

CENG403 - Spring 2025: Homework set Write Code Blocks Practice

Your Name

TASK 1: DEFORMABLE CNN - WRITE CODE BLOCKS

.1: Floor Operation

Problem 1.1: Floor Operation

Write code to get the floor of a float value q_y and store it in $y0$:

.2: Ceiling Operation

Problem 1.2: Ceiling Operation

Write code to get the ceiling of a float value q_x and store it in $x1$:

.3: Kernel Index Calculation

Problem 1.3: Kernel Index Calculation

Write code to calculate linear kernel index from 2D position (kh, kw) with kernel width K_w :

.4: Y Offset Extraction

Problem 1.4: Y Offset Extraction

Write code to extract Y offset from delta tensor for batch n , kernel index k , output position (h_{out}, w_{out}) :

.5: X Offset Extraction

Problem 1.5: X Offset Extraction

Write code to extract X offset from delta tensor for batch n, kernel index k, output position (h_out, w_out):

.6: Base Position Calculation

Problem 1.6: Base Position Calculation

Write code to calculate base sampling position h_start from output position h_out and stride:

.7: Final Sampling Position

Problem 1.7: Final Sampling Position

Write code to calculate final sampling position sample_y from h_start, kh, dilation, and delta_y:

.8: Bounds Check Condition

Problem 1.8: Bounds Check Condition

Write code to check if coordinates (y, x) are within image bounds (H, W):

.9: Safe Pixel Access

Problem 1.9: Safe Pixel Access

Write code to get pixel value at (y, x) from image img, returning 0.0 if out of bounds:

.10: Fractional Part Calculation

Problem 1.10: Fractional Part Calculation

Write code to calculate fractional part dx from q_x and its floor $x0$:

.11: Linear Interpolation

Problem 1.11: Linear Interpolation

Write code to linearly interpolate between v_{left} and v_{right} using weight dx :

.12: Bilinear Weight Calculation

Problem 1.12: Bilinear Weight Calculation

Write code to calculate bilinear interpolation weight for points p and q :

.13: Value Accumulation

Problem 1.13: Value Accumulation

Write code to accumulate weighted interpolated value to current_value using weight , mask , and interpolated :

.14: Corner Position Calculation

Problem 1.14: Corner Position Calculation

Write code to calculate all four corner positions (y_0, x_0) , (y_0, x_1) , (y_1, x_0) , (y_1, x_1) from q_y and q_x :

.15: Mask Application

Problem 1.15: Mask Application

Write code to apply modulation mask m_k to an interpolated value:

TASK 2: CNN PYTORCH - WRITE CODE BLOCKS

.1: Conv Layer Definition

Problem 2.1: Conv Layer Definition

Write code to define a Conv2d layer with 32 input channels, 64 output channels, kernel size 3, padding 1:

.2: BatchNorm Layer Definition

Problem 2.2: BatchNorm Layer Definition

Write code to define a BatchNorm2d layer for 128 channels:

.3: MaxPool Layer Definition

Problem 2.3: MaxPool Layer Definition

Write code to define a MaxPool2d layer that halves spatial dimensions:

.4: Linear Layer Definition

Problem 2.4: Linear Layer Definition

Write code to define a Linear layer with 4096 inputs and 512 outputs:

.5: Dropout Layer Definition

Problem 2.5: Dropout Layer Definition

Write code to define a Dropout layer with probability 0.5:

.6: ReLU Activation

Problem 2.6: ReLU Activation

Write code to apply ReLU activation to variable x:

.7: Tensor Flattening

Problem 2.7: Tensor Flattening

Write code to flatten tensor x while preserving batch dimension:

.8: Device Transfer

Problem 2.8: Device Transfer

Write code to move tensor images to device:

.9: Optimizer Zero Grad

Problem 2.9: Optimizer Zero Grad

Write code to clear gradients from optimizer:

.10: Forward Pass

Problem 2.10: Forward Pass

Write code to perform forward pass through model with input images:

.11: Loss Calculation

Problem 2.11: Loss Calculation

Write code to calculate loss using criterion with outputs and labels:

.12: Backward Pass

Problem 2.12: Backward Pass

Write code to perform backward pass on loss:

.13: Optimizer Step

Problem 2.13: Optimizer Step

Write code to update model parameters using optimizer:

.14: Top-1 Prediction

Problem 2.14: Top-1 Prediction

Write code to get top-1 predictions from outputs:

.15: Accuracy Calculation

Problem 2.15: Accuracy Calculation

Write code to calculate accuracy from predicted and labels tensors:

.16: Model Training Mode

Problem 2.16: Model Training Mode

Write code to set model to training mode:

.17: Model Evaluation Mode

Problem 2.17: Model Evaluation Mode

Write code to set model to evaluation mode:

.18: No Gradient Context

Problem 2.18: No Gradient Context

Write code to create context where gradients are disabled:

.19: Dataset Size Calculation

Problem 2.19: Dataset Size Calculation

Write code to calculate training size as 80% of total dataset size:

.20: Random Split

Problem 2.20: Random Split

Write code to split dataset into `train_set` and `val_set` with sizes `train_size` and `val_size`:

TASK 3: RNN - WRITE CODE BLOCKS

.1: Character Set Creation

Problem 3.1: Character Set Creation

Write code to create sorted list of unique characters from text:

.2: Character to Index Mapping

Problem 3.2: Character to Index Mapping

Write code to create dictionary mapping each character to its index:

.3: Index to Character Mapping

Problem 3.3: Index to Character Mapping

Write code to create dictionary mapping each index to its character:

.4: Input Sequence Creation

Problem 3.4: Input Sequence Creation

Write code to create input sequence (all characters except last) from text:

.5: Target Sequence Creation

Problem 3.5: Target Sequence Creation

Write code to create target sequence (all characters except first) from text:

.6: One-Hot Vector Creation

Problem 3.6: One-Hot Vector Creation

Write code to create one-hot vector of given size with 1 at given index:

.7: Input-to-Hidden Weight Initialization

Problem 3.7: Input-to-Hidden Weight Initialization

Write code to initialize W_{xh} weight matrix for RNN with hidden size H and vocab size V :

.8: Hidden-to-Hidden Weight Initialization

Problem 3.8: Hidden-to-Hidden Weight Initialization

Write code to initialize W_{hh} weight matrix for RNN with hidden size H :

.9: Hidden Bias Initialization

Problem 3.9: Hidden Bias Initialization

Write code to initialize bias vector b_{xh} for hidden layer with size H :

.10: Output Weight Initialization

Problem 3.10: Output Weight Initialization

Write code to initialize W_{hy} weight matrix from hidden to output with vocab size V and hidden size H :

.11: Hidden State Initialization

Problem 3.11: Hidden State Initialization

Write code to initialize hidden state vector with zeros of size H :

.12: Input Contribution Calculation

Problem 3.12: Input Contribution Calculation

Write code to calculate input contribution to hidden state using W_{xh} and x_t :

.13: Hidden Recurrence Calculation

Problem 3.13: Hidden Recurrence Calculation

Write code to calculate recurrent contribution to hidden state using W_{hh} and previous hidden state h :

.14: Hidden State Update

Problem 3.14: Hidden State Update

Write code to update hidden state using \tanh activation with all contributions and biases:

.15: Output Logits Calculation

Problem 3.15: Output Logits Calculation

Write code to calculate output logits s_t from hidden state h using W_{hy} and b_y :

.16: Character Index Lookup

Problem 3.16: Character Index Lookup

Write code to get index of character 'e' from `char2idx` dictionary:

.17: Input List Creation

Problem 3.17: Input List Creation

Write code to convert input sequence to list of one-hot vectors:

.18: Target Tensor Creation

Problem 3.18: Target Tensor Creation

Write code to convert target sequence to tensor of character indices:

.19: Logits Stacking

Problem 3.19: Logits Stacking

Write code to stack list of logits tensors into single tensor:

.20: Log Softmax Calculation

Problem 3.20: Log Softmax Calculation

Write code to calculate log softmax of logits along vocabulary dimension:

.21: NLL Loss Calculation

Problem 3.21: NLL Loss Calculation

Write code to calculate negative log likelihood loss from log_probs and targets:

.22: Gradient Calculation

Problem 3.22: Gradient Calculation

Write code to calculate gradient of loss with respect to W_{xh} :

DATA PREPROCESSING - WRITE CODE BLOCKS

.1: CIFAR-100 Mean Values

Problem 4.1: CIFAR-100 Mean Values

Write code to define CIFAR-100 normalization mean values:

.2: CIFAR-100 Std Values

Problem 4.2: CIFAR-100 Std Values

Write code to define CIFAR-100 normalization standard deviation values:

.3: ToTensor Transform

Problem 4.3: ToTensor Transform

Write code to create ToTensor transform:

.4: Normalization Transform

Problem 4.4: Normalization Transform

Write code to create Normalize transform with CIFAR-100 mean and std:

.5: Random Crop Transform

Problem 4.5: Random Crop Transform

Write code to create RandomCrop transform with size 32 and padding 4:

.6: Random Flip Transform

Problem 4.6: Random Flip Transform

Write code to create RandomHorizontalFlip transform:

.7: Transform Composition

Problem 4.7: Transform Composition

Write code to compose multiple transforms into single transform:

.8: CIFAR-100 Dataset Loading

Problem 4.8: CIFAR-100 Dataset Loading

Write code to load CIFAR-100 training dataset with transform:

.9: DataLoader Creation

Problem 4.9: DataLoader Creation

Write code to create DataLoader with batch size 128 and shuffle=True:

OPTIMIZATION AND TRAINING - WRITE CODE BLOCKS

.1: CrossEntropy Loss Definition

Problem 5.1: CrossEntropy Loss Definition

Write code to define CrossEntropy loss function:

.2: SGD Optimizer Definition

Problem 5.2: SGD Optimizer Definition

Write code to define SGD optimizer with learning rate 0.01 and momentum 0.9:

.3: Adam Optimizer Definition

Problem 5.3: Adam Optimizer Definition

Write code to define Adam optimizer with learning rate 0.001:

.4: Model Parameter Count

Problem 5.4: Model Parameter Count

Write code to count total number of parameters in model:

.5: Learning Rate Update

Problem 5.5: Learning Rate Update

Write code to multiply learning rate by 0.1 for all parameter groups:

.6: Model State Save

Problem 5.6: Model State Save

Write code to save model state dictionary to file 'model.pth':

.7: Model State Load

Problem 5.7: Model State Load

Write code to load model state dictionary from file 'model.pth':

.8: Gradient Clipping

Problem 5.8: Gradient Clipping

Write code to clip gradients to maximum norm of 1.0:

3cm

.9: Top-5 Accuracy

Problem 5.9: Top-5 Accuracy

Write code to calculate top-5 accuracy from outputs and labels:

.10: Loss Item Extraction

Problem 5.10: Loss Item Extraction

Write code to extract scalar value from loss tensor:

DEBUGGING AND UTILITIES - WRITE CODE BLOCKS

.1: Tensor Shape Check

Problem 6.1: Tensor Shape Check

Write code to print shape of tensor x:

.2: Tensor Device Check

Problem 6.2: Tensor Device Check

Write code to check which device tensor x is on:

.3: Model Device Transfer

Problem 6.3: Model Device Transfer

Write code to move entire model to GPU:

.4: Gradient Existence Check

Problem 6.4: Gradient Existence Check

Write code to check if parameter has gradients:

.5: Memory Usage Check

Problem 6.5: Memory Usage Check

Write code to check CUDA memory usage:

.6: Random Seed Setting

Problem 6.6: Random Seed Setting

Write code to set PyTorch random seed to 42:

.7: Numpy Seed Setting

Problem 6.7: Numpy Seed Setting

Write code to set numpy random seed to 42:

.8: Model Summary

Problem 6.8: Model Summary

Write code to print model architecture:

.9: Batch Dimension Check

Problem 6.9: Batch Dimension Check

Write code to get batch size from tensor x:

.10: Tensor Type Conversion

Problem 6.10: Tensor Type Conversion

Write code to convert tensor x to float type:

ANSWER BANK

Task 1 - Deformable CNN Answers:

Problem Task 1 - Deformable CNN Answers:

```
1.1: y0 = int(np.floor(q_y))
1.2: x1 = int(np.ceil(q_x))
1.3: k = kh * K_w + kw
1.4: delta_y = delta[n, 2 * k, h_out, w_out]
1.5: delta_x = delta[n, 2 * k + 1, h_out, w_out]
1.6: h_start = h_out * stride
1.7: sample_y = h_start + kh * dilation + delta_y
1.8: if 0 <= y < H and 0 <= x < W:
1.9: value = img[y, x] if (0 <= y < H and 0 <= x < W) else 0.0
1.10: dx = q_x - x0
1.11: result = v_left * (1 - dx) + v_right * dx
1.12: weight = (1 - abs(p_x - q_x)) * (1 - abs(p_y - q_y))
1.13: current_value += weight * mask * interpolated
1.14: y0, x0 = int(np.floor(q_y)), int(np.floor(q_x))
    y1, x1 = y0 + 1, x0 + 1
1.15: modulated_value = m_k * interpolated_value
```

Task 2 - CNN PyTorch Answers:

Problem Task 2 - CNN PyTorch Answers:

```
2.1: self.conv = nn.Conv2d(32, 64, kernel_size=3, padding=1)
2.2: self.bn = nn.BatchNorm2d(128)
2.3: self.pool = nn.MaxPool2d(2, 2)
2.4: self.fc = nn.Linear(4096, 512)
2.5: self.dropout = nn.Dropout(0.5)
2.6: x = F.relu(x)
2.7: x = x.view(x.size(0), -1)
2.8: images = images.to(device)
2.9: optimizer.zero_grad()
2.10: outputs = model(images)
2.11: loss = criterion(outputs, labels)
```

```

2.12: loss.backward()

2.13: optimizer.step()

2.14: _, predicted = torch.max(outputs, 1)

2.15: accuracy = (predicted == labels).sum().item() / labels.size(0) * 100

2.16: model.train()

2.17: model.eval()

2.18: with torch.no_grad():

2.19: train_size = int(0.8 * len(dataset))

2.20: train_set, val_set = random_split(dataset, [train_size, val_size])

```

Task 3 - RNN Answers:

Problem Task 3 - RNN Answers:

```

3.1: chars = sorted(list(set(text)))

3.2: char2idx = {ch: i for i, ch in enumerate(chars)}

3.3: idx2char = {i: ch for i, ch in enumerate(chars)}

3.4: input_seq = text[:-1]

3.5: target_seq = text[1:]

3.6: vec = torch.zeros(size)
vec[idx] = 1.0

3.7: W_xh = torch.randn(H, V, requires_grad=True) * 0.1

3.8: W_hh = torch.randn(H, H, requires_grad=True) * 0.1

3.9: b_xh = torch.zeros(H, requires_grad=True)

3.10: W_hy = torch.randn(V, H, requires_grad=True) * 0.1

3.11: h = torch.zeros(H)

3.12: input_contrib = W_xh @ x_t

3.13: hidden_contrib = W_hh @ h

3.14: h = torch.tanh(W_xh @ x_t + b_xh + W_hh @ h + b_hh)

3.15: s_t = W_hy @ h + b_y

3.16: idx = char2idx['e']

3.17: inputs = [one_hot(char2idx[ch], V) for ch in input_seq]

3.18: targets = torch.tensor([char2idx[ch] for ch in target_seq], dtype=torch.long)

3.19: logits = torch.stack(logits_list)

3.20: log_probs = F.log_softmax(logits, dim=1)

```

```
3.21: loss = F.nll_loss(log_probs, targets)
```

```
3.22: grad.W_xh = torch.autograd.grad(loss, W_xh, retain_graph=True)[0]
```

Additional Sections Answers:

Problem Additional Sections Answers:

```
4.1: mean = [0.5071, 0.4867, 0.4408]
```

```
4.2: std = [0.2675, 0.2565, 0.2761]
```

```
4.3: transform = transforms.ToTensor()
```

```
4.4: normalize = transforms.Normalize(mean=[0.5071, 0.4867, 0.4408], std=[0.2675, 0.2565, 0.2761])
```

```
4.5: crop = transforms.RandomCrop(32, padding=4)
```

```
4.6: flip = transforms.RandomHorizontalFlip()
```

```
4.7: transform = transforms.Compose([transform1, transform2, ...])
```

```
4.8: dataset = CIFAR100(root='./data', train=True, transform=transform)
```

```
4.9: loader = DataLoader(dataset, batch_size=128, shuffle=True)
```

```
5.1: criterion = nn.CrossEntropyLoss()
```

```
5.2: optimizer = optim.SGD(model.parameters(), lr=0.01, momentum=0.9)
```

```
5.3: optimizer = optim.Adam(model.parameters(), lr=0.001)
```

```
5.4: total_params = sum(p.numel() for p in model.parameters())
```

```
5.5: for param_group in optimizer.param_groups: param_group['lr'] *= 0.1
```

```
5.6: torch.save(model.state_dict(), 'model.pth')
```

```
5.7: model.load_state_dict(torch.load('model.pth'))
```

```
5.8: torch.nn.utils.clip_grad_norm_(model.parameters(), 1.0)
```

```
5.9: _, top5_pred = outputs.topk(5, dim=1)
top5_acc = top5_pred.eq(labels.view(-1, 1).expand_as(top5_pred)).sum().item()
```

```
5.10: loss_value = loss.item()
```

```
6.1: print(x.shape)
```

```
6.2: print(x.device)
```

```
6.3: model = model.to('cuda')
```

```
6.4: if param.grad is not None:
```

```
6.5: print(torch.cuda.memory_allocated())
```

```
6.6: torch.manual_seed(42)
```

```
6.7: np.random.seed(42)
```

```
6.8: print(model)
```

```
6.9: batch_size = x.size(0)
```

```
6.10: x = x.float()
```

Additional Answers

Problem Additional Answers

C1: 32 x 32, C2: 8 x 8, C3: 4096, C4: 73856, C5: 256

S1: numpy, torch.nn, F, transforms

S2: nn.Module, super

S3: def forward(self, x)

S4: nn.CrossEntropyLoss()

S5: optim.SGD(model.parameters(), lr=0.01, momentum=0.9)

M1: x = self.dropout(x) if self.training else x

M2: for param_group in optimizer.param_groups: param_group['lr'] *= 0.1

M3: torch.save(model.state_dict(), 'model.pth')

M4: outputs = model(images.to(device))

M5: correct = (predicted == labels).sum().item()