Holographic Holes and Differential Entropy [1]

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Hole-ography is a method to reconstruct a curve on t = const and its length in pure AdS_3 from the differential entropy, which is a quantity defined by a family of the entanglement entropy of CFT_2 [2] (see my overview). Here t is the time of the static coordinate. In [1], they showed that the hole-ography can be also used for more generic bulk geometries subject to some assumptions, with curves not restricted to be on t = const.

A spacelike geodesic was characterized by an θ -interval, $[\theta - \alpha, \theta + \alpha]$, in [2]. However, if we want to describe curves not limited to be on t = const, θ -intervals are not useful. Thus we might better to express a geodesic by its boundary endpoints: $\gamma_L(\lambda)$, $\gamma_R(\lambda)$. Here λ is a parameter labeling a family of the endpoint pairs to specify a spatial geodesic, and the family creates a spacelike curve in the bulk, as its envelop. We call the bulk curve $c_{\gamma} = c_{\gamma}^{M}(\lambda)$, where M expresses the bulk coordinates and the geodesic specified by $\gamma_L(\lambda)$ and $\gamma_R(\lambda)$ is tangent at $c_{\gamma}^{M}(\lambda)$.

The differential entropy is defined as¹⁾

$$E = \int d\lambda \left. \frac{\partial S(\gamma_L(\lambda), \gamma_R(\lambda'))}{\partial \lambda'} \right|_{\lambda' = \lambda}, \tag{1}$$

where $S(\gamma_L, \gamma_R)$ is the length of the geodesic from γ_L to γ_R , which is dual to the boundary entanglement entropy, or more precisely the entwinement [3]. The following statement was shown by them: given that the pair $(\gamma_L(\lambda), \gamma_R(\lambda))$ is periodic and smooth, then the length of c_{γ} is equal to E^{2} .

Let us follow the proof. Length S in (1) is expressed as

$$S(\gamma_L(\lambda), \gamma_R(\lambda)) = \int_{s_L}^{s_R} ds \sqrt{(\dot{x}(s; \lambda), \dot{x}(s; \lambda))} \qquad (x(s_{L,R}) = \gamma_{L,R}(\lambda)), \tag{2}$$

where (,) is the inner product defined by the bulk metric, $x(s,\lambda)$ is the geodesic from $\gamma_L(\lambda)$ to $\gamma_R(\lambda)$, and $\dot{}:=\partial/\partial s$. Since S is of the ordinary action form,³⁾ we can use the knowledge of analytical mechanics. The integrand in (1) is rewritten as

$$\frac{\partial S(\gamma_L(\lambda), \gamma_R(\lambda'))}{\partial \lambda'} \bigg|_{\lambda'=\lambda} = \gamma_R^{\mu}{}'(\lambda) \frac{\partial S}{\partial \gamma_R^{\mu}} (\gamma_L(\lambda), \gamma_R(\lambda))
= \gamma_R^{M}{}'(\lambda) \frac{\partial S}{\partial \gamma_R^{M}} (\gamma_L(\lambda), \gamma_R(\lambda))
= \frac{\partial x^M(s_R; \lambda)}{\partial \lambda} p_M(x(s_R; \lambda), \dot{x}(s_R; \lambda)),$$
(3)

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¹⁾ This definition is equivalent to that of [2] when geodesics are on t = const, as explained in [1].

²⁾ Great attention should be paid to that the periodicity is assumed. For example, BTZ black hole unfortunately breaks this assumption.

 $^{^{3)}}$ The reparameterization-invariance of s and that it consists of up to the first derivative of the position.

where $p_M(x(s), \dot{x}(s))$ is the conjugate momentum of off-shell position $x^M(s)$. (If those are accompanied by "; λ ", then they take the on-shell value defined above.) In the last equality, we have used the knowledge that the derivative of the on-shell action with the final position is the conjugate momentum at the position.

On the other hand, the length of c_{γ} , which we call L, is given as

$$L = \oint d\lambda \sqrt{(c'_{\gamma}(\lambda), c'_{\gamma}(\lambda))}.$$
 (4)

This is of the off-shell version of (2). It is easy to show that equation

$$\sqrt{(\dot{y}(s), \dot{y}(s))} = \dot{y}^{M}(s)p_{M}(y(s), \dot{y}(s))$$
(5)

holds in general (even in off-shell),⁴⁾ and hence,

$$L = \oint d\lambda \, c_{\gamma}^{M'}(\lambda) p_M(c_{\gamma}(\lambda), c_{\gamma}'(\lambda)). \tag{6}$$

As c_{γ} is the envelop of $\{\dot{x}(s;\lambda)\}$, at the tangent point $s=s_c$, we have

$$x(s_c; \lambda) = c_{\gamma}(\lambda), \qquad \exists \alpha(\lambda) > 0, \ \alpha(\lambda)\dot{x}(s_c; \lambda) = c'_{\gamma}(\lambda).$$
 (7)

Note that s_c can be chosen to be independent of λ by reparameterizing s. Then we obtain

$$L = \oint d\lambda \frac{\partial x^{M}(s_{c}; \lambda)}{\partial \lambda} p_{M}(x(s_{c}; \lambda), \alpha(\lambda)\dot{x}(s_{c}; \lambda))$$

$$= \oint d\lambda \frac{\partial x^{M}(s_{c}; \lambda)}{\partial \lambda} p_{M}(x(s_{c}; \lambda), \dot{x}(s_{c}; \lambda)), \tag{8}$$

where in the last equality, we have used follows from the property of the momentum that $p(y(s), \alpha \dot{y}(s)) = p(y(s), \dot{y}(s))$ following from (5).

Therefore, the remaining task to accomplish is to show that

$$E - L = \oint d\lambda \left. \frac{\partial x^M(s;\lambda)}{\partial \lambda} p_M(x(s;\lambda), \dot{x}(s;\lambda)) \right|_{r_s}^{s_R}$$
(9)

must vanish. Using the relation between the on-shell action and the momenta of endpoints again, we can rewrite the above as

$$E - L = \oint d\lambda \frac{\partial}{\partial \lambda} S(x(s_c; \lambda), x(s_R; \lambda)).$$
 (10)

Since $x(s;\lambda)$ is also periodic about λ by the assumption, we see this vanish.

⁴⁾ This generally follows from the reparameterization-invariance, but can also be shown directly of course.

References

- [1] M. Headrick, R.C. Myers and J. Wien, *Holographic Holes and Differential Entropy*, *JHEP* **10** (2014) 149 [1408.4770].
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