## PARAMETRIC NOISE / HETER OGENETTY

Ex 
$$\frac{dy}{dt} = Ay$$
  $\frac{t}{t}$   $\frac{dy}{dt} = Ay$   $\frac{t}{t}$   $\frac{dy}{dt} = Xe^{t}At$ 

SUPPOSE 
$$Y = g(X)$$

RAMON
VARIABLE

SOME
FUNCTION

 $X \sim P_X(x)$ 

WHAT IS  $P_Y(y)$ ?

 $X \sim VNIF(0,1)$ 
 $Y = C \times X$ 
 $Y = C$ 

GIVEN 
$$F_{x}(x)$$
 then

$$F_{y}(y) = F_{x}(\frac{y-b}{a})$$

$$P_{y}(y) = \frac{1}{a} P_{x}(\frac{y-b}{a})$$
CHECK

$$y = ax+b$$

$$x > y-b$$

$$x > y-b$$

$$= 1 - F_{x}(\frac{y-b}{a})$$

$$P_{y}(y) = -\frac{1}{a} P_{x}(\frac{y-b}{a})$$

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a.40

$$EX \quad Y = X^{2} \quad \Rightarrow \quad g(x) = x^{2}$$

$$Iy = \left\{ \begin{bmatrix} -\sqrt{y} & \sqrt{y} \\ -\sqrt{y} \end{bmatrix} \right\} = y \neq 0$$

$$Y = X^{2} \quad \alpha$$

$$Y = X^{3} \quad \alpha$$

$$g(x) = x^{2} \quad \alpha$$

$$Y = X^{3} \quad \alpha$$

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$$Y$$

$$F_{Y}(y) = \left(F_{x}(J_{y}) - F_{x}(J_{y})\right) \quad y \ge 0$$

$$y < 0$$

$$PY(y) = \left(\frac{1}{2Jy}P_{x}(Jy) + \frac{1}{2Jy}P_{x}(Jy)\right)$$

$$y \ge 0$$

$$y \le 0$$

LET 
$$X \sim p_X(x)$$
 AND  $Y = g(x)$ 

THEN

$$PY(g) = \sum_{K} P \times (x_{K}(y)) \cdot \left| \frac{dx_{K}}{dg} \right|$$

WHERE EXX3 IS THE PRE-IMAGE

$$PY(y) = \sum_{k} Px(g_{k}^{-1}(y)) \left( \frac{|Qy|}{Qx} \right)$$

$$PY(y) = Px(g'(y)) \left(\frac{dg}{dx}\right)^{-1}$$

$$\frac{1}{k}$$

$$T = \frac{1}{K} \qquad \text{MEAN} \\ TIME \qquad \left( \text{TIME} \right) \\ Q(K) = \frac{1}{K} \qquad \frac{QQ}{QK} = \frac{1}{K^2} \\ Q'(t) = \frac{1}{L}$$

$$PT(t) = PK \left( g^{-1}(t) \right) \left( \frac{\log t}{dk} \right)^{-1}$$

$$= \left( \frac{1}{k^2} \right)^{-1} \left( \frac{1}{k^2} \right)^{$$

