

OUTLINE

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Executive Summary

- In this project, I've built a ML model to determine weather the SpaceX Falocn-9 rocket's first stage will land successfully or not.
- The ML model used for this project is Classification. And to determine the accuracy of the model I used Confusion Matrix method.
- Several algorithm for Classification used also, such: Logistic Regression, KNN, SVM, Decision Trees. And compare between them to determine the best option and that option was (either Logistic Regression and SVM).

Introduction

• SpaceX has launched Falcon-9 rocket on their website, the rocket comes with a great price (62million\$), comparing to other manufacturer which their cost nearby(165million\$).

• The reason for this is that SpaceX can use the first stage of the rocket again.

Data Collection Methodology

- The data used for this project from SpaceX official website.
- The methodology to get this data is API.
- To prepare the data well, I used some functions to get important features in consist way, like: (Booster Version, Payload Mass, Cores, and Launch Site).
- Also, since the ML is classification, I had to convert all object data into a numerical data to prepare it for analysis, I create a new feature columns called Class that represent weather the launch landed or not by (0 & 1).

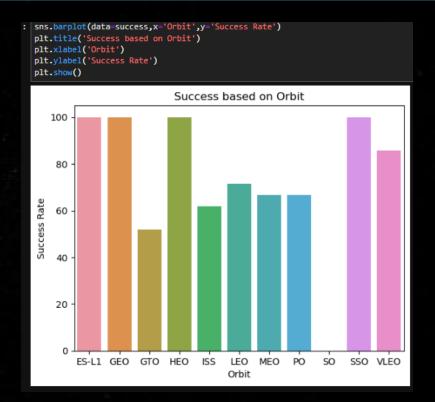
Exploratory Data Analysis (EDA) Methodology

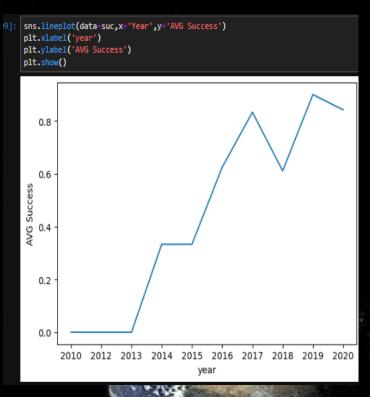
- For EDA, visual plots were very helpful to discover more about the data and the relationships between features.
- I used various plots, such: Line plot, Cat plot, Bar charts, and more..
- Also, a new feature has been created (
 AVG success rate), Average Success Rate,
 to figure out the relationship between
 several features and landing average
 success rate.
- I also used SQL queries for EDA.

Predictive Model Methodology

- The predictive model was Classification.
 I've used several algorithm such: KNN,
 SVM, Decision Trees, and Logistic
 Regression.
- To compare between them, I've created a function that draw a confusion matrix to ease the process of analysis.
- Also, Cross-Validation was used using Grid Search to better overcome overfitting and underfitting.

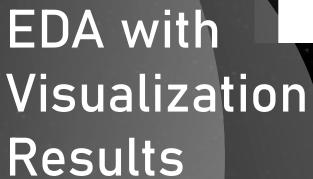
EDA with Visualization Results

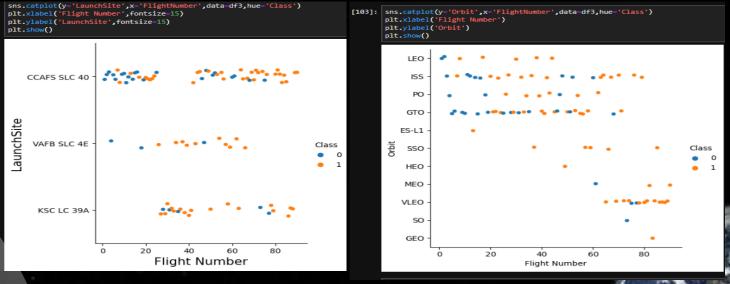




As we can see, Orbit has clear affect on the Success rate of the landing process And GTO is the least one.

From 2013 AVG success rate increased significantly.

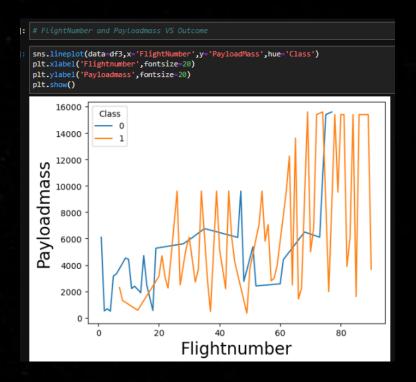




We can see here that GTO orbit has the most flights and we can say the success and failure were almost equal. Flights to SSO orbit always succeed landing.

CCAFS SLC 40 has the most flights and after 50 flights the success rate increased.

EDA with Visualization Results

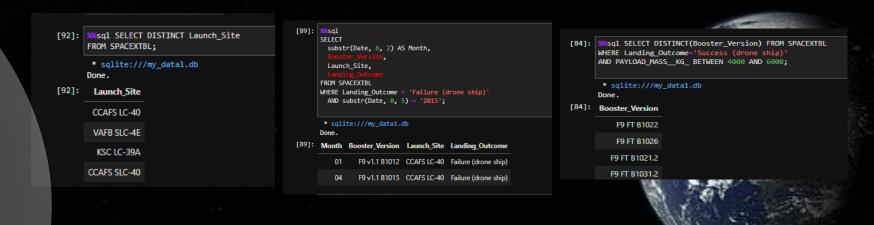


The effect of payload to success rate was clear if the payload above 12 Ton and flights above 75.





SQL Results for EDA



We notice here that CCAFSLC-40 have the biggest customer such, SpaceX and NASA.

And, there are several launch sites as shown above.

SQL Results for EDA



%%sql SELECT Landing_Outcome,COUNT(*) FROM SPACEXTBL GROUp BY Landing_Outcome; * sqlite:///my_data1.db Landing_Outcome COUNT(*) Controlled (ocean) Failure Failure (drone ship) Failure (parachute) 21 No attempt No attempt Precluded (drone ship) 38 Success 14 Success (drone ship) Success (ground pad) Uncontrolled (ocean)

Also, some landing outcomes for several locations

First success ground pad location was in 2015

Folium Results



We notice from this map, that launch sites are explicitly located at eastern and western coasts of US.

Logistic Regression

The model performs very well and give overall accuracy 94%, also since the problem is False Positive the confusion matrix did well as well.

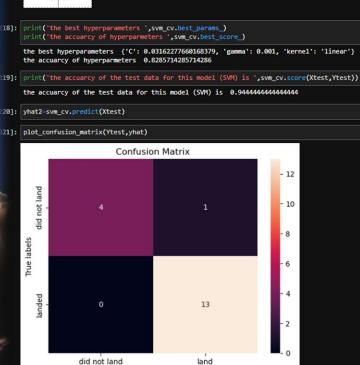


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did not land



The model performs very well and give overall accuracy 94%, also since the problem is False Positive the confusion matrix did well as well.



Decision Tree

The model performs good and give overall accuracy 83%, also since the problem is False Positive the confusion matrix did well as well.

Predictive Model Results ▶ DecisionTreeClassifier

estimator: DecisionTreeClassifier

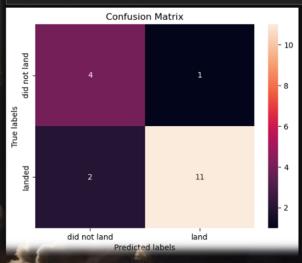
print('the best parameters here are ',tree_cv.best_params_ print('the accuracy here ',tree_cv.best_score_)

the best parameters here are {'criterion': 'entropy', 'max_depth': 18, 'max_features': 'sqrt', 'min_samples_leaf': 2, 'min_samples_split': 10, 'splitter': 'best' the accuracy here 0.8857142857142858

]: print('the accuracy of test data for this model (Tree) is ',tree_cv.score(Xtest,Ytest))

3]: yhat3=tree_cv.predict(Xtest)

]: plot_confusion_matrix(Ytest,yhat3)



The model performs good and give overall





