

- INS\_IEP: A MATLAB package for fitting Inelastic
- <sup>2</sup> Neutron Scattering data.
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22

## Summary

Inelastic neutron scattering (INS) is a spectroscopic technique used to measure the magnetic excitations in materials with interacting electron spins. INS experiments yield data about the eigenvalues of the spin Hamiltonian of the material being studied. Fitting a model spin system to these experimental eigenvalues can be formulated as an inverse eigenvalue problem (IEP), where the matrix formed is the spin Hamiltonian operator of the sample molecule. INS\_IEP is a MATLAB package that uses deflated numerical optimisation techniques to systematically find multiple solutions to this IEP. The package requires and is fully compatible with easyspin (Stoll & Schweiger, 2006), a package for solving fitting problems in electron paramagnetic resonance (EPR).

### Statement of need

Neutrons are an excellent bulk probe of material properties since they carry no charge and therefore penetrate deeply into matter. Neutrons also carry a quantum spin of a half, making them a sensitive probe of magnetism (Squires, 2012). Reactors and spallation sources with dedicated high-flux neutron sources serve the international research community with neutron scattering experiment capabilities for material research. Inelastic neutron scattering (INS) is one such experimental technique that can be used to study magnetism. In an INS experiment, a sample under investigation is irradiated with a beam of neutrons and the scattered neutron energy and momentum transfer are detected. For samples composed of finite-size clusters of magnetic moment-carrying atoms, such as single ions or molecular-based magnets, the detected neutron energy transfer gives direct access to the quantum spin excitations (M. Baker & Mutka, 2012; Furrer & Waldmann, 2013; "Spectroscopy Methods for Molecular Nanomagnets," 2014).

The energy of such excitations relates to the energy difference between eigenvalues of the Hamiltonian matrix that describes the quantum spin dynamics of the compound in question. Single-ion and molecular-based magnets are studied as prototype components (quantum bits, sensors) for quantum technologies. INS can therefore provide crucial information concerning the precise quantum properties of such systems. However, to relate the INS experimental results to the Hamiltonian that describes quantum spin dynamics requires parameterisation of matrix elements such that a set of eigenvalues and eigenstates matching the experiment are determined. This situation is known as the inverse eigenvalue problem.

To date, this problem is addressed in an iterative process where parameters of the Hamiltonian are varied manually, often one at a time, and the resultant eigenvalues compared to the experimental values - each such iteration requires an eigendecomposition of the Hamiltonian matrix. INS\_IEP presents an elegant solution to solving this problem, using algorithms to calculate multiple parameter sets that minimise the difference in eigenvalues, reducing the



- number of Hamiltonian matrix diagonalisations, and providing a more robust method to reliably
- extract an accurate spin Hamiltonian model from INS experimental data.

# **Key Concepts**

### The Spin Hamiltonian

- The Spin Hamiltonian,  $H_i$  is an approximation of the Hamiltonian that uses spin coordinates
- instead of orbital coordinates, and is widely used to model data arising from many spectroscopy
- techniques (Launay & Verdaguer, 2014). It can be modeled as a linear combination of
- interaction terms; in this package we will use the zero field interaction,  ${\cal H}_{ZFI}$ , and the
- electron-electron interaction,  $H_{EEI}$ :

$$H = H_{ZFI} + H_{EEI}.$$

- Both of these terms can themselves be modelled as the linear sum of other basis matrices.
- The zero field interaction can be written as:

$$H_{ZFI} = \sum_{-k \leq q \leq k} B_k^q O_k^q$$

- where the  $O_k^q$  are Stevens Operators (Rudowicz & Chung, 2004), and  $B_k^q$  the associated parameter. When there are multiple spin centres it is necessary to take Kronecker products of
- the operator with identity matrices of the appropriate for each other spin centre.
- When there are multiple spin centres it is also necessary to include an electron-electron
- interaction term,  $H_{EEI}$ . This term will be the sum of interaction terms between each pair of
- spin centres:

$$H_{EEI} = -\sum_{i \neq j} J_{ij} S_i \cdot S_j$$

- where  $S_i$  is the vector of spin operators  $S_i = [S_x, S_y, S_z]$  for the *i*-th spin centre, and  $J_{ij}$  is
- the parameter to be found that represents the strength of interaction between the two spin
- centres. Note that in the isotropic case J can be thought of as a scalar value, but in the
- anisotropic case will be a matrix where the off diagonals are skew symmetric (often the off
- diagonals are assumed to be zero). While the summation is in theory over all spin centre
- combinations, in practice many of these contributions will be negligible often only the nearest
- neighbour interactions are modeled.
- It is important to mention that these matrix operators can be very large. The size is defined
- by the number of spin centres (n) and the spin  $(S_i)$  of each spin centre. The dimension of
- matrices is given by:

$$\prod_{i=1}^{n} (2S_i + 1).$$

- The operators are however highly sparse, this means that it is possible to use eigensolvers that
- can take advantage of this sparsity.

#### Inverse Eigenvalue Problem

- The INS experiments provide eigenvalues of the Spin Hamiltonian matrix of the sample, the
- task of calculating the matrix from the eigenvalues is an inverse eigenvalue problem:
- Let A(x) be the affine family of matrices,



$$A(x) = A_0 + \sum_{i=1}^\ell x_i A_i,$$

where  $x \in \mathbb{C}^\ell$  and  $A_0,\dots,A_\ell \in \mathbb{R}^{n \times n}$  are linearly independent Hermitian matrices, and denote the ordered eigenvalues of A(x) as  $\lambda_1(x) \leq \cdots \leq \lambda_n(x)$ . Then the least squares inverse eigenvalue problem (LSIEP) is to find the parameters  $x \in \mathbb{R}^{\ell}$  that minimises

$$F(x) = \frac{1}{2}||r(x)||_2^2 = \frac{1}{2}\sum_{i=1}^m (\lambda_i(x) - \lambda_i^*)^2$$

where  $\lambda_1^* \leq ... \leq \lambda_m^*$  are the experimental eigenvalues (Chen & Chu, 1996). In the case of INS fitting the  $A_i$  basis matrices will be a combination of Stevens operators and electron-electron exchange terms. The IEP described above is formulated as an least squares problem because the number of eigenvalues that can be probed by INS experiments is often a small subset of the full spectrum. Due to the low temperatures that these experiments are performed at (can be as low as 1K) it is always the smallest eigenvalues that are involved. Note also that since it is the energy difference between the eigenvalues that is probed we actually have to modify the IEP - either by adding an additional parameter (an identity matrix) that shifts the values of the eigenvalues, or by changing the above formula for F to directly sum the difference in eigenvalues thereby reducing the number of residual equations in r(x) by one.

As far as we are aware this is the first time that the fitting of INS data has been explicitly formulated as an IEP. An advantage of this formulation is that there are explicit formulas for the derivatives of r(x). The first derivative (Jacobian) is:

$$J_r(x) = \begin{pmatrix} q_1(x)^T A_1 q_1(x) & \dots & q_1(x)^T A_\ell q_1(x) \\ \vdots & \ddots & \vdots \\ q_m(x)^T A_1 q_m(x) & \dots & q_m(x)^T A_\ell q_m(x) \end{pmatrix},$$

and the second derivative (Hessian) is:

$$(H_r)_{ij} = 2\sum_{k=1}^m (\lambda_k - \lambda_k^*) \sum_{\substack{t=1\\ j \neq \lambda}}^m \frac{(q_t^T A_i q_k)(q_t^T A_j q_k)}{\lambda_k - \lambda_t}.$$

Another advantage is the number of constraints to fit is much smaller than fitting the spectrum itself, as it corresponds to fitting only the locations of the peaks of the spectrum.

### Methods

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All of the methods used are iterative schemes of the form  $x^{k+1} = x^k + p^k$  where the step  $p^k$ uniquely defines each algorithm:

- Newton's method:  $p^k = (J_r^T J_r + H_r r) 1J_r^T r$  (Nocedal & Wright, 2006) 
   Gauss-Newton method:  $p^k = (J_r^T J_r)^{-1} J_r^T r$  (Nocedal & Wright, 2006) 
   Lift and Projection Method:  $p^k = B^{-1} J_r^T r$  (Bloor Riley et al., 2025a)

Where the matrix  $\boldsymbol{B}$  is the Gram matrix formed from the frobenius inner products of the basis matrices:  $B_{ij} = \langle A_i, A_j \rangle_F$ . The Lift and Projection method is a Riemannian Gradient descent 100 method (Bloor Riley et al., 2025a), inspired by the Lift and Projection method (Chen & Chu, 101 1996), specifically designed for solving IEPs. In (Bloor Riley et al., 2025a) it is proven that the method is a strictly descending algorithm, that is it reduces the value of the objective function 103 every step. Both the deflated Gauss-Newton method and the Riemannian Gradient descent 104 Lift and Projection method are new methods designed for this package (Bloor Riley et al., 2025a, 2025b).



#### Deflation

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The number of eigenvalues that can be probed via INS experiments varies depending on the equipment and sample in question, meaning that the fitting problem is often under or even over determined. The IEP is also highly nonlinear and due to the experimental nature of the data may be ill-posed. One consequence of this is that the solution space may be very 'bumpy', that is there may exist many local minimisers to the problem. For example in Figure 1, there are clearly 4 distinct solutions (for more details see Example 1 and the file Example1\_Mn12.m in the examples folder). We seek to solve the problem of multiple local minima by the use of Deflation, a numerical technique used to find multiple solutions to systems of equations (Farrell et al., 2015). Fortunately it is cheap to apply deflation for the above methods, it is simply a change to the length of the step - notably this means that the direction of each step does not change. It is proven in (Bloor Riley et al., 2025b) that the deflated methods will not converge to deflated points. The usual requirements still apply to the convergence of the new methods - that the initial guess is close enough to the new minimum, and that the Jacobian is full rank in a neighbourhood around that minimum. The rate of convergence of the deflated methods is also more complicated, although the number of iterations required to converge can go up with the number of deflations this is not a strict correlation, as can be seen in Figure 2.

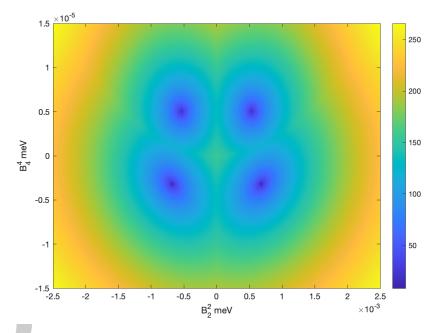
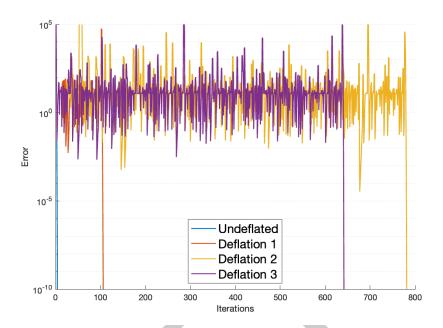


Figure 1: Contour plot of how F varies with the two parameters  $B_2^2$  and  $B_4^4$  for the molecule Mn\_12 as described in Example 1. There are four locally minimising parameter pairs corresponding to the four blue regions





**Figure 2:** Comparison of the convergence behaviour for computing each solution in Example 1. The gradient of the lines as the method approaches the solution shows how the methods are quadratically convergent local to a minimum.

### 24 Examples

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# Example 1 - Mn12

The first example we will look at is Manganese-12-acetate. This is a well known example in the INS and magnetism community, as one of the first molecules that behaves like a nano-sized magnet with a molecular magnetic coercivity as well as its role in the research of quantum tunnelling of magnetisation (Friedman et al., 1996; Sessoli et al., 1993).

The Spin Hamiltonian of this system, using the giant spin approximation, can be represented as a  $21 \times 21$  matrix modelled using 4 Stevens operators (Bircher et al., 2004):

$$H = B_2^0 O_2^0 + B_4^0 O_4^0 + B_2^2 O_2^2 + B_4^4 O_4^4 \in \mathbb{R}^{21 \times 21}$$

We utilise the same spin system syntax as easyspin, so to set up the problem we first set up the model, along with initial guesses for the parameters:

```
%One spin centre (because giant spin approximation)
Sys0.S=10;
%Four Stevens operators
Sys0.B2 = [-100,0,-1000,0,0];
Sys0.B4 = [-1,0,0,0,-1,0,0,0,0];
```

Then we input the experimental eigenvalues - these are typically shifted such that the smallest eigenvalue is zero - and define which parameters to fit. Note that all values given must be in Hertz, so it may be useful to use conversions.



```
%Vary all non zero parameters (no Fixed parameters):
Vary = Sys0;
```

Then all that is required is to call INS\_IEP with these three inputs:

```
SysOut = INS_IEP(Sys0, Vary, Exp);
```

If we wish to find all four solutions as shown in Figure 1 then we use the additional option:

```
Opt.NDeflations = 4;
SysOut = INS_IEP(Sys0,Vary,Exp,Opt);
```

In this case SysOut will be an array of four spin structures each containing a distinct locally optimal solution. It is possible to access information about the convergence of each deflation by using SysOut.Output. For example by utilising the iterates recorded, stored in SysOut.Output.Iterates it is possible to plot a graph of convergence, as can be seen in Figure 2. The Output structure also contains the value of F at the final point, as well as the number of iterations it took to get there.

A full list of options is provided in the help of INS IEP.

### **Example 2 - Chromium(iii) Horseshoes**

The second example concerns antiferro-magnetically coupled chromium(III) chains six atoms long (M. L. Baker et al., 2011), although different length chains are of interest and can also be modelled. Because there are multiple spin centres an electron-electron interaction term is required. The spin hamiltonian is a 4096×4096 matrix composed of two Stevens operators and one interaction term, since it is known a priori that each spin centre will have the same value parameters we pin the parameters here, by setting the initial guess as the same value:

```
Sys0.S = [1.5 \ 1.5 \ 1.5 \ 1.5 \ 1.5 \ 1.5];
Sys0.B2 =
                                        0;
            [1
                    (1)
                                 0
                   (1)
                                       0;
                   0
            1
                         -1
            1
                   0
                                0
                                       0:
                         -1
                                0
                         _1
                                       0:
                         -1
                                0
                                       0];
Sys0.J = [100,0,0,0,0,100,0,0,100,0,0,100,0,100];
Vary = Sys0;
Exp.ev = [0,0.355,0.457,0.497,1.576,1.577,1.592,1.629,1.632,
           2.97, 2.98, 3.002, 3.004, 3.01, 3.038, 3.821, 3.824, 3.827,
           3.837,3.856,3.879,3.888,3.895,3.903];
```

Note that only 24 eigenvalues were found experimentally, so this will form a partial LSIEP. To find the solution system is as simple as:

```
SysOut = INS_IEP(Sys0, Vary, Exp);
```

155 It is possible to find multiple minimising systems even if they do not make any sense physically, 156 however due to the scaling of the problem a change in the default deflation parameters is 157 necessary:

```
Opt = struct('NDeflations',4,'Sigma',1e-7);
SysOut= INS_IEP(SysO,Vary,Exp,Opt);
```

- The output contains four different spin systems that all have the same eigenvalues as input, one is the original solution up to a change of sign of the  $B_2^2$  parameter, and all have the same exchange term.
- 61 Additional examples can be found in the Examples folder.



Note also that using mint (M. L. Baker, 2022), which is fully compatible with INS\_IEP it is possible to simulate the INS spectrum of any calculated system - which can then be compared to the experimental spectrum. A description of how to do this can also be found in the examples folder.

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206

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