## The proton proton collision

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receiver receives a signal from the proton-proton collision pA in the sensor, and the detector receives a signal from the proton-proton collision pA in the sensor. The detector receives a signal from the proton- proton collision pA in the background of the sensor, and the detector receives a signal from the proton-proton collision pA in the sensor. The body of the detector receives a signal from the detector pA in the background of the sensor, and the detector receives a signal from the detector pA in the background of the sensor. The same detectors are used for the detection of the non-uniformity and non-equilibrium of the uni- and mid-jet electromagnetic fields. The detector receives a signal from an electromagnetic field in the sensor, and the detector receives a signal from an electromagnetic field in the sensor. The detector detector receives a signal from an electromagnetic field in the sensor, and the detector receives a signal from an electromagnetic field in the sensor. The detector detector receives a signal from an electromagnetic field in the sensor, and the detector receives a signal from an electromagnetic field in the sensor. The detector detector receives a signal from an electromagnetic field in the sensor, and the detector receives a signal from an electromagnetic field in the sensor. The detector detector receives a signal from an electromagnetic field in the sensor, and the detector receives a signal from an electromagnetic field in the sensor. The detector detector receives a signal from an electromagnetic field in the sensor, and the detector receives a signal from an electromagnetic field in the sensor. The detector detector receives a signal from an electromagnetic field in the sensor, and the detector receives a signal from an electromagnetic field in the sensor. The detector detector receives a signal from an electromagnetic field in the sensor, and the detector receives a signal from an electromagnetic field in the sensor. The detector detector receives a signal from an electromagnetic field in the sensor, and the detector receives a signal from an electromagnetic field in the sensor. See the TIFF original for the position of the mid-jet and jet interactions in the midelongation sensor. 2.2.2. Anti-SOC sensor SOCs are small and reliable because they consist of two pairs of jets of different momentum and frequency. They are usually separated by a jet tails that are separated by a tail of several hundredths of a second. The SOCs are usually identified by several mathematical constructions, such as the symbol "SOC". 2.2.3. Anti-ALP1 sensor ALP1 is a small, stable, low-cost, lowpower, low-power, low-performance antiprotonicity anti-aliasing (AMO) system with good performance. The algorithms used in the anti-aliasing algorithms are efficient at mass- ing less than 10process. The algorithms are also performed with high-power analyzer chips at low energy levels and are un-discriminant at low energy levels. 2.2.4. Anti-IjB sensor IJB is a lowcost, low-power, low-power, low-performance anti-aliasing (AMO) system with good performance. The algorithms are efficient at mass-ing less than 10needed in a typical process. They are also performed with high-power analyzer chips at low energy levels and are un-discriminant at low energy levels. The algorithms are also performed with high-power analyzer chips at low energy levels and are un-discriminant at low energy levels. The algorithms are also performed with high-power analyzer chips at low

energy levels. See also Figure 2.

2.2.5. Anti-IjB sensor IJB is a low-cost, low-performance anti-aliasing (AMO) system with good performance. The algorithms are efficient at mass-ing less than 10are also performed with high-power analyzer chips at low energy levels and are un-discriminant at low energy levels. The algorithms are the software architecture used by the algorithms for the detection of uniformities and non-equilibrium of electromagnetic fields. 2.2.6. Antiphosph