

Lecture 15: 2D Elliptic CG

Introduction

So far we have learned how to solve the 1D Poisson problem: $\frac{d^2 g}{dx^2} = f(x)$ w/ appropriate BCS.

Let us now consider the multi-dimensional Poisson problem:

$$(15.1) \quad \nabla^2 g(\bar{x}) = f(\bar{x}) \quad \text{w/} \quad \bar{x} = x_i \quad i=1, \dots, d$$

where $\nabla^2 = \bar{\nabla} \cdot \bar{\nabla}$ w/ BCS:

$$g|_{\Omega_0} = g(\bar{x}) \quad \text{and/or} \quad \hat{n}_\Omega \cdot \bar{\nabla} g|_{\Omega_\nu} = h(\bar{x})$$

Integral Form

To discretize (15.1) we first approximate $g_N^{(e)}(\bar{x})$ as follows:

$$(15.2) \quad g_N^{(e)}(\bar{x}) = \sum_{i=1}^{M_N} \psi_i(\bar{x}) g_i^{(e)} \quad \text{w/} \quad f_N^{(e)}(\bar{x}) = \sum_{i=1}^{M_N} \psi_i(\bar{x}) f_i^{(e)}$$

* Subbing into (15.1) gives:

$$(15.3) \quad \int_{\Omega_e} \psi_i \nabla^2 g_N^{(e)} d\Omega_e = \int_{\Omega_e} \psi_i f_N^{(e)} d\Omega_e \quad \forall \psi \in H^1$$

where IBP gives: $\bar{\nabla} \cdot (\psi_i \bar{\nabla} f_v^{(e)}) = \bar{\nabla} \psi_i \cdot \bar{\nabla} f_v^{(e)} + \psi_i \nabla^2 f_v^{(e)}$

which gives in (15.3)

$$(15.4) \quad \int_{\Omega_e} \bar{\nabla} \cdot (\psi_i \bar{\nabla} f_v^{(e)}) d\Omega_e - \int_{\Omega_e} \bar{\nabla} \psi_i \cdot \bar{\nabla} f_v^{(e)} d\Omega_e = \int_{\Omega_e} \psi_i f_v^{(e)} d\Omega_e$$

Using the divergence theorem for the 1st term on the LHS yields:

$$(15.5) \quad \int_{\Gamma_e} \hat{n} \cdot (\psi_i \bar{\nabla} f_v^{(e)}) d\Gamma_e - \int_{\Omega_e} \bar{\nabla} \psi_i \cdot \bar{\nabla} f_v^{(e)} d\Omega_e = \int_{\Omega_e} \psi_i f_v^{(e)} d\Omega_e$$

Subbing (15.2) into (15.5) yields:

$$\int_{\Gamma_e} \hat{n} \cdot (\psi_i \bar{\nabla} f_v^{(e)}) d\Gamma_e - \int_{\Omega_e} \bar{\nabla} \psi_i \cdot \left(\sum_{j=1}^{M_v} \bar{\nabla} \psi_j f_j^{(e)} \right) d\Omega_e = \int_{\Omega_e} \psi_i \left(\sum_{j=1}^{M_v} \psi_j f_j^{(e)} \right) d\Omega_e \quad (15.6)$$

Mapping $\bar{x} = \bar{\Psi}(\bar{y})$

We now need to discuss the mapping from $\bar{x} \rightarrow \bar{y}$
 & $\bar{y} \rightarrow \bar{x}$.

Recall from (15.2) that $f_n^{(e)}(\bar{x}) = \sum_{j=1}^{M_N} \psi_j(\bar{x}) f_j^{(e)}$
 which means that we can write:

$$\bar{\nabla} f_n^{(e)}(\bar{x}) = \sum_{j=1}^{M_N} \bar{\nabla} \psi_j(\bar{x}) f_j^{(e)}$$

where $\bar{\nabla} f = \frac{\partial f}{\partial x} \hat{i} + \frac{\partial f}{\partial y} \hat{j}$ in 2D where, e.g.,

$$\frac{\partial f_n^{(e)}}{\partial x}(\bar{x}) = \sum_{j=1}^{M_N} \frac{\partial \psi_j}{\partial x} f_j^{(e)} \quad \& \quad \text{using the chain rule:}$$

$$\frac{\partial \psi}{\partial x} = \frac{\partial \psi}{\partial y} \frac{\partial y}{\partial x} + \frac{\partial \psi}{\partial n} \frac{\partial n}{\partial x} \quad \text{where } \psi_j(y, n) = h_j(y) \otimes h_n(n)$$

and

$$\frac{\partial \psi_j}{\partial y}(y, n) = \frac{\partial h_j(y)}{\partial y} \otimes h_n(n) \quad \& \quad \frac{\partial \psi_j}{\partial n}(y, n) = h_j(y) \otimes \frac{\partial h_n(n)}{\partial n}$$

where $h(y)$ & $h(n)$ are the basis functions defined in Ch. 3.

Metric Tensors To go from $\bar{x} \rightarrow \bar{x}$ & $\bar{x} \rightarrow \bar{x}$
 we need to define the mapping as follows, let:

$$d\bar{x} = \frac{\partial \bar{x}}{\partial y} dy + \frac{\partial \bar{x}}{\partial n} dn \quad \text{as follows:}$$

$$dx = \frac{\partial x}{\partial y} dy + \frac{\partial x}{\partial n} dn$$

$$dy = \frac{\partial y}{\partial x} dx + \frac{\partial y}{\partial n} dn$$

which we write in matrix form:

$$(15.7) \begin{pmatrix} dx \\ dy \end{pmatrix} = \begin{pmatrix} \frac{\partial x}{\partial \xi} & \frac{\partial x}{\partial \eta} \\ \frac{\partial y}{\partial \xi} & \frac{\partial y}{\partial \eta} \end{pmatrix} \begin{pmatrix} d\xi \\ d\eta \end{pmatrix}$$

$= J$ is the Jacobian of the map

from $\bar{\xi} \rightarrow \bar{x}$

The determinant $\det(J) \equiv |J| = x_{\xi}y_{\eta} - x_{\eta}y_{\xi}$.

The inverse map can be found as follows:

$$d\xi = \frac{\partial \xi}{\partial x} dx + \frac{\partial \xi}{\partial y} dy$$

$$d\eta = \frac{\partial \eta}{\partial x} dx + \frac{\partial \eta}{\partial y} dy$$

which in matrix form is:

$$(15.8) \begin{pmatrix} d\xi \\ d\eta \end{pmatrix} = \begin{pmatrix} \frac{\partial \xi}{\partial x} & \frac{\partial \xi}{\partial y} \\ \frac{\partial \eta}{\partial x} & \frac{\partial \eta}{\partial y} \end{pmatrix} \begin{pmatrix} dx \\ dy \end{pmatrix}$$

$= J^{-1}$ is the inverse Jacobian

Eq. (15.6) & (15.7) tell us that the map

from $\bar{x} \rightarrow \bar{r}$ & $\bar{r} \rightarrow \bar{x}$ are given as follows:

$$\begin{pmatrix} dx \\ dy \end{pmatrix} = J \begin{pmatrix} dr \\ dn \end{pmatrix} \quad \& \quad \begin{pmatrix} dr \\ dn \end{pmatrix} = J^{-1} \begin{pmatrix} dx \\ dy \end{pmatrix}$$

where $J = \begin{pmatrix} x_r & x_n \\ y_r & y_n \end{pmatrix}$ & $J^{-1} = \begin{pmatrix} \xi_x & \xi_y \\ n_x & n_y \end{pmatrix}$ (15.8)

where $J^{-1} = \frac{1}{|J|} \begin{pmatrix} y_n & -x_n \\ -y_r & x_r \end{pmatrix}$ (15.1)

Equating (15.8) & (15.1) shows that

$$\xi_x = \frac{1}{|J|} y_n, \quad \xi_y = -\frac{1}{|J|} x_n,$$

$$n_x = -\frac{1}{|J|} y_r, \quad n_y = \frac{1}{|J|} x_r$$

Next, we need to define \bar{x}_r & \bar{x}_n . Using the basis function expansion, yields:

from $\bar{x}_n^{(c)}(r,n) = \sum_{j=1}^{M_N} \psi_j(r,n) \bar{x}_j^{(c)}$ we write:

$$\frac{\partial \bar{x}_n}{\partial \bar{r}}(r,n) = \sum_{j=1}^{M_N} \frac{\partial \psi_j(r,n)}{\partial \bar{r}} \bar{x}_j^{(c)}$$

which allows us to build all of the metric terms.
The alg. for doing this is described in Alg. 12.1.