# CS302 Operating System Lab 2

Process, Pipe and Signals

CS302 TA group

# **Process**

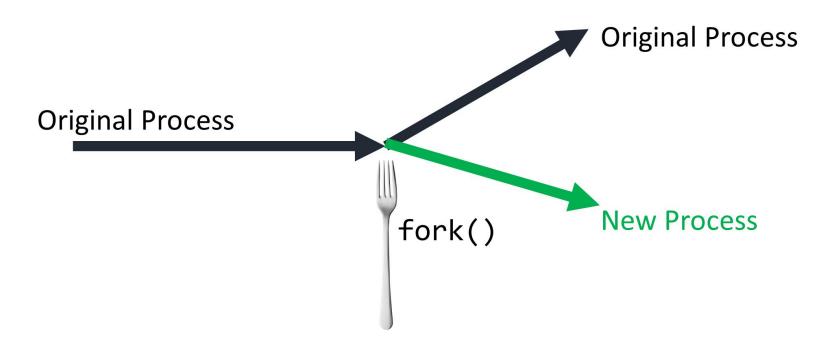
- Today, we will focus these five main keywords:
  - pid: process identifier
  - fork: a function that duplicate a process
  - exec\*: a function family that replace a process
  - signal: handle unexpected situations
  - pipe: Inter-process Communication

#### **Process Identification**

- · Command of showing Process in Linux:
  - -top, ps, (htop)...
  - -just man them to see details if you are not familiar of them
- We can identify one process uniquely by its Process ID (PID)
  - we can use getpid() to get the pid of current process

- Write a C program that use getpid() to display the pid of current process.
  - -Try man getpid if you do not know how to use it
  - -Don't be shy to ask questions

- Use system call fork to create a process
- · after fork, the original process splits into two
  - -fork copies almost all things about the original process
  - -OS allocates the pid, and pass the value to fork()

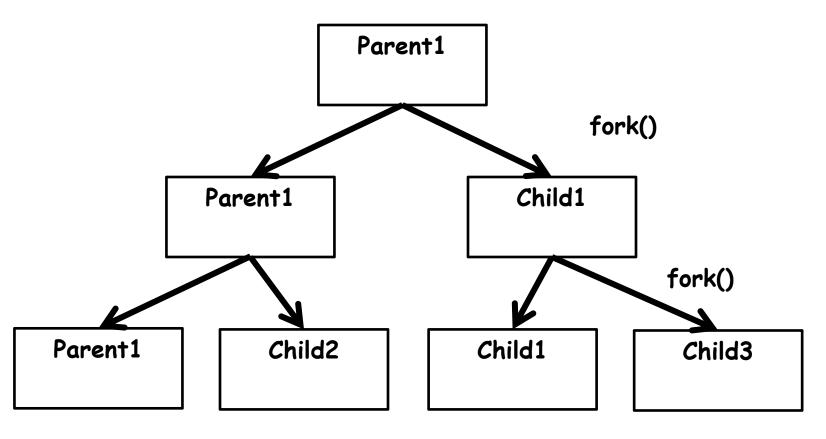


- Write a program that call fork() to generate a new process, and print the pid of the processes( both parent and child process)
  - -Try man fork if you are not familiar with the function
  - -Don't be shy to ask questions

- Exercises: How many A, B and C will be printed?
  - a) A: 1 time, B: 2 times, C: 2 times
  - b) A: 1 time, B: 2 times, C: 4 times
  - c) A: 1 time, B: 1 times, C: 2 times
  - d) A: 1 time, B: 2 times, C: 3 times

```
#include <stdio.h>
#include <unistd.h>
int main(int argc, char *argv[]){
    printf("A\n");
    fork():
    printf("B\n");
    fork():
    printf("C\n");
    return 0;
```

• The sequence of process running after fork:



Who runs first?

- Exercises: The result of running the following program is
- (A) A\nB\nB\nC\nC\nC\nC\n
- (B) A\nB\nC\nB\nC\nC\nC\n
- (C) Not sure

```
#include <stdio.h>
#include <unistd.h>
int main(int argc, char *argv[]){
    printf("A\n");
    fork();
    printf("B\n");
    fork();
    printf("C\n");
    return 0;
```

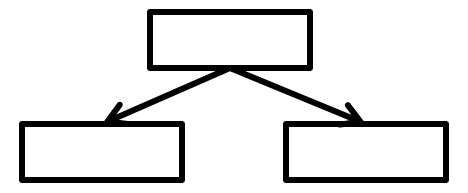
- Write a program that verify the return value of fork() function.
  - -Try man fork if you are not familiar with the function
  - -Don't be shy to ask questions

#### **Process Execution**

- exec\*() function family
  - -Contains: execl, execlp, execle, execv, execvp, execve.
  - -Only one system call: execve()
  - "l" means list, "v" means vector
  - "p" means path, "e" means environment
- Try man exec to see details

- Write a simple program that print anything you want. And then call exec\*() function to execute it.
  - -Try man exec if you are not familiar with these functions
  - -Don't be shy to ask questions

· Now, we have the method to duplicate a process

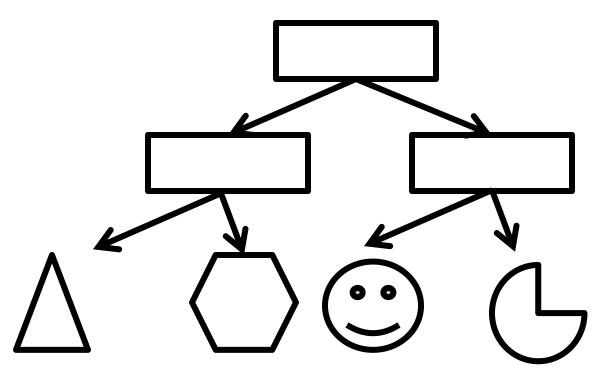


· And, we have the method to replace a process



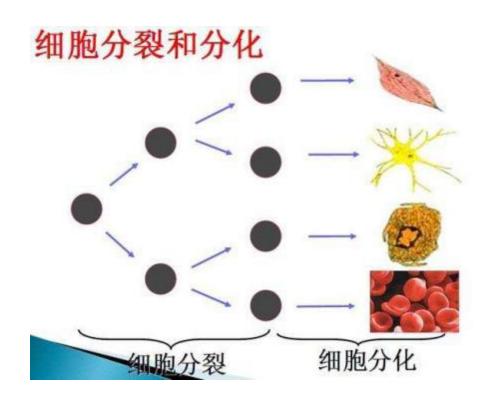
• Then we can get ...

· We can get diversity functions we need



## Interesting idea of mine

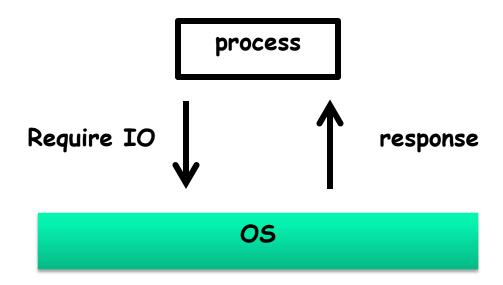
- fork() like cell division
- exec\*() like cell differentiation
- · Init process like Fertilized egg
- · What we can get is actually a human.



- Let's return to the topic we discussed before:
  - -The sequence of running a program.
  - -What does shell exactly do.

- · But if we want the process running in the way we want?
  - -wait\*(), signal(), kill()
  - -Try man wait to know details

- After require 10, our process can call wait\*() to suspend until be waked up.
  - -wait() for any one of the children, and only detect the termination
  - -waitpid() depends on the parameters



• Write a program that after fork(), the child process runs first. And then parent runs.

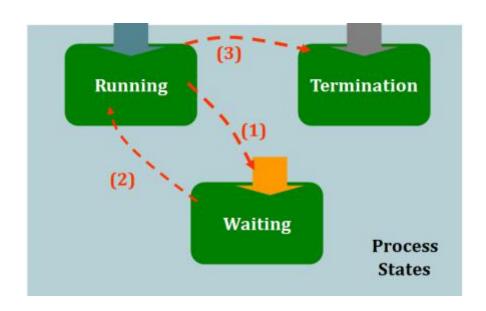
· Recall shell's command

# **Signal**

- Signal is a kind of interrupt to the running process.
  - -SIGINT, SIGCHLD, SIGHUP, SIGALARM
- · Signal handling
  - -Ignore
    - » SIGKILL, SIGSTOP never be ignored
  - -Catch
    - » By user function
  - -Default
    - » By kernel default handler

# **Signal**

- Signals
  - -Signals play a really important role in switching process states.



# Signal

- Signal sending(kill, sigqueue)
  - -kill() send a signal to process
  - -Try kill -I to see all signals
- Signal registration(signal, sigaction)
  - -signal() functions is used to set the handler when the process received a given signal.
  - -E.g. signal(SIGINT, my\_handler) will let the process run function my\_handler when reveived signal SIGINT.

- Write a program that waiting for signal SIGINT. After the first time from receiving SIGINT, the process must ignore SIGINT. And find a way to test your program.
  - -Hint: You may need getpid(), signal() functions and kill command
  - -If you are not familiar with these functions/commands, use man
  - -Be free to ask questions, but I hope you can solve your problems by yourself.

# **Pipe**

- · pipe overview
  - -Pipe is a unidirectional data channel for interprocess communication.
- System call pipe ()
  - -pipe() will create a pipe.
  - -Try man pipe to know details.
  - -File descriptor: handle used to access a file or other input/output resource.

# Learn to use pipe

A pipe



- A pipe with fork
   -Why they share the same pipe?
  - parent 1 parent 0

    child 1 child 0

 As you know, if we want to do inter-process communication, we need at least two processes. Write a program that call fork() to generate a child process, and use pipe() to create a pipe between them. And then, you should input message in one of the process and display the message in the other process.

-If you are not familiar with these functions/commands, use man

-Be free to ask questions, but I hope you can solve your problems by

yourself. mark@marklinux:~/os/lab2\$ ./pipe new -An exampe child process begins, pid = 8897 child process begins, pid = 8898 My pid is 8898 Please input a string: hello Write finished My pid is 8897 read begins Read finished Message is: hello

> My pid is 8898 Please input a string:

## Read code together

```
int pid;
int pipe fd[2];
char buff[1024], input[1024];
void write data(){
   sleep(1);
   printf("\nMy pid is %d\n", getpid());
   printf("Please input a string:\n");
   scanf("%s", input);
   write(pipe fd[1], input, strlen(input));
   printf("Write finished\n");
   kill(getppid(), SIGALRM);
void finish write(){
   close(pipe fd[1]);
   printf("%d finish write\n", getpid());
   exit(0);
void read data(){
   sleep(1);
   printf("\nMy pid is %d\n", getpid());
   printf("read begins\n");
   memset(buff, 0, sizeof(buff));
   read(pipe fd[0], buff, 1024);
   printf("Read finished\n");
   printf("Message is: %s\n", buff);
kill(pid, SIGALRM);
```

```
oid finish read(){
   close(pipe fd[0]);
   printf("%d finish read\n", getpid());
   exit(0);
int main(){
   if (pipe(pipe fd) < 0){</pre>
       printf("pipe create failed\n");
   if ((pid = fork()) < 0){
       printf("fork failed\n");
   }
   if (!pid){
       printf("child process begins, pid = %d\n", getpid());
signal(SIGALRM, write data);
       signal(SIGINT, finish write);
       kill(getpid(), SIGALRM);
       while (1){
        }
   else{
       printf("parent process begins, pid = %d\n", getpid());
       signal(SIGALRM, read data);
       signal(SIGINT, finish read);
       while (1){
       }
```

# **Assignment**

• Finish the Lab report.