

# Multi-channel Tree Algorithms for LTE RACH Reliable High Throughput Access

Alberto Martínez Alba

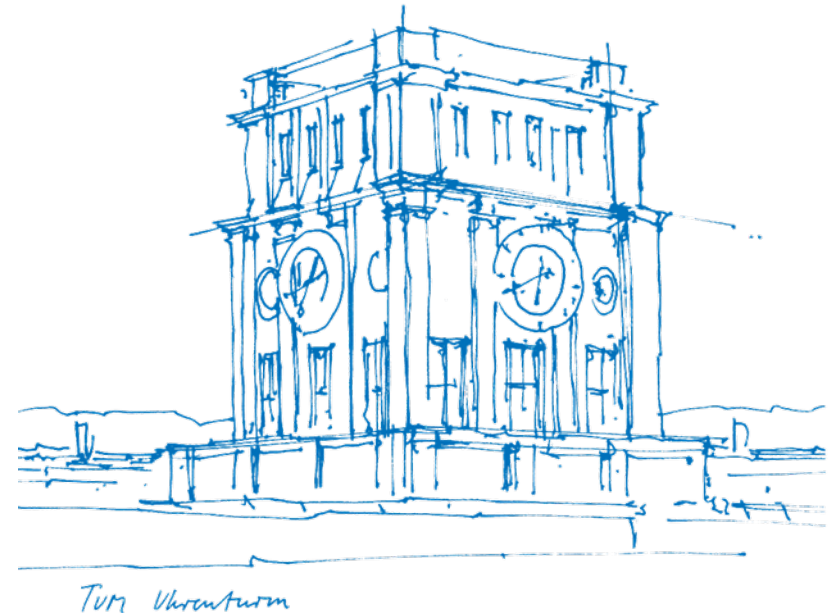
Murat Gürsu

Technische Universität München

Fakultät für Elektrotechnik und Informationstechnik

Lehrstuhl für Kommunikationsnetze

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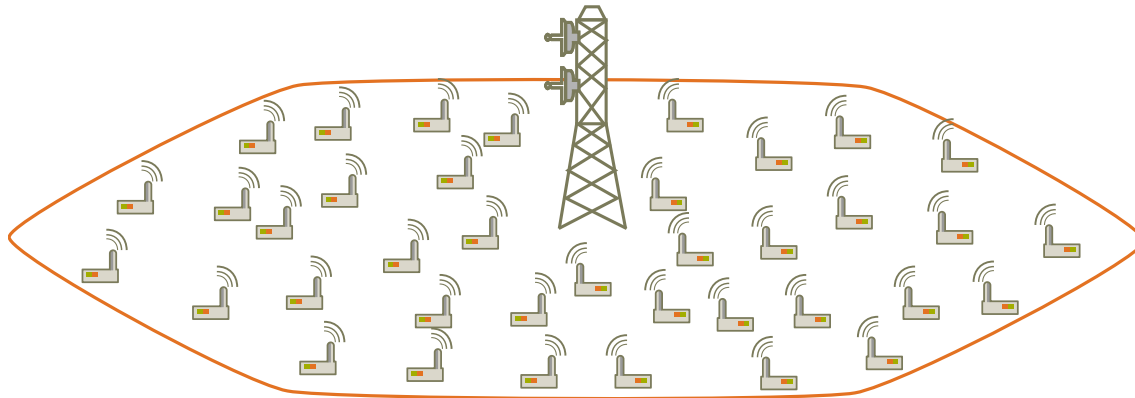
- Motivation
- LTE RACH and Tree Algorithms
- Multi-channel Tree Algorithms
  - Length of the tree
  - Access delay
- Simulations
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# Motivation (I)

- LTE Radio Access Network (RAN) **overload control** [1]:
  - Large number of MTC devices
  - Network congestion
  - Protect the Uplink **Random Access Channel** (RACH) from overload

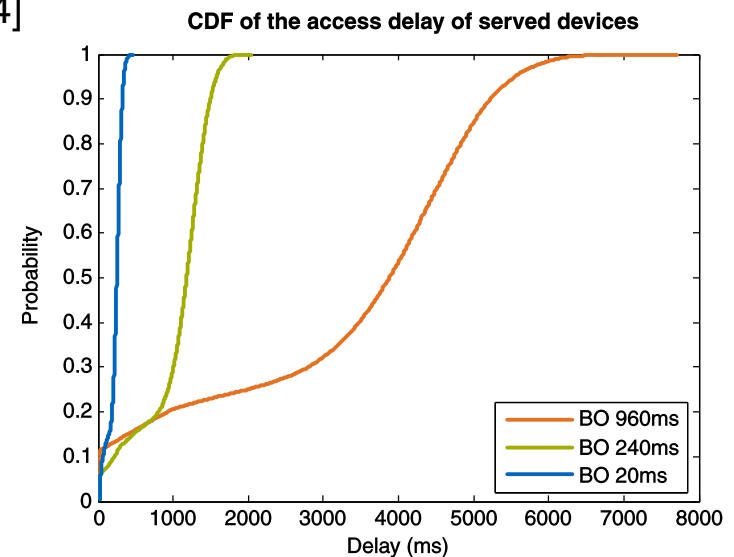


Congested network

# Motivation (II)

- LTE RACH is based on (multi-channel) **Slotted ALOHA** access [2]
  - Slotted ALOHA cannot guarantee **reliability** [3]
  - **Tree Algorithms** can improve Slotted-ALOHA
- **Reliability:** ability of a network to **serve** some devices within the **required time**
- **Example:** 30,000 devices beta-distributed in 10 s [4]

	BO = 20 ms	BO = 240 ms	BO = 960 ms
Access success prob.	19.14%	23.84%	41.97%



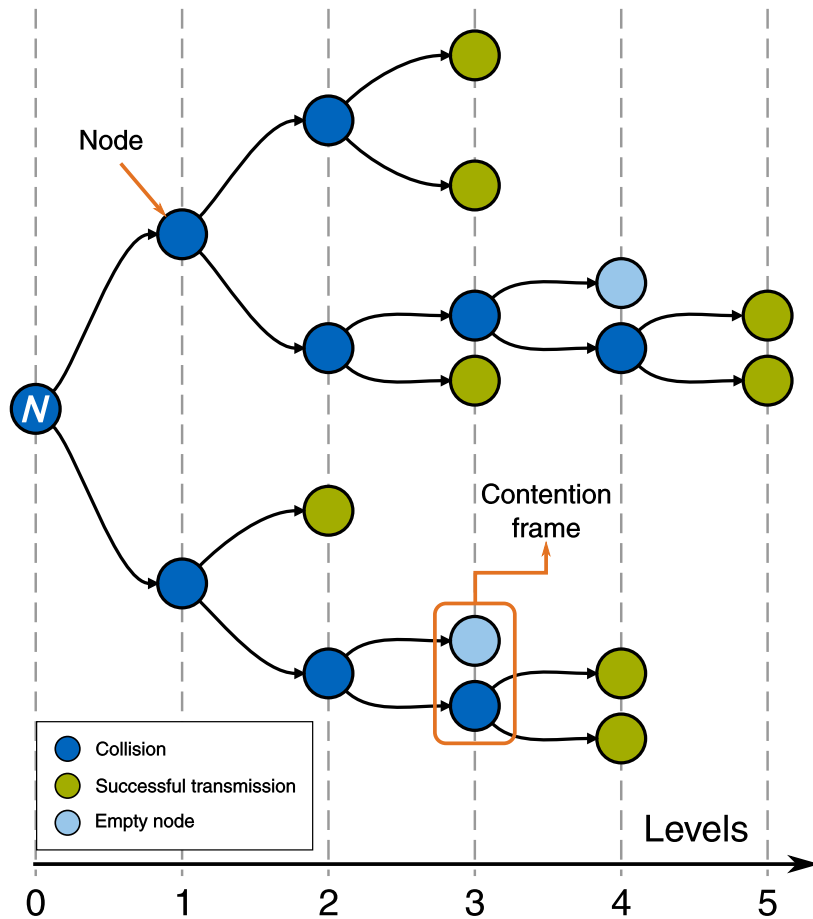
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# LTE-RACH and Tree Algorithms

- Tree Algorithms are **Contention Resolution Algorithms** [5]
- Tree Algorithms are designed to guarantee **access success** [3][5]
- **Access delay** is still an issue
- LTE-RACH is **multi-channel** (orthogonal preambles) [6]
- Statistics of the access delay of **multi-channel Tree Algorithms** are needed

# Example of a Tree Algorithm (I)

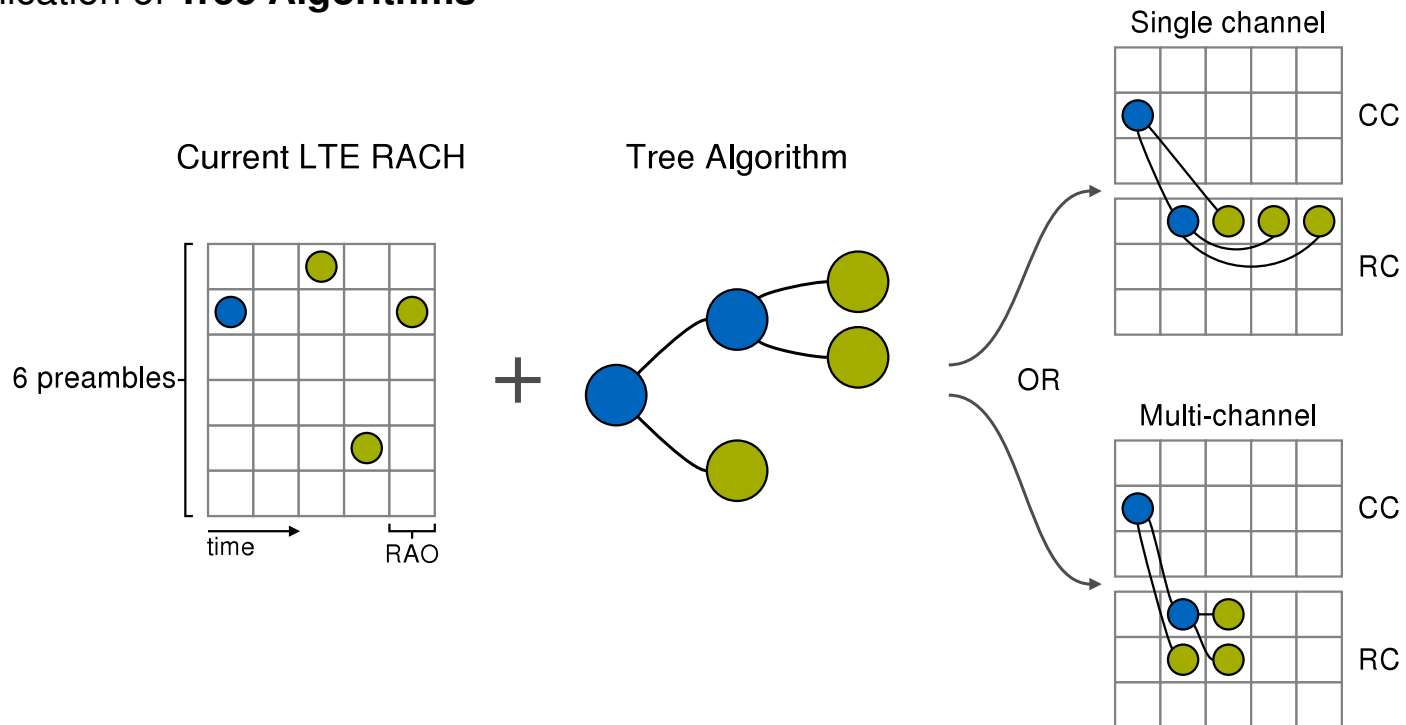


- $N = 8$  initial contenders
- No **new devices** allowed
- **Feedback** is required
- Collision =  $q$  **new nodes**
- $S = 19$  **nodes** to complete the tree
- $L = 5$  **levels**



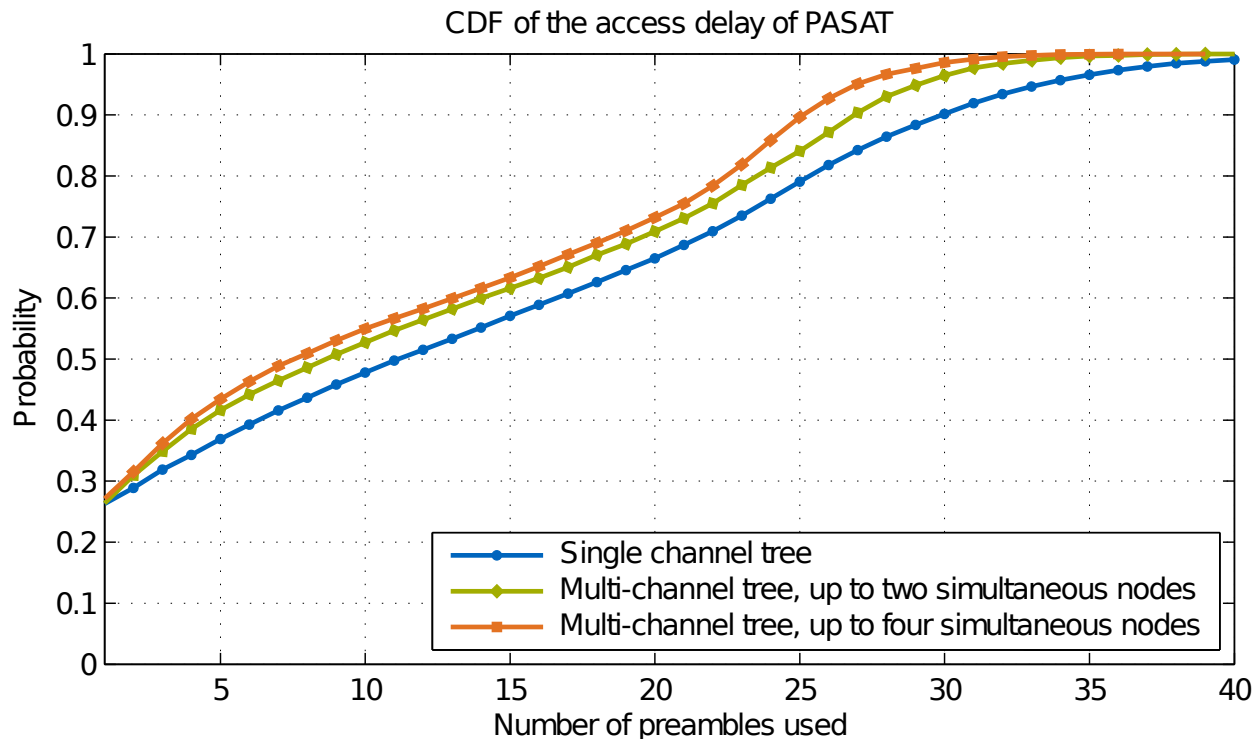
# PASAT-Algorithm

- Key idea:
  - Separation of LTE RACH into **Contention Channel (CC)** and **Resolution Channel (RC)**
  - Application of **Tree Algorithms**



# PASAT-Algorithm (II): simulation results

- For  $N = 3000$  devices beta-distributed within 1 second (200 RAOs):



- **Conclusion:** in this case, multi-channel Tree Algorithms perform better.

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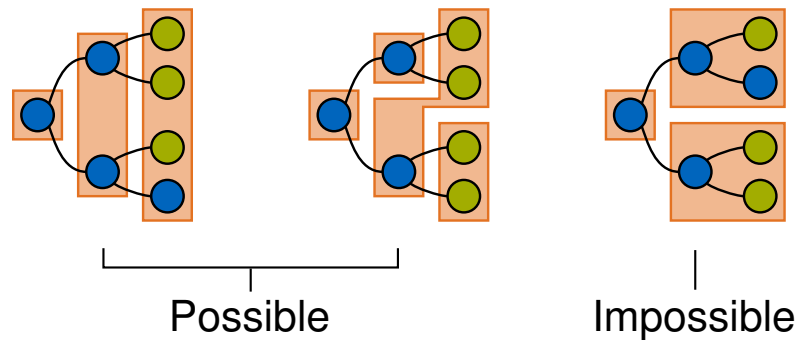
# Multi-channel Tree Algorithms

## Key idea:

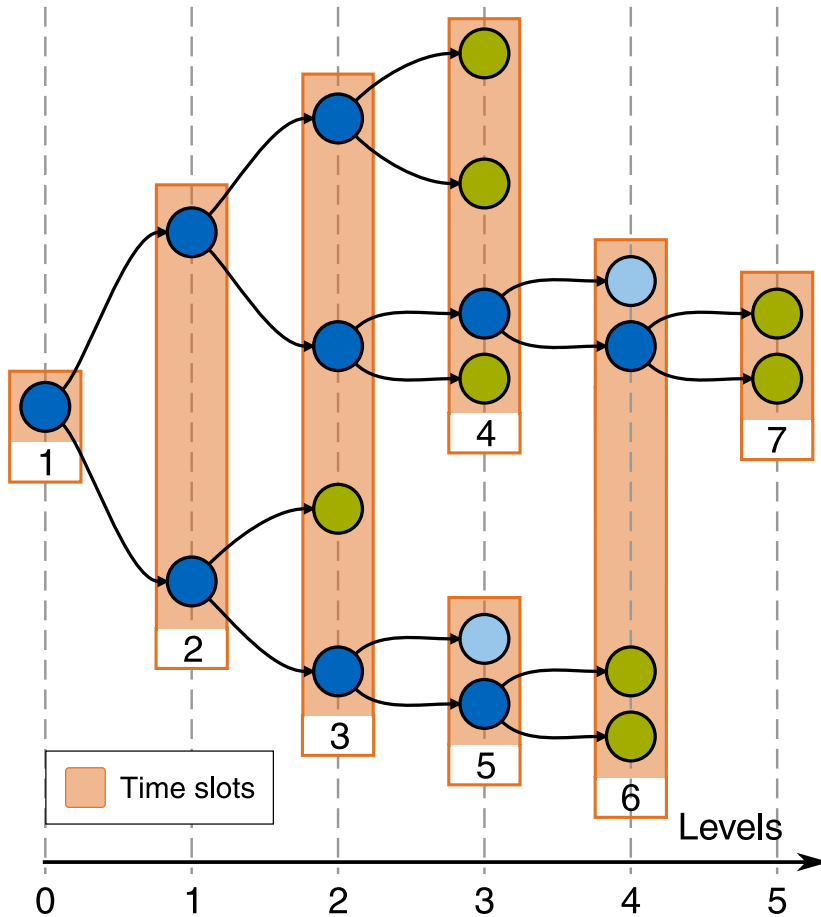
Transmit multiple nodes at the same time  $\rightarrow$  Reduce access delay

## Limitation:

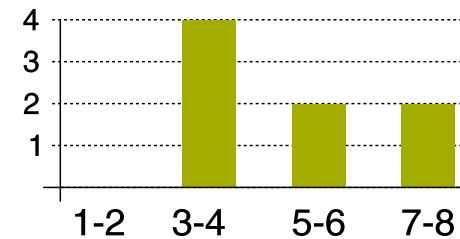
Only nodes that are not descendant from one another can be transmitted together



# Example of a multi-channel Tree Algorithm



- $G = 2 \rightarrow 4$  nodes per slot
- No direct conversion from single channel
- Access delays:  
 $\{3, 4, 4, 4, 6, 6, 7, 7\}$
- Average access delay: 5.125 slots
- Histogram of transmissions



# State of the art of Tree Algorithms

- This statistics can be **found in the literature** about TAs:
  - Average, variance and probability-generating function (PGF) of the length of the tree [3][7][8][9]
  - Average and probability-generating function (PGF) of the access delay [9]
  - PMF of the number of levels to complete the tree [10]
  - PMF of the number of levels to successfully transmit [10]
- However, the following important statistics are **missing for multi-channel** trees:
  - CDF of the **length** of the tree
  - CDF of the **access delay**

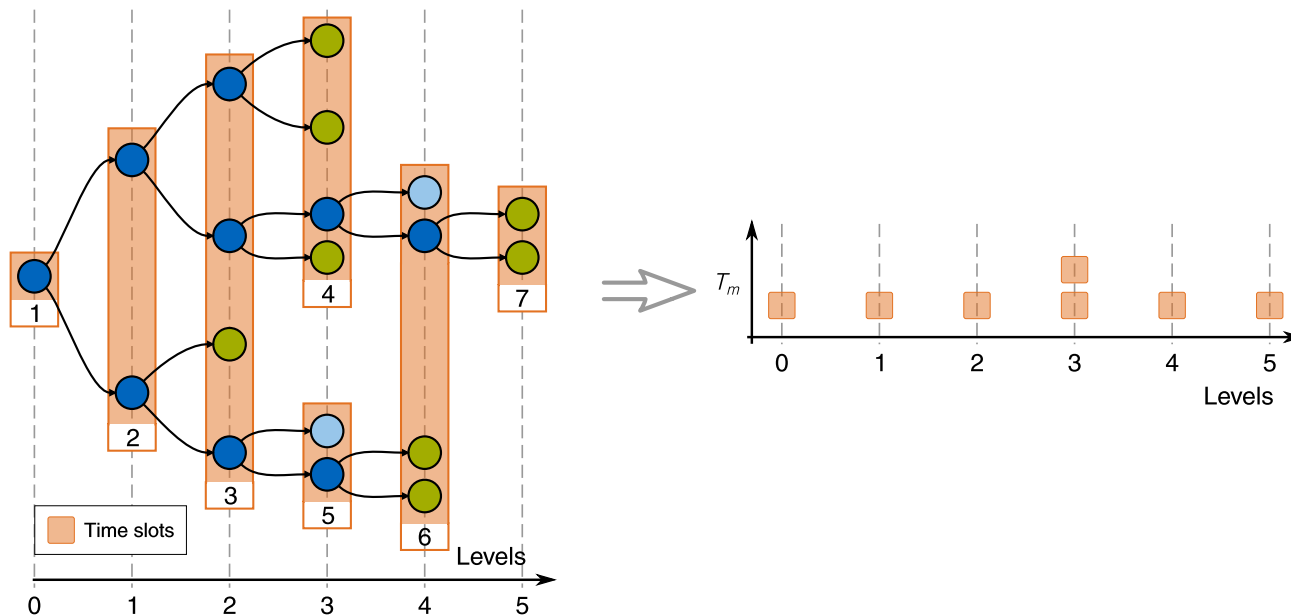
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# PMF of the length of a multi-channel Tree (I)

- Before facing the **CDF of the access delay**, the **CDF of the tree length** is needed
- The total number of **slots**  $T$  in a tree is given by:

$$T \approx 1 + \sum_{m=1}^M T_m$$





# PMF of the length of a multi-channel Tree (II)

- We need to find out the **joint PMF** of all variables:

$$p_{T_1, \dots, T_M}(t_1, \dots, t_M) \longrightarrow p_T(t)$$

- Assuming a Markov process, the **joint distribution** will be [11]:

$$p_{T_1, \dots, T_M}(t_1, \dots, t_M) = p_{T_1}(t_1) p_{T_2|T_1}(t_2|t_1) \dots p_{T_M|T_{M-1}}(t_M|t_{M-1})$$

- There is a direct translation between **collisions** and slots:

$X_m \rightarrow$  Number of collisions in the level  $m$

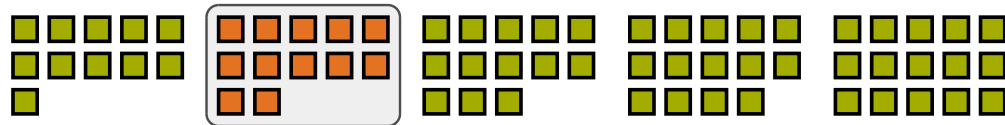
$$p_{X_m|X_{m-1}}(x_m|x_{m-1}) \longrightarrow p_{T_m|T_{m-1}}(t_m|t_{m-1})$$

# PMF of the length of a multi-channel Tree (III)

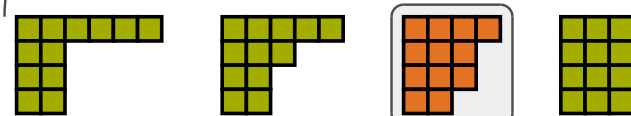
Number of **collisions** is known



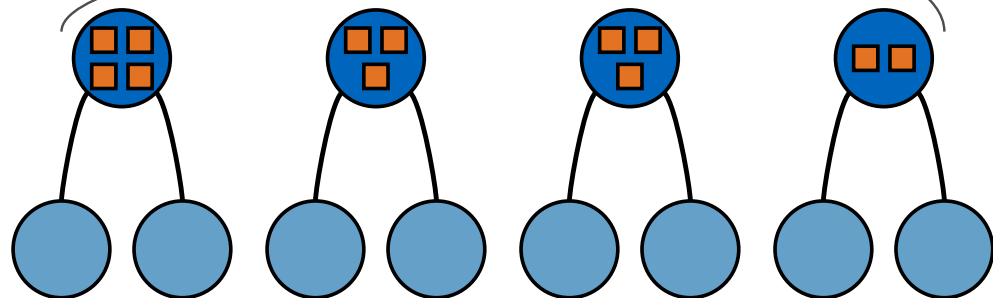
Prob. to have some **contenders**,  
given collisions



Prob. to have a certain **partition**,  
given collisions and contenders



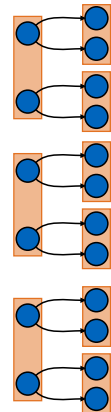
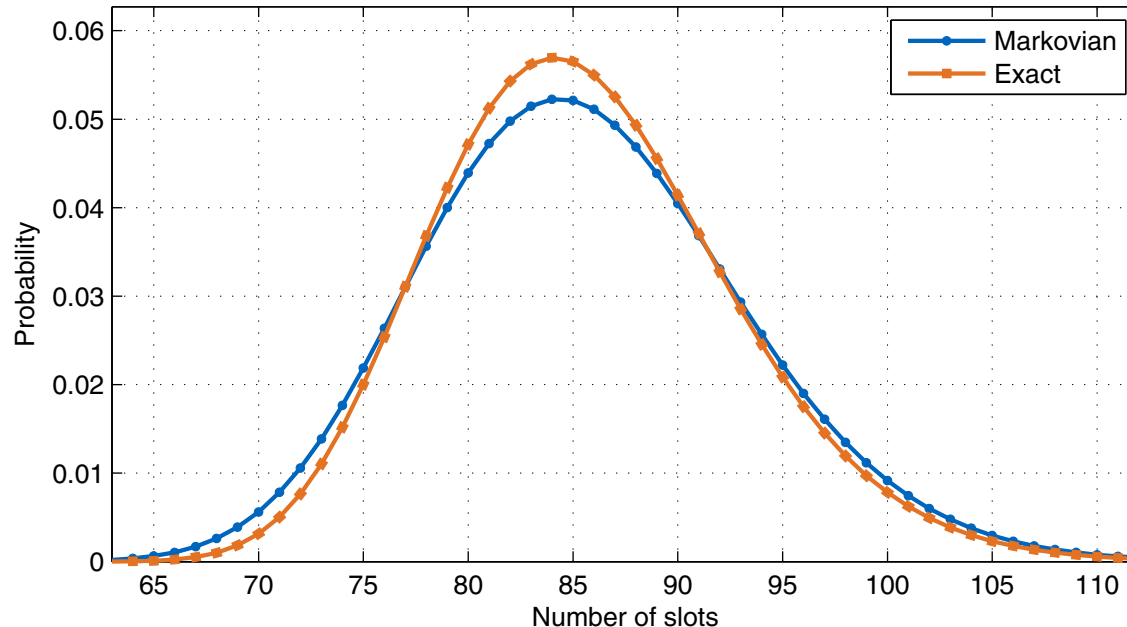
Prob. to have generate **collisions**  
in each node, given collisions,  
contenders and a partition



$$p_{X_m|X_{m_1}}(x_m|x_{m-1})$$

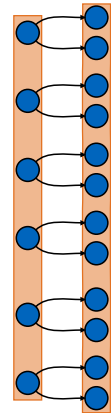
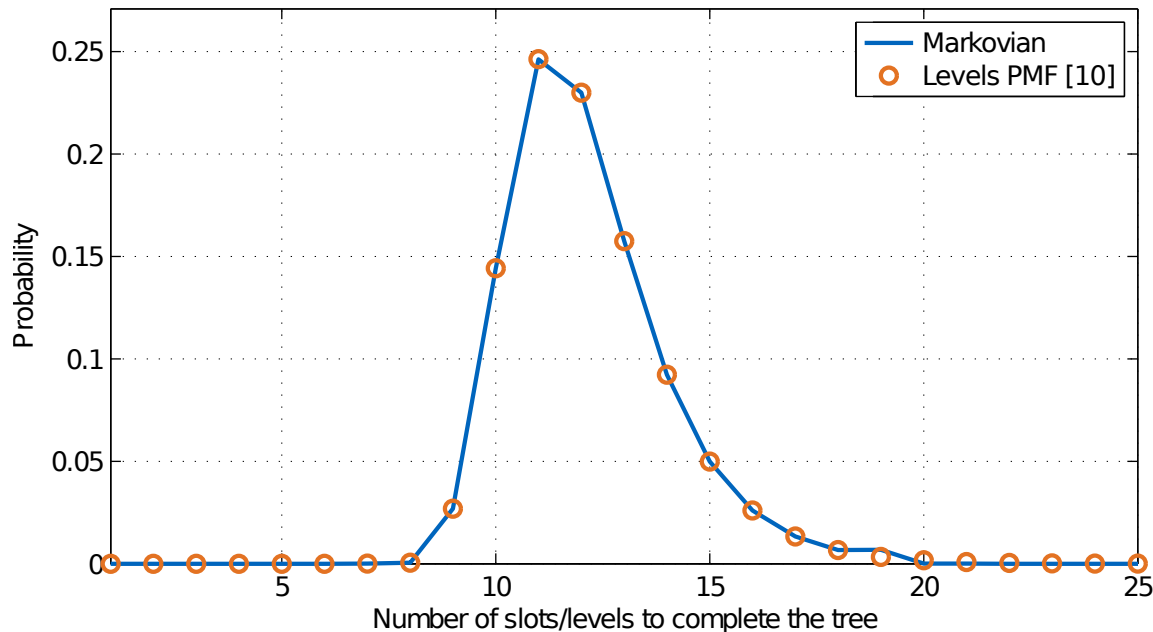
# Results of the length of a multi-channel Tree (I)

- If we set  $G = 1 \rightarrow$  **single channel** scenario
- We can use this value to **compare** our technique with the independent approach and the exact solution
- For  $N = 60$ :



# Results of the length of a multi-channel Tree (II)

- Conversely, for  $G \gg 1$ , the number of used time slots should **converge** to the **number of levels**
- For  $G = 25$  and  $N = 60$  we obtain:

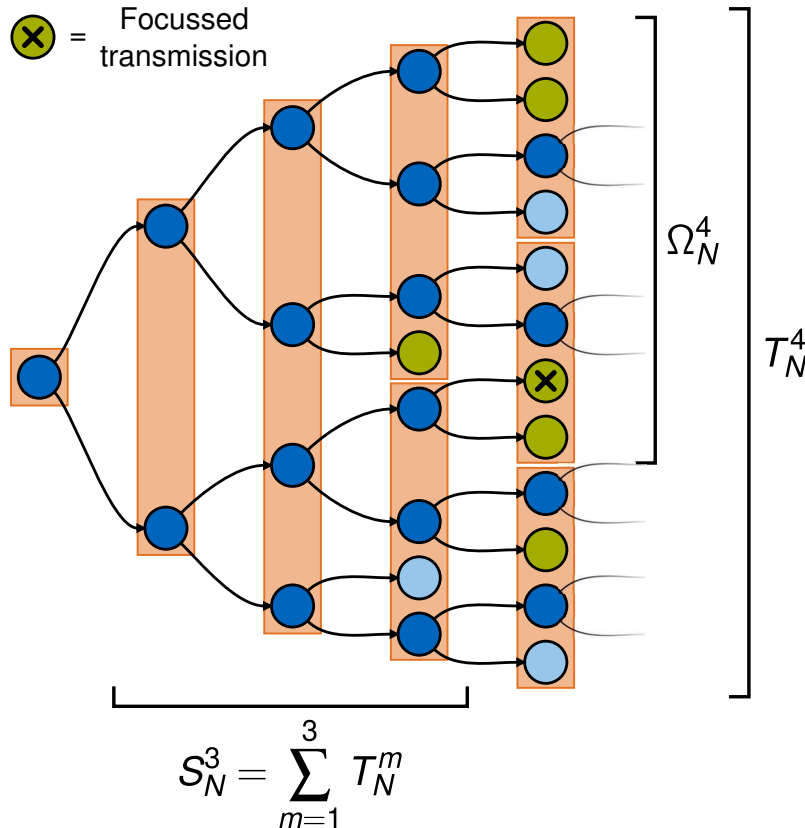


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# Multi-channel access delay (I)

- Example of one device transmitting in the slot 2 in the level 4:



Total delay:

$$\Theta_N^4 = 1 + S_N^3 + \Omega_N^4$$

In general:

$$\Theta_N^m = 1 + S_N^{m-1} + \Omega_N^m$$

# Multi-channel access delay (II)

- The joint PMF is needed:

$$p_{S_N^{m-1}, \Omega_N^m}(s_{m-1}, \omega_m) \longrightarrow p_{\Theta_N^m}(\theta_m)$$

- This PMF can be obtained from the statistics of the length of the tree.
  - $S_N^{m-1}$  is the length of the tree up to level  $m-1$
  - $\Omega_N^m$  is (almost) an uniform random variable
- Finally, the probability  $p_{M_N}(m)$  to transmit in the level  $m$  [10] is required:

$$p_{\Theta_N}(\theta) = \sum_{m=1}^{\infty} p_{\Theta_N^m}(\theta_m) \cdot p_{M_N}(m)$$

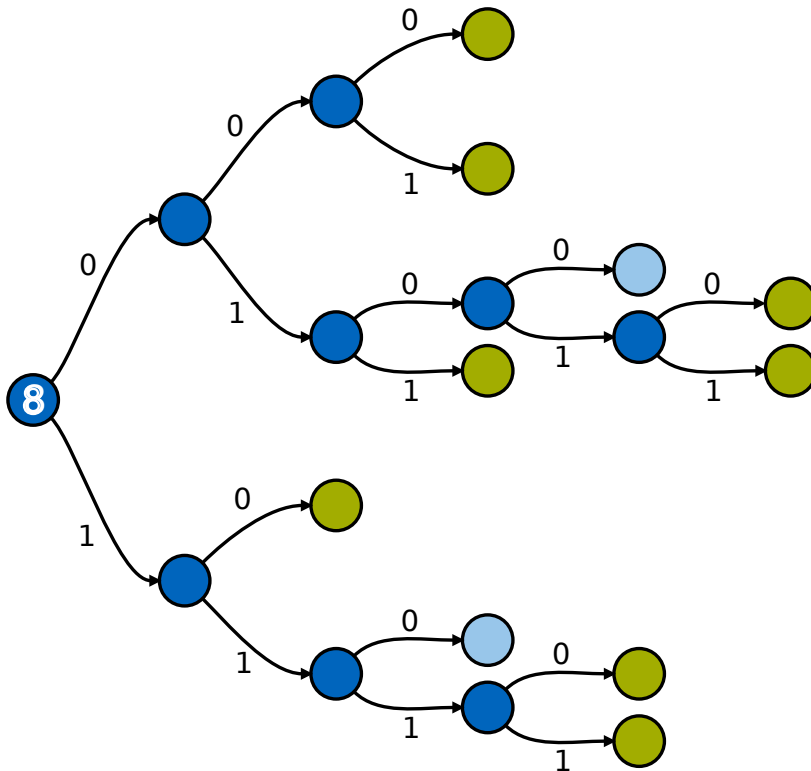
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# Simulation design (I)

- Conversion of a tree into a **decisions matrix**.



$\Leftrightarrow$

$$\mathbf{C} = \begin{bmatrix} 0 & 0 & 0 & - & - \\ 0 & 0 & 1 & - & - \\ 0 & 1 & 0 & 0 & - \\ 0 & 1 & 0 & 1 & 0 \\ 0 & 1 & 0 & 1 & 1 \\ 1 & 0 & - & - & - \\ 1 & 1 & 1 & 0 & - \\ 1 & 1 & 1 & 1 & - \end{bmatrix}$$

# Simulation design (II)

- Structure of **one run**:

1. Randomly **generate** matrices **C**.
2. **Process** matrices **C** to obtain length  $L$  and access delays  $\theta$ .

- Calculation of the **number of runs**:

1. Choose probability  $\alpha$  to exceed a difference of  $\varepsilon$  between the empirical and the theoretical CDFs.
2. Use the **Dvoretzky–Kiefer–Wolfowitz (DKW) inequality** to compute the number of iterations  $n$ :

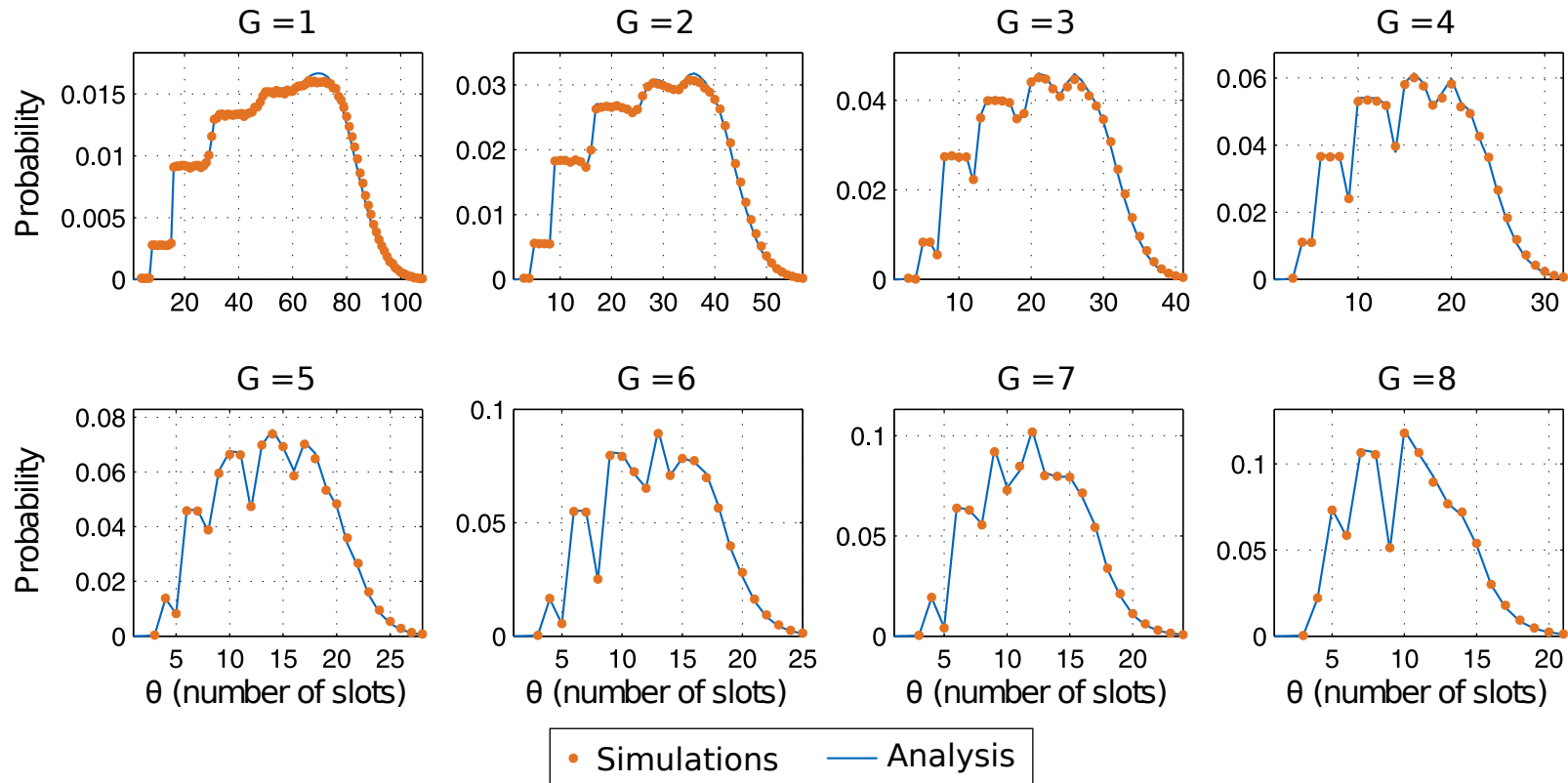
$$\alpha \leq 2e^{-2n\varepsilon^2}$$

For example, for  $\alpha = 0.01$  and  $\varepsilon = 0.01$ :

$$n \approx 26500$$

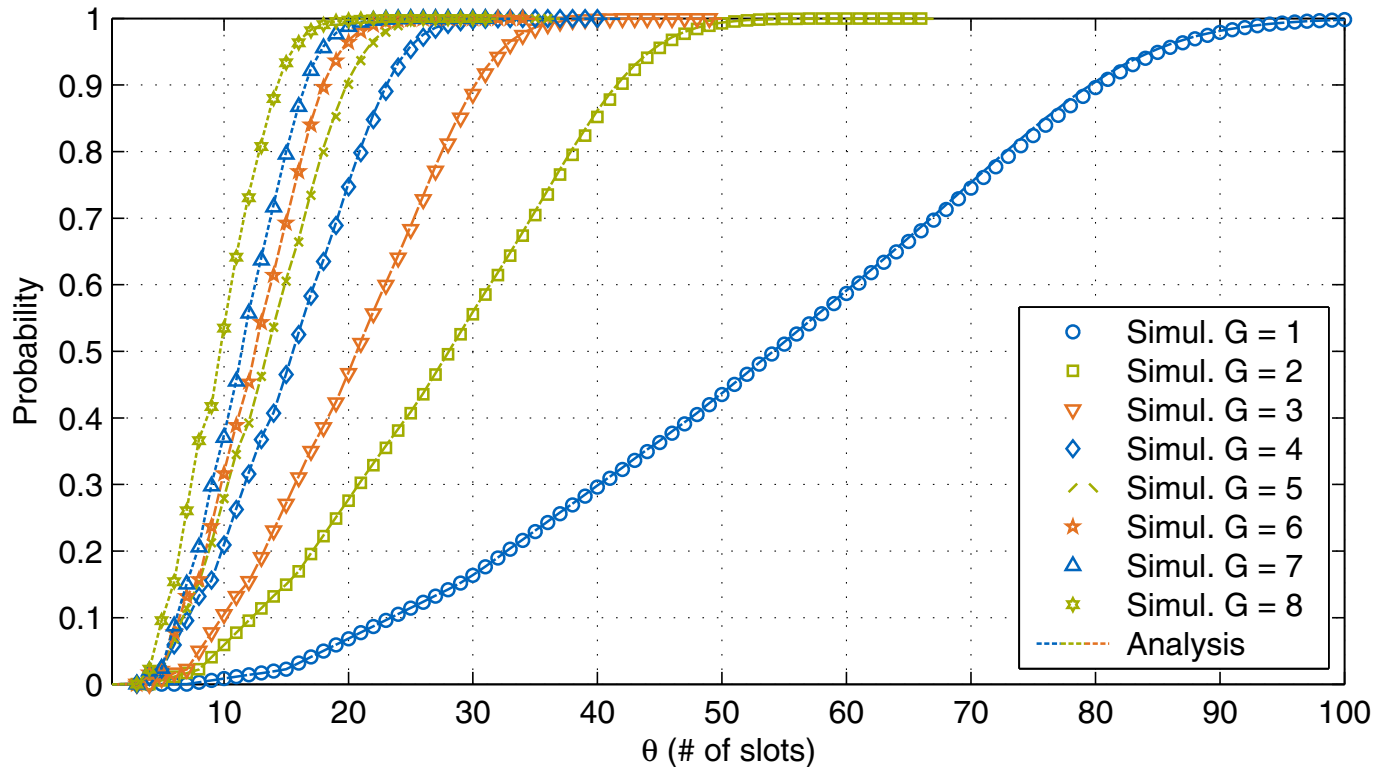
# Simulation results (I)

- After 26500 iterations, PMFs of the **access delay** for  $N = 60$ :



## Simulation results (II)

- After 26500 iterations, CDFs of the **access delay** for  $N = 60$ :



# Simulation results (III): goodness of fit

- Although simulations show **accurate results**, the model is still an **approximation**.
- Measure of the goodness of fit: **Kolmogorov-Smirnov statistic**  $\mathcal{D}$  (maximum difference between empirical and theoretical CDFs).

$G$	1	2	3	4	5	6	7	8
$\mathcal{D}$	0.0108	0.0090	0.0096	0.0081	0.0082	0.0057	0.0042	0.0061

Table 1: Kolmogorov–Smirnov statistic for different values of  $G$

- For  $G > 1$ , the **maximum error is below 1%**.

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# Conclusions

- The problem of guaranteeing **reliability** of mobile networks under **massive arrivals** was addressed
- A **new approach** for improving the LTE RACH based on **Tree Algorithms** was presented
- A **Markovian approximation** was used to obtain an analytical model of multi-channel Tree Algorithms
- The **CDFs of the length of the tree and the access delay** were obtained as a result of the Markovian approach
- **Simulations** were performed in order to confirm the analytical results

# Future work

- Implementation of multi-channel Tree Algorithms for different **traffic classes**
- Guaranteed reliability might be provided via **collision estimation**
- **Q-ary** multi-channel Tree Algorithms



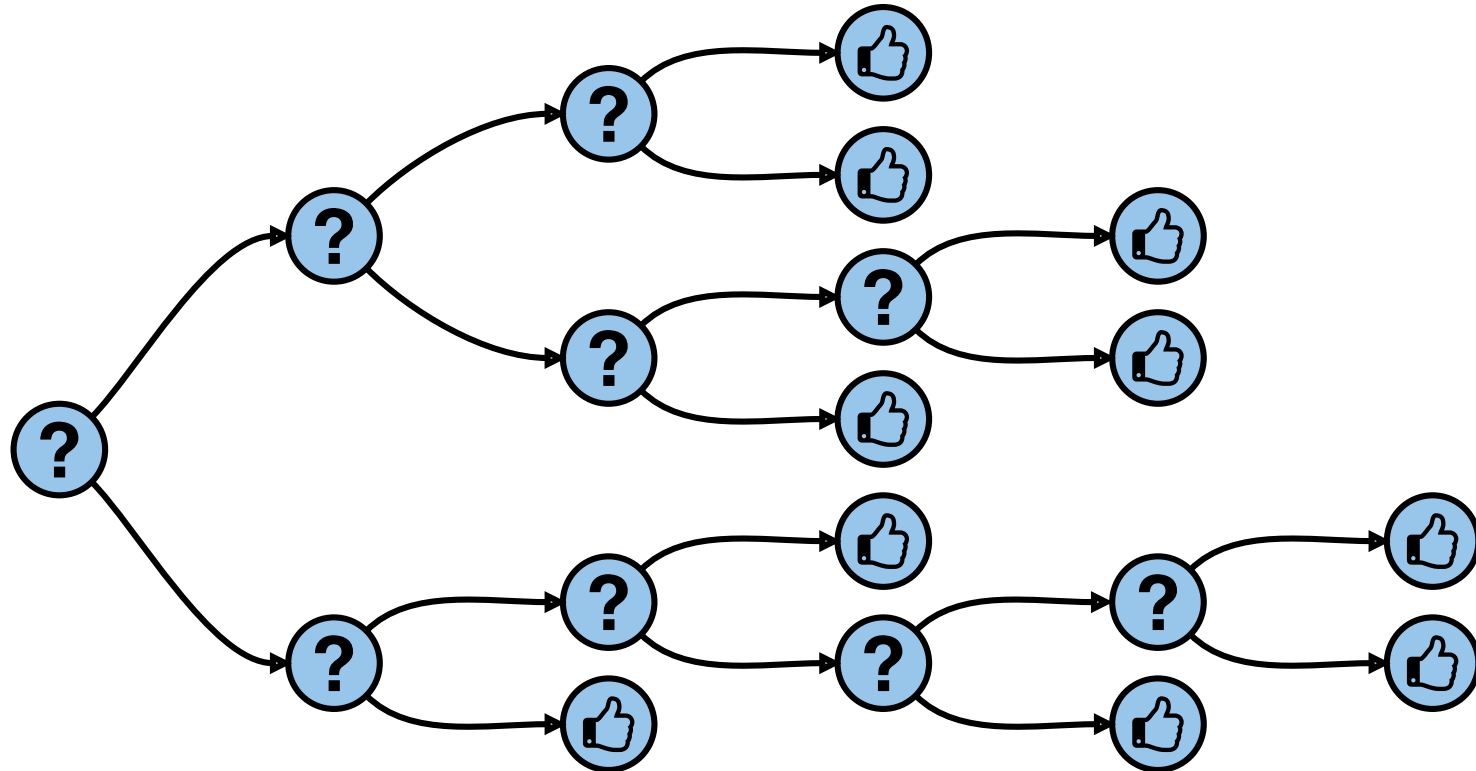
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- [2] C. H. Wei, G. Bianchi, and R. G. Cheng. “Modeling and Analysis of Random Access Channels With Bursty Arrivals in OFDMA Wireless Networks”. In: *IEEE Transactions on Wireless Communications* 14.4 (2015), pp. 1940–1953. ISSN: 1536-1276. DOI: 10.1109/TWC.2014.2377121.
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- [10] A. J. E. M. Janssen and M. J. de Jong. “Analysis of contention tree algorithms”. In: *IEEE Transactions on Information Theory* 46.6 (2000), pp. 2163–2172. ISSN: 0018-9448. DOI: 10.1109/18.868486.
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# Questions?

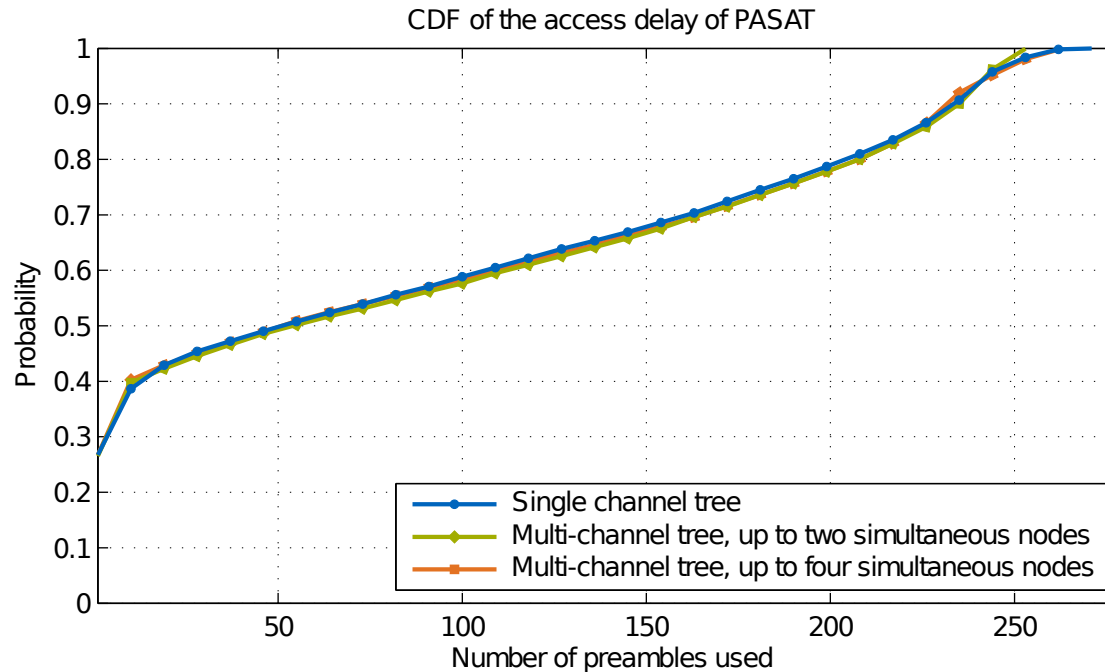


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<sup>1</sup>Icons made by Dave Gandy from [www.flaticon.com](http://www.flaticon.com) is licensed by CC 3.0 BY

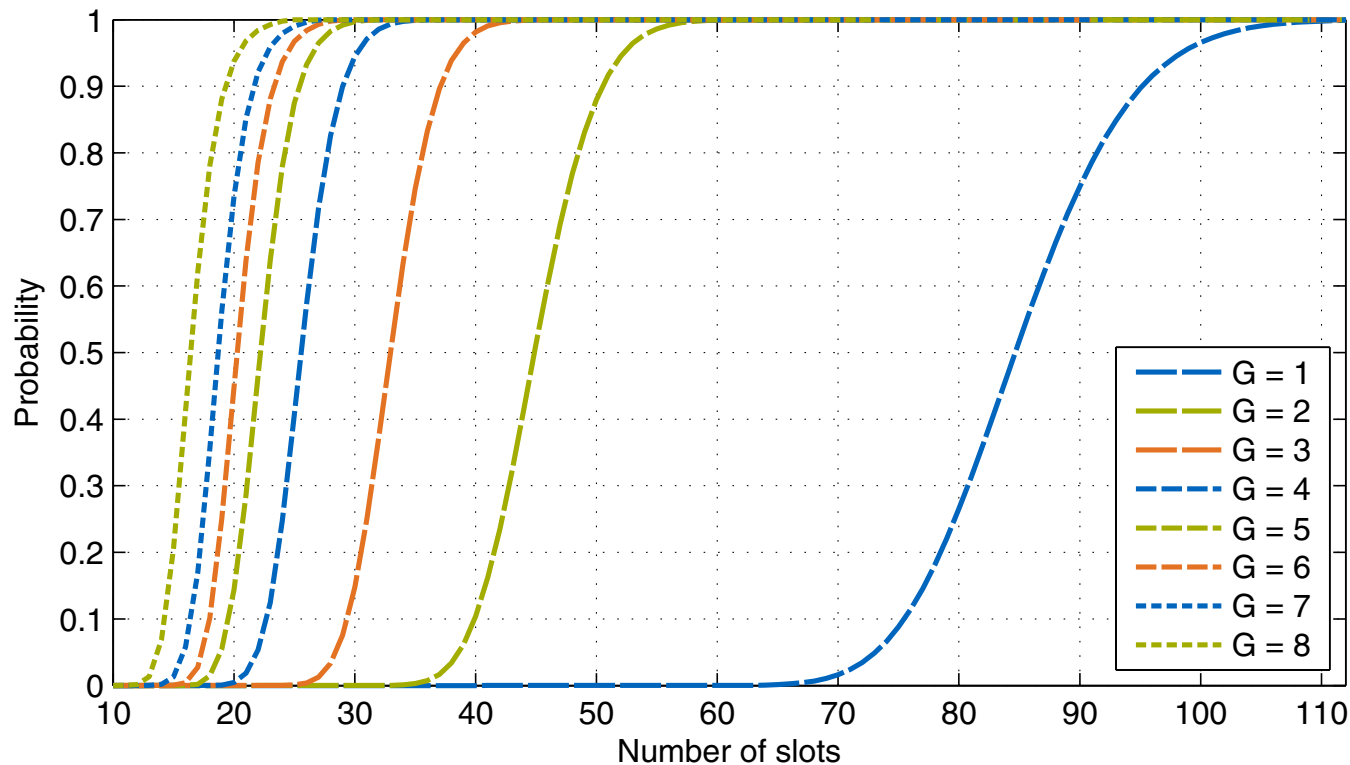
# Appendix A: additional PASAT simulation results

- For  $N = 30000$  devices beta-distributed within 10 second (200 RAOs):



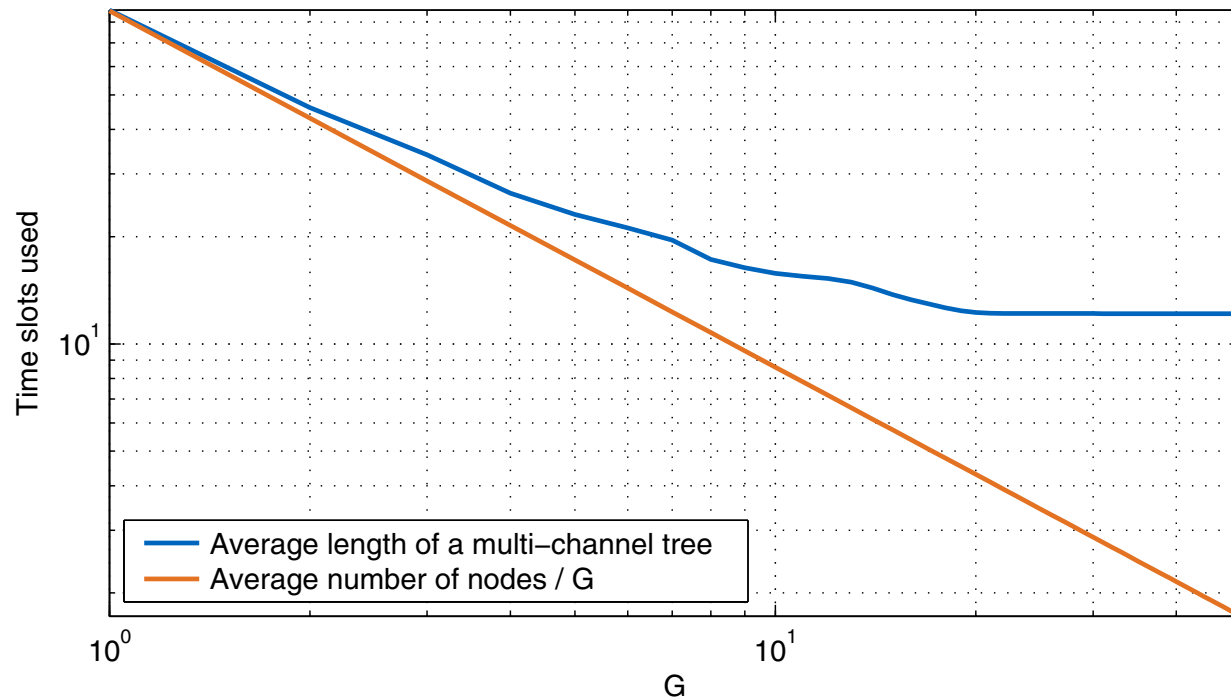
# Appendix B: results of the length of a multi-channel Tree

- **CDFs of the multi-channel Tree length** for several values of  $G$  with  $N = 60$

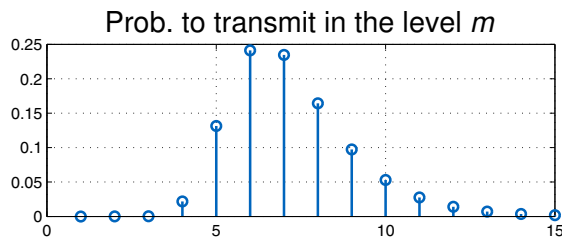


# Appendix B: results of the length of a multi-channel Tree (IV)

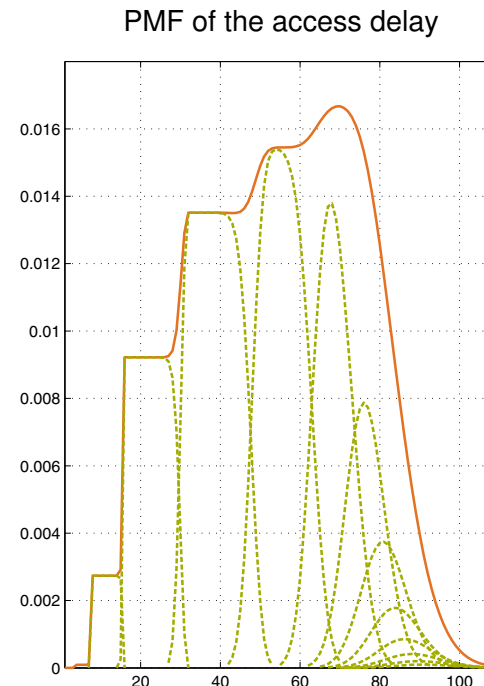
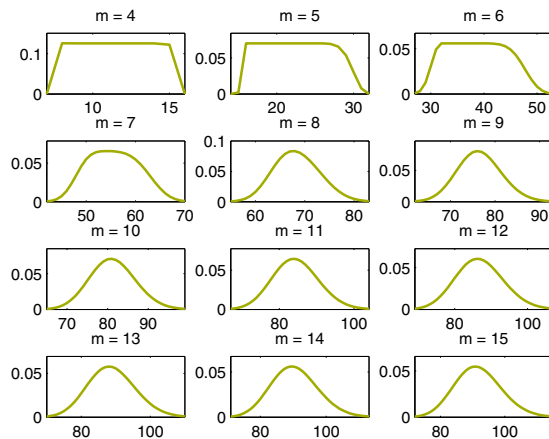
- Evolution of **average of the multi-channel Tree length** for several values of  $G$  with  $N = 60$



# Appendix C: explanation of the PMF of the access delay

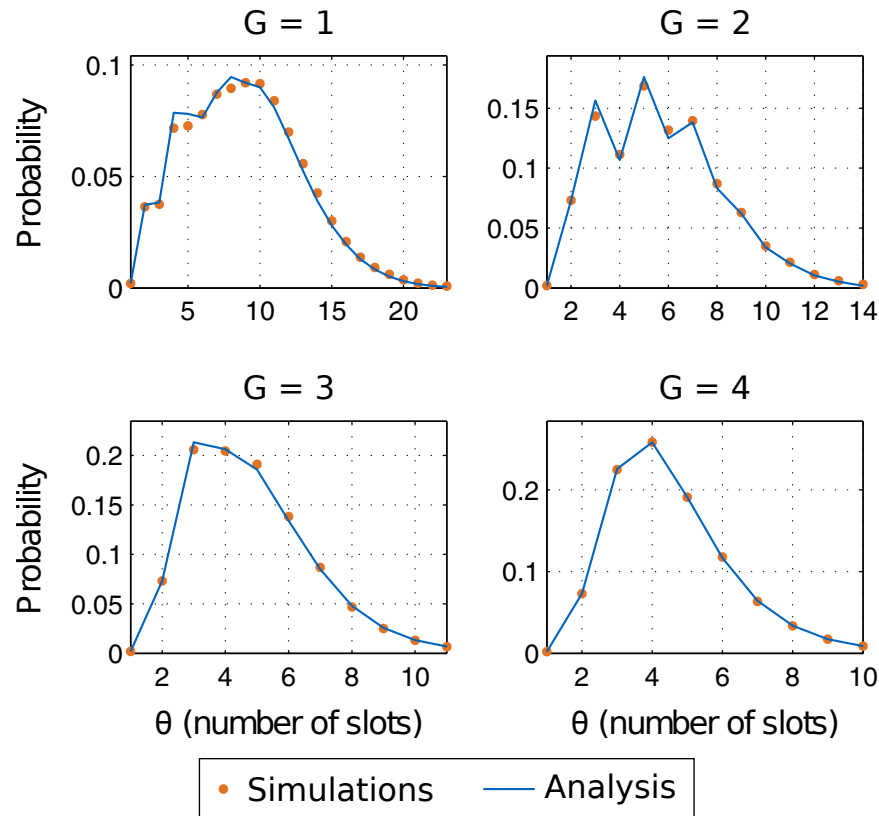


PMF of the access delay, knowing that transmission occurred in the level  $m$



# Appendix D: additional simulation results

- After 26500 iterations, PMFs of the **access delay** for  $N = 10$ :





# Appendix E: Modeling a Multichannel Tree

$S_m \longrightarrow$  Number of nodes at level  $m$

$T_m \longrightarrow$  Number of slots at level  $m$

$G \longrightarrow$  Number of contention frames in a slot

The number of slots at level  $m$  can be expressed as:

$$T_m = \left\lceil \frac{S_m}{G \cdot q} \right\rceil = \left\lceil \frac{X_{m-1}}{G} \right\rceil$$

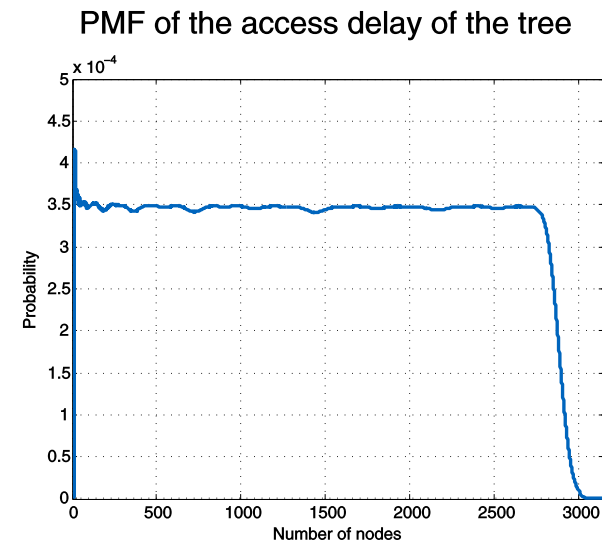
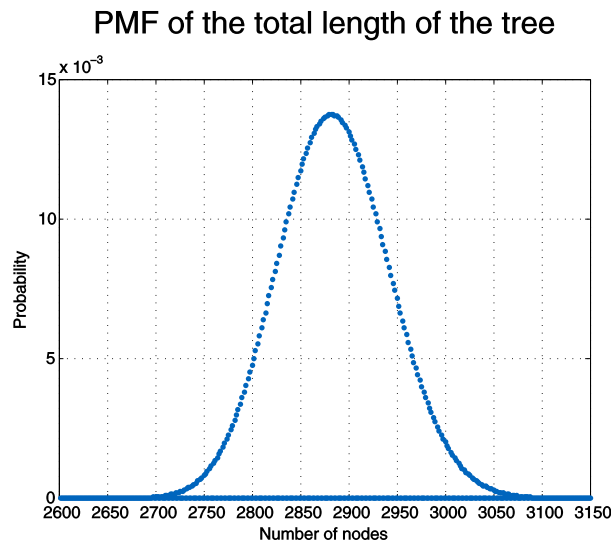
The total number of slots needed by the tree is then:

$$T = 1 + \sum_{m=1}^{\infty} T_m \approx 1 + \sum_{m=1}^M T_m$$

We can set  $M$  as  $\Pr\{L > M\} \leq \varepsilon$  [10] for a small enough  $\varepsilon$  (e.g.  $\varepsilon = 0.01$ )

# Appendix F: Proposed contributions to the analysis of tree algorithms (I)

- Extension of probability-generating function
  - We can enhance the utility of the PGF by using an FFT-computed expression instead of the classical Z-transform [10]
  - With this modification we can extend the analysis of the length of the tree and the access delay for thousands of devices with low computational cost



# Appendix F: Proposed contributions to the analysis of tree algorithms (II)

- Calculation of the marginal PMFs of the number of nodes in each level
  - It is possible to transform some tree-based problems to a bins-and-balls approach [8]
  - With this approach, we can obtain the marginal PMF of the number of nodes at level  $m$  as [2]:

$$f_{S_m}(s_m) = X_{2^{m-1}}(N, s_m)$$

$$X_R(N; k) = \sum_{x=k}^{\min(N-k, R)} \frac{\psi_{x,k}^N \binom{R}{x} x!}{R^N}$$

where  $\psi_{x,k}^N$  are the number of ways to arrange  $N$  balls into  $x$  bins, such that  $k$  of them have more than one ball. This numbers are defined throught the recursion [2]:

$$\psi_{x,k}^N = k\psi_{x,k}^{N-1} + (x - k + 1)\psi_{x,k-1}^{N-1} + \psi_{x-1,k}^{N-1}$$

- The expression for  $X_R(N; k)$  is however hard to compute. We further propose:

$$\frac{\psi_{x,k}^N \binom{R}{x} x!}{R^N} = \xi_{x,k}^{R,N} = \frac{1}{R} \left[ k\xi_{x,k}^{R,N-1} + (x - k + 1)\xi_{x,k-1}^{R,N-1} + (R - x + 1)\xi_{x-1,k}^{R,N-1} \right]$$

# Appendix G: Average length of a Multichannel Tree (I)

- One of the few parameters that whose analysis can be found in the literature [7063635]
- In [7063635], they stated:

$$E\{T\} = 1 + \sum_{m=1}^{\infty} \left\lceil \frac{E\{X_m\}}{G} \right\rceil$$

where  $E\{X_m\}$  is the average number of collisions at level  $m$

- However, this implies the following relation

$$T_m = \left\lceil \frac{X_{m-1}}{G} \right\rceil \longrightarrow E\{T_m\} = \left\lceil \frac{E\{X_{m-1}\}}{G} \right\rceil$$

which is in general **wrong**, and therefore it must be only taken as an approximation

# Appendix G: Average length of a Multichannel Tree (II)

- However, an exact expression can be worked out
- First, we should reformulate the ceil function as:

$$\left\lceil \frac{X_{m-1}}{G} \right\rceil = \begin{cases} \frac{X_{m-1}}{G} & \text{if } X_{m-1} \bmod G = 0 \\ \frac{X_{m-1}+G-1}{G} & \text{if } X_{m-1} \bmod G = 1 \\ \vdots & \vdots \\ \frac{X_{m-1}+1}{G} & \text{if } X_{m-1} \bmod G = G-1 \end{cases}$$

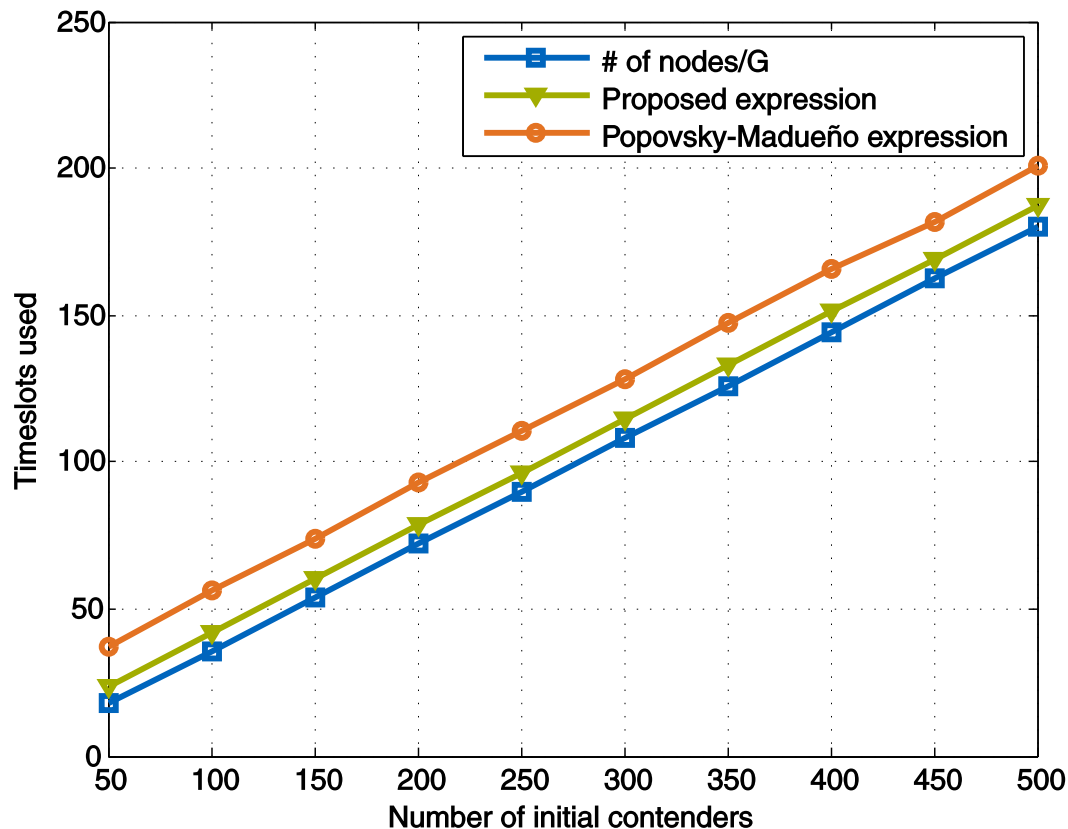
- Now we apply the law of total expectation:

$$\begin{aligned} E \left\{ \left\lceil \frac{X_{m-1}}{G} \right\rceil \right\} &= \frac{1}{G} E\{X_{m-1}\} \Pr\{X_{m-1} \bmod G = 0\} + \dots + \frac{1}{G} E\{X_{m-1} + 1\} \Pr\{X_{m-1} \bmod G = G-1\} \\ &= \frac{1}{G} \left( E\{X_{m-1}\} + \sum_{k=1}^{G-1} (G-k) \cdot \sum_{j=0}^{\infty} \Pr\{X_{m-1} = G \cdot j + k\} \right) \end{aligned}$$

- In order to perform this calculation, we need to know the marginal PMFs of the collisions at each level

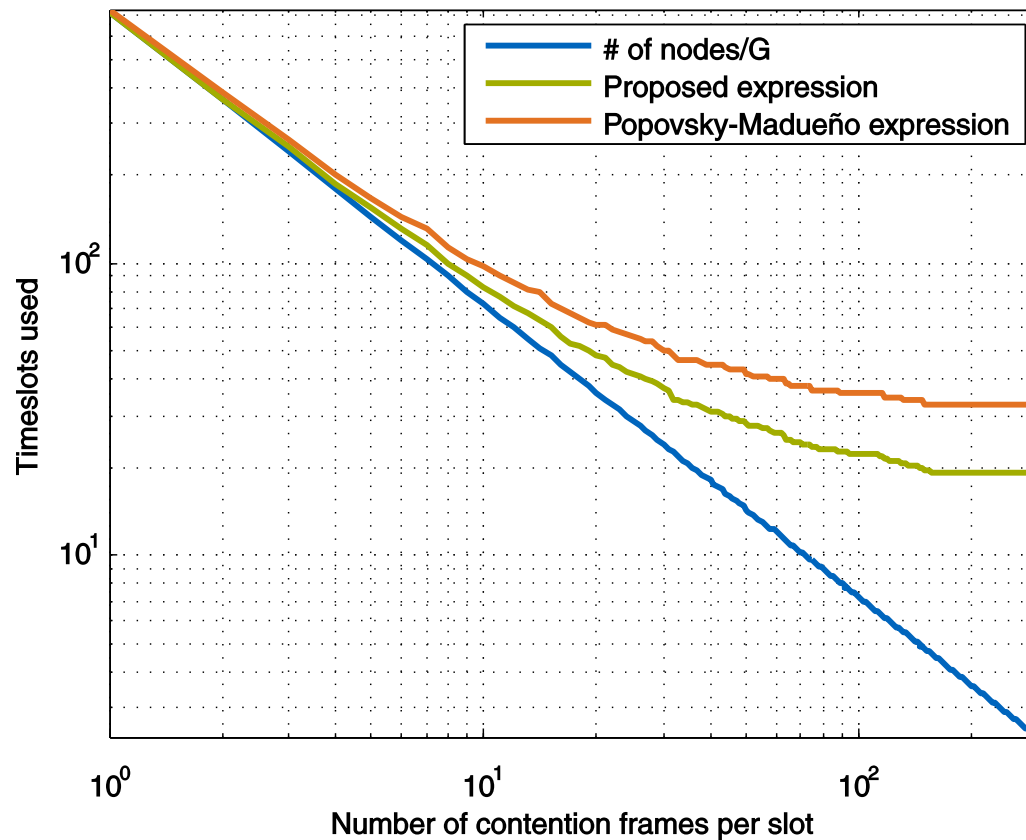
# Appendix G: Average length of a Multichannel Tree (III)

Lengths as a function of initial contenders, with  $G = 4$



# Appendix G: Average length of a Multichannel Tree (IV)

Lengths as a function of the number of nodes per timeslots, with  $N = 500$



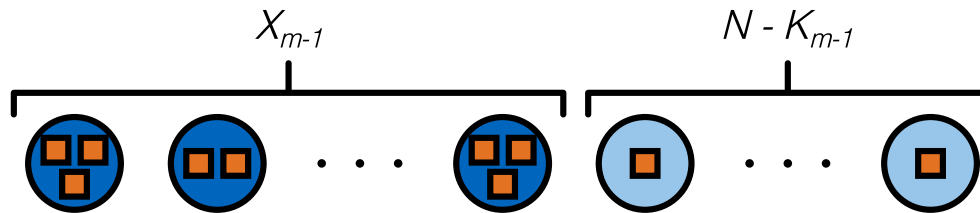
# Appendix H: Markovian approach (I)

- The probability  $f_{K_{m-1}|X_{m-1}}(k_{m-1}|x_{m-1})$  is computed as the following ratio:

$$f_{K_{m-1}|X_{m-1}}(k_{m-1}|x_{m-1}) = \frac{\Gamma_{K_{m-1}}^{X_{m-1}}}{\sum_{K_{m-1}} \Gamma_{K_{m-1}}^{X_{m-1}}} = \frac{\text{\# of ways to have } K_{m-1} \text{ contenders given } X_{m-1} \text{ collisions}}{\text{\# of ways to have } X_{m-1} \text{ collisions}}$$

- The term  $\Gamma_{K_{m-1}}^{X_{m-1}}$  is obtained by approaching the problem as a **bins-and-balls problem** [2]:

$$\Gamma_{K_{m-1}}^{X_{m-1}} = \psi_{N-K_{m-1}+X_{m-1}, X_{m-1}}^N \left( \binom{q^{m-1}}{N-K_{m-1}+X_{m-1}} (N-K_{m-1}+X_{m-1})! \right)$$





## Appendix H: Markovian approach (II)

- Now we are left with the computation of  $f_{X_m|X_{m-1},K_{m-1}}(x_m|x_{m-1},k_{m-1})$
- We have to **decompose**  $K_{m-1}$  into partitions of  $X_{m-1}$  collisions. Let us call  $\pi_i$  the partition  $i$  of  $K_{m-1}$  into  $X_{m-1}$  parts, all of them greater than 1. Then:

$$f_{X_m|X_{m-1},K_{m-1}}(x_m|x_{m-1},k_{m-1}) = \sum_i f_{X_m|X_{m-1},K_{m-1},\Pi_i}(x_m|x_{m-1},k_{m-1},\pi_i) \cdot f_{\Pi_i}(\pi_i)$$

- Let us define  $\pi_i = \{\kappa_1, \kappa_2, \dots, \kappa_{X_{m-1}}\}$  and  $\# \pi_i = \{\#_1, \#_2, \dots, \#_{X_{m-1}}\}$ , where  $\#_j$  is the number of parts equal to  $j$  of  $\pi_i$ . It can be shown that:

$$f_{\Pi_i}(\pi_i) = \frac{K_{m-1}!}{\psi_{X_{m-1},X_{m-1}}^{K_{m-1}}} \cdot \prod_{j=1}^{X_{m-1}} \frac{1}{\kappa_j! \#_j!}$$

- Finally, given some partition  $\pi_i$ , the **total number of collisions** at level  $m$  will be the sum of the number of collisions in each independent subtree

# Appendix I: From joint to sum distribution

- Let us define the auxiliary random variable:

$$\Sigma_m = \sum_{j=1}^m X_j$$

- We can apply the associative property to express our desired PMF as a function of a bivariate joint PMF:

$$f_{X=X_1+\dots+X_m}(x = x_1 + \dots + x_m) = f_{X=\Sigma_{m-1}+X_m}(x = \sigma_{m-1} + x_m) = \sum_{j=0}^x f_{\Sigma_{m-1}, X_m}(j, \sigma_{m-1} - j)$$

- After some basic manipulation, we can express that bivariate function as:

$$f_{\Sigma_{m-1}, X_m}(x_m, \sigma_{m-1}) = \sum_{x_{m-1}} f_{X_m|X_{m-1}}(x_m|x_{m-1}) f_{X_{m-1}, X_{m-1}+\Sigma_{m-2}}(x_{m-1}, \sigma_{m-2})$$

which exhibits a clear recursive structure, much more suitable to compute