

# Networks/Graphs

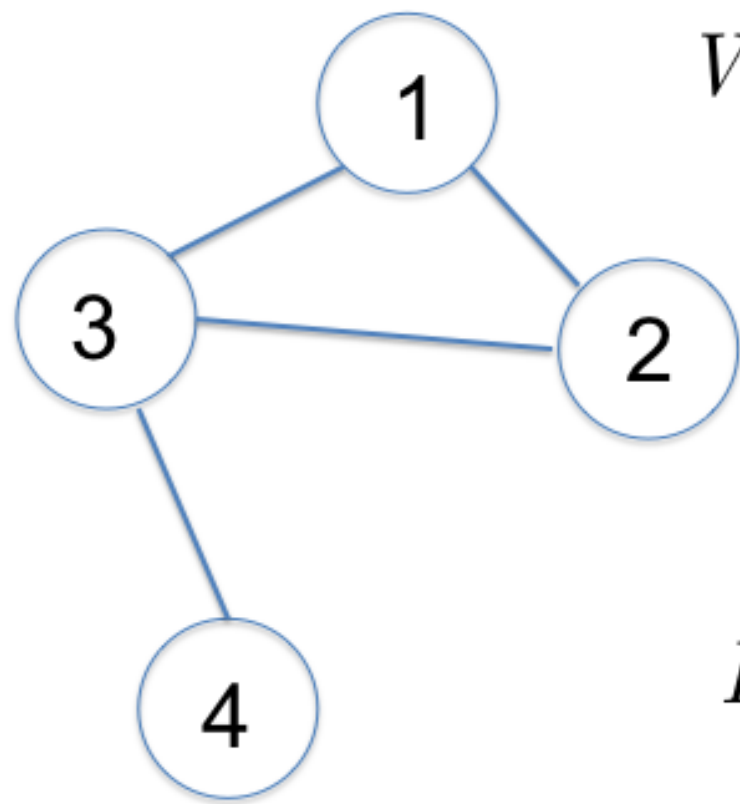
A graph  $G$  contains

- a vertex set  $V = \{v_i\}_{i=1}^n$ .

(Just refer to node  $v_i$  as node  $i$ . )

- an edge set  $W$ :  $W_{ij} = 1$  if  $v_i$  and  $v_j$  are connected, i.e.,  $(i, j)$  is in the edge set.

$W_{ij}$  may take any positive real value, indicating the strength of the connection. Think of  $W$  as an  $n \times n$  symmetric matrix.



$$W = \begin{pmatrix} 0 & 1 & 1 & 0 \\ 1 & 0 & 1 & 0 \\ 1 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \end{pmatrix}$$

$$D = \begin{pmatrix} 2 & 0 & 0 & 0 \\ 0 & 2 & 0 & 0 \\ 0 & 0 & 3 & 0 \\ 0 & 0 & 0 & 1 \end{pmatrix}$$

# Similarity Graphs

- $V = \{x_i\}_{i=1}^n$
- $W = \{w_{ij}\}, \quad w_{ij} = \text{similarity}(x_i, x_j).$
- Ex1:  $w_{ij} = \text{correlation or } \exp(-\frac{\|x_i - x_j\|^2}{2\sigma^2}).$
- Ex2:  $\epsilon$ -neighborhood graph:

$$w_{ij} = 0 \text{ if } d(x_i, x_j) \geq \epsilon.$$

- Ex3:  $k$ NN graph:  $w_{ij} = 0$  if neither  $i$  nor  $j$  is among the other's  $k$ NN.  
In a mutual  $k$ NN graph,  $w_{ij} = 0$  if at least one of  $i, j$  is not among the other's  $k$ NN.

# Graph Partition

Consider bi-partitions.

- $V = A \cup B$
- What is a **good** partition?
- How to find such a partition?

# Clustering Objectives

- Goodness of clustering
  - Points in the same cluster should be **similar**.
  - Points in different clusters should be **dissimilar**.
- In the similarity graph representation, we want to
  - Maximize **within-cluster** weights;
  - Minimize **between-cluster** weights.

# MinCut

- Objective function

$$J_{\text{Mcut}} = s(A, B) = \sum_{i \in A} \sum_{j \in B} w_{ij}$$

- Partition membership indicator

$$q_i = 1, i \in A; \quad -1, i \in B \quad (\|q\|^2 = n)$$

- Objective function

$$J_{\text{Mcut}} = \frac{1}{8} \sum_{i,j} w_{ij} (q_i - q_j)^2 = \frac{1}{4} q^t (D - W) q.$$

- Approximate  $q$  by the 2nd eigenvector of

$$(D - W)q = \lambda q, \quad D = \text{diag}(W\mathbf{1}).$$

- Laplacian matrix of a graph:  $L = D - W$

- $L$  is symmetric and semi-positive definite.

$$\alpha^t L \alpha = \frac{1}{2} \sum_{i,j} w_{ij} (\alpha_i - \alpha_j)^2 \geq 0.$$

- 1st eigenvector is  $\mathbf{1}_{n \times 1}$  with  $\lambda_1 = 0$ .
- 2nd eigenvector is the desired solution (Let's exclude the trivial case where  $L$  has a block diagonal form).
- Higher eigenvectors can also be used for further partition.

- Recovering the partition: choose the splitting point for  $q$ .

- split at 0

$$A = \{i; q(i) < 0\}, \quad B = \{i; q(i) \geq 0\}.$$

- split at median, if requires  $|A| = |B|$  (balance sizes);
- choose the optimal splitting point to minimize  $s(A, B)$ .

- Drawback of MinCut.



# Normalized Cut

- Normalized cut (Shi & Malik, 1997)

$$\begin{aligned} J_{\text{Ncut}} &= \frac{s(A, B)}{s(A, V)} + \frac{s(B, A)}{s(B, V)} \\ &= 2 - \frac{s(A, A)}{s(A, V)} - \frac{s(B, B)}{s(B, V)} \end{aligned}$$

$v_A = s(A, V)$ : sum of weights on edges originating from set  $A$   
(Volume)

- $\min J_{\text{Ncut}}$  is equivalent to
  - minimize normalized between-cluster weights;
  - maximize normalized within-cluster weights.

- Partition membership indicator

$$q_i = \sqrt{\frac{v_B}{v_A} \frac{1}{v}}, \quad i \in A; \quad q_i = -\sqrt{\frac{v_A}{v_B} \frac{1}{v}}, \quad i \in B$$

where  $v = s(V, V)$ . ( $q^t D q = 1, q^t D \mathbf{1} = 0$ )

- Objective function

$$J_{\text{Ncut}} = \sum_{i,j} w_{ij} (q_i - q_j)^2 = \frac{1}{2} q^t (D - W) q.$$

Solve  $q$  by the generalized eigenvalue problem (2nd eigenvector)

$$(D - W)q = \lambda Dq,$$

or

$$(I - D^{-1}W)q = \lambda q.$$

## Multi-partition ( $K > 2$ )

- Recursive bi-partition
- Use multi-partition objective functions
- Spectral clustering
  - Embed data in a subspace of eigenvectors
  - Cluster embedded data points using another algorithm, such as K-means.

# Spectral Clustering

- Define

$$D = \text{diag}(W_{i+}), \quad L = I - D^{-1}W$$

where  $L$  is known as the (normalized) graph Laplacian.

- The first  $m$  (non-constant) eigen-vectors (corresponding to the lowest eigen-values) of  $L$ ,  $X_1, \dots, X_m$ , form a new data matrix

$$\mathbf{X}_{n \times m} = [X_1, \dots, X_m],$$

i.e., each node corresponds to a data point in  $\mathbb{R}^m$ .

- Run  $k$ -means based on the data matrix  $\mathbf{X}$ .

- Next, we justify the use of spectral clustering via the so-called Stochastic Blockmodel.
- Stochastic Blockmodel, a probabilistic model for graphs, assumes a grouping structure among the nodes. We can show that if we run spectral clustering on the corresponding  $W$  matrix, we can correctly retrieve the underlying grouping structure.

# Statistical Models for Graphs/Networks

- Node set  $V$  is given;  $\mathcal{W}$  is a stochastic binary matrix.
- The simplest (one parameter) model (aka Erdos-Renyi model)

$$\mathbb{P}(\mathcal{W}_{ij} = 1) = p.$$

- The most complicated (many parameters) model

$$\mathbb{P}(\mathcal{W}_{ij} = 1) = w_{ij}.$$

- Something in the middle: cluster  $w_{ij}$ 's.

## Stochastic Blockmodel (Holland et al., 1983)

- Suppose  $n$  nodes are from  $k$  groups/blocks.
- $B_{k \times k}$ : connecting probability between nodes from the  $k$  blocks.
- Conditioning on node  $i$  in  $l$ -th block and node  $j$  in  $h$ -th block,

$$\mathbb{P}(\mathcal{W}_{ij} = 1) = w_{ij} = B_{lh}.$$

- Block/cluster membership  $\mathbf{z}_i \in (0, 1)^k$ :

node  $i$  in  $l$ th block, iff  $z_{ih} = 0$ , except  $z_{il} = 1$ .

Stack all the  $\mathbf{z}_i$ 's as a  $n \times k$  matrix  $\mathbf{Z}$ . Then, the stochastic blockmodel implies

$$W_{n \times n} = \mathbf{Z}_{n \times k} \mathbf{B} \mathbf{Z}^T.$$

- Each row of  $\mathbf{Z}$  has one and only one value equal to 1 and all others 0.



# Spectral Clustering at the Population Level

- Assume  $W = \mathbf{ZBZ}^T$  is known. Define the population laplacian  $L$ :

$$D_{ii} = \sum_k W_{ik}$$
$$L = D^{-1/2} W D^{-1/2}$$

- It can be shown that the top  $k$  eigen-vectors of  $L$  are equal to  $\mathbf{Z}\mu$  where  $\mu$  is a  $k \times k$  matrix. Therefore spectral clustering can retrieve the  $k$  clusters correctly<sup>a</sup>.

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<sup>a</sup>Lemma 3.1 from “Spectral clustering and the high-dimensional stochastic block-model” by Karl Rohe, Sourav Chatterjee, & Bin Yu.

1) Show that  $L$  can be re-expressed as  $L = (\mathbf{Z}B_L\mathbf{Z}^T)$  where

$$D_B = \text{diag}(B\mathbf{Z}^T\mathbf{1}_n) \in \mathbb{R}^{k \times k}$$

$$B_L = D_B^{-1/2} B D_B^{-1/2}$$

2) Assume  $(\mathbf{Z}^T\mathbf{Z})^{1/2}B_L(\mathbf{Z}^T\mathbf{Z})^{1/2}$  has the following SVD,

$$(\mathbf{Z}^T\mathbf{Z})^{1/2}B_L(\mathbf{Z}^T\mathbf{Z})^{1/2} = V\Gamma V^T.$$

3) Left-multiply  $\mathbf{Z}(\mathbf{Z}^T\mathbf{Z})^{-1/2}$  and right-multiply its transpose on both sides,

$$\mathbf{Z}B_L\mathbf{Z}^T = \mathbf{Z}_\mu\Gamma(\mathbf{Z}_\mu)^T,$$

where  $\mu = (\mathbf{Z}^T\mathbf{Z})^{-1/2}V$ . Note that  $(\mathbf{Z}_\mu)^T(\mathbf{Z}_\mu) = \mathbf{I}_k$ . So  $\mathbf{Z}_\mu$  are the eigen-vectors.