



Automatic Lens Smear Detection

Homework 1, 2019.4.21
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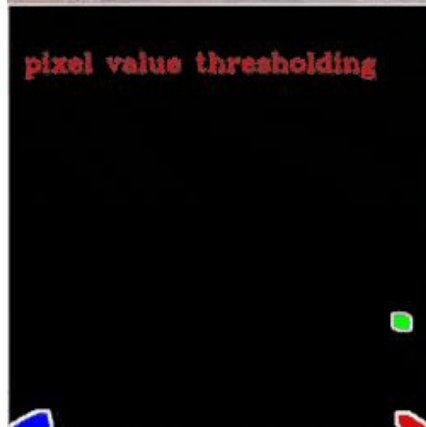
Video Demo of Smear Detection Result

Original video



Variation image:
White pixel means
less variation

Thresholding on
variation image, and
find connected
components.



Detected smears

(Check out the video [here](#))

What is a lens smear?

Dirt, dust or smear on the lens that stains the picture.



We want to detect and remove the smears before using these images for building road map.

Assumption:

A smear is a circular-shaped region with black/white color that is different from its surroundings.

Workflow of algorithms:

Step 1: Apply **Gaussian blurring** to smooth the source image.

Step 2: Transform image color from RGB to **gray**.

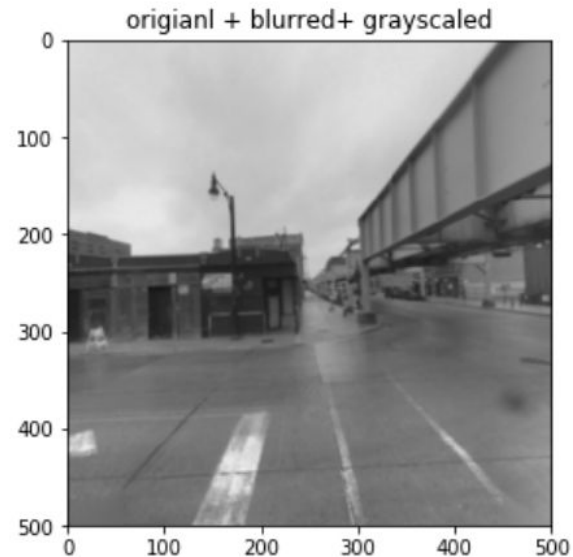
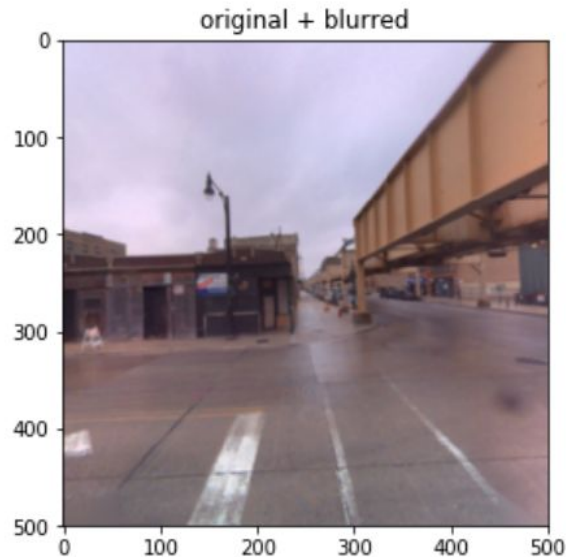
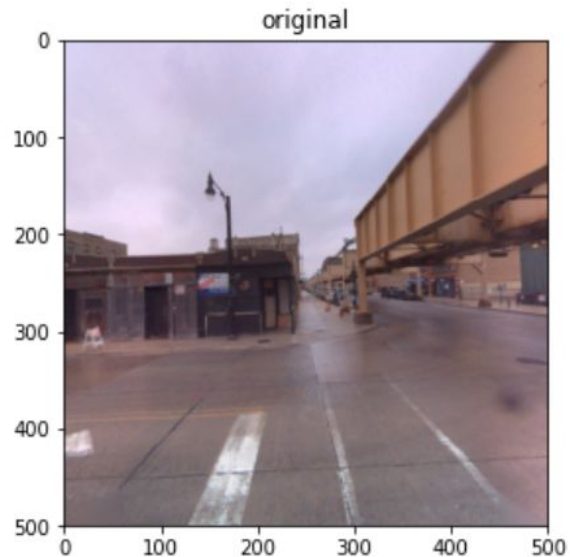
Step 3: **Binarize image** by image thresholding algorithm.

Step 4: Do **edge detection** to find object contours.

Step 5: Choose **connected components** with proper shape and size, which are the smears.

Method 1 - Approach

Step 1-2: Gaussian blurring + Transform RGB to gray



Method 1 - Approach

Step 3: **Binarize image** by image thresholding algorithm.

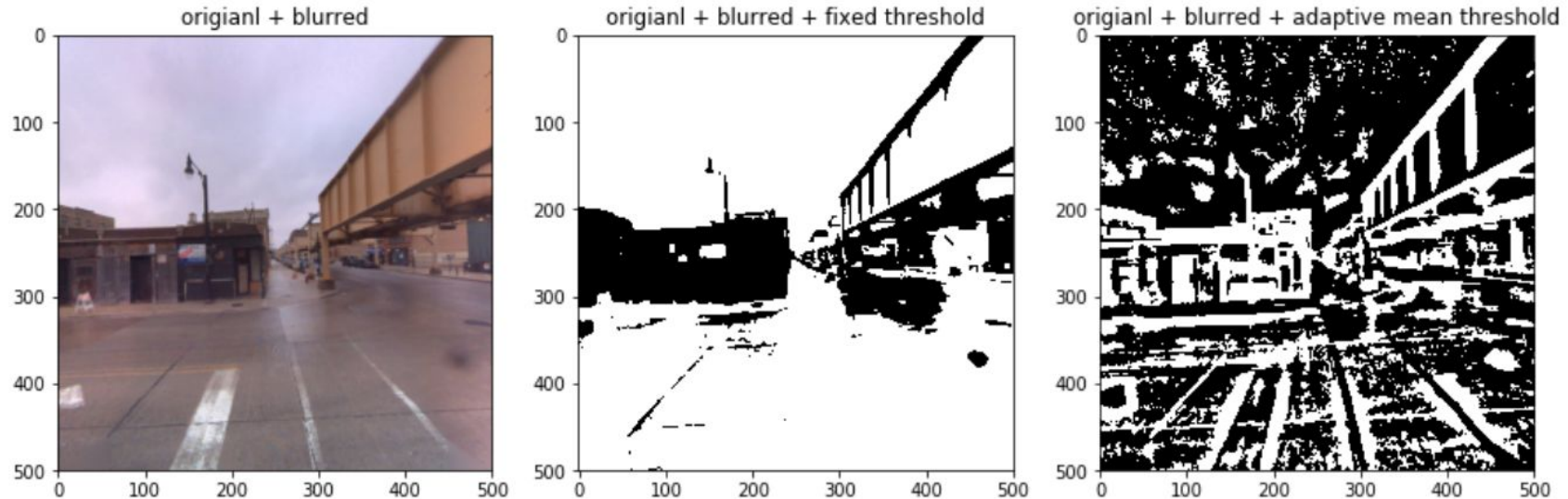


Figure: Comparison of **fixed threshold** and **adaptive mean threshold** algorithm.

Method 1 - Approach

Step 3: **Binarize image** by image thresholding algorithm.

Fixed threshold is better if we know the smear's pixel intensity.

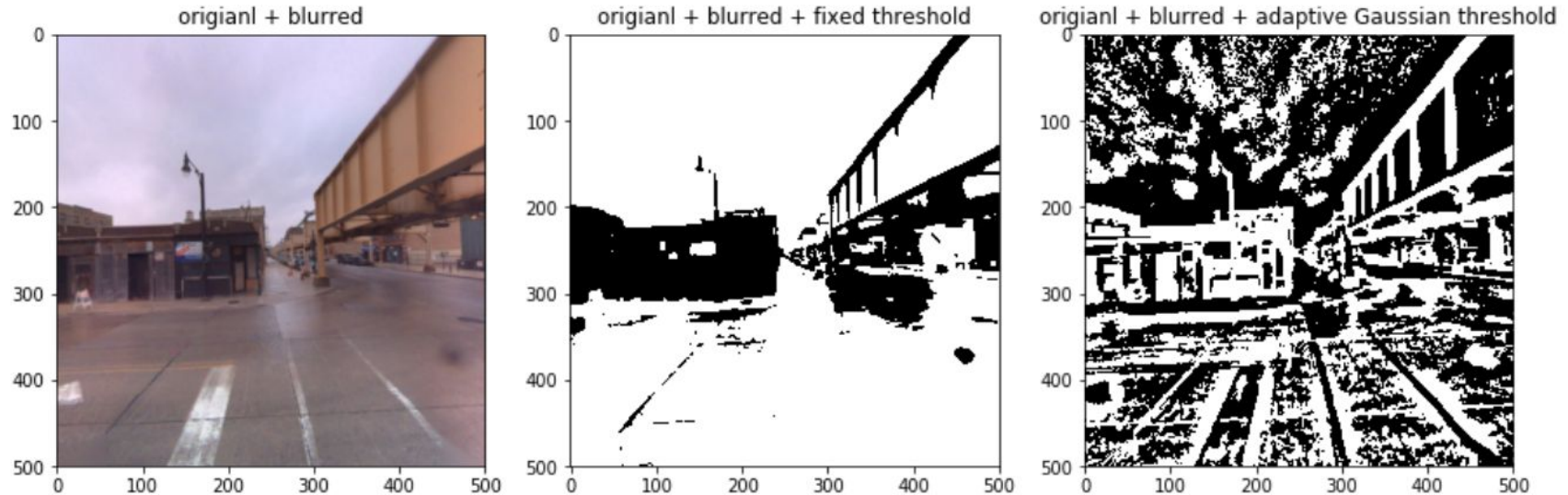
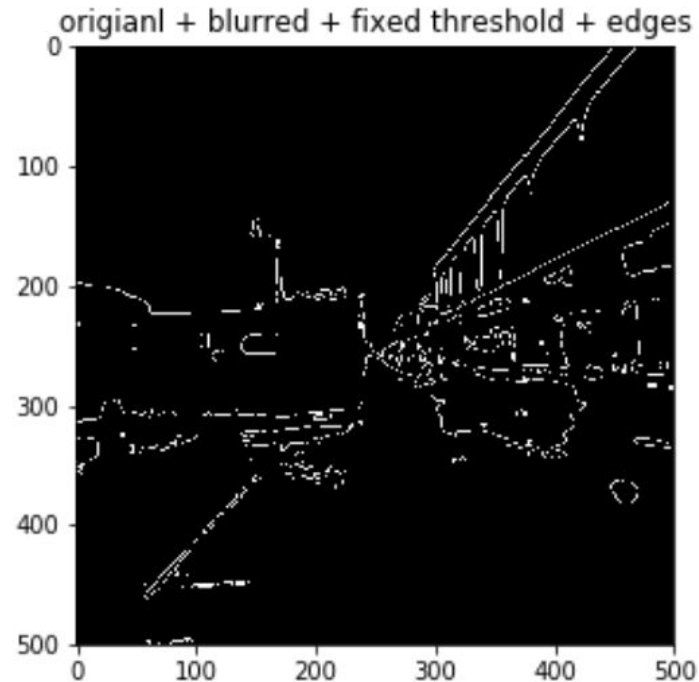
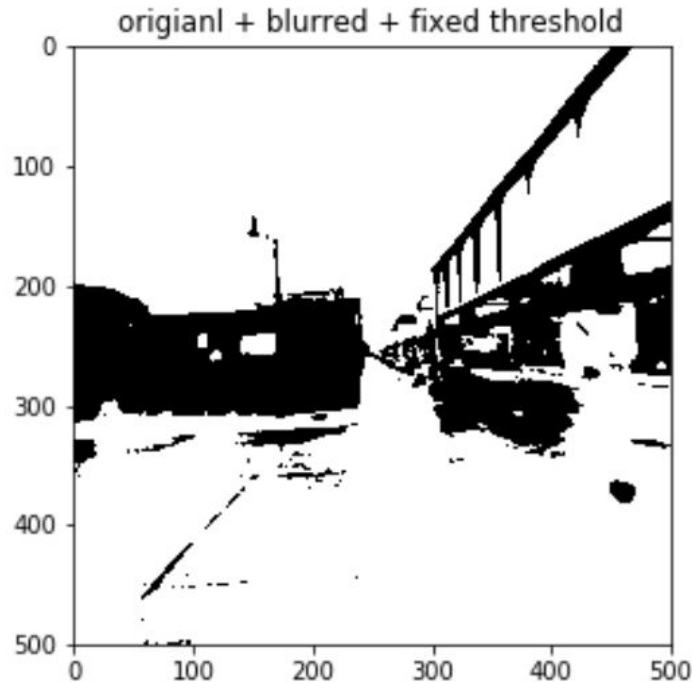


Figure: Comparison of **fixed threshold** and **adaptive Gaussian threshold** algorithm.

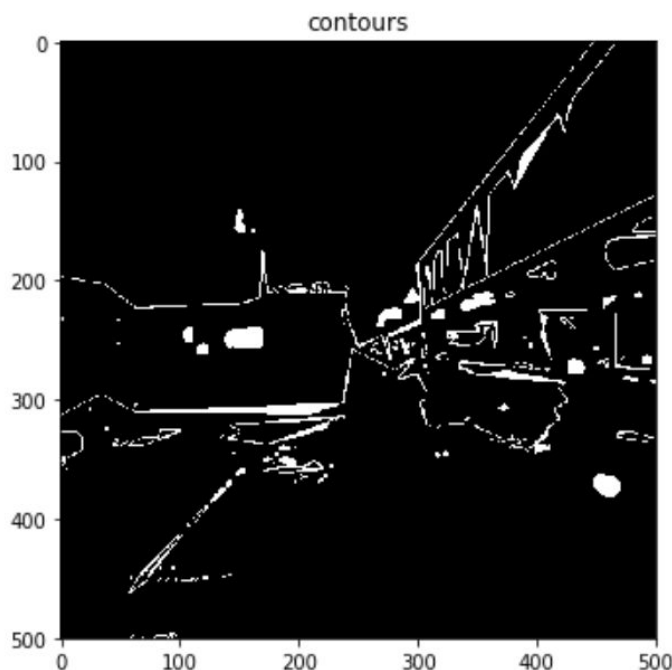
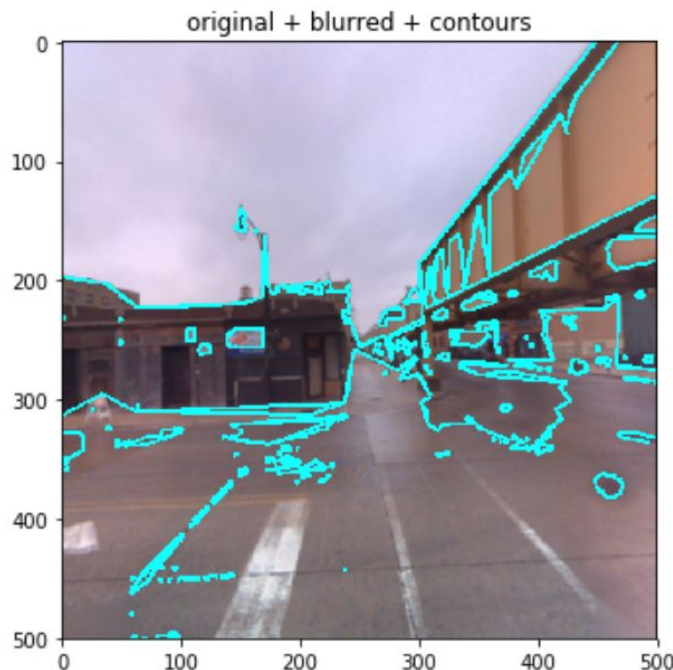
Method 1 - Approach

Step 4: Do **edge detection** to find object contours.

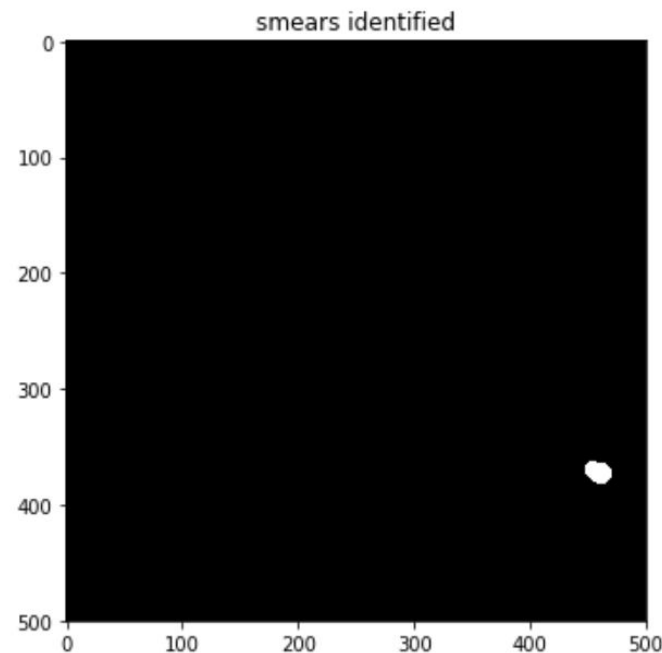
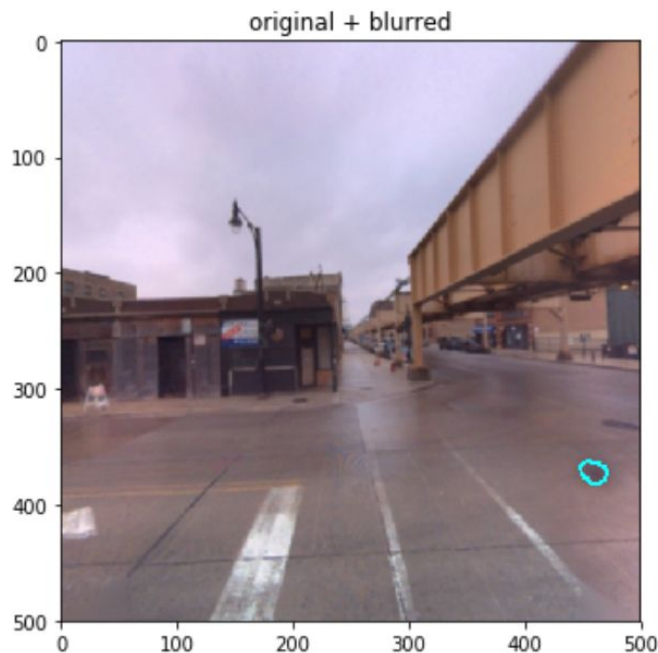


Method 1 - Approach

Step 5: Detect **connected components** from the edge detection result. Find contours, and analyse the shape and size.



Result: A region with circular shape and a proper size is considered as a lens smear.



Assumption: A smear is at a fixed position on the lens, which keeps unchanged during the video.

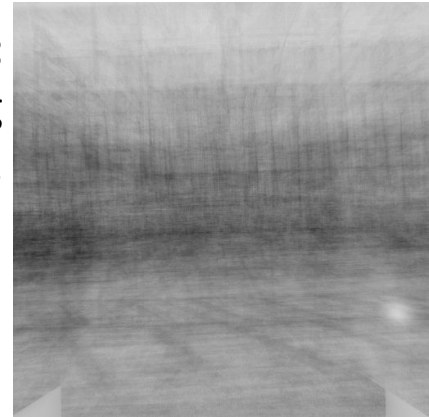
Workflow of algorithms:

1. Use a window size of 500 frames to store past gray images.
2. Sum up the differences between each adjacent image pairs.

Variation image:

Whiter pixel means its corresponding pixel in video **changes less**.

3. Use Method 1 to detect smears —————→ on this image, which are white regions.



The smear is robustly detected in the video:





Thank you!
