

(Ch 5)

Lecture 8: Mass & Differentiation

Let's assume that we wish to solve the PDE:

$$\frac{\partial u}{\partial t} + \frac{\partial f}{\partial x} = 0 \quad \text{with } f = gu, \quad u = \text{const} > 0 \text{ \& periodic BCs.}$$

The integral form of this problem is:

$$\int_{\Omega_c} \psi_i \left(\frac{\partial g u}{\partial t} + \frac{\partial f u}{\partial x} \right) d\Omega_c = 0$$

$$\text{when } g_u(x, t) = \sum_{j=0}^N \psi_j(x) g_j(t) \quad \& \quad u(x, t) = \sum_{j=0}^N \psi_j(x) f_j(t)$$

CG Method The CG formulation reads: find $g_u \in H^1$
s.t.

$$(8.1) \quad \int_{\Omega_c} \psi_i \frac{\partial g u}{\partial t} d\Omega_c + \int_{\Omega_c} \psi_i \frac{\partial f u}{\partial x} d\Omega_c = 0 \quad \forall \psi \in H^1$$

w/ $g_u, \psi \in C^0$

To simplify the discussion, let us derive the CG formulation for $N=1 \rightarrow$ Linear basis functions.

\therefore the approximations become:

$$(8.2) \quad g_u(x, t) = \sum_{j=0}^1 \psi_j(x) g_j(t) \quad \& \quad f_u(x, t) = \sum_{j=0}^1 \psi_j(x) f_j(t)$$

From (8.2) we can write:

$$(8.3) \quad \frac{\partial f_u}{\partial t} = \sum_{j=0}^1 \psi_j(x) \frac{df_j(t)}{dt} \quad \& \quad \frac{\partial f_u}{\partial x} = \sum_{j=0}^1 \frac{d\psi_j}{dx}(x) f_j(t)$$

which can be substituted into (8.1) to yield:

$$(8.4) \quad \int_{\Omega_e} \psi_i \sum_{j=0}^1 \psi_j(x) \frac{df_j(t)}{dt} dx + \int_{\Omega_e} \psi_i \sum_{j=0}^1 \frac{d\psi_j}{dx}(x) f_j(t) dx = 0 \quad \forall i=0,1$$

Because $\frac{df_j(t)}{dt}$ & $f_j(t)$ are independent of space, we can factor

them from the integrals to yield:

$$\int_{\Omega_e} \psi_i \psi_j dx \frac{df_j(t)}{dt} + \int_{\Omega_e} \psi_i \frac{d\psi_j}{dx} dx f_j(t) = 0 \quad \forall i,j=0,1$$

The matrix-vector form of this problem then becomes:

$$(8.5) \quad M_{ij}^{(e)} \frac{df_j^{(e)}}{dt} + D_{ij}^{(e)} f_j^{(e)} = 0$$

where the superscript (e) has been added to remind the reader that the approximation is currently only defined within the element Ω_e . We will discuss how to

construct the global solution later in this lecture.

In (8.5), the mass & differentiation matrices are defined as:

$$M_{ij}^{(e)} = \int_{\Omega_e} \psi_i(x) \psi_j(x) d\Omega_e$$

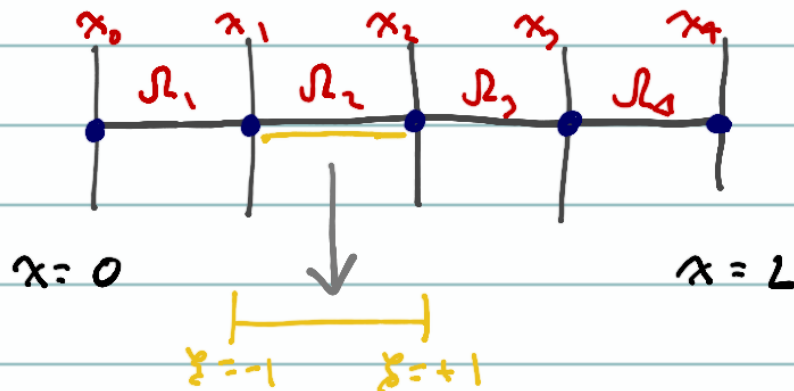
$$D_{ij}^{(e)} = \int_{\Omega_e} \psi_i(x) \frac{\partial \psi_j}{\partial x}(x) d\Omega_e \quad i, j = 0, 1$$

Basis Functions & Reference Element

We already learned that in 1D we can define the Lagrange basis functions as follows:

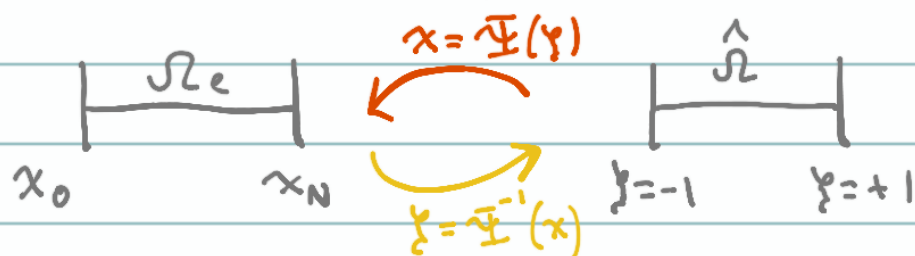
$$\psi_i(x) = \prod_{\substack{j=0 \\ j \neq i}}^N \left(\frac{x - x_j}{x_i - x_j} \right)$$

Next assume that we want to solve a PDE in the global domain:



We can choose to build $\psi_i(x)$ within each element Ω_e or we can build $\psi_i(\xi)$ in the reference element defined in the interval $\xi \in [-1, +1] \rightarrow$ ^{space for} Legendre, Lobatto, etc

The idea is to map each element Ω_c as follows:



Upon performing this mapping, we can build the basis functions only in $\hat{\Omega}$ as such:

$$(8.6) \quad \psi_i(\xi) = \prod_{\substack{j=0 \\ j \neq i}}^N \left(\frac{\xi - \xi_j}{\xi_i - \xi_j} \right); \quad \frac{d\psi_i(\xi)}{d\xi} = \sum_{\substack{n=0 \\ n \neq i}}^N \frac{1}{\xi_i - \xi_n} \prod_{\substack{j=0 \\ j \neq i \\ j \neq n}}^N \left(\frac{\xi - \xi_j}{\xi_i - \xi_j} \right)$$

HW 2 Derive ψ_i & ψ_i' for $N=1$ & $N=2$

Map $x = \Psi(\xi)$ The map from the physical to the reference space is found by first expanding the physical coordinates using the basis functions (isoparametric map). I.e.,

$$(8.7) \quad x_n(\xi) = \sum_{j=0}^N \psi_j(\xi) x_j \quad \& \quad \text{for } N=1 \text{ we get}$$

$$x_n(\xi) = \psi_0(\xi) x_0 + \psi_1(\xi) x_1$$

$$= \frac{1}{2}(1-\xi)x_0 + \frac{1}{2}(1+\xi)x_1$$

$$= \frac{x_0 + x_1}{2} + \frac{\xi}{2}(x_1 - x_0) \quad \text{Let } \Delta x = x_1 - x_0$$

$$= \frac{x_0 + (x_0 + \Delta x)}{2} + \frac{\xi}{2} \Delta x$$

$$(8.8.1) \quad x_N(\xi) = x_0 + \frac{\Delta x}{2} (\xi + 1)$$

$$(8.8.2) \quad \text{Use the inverse map} \rightarrow \xi = 2 \left(\frac{x(\xi) - x_0}{\Delta x} \right) - 1$$

$\Psi^{-1}: \xi \rightarrow x$

$\Psi: x \rightarrow \xi$

Jacobian From this map, we can compute the Jacobian of the mapping as follows:

$$\frac{dx_N(\xi)}{d\xi} \equiv \frac{dx}{d\xi} = \frac{\Delta x}{2} \quad \& \quad \frac{d\xi}{dx} = \frac{2}{\Delta x}$$

Integration in the Reference element

Now that we have the Jacobian of the transformation we can use it to perform integration inside the reference element as such:

$$\begin{aligned} M_{ij}^{(e)} &\equiv \int_{\Omega_e} \psi_i(x) \psi_j(x) d\Omega_e = \int_{x_0}^{x_1} \psi_i(x) \psi_j(x) dx \\ &= \int_{-1}^{+1} \psi_i(\xi) \psi_j(\xi) \frac{dx}{d\xi} d\xi \equiv \int_{-1}^{+1} \psi_i(\xi) \psi_j(\xi) \frac{\Delta x^{(e)}}{2} d\xi \end{aligned}$$

where $\Delta x^{(e)}$ is the size of the element Ω_e

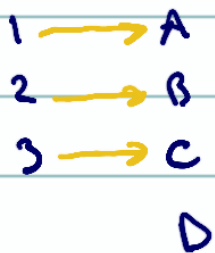
Similarly, we write:

$$\begin{aligned}
 D_{ij}^{(e)} &\equiv \int_{x_0}^{x_1} \psi_i(x) \frac{d\psi_j(x)}{dx} dx \\
 &= \int_{-1}^{+1} \psi_i(\xi) \left(\frac{d\psi_j(\xi)}{d\xi} \frac{d\xi}{dx} \right) \left(\frac{dx}{d\xi} d\xi \right) \\
 &= \int_{-1}^{+1} \psi_i(\xi) \frac{d\psi_j(\xi)}{d\xi} d\xi
 \end{aligned}$$

More on Map $x = \Psi(\xi)$

The map Ψ is bijective. I.e., it is both injective & surjective as follows:

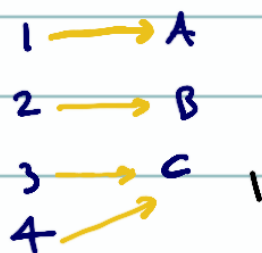
Injective



one-to-one
map

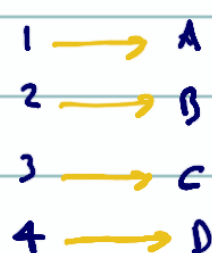
But output
may not have
an input

Surjective



every output
has an input

Bijective (affine)



Perfect one-to-one
map

Mass Matrix The mass matrix is given by:

$$(8.9) \quad M_{ij}^{(e)} = \frac{\Delta x^{(e)}}{2} \int_{-1}^{+1} \psi_i(\xi) \psi_j(\xi) d\xi \quad i, j = 0, \dots, N$$

& for $N=1$ we have $\psi_0 = \frac{1}{2}(1-\xi)$, $\psi_1 = \frac{1}{2}(1+\xi)$

which gives for (8.9)

$$(8.10) \quad M_{ij}^{(e)} = \frac{\Delta x^{(e)}}{2} \int_{-1}^{+1} \begin{pmatrix} \psi_0^2 & \psi_0 \psi_1 \\ \psi_1 \psi_0 & \psi_1^2 \end{pmatrix} d\xi$$

$$= \frac{\Delta x^{(e)}}{2} \int_{-1}^{+1} \frac{1}{4} \begin{pmatrix} (1-\xi)^2 & 1-\xi^2 \\ 1-\xi^2 & (1+\xi)^2 \end{pmatrix} d\xi$$

$$= \frac{\Delta x^{(e)}}{8} \int_{-1}^{+1} \begin{pmatrix} 1-2\xi+\xi^2 & 1-\xi^2 \\ 1-\xi^2 & 1+2\xi+\xi^2 \end{pmatrix} d\xi$$

$$= \frac{\Delta x^{(e)}}{8} \begin{pmatrix} \xi - \xi^2 + \frac{1}{3}\xi^3 & \xi - \frac{1}{3}\xi^3 \\ \xi - \frac{1}{3}\xi^3 & \xi + \xi^2 + \frac{1}{3}\xi^3 \end{pmatrix} \Big|_{-1}^{+1}$$

$$= \frac{\Delta x^{(e)}}{8} \begin{pmatrix} 2 + \frac{2}{3} & 2 - \frac{2}{3} \\ 2 - \frac{2}{3} & 2 + \frac{2}{3} \end{pmatrix} = \frac{\Delta x^{(e)}}{6} \begin{pmatrix} 2 & 1 \\ 1 & 2 \end{pmatrix}$$

Mass Matrix & Numerical Integration

Note that the product of basis functions in the mass matrix is a $2N$ polynomial. This means that if we use either N Legendre points or $N+1$ Lobatto points, that we can integrate them exactly.

Exact Integration

Let's use $Q=2$ Lobatto points: $\xi = [-1, 0, +1]$
 & $\omega = [\frac{1}{3}, \frac{4}{3}, \frac{1}{3}]$

& so we have:

$$M_{ij}^{(e)} = \frac{\Delta x^{(e)}}{2} \int_{-1}^{+1} \psi_i(\xi) \psi_j(\xi) d\xi = \frac{\Delta x^{(e)}}{2} \sum_{n=0}^Q \omega_n \psi_i(\xi_n) \psi_j(\xi_n)$$
$$= \frac{\Delta x^{(e)}}{8} \sum_{n=0}^Q \omega_n \begin{pmatrix} (1-\xi_n)^2 & 1-\xi_n^2 \\ 1-\xi_n^2 & (1+\xi_n)^2 \end{pmatrix}$$

e.g. $1-\xi_n^2$ term = $\omega_0 (1-\xi_0)^2 + \omega_1 (1-\xi_1)^2 + \omega_2 (1-\xi_2)^2$
 which yields = $\frac{1}{3} (1+1)^2 + \frac{4}{3} (1)^2 + \frac{1}{3} (0) = \frac{8}{3}$

$$M_{ij}^{(e)} = \frac{\Delta x^{(e)}}{8} \begin{pmatrix} 8/3 & 4/3 \\ 4/3 & 8/3 \end{pmatrix}$$

Inexact Integration

Let's use $N=Q=1$ which, we know, will not yield exact integration using Lobatto points.

We have: $\xi \in [-1, +1]$ $\omega \in [+1, +1]$

$$M_{ij}^{(c)} = \frac{\Delta x^{(c)}}{2} \sum_{n=0}^1 \omega_n \psi_i(\xi_n) \psi_j(\xi_n)$$

$$= \frac{\Delta x^{(c)}}{2} \sum_{n=0}^1 \omega_n \begin{pmatrix} (1-\xi_n)^2 & 1-\xi_n^2 \\ 1-\xi_n^2 & (1+\xi_n)^2 \end{pmatrix}$$

$$= \frac{\Delta x^{(c)}}{8} \begin{pmatrix} (1)(4) + (1)(0) & (1)(0) + (1)(0) \\ (1)(0) + (1)(0) & (1)(0) + (1)(4) \end{pmatrix}$$

$$= \frac{\Delta x^{(c)}}{8} \begin{pmatrix} 4 & 0 \\ 0 & 4 \end{pmatrix} = \frac{\Delta x^{(c)}}{2} \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$$

HW Use $Q = N=1$ c/ Legendre Points

Differentiation Matrix

we have:

$$D_{ij}^{(c)} = \int_{-1}^{+1} \psi_i(\xi) \frac{d\psi_j}{d\xi}(\xi) d\xi$$

for $N=1$ we have:

$$\psi_i = \frac{1}{2}(1 + \xi_i \xi) \quad \xi_i = -1, +1 \quad i=0,1$$

$$\frac{d\psi_i}{d\xi} = \frac{1}{2} \xi_i, \quad c(\xi) \quad \text{quadrature:}$$

$$D_{ij}^{(c)} = \int_{-1}^{+1} \begin{pmatrix} \psi_0 \frac{d\psi_0}{d\xi} & \psi_0 \frac{d\psi_1}{d\xi} \\ \psi_1 \frac{d\psi_0}{d\xi} & \psi_1 \frac{d\psi_1}{d\xi} \end{pmatrix} d\xi = \int_{-1}^{+1} \begin{pmatrix} -\frac{1}{4}(1-\xi) & \frac{1}{4}(1-\xi) \\ -\frac{1}{4}(1+\xi) & \frac{1}{4}(1+\xi) \end{pmatrix} d\xi$$

$$D_{ij}^{(e)} = \frac{1}{4} \begin{pmatrix} -\xi + \frac{1}{2}\xi^2 & \xi - \frac{1}{2}\xi^2 \\ -\xi - \frac{1}{2}\xi^2 & \xi + \frac{1}{2}\xi^2 \end{pmatrix} \Big|_{-1}^{+1} = \frac{1}{4} \begin{pmatrix} -2 & 2 \\ -2 & 2 \end{pmatrix}$$

$$D_{ij}^{(e)} = \frac{1}{2} \begin{pmatrix} -1 & 1 \\ -1 & 1 \end{pmatrix}$$

Question Why does the row sum of $D_{ij}^{(e)}$ yield: $\sum_{j=0}^1 D_{ij}^{(e)} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

Taylor Series for a derivative, e.g.,

$$\frac{f_{i+1} - f_{i-1}}{2\Delta x} = \frac{1}{2\Delta x} \begin{pmatrix} -1 & 0 & 1 \end{pmatrix} \begin{pmatrix} f_{i-1} \\ f_i \\ f_{i+1} \end{pmatrix}$$

Differentiation Matrix & Numerical Integration

Note that the polynomial in D is $O(N + N - 1) = O(2N - 1)$

\therefore we can use Lobatto w/ $Q = N = 2$ & get exact integration. Let's try it.

$$\omega_n \in [-1, +1], \xi_n = [-1, +1]$$

$$D_{ij}^{(e)} = \frac{1}{4} \sum_{n=0}^1 \omega_n \begin{pmatrix} -(1 - \xi_n) & 1 - \xi_n \\ -(1 + \xi_n) & 1 + \xi_n \end{pmatrix} = \frac{1}{4} \begin{pmatrix} (1)(-2) + (1)(0) & (1)(0) + (1)(2) \\ (1)(0) + (1)(-2) & (1)(0) + (1)(2) \end{pmatrix}$$

$$= \frac{1}{4} \begin{pmatrix} -2 & 2 \\ -2 & 2 \end{pmatrix} = \frac{1}{2} \begin{pmatrix} -1 & 1 \\ -1 & 1 \end{pmatrix} \rightarrow \text{Same as in analytic integration}$$

Ex Try using $Q = 2$ w/ $\xi \in [-1, 0, +1]$ & $\omega \in [\frac{1}{3}, \frac{2}{3}, \frac{1}{3}]$