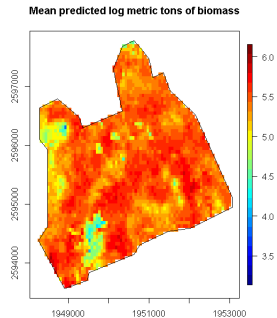
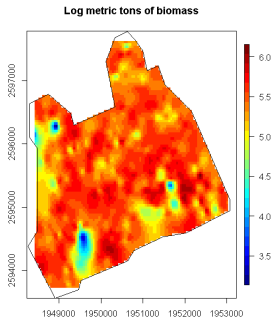
	2.5%	25%	50%	75%	97.5%
(Intercept)	-0.253	0.937	1.586	2.069	3.189
Elevation	0.000	0.000	0.000	0.001	0.001
Slope	-0.017	-0.011	-0.008	-0.005	0.002
Brightness	-0.005	0.006	0.010	0.015	0.025
Greenness	-0.005	0.003	0.005	0.008	0.014
Wetness	0.007	0.015	0.019	0.023	0.032
σ^2	0.042	0.074	0.086	0.095	0.108
τ^2	0.005	0.010	0.015	0.030	0.063
ϕ	0.004	0.008	0.010	0.012	0.016

Recovery of $w(s)$

- *spRecover* function recovers both β and w



- *spPredict* function



What we covered today

- Convergence diagnostics
- Model comparison using Bayesian output
- MH algorithm
- Writing your own MCMC
- Using Nimble package to run the MCMC
- Spatial predictions from Bayesian output
- MCMC-free and fully Bayesian spatial analysis using spBayes package

References

- **Expository article on Gibbs sampler:** Casella, G. and George, E.I. (1992), Explaining the Gibbs Sampler, *The American Statistician*, 46, 167-174.
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http://patricklam.org/teaching/convergence_print.pdf
- Gelfand, A. E. , and Smith. A. F. M. (1990). *Sampling-Based Approaches to Calculating Marginal Densities.* *Journal of the American Statistical Association*, 85(410), 398–409.
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