(Ch. 1) Lecture 3: Convenience & Norns

Convenied Lex Equivilence Theorem States that a Numerical method must be consistent with the underlying Continuous courtions, i.e. take

Continuer equations, i.e., take $\frac{\partial z}{\partial t} + \frac{\partial z}{\partial x} = 0$ $\frac{1^{3+} \text{ order}}{2^{2+} \text{ order}}$ $\frac{\partial z}{\partial t} + \frac{1}{2^{2+} \text{ order}}$

+ O(be, dr) = 0

The discretized form recovers the continuous form as $(\Delta t, \Delta_X) \rightarrow 0$ at the rite of $O(\Delta t, \Delta_X)$.

Furthernore, it consistency is met, the Stedility

(i.e., the numerical Sol is bounded) if the necessary &

Sufficient Condition for Convergence.

Def Convergence means that, it the continuous es.

Not a unique analytic Solution, then given enough
resolution our conscitut & Stable Nonerical method
will converge to the "truth" at the rate of

O(Ath, Axu) when K & N are the orders of accoming
of our method in time & Spece, respectively.

Hower, it he hist to compen our numerical sol.

L/the truth then we need a metric to measure

how close we are.

Error Noras LR UX noras to perfora this test. Let's assure that he live in a vector spece, LP. Then let grant & general se the numerical se exact Solutions. Neget let us define the LP error as: (3.1) || gnon gexcet || LP = \[\langle \langl am din () = N The most conner crow norms that one encounters (3.2.1) L': 1/20- gexuelles = 5 / 2:00- 2:000 (3.2.3) Loo: 11 por - generalle = max (12 non - general) $|\overline{x}|_{2} = |\overline{x}|_{|x|} = |x| + |x| = |x|$ $|\overline{x}|_{2} = |x| + |x| = |x|$ or 1-novy

