

Lecture 6: 1d Interpolation

Assume we want to interpolate a function $f(x)$ by an N^{th} degree interpolant I_N s.t.

$$I_N(f(x_i)) = f(x_i) \quad \text{when } x_i \text{ are } i=0, \dots, N$$

distinct points where we sample the function. Here, we have chosen to match the function exactly at all x_i points. Between points x_i we write:

$$(6.1) \quad f(x) = \sum_{i=0}^N \psi_i(x) \tilde{f}_i + e_N(x) \quad \text{when } e_N(x) \text{ is}$$

the error incurred by approximating $f(x)$ with only N terms in the series. We can use two types of interpolation: Modal and Nodal.

Modal Interpolation For the domain $x \in [-1, +1]$ w/o periodicity, we obtain the SLD

$$\frac{d}{dx} \left[(1-x^2) \frac{d\psi}{dx} \right] + \lambda \psi = 0 \quad \text{when } p(x) = 1-x^2 \\ \& \quad \psi(x) = 1$$

which admits solutions of the type:

$$\psi(x) = \sum_{n=0}^{\infty} a_n x^n$$

& using Gram-Schmidt, we can derive the Legendre polynomials (see Ch. 18.5.2)

When they define an O.G. set as follows:

$$\int_{-1}^{+1} \omega(x) P_i(x) P_j(x) dx = \delta_{ij} \quad \forall (i,j) = 0, \dots, N$$

When $\omega(x) = 1$ it $P_i(x)$ have been Orthonormalized.

How Model Functions Work

Note that the first 3 Legendre polynomials are $P_0(x) = 1$, $P_1(x) = x$, & $P_2(x) = \frac{3}{2}x^2 - \frac{1}{2}$ (unnormalized).

If we wish to approximate the function $f(x) = a + bx + cx^2$ then we would find:

$$\begin{aligned} f(x) &\equiv \sum_{j=0}^N P_j(x) \tilde{f}_j = P_0(x) \tilde{f}_0 + P_1(x) \tilde{f}_1 + P_2(x) \tilde{f}_2 \\ &= \tilde{f}_0 + \tilde{f}_1 x + \tilde{f}_2 \left(\frac{3}{2}x^2 - \frac{1}{2} \right) \\ &= \left(\tilde{f}_0 - \frac{1}{2} \tilde{f}_2 \right) + \tilde{f}_1 x + \tilde{f}_2 \left(\frac{3}{2}x^2 \right) \end{aligned}$$

$$\therefore a = \tilde{f}_0 - \frac{1}{2} \tilde{f}_2, \quad b = \tilde{f}_1, \quad c = \frac{3}{2} \tilde{f}_2$$

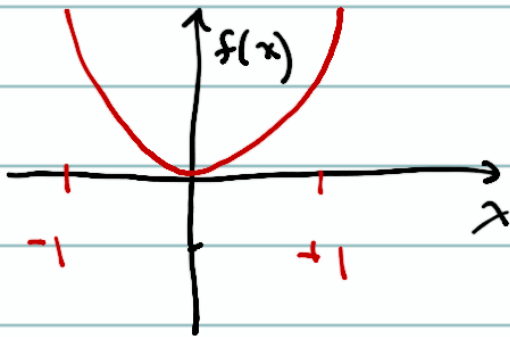
resulting in:

$$\tilde{f}_0 = a + \frac{1}{3}c$$

$$\tilde{f}_1 = b$$

$$\tilde{f}_2 = \frac{2}{3}c \quad \& \quad \text{we obtain the nodal approximation:}$$

EX 6.1 Use the $N=2$ Legendre polynomials to approximate $f(x) = x^2$ in $x \in [-1, +1]$



To find $f(x)$ for any x we need to sum all N terms in the expansion:

$$f(x) = p_0(x)\tilde{f}_0 + p_1(x)\tilde{f}_1 + p_2(x)\tilde{f}_2$$

e.g. Let $x_0 = -1$, $x_1 = 0$, & $x_2 = +1$

we can write:

$$f(x_0) = p_0(x_0)\tilde{f}_0 + p_1(x_0)\tilde{f}_1 + p_2(x_0)\tilde{f}_2 \equiv 1$$

$$f(x_1) = p_0(x_1)\tilde{f}_0 + p_1(x_1)\tilde{f}_1 + p_2(x_1)\tilde{f}_2 \equiv 0$$

$$f(x_2) = p_0(x_2)\tilde{f}_0 + p_1(x_2)\tilde{f}_1 + p_2(x_2)\tilde{f}_2 \equiv 1$$

or:

$$\begin{pmatrix} f(x_0) \\ f(x_1) \\ f(x_2) \end{pmatrix} = \begin{pmatrix} p_0(x_0) & p_1(x_0) & p_2(x_0) \\ p_0(x_1) & p_1(x_1) & p_2(x_1) \\ p_0(x_2) & p_1(x_2) & p_2(x_2) \end{pmatrix} \begin{pmatrix} \tilde{f}_0 \\ \tilde{f}_1 \\ \tilde{f}_2 \end{pmatrix}$$

which can be generalized for x_i & $p_j(x_i)$ $i, j = 0, \dots, N$

Vandermonde Matrix

In \mathbb{R}^n we can write the Legendre interpolation as follows:

$$\begin{pmatrix} f_0 \\ f_1 \\ \vdots \\ f_n \end{pmatrix} = \begin{pmatrix} p_0(x_0) & p_1(x_0) & \dots & p_n(x_0) \\ p_0(x_1) & p_1(x_1) & \dots & p_n(x_1) \\ \vdots & \vdots & \ddots & \vdots \\ p_0(x_n) & p_1(x_n) & \dots & p_n(x_n) \end{pmatrix} \begin{pmatrix} \tilde{f}_0 \\ \tilde{f}_1 \\ \vdots \\ \tilde{f}_n \end{pmatrix}$$

which we write as: Vandermonde Matrix

$$f_i = V_{ij} \tilde{f}_j \rightarrow \text{Legendre Transform map}$$

Note that V provides the map b/w model & model space since given \tilde{f}_i we now know f_i .
And vice-versa, given f_i we know \tilde{f}_i from:

$$\tilde{f}_i = V^{-1}_{ij} f_j \quad \text{for } \det(V) \neq 0$$

Inverse Legendre transform map.

Mod-1 Interpolation Let us write:

$$f(x) = \sum_{j=0}^N L_j(x) f_j \quad \text{where} \quad f_j = f(x_j) \rightarrow \text{ie, } f_j \text{ are the values of } f \text{ at } x_j$$

Then we now insist that the interpolant match the function exactly at certain locations x_j , $j=0, \dots, N$. This then means that $L_j(x)$ are cardinal functions w/ the following property:

$$L_j(x_i) \equiv L_{ij} = \begin{cases} 1 & \text{if } i=j \\ 0 & \text{if } i \neq j \end{cases} \equiv \delta_{ij}$$

w/ the Partition of Unity property: $\sum_{j=0}^N L_j(x) = 1 \quad \forall x \in [-1, 1]$

How to Derive Lagrange Polynomial

If $\psi_i(x)$ defines the O.G. polynomial which are the solutions to the SLO (i.e., $\psi_i(x)$ are the eigenfunctions & natural basis on this domain) then we can use Lagrange polynomials to write:

$$(6.2) \quad \psi_i(x) = \sum_{j=0}^N \psi_i(x_j) L_j(x) \quad \text{where}$$

x_j are any set of points where $\psi_i(x)$ have been

sampled & used to define $L_j(x)$.

In fact, note that $\ell_i(x_j) = V_{ij}$ is in fact the generalized Vandermonde matrix & so we can rewrite (6.2) as follows:

$$(6.3) \quad V_{ij} L_j(x) = \ell_i(x)$$

If V_{ij} is non-singular then we can left-multiply by V^{-1} to get:

$$(6.4) \quad L_i(x) = V_{ij}^{-1} \ell_j(x) \rightarrow \text{This is the general that we could use in multi-dimensions.}$$

Lagrange Polynomials in 1D In 1D \exists a simpler form given by:

$$(6.5) \quad L_i(x) = \prod_{\substack{j=0 \\ j \neq i}}^N \left(\frac{x - x_j}{x_i - x_j} \right) = \frac{(x - x_0)(x - x_1) \dots (x - x_N)}{(x_i - x_0)(x_i - x_1) \dots (x_i - x_N)}$$

where if $x = x_i$, $L_i(x_i) = 1$

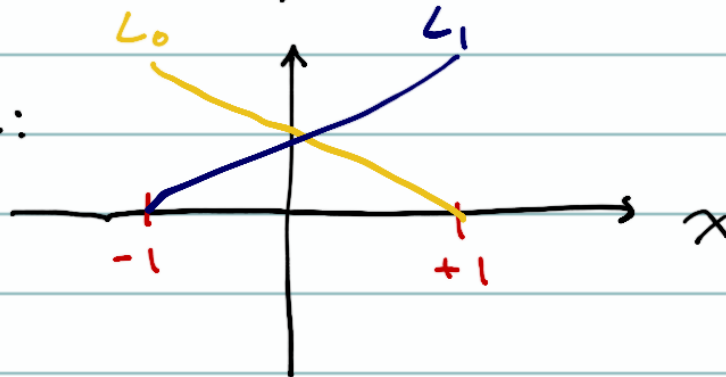
Ex 6.2 For $N=1$ we get $x_0 = -1$ & $x_1 = +1$ & so:

$$L_i(x) = \frac{(x - x_0)(x - x_1)}{(x_i - x_0)(x_i - x_1)} \quad j \neq i$$

$$\therefore L_0(x) = \frac{(x-x_1)}{(x_0-x_1)} = \frac{x-1}{-1-1} = \frac{1}{2}(1-x)$$

$$L_1(x) = \frac{(x-x_0)}{(x_1-x_0)} = \frac{x+1}{2} = \frac{1}{2}(1+x)$$

which look like:



Note that $L_0(x_0) = \frac{1}{2}(1+1) = 1$ & $L_0(x_1) = \frac{1}{2}(1-1) = 0$
 & $L_1(x_0) = 0$ & $L_1(x_1) = \frac{1}{2}(2) = 1$

& $\sum_{i=0}^N L_i(x) \equiv L_0(x) + L_1(x) = \frac{1}{2}(1-x) + \frac{1}{2}(1+x) = 1 \rightarrow$ Cardinality
partition of unity

HW 1 Construct $L_i(x)$ for $i=0, \dots, 2$ w/
 $x_0=-1$, $x_1=0$, & $x_2=+1$. Plot them
 & show Cardinality & Partition of Unity.

Constructing Good Interpolants

In 1D, we construct Lagrange polynomials using:

$$L_i = \prod_{j \neq i} \frac{x-x_j}{x_i-x_j} \quad \text{when we need to know}$$

a priori the points (called roots) x_i $i=0, \dots, N$.

So far we have used equi-spaced points (e.g., $x_0 = -1$
 $x_1 = 0$
 $x_2 = +1$)

But continuing in this way for large N is not a good idea, as we shall see. Before describing the issue & the solution, let's introduce the Lebesgue function.

Lebesgue Function For the Lagrange polynomials L_i the Lebesgue function:

$$\mathcal{L}_N(x) = \sum_{i=0}^N |L_i(x)| \quad \& \quad \text{the}$$

Lebesgue constant is: $\mathcal{L}_N \equiv \max(\mathcal{L}_N(x)) = \max\left(\sum_{i=0}^N |L_i(x)|\right)$

Constructing Good Interpolation Points

To construct good interpolation points, let's look at the roots of O.G. polynomials.

Chebyshev Points The roots of these polynomials are obtained in closed-form solution as follows:

$$x_i = \cos\left(\frac{2i+1}{2N+2} \pi\right) \quad \text{for } i=0, \dots, N$$

These points are optimal for interpolation but do not include the endpoints $x = \pm 1$

Legendre Points

The roots of these polynomials are obtained via Newton's method or such:

$$Q_N(x^{(n+1)}) = Q_N(x^{(n)}) + (x^{(n+1)} - x^{(n)}) \frac{dQ_N}{dx}(x) \equiv 0$$

or

$$x^{(n+1)} = x^{(n)} - \frac{Q_N(x^{(n)})}{Q'_N(x^{(n)})}$$

which requires a good starting value $x^{(0)} = \text{Chebyshev points}$.

These points are very good but do not include the endpoints $x = \pm 1$.

Lobatto Points

If we require the endpoints, then we require a different set of points.

Simply writing: $P_N^m(x) = (1+x)(1-x)P_{N-2}(x)$ will

certainly now include the endpoints but the polynomials are no longer O.G.

Instead, we can define:

$$L_N(x) = (1-x^2) P'_{N-1}(x) \rightarrow \text{Lobatto polynomials}$$

$$\text{are O.G. s.t. } \int_{-1}^{+1} L_i(x) L_j(x) dx = C \delta_{ij}$$

& also include the endpoints.

The zeros of $L_N(x)$ are endpoints + roots of $P'_{N-1}(x)$.
The zeros/roots of $P'_{N-1}(x)$ is where the extrema of $P_N(x)$ occur. Therefore, using these points to construct the Lagrange polynomials ensure good behavior (no wild oscillation, see Fig 3.4 in text)

